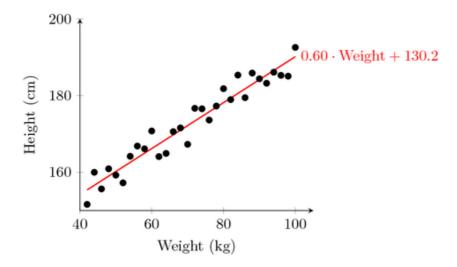
1 Linear regression (for regression)

Model a scalar target with one or more quantitative features.

Although regression computes a linear combination, features can be transformed by nonlinear functions if relationships are known or can be guessed.



Example of prediction using a linear regression model

1.1 Univariate linear regression

• Description

Simple linear regression is a statistical method that studies the relationship between two variables:

- *x*: the predictor, explanatory, independent variable,
- *y*: the response, outcome, dependent variable.
- · Model's hypothesis

$$h(x) = \theta_0 + \theta_1 * x = \hat{y}$$

- Model's parameters (# 2)
 - $\circ \theta_0$
 - $\circ \theta_1$
- Cost function (in this case, the squared error function)

$$J(\theta_0, \theta_1) = \frac{1}{2m} \sum_{i=1}^{m} (\hat{y}^i - y^{(i)})^2$$

Goal

 $minimize_{\theta_0,\theta_1}J(\theta_0,\theta_1)$

- Algorithm
 - gradient descent
 - start with some initial values for θ_0 and θ_1 (usually zero)
 - keep changing θ_0 and θ_1 to reduce $J(\theta_0, \theta_1)$

$$\bullet \theta_0 = \theta_0 - \alpha \frac{\partial}{\partial \theta_0} J(\theta_0, \theta_1) = \theta_0 - \alpha \left(\frac{1}{m} \sum_{i=1}^m \left(\hat{y}^i - y^{(i)} \right) \right)$$

$$\bullet \theta_1 = \theta_1 - \alpha \frac{\partial}{\partial \theta_1} J(\theta_0, \theta_1) = \theta_1 - \alpha \left(\frac{1}{m} \sum_{i=1}^m \left(\hat{y}^i - y^{(i)} \right) \cdot x^{(i)} \right)$$

• directly use the following **formulas**

$$\bullet \ \theta_1 = \frac{\sum_{i=1}^m (x^{(i)} - \bar{x})(y^{(i)} - \bar{y})}{\sum_{i=1}^m (x^{(i)} - \bar{x})^2}$$

$$\bullet \ \theta_0 = \bar{y} - \theta_1 \bar{x}$$

- Notations
 - *x*: the independent variable
 - *y*: the dependent variable
 - *m*: the number of training examples
 - $x^{(i)}$: the input value of the i^{th} training example
 - $y^{(i)}$: the target value of the i^{th} training example
 - $\hat{y}^{(i)}$: the prediction made on the i^{th} training example by the current hypothesis function
 - \circ α : the learning rate; determines how big steps we take when updating the θ parameters
- Hyperparameters:
 - \circ α : if too small, slow gradient descent; if too large, gradient descent may fail to converge
- Problems:
 - o gradient descent may converge to a local minimum

1.2 Multivariate linear regression

• Description

Multivariate linear regression is a statistical method that studies the relationship between multiple variables:

- n variables $x = \{x_1, x_2, \dots, x_n\}$: the predictor, explanatory, independent variables,
- one *y* variable: the response, outcome, dependent variable.
- · Model's hypothesis

$$h(x) = \theta_0 + \theta_1 * x_1 + \theta_2 * x_2 + \dots + \theta_n * x_n = \hat{y}$$

• Model's parameters (# n + 1)

$$\theta = \{\theta_0, \theta_1, \dots, \theta_n\}$$

• Cost function (in this case, the squared error function)

$$J(\theta) = \frac{1}{2m} \sum_{i=1}^{m} (\hat{y}^{(i)} - y^{(i)})^2$$

Goal

 $minimize_{\theta}J(\theta)$

- Algorithm
 - o gradient descent
 - start with some initial values for θ_0 , θ_1 , ..., θ_n (usually 0)
 - keep changing θ s to reduce $J(\theta)$

$$\bullet \ \theta_0 = \theta_0 - \alpha \frac{\partial J}{\partial \theta_0} = \theta_0 - \alpha \left(\frac{1}{m} \sum_{i=1}^m \left(\hat{y}^i - y^{(i)} \right) \right)$$

$$\bullet \ \theta_1 = \theta_1 - \alpha \frac{\partial J}{\partial \theta_1} = \theta_1 - \alpha \left(\frac{1}{m} \sum_{i=1}^m \left(\hat{y}^i - y^{(i)} \right) \cdot x_1^{(i)} \right)$$

• ..

•
$$\theta_n = \theta_n - \alpha \frac{\partial J}{\partial \theta_n} = \theta_n - \alpha \left(\frac{1}{m} \sum_{i=1}^m \left(\hat{y}^i - y^{(i)} \right) \cdot x_n^{(i)} \right)$$

Notations

- *x*: the independent variables
- *y*: the dependent variable
- *m*: the number of training examples
- *n*: the number of features representing each training example
- $x^{(i)}$: the input values of the i^{th} training example
- $x_i^{(i)}$: the value of the j^{th} feature of the i^{th} training example
- $y^{(i)}$: the target value of the i^{th} training example
- \circ $\hat{y}^{(i)}$: the prediction made on the i^{th} training example by the current hypothesis function
- \circ α : the learning rate; determines how big steps we take when updating the θ parameters
- Hyperparameters:
 - α
- · Problems:
 - o make sure features are on similar scales; gradient descent may be slow otherwise

• rescaling:
$$x' = \frac{x - min(x)}{max(x) - min(x)}$$

- mean normalization: $x' = \frac{x mean(x)}{max(x) min(x)}$
- standardization: $x' = \frac{x mean(x)}{std(x)}$
- o make sure the gradient descent is working correctly
 - plot the value of the cost function J over the number of iterations (# epochs)
 - for a sufficiently small α , $J(\theta)$ should decrease on every iteration
 - if α is too small, the gradient descent can be slow to converge
 - if α is too large, $J(\theta)$ may not decrease on every iteration; may not converge
 - try values $\alpha \in \{..., 0.001, 0.01, 0.1, 1, ...\}$
- o try adding new features if the model doesn't perform well
 - e.g., use a polynomial regression

$$\theta_0 + \theta_1 * x \Rightarrow \theta_0 + \theta_1 * x + \theta_2 * x^2 + \theta_3 * x^3$$

- use regularization in case of overfitting
 - cost function with the regularization term

$$J(\theta) = \frac{1}{2m} \sum_{i=1}^{m} \left(\hat{y}^{(i)} - y^{(i)} \right)^2 + \frac{\lambda}{2m} \sum_{j=1}^{n} \theta_j^2$$

• parameter update in gradient descent (for $j \in \{1, 2, ..., n\}$)

$$\theta_j = \theta_j - \alpha \frac{\partial J}{\partial \theta_j} = \theta_j - \alpha \left(\frac{1}{m} \sum_{i=1}^m \left(\hat{y}^i - y^{(i)} \right) \cdot x_j^{(i)} + \frac{\lambda}{m} \theta_j \right) = \theta_j \left(1 - \alpha \frac{\lambda}{m} \right) - \alpha \frac{1}{m} \sum_{i=1}^m \left(\hat{y}^i - y^{(i)} \right) \cdot x_j^{(i)}$$

- intuition: shrink model parameters in order to smooth out the decision boundary
- lacksquare λ is the regularization parameter and needs to be tuned