



RnR Manager User Guide

Release 6.10.0

Contents

1	Preface	1
1.1	About The RnR Manager User Guide	1
1.2	Intended Audience	1
1.3	Organisation	1
1.4	Conventions	1
2	Introduction	3
2.1	Overview	3
2.2	Key Concepts	5
3	Installation	9
3.1	Pre-requisites	9
3.2	Supported Platforms	9
3.3	General Installation Instructions	9
4	Using the Record and Replay Manager	11
4.1	RnR Manager Overview	11
4.2	Domain Browser	14
4.3	Service Status	16
4.4	Storage Status	16
4.5	Scenario Status	18
4.6	Topics – One Click Record	20
4.7	Scenario Editors	22
4.8	Storage Data	39
4.9	Storage Editor	43
5	Contacts & Notices	49
5.1	Contacts	49
5.2	Notices	49

1

Preface

1.1 About The RnR Manager User Guide

The *Vortex OpenSplice Record and Replay Manager (RnR Manager) User Guide* is intended to provide a complete reference on how to use this tool to manage the Vortex OpenSplice Record and Replay Service (*RnR Service*).

This *User Guide* is intended to be used after the Vortex OpenSplice software including the RnR Service has been installed on the network and configured according to the instructions in the Vortex OpenSplice *Getting Started Guide*.

1.2 Intended Audience

The *User Guide* is intended to be used by all Vortex OpenSplice users, including programmers, testers, system designers and system integrators.

1.3 Organisation

The *User Guide* is organised as follows:










The *Introduction* gives an overview of the purpose and design of RnR Manager, together with general descriptions of its features.

Installation describes how to install RnR Manager and its license file.

Using the Record and Replay Manager gives detailed descriptions of all of the functions and features of RnR Manager.

1.4 Conventions

The icons shown below are used in Vortex product documentation to help readers to quickly identify information relevant to their specific use of Vortex OpenSplice.

<i>Icon</i>	<i>Meaning</i>
	Item of special significance or where caution needs to be taken.
	Item contains helpful hint or special information.
	Information applies to Windows (<i>e.g.</i> XP, 2003, Windows 7) only.
	Information applies to Unix-based systems (<i>e.g.</i> Solaris) only.
	Information applies to Linux-based systems (<i>e.g.</i> Ubuntu) only.
	C language specific.
	C++ language specific.
	C# language specific.
	Java language specific.

2

Introduction

*The Vortex OpenSplice Record and Replay Manager, or **RnR Manager**, is a tool to control Vortex OpenSplice Record and Replay Services (RnR Services) and to inspect and change recorded data.*

2.1 Overview

This section provides a brief introduction to the Vortex OpenSplice RnR Service and the RnR Manager tool.



Version 6.4 of RnR Manager is compatible with Vortex OpenSplice version 6.4. It is not compatible with earlier versions of Vortex OpenSplice.

2.1.1 Vortex OpenSplice Record and Replay Service

RnR Services are the Vortex OpenSplice software modules responsible for implementing record and replay.

Vortex OpenSplice RnR Service Features

Features provided by the RnR Service include the ability to:

- Control and monitor the service using regular DDS topics.
- Use expressions with wildcards to select partitions and topics of interest, for record and/or replay.
- Store data in XML records for easy post-analysis and data-mining.
- Store data in CDR records for efficient recording and replaying of high-volume data
- Create scenarios, grouping multiple commands into a logical set.
- Use replay filters to replay only the data recorded in a specific time-range.
- Query and edit storage data.

Non-Intrusiveness of Vortex OpenSplice RnR

Vortex OpenSplice Record and Replay is a pluggable service of the Vortex OpenSplice Middleware and is capable of recording and/or replaying DDS datasets (*i.e.* topic samples) in a DDS system. As a ‘DDS service’, Record and Replay benefits from the inherent ‘decoupling in time and space’ that the DDS architecture offers, with respect to automatic discovery of the service’s dynamic interest in subscribing or publishing data as well as the transparent routing of information to and from the service.

Relevant characteristics of this service with respect to ‘intrusiveness’ for an existing system are:

1. The RnR service can be optionally configured on any DDS node in the system.
 - (a) When run as part of an existing federation of applications, it utilizes the federation’s shared memory segment to obtain the data. (So locally-published data is not required to travel over the network to be recorded by the service and *vice versa* for replaying towards co-located subscribers.)

- (b) When run on a dedicated RnR node, to be recorded data is transparently forwarded to that RnR node typically using multicast network features (so as not to induce extra network traffic).
- 2. RnR services are controlled in ‘the DDS way’, *i.e.* a data-centric way where command and status topics enable DDS based ‘remote control’ of the service from anywhere in the system.
 - (a) A dedicated record and replay partition is utilized by RnR to bound the control/status flows.
 - (b) In the case of a dedicated RnR node, this partition can be configured to be a so-called ‘local partition’, thus bounding all control/status traffic to the RnR node (see Section 2.5.2.6 in the Vortex OpenSplice *Deployment Guide*).
- 3. Replaying (subsets) of recorded data ‘by definition’ has an impact on an existing system:
 - (a) As it can induce unanticipated traffic flows towards subscribing applications.
 - (b) As it typically triggers application processing of such replayed data.
 - (c) Which can be considered intentional and inherent to the purpose of replaying recorded data.

Summarizing, it can be stated that when dedicating a specific computing node for Recording and Replaying and confining the control and status traffic to control the service to stay inside that node, recording the data in a multicast-enabled network is non-intrusive.



Note: The few shared topic-definitions (definitions ONLY, not actual samples of these topics when these are ‘confined’ to the RnR node) that would be visible system-wide when inspecting the built-in topics of the system (for instance with a tool like the Vortex OpenSplice Tuner) are considered not intrusive as they only imply a small amount of static data space occupied by the related built-in topic samples.)

Vortex OpenSplice Deployment Documentation

Please refer to the Vortex OpenSplice *Deployment Guide* (`OpenSplice_Deployment.pdf`) for more detailed information on how to configure Vortex OpenSplice.

The Vortex OpenSplice configuration editor (`osplconf`) provides facilities to create, modify and save configuration files. This tool is described in Section 3.2 in the Vortex OpenSplice *Deployment Guide*.

Vortex OpenSplice RnR Service Configuration Example - `ospl.xml`

In order to use the RnR service, a new service needs to be defined in the xml configuration files. In the example below, the RnR-related entries are highlighted in red.

RnR Service Configuration in `ospl.xml`



The service name in the example is `rnrService1`. A system can have many `rnr` services. The service name can be any string value.

2.1.2 RnR Manager Product Overview

The Vortex OpenSplice Record and Replay Manager, or RnR Manager, is a tool to control Vortex OpenSplice Record and Replay Services (RnR Services) and to inspect and change recorded data.

RnR Manager uses the internal Control and Monitoring API for access to the Vortex OpenSplice Middleware. Connections to local nodes *via* JNI and remote nodes (*via* SOAP) are supported. The manager tool does not need to have Vortex OpenSplice installed locally. A connection can be made remotely to a node that is running Vortex OpenSplice.

RnR Manager Features

Features provided by the RnR Manager product include:

- Control and Monitor all Recorder and Player instances in the system.
- Connect to local and remote nodes.
- Monitor RnR Service status (scenarios, storages and services).
- Record and Replay scenarios.
- Import and export recorded data.
- Query and edit recorded data.

2.2 Key Concepts

2.2.1 Services

The Vortex OpenSplice middleware `RnRService` is responsible for implementing record and replay functionality.

A system may be configured to have multiple RnR Service instances.

An RnR Service is identified by a name. This name (also known as `rnrId`) is used to address the commands to a specific RnR Service. It is defined by the 'name' attribute of the service tag in the Vortex OpenSplice configuration. For example:

```

<OpenSplice>
  <Domain>
    <Name>domain_name</Name>
    <Id>0</Id>
    <Database>
      <Size>10485670</Size>
    </Database>
    <Service name="durability">
      <Command>durability</Command>
    </Service>
    <Service name="cmsoap">
      <Command>cmsoap</Command>
    </Service>
    <Service name="rnr_service_name">
      <Command>rnr</Command>
    </Service>
  </Domain>
</RnrService name = "rnr_service_name"/>

```

Where "rnr_service_name" will be used to identify this service.

The middleware uses this identifier to resolve the configuration options that apply to the service. A Record and Replay service only accepts commands with an `rnrId` that matches its Service name. In addition, an asterisk '*' can be used as `rnrId` for commands targeted at all available RnR Services in a domain.

2.2.2 Scenarios

The actions of a Record and Replay service are organized in '*scenarios*'. Scenarios are used to logically discriminate between different recording and replay command sequences (or sessions). A scenario is an instance of the scenario topic, a group of commands sharing the same `scenarioName`.

During initialization the RnR Service starts an initial scenario, called the `BuiltinScenario`. This is a special scenario that is always running while the service is operational. RnR Manager uses the `BuiltinScenario` to configure and control the RnR Service and create new scenario topic readers for each scenario '`rr_scenarioReader_<scenarioName>`'.

A Scenario may be in one of the following states:

SCENARIO_RUNNING Scenario is active and able to receive and process commands

SCENARIO_STOPPED Scenario is stopped and unable to receive commands

SCENARIO_SUSPENDED Scenario is suspended and will resume processing commands when scenario is (re)started or continued



Note that the `BuiltinScenario` can not be stopped.

Scenario Commands

RnR commands are sent to the Scenario's `Command` topic. Supported scenario commands are: *Add Record*, *Add Replay*, *Remove Record*, *Remove Replay*, *Set Replay Speed*, *Truncate*, *Start*, *Stop* and *Suspend*.

Add Record Specify interest to record data to a storage.

Add Replay Specify interest to replay data from a storage.

Remove Record Remove record interest from a storage.

Remove Replay Remove replay interest from a storage.

Set Replay Speed Change the replay speed of a storage.

Truncate Remove data from a storage.

Start Start a scenario, or continue a suspended scenario.

Stop Stop a running scenario.

Suspend Suspend processing of new commands in a running scenario.

Config Add a storage to the service or modify properties of an existing storage.



It is important to understand that a scenario, once stopped, cannot be started again. However, it is possible to start a new scenario with the same name as the stopped scenario. If any commands of the original scenario were published as transient data they will be delivered to and processed by the new scenario, giving the impression that the scenario has been re-started.

Different versions of the scenario topic

Starting with Vortex OpenSplice RnR Manager V6.6.0, the tool interacts with two versions of the RnR service provided scenario command topic: `rr_scenario` and `rr_scenario_v2`. The new version of the topic contains support for Transformations (partition, QoS) of data during replay.

The tool will only publish commands to the `v2` command topic. If there exist scenarios from the previous version of the topic, *e.g.* from a persistent DDS store, then the tool will be able to read in the scenario commands for display in the *Scenario Editor* but if the scenario is stopped and started again from the editor, the scenario commands will be republished in the `v2` command topic, and the old topic scenario will be disposed.

Vortex OpenSplice RnR Manager expects the `rr_scenario_v2` topic to be registered by the time it needs to publish commands, *e.g.* when starting/stopping a scenario or creating a storage. If the `v2` topic is not registered, command publication will not take place. The tool does not attempt to publish commands on the old `rr_scenario` topic.

2.2.3 Storages

The RnR Service operates in conjunction with *storages*, which can be configured statically in a configuration file or dynamically through interaction with the service.

RnR Manager determines the available storages by subscribing to the storage status topic. It can be used to add new storages to a service.

Storages may have the following states:

STORAGE_READY Defined, but not opened yet.

STORAGE_OPEN Storage successfully opened and can be written to.

STORAGE_ERROR An unrecoverable error has occurred in the storage.

STORAGE_OUTOFRESOURCES The storage is out of resources.

STORAGE_CLOSED The storage has been closed and can no longer be written to.

2.2.4 Samples

The RnR Service records and replays DDS data, or *Samples*. A recorded Sample is stored in XML form in the file associated with the Storage. In addition to recording the topic data (for future replay), the RnR Service records additional Sample Information such as the Partition, Topic name, and recording time (timestamp).

When a Storage is imported into RnR Manager, the Sample data and recording information can be viewed using the *Storage Editor*.

2.2.5 Time Ranges

Time Ranges can be used to limit the selection of data in a replay session. Users can select sample data based on the recorded timestamps. A range is defined with a start and an end timestamp.

3

Installation

3.1 Pre-requisites

Vortex OpenSplice RnR Manager requires Oracle Java of at least version 1.6. OpenJDK Java is not supported.

RnR Manager does not need Vortex OpenSplice to be installed on the same system in order to control the RnR service. However, certain features of RnR Manager require a local installation of Vortex OpenSplice in order to operate. This includes connecting to a locally running Vortex OpenSplice domain using Domain URI, or Domain ID, and the storage Import/Export functions.

(Please refer to the Vortex OpenSplice *Getting Started Guide* for full details of how to install Vortex OpenSplice.)

Other information regarding recent changes to RnR Manager, or known issues are given in the *Release Notes* included with the distribution.

3.2 Supported Platforms

The RnR Manager will run on the Windows and Linux operating systems.

3.3 General Installation Instructions

To install the Vortex OpenSplice RnR Manager, start the installer and follow the on-screen instructions.

3.3.1 Installation on Unix and Linux

Unix

Linux

On Unix-based platforms (including Linux), first ensure that execute permission is enabled, then run the installer from the command line:

```
% VortexOpenSpliceRnRManager-<version>-<platform>-installer.bin
```

where <version> is the release version number and <platform> is the build for your platform.

3.3.2 Installation on Windows

Windows

On Windows-based platforms, start the installer by double-clicking on its filename in *Windows Explorer*:

```
VortexOpenSpliceRnRManager-<version>-windows-installer.exe
```

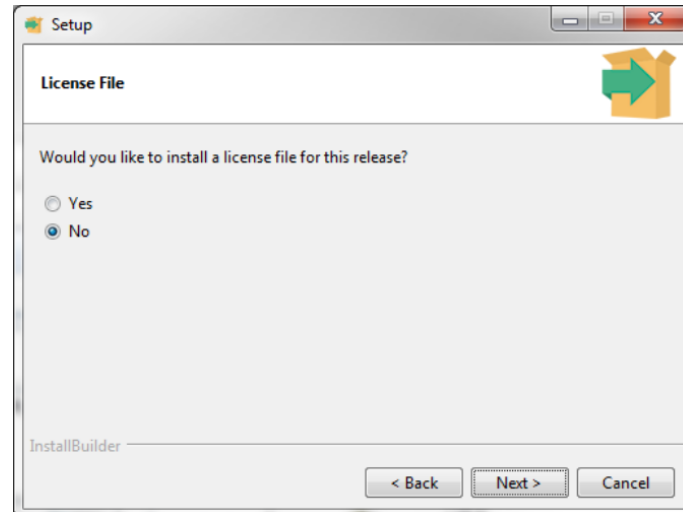
where <version> is the release version number.

3.3.3 Installing the license file

i Please refer to the Vortex OpenSplice *Getting Started Guide* for full details of how Vortex OpenSplice is licensed.

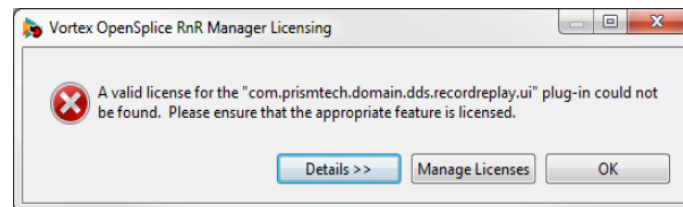
ADLINK supplies a license file for the RnR Manager product. This file is *not* included in the software distribution. During the installation, you have the option of specifying the license file.

Installing a License file



If you did not specify a license file during the installation, you will see a licensing error on startup.

License file error



Click the *Manage Licenses* button and then *Import License File*. Click the button *Restart Workbench* after importing the license file.

4

Using the Record and Replay Manager

RnR Manager does not need to be installed on a system with Vortex OpenSplice; it just needs to connect to a computer running Vortex OpenSplice with RnR Services configured.

4.1 RnR Manager Overview

4.1.1 Starting RnR Manager

RnR Manager is started by executing the `startRnRManager` script, located in the `eclipse` directory of the RnR Manager install directory. The script's purpose is to ensure the proper setting of the Vortex OpenSplice environment variables prior to application launch.

The script allows for command line options to be passed to the application. Any command line options accepted by an Eclipse application are also accepted by RnR Manager. A particularly useful option is `-data <directory>`, which allows a user to specify a custom directory use as the RnR Manager workspace, in case the default directory is shared or write protected.

Example of starting RnR Manager with a non default workspace location:

```
<path-to-RnRManager>/startRnRManager.sh -data /home/user/rnrworkspace
```

```
<path-to-RnRManager>\startRnRManager.bat -data C:\Users\user\rnrworkspace
```



Path arguments to the start script must be absolute paths.

4.1.2 Views

The RnR Manager supports various views to monitor the state of a connected domain. It also provides two editors.

These views and editors provide users with the ability to manage OSPL record and replay functionality. Additionally, record and replay data can be queried, and edited.

The views are:

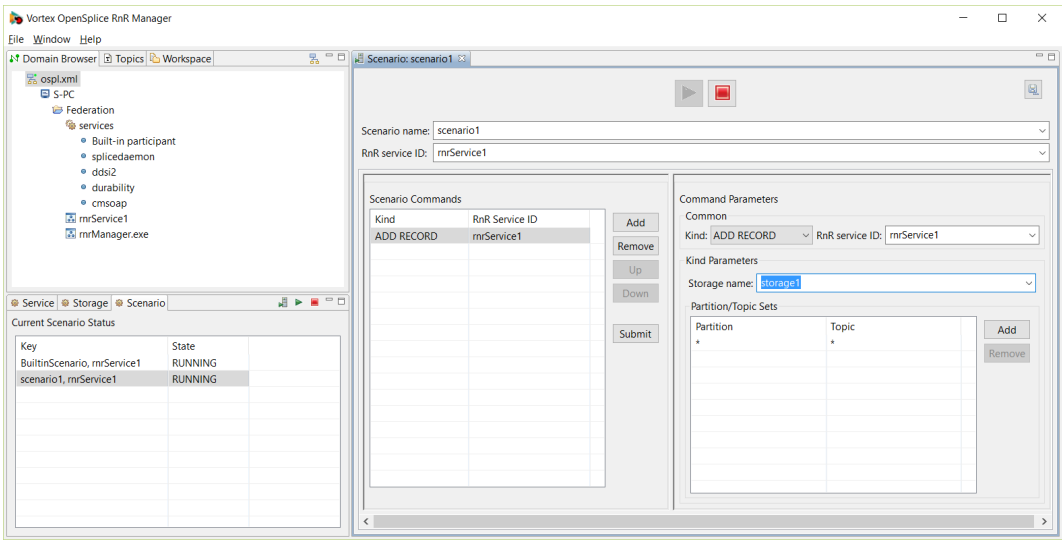
- Domain Browser
- Service Status
- Storage Status
- Scenario Status
- Imported Storages

The editors are:

- Scenario Editor
- Storage Editor

Each view and editor has a detailed section to describe its features and intended usage.

RnR Manager Overview




4.1.3 Preferences

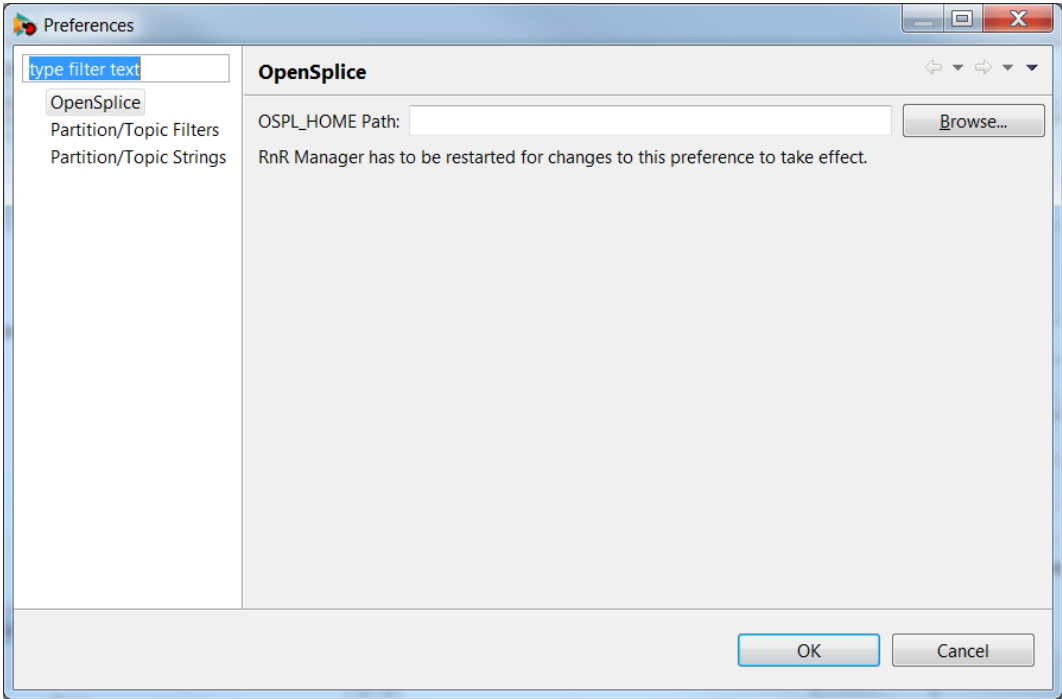
RnR Manager preferences can be set using the main Window/Preferences menu.

OpenSplice

This preference page enables you to set the `OSPL_HOME` path for the RnR Manager if one is not set for the environment.

 RnR Manager must be restarted for this preference to come into effect.

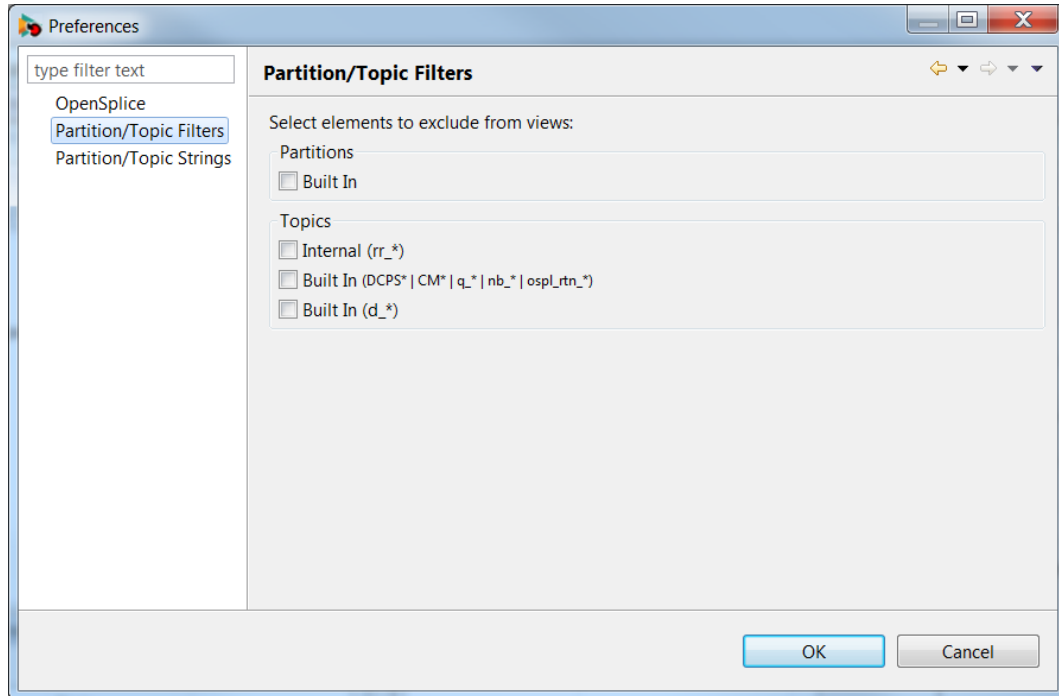
OpenSplice Preferences page



Partition/Topic Filters

The *Partition/Topic Filters* page enables you to specify which partitions and topics you would like to filter out in the general UI display. For example, any topics that are filtered out would not be seen in the in dropdowns used to list topics or in the Topics view.

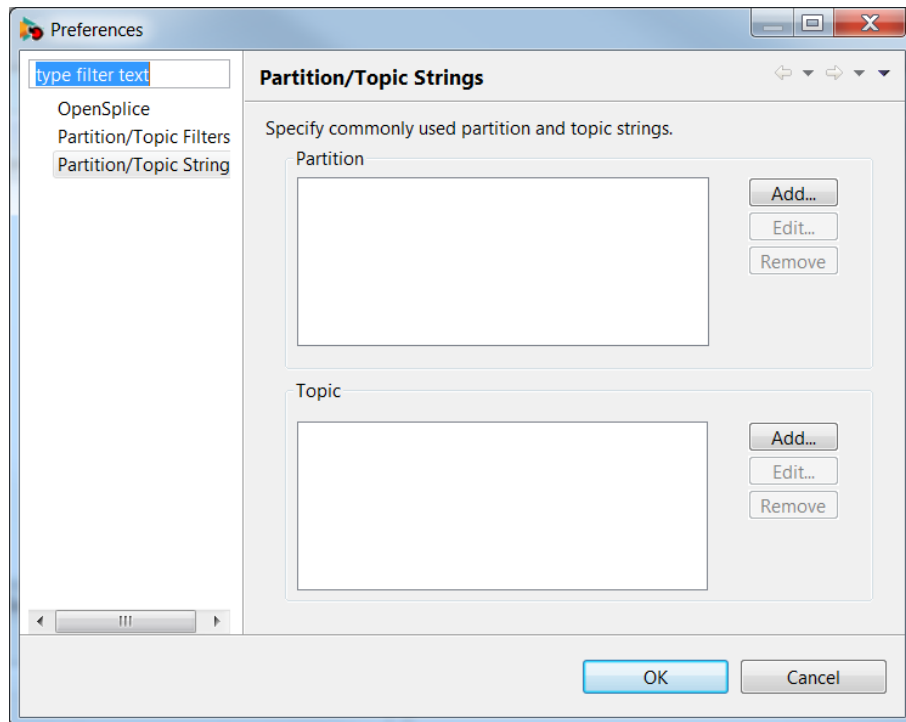
Partition/Topic Filters Preferences page



Partition/Topic Strings

The *Partition/Topic Strings* page enables you to specify partition and topic strings that are displayed in the general UI. For example, any topic strings that are added here are displayed in drop-down topic lists.

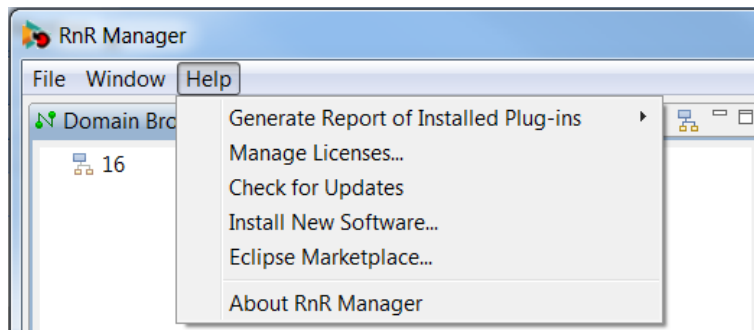
Partition/Topic Strings



4.1.4 Help

Various help actions are available from the main *Help* menu. These include actions for managing licenses, checking for updates, and product *About...* information.

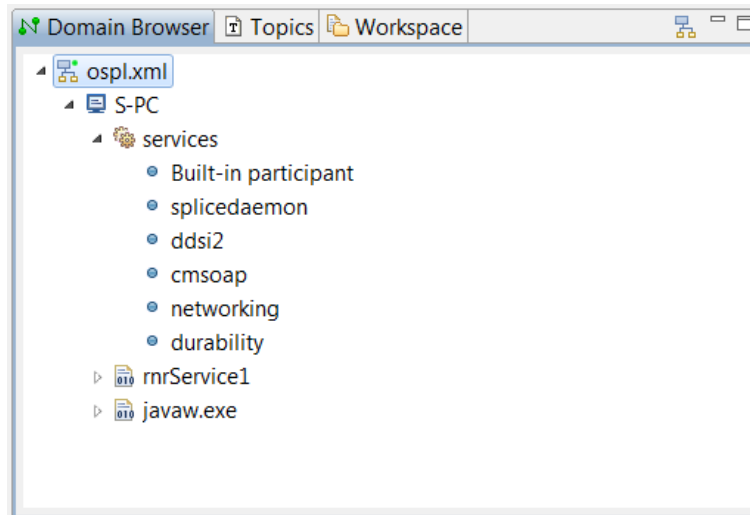
Help menu



4.2 Domain Browser

The Domain Browser is used to define and connect to a domain. It also provides information about domain nodes, and the services the nodes support.

Domain Browser



4.2.1 Defining a domain

To define an OSPL domain, click on the button in the top right corner of the Domain Browser.

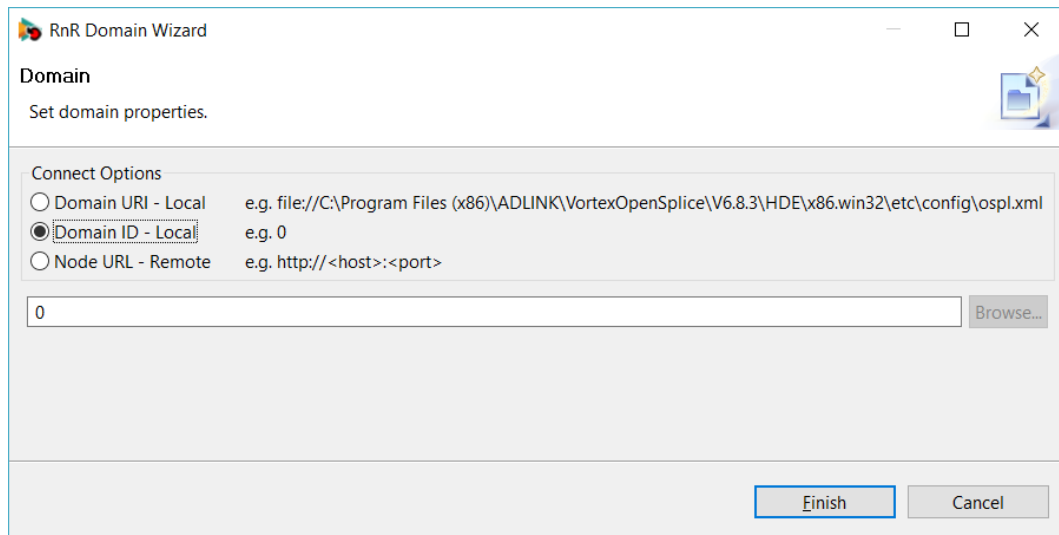
Add Domain button



The RnR Wizard dialog will open. Multiple domain connection options are provided:

- A *local* domain can be connected to using an xml file or by specifying a domain id.
- A *remote* domain can be connected to using the node URL.

RnR Domain Wizard

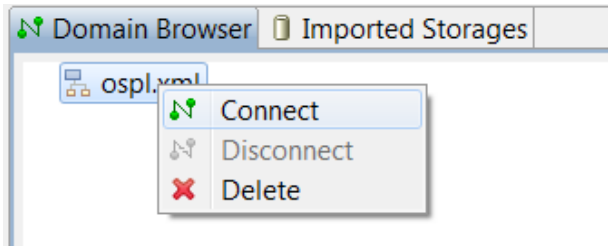



4.2.2 Domain Connect

Once a domain has been defined, an entry will appear in the Domain Browser.


To connect, double-click on the entry, or right-click to display the domain menu and choose *Connect*.

Connect to Domain



When *Connect* is clicked, an attempt is made to connect to the RnR Services of the selected domain. If successful, the domain icon will change to  and you will be able to expand the domain to browse the nodes.

RnR Manager needs to be connected to the RnR Services of a domain in order to manage the recording and/or replaying of sample data.

 RnR Manager can only connect to one domain at a time.

4.2.3 Domain Disconnect and Delete

To disconnect or delete a domain, right-click on the domain to display the *Domain* menu.

4.3 Service Status

The service status view lists the current state of the OSPL RnR services available to the currently connected domain.

The list can be sorted by *Key* or *State* by clicking on the column header.

Service Status view

Current Service Status		
Key	State	RnR Service ID / Node
mrService1	OPERATIONAL	mrService1, S-PC
mrServiceZ	OPERATIONAL	mrServiceZ, z-PC

4.4 Storage Status

The storage status view lists the current state of the OSPL RnR storages available to the currently-connected domain.

The list can be sorted by *Key* or *State* by clicking on the column header.

Storage Status view

Current Storage Status				
Key	State	File Name	Type	Max File Size (B)
storage1, mrService1	CLOSED	storage1F	CDR	0
storage2, mrService1	READY	storage2F	CDR	0
storage3, mrService1	READY	c:\DDS\storage3F	XML	2147483648

4.4.1 Creating a new storage

To create a new storage, click on the Add new storage button in the top right corner of the view to open the *Create Storage* dialog.

Add new storage button



Create Storage dialog

A wizard runs, with the input fields required for creating and configuring a new RnR storage.

The *RnR Service ID* field specifies for which service the storage will be created.

The *Storage name* field specifies what name the RnR service will recognize the storage by.

(See also *Storage Attributes* below.)

Clicking on *Finish* will create the storage. The *Storage status* view should be updated with a new entry for the newly-created storage.

Storage Attributes

When creating new storages or reconfiguring existing storages, such as when using the *Create Storage* wizard, the following attributes can be set:

File name - The file name and path on the RnR service's local filesystem in which it will keep the storage data. Relative paths are relative to the RnR service's process working directory. File names have no rules or restrictions for file extensions; file names can have any extension, or no extension if required.

Storage type - The encoding format for the storage. The file formats available are CDR (binary) and XML. The CDR format is more efficient (compact) than XML.

Max file size - The maximum size *per* storage file. When approaching the maximum size while recording, a new storage file is automatically created with a sequence number appended to the filename. The active file is also switched transparently while replaying from a storage that contains multiple data files (eg. if file name is "file", the name sequence is file, file0, file1, etc.).

Valid *max size* is any positive integer in denominations of bytes, kilobytes, megabytes, or gigabytes, up to a maximum value of $2^{64} - 1$ total bytes. Leaving the field empty, or inputting the value 0, is considered to be unlimited file size.

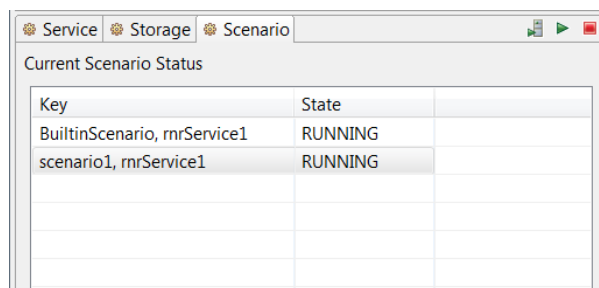
4.5 Scenario Status

Record and Replay is based on *Scenarios*. Scenarios are used to logically discriminate between different recording and replaying command sequences. A scenario is an instance of the scenario topic, a group of commands sharing the same `scenarioName`.

The *Scenario status* view lists the current state of the OSPL RnR scenarios available to the currently-connected domain.

The list can be sorted by *Key* or *State* by clicking on the column header.

Scenario Status view



Key	State
BuiltinScenario, mrService1	RUNNING
scenario1, mrService1	RUNNING

4.5.1 Open Scenario Editor

To open an empty scenario editor, click on the *Create scenario* button in top right corner of the scenario status view.

Please refer to [Scenario Editors](#) for more information on the Scenario Editor.

Create scenario button



4.5.2 Starting Scenario(s)

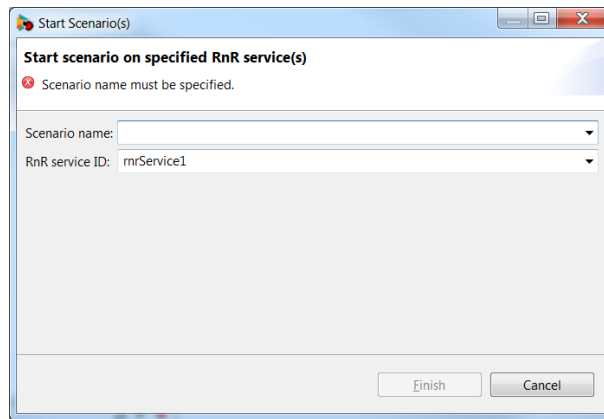
To start a scenario or set of scenarios, click on the *Start scenario(s)* button to open the *Start Scenario(s)* dialog.

Start scenario button



The wildcard character '*' (asterisk) is supported.

Start Scenario(s) dialog

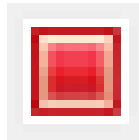


A `start scenario` command is executed using the parameters specified in the dialog.

4.5.3 Stopping Scenario(s)

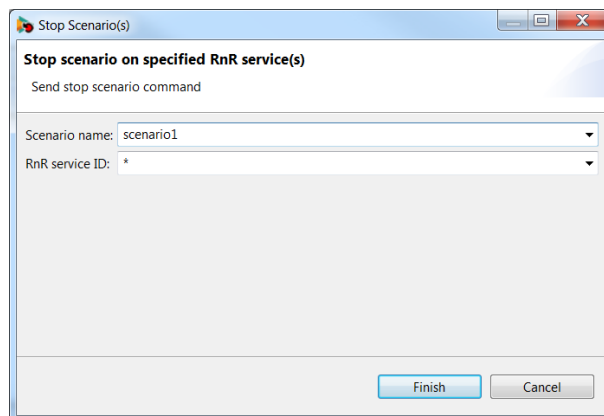
To stop a scenario or set of scenarios, click on the *Stop scenario(s)* button to open the *Stop Scenario(s)* dialog.

Stop scenario button



The wildcard character ``*'` (asterisk) is supported.

Stop Scenario(s) dialog



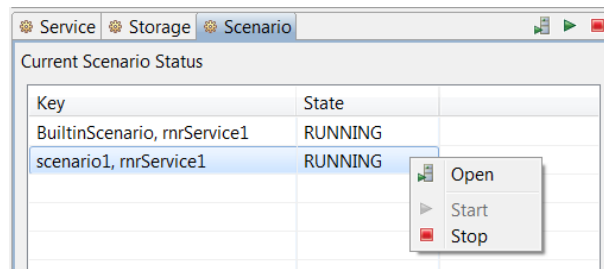
A `stop scenario` command is executed using the parameters specified in the dialog.

4.5.4 Scenario Menu

Actions are available for a scenario with a specific scenario name and `rnrID`.

To access the scenario menu, right-click on a scenario name in the scenario status table.

Scenario Menu



The scenario menu has the following options:

Open – Opens a scenario editor on the selected scenario and RnR service. Please refer to [Scenario Editors](#) for more information on the Scenario Editor.

Start – Start the selected scenario. This menu item is disabled if the scenario is already in the `RUNNING` state.

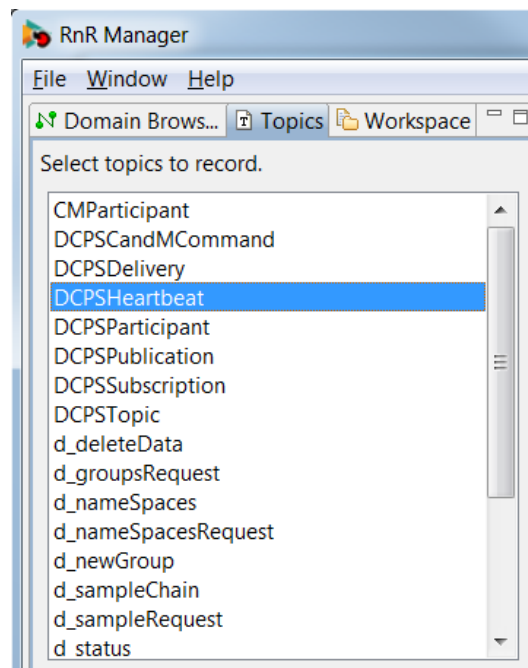
Stop – Stop the selected scenario. This menu item is disabled if the scenario is not in the `RUNNING` state.

4.6 Topics – One Click Record

The *Topics* view displays all of the DDS system topics that are available for recording. This view enables the user to start recording quickly using the *Record Topic(s)* dialog. Default parameters for the recording are provided for the selected topics.

To verify the status of the recording, the storage and scenario views can be viewed. The scenario editor can also be opened for the scenario.

The Topics list



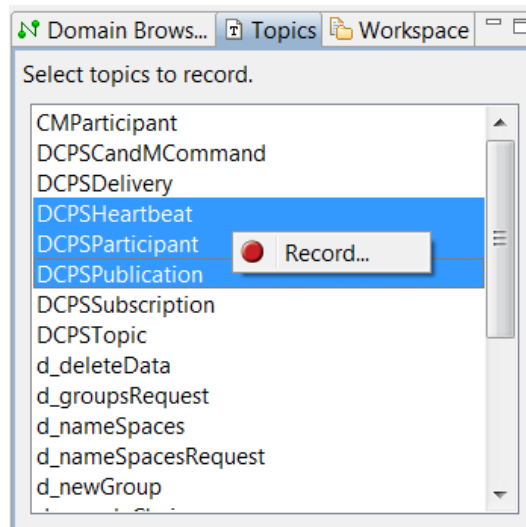
4.6.1 To Record a Topic

Step 1

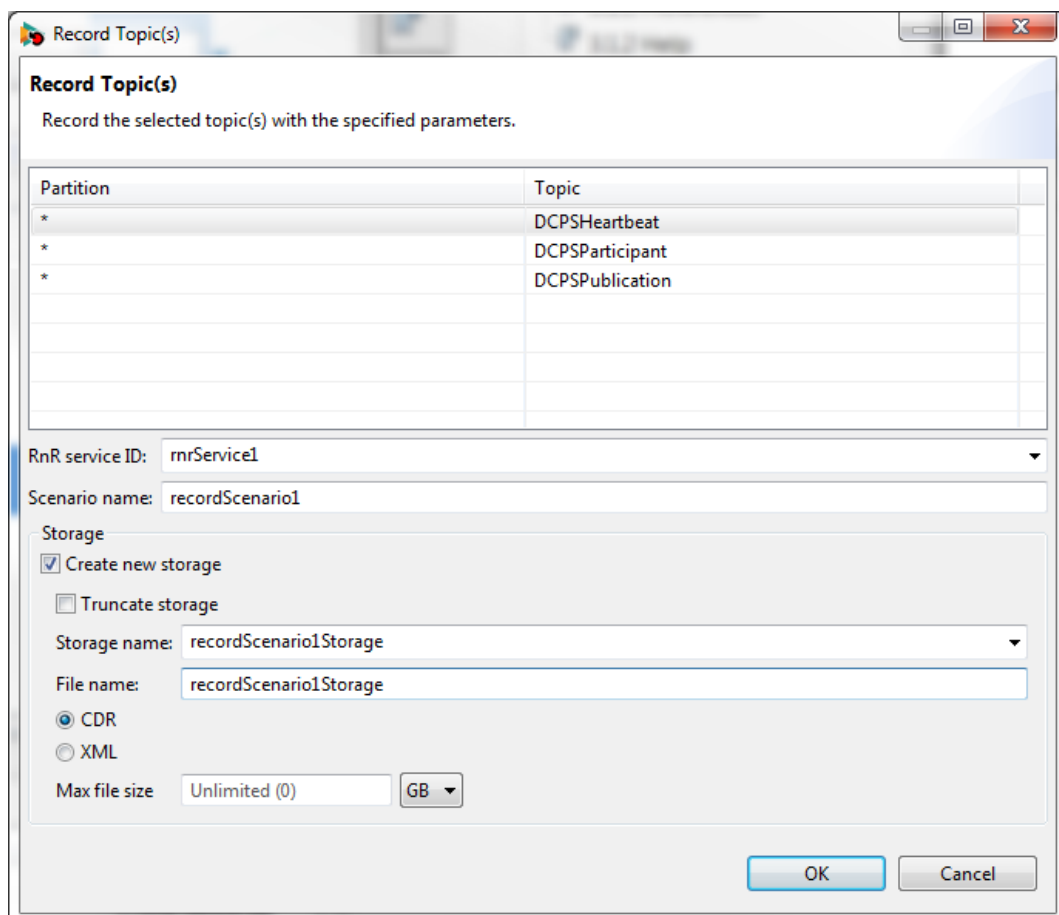
Select one or more topics to record in the topic list.

Step 2

Right-click and choose *Record...* to open the *Record Topic(s)* dialog.

Topics selected for recording**Step 3**

Modify the default parameters if required and click on *OK*.

Record Topic(s) dialog parameters**4.6.2 The Record Topic(s) Dialog**

Default parameters are provided in the dialog in order to provide 'one click' functionality. These default parameters can be edited if required.

Partition/Topic pairs

The partition/topic pairs listed in the dialog reflect the selection in the *Topics* view when the dialog is opened. The partitions can be modified by selecting from a drop-down list. The topics are not editable.

Record Topic(s) dialog Partition parameter

The fields are:

RNR Service ID – Specify the RNR Service ID parameter.

Scenario Name – Specify the scenario name. By default if one topic is chosen, a name that reflects the topic is used. Otherwise a generic record name is provided.

The currently-known scenarios in the DDS system are checked, and a scenario name is provided where no current scenarios of that name are known.

Storage Name – A default storage name is provided that matches the scenario name. If that storage is already known to the DDS system, a warning message is provided at the top of the dialog.

The storage name can be modified to be any string; a drop-down list is provided to allow for the selection of existing storages.

Truncate existing storage – If this option is checked, a `truncate` command will be added for the specified storage. Otherwise, no `truncate` command is submitted.

Create new storage – If this option is checked, the storage specified by the *Storage name* field will be created/configured with the specified storage attributes. See [Storage Attributes](#) for more information.

4.7 Scenario Editors

The actions of a Record and Replay service are organized in *scenarios*.

A scenario is an instance of the scenario topic, a group of commands sharing the same `scenarioName`. Each service subscribes to the command topic and uses a content filter to only process commands with an `rnrPid` matching the service name (or ``*'`).

It is possible to create an intricate nesting of scenarios by defining a scenario that includes control commands targeting other scenarios.

RnR Manager has two editors related to scenarios. These editors are used to view and edit the commands of a scenario.

Scenario Editor – Enables viewing, adding, and editing scenarios in the DDS system.

Scenario File Editor – Enables viewing and editing of scenario data that is persisted using an xml file. The scenarios are saved as xml, and can be loaded into the DDS system as required.

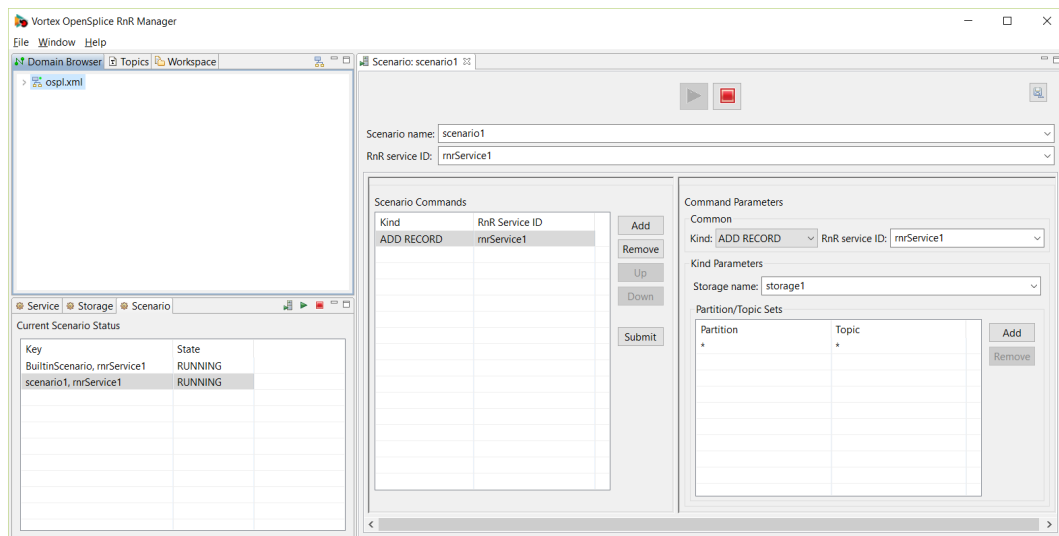
4.7.1 Overview of the Scenario Editor

The scenario editor is used to view and edit the commands of a scenario within the DDS system.

The scenario editor can be opened from the *Scenario Status* view by any of the following actions:

- double-clicking on a selected scenario in the table
- right-clicking on a selected scenario in the table and then choosing *Open*
- clicking on the *Create Scenario* button

The Scenario Editor



Scenario Editor elements:

Start and Stop buttons

The *Start* and *Stop* buttons, when clicked, submit the *Start* and *Stop* commands for the specified scenario and RnR service ID. These commands are published with a durability setting of *VOLATILE*.

Scenario name and RnR service ID

A new scenario name can be entered, or an existing scenario can be selected from the drop-down list.

Scenarios with the same scenario name can exist on multiple `rnR` services. The RnR service ID is also specified to identify the appropriate scenario. The wildcard character ``*'` (asterisk) can be used to denote all `rnR` services.

Scenario Commands

The scenario commands table displays all commands for a scenario with the specified RnR service ID.

Command Parameters

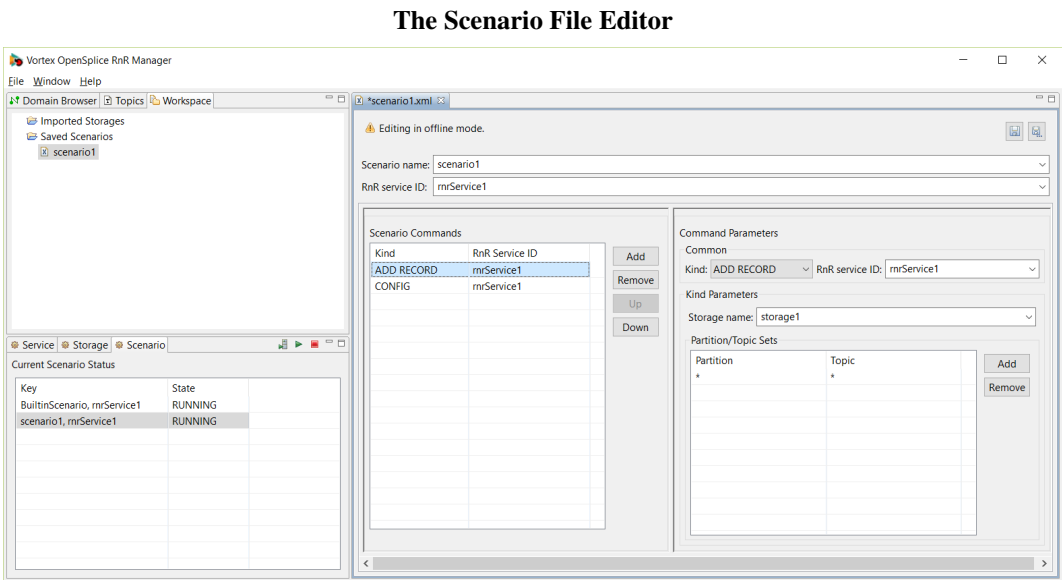
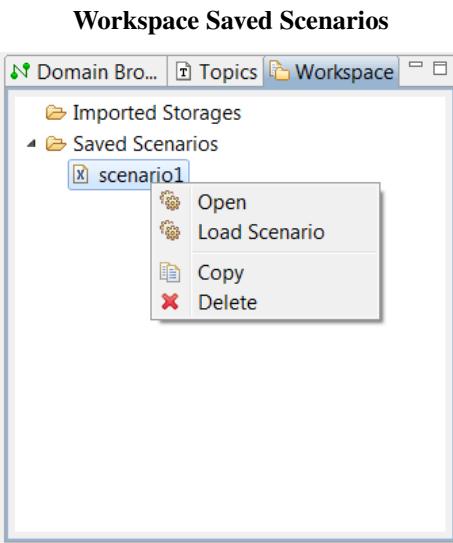
The command parameters section displays the values associated with the selected command in the scenario commands table.

4.7.2 Overview of the Scenario File Editor

The scenario file editor can be used to edit the commands of a scenario and save them to an xml file. This xml file can later be loaded and submitted to a DDS scenario.

The scenario file editor can be opened from the *Workspaces* view by any of the following actions:

- double-clicking on a scenario file (under the *Saved Scenarios* folder)
- right-clicking on a selected scenario file and then choosing *Open*



Scenario File Editor elements:

Save and *Save As...* buttons

The *Save* button saves the current xml file.

The *Save As...* button saves the scenario to a new file and opens a new scenario file editor.

Scenario name and *RnR service ID*

A new scenario name can be entered, or an existing scenario can be selected from the drop-down list.

Scenarios with the same scenario name can exist on multiple `rnr` services. The RnR service ID is also specified to identify the appropriate scenario. The wildcard character '*' (asterisk) can be used to denote all `rnr` services.

Scenario Commands

The scenario commands table displays all commands for a scenario with the specified RnR service ID.

Command Parameters

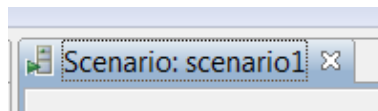
The command parameters section displays the values associated with the selected command in the scenario commands table.

4.7.3 Re-sizing the Editors

Full View

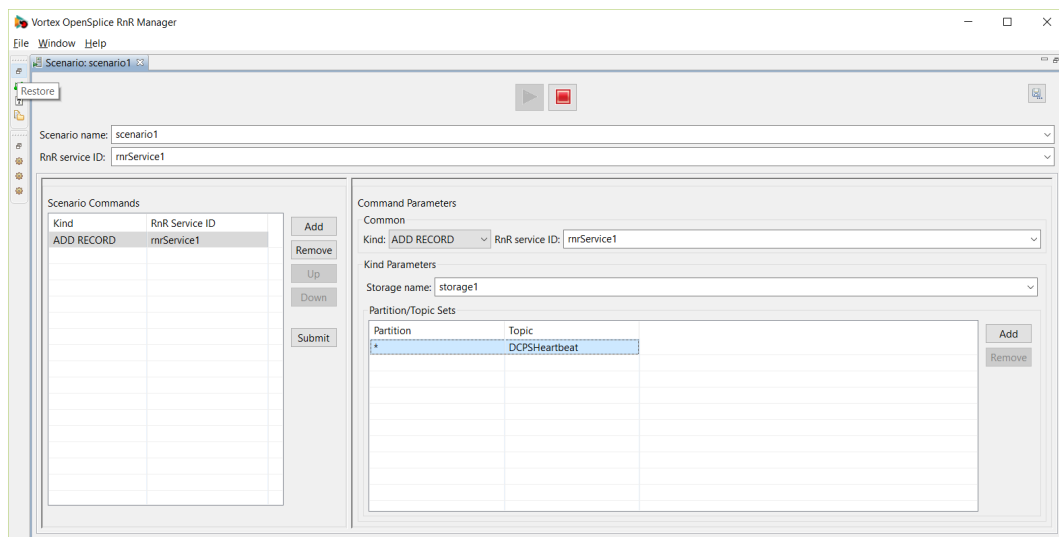
In order to maximize the view of an editor, double-click on the editor tab.

Scenario Editor tab



To restore the regular view, click on the 'restore' button, or double-click again on the editor tab.

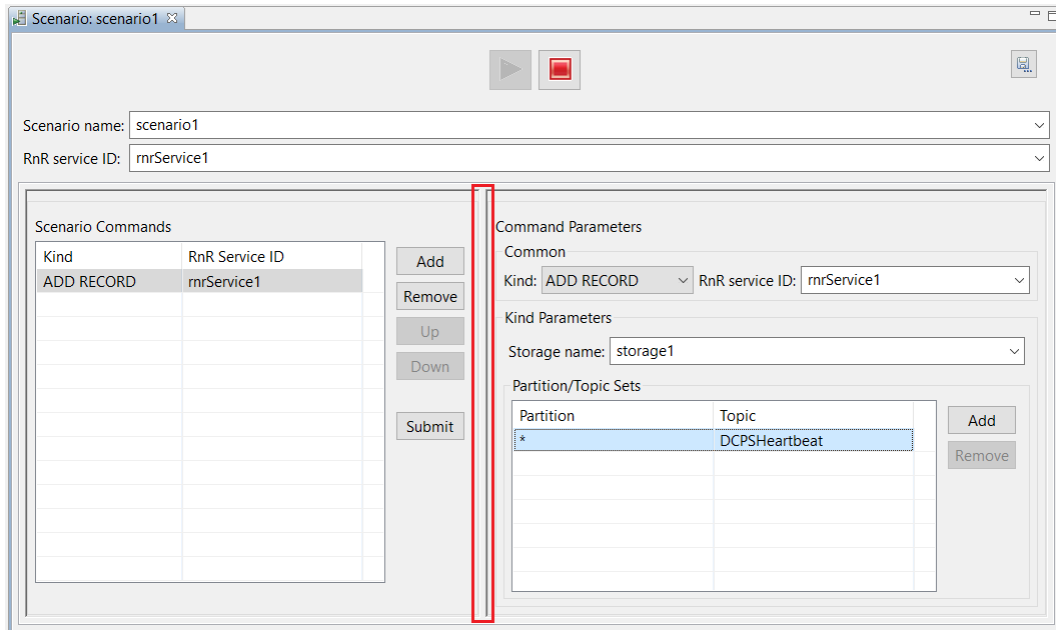
Resizing an Editor



Resize Editor groups

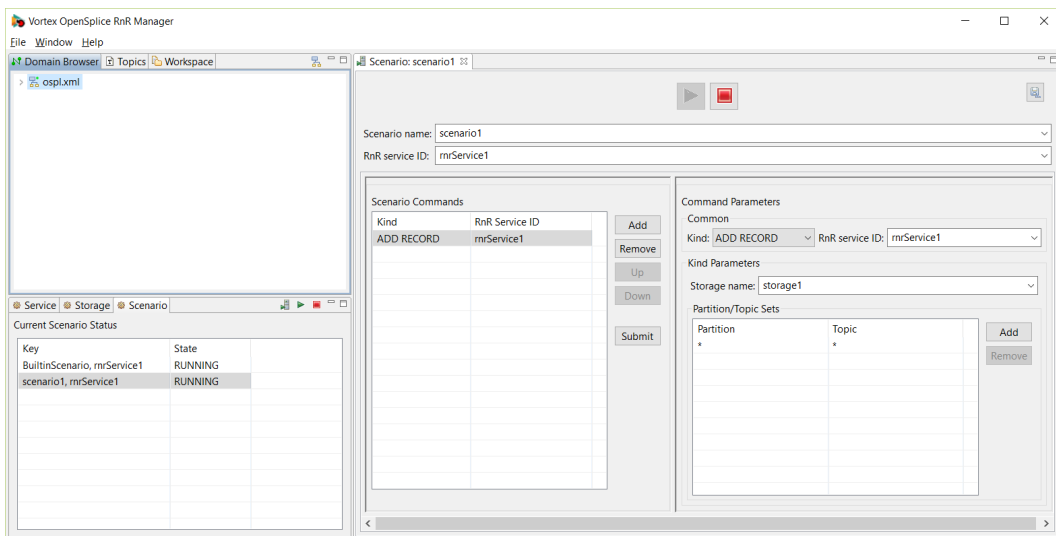
The widths of the Scenario Commands and Command Parameters groups can be changed by dragging the border with the mouse.

Resizing Editor groups



4.7.4 Scenario Editor Features

A Scenario Editor



The scenario editor displays the current state and the existing commands of a scenario in the DDS system.

- Existing commands for a specific scenario are displayed and are not editable.
- New commands can be added and submitted.

The functionality provided by the editor changes depending on the state of the scenario.

The state of a scenario can also be determined by viewing the scenario in the *Scenario Status* view.

Running vs. Stopped Scenarios

For **RUNNING** scenarios:

The *Start* button is disabled, the *Stop* button is enabled.

The *Submit* button is enabled.

Previously-submitted commands are displayed in the scenario commands table, but are 'view only'. A visual indicator of this is that the font color is light gray. These commands can not be removed or edited.

Editable and non-editable commands

Kind	RnR Service ID
STOP	mrService1
STOP	mrService1

Add
Remove
Up
Down
Submit

For STOPPED scenarios:

The *Start* button is enabled, the *Stop* button is disabled.

The *Submit* button is disabled, as it is not necessary. All commands are submitted if the *Start* button is clicked.

Previously-submitted commands displayed in the scenario commands table that were uneditable while the scenario was in the RUNNING state become editable again when in the STOPPED state.

Adding new commands

To add a new command, click on the *Add* button in the *Scenario Commands* section.

Specify the appropriate parameters for this new command in the *Command Parameters* section.

- If a scenario is already in the RUNNING state, click on the *Submit* button to submit the command or commands.
- If a scenario is in the STOPPED state, click on the *Start* button at the top of the editor to submit all the new commands and start the scenario.

A Running Scenario

The screenshot shows the Vortex OpenSplice RnR Manager interface. The 'Scenario Commands' table has the following content:

Kind	RnR Service ID
ADD RECORD	mrService1
REMOVE RECORD	mrService1

The 'Command Parameters' section shows a dropdown menu for 'Kind' with the following options: ADD RECORD, ADD REPLAY, REMOVE RECORD, REMOVE REPLAY, REPLAY SPEED, TRUNCATE, START, STOP, SUSPEND, CONFIG. The 'RnR service ID' is set to 'mrService1'.

Existing commands



Once a command has been submitted for a scenario, it cannot be deleted or edited.

Removing commands

The *Remove* button is only enabled if a command is editable.

Only newly-added commands are editable.

Ordering commands

The *Up* and *Down* buttons allow for the commands to be re-ordered, if the selected command is editable.

Alternatively, the editable selected command can be moved by dragging and dropping it in the commands table.

Only newly-added commands are editable in running Scenarios. If a scenario is stopped, then all commands can be re-ordered.

Duplicating commands

Scenario commands can be duplicated using *Copy* and *Paste* buttons available by right-clicking them to bring up the context menu.

Users can copy any command, which will copy all of the settings included in that command and place it on RnRManager's clipboard.

Users can only paste a copied command where the "Paste" context menu entry is enabled. Pasting a command will insert it after a selected command, however users cannot insert commands after already submitted commands in a running scenario; they will have to stop the scenario to do that similar to the re-ordering of the commands in the previous section.

To paste a command:

1. Select the command after which you want to insert it
2. Right click on that command
3. Press the "Paste" button

All scenario commands can be duplicated, whether they have been submitted or not in both Live and Offline mode in the Scenario Editor.

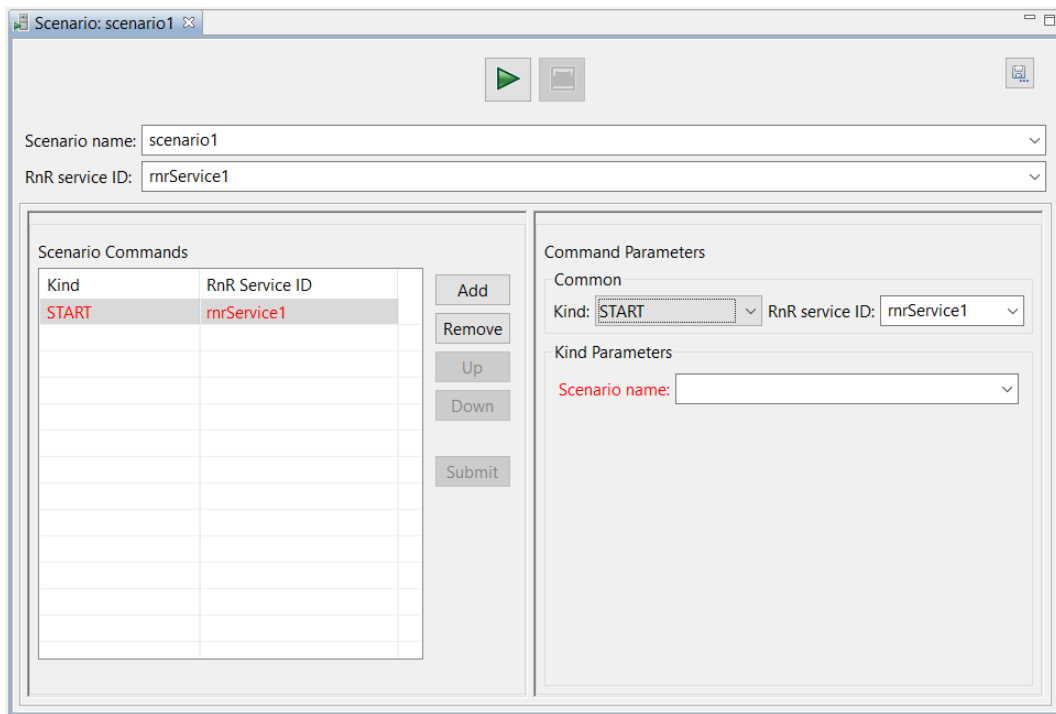
Validation

Commands that have invalid parameters are highlighted with red text in the scenario commands table. Individual invalid command parameters also have their labels highlighted with red text.

If the command is edited to correct the parameters, the entry in the scenario commands table will no longer be highlighted with red.

The *Submit* and *Start* buttons will do nothing if there are validation errors.

Invalid command parameters



Save As...

The scenario editor has a *Save As...* button in the top-right corner.

Scenario Editor *Save As...* button

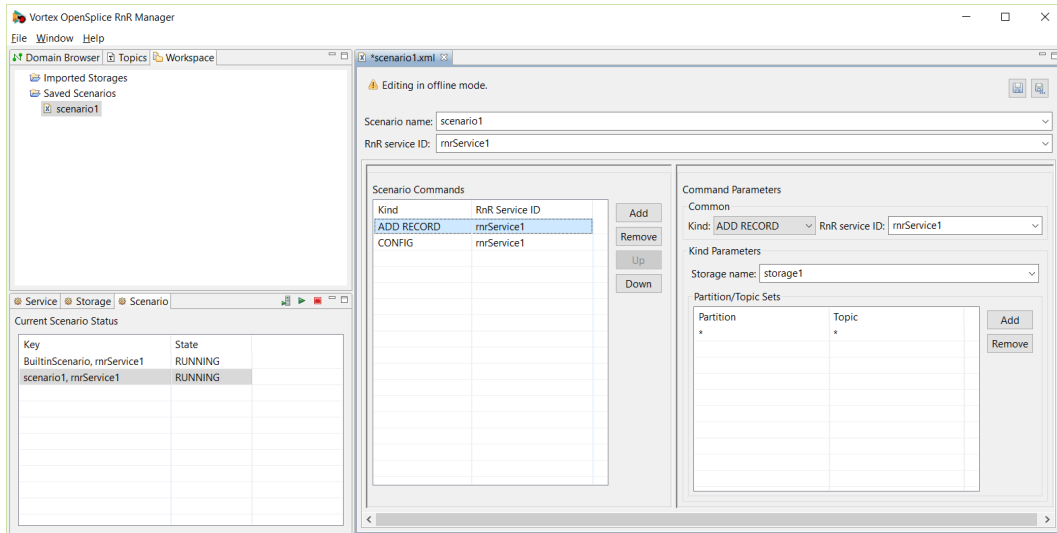


The *Save As...* functionality enables the saving of a scenario's commands and command parameters as an xml file that is not known to the DDS system.

Please refer to the next section, *Scenario File Editor Features*, for more information on saving scenarios to files.

4.7.5 Scenario File Editor Features

The Scenario File Editor



Creating New Files

Scenario Editor Save As

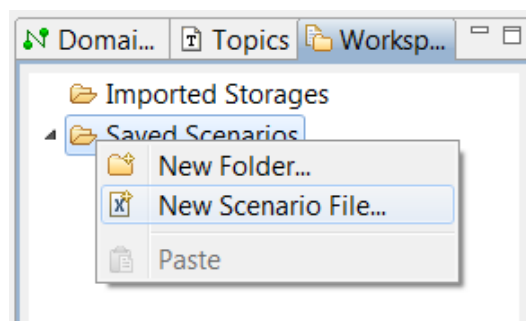
A new scenario file can be created by clicking on the *Save As...* button in the top right corner of the scenario editor. This will save the commands specified in the scenario editor to an xml file.

This allows for the saving of a specific DDS system scenario to be loaded at a later date.

New Scenario File

A new file can be created by right-clicking on a folder under the *Saved Scenarios* directory structure in the *Workspace* view and choosing *New Scenario File...*

New Scenario File



Editing Commands

- To add a new command, click on the *Add* button in the *Scenario Commands* section. Specify the appropriate parameters for this new command in the *Command Parameters* section.
- To remove a command, click on the *Remove* button in the *Scenario Commands* section.

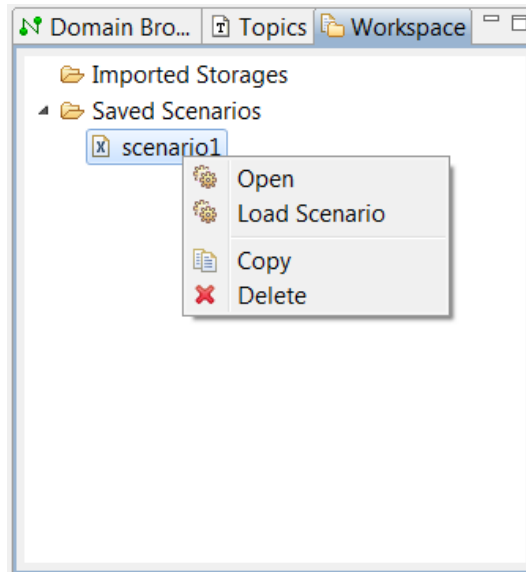
Load Scenario

A scenario file can be quickly loaded and submitted into the DDS system.

Step 1

Select the xml file, right-click and choose *Load Scenario*.

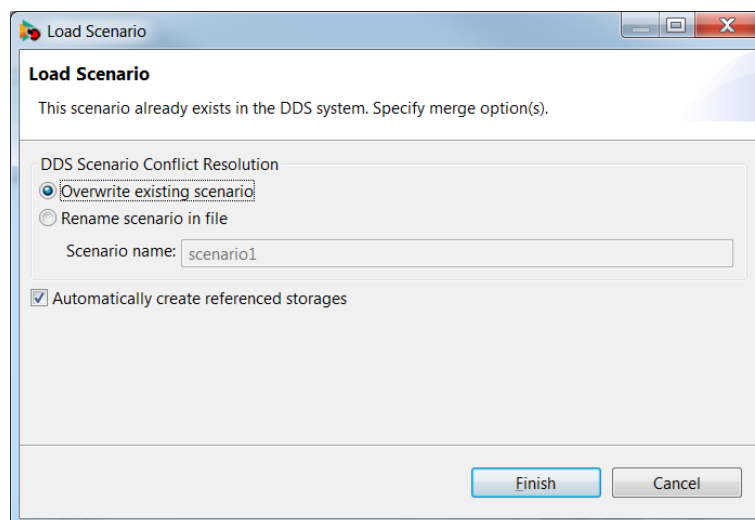
Load Scenario



Step 2

Specify merge options in the *Load Scenario* wizard.

Load Scenario wizard



If a scenario with the same name already exists, the wizard offers these merge options:

Overwrite existing scenario – The existing scenario with the same name will be stopped (if not already stopped) and disposed.

Rename scenario in file – The scenario name in the file will be changed, and that scenario name will be loaded.

Automatically create referenced storages – Create any storages referenced in the file if they do not already exist in the DDS system.

A new scenario editor opens and the commands from the file are displayed.

Step 3

Click on *Play* to submit the scenario commands to the DDS system.

Validation

Commands that have invalid parameters are highlighted with red text in the scenario commands table. Individual invalid command parameters also have their labels highlighted with red text.

If the command is edited to correct the parameters, the entry in the scenario commands table will no longer be highlighted with red.



A scenario file *can* be saved with invalid parameters.

4.7.6 Command Parameters

To view or edit the command parameters of a scenario command, choose the command in the *Scenario Commands* table. The values associated with that command will populate the scenario editor's *Command Parameters* section. If the command is editable, the parameters can be modified.

Common Parameters

Various command types are supported. To specify the command type, use the dropdown box entitled *Kind*.

The RnR service ID is also a common parameter for all command kinds.

Kind Parameters

The *Kind Parameters* section is where all the command kind-specific parameters are edited or viewed.

The command kinds supported are:

- Add Record
- Add Replay
- Remove Record
- Remove Replay
- Set Replay Speed
- Truncate
- Start
- Stop
- Suspend
- Config

Add Record

The add record command is used to specify an interest to record data to a storage.

Add Record parameters

Partition	Topic
*	DCPSHeartbeat

The parameters are:

Storage name – The name of the storage in which the data is to be stored. If the storage cannot be resolved, the command is ignored. To assist you, a dropdown list of recognized storages is provided.

Partition/Topic Sets – One or more partition/topic sets can be added to define the record interest.

Wildcards are supported: `?` will match a single character and `*` will match any number of characters. If expressions (partially) overlap, data will only be recorded once.

Add Replay

The add replay command is used to specify an interest to replay data from a storage.

Add Replay parameters

Command Parameters

Common

Kind: **ADD REPLAY** RnR service ID: **mrService1**

Kind Parameters

Storage name: **default**

☒ Use original timestamps
☐ Skip to first sample

Partition/Topic Sets Time Ranges QoS Transformations

Partition	Topic
*	DCPSHeartbeat

Add Remove

Add Replay time ranges

Partition/Topic Sets Time Ranges QoS Transformations

Start Secs	Start Nanos	End Secs	End Nanos
1377537436	0	1377537479	0

Add Remove

Add Replay QoS transformations

Partition/Topic Sets Time Ranges QoS Transformations

QoS Type	Replacement Value	Original Value
Partition	p2	p1
Transport priority	50	
Latency	10 sec 500000000 nsec	

Add Remove

The parameters are:

Storage name – The name of the storage from which the data will be replayed. If the storage cannot be resolved the command is ignored.

Use original timestamps – With the default value of `true`, when a sample is recorded, its original write and allocation timestamps are preserved. When this sample is replayed, it will be delivered to readers with these original timestamps. Depending on resource limits and QoS settings, readers may discard the replayed data if data with more recent timestamps is available. By setting `useOriginalTimestamps` to `false`, the timestamps will be updated with the current time upon replay.

Skip to first sample – By default this value is `false` and when a sample matches interest expressions but doesn't match any of the supplied time-ranges, the Record and Replay service tries to mimic original timing behaviour by sleeping until the next sample is evaluated based on record timestamps. Sometimes this is not the required behavior and the service should simply skip all non-matching samples and start replaying im-

mediately the first sample that matches an interest expression and time-range. This behaviour can be enabled by setting `skipToFirstSample` to `true`.

Partition/Topic Sets – One or more partition/topic sets can be added to define the replay interest.

Wildcards are supported: `'?'` will match a single character and `'*'` will match any number of characters. If expressions (partially) overlap, data will only be published into DDS once.

Time Ranges – Specifying time ranges is optional.

Time ranges are used in combination with partition/topic sets to select a subset of data available in a storage for replay. Each time range is applied to each partition/topic set. A sample read from a storage is only replayed if its partition/topic can be matched against the partition/topic sets and its record-time can be matched against the time-ranges. The time ranges are optional; when omitted, a sample is replayed when a partition/topic set matches.

QoS Transformations - Specifying QoS transformations is optional.

A series of transformations to apply to each sample's QoS upon replay. Transformations are only applied for replay samples that have matched the partition/topic set *AND* the time ranges (if specified). The supported transformations types and their valid values are described in the tables below.

QoS Type	Description
Partition	Partition in which the sample is replayed
Deadline	Deadline QoS policy
Latency	Latency budget QoS policy
Ownership strength	Ownership strength QoS policy (applies only to samples written with exclusive ownership-kind QoS policy)
Transport priority	Transport priority QoS policy
Lifespan	Lifespan QoS policy

QoS Type	Valid Values
Partition	Partition transformations are supported for non-empty partition names consisting of alphanumeric and special characters <code>'-'</code> , <code>'/'</code> and <code>'_'</code> .
Ownership strength Transport priority	Any positive 32 bit integer.
Deadline Latency Lifespan	A floating point value for seconds and nanoseconds. <i>eg.</i> inputting <code>10.5</code> is 10 seconds and 500000000 nanoseconds. Additionally, the string <code>"Infinite"</code> is also valid input, signifying the 'infinite' time period (2147483647.2147483647)

The string value written to the *Replacement Value* column will be the new value of the QoS policy. Optionally, values in the *Original Value* column are taken as the filter to conditionally apply the transformation; *e.g.* for a Partition transformation with *Replacement Value* `"p2"` and *Original Value* `"p1"`, all samples with partition `"p1"` will be transformed to partition `"p2"`.



Note that the original value needs to be an *exact* match; wildcards and expressions are *not* supported.

Time Range Copy and Paste

The time range record values can be copied from the storage editor and pasted into the scenario editor. Please refer to [Selected Row\(s\) Menu](#) for details of how to copy a time range.

To paste the record time range, Add a new time range. Select the time range in the Time Ranges table, and right-click and then choose Paste Record Time Range.

Paste Record Time Range

Start Secs	Start Nanos	End Secs	End Nanos
0	0	0	0

Remove Record

The remove record command is used to remove a record interest from a storage.

Remove Record parameters

Command Parameters

Common

Kind: **REMOVE RECORD** RnR service ID: mrService1

Kind Parameters

Storage name:


Partition/Topic Sets

Partition	Topic
*	DCPSHeartbeat

The parameters are:

Storage name – The name of the storage of which record-interest is removed.

Partition/Topic Sets – One or more partition/topic sets can be added to define the record interest(s) to be removed.

 Note that the partition/topic sets need to match those used previously in an add record command.

Remove Replay

The remove replay command is used to remove a replay interest from a storage.

Remove Replay parameters

Command Parameters

Common

Kind: **REMOVE REPLAY** RnR service ID: mrService1

Kind Parameters

Storage name: default


Partition/Topic Sets

Partition	Topic
*	DCPSHeartbeat

The parameters are:


Storage name – The name of the storage of which replay-interest is removed.

Partition/Topic Sets – One or more partition/topic sets can be added to define the replay interest(s) to be removed.

 Note that the partition/topic sets need to match those used previously in an add replay command.

QoS Transformations - Specifying QoS transformations is optional.

The QoS transformations to remove from the replay interest. If specified, a replay interest will no longer apply the transformation.

 If any replay interest is to be removed completely, the set of transformations should match *exactly* the set included in add_replay command(s) responsible for adding the interest.

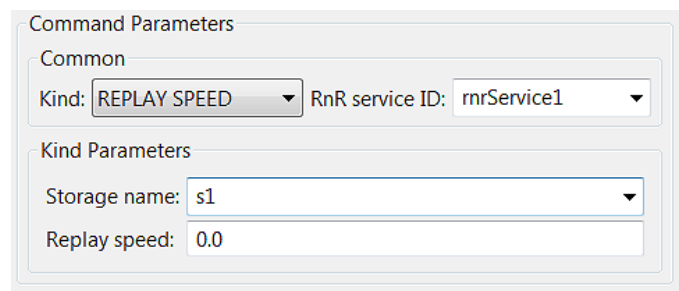
Time Ranges – Specifying time ranges is optional.

The time ranges to remove. Similar to the add replay command, this parameter is optional. If this parameter is specified, only the interest that exactly matches the time ranges is removed. As a shortcut, if no time ranges are specified, any interest that matches the interest expressions in the remove replay command is removed regardless of the time ranges attached to that interest.

Set Replay Speed

The set replay speed command is used to change the replay speed of a storage.

Replay Speed parameters



Command Parameters

Common

Kind: **REPLAY SPEED** RnR service ID: **rnrService1**

Kind Parameters

Storage name: **s1**

Replay speed: **0.0**

The parameters are:

Storage name – The name of the storage of which to change the replay speed. If the storage cannot be resolved the command is ignored.

Replay speed – Floating-point value containing the new replay-speed. The following values have a special meaning:

–1 : *Maximum speed*

Delays between samples are skipped and the samples from the storage are inserted into DDS as fast as possible.

1 : *Same speed*

Replays samples with the same timing characteristics as when originally recorded.

0 : *Pause the storage*

No samples are replayed until the speed is increased.

The default replay speed is 1 (samples are replayed with the same timing characteristics as when originally recorded).

Truncate

This command can be used to clear a storage.

When recording samples to an existing storage, the data is *appended*. If instead the required behaviour is to *overwrite* the storage, the truncate command can be used to remove the data recorded to the storage during previous sessions.



Note that the truncate command can only be executed if the storage isn't busy recording and/or replaying data. Thus it may be necessary to first publish remove record/replay commands, in order to remove all interest from a storage so that it gets closed by the RnR service, before the truncate command can be successfully processed. The *Storage Status* view can be used to verify the state of the storage.

Truncate parameter

Command Parameters

Common

Kind: **TRUNCATE** RnR service ID: **mrService1**

Kind Parameters

Storage name: **s1**

The parameter is:

Storage name – The name of the storage to clear.

Start

The start command instructs the service to start processing "scenario name". The service will publish a status update that changes the state of the scenario to **RUNNING**. If the target scenario is already known to the service, and is in the suspended state, a start command causes the scenario to resume processing commands, changing the scenario status from **SUSPENDED** to **RUNNING**.

Start parameter

Command Parameters

Common

Kind: **START** RnR service ID: **mrService1**

Kind Parameters

Scenario name: **scenario1**

The parameter is:

Scenario name – The name of the scenario to start.

Stop

The stop command stops the execution of a scenario, including any recording and/or replaying that was defined as part of that scenario.

Stop parameter

Command Parameters

Common

Kind: **STOP** RnR service ID: **mrService1**

Kind Parameters

Scenario name: **scenario1**

The parameter is:

Scenario name – The name of the scenario to stop.



It is important to understand that a scenario, once stopped, cannot be started again.

However, it is possible to start a new scenario with the same name as the stopped scenario. If any commands of the original scenario were published as transient data they will be delivered to and processed by the new scenario, giving the impression that the scenario has been re-started.

Suspend

The suspend command suspends the processing of commands by the scenario. This enables applications to submit a number of commands to a scenario, without any immediate effects. When the scenario is resumed all new commands are processed as if they were published in a batch although in reality they may have been published with varying intervals.

Suspend parameter

Command Parameters

Common

Kind: **SUSPEND** RnR service ID: **mrService1**

Kind Parameters

Scenario name: **scenario1**

The parameter is:

Scenario name – The name of the scenario to suspend.

CONFIG

The config command is used to modify the runtime configuration of an RnR service.

config : Sequence of KeyValue objects.

A config command can be used to add a storage to the service or modify properties of an existing storage. Storages can also be configured in the OpenSplice configuration file, but config commands provide the opportunity to create and configure storages dynamically.

A single config command can apply to multiple storages, if the config sequence consists of multiple elements. The key of the KeyValue object should always be 'Storage'.

CONFIG command

Command Parameters

Common

Kind: **CONFIG** RnR service ID: **mrService1**

Kind Parameters

Storage Configurations

Name	Filename	Kind	Max size	Statistics	Interval	Reset
storage1	storage1	CDR	500M	Enable	30	False
storage2	C:\storages\storage2	CDR	Unlimited (0)	N/A		

Add Remove

One or more storage configurations can be specified in the CONFIG command.

Name – The name used to identify the storage in Record and Replay commands.

Filename – The file used to store XML data. The filename may include a relative or absolute path. If a path is omitted, the storage file is created in the current working directory.

Kind – This attribute sets the format of the storage file. The data can either be stored in XML or CDR format.



Note that when changing the Kind of an existing storage it is recommended that a `TRUNCATE` command be issued first so that the storage file does not contain data of both formats.

Max file size - This optional attribute specifies a maximum storage size for individual files. Exceeding a single file size rolls the storage over to a new numbered index file. No value or 0 indicates unlimited file size. Valid input is any positive integer not greater than $2^{64} - 1$ (in bytes). The value can have a suffix to indicate magnitude: `K` (kilobyte), `M` (megabyte) or `G` (gigabyte); for example, `10M` results in 10485760 bytes. The suffix is not case sensitive.

Statistics - This optional attribute specifies whether statistics should be maintained for this storage.

Interval - This attribute specifies the publication interval of the statistics belonging to this storage, in a Record and Replay storage statistics topic. The publish interval is a value in seconds but may also be set to `-1`, which means that the statistics are published when the storage is closed. Note that a value of 0 means that statistics are never published for this storage.

Reset - This attribute enables you to reset the current values of statistics belonging to the storage. Note that this only makes sense in a configuration command for an existing storage, since new storages created from the OpenSplice configuration file always start out with empty statistics.

4.7.7 BuiltinScenario

OpenSplice BuiltinScenario

Since commands are targeted at a service and a scenario, the service must start an initial scenario. If it did not, there wouldn't be anything to address commands to.

During startup, the service starts this initial scenario, called the `BuiltinScenario`. This is a special scenario that is always running while the service is operational. It serves as the starting hook for any new scenarios. To run a new scenario, a start command must be published for the `BuiltinScenario`. Like any scenario, the `BuiltinScenario` can also process other commands like record and/or replay commands.



Note that the `BuiltinScenario` cannot be stopped.

Since one can assume that the `BuiltinScenario` is always available and running, it is a safe choice to address config and control commands to the `BuiltinScenario`. Especially in a dynamic and distributed environment, in which DDS is regularly used, this can be helpful when interacting with the service through scripts or perhaps when injecting commands stored in a persistent store.

BuiltinScenario in RnR Manager

The scenario editor disables the start and stop functionality for the `BuiltinScenario`.

Start and *Stop* actions are also disabled in the *Scenario Status* view.

4.8 Storage Data

The OpenSplice Record and Replay service enables the recording and replaying of data. The service records the data to storage xml files. These xml files can get quite large, and can be difficult to query and read.

RnR Manager provides a Storage Editor that makes it easier to query, view and update this storage data.

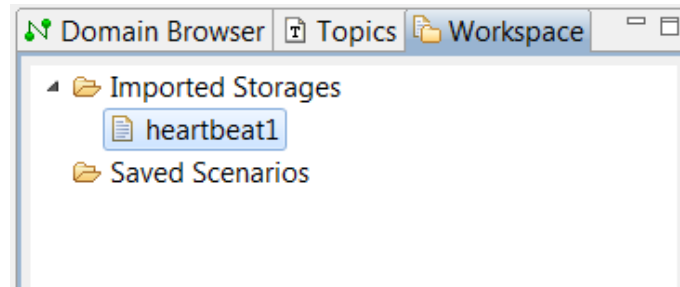
On import, the xml storage files are converted to a database file. The database can then be queried and updated. Updated data can be exported back into the OpenSplice Record and Replay service storage xml format if required.

4.8.1 Workspace - Imported Storages

The starting point for viewing storage data is the *Workspace* view.

To import storage data, navigate to the *Workspace* view and select the *Imported Storages* folder. Right-click to display a menu with options for manipulating storage database files.

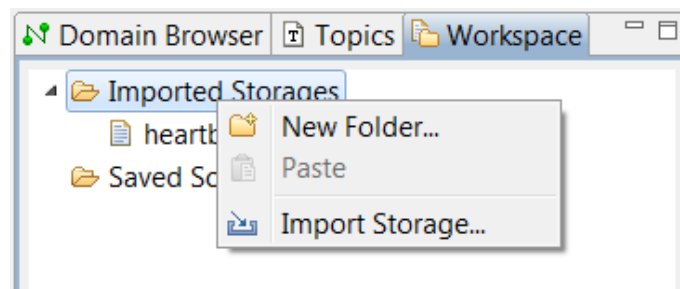
Imported Storages view



4.8.2 Database File Management

The *Imported Storages* folder displays the database files that have been imported. The files can be managed by using the menu options provided in the view. These menu options are accessible by right-clicking on the items in the view.

Imported Storages menu

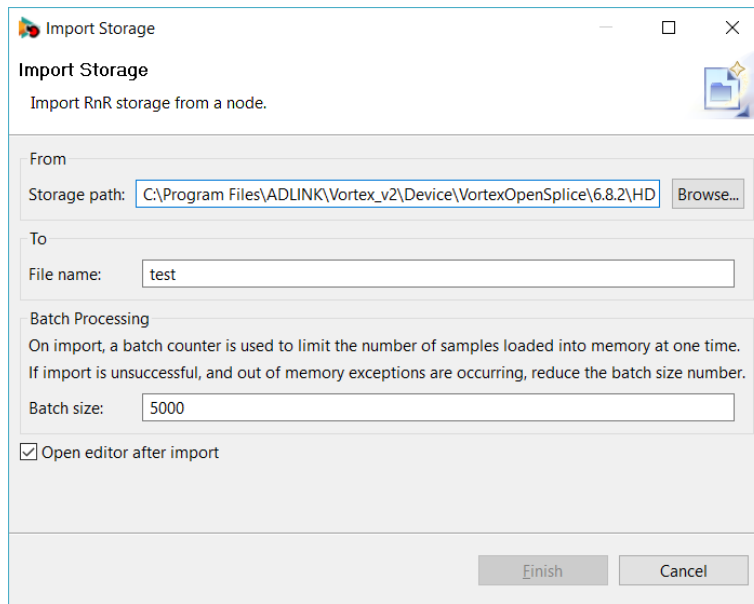


These database files are created in a workspace project maintained by the RnR Manager, which provides facilities to open, copy, paste, delete, and create new folders within this workspace.

4.8.3 Import Storage

To import OpenSplice record and replay storage data, open the *Import Storage* dialog by choosing the *Import Storage...* option from the right-click menu. (A folder must be selected in the view.)

Import Storage



To import:

Step 1

Browse to and select your local storage file.

If storage file names were configured with a relative path, the RnR service creates the storage files relative to its process working directory.

Using the file chooser, select the `.meta` file associated with the storage. The storage data file is automatically resolved.

Step 2

Specify the database file name. The file will be created in the selected folder.

Step 3

If necessary, decrease the batch size. The default batch size is 5000.

A batch counter is used to limit the number of samples loaded into memory. If the import is unsuccessful, and/or 'out of memory' exceptions are occurring, reduce the batch size number.

4.8.4 Export

To export OpenSplice record and replay storage data, open the *Export Storage* dialog by choosing the *Export Storage...* option from the right-click menu. (A database file must be selected in the view.)

On export a new OpenSplice storage is created and the sample data contained in the imported database file will be written to this storage.

Storage Parameters

The storage parameters are specified on the first page of the Export Storage wizard.

Export Storage - Create Storage

Export Storage

Create Storage

Specify the parameters to create a new storage.

To

Storage Type

☒ CDR

☐ XML

RnR service ID: rnrService1

Storage name: modifiedStorage

File name: C:\storages\modifiedStorage Browse...

Max file size: Unlimited (0) GB

Batch Processing

On export, a batch counter is used to limit the number of samples loaded into memory at one time. If export is unsuccessful, and out of memory exceptions are occurring, reduce the batch size number.

Batch size: 10000

< Back Next > Finish Cancel

If RnR Manager is currently connected to a DDS domain, the storage attributes are editable, and clicking on the *Finish* button configures a new storage with the specified storage attributes. If RnR Manager is not connected, only the file name attribute is editable, and clicking *Finish* only does the data export to file. See [Storage Attributes](#) for further information.

If necessary, decrease the batch size. The default batch size is 10000.

A batch counter is used to limit the number of samples loaded into memory. If the export is unsuccessful, and/or 'out of memory' exceptions are occurring, reduce the batch size number.

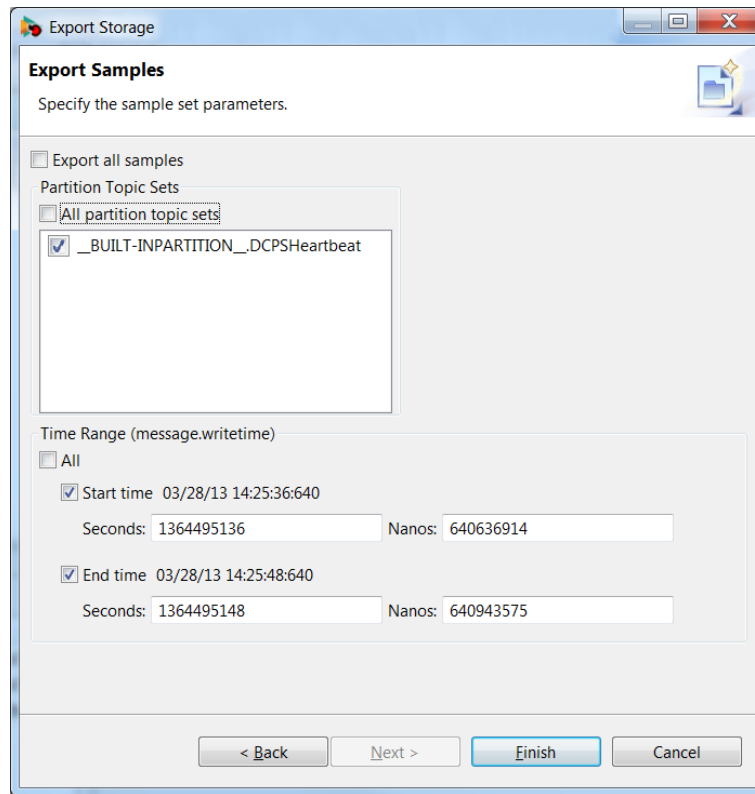
Sample Set Parameters

The second page of the wizard enables you to export a subset of the sample data contained in the database. You can also edit the actual database file to contain the appropriate subset using the storage editor. The ability to specify subset parameters is an additional feature of export.

All unique partition/topic sets of the database file are displayed. You can choose to exclude any of these sets by unchecking it the list.

Additionally you can define a time range for the export. Any data samples that do not fall within the time range are excluded.

Export Storage Samples



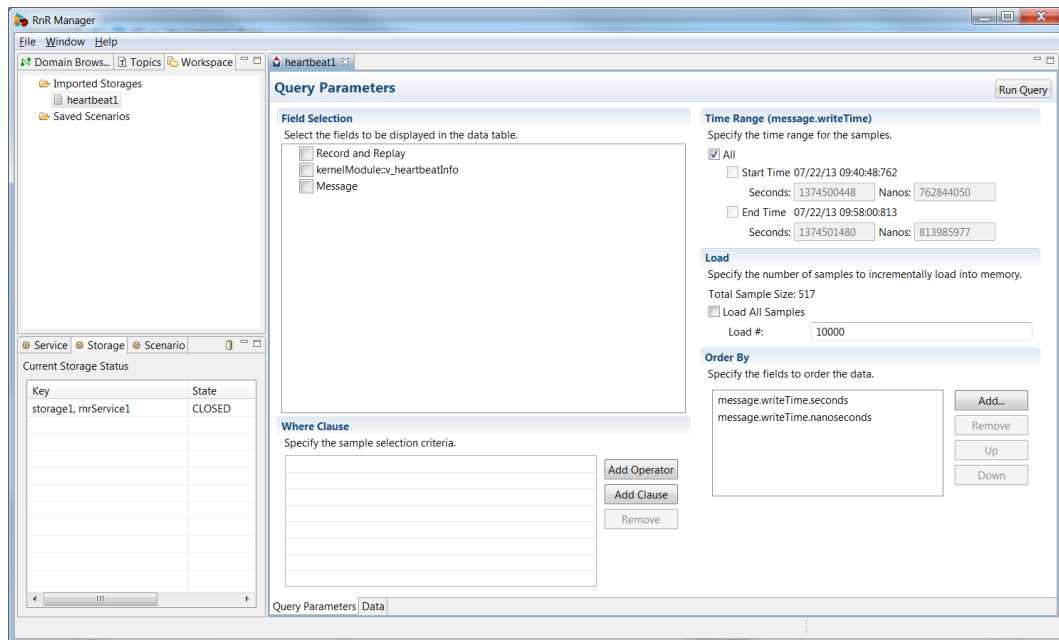
4.9 Storage Editor

Once a storage has been imported, the database file can be queried and updated using the *Storage Editor*.

The storage editor is opened by double-clicking on the database file in the *Imported Storages* folder in the *Workspace* view. It can also be opened automatically on import.

The editor is comprised of two pages. The first page is used to define the query parameters. You can specify query parameters to view subsets of the sample data. The second page displays the sample data that meet the query parameter criteria.

Storage Editor



4.9.1 Query Parameters

Field Selection

This section is used to select the data fields (columns) that you would like to see displayed in the data page table.

The *Record and Replay* node lists the fields that are written to each record and replay sample.

The *Message* node lists the fields that are written with each sample.

The other nodes contain the fields that are specific to each MetaType or topic.

Where Clause

The *where* section can be used to defined SQL-like *where* conditions.

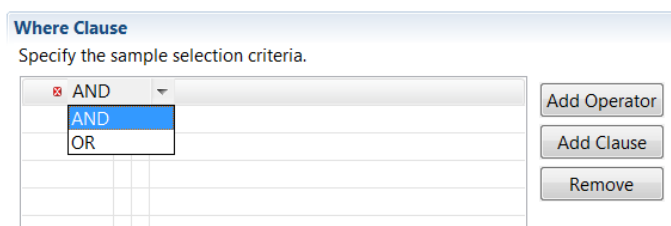
This section is optional. If no entries are added, no additional conditions are added when running the query and populating the data page.

Operator

To define a *where* condition an operator must be added. The operator can be an AND or an OR.

To add an operator, click on the *Add Operator* button. By default, AND is selected. To add OR, select the cell, then choose the OR item in the dropdown menu.

Add Operator



Each operator must have at least one child clause for the query to be valid. If this condition is not met, a red icon is displayed to indicate a problem. The *Run Query* button will not be enabled unless all validation problems on the query page are resolved.

Invalid AND

Where Clause

Specify the sample selection criteria.

✖ AND		

Clause

To add *where* selection criteria, add one or more clauses to your operator. Each clause contains a field, an operator and a value.

Field – A database field or metaType field. Available fields are provided in a dropdown list.

Clause field

OR		
✖ topic	! <Value>	
	partition	
	topic	
	recordtime.seconds	
	recordtime.nanoseconds	
	message.userData.id.systemId	

Clause Operator – Various comparison operators are available for selection in a dropdown list.

Clause Operator

Where Clause

Specify the sample selection criteria.

OR		
topic =	tbeat	
topic =		
	<>	
	>	
	<	
	>=	

Value – The expected value of the database field.

Each clause must have a defined field and value. If this condition is not met, a red icon is displayed to indicate a problem. The *Run Query* button will not be enabled unless all validation problems on the query page are resolved.

Invalid Clause

Where Clause

Specify the sample selection criteria.

AND		
✖ <Field> = ✖ <Value>		

Add Operator

Add Clause

Remove

Valid Condition

Where Clause
Specify the sample selection criteria.

OR			
topic =	DCPSHeartbeat		
topic =	circle		

Add Operator
Add Clause
Remove

Time Range (message.writeTime)

By default the time range is set to all times. A start and/or end time can be defined to query samples within a specific time range.

Load

Many of the storage files have a large amount of data. For larger files, it is not always possible to load all of the data into memory. For these cases, samples can be incrementally loaded into memory.

The number of samples to load at a time is specified in the `Load #` field.

You can then use the *Next* and *Previous* buttons on the data page to view the samples incrementally.



Note: Any edits made to loaded data will **not** be retained when the *Next* and *Previous* buttons are clicked. Such edits must be saved explicitly prior to loading next or previous samples.

Order By

The data display can be ordered by data fields. By default, the order is done using the `message.writeTime` fields. You can add any data field to the order by criteria.

Data

The data page contains one table that displays the samples that meet the query criteria. Each row is one sample.

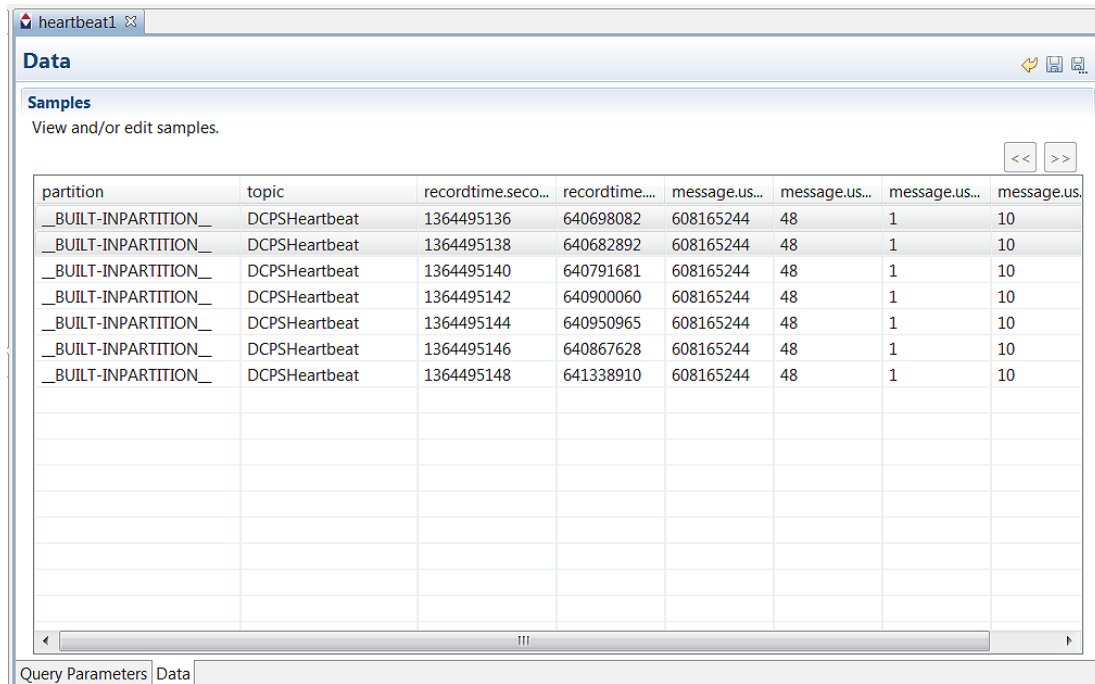
The columns are resizable. The columns can also be re-ordered by dragging them in the table.

To get the full name of the column, hover on the column header with the mouse.

Values can be edited in the table on a *per cell* basis.

To change the data that is displayed, specify different query parameters on the query page, and click on the *Run Query* button.

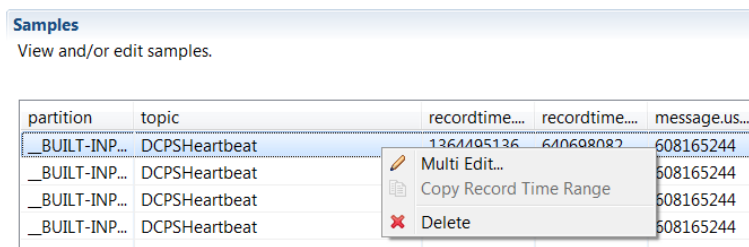
Data page



Selected Row(s) Menu

Actions are available for the table's selected row(s). These actions are accessed by using right-click.

Data table actions

**Multi Edit...**

The table supports editing a selected row's field value.

However, if a batch change is required, it is not possible to do it in the table itself. The *Multi Edit* dialog provides support for batch changes.

Step 1

Select the rows you would like to edit in the table.

Step 2

Right-click and choose the *Multi Edit...* action.

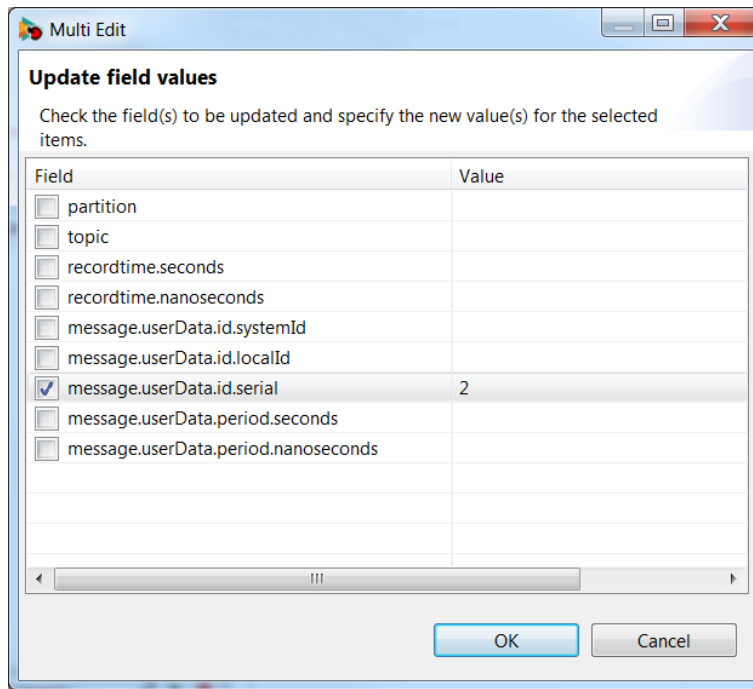
Step 3

Check the field(s) you would like to batch update.

Step 4

Specify the value(s) to be applied to all the selected rows.

Multi Edit dialog



Copy Record Time Range

This action is enabled when more than one row is selected. It is used in conjunction with the scenario editor.

The record time of the first and last selected row are saved. These values can be pasted into the scenario editor for a replay command. Please refer to [Add Replay](#) for details of how to paste the values into the scenario editor.

Delete

The delete action deletes all selected rows.

Next and Previous

The *Next* and *Previous* buttons are enabled when the samples are being loaded incrementally.

Please see [Load](#) for details of load functionality.

Next and Previous buttons



Undo, Save and Save As...

Undo, Save, and Save As... buttons



The buttons are:

Undo — Undo all changes to the database file since the last save.

Save — Save all changes to the database file.

Save As... — Save the currently loaded samples into a new database file.

5

Contacts & Notices

5.1 Contacts

ADLINK Technology Corporation

400 TradeCenter
Suite 5900
Woburn, MA
01801
USA
Tel: +1 781 569 5819

ADLINK Technology Limited

The Edge
5th Avenue
Team Valley
Gateshead
NE11 0XA
UK
Tel: +44 (0)191 497 9900

ADLINK Technology SARL

28 rue Jean Rostand
91400 Orsay
France
Tel: +33 (1) 69 015354

Web: <http://ist.adlinktech.com/>

Contact: <http://ist.adlinktech.com>

E-mail: ist_info@adlinktech.com

LinkedIn: <https://www.linkedin.com/company/79111/>

Twitter: https://twitter.com/ADLINKTech_usa

Facebook: <https://www.facebook.com/ADLINKTECH>

5.2 Notices

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