## Lecture 9

Linear programming duality associates to a linear programming problem a **dual problem**, with the property that the optimal values of the original and of the dual problem coincide. Duality is an important tool in applications and in the design of algorithms. Linear programming duality rests upon an important family of results in convex geometry, known collectively as Farkas' Lemma.

## 9.1 Farkas' Lemma

Recall the definition of a convex cone. This is a set C such that for all  $x, y \in C$  and  $\lambda_1, \lambda_2 \ge 0$  we have  $\lambda_1 x + \lambda_2 y \in C$ .

**Lemma 9.1.** (Hyperplane separation for cones) Let  $C \neq \mathbb{R}^n$  be a closed convex cone and  $z \notin C$ . Then there exists a linear hyperplane such that  $C \subseteq H_-$  and  $z \in \text{int} H_+$ .

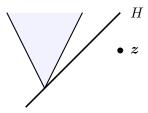


Figure 9.1: Separating hyperplane for a cone

*Proof.* From Lecture 7 we know that there exists an affine hyperplane  $H^a$  separating C and z. Let this affine hyperplane be given by  $\langle \boldsymbol{a}, \boldsymbol{x} \rangle = b$ . We would like to show that  $H = \{\boldsymbol{x} : \langle \boldsymbol{a}, \boldsymbol{x} \rangle = 0\}$  is a linear hyperplane separating C and z. From  $\langle \boldsymbol{a}, \boldsymbol{z} \rangle > b$  we clearly get  $\langle \boldsymbol{a}, \boldsymbol{z} \rangle > 0$ . Also,  $\mathbf{0} \in H_-$ , since  $\langle \boldsymbol{a}, \mathbf{0} \rangle = 0$ . Assume now that there exists a point  $\boldsymbol{x} \in C$  such that  $\langle \boldsymbol{a}, \boldsymbol{x} \rangle = c > 0$ . Since C is a cone, for all  $\lambda > 0$  we have that  $\lambda \boldsymbol{x} \in C$ . Choosing  $\lambda$  so that  $\lambda > b/c$  we get

$$\langle \boldsymbol{a}, \lambda \boldsymbol{x} \rangle = \lambda c > b,$$

in contradiction to  $C \subset H^a_-$ . This shows that H is a linear separating hyperplane.  $\square$ 

**Theorem 9.2.** (Farkas' Lemma) Given a matrix  $A \in \mathbb{R}^{m \times n}$  and  $b \in \mathbb{R}^m$ , there exists a vector x such that

$$Ax = b, \quad x > 0$$

if and only if there is not  $\mathbf{y} \in \mathbb{R}^m$  such that

$$\mathbf{A}^{\top} \mathbf{y} \ge \mathbf{0}, \quad \langle \mathbf{y}, \mathbf{b} \rangle < 0.$$

*Proof.* Assume Ax = b has a solution  $x \ge 0$ . Then for any  $y \ne 0$  such that  $A^{\top}y \ge 0$ ,

$$0 \le \langle \boldsymbol{A}^{\top} \boldsymbol{y}, \boldsymbol{x} \rangle = \langle \boldsymbol{y}, \boldsymbol{A} \boldsymbol{x} \rangle = \langle \boldsymbol{y}, \boldsymbol{b} \rangle,$$

which shows that  $\mathbf{A}^{\top} \mathbf{y} \geq \mathbf{0}$  and  $\langle \mathbf{y}, \mathbf{b} \rangle < 0$  are not simultaneously possible.

Assume now that Ax = b has no solution that satisfies  $x \ge 0$ . Let  $a_1, \ldots, a_n$  be the columns of A. The set of Ax for  $x \ge 0$  is the set of all nonnegative linear combinations

$$C = \{ z \in \mathbb{R}^m : z = x_1 a_1 + \dots + x_n a_n, \ x_i \ge 0 \},$$

and this set is a convex cone. The assumption that there is no nonnegative x such that Ax = b means that  $b \notin C$ . By Lemma 9.1, there exists a linear hyperplane  $H = \{x : \langle y, x \rangle = 0\}$  such that  $C \in H_-$  and  $b \in \text{int} H_+$ . Formulated differently, there exists a  $y \in \mathbb{R}^m$  such that

$$\forall z \in C : \langle z, y \rangle \ge 0, \quad \langle b, y \rangle < 0.$$

Since every  $z \in C$  has the form  $z = \sum_{i=1}^{n} x_i a_i$  with  $x_i \ge 0$ , the relation

$$\langle \boldsymbol{z}, \boldsymbol{y} \rangle = \sum_{i=1}^n x_i \langle \boldsymbol{a}_i, \boldsymbol{y} \rangle \geq 0$$

for all  $x \ge 0$  is equivalent to the condition that  $\langle a_i, y \rangle \ge 0$  for  $1 \le i \le n$ , which again is equivalent to  $A^{\top}y \ge 0$ . This concludes the proof.

The following consequence is perhaps a more familiar form of Farkas' Lemma.

**Corollary 9.3.** Given a matrix  $A \in \mathbb{R}^{m \times n}$  and  $b \in \mathbb{R}^m$ , there exists a vector  $x \neq 0$  such that

$$Ax \leq b$$

if and only there is no y such that

$$y \ge 0$$
,  $A^{\top}y = 0$ ,  $\langle y, b \rangle < 0$ .

*Proof.* Consider the matrix

$$A' := (A - A I),$$

where I is the  $m \times m$  identity matrix. A nonnegative solution of A'x' = b has the form  $x' = (x_1, x_2, x_3)^{\top}$ , and implies  $A(x_1 - x_2) + x_3 = b$ . Therefore, such a solution x' exists if and only if the system

$$Ax \le b$$

has a solution. Applying Theorem 9.2, the complementary condition is

$$\mathbf{A}'^{\top} \mathbf{y} \ge \mathbf{0}, \quad \langle \mathbf{b}, \mathbf{y} \rangle < 0,$$

which in terms of A translates to

$$\mathbf{A}^{\top} \mathbf{y} = \mathbf{0}, \quad \mathbf{y} \ge 0, \quad \langle \mathbf{b}, \mathbf{y} \rangle < 0.$$

This concludes the proof.

One more important corollary will be given without proof.

**Corollary 9.4.** Let  $A \in \mathbb{R}^{m \times n}$  and  $b \in \mathbb{R}^m$ . Then for  $\delta > 0$  and every vector  $x \in \mathbb{R}^n$  with  $Ax \leq b$ ,  $\langle c, x \rangle \leq \delta$  holds if and only if there exists  $y \in \mathbb{R}^m$  such that

$$y \ge 0$$
,  $A^{\top}y = c$ ,  $\langle y, b \rangle \le \delta$ .

## 9.2 Linear programming duality

After studying the feasible sets of linear programming, the polyhedra, we now return to linear programming itself, in the form

maximize 
$$\langle c, x \rangle$$
 subject to  $Ax \leq b$ . (9.1)

Geometrically this amounts to moving the hyperplane orthogonal to c to the highest level along c, under the condition that it still intersects  $P = \{x : Ax \le b\}$ .

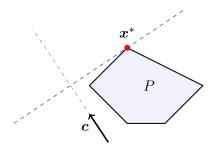


Figure 9.2: Geometry of linear programming

The famous duality theorem for linear programming states that if the maximum of (9.1) exists, then it coincides with the solution of a *dual* linear programming problem.

**Theorem 9.5.** Let  $A \in \mathbb{R}^{m \times n}$ ,  $b \in \mathbb{R}^m$  and  $c \in \mathbb{R}^n$ . Then the optimal value of

maximize 
$$\langle c, x \rangle$$
 subject to  $Ax \leq b$  (P)

coincides with the optimal value of

minimize 
$$\langle b, y \rangle$$
 subject to  $A^{\top}y = c, y \ge 0,$  (D)

provided both (P) and (D) have a finite solution.

The problem (P) is called the *primal* problem, and (D) the *dual* problem.

## **Example 9.6.** Consider the simple problem

maximize 
$$x_1$$
 subject to  $x_1 + x_2 \le 1, x_1 \ge 0, x_2 \ge 0.$ 

The dual problem is

minimize 
$$y_1$$
 subject to  $y_1 - y_2 = 1, y_1 - y_3 = 0, y_1 \ge 0, y_2 \ge 0, y_3 \ge 0.$ 

For the proof we need the following observation.

**Lemma 9.7.** Let  $P \subset \mathbb{R}^n$  be a polyhedron and  $\mathbf{c} \in \mathbb{R}^n$  such that  $\sup_{\mathbf{x} \in P} \langle \mathbf{c}, \mathbf{x} \rangle$  is finite. Then the supremum is attained, that is, it is a maximum.

Proof of Theorem 9.5. Let  $P = \{ \boldsymbol{x} : \boldsymbol{A}\boldsymbol{x} \in \boldsymbol{b} \}$  and  $D = \{ \boldsymbol{y} \in \mathbb{R}^m : \boldsymbol{A}^\top \boldsymbol{y} = \boldsymbol{c}, \boldsymbol{y} \geq \boldsymbol{0} \}$ . If  $\boldsymbol{x} \in P$  and  $\boldsymbol{y} \in Q$ , then

$$\langle oldsymbol{c}, oldsymbol{x} 
angle = \langle oldsymbol{A}^ op oldsymbol{y}, oldsymbol{x} 
angle \leq \langle oldsymbol{y}, oldsymbol{b} 
angle,$$

so that in particular

$$\max_{\boldsymbol{x} \in P} \langle \boldsymbol{c}, \boldsymbol{x} \rangle \leq \min_{\boldsymbol{y} \in Q} \langle \boldsymbol{b}, \boldsymbol{y} \rangle,$$

which shows one inequality. To show the other inequality, set  $\delta = \max_{\boldsymbol{x} \in P} \langle \boldsymbol{c}, \boldsymbol{x} \rangle$ . By definition, if  $A\boldsymbol{x} \leq \boldsymbol{b}$ , then  $\langle \boldsymbol{c}, \boldsymbol{x} \rangle \leq \delta$ . By Corollary 9.4, there exists a vector  $\boldsymbol{y} \in \mathbb{R}^m$  such that

$$y \ge 0$$
,  $A^{\top}y = c$ ,  $\langle b, y \rangle \le \delta$ .

In particular,

$$\min_{\boldsymbol{y} \in Q} \langle \boldsymbol{b}, \boldsymbol{y} \rangle \leq \delta = \max_{\boldsymbol{x} \in P} \langle \boldsymbol{c}, \boldsymbol{x} \rangle.$$

This finishes the proof.