

## SCUOLA DI INGEGNERIA Corso di Laurea Magistrale in Ingegneria Informatica

# Improving WATSS web application with Computer Vision techniques

Visual and Multimedia Recognition

Lorenzo Cioni

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#### Introduction

WATSS, **Web Annotation Tool for Surveillance Scenarios**, is a web-based annotation tool developed to annotate dataset in surveillance systems [1].

**Main goal**: improve WATSS with some **Computer Vision approaches**, in order to make easy for users to use this tool and make the annotation process more *automatic*.



## LabelMe [4]

- Web-based tool, also released as mobile application
- Annotate scenes with polygonal areas
- Nested objects and occlusion annotations
- Zoom in and out of the scene



#### ViPER-GT

- Java application tool
- Annotate scenes with geometrical shapes
- Timeline and annotation highlighting on time change
- Linear interpolation between annotations
- Zoom in and out of the scene



## VATIC [3]

- Online tool
- Developed for object detection
- Crowd-sourcing to Amazon's Mechanical Turk
- Multiple plugins: object tracking, sentence annotation, etc.



#### **WATSS**

- Web-based tool
- Annotation with bounding box
- Occlusion area
- Coarse gaze estimation
- Groups and POI under observation
- Multiple cameras manager

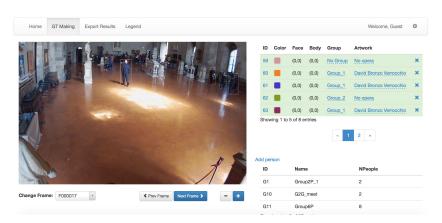


## **Improvements**

- User interface renovation
- Simpler annotation making and editing
- Video timeline for annotations
- Automatic proposals generation
- Scene geometry-based enhancement
- Easy setup process

#### User interface renovation

#### The old WATSS user interface



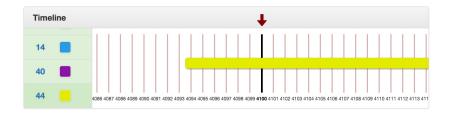
#### User interface renovation

#### The **new** WATSS user interface



#### Video timeline

In the video **timeline** all the video frames are shown, coloring the ones with at least one annotated person.



Selecting a person in the list, the timeline displays its **history** highlighting frames where it is present. It is possible to navigate video frames by clicking on it.



## Proposals generation

It is possible to generate **proposals** for a person in some selected frames based on previous annotation of a it using timeline: just click and drag highlighted annotation.

Proposals generation is based on the combination of three different techniques:

- Motion detection using a background substractor
- Pedestrian detection using HOG descriptors
- Kalman filter for the motion estimation

#### Motion detection

Motion detection is based on a **background substraction** method: moving objects are detected performing a subtraction between the current frame and a background model of the current scene, obtaining a **foreground mask**.

Each pixel of a frame is modeled as a **Mixture of Gaussians** and those which correspond to background colors are selected according to variance and persistence.

Pixel values that do not fit the background distributions are considered part of the foreground.

Background modeling consists of two main steps:

- Background initialization: background model evaluation.
- Background update: background model is adapted to possible changes in the scene.

#### Motion detection

Using the foreground mask, a set of **detections** are extracted based on contours.

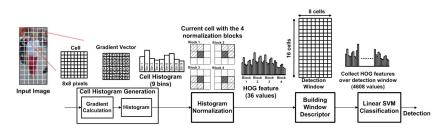


Given the previous frame person bounding box, those that do not *overlap* or are *inconsistent* with its dimensions are discarded.

13 di 23

#### Pedestrian detector

The used *pedestrian detection* technique is based on **Histogram of Oriented Gradients** and SVM classifier.



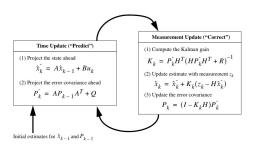
As in the previous case, detections are filtered according to person history in scene.

Figure from Suleiman, A., Sze, V. J Signal Process Systems (2016)



#### Kalman filter

A **Kalman filter** is an optimal estimator used for following state estimation based on a set of previous observations.



As system state is considered the **coordinates** (x, y) **of the person** in the current scene, using motion and pedestrian detection for updating the measure.

15 di 23

## Proposals generation

A proposal for a generic frame is the result of the combination of the above descripted methods. each resulted bounding box is compared with the previous frame annotation for evaluating a **score**:

$$score(r) = \frac{intersection(r, p)}{union(r, p)}$$

where r is a resulting bounding box (i.e. the output of the motion detector) and p is the bounding box of the previous frame.

If motion or pedestrian detector fails, then the *Kalman filter prediction* is used as proposal.

## Proposals generation example













## Scene geometry

In the annotation insertion step, it is possible to use **scene geometry** knowledge in order to generate proposal based on the pointer position.

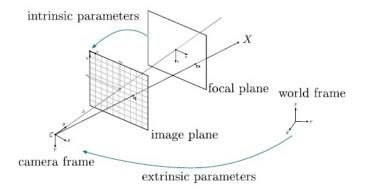
#### Requirements:

- Static cameras: they must be fixed in their positions
- Camera calibration parameters
  - Intrinsic parameters, K
  - Estrinsic parameters, rotation R and translation t
  - A cross-ratio  $\mu$ , being projective invariant

#### Camera calibration

Given  $\mathbf{X} = (X, Y, Z, 1)$ , coordinates in **world**, and  $\mathbf{x} = (x, y, 1)$ , coordinates in **scene**:

$$\mathbf{x} = K[R|t]X$$



19 di 23

## Human height estimation

From camera parameters, it is possible to evaluate vanishing line I and vanishing point  ${\bf v}$ 

$$I = P * [0, 0, 1]'$$

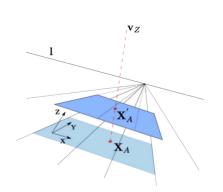
$$v = ((K')^{-1} * K^{-1}) * I$$

$$W = I + (\frac{1}{(1 - \mu)} - 1) * \frac{v * I'}{v' * I}$$

Giveng head position head = (x, y, 1) and **W**:

$$feet = W^{-1} * head$$

$$height = |head_y - feet_y|$$



#### Demo

#### Time for a demo!



#### Web Annotation Tool for Surveillance Scenarios

This tool is designed to annotate person and group bounding boxes, visible area, head gaze, body gaze and observed points of interest (poi) on surveillance datasets.

You may try it on sequences acquired from the Bargello Museum, go to GT Making section and enter with the user Guest.

#### Features

- Bounding Box
- Visible area
- Head gaze
- · Body gaze
- · Points of interest
- · Video timeline with annotations
- · Annotations proposals

#### Preview





#### Conclusions

WATSS application has been improved with **new features** and a renewed **user interface**.

Some features are based on Computer Vision techniques, as automatic annotation proposals generation and scene geometry-based annotation insertion. **Future works**:

- Use scene geometry in proposals generation
- Using different people detector, e.g. an upper body detector, for more accurate proposals
- Different types of **annotation shapes**, e.g circle, ellipsis, polygon etc.

#### References

- [1] F. Bartoli, L. Seidenari, G. Lisanti, S. Karaman, and A. Del Bimbo. *Watts: A web annotation tool for surveillance scenarios.* In *Proceedings of the 23rd ACM International Conference on Multimedia, MM '15*, pages 701–704, New York, NY, USA, 2015. ACM.
- [2] F. Bartoli, G. Lisanti, L. Seidenari, S. Karaman, and A. Del Bimbo. *Museumvisitors: A dataset for pedestrian and group detection, gaze estimation and behavior understanding.* In *Proceedings of the IEEE Conference on Computer Vision and Pattern Recognition Workshops*, pages 19–27, 2015.
- [3] C. Vondrick, D. Patterson, and D. Ramanan. *Efficiently scaling up crowdsourced video annotation*. Int. J. Comput. Vision, 101(1):184–204, Jan. 2013.
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- [5] A. Del Bimbo, G. Lisanti, and F. Pernici. *Scale invariant 3d multi-person tracking using a base set of bundle adjusted visual landmarks.* In Computer Vision Workshops (ICCV Work- shops), 2009 IEEE 12th International Conference on, pages 1121–1128. IEEE, 2009.