

EnOcean Equipment Profiles (EEP)

Version: 2.6.4 - Dec 17, 2015

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■ A5-12-04: Temperature and Load Sensor ■ A5-12-05: Temperature and Container Sensor

■ A5-12-10: Current meter 16 channels

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             ■ A5-3F-7F: Universal
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■ D2-01-01: Type 0x01 (description: see table)
             ■ D2-01-02: Type 0x02 (description: see table)
             ■ D2-01-03: Type 0x03 (description: see table)
             ■ D2-01-04: Type 0x04 (description: see table)
             ■ D2-01-05: Type 0x05 (description: see table)
             ■ D2-01-06: Type 0x06 (description: see table)
             ■ D2-01-07: Type 0x07 (description: see table)
             ■ D2-01-08: Type 0x08 (description: see table)
             ■ D2-01-09: Type 0x09 (description: see table)
             ■ D2-01-0A: Type 0x0A (description: see table)
             ■ D2-01-0B: Type 0x0B (description: see table)
             ■ D2-01-0C: Type 0x0C
             ■ D2-01-0D: Type 0x0D
             ■ D2-01-0E: Type 0x0E
             ■ D2-01-0F: Type 0x0F
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■ D2-01-11: Type 0x11 (description: see table)
             ■ D2-01-12: Type 0x12
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             ■ D2-02-00: Type 0x00
             ■ D2-02-01: Type 0x01 (description: see table)
             ■ D2-02-02: Type 0x02 (description: see table)
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             ■ D2-03-00: Type 0x00
             ■ D2-03-10: Mechanical Handle
      5. D2-04: CO2, Humidity, Temperature, Day/Night and Autonomy
             ■ D2-04-00: Type 0x00
             ■ D2-04-01: Type 0x01 (description: see table)
             ■ D2-04-02: Type 0x02 (description: see table)
             ■ D2-04-03: Type 0x03 (description: see table)
             ■ D2-04-04: Type 0x04 (description: see table)
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■ D2-04-05: Type 0x05 (description: see table)

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■ D2-04-06: Type 0x06 (description: see table)
                    ■ D2-04-07: Type 0x07 (description: see table)
                    ■ D2-04-08: Type 0x08 (description: see table)
                    ■ D2-04-09: Type 0x09 (description: see table)
                    ■ D2-04-10: Type 0x10 (description: see table)
                    ■ D2-04-1A: Type 0x1A (description: see table)
                    ■ D2-04-1B: Type 0x1B (description: see table)
                    ■ D2-04-1C: Type 0x1C (description: see table)
                    ■ D2-04-1D: Type 0x1D (description: see table)
                    ■ D2-04-1E: Type 0x1E (description: see table)
             6. D2-05: Blinds Control for Position and Angle
                    ■ D2-05-00: Type 0x00
             7. D2-06: Multisensor Window Handle
                    ■ D2-06-01: Alarm, Position Sensor, Vacation Mode, Optional Sensors
             8. D2-10: Room Control Panels with Temperature & Fan Speed Control, Room Status Information
               and Time Program
                    ■ D2-10-00: Type 0x00
                   ■ D2-10-01: Type 0x01
■ D2-10-02: Type 0x02
             9. D2-20: Fan Control
                    ■ D2-20-00: Type 0x00
                    ■ D2-20-01: Type 0x01
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■ D2-30-02: Type 0x02 (description: see table)
■ D2-30-03: Type 0x03 (description: see table)
                    ■ D2-30-04: Type 0x04 (description: see table)
                    ■ D2-30-05: Type 0x05 (description: see table)
                    ■ D2-30-06: Type 0x06 (description: see table)
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                    ■ D2-31-01: Type 0x01 (description: see table)
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                    ■ D2-32-00: Type 0x00
                    ■ D2-32-01: Type 0x01
                    ■ D2-32-02: Type 0x02
           13. D2-40: LED Controller Status
                    ■ D2-40-00: Type 0x00
                    ■ D2-40-01: Type 0x01
           14. D2-50: Heat Recovery Ventilation
                    ■ D2-50-00: Type 0x00
                    ■ D2-50-01: Type 0x01 (description: see table)
           15. D2-A0: Standard Valve
                    ■ D2-A0-01: Valve Control (BI-DIR)
3. Appendix
      1. RPS Teach-in
      2. 1BS Teach-in
      3. 4BS Teach-in
      4. Smart Ack Teach-in (without repeater)
      5. Smart Ack Teach-in (with repeater)
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      8. Smart Ack: functional principle (with repeater)
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     11. Existing 'bidirectional' profile structures
     12. MSC telegram - Manufacturer Specific Communication
     13. Manufacturer ID's
     14. XML + DOC Maintenance process
             1. General
             2. XML file
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1) Introduction

15. Revision

EEP 2.6.4 Specification © EnOcean Alliance

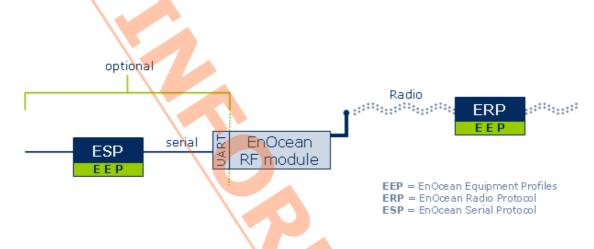
1.1) Terms, Abbreviations

EnOcean 1 Byte Communication BAS		
BAS Building Automation System Choice Unique identification of EnOcean radio telegram types (RPS, 1BS, 4BS,); equivalent with RORG Client Bidirectional Smart Ack Device Data Payload of ERP telegrams or ESP packets EEP EnOcean Equipment Profiles ERP EnOcean Radio Protocol ESP EnOcean Serial Protocol HTML Hyper Text Markup Language; HTML can be displayed using a internet browser MSC Manufacturer Specific Communication N/A Not applicable ORG Organizational number for EnOcean radio telegram types (out-dated with EEP 2.1; used for ESP2 interface RORG Radio ORG = organization number for EnOcean radio telegram types (new with EEP 2.1); equivalent with 'Choice' RMCC Remote Management Control Commands RPC Remote Procedure Calls	1BS	EnOcean 1 Byte Communication
Choice Unique identification of EnOcean radio telegram types (RPS, 1BS, 4BS,); equivalent with RORG Client Bidirectional Smart Ack Device Data Payload of ERP telegrams or ESP packets EEP EnOcean Equipment Profiles ERP EnOcean Radio Protocol ESP EnOcean Serial Protocol HTML Hyper Text Markup Language; HTML can be displayed using a internet browser MSC Manufacturer Specific Communication N/A Not applicable ORG Organizational number for EnOcean radio telegram types (out-dated with EEP 2.1; used for ESP2 interface RORG Radio ORG = organization number for EnOcean radio telegram types (new with EEP 2.1); equivalent with 'Choice' RMCC Remote Management Control Commands RPC Remote Procedure Calls	4BS	EnOcean 4 Byte Communication
Client Bidirectional Smart Ack Device Data Payload of ERP telegrams or ESP packets EEP EnOcean Equipment Profiles ERP EnOcean Radio Protocol ESP EnOcean Serial Protocol HTML Hyper Text Markup Language; HTML can be displayed using a internet browser MSC Manufacturer Specific Communication N/A Not applicable ORG Organizational number for EnOcean radio telegram types (out-dated with EEP 2.1; used for ESP2 interface RORG Radio ORG = organization number for EnOcean radio telegram types (new with EEP 2.1); equivalent with 'Choice' RMCC Remote Management Control Commands RPC Remote Procedure Calls	BAS	Building Automation System
Data Payload of ERP telegrams or ESP packets EEP EnOcean Equipment Profiles ERP EnOcean Radio Protocol ESP EnOcean Serial Protocol HTML Hyper Text Markup Language; HTML can be displayed using a internet browser MSC Manufacturer Specific Communication N/A Not applicable ORG Organizational number for EnOcean radio telegram types (out-dated with EEP 2.1; used for ESP2 interface RORG Radio ORG = organization number for EnOcean radio telegram types (new with EEP 2.1); equivalent with 'Choice' RMCC Remote Management Control Commands RPC Remote Procedure Calls	Choice	Unique identification of EnOcean radio telegram types (RPS, 1BS, 4BS,); equivalent with RORG
EEP EnOcean Equipment Profiles ERP EnOcean Radio Protocol ESP EnOcean Serial Protocol HTML Hyper Text Markup Language; HTML can be displayed using a internet browser MSC Manufacturer Specific Communication N/A Not applicable ORG Organizational number for EnOcean radio telegram types (out-dated with EEP 2.1; used for ESP2 interface RORG Radio ORG = organization number for EnOcean radio telegram types (new with EEP 2.1); equivalent with 'Choice' RMCC Remote Management Control Commands RPC Remote Procedure Calls	Client	Bidirectional Smart Ack Device
ERP EnOcean Radio Protocol ESP EnOcean Serial Protocol HTML Hyper Text Markup Language; HTML can be displayed using a internet browser MSC Manufacturer Specific Communication N/A Not applicable ORG Organizational number for EnOcean radio telegram types (out-dated with EEP 2.1; used for ESP2 interface RORG Radio ORG = organization number for EnOcean radio telegram types (new with EEP 2.1); equivalent with 'Choice' RMCC Remote Management Control Commands RPC Remote Procedure Calls	Data	Payload of ERP telegrams or ESP packets
ESP EnOcean Serial Protocol HTML Hyper Text Markup Language; HTML can be displayed using a internet browser MSC Manufacturer Specific Communication N/A Not applicable ORG Organizational number for EnOcean radio telegram types (out-dated with EEP 2.1; used for ESP2 interface RORG Radio ORG = organization number for EnOcean radio telegram types (new with EEP 2.1); equivalent with 'Choice' RMCC Remote Management Control Commands RPC Remote Procedure Calls	EEP	EnOcean Equipment Profiles
HTML Hyper Text Markup Language; HTML can be displayed using a internet browser MSC Manufacturer Specific Communication N/A Not applicable ORG Organizational number for EnOcean radio telegram types (out-dated with EEP 2.1; used for ESP2 interface RORG Radio ORG = organization number for EnOcean radio telegram types (new with EEP 2.1); equivalent with 'Choice' RMCC Remote Management Control Commands RPC Remote Procedure Calls	ERP	EnOcean Radio Protocol
MSC Manufacturer Specific Communication N/A Not applicable ORG Organizational number for EnOcean radio telegram types (out-dated with EEP 2.1; used for ESP2 interface RORG Radio ORG = organization number for EnOcean radio telegram types (new with EEP 2.1); equivalent with 'Choice' RMCC Remote Management Control Commands RPC Remote Procedure Calls	ESP	EnOcean Serial Protocol
N/A Not applicable ORG Organizational number for EnOcean radio telegram types (out-dated with EEP 2.1; used for ESP2 interface RORG Radio ORG = organization number for EnOcean radio telegram types (new with EEP 2.1); equivalent with 'Choice' RMCC Remote Management Control Commands RPC Remote Procedure Calls	HTML	Hyper Text Markup Language; HTML can be displayed using a internet browser
ORG Organizational number for EnOcean radio telegram types (out-dated with EEP 2.1; used for ESP2 interface RORG Radio ORG = organization number for EnOcean radio telegram types (new with EEP 2.1); equivalent with 'Choice' RMCC Remote Management Control Commands RPC Remote Procedure Calls	MSC	Manufacturer Specific Communication
RORG Radio ORG = organization number for EnOcean radio telegram types (new with EEP 2.1); equivalent with 'Choice' RMCC Remote Management Control Commands RPC Remote Procedure Calls	N/A	Not applicable
'Choice' RMCC Remote Management Control Commands RPC Remote Procedure Calls	ORG	Organizational number for EnOcean radio telegram types (out-dated with EEP 2.1; used for ESP2 interface)
RPC Remote Procedure Calls	RORG	
	RMCC	Remote Management Control Commands
RPS EnOcean telegram type for Repeated Switch Communication	RPC	Remote Procedure Calls
	RPS	EnOcean telegram type for Repeated Switch Communication
Smart Acknowledge EnOcean standard for energy-optimized bidirectional transmission		Smart Acknowledge EnOcean standard for energy-optimized bidirectional transmission
Ack		
UART Universal Asynchronous Receiver Transmitter	UART	Universal Asynchronous Receiver Transmitter
VLD EnOcean Variable Length Data telegram	VLD	EnOcean Variable Length Data telegram
XML Extensible Markup Language; designed to transport and store data	XML	Extensible Markup Language; designed to transport and store data
XSL Extensible Stylesheet Language; XML based language to visualize XML (data)	XSL	Extensible Stylesheet Language; XML b <mark>ased la</mark> nguage to visualize XML (data)

1.2) General

The EnOcean radio protocol (ERP) is optimized to transmit information with utmost reliability using extremely little power while ensuring that the products of customers applying EnOcean technology are compatible with each other. Only the very shortest transmission period (< 1ms) for an EnOcean telegram allows the design of, for example, a battery-free radio switch, which can produce a full radio command with just approx. 50 µWs (50μ J) of energy. At the same time, the reliability of the system increases, as the possibility of data collision is strongly reduced. Every data bit in the radio telegram is essential. For each '0' or '1' state, content descriptions are definied, which must be followed by the sender and the receiver likewise. Depending on the telegram type and the function of the device the user data (payload) is defined in:

EEP (EnOcean Equipment Profiles)



The ERP specification defines the structure of the entire radio telegram. The user data embedded in this structure is defined by the EEP.

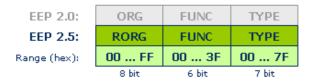
The objective of interoperability is easier to reach with as less profiles as required. Therefore, it is EnOcean Alliance's goal to configure each profile as universally as possible, to target a spectrum of devices in the building automation sector for all manufacturers.

It is of high interest to the EnOcean Alliance that Alliance members verify new devices or newly joined companies verify their products against the existing EEP Profiles and adopt these during testing. Every newly defined EEP would increase diversity and therefore decrease interoperability.

The technical characteristics of a device define three profile elements, which make up the organizational description of all profiles:

- 1. The ERP radio telegram type (RORG)
- 2. Basic functionality of the data content (FUNC)
- 3. Type of device in its individual characteristics (TYPE)

Therefore, every EEP profile has a number, reflecting these three components:



Every field is represented by a hexadecimal number, where the maximum value is limited by the available bits.

Before the definition of a new profile existing profiles should be checked first for suitability. A new profile is to be defined only if the existing profiles would not be adequate.

Once a new profile is to be developed it should be submitted to the TWG of the EnOcean Alliance. The information to be provided is

- the XML-data, plus
- the profile as text in a pdf-file (the .pdf-data is to be generated from the XML-data)

The TWG will review and ratify the profile. Following the recommendation by the TWG the BoD will disapprove or approve the profile.

When defining a new profile rules, abbreviations and terms as per this document have to be applied.

To maintain the XML-data and the linked pdf-document in a proper way a document maintenance process is defined. For details refer to appendix 3.14 Data + document maintenance process.

1.3) What's new in EEP 2.6.4?

New 4BS profiles:

- A5-06-04 Curtain Wall Brightness Sensor
- A5-10-22 Temperature, Setpoint, Humidity, Fan Speed
- A5-10-23 Temperature, Setpoint, Humidity, Fan Speed, Occupancy
- A5-11-05 Dual-Channel Switch Actuator

New VLD profiles:

- D2-01-0C Pilot Wire Commands
- D2-01-0D Micro smart plug with 1 channel, no metering capabilities
- D2-01-0E Micro smart plug with 1 channel, and metering capabilities
- D2-01-0F Slot-in module with 1 channel, no metering capabilities
- D2-01-12 Slot-in module with 2 channels, no metering capabilities
- D2-06-01 Multisensor Window Handle: Alarm, Position Sensor, Vacation Mode, Optional Sensors
- D2-50-xx Heat Recovery Ventilation

1.4) Telegram types (RORG)

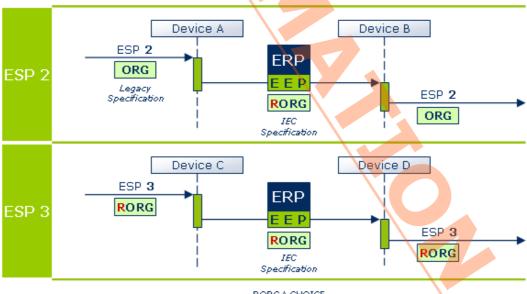
The various Radio-Telegram types are grouped ORGanizationally.

The specifications of ERP (EnOcean Radio Protocol) and of ESP (EnOcean Serial Protocol) group telegram types by 'CHOICE' number. 'RORG' at EEP 2.1(2.5) corresponds to 'CHOICE'.

The following RORG are used in EEP 2.5:

The following i			
Telegram	RORG	ORG	
RPS	F6	05	Repeated Switch Communication
1BS	D5	06	1 Byte Communication
4BS	A5	07	4 Byte Communication
VLD	D2	=RORG	Variable Length Data
MSC	D1	=RORG	Manufacturer Specific Communication
ADT	A6	=RORG	Adressing Destination Telegram
SM_LRN_REQ	C6	=RORG	Smart Ack Learn Request
SM_LRN_ANS	C7	=RORG	Smart Ack Learn Answer
SM_REC	A7	=RORG	Smart Ack Reclaim
SYS_EX	C5	=RORG	Remote Management
SEC	30	=RORG	Secure telegram
SEC_ENCAPS	31	=RORG	Secure telegram with R-ORG encapsulation

For compatibility reasons, the old ORG values on the serial ESP2 interfaces remain valid. However, on the air interface, each ESP2 telegram is transported with the appropriate RORG (= CHOICE).



ORG A CHOICE

EEP = EnOcean Equipment Profiles

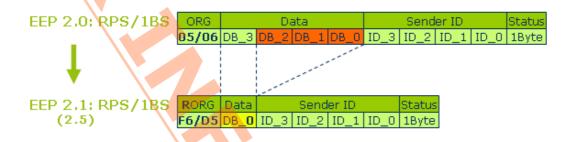
ERP = EnOcean Radio Protocol

ESP = EnOcean Serial Protocol

1.5) EEP modifications at RPS and 1BS data telegram

Both telegram types carry a one byte payload (DB_0) on the wireless interface (ERP).

EEP 2.0 follows the specification of the serial interface / ESP2, which defines the payload to be carried in DB_3 (see succeeding figure). The trailing bytes, DB_2, DB_1 and DB_0 are marked as 'unused'.

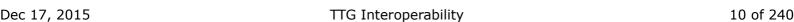


For orthogonal data structural reasons, this deviation will be avoided with EPP 2.1, 2.5 and future versions. The new ESP3 serial interface already respects this.

For reasons of compatibility of end devices, the ESP2 interface remains unaltered, i.e. the DB_0 byte (radio) will continue to be transferred as a DB_3 byte (serial) (including the 3 unused bytes).

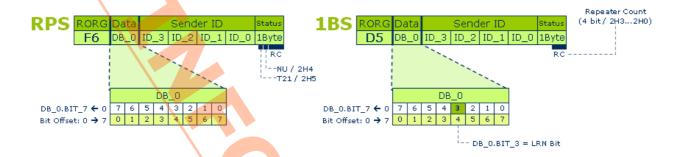
The conversation has to happen on the application layer as the XML-data structure of EEP 2.1 / 2.5 only refers to the DB_0 byte.

As a consequence of this modification the LRN bit is now described in a row for the 1BS and 4BS telegram types as standardized with the DB_0.BIT_3 position.



1.6) Structure and addressing of the telegram types

1.6.1) RPS / 1BS



The RPS and the 1BS telegrams offer only 1 byte user data. These two telegrams differ in the respective learning operations (the 1BS has a LRN bit), and in the way the status byte is used. Comment for RPS status bits:

T21 = 0 = PTM switch module of type 1 / synonymous for module PTM1xx

T21 = 1 = PTM switch module of type 2 / synonymous for module PTM2xx

NU = 1 = N-message (N = normal)

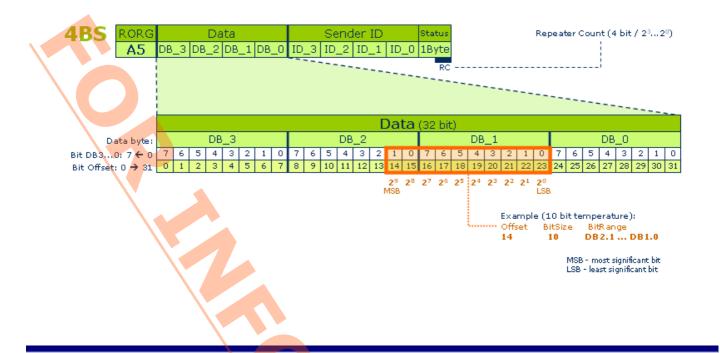
NU = 0 = U-message (U = unassigned)

1.6.2) 4BS

A 4BS telegram carries a payload of 4 bytes. The sequence of the 4 data bytes is historically reversed, so that DB_3 appears first and DB_0 last on the radio interface. The bits are addressed in the sequence of the data flow, however (offset). Hence, DB_3.BIT_7 has the offset position 0 and DB_0.BIT_3 (LRN bit) has the offset position 28. The actual content-bits in a byte are not affected by this, i.e., they are described from right (2H0) to left (2H7) in the ascending order.

The example of a 10-bit temperature profile (see below) illustrates the binary valuation of the individual bits, so that a number range from 0 ... 1023 can be addressed.

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1.6.3) VLD

VLD telegrams carry a variable payload between one and 14 bytes, depending on their design. The teach-in process applies the Smart Ack procedure (see appendices 3.4 and 3.5).

The example following displays a VLD telegram with 6 bytes user data. DB_5.BIT_7 is the first transmitted bit with offset 0.



1.7) Teach-in procedures

The 'Teach-in' defines the mutual communication between wireless devices in an 868 (315) MHz radio network. The 'Teach-in' defines to which transmitter(s) a receiver needs to listen to.

For this purpose of a determined relationship between transmitter and receiver each transmitting device has a unique Sender-ID which is part of each radio telegram. The receiving device detects from the Sender-ID whether the device is known, i.e., was already learned, or unknown.

A telegram with unknown Sender-ID is disregarded.

The 'teach-in' process is different for each telegram type (RPS, 1BS, 4BS, Smart Ack), but the following points are valid for all telegrams:

• First, the receiver must be switched into learning mode. Now, the Sender-ID of an arriving telegram is interpreted as an authorized information source and will be stored at the receiver. The further steps of 'teach-in' are defined by the device type or the telegram type. Thus, normal data telegrams or special teach-in telegrams can be used. Frequently, a learn button triggers the teach-in process.

- The telegram of the respective transmitter should be triggered at least once (by pressing the desired switch rocker or triggering a sensor).
- The bits of the payload (data bytes) can have multiple functions depending on the interpretation set by
 identification or status bits. Only in the 1BS and 4BS telegram the 'LRN BIT' DB_0.BIT_3 is reserved exclusively
 and must not be used elsewhere.

The following issues are relevant for a number of application but not mandatory for specification perspective:

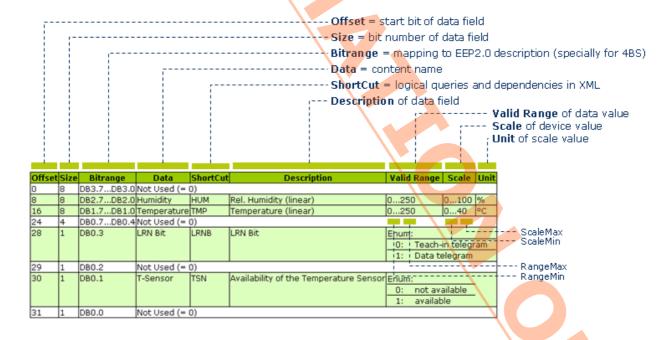
- To prevent unwanted devices from being learned the input sensitivity of the receiver is often restricted, and thus an IN-ROOM operation is created. Typically, the device to be learned is placed close by the receiver.
- Dolphin-based transmitters (e.g. TCM 300 or TCM 2x with Dolphin library) can also be switched into the learn-mode via a remote management command. This remote 'teach-in' mode can only be activated within the first 30 min after receiver power-up. To avoid inadvertent learning the transmitter telegrams have to be triggered 3 times within 2 seconds.

For further details on the 'Teach-in' processes refer to appendices 3.1 to 3.6.

1.8) Viewing XML-data

- The XML-file and all the associated files (CSS, DTD, XSL) and the 'graphics' folder must be stored in the same directory.
- The XML-file is best opened using an Internet browser, generating an HTML-view which displays the describing chapters, graphics and data tables.
- Mozilla Firefox V3.6 or upwards is recommended for optimum screen and print view.

The following example illustrates the HTML-view of the XML-data of a 4BS telegram (= payload of 32 bits).



Data ranges unused are displayed in the table as white rows.

The 'Bit range' column displays the starting-point and the end-point of the respective data.

The 'Valid range', 'Scale' and 'Unit' columns are displayed separately only for measurement values. However, these 3 columns are merged into one if the data comes from an enumeration (enum).

Assuming a linear conversion between the value to be measured and the 'valid range' of data the resolution can be calculated as follows:

```
Conversion: Valid Range ---> Scale

Multiplier = Scale MAX - Scale MIN Range MAX - Range MIN

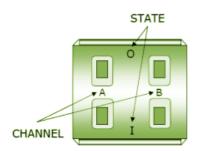
Device value = Multiplier * (rawValue - Range MIN) + Scale MIN
```

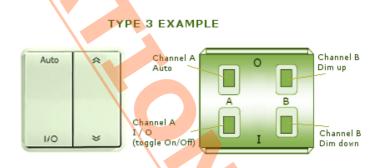
F6: RPS Telegram

Repeated Switch Communication Note for all F6-RPS EEP usage on ERP 2 Submitted by EnOcean ERP 2 (EnOcean Radio Protocol 2) is the radio protocol with FSK encoding. It is compatible on the application level with ERP 1. With ERP 2 all EPPs, Protocols (Security / Smart Acknowledge) can be used as it was before. Only difference are the RPS profiles. The ERP 2 (EnOcean Radio Protocol 2) – does not use the RPS telegrams as ERP 1 did. The biggest difference is the usage of the Status Field. The Status field in ERP 2 is defined as a repeater count field (also other position in the telegram). Other functionalities and fields T21 and NU are not present any more. Therefore a new encoding was developed. EEP describe an equipment – device – application. The meaning of the data did not change only the coding. The logic and semantic of the application is still the same. So it is defined that RPS profiles on ERP 2 have different coding of the actual telegram data, but the logic is same on ERP 1 and ERP 2. The new coding is published as new profiles. This is required to keep the same interfaces on the EEP processing (e.g. existing gateways / IP gateways – we do not want have additional information which radio protocol was used – ERP1/ERP2). The exact details are listed below. The profiles are defined in way that a seamless translation between ERP 1 and ERP 2 vice versa is possible without contextual information, what profile it is in particular.

F6-02: Rocker Switch, 2 Rocker

For clarification reasons the following picture shows a PTM200 transmitter module from EnOcean GmbH which transmits RPS telegrams and is one possibility to be used in applications that require an EEP F6-02-xx. Please note that PTM200 does not support transmission of teach-in telegrams.





The button naming used below is referring to CHANNEL and STATE of the PTM200. Thus "Button AI" means STATE "I" on CHANNEL "A".

There are two different message types, the N-message and the U-message, which need to be identified from the Status Field of an EnOcean RPS telegram. For that reason not only the data bytes are given for each EEP but the T21 and NU bits of the Status Field are listed as well.

RORG	F6	RPS Telegram
FUNC	02	Rocker Switch, 2 Rocker
TYPE	01	Light and Blind Control - Application Style 1

This EEP definition is based on the assumption that a RPS switch module (e.g. PTM200) is installed in a 0-STATE up position! Application Style 1 is widely used in EU but may be found in other markets as well.

Statusfield:

Offset Size Data Value

2	1	T21	1
3	1	NU	1

Datafield:

C	ffset	Size	Bitrange	Data	ShortCut	Description		Valid Range	Scale	Unit
0		3	DB0.7DB0.5		R1		Enum:			
				action			0:	Button AI: "Switch light on" or " "Move blind closed"	Dim light dow	n" or
			1				1:	Button A0: "Switch light off" or ' "Move blind open"	'Dim light up"	or
							2:	Button BI: "Switch light on" or " "Move blind closed"	Dim light dow	n" or
							3:	Button B0: "Switch light off" or " "Move blind open"	'Dim light up"	or
3		1	DB0.4	Energy Bow	EB		Enum:			
							0:	released		
							1:	pressed		
4		3	DB0.3DB0.1		R2		Enum:			
				action			0:	Button AI: "Switch light on" or " "Move blind closed"	Dim light dow	n" or
							1:	Button A0: "Switch light off" or ' "Move blind open"	'Dim light up"	or
							2:	Button BI: "Switch light on" or " "Move blind closed"	Dim light dow	n" or
							3:	Button B0: "Switch light off" or " "Move blind open"	'Dim light up"	or
7		1	DB0.0	2nd Action	SA		Enum:			
							0:	No 2nd action		
							1:	2nd action valid		

Statusfield:

Offset	Size	Data	Value
2	1	T21	1
3	1	NU	0

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	3		Number of buttons pressed simultaneously (other bit combinations are not valid)	R1		Enum: 0: no	button	
						3: 3 d bu	or 4 ttons	
3	1	DB0.4	Energy Bow	EB			eased essed	
4	4	DB0.3DB0.0	Not Used (= 0)					

RORG	F6	RPS Telegram
FUNC	02	Rocker Switch, 2 Rocker
TYPE	02	Light and Blind Control - Application Style 2

This EEP definition is based on the assumption that a RPS switch module (e.g. PTM200) is installed in an I-STATE up position! Application Style 2 is typically used in US and CAN but may be found in other markets as well.

Statusfield:

Offset	Size	Data	Value
2	1	T21	1
3	1	NU	1

Datafield:

Offset	Size	Bitrange	Data	ShortCut	Description	V	alid Range	Scale	Unit
0	3	DB0.7DB0.5		R1		Enum:			
			action			"5	utton AI: Switch light on" or ' Move blind open"	'Dim light up"	or
						"s	utton A0: switch light off" or " Move blind closed"	Dim light dow	า" or
		,				"5	utton BI: Switch light on" or ' Move blind open"	'Dim light up"	or
						"5	utton B0: Switch light off" or ` Move blind closed"	`Dim light dow	n" or
3	1	DB0.4	Energy Bow	EB		Enum:			
						0: re	eleased		
						1: pr	ressed		
4	3	DB0.3DB0.1		R2		Enum:			
			action			"5	utton AI: Switch light on" or ' Move blind open"	'Dim light up" (or
						"s	utton A0: switch light off" or " Move blind closed"	Dim light dow	า" or
						"5	utton BI: Switch light on" or ' Move blind open"	'Dim light up"	or
						"5	<mark>utt</mark> on B0: Sw <mark>it</mark> ch light off" or ' Move <mark>b</mark> lind closed"	`Dim light dow	n" or
7	1	DB0.0	2nd Action	SA		-	o 2nd action		
						1: 2r	nd action valid		

Statusfield:

Offset	Size	Data	Value
2	1	T21	1
3	1	NU	0

Offs	et Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	3	DB0.7DB0.5	Number of buttons pressed simultaneously (other bit combinations are not valid)	R1		3: 3 0	button or 4 ttons	
3	1	DB0.4	Energy Bow	EB			eased essed	- /
4	4	DB0.3DB0.0	Not Used (= 0)					

RORG	F6	RPS Telegram		
FUNC	02	Rocker Switch, 2 Rocker		
TYPE	03	Light Control - Application Style 1		

Submitter: Servodan

Definition of Auto, I/O for Rocker switch, Dim control (PTM200)

Statusfield:

Offset	Size	Data	Value
2	1	T21	1
3	1	NU	1/

Datafield:

Offset	Size	Bitrange	Data	ShortCut	Description		Valid Range	Scale	Unit
0	8	DB0.7DB0.0	Rocker	RA		Enum:			
			action			0x30:	Button A0: Set the controller in a	automatic mode	e
						0x10:	Button A1: Set the controller in r toggles between switch light on and sw	,	and
						0x70:	Button B0: Dim light up		
						0x50:	Button B1: Dim light down		

RORG	F6	RPS Telegram				
FUNC	02	Rocker Switch, 2 Rocker				
TYPE	04	Light and blind control ERP2				

Submitter: EnOcean GmbH

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range Scale Unit
0	1	DB0.7	Energy Bow	EBO	State of the energy bow	Enum: 0: released 1: pressed
1	1	DB0.6	Button coding	ВС	Signalize button coding	Enum: 0: button
2	2	DB0.5DB0.4	Not Used (= 0	1)		
4	1	DB0.3	ВІ	RBI	State I of the rocker B	Enum: 0: not pressed 1: pressed
5	1	DB0.2	В0	RB0	State 0 of the rocker B	Enum: 0: not pressed 1: pressed
6	1	DB0.1	AI	RAI	State I of the rocker A	Enum: 0: not pressed 1: pressed
7	1	DB0.0	A0	RA0	State 0 of the rocker A	Enum: 0: not pressed 1: pressed

F6-03: Rocker Switch, 4 Rocker

RORG	F6	RPS Telegram
FUNC	03	Rocker Switch, 4 Rocker
TYPE	01	Light and Blind Control - Application Style 1

This EEP definition is based on the assumption that a RPS switch module is installed in a 0-STATE up position! Application Style 1 is widely used in EU but may be found in other markets as well.

Statusfield:

Offset	Size	Data	Value
2	1	T21	0
3	1	NU	1

Offset	Size	Bitrange	Data	ShortCut	Description		Valid Range	Scale	Unit
0	3	DB0.7DB0.5	Rocker 1st	R1		Enum:			
			action			0:	Button AI: "Switch light on" or "Move blind closed"	"Dim light dow	n" or
						1:	Button A0: "Switch light off" or "Move blind open"	"Dim light up"	or
						2:	Button BI: "Switch light on" or "Move blind closed"	"Dim light dow	n" or
						3:	Button B0: "Switch light off" or "Move blind open"	"Dim light up"	or
						4:	Button CI: "Switch light on" or "Move blind closed"	"Dim light dow	n" or
						5:	Button C0: "Switch light off" or "Move blind open"	"Dim light up"	or
						6:	Button DI: "Switch light on" or "Move blind closed"	"Dim light dow	n" or
						7:	Button D0: "Switch light off" or "Move blind open"	"Dim light up"	or
3	1	DB0.4	Energy Bow	EB		Enum: 0: 1:	released pressed		
4	3	DB0.3DB0.1	Rocker 2nd	R2		Enum:			
	3		action			0:	Button AI: "Switch light on" or "Move blind closed"	"Dim light dow	n" or
						1:	Button A0: "Switch light off" or "Move blind open"	"Dim light up"	or
						2:	Button BI: "Switch light on" or "Move blind closed"	"Dim light dow	n" or
						3:	Button B0: "Switch light off" or "Move blind open"	"Dim light up"	or
						4:	Button CI: "Switch light on" or "Move blind closed"	"Dim light dow	n" or
						5:	Button CO: "Switch light off" or "Move blind open"	"Dim light up"	or
						6:	Button DI: "Switch light on" or "Move blind closed"	"Dim light dow	n" or

					7: Button D0: "Switch light off" or "Dim light up" or "Move blind open"
7	1	DB0.0	2nd Action	SA	 Enum: 0: No 2nd action
					1: 2nd action valid

Statusfield:

Offset	Size	Data	Value
2	1	T21	0
3	1	NU	0

Datafield:

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range Scale Unit
0		DB0.7DB0.5	Number of buttons pressed simultaneously	R1		Enum: 0: no Button pressed 1: 2 buttons pressed 2: 3 buttons pressed 3: 4 buttons pressed 4: 5 buttons pressed 5: 6 buttons pressed 6: 7 buttons
						pressed 7: 8 buttons pressed
3	1	DB0.4	Energy Bow	EB		Enum: 0: released 1: pressed
4	4	DB0.3DB0.0	Not Used (= 0)			

RORG	F6	RPS Telegram
FUNC	03	Rocker Switch, 4 Rocker
TYPE	02	Light and Blind Control - Application Style 2

A This EEP definition is based on the assumption that a RPS switch module is installed in a I-STATE up position! Application Style 2 is typically used in US and CAN but may be found in other markets as well.

Statusfield:

Offset	Size	Data	Value
2	1	T21	0
3	1	NU	1

•	Offset	Size	Bitrange	Data	ShortCut	Description		Valid Range	Scale	Unit
()	3	DB0.7DB0.5	Rocker 1st	R1		Enum:			
				action			1:	Button AI: "Switch light on" or " "Move blind open" Button A0: "Switch light off" or " "Move blind closed" Button BI: "Switch light on" or "	Dim light dow	'n" or
								"Switch light on" or " "Move blind open"	ווויט ilght up	Or •

						3: Button B0: "Switch light off" or "Dim light down" or "Move blind closed" 4: Button CI: "Switch light on" or "Dim light up" or "Move blind open" 5: Button C0: "Switch light off" or "Dim light down" or "Move blind closed" 6: Button DI: "Switch light on" or "Dim light up" or "Move blind open" 7: Button D0: "Switch light off" or "Dim light down" or "Move blind closed"
3	1	DB0.4	Energy Bow	EB		Enum:
			3,			0: released
						1: pressed
4	3	DB0.3DB0.1	Rocker 2nd	R2		Enum:
			action			0: Button AI: "Switch light on" or "Dim light up" or "Move blind open" 1: Button A0: "Switch light off" or "Dim light down" or "Move blind closed" 2: Button BI:
						"Switch light on" or "Dim light up" or "Move blind open"
						3: Button B0: "Switch light off" or "Dim light down" or "Move blind closed"
				No.	(=	4: Button CI: "Switch light on" or "Dim light up" or "Move blind open"
						5: Button C0: "Switch light off" or "Dim light down" or "Move blind closed"
						6: Button DI: "Switch light on" or "Dim light up" or "Move blind open"
						7: Button D0: "Switch light off" or "Dim light down" or "Move blind closed"
7	1	DB0.0	2nd Action	SA		Enum: 0: No 2nd action 1: 2nd action valid

Statusfield:

Offset	Size	Data	Value
2	1	T21	0
3	1	NU	0

Offset	Size	Bitrange	Data	ShortCut	Description	Valid	Range	Scale	Unit
0	3	DB0.7DB0.5	Number of buttons pressed	R1		Enum:			
			simultaneously			0:	no butt	on	
							pressed		
						1:	2 butto		
							pressed	$\overline{}$	
						2:	3 butto		
							pressed		
						3:	4 butto		
							pressed		
						4:	5 butto		

					5:	6 buttons pressed
					6:	7 buttons pressed
					7:	8 buttons pressed
3	1	DB0.4	Energy Bow	EB	 Enum	:
					0:	released
					1:	pressed
4	4	DB0.3DB0.0	Not Used (= 0)			

F6-04: Position Switch, Home and Office Application

	\	
RORG	F6	RPS Telegram
FUNC	04	Position Switch, Home and Office Application
TYPE	01	Key Card Activated Switch

Insertion of Key Card generates an N-Message, take-out a U-Message

Statusfield:

Offset	Size	Data	Value
2	1	T21	1
3	1	NU	1

Datafield:

Offset	Size	Bitrange	Data	ShortCut	Descr	iption	Valid	Range	Scale	Unit
0	8	DB0.7DB0.0	Key Card	KC			Enum	1:		
							112	2: inserted	d (0x70)

Statusfield:

Offset	Size	Data	Value
2	1	T21	1
3	1	NU	0

Datafield:

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale Unit
0	8	DB0.7DB0.0	Key Card	KC		Enum:	
						0: taken	out

RORG	F6	RPS Telegram
FUNC	04	Position Switch, Home and Office Application
TYPE	02	Key Card Activated Switch ERP2

Submitter: EnOcean GmbH

When card is inserted field EBO and SOC are both having value 1. When take out, both are having value 0. This coding is required to have a context less translation of RPS profiles between ERP 1 and ERP 2.

(Offset	Size	Bitrange	Data	ShortCut	Description	Valid	Range Scale	Unit
(C	1	DB0.7	Energy Bow	EBO	State of the energy bow	Enum	:	
							0:	taken out	
							1:	card inserte	d

1	1	DB0.6	Button coding	ВС	Signalize button coding	Enum	:
						0:	button
2	3	DB0.5DB0.3	Not Used (= 0)			
5	1	DB0.2	State of card	SOC	State of the card	Enum	:
						0:	taken out
						1:	card inserted
6	2	DB0.1DB0.0	Not Used (= 0	1)			

F6-05: Detectors

RORG	F6		RPS Telegram
FUNC	05		Detectors
TYPE	01	Liquid Lea	kage Sensor (mechanic harvester)

Submitter: Afriso / EnOcean

Description:

This profile is used for devices detecting leakage. It is commonly placed on ground where a leakage causes damage. The principle is that "paper rings" swell in water and trigger an ECO 200 (generator) based transmitter.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event-triggered

Communication interval: NA Trigger event: (water detection) Teach-in method: RPS teach-in

Statusfield:

Offset	Size	Data	Value
2	1	T21	1
3	1	NU	1

Datafield:

Offse	size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB0.7DB0.0	Water sensor		Alert signal that the sensor detected water leakage	Enum: Wate	r	
						0x11: detec	ted	

F6-10: Mechanical Handle

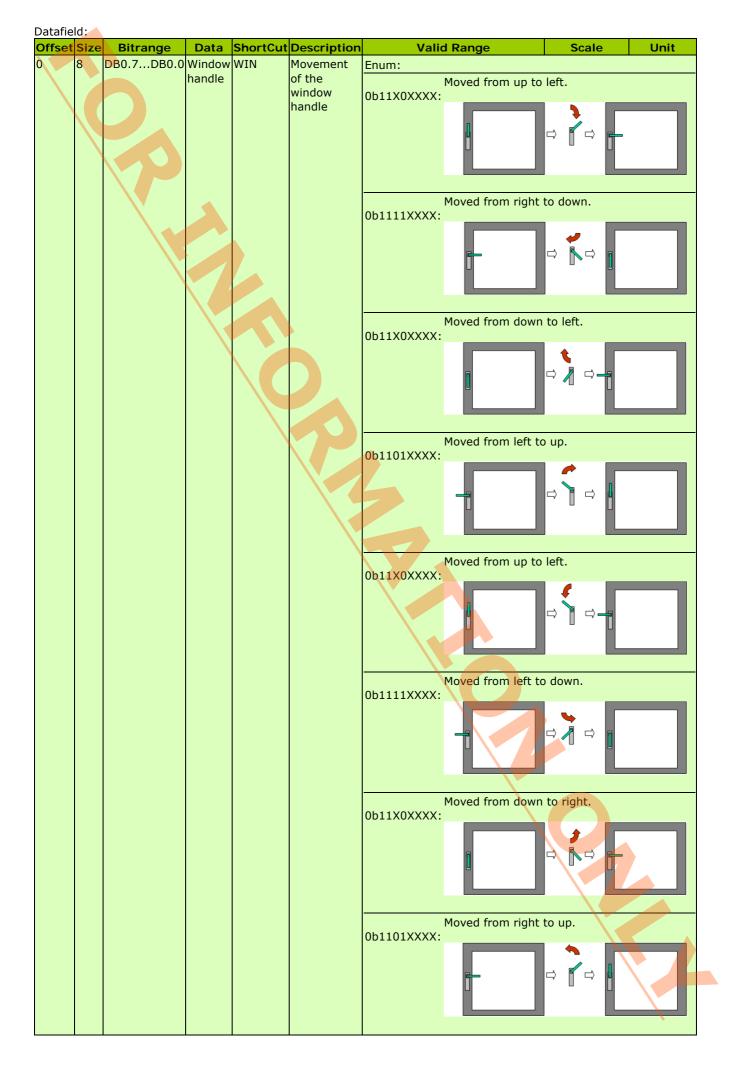
RORG	F6	RPS Telegram
FUNC	10	Mechanical Handle
TYPE	00	Window Handle

Submitter: HOPPE AG

The bits marked with 'X' in DB_0 should not be checked. These bits can be '1' or '0' and should not be assumed to be a defined value, because both of them are allowed and not predictable!

Statusfield:

Offset	Size	Data	Value
2	1	T21	1
3	1	NU	0

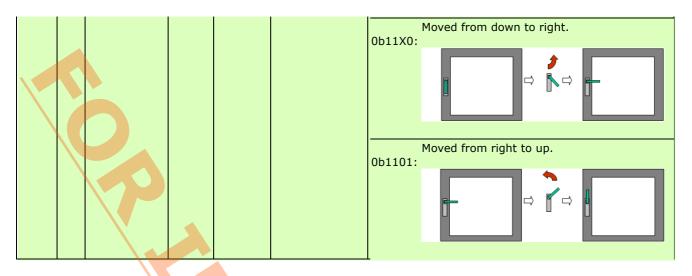


RORG	F6	RPS Telegram
FUNC	10	Mechanical Handle
TYPE	01	Window Handle ERP2

Submitter: HOPPE AG

DB0.6 – needs to show that RPS/ERP2 has a different coding as RPS/ERP1.

Offset			Data	ShortCut	Description	Valid Range	Scale	Unit
0	1	DB0.7	Not Use					
1	1	DB0.6	Handle	HC	Signalize	Enum:		
			coding		window handle	1: handle		
_	_			1 ()	coding			
2		DB0.5DB0.4				I_		
4	4	DB0.3DB0.0	value	HVL	Value of the 4MSB of the	Enum:	6	
			value		Data field of	Moved from up to les 0b11X0:	rt.	
			//		ERP1 coding	ODITAO.		
				\		Moved from right to	down	
				`		Ob1111:	down.	
						Moved from down to	left.	
						0b11X0:		
					\		•	
						U	" Ц	
						Moved from left to u	p.	
						0b1101:		
						M 12	6	
						Moved from up to lead to be 11X0:	rt.	
						ODITAO.		
						n n		
						Moved from left to d	own	
						0b1111:	J.Mil	
				I				



D5: 1BS Telegram

D5-00: Contacts and Switches

RORG	D5	1BS Telegram
FUNC	IC 00 Contacts and Switch	
TYPE 01 Single Input Cont		Single Input Contact

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range Scale Unit
4	1	DB0.3	Learn Button	LRN		0: pressed 1: not pressed
7	1	DB0.0	Contact	СО		Enum: 0: open 1: closed

A5: 4BS Telegram

A5-02: Temperature Sensors

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	01	Temperature Sensor Range -40°C to 0°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	-400	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-ir	n telegra	m
						1: Data tel	egram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	02	Temperature Sensor Range -30°C to +10°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	-30+10	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegrar	n
						1: Data t	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	03	Temperature Sensor Range -20°C to +20°C

Offset	Size	Bitrange	Data	ShortCut	Description	on	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)					
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (I	linear)	2550	-20+20	°C
24	4	DB0.7DB0.4	Not Used (=	0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		Enum:		
							0: Teach-	in telegrar	n
							1: Data t	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)					

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	04	Temperature Sensor Range -10°C to +30°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	-10+30	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegra	m
						1: Data te	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	05	Temperature Sensor Range 0°C to +40°C

Offse	et	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0		16	DB3.7DB2.0	Not Used (=	0)				
16		8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40	°C
24		4	DB0.7DB0.4	Not Used (=	0)				
28		1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
							0: Teach-ir	n telegrai	m
							1: Data te	legram	
29		3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	06	Temperature Sensor Range +10°C to +50°C

Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
16	DB3.7DB2.0	Not Used (=	0)				
8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	+10+50	°C
4	DB0.7DB0.4	Not Used (=	0)				
1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
					0: Teach-	in telegran	า
					1: Data t	elegram	
3	DB0.2DB0.0	Not Used (=	0)				
	16 8 4 1	16 DB3.7DB2.0 8 DB1.7DB1.0 4 DB0.7DB0.4 1 DB0.3	16 DB3.7DB2.0 Not Used (= 8 DB1.7DB1.0 Temperature 4 DB0.7DB0.4 Not Used (= 1 DB0.3 LRN Bit	16 DB3.7DB2.0 Not Used (= 0) 8 DB1.7DB1.0 Temperature TMP 4 DB0.7DB0.4 Not Used (= 0) 1 DB0.3 LRN Bit LRNB	16 DB3.7DB2.0 Not Used (= 0) 8 DB1.7DB1.0 Temperature TMP Temperature (linear) 4 DB0.7DB0.4 Not Used (= 0) 1 DB0.3 LRN Bit LRNB LRN Bit	16 DB3.7DB2.0 Not Used (= 0) 8 DB1.7DB1.0 Temperature TMP Temperature (linear) 2550 4 DB0.7DB0.4 Not Used (= 0) 1 DB0.3 LRN Bit LRNB LRN Bit Enum: 0: Teach- 1: Data to	16 DB3.7DB2.0 Not Used (= 0) 8 DB1.7DB1.0 Temperature TMP Temperature (linear) 2550 +10+50 4 DB0.7DB0.4 Not Used (= 0) Enum: 0: Teach-in telegram 1 DB0.3 LRN Bit LRN Bit Enum: 0: Teach-in telegram

RORG	A5	4BS Telegram			
FUNC 02 Temperature Sensors					
TYPE	07	Temperature Sensor Range +2	20°C to +60°C		

Offset	Size	Bitrange	Data	ShortCut	Description	Valid	Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)					-
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	255	.0	<mark>+</mark> 20+60	°C
24	4	DB0.7DB0.4	Not Used (=	0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum			
						0:	Teach-i	in telegran	1
						1:	Data te	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)					

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	08	Temperature Sensor Range +30°C to +70°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	+30+70	°C
24	4	DB0.7DB0.4	Not Used (=	0)				

28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum	:
						0:	Teach-in telegram
						1:	Data telegram
29	3	DB0.2DB0.0	Not Used (=	0)	_	•	

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	09	Temperature Sensor Range +40°C to +80°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale Un
0	16	DB3.7DB2.0	Not Used (=	0)			
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	+40+80 °C
24	4	DB0.7DB0.4	Not Used (=	0)			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:	
					0: Te		in telegram
						1: Data t	elegram
29	3	DB0.2DB0.0	Not Used (=	0)			

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	0A	Temperature Sensor Range +50°C to +90°C

Offset	Size	Bitrange	Data	ShortCut	Descripti	ion	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)					
16	8	DB1.7DB1.0	Temperature	TMP	Temperature ((linear)	2550	+50+90	°C
24	4	DB0.7DB0.4	Not Used (=	0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		Enum:		
								in telegran elegram	<u>n</u>
29	3	DB0.2DB0.0	Not Used (=	0)			Data (

RORG	A5	4BS Telegram			
FUNC	02	Temperature Sensors			
TYPE	0B	Temperature Sensor Range +60°C to +100°C			

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit	
0	16	DB3.7DB2.0	Not Used (=	0)					
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	+60+100	°C	
24	4	DB0.7DB0.4	0B0.7DB0.4 Not Used (= 0)						
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:			
						0: Teach-	in telegram		
						1: Data t	elegram		
29	3	DB0.2DB0.0	Not Used (=	0)					

RORG	A5	4BS Telegram			
FUNC	02	Temperature Sensors			
TYPE	10	Temperature Sensor Range -60°C to +20°C			

Offset	Size	Bitranç	ge	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7D	B2.0	Not Used (=	0)				
16	8	DB1.7D	B1.0	Temperature	TMP	Temperature (linear)	2550	-60+20	°C
24	4	DB0.7D	B0.4	Not Used (=	0)				
28	1	DB0.3		LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-i		in telegrar	n
							1: Data t	elegram	
29	3	DB0.2D	B0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	11	Temperature Sensor Range -50°C to +30°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	-50+30	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegrar	n
						1: Data t	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram	
FUNC	02	Temperature Sensors	
TYPE	12	Temperature Sensor Range -40°C to	+40°C

Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
16	DB3.7DB2.0	Not Used (=	0)				
8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	-40+40	°C
4	DB0.7DB0.4	Not Used (=	0)				
1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
					0: Teach-	in telegrar	n
					1: Data te	elegram	
3	DB0.2DB0.0	Not Used (=	0)				
	16 8 4 1	16 DB3.7DB2.0 8 DB1.7DB1.0 4 DB0.7DB0.4 1 DB0.3	16 DB3.7DB2.0 Not Used (= 8 DB1.7DB1.0 Temperature 4 DB0.7DB0.4 Not Used (= 1 DB0.3 LRN Bit	16 DB3.7DB2.0 Not Used (= 0) 8 DB1.7DB1.0 Temperature TMP 4 DB0.7DB0.4 Not Used (= 0) 1 DB0.3 LRN Bit LRNB	16 DB3.7DB2.0 Not Used (= 0) 8 DB1.7DB1.0 Temperature TMP Temperature (linear) 4 DB0.7DB0.4 Not Used (= 0) 1 DB0.3 LRN Bit LRNB LRN Bit	16	16

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	13	Temperature Sensor Range -30°C to +50°C

Offset Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit

0	16	DB3.7DB2.0	Not Used (=	0)			
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	-30+50 °C
24	4	DB0.7DB0.4	Not Used (=	0)			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:	
						0: Teach	-in telegram
						1: Data t	elegram
29	3	DB0.2DB0.0	Not Used (=	0)			

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	14	Temperature Sensor Range -20°C to +60°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)	-			
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	-20+60	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegrar	n
						1: Data t	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	15	Temperature Sensor Range -10°C to +70°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid	Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)					
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	255	0	-10+70	°C
24	4	DB0.7DB0.4	Not Used (=	0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum			
						0:	Teach-	in telegrar	n
						1:	Data t	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)					

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	16	Temperature Sensor Range 0°C to +80°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+80	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-i	n telegra	m
						1: Data te	legram	
29	3	DB0.2DB0.0	Not Used (=	0)				

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RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	17	Temperature Sensor Range +10°C to +90°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	+10+90	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegran	า
						1: Data t	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	18	Temperature Sensor Range +20°C to +100°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	+20+100	°C
24	4	DB0.7DB0.4	Not Used (=	lot Used (= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegram	
						1: Data t	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	19	Temperature Sensor Range +30°C to +110°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	+30+110	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegram	
						1: Data to	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	1A	Temperature Sensor Range +40°C to +120°C

Offset	t Siz	ze	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16		DB3.7DB2.0	B3.7DB2.0 Not Used (= 0)					
16	8		DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	+40+120	°C
24	4		DB0.7DB0.4	Not Used (=	Not Used (= 0)				
28	1		DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
	M						0: Teach-	in telegram	
							1: Data t	elegram	
29	3	DB0.2DB0.0 Not Used (= 0)							

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	1B	Temperature Sensor Range +50°C to +130°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	+50+130	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegram	
						1: Data t	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	20	10 Bit Temperature Sensor Range -10°C to +41.2°C

Size	Bitrange	Data	ShortCut	Description	Valid	Range	Scale	Unit
14	DB3.7DB2.2	Not Used (=	0)					-
10	DB2.1DB1.0	Temperature	TMP	Temperature (linear)	1023.	0	-10+41.2	°C
4	DB0.7DB0.4	Not Used (=	0)					
1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum			
					0:	Teach-	in telegram	
					1:	Data t	elegram	
3	DB0.2DB0.0	2DB0.0 Not Used (= 0)						-
	14 10 4 1	14 DB3.7DB2.2 10 DB2.1DB1.0 4 DB0.7DB0.4 1 DB0.3	14 DB3.7DB2.2 Not Used (= 10 DB2.1DB1.0 Temperature 4 DB0.7DB0.4 Not Used (= 1 DB0.3 LRN Bit	14 DB3.7DB2.2 Not Used (= 0) 10 DB2.1DB1.0 Temperature TMP 4 DB0.7DB0.4 Not Used (= 0) 1 DB0.3 LRN Bit LRNB	14 DB3.7DB2.2 Not Used (= 0) 10 DB2.1DB1.0 Temperature TMP Temperature (linear) 4 DB0.7DB0.4 Not Used (= 0) 1 DB0.3 LRN Bit LRNB LRN Bit	14 DB3.7DB2.2 Not Used (= 0) 10 DB2.1DB1.0 Temperature TMP Temperature (linear) 1023. 4 DB0.7DB0.4 Not Used (= 0) 1 DB0.3 LRN Bit LRNB LRN Bit Enum 0: 1: 0: 1:	14 DB3.7DB2.2 Not Used (= 0) 10 DB2.1DB1.0 Temperature TMP Temperature (linear) 10230 4 DB0.7DB0.4 Not Used (= 0) 1 DB0.3 LRN Bit LRN Bit LRN Bit Enum:	14 DB3.7DB2.2 Not Used (= 0) 10 DB2.1DB1.0 Temperature TMP Temperature (linear) 10230 -10+41.2 4 DB0.7DB0.4 Not Used (= 0) 1 DB0.3 LRN Bit LRNB LRN Bit 0: Teach-in telegram 1: Data telegram

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	30	10 Bit Temperature Sensor Range -40°C to +62.3°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	14	DB3.7DB2.2	Not Used (=	0)				
14	10	DB2.1DB1.0	Temperature	TMP	Temperature (linear)	10230	-40+62.3	°C
24	4	DB0.7DB0.4	Not Used (=	0)				

28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum	:
						0:	Teach-in telegram
						1:	Data telegram
29	3	DB0.2DB0.0	Not Used (=	0)	_	•	

A5-04: Temperature and Humidity Sensor

RORG	A5	4BS Telegram
FUNC	04	Temperature and Humidity Sensor
TYPE	01	Range 0°C to +40°C and 0% to 100%

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used (=	0)				
8	8	DB2.7DB2.0	Humidity	HUM	Rel. Humidity (linear)	0250	0100	%
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0250	0+40	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-i	n telegra	m
						1: Data te	legram	
29	1	DB0.2	Not Used (=	0)		_		
30	1	DB0.1	T-Sensor	TSN	Availability of the Temperature Sensor	Enum:		
					0		ilable	
						1: availab	le	
31	1	DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram	
FUNC	04	Temperature and Humidity Sens	or
TYPE	02	Range -20°C to +60°C and 0% to 1	L00%

Submitter: Eltako

Description:

In contrast to EEP A5-04-01, the temperature range is extended: -20°C...+60°C.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication interval: -

Trigger event: change in temperature, change in humidity

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: 4BS teach-in

Security

Encryption supported: -Security level format: -

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used (=	0)				
8	8	DB2.7DB2.0	Humidity	HUM	Rel. Humidity (linear)	0250	0100	%
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0250	-20+60	°C
24	4	DB0.7DB0.4	Not Used (=	0)				

28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum	:
						0:	Teach-in telegram
						1:	Data telegram
29	1	DB0.2	Not Used (=	0)			
30	1	DB0.1	T-Sensor	TSN	Availability of the Temperature Sensor	Enum	:
						0:	not available
						1:	available
31	1	DB0.0	Not Used (=	0)		<u> </u>	

RORG	A5		4BS Telegram
FUNC	04		Temperature and Humidity Sensor
TYPE	03	Range	-20°C to +60°C 10bit-measurement and 0% to 100%

Submitter: ITEC

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication interval: 20 seconds – 1 hour (one time configuration)

Trigger event: threshold/delta for observed value, heartbeat

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: 4BS teach-in 2

Security

Encryption supported: -Security level format: -

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Humidity	HUM	Rel. Humidity (linear)	0255	0100	%
8	6	DB2.7DB2.2	Not Used (= 0))				
14	10	DB2.1DB1.0	Temperature	TMP	Temperature (linear)	01023	-20+60	°C
24	4	DB0.7DB0.4	Not Used (= 0)	lot Used (= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegrar	n
						1: Data t	elegram	
29	2	DB0.2DB0.1	Not Used (= 0))				
31	1	DB0.0	Telegram Type	TTP	Telegram Type	Enum:		
						0: Hearth	eat	
						1: Event	triggered	

A5-05: Barometric Sensor

RORG	A5	4BS Telegram
FUNC	05	Barometric Sensor
TYPE	01	Range 500 to 1150 hPa

Submitter: ITEC

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication interval: 20 seconds – 1 hour (one time configuration)

Trigger event: threshold/delta for observed value, heartbeat

Tx delay: -

Rx timeout: -

Teach-in

Teach-in method: 4BS teach-in 2

<u>Security</u> Encryption <u>supported</u>: -Security level format: -

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	6	DB3.7DB3.2	Not Used (= 0))		_	-	
6	10	DB3.1DB2.0	Barometer	BAR	Barometer (linear)	01023	5001150	hPa
16	12	DB1.7DB0.4	Not Used (= 0))				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-	in telegram	
						1: Data t	elegram	
29	2	DB0.2DB0.1	Not Used (= 0))				
31	1	DB0.0	Telegram Type	TTP	Telegram Type	Enum:		
						0: Hearth	eat	
						1: Event	triggered	

A5-06: Light Sensor

RORG	A5	4BS Telegram
FUNC	FUNC 06 Light Se	
TYPE	01	Range 300lx to 60.000lx

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage	SVC	Supply voltage (linear)	0255	05.1	V
8	8	DB2.7DB2.0	Illumination	ILL2	Illumination (linear)	0255	30030000	lx
16	8	DB1.7DB1.0	Illumination	ILL1	Illumination (linear)	0255	60060000	lx
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
					\\	0: Teach-in telegram		
						1: Data tele	gram	
29	2	DB0.2DB0.1	Not Used (= 0))				
31	1	DB0.0	Range select	RS	Range	Enum:		
						0: Range acc. to DB_1 (ILL1)		L1)
						1: Range ac	c. to DB_2 (ILI	L2)

RORG	A5	4BS Telegram
FUNC	06	Light Sensor
TYPE	02	Range 0lx to 1.020lx

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage	SVC	Supply voltage (linear)	0255	05.1	V
8	8	DB2.7DB2.0	Illumination	ILL2	Illumination (linear)	0255	0510	lx
16	8	DB1.7DB1.0	Illumination	ILL1	Illumination (linear)	0255	01020	lx
24	4	DB0.7DB0.4	Not Used (= 0)					

28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:
						0: Teach-in telegram
						1: Data telegram
29	2	DB0.2DB0.1	Not Used (= 0))		
31	1	DB0.0	Range select	RS	Range	Enum:
						0: Range acc. to DB_1 (ILL1)
						1: Range acc. to DB_2 (ILL2)

RORG	A5	4BS Telegram
FUNC	06	Light Sensor
TYPE	03	10-bit measurement (1-Lux resolution) with range 0lx to 1000lx

Submitter: Lutuo Technology

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage		Supply voltage (linear) 251255: reserved for error code	0250	05.0	V
8	10	DB2.7DB1.6	Illumination		Illumination (linear) DB2 = 8 MSB, DB1 = 2 LSB 1001: over range, 10021024: reserved	01000	01000	lx
18	10	DB1.5DB0.4	Not Used (= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach telegr 1: Data t		
29	3	DB0.2DB0.0	Not Used (= 0)				

RORG	A5	4BS Telegram
FUNC	06	Light Sensor
TYPE	04	Curtain Wall Brightness Sensor

Submitter: Echoflex Solutions

Description

This EEP is intended for use with wireless daylight sensors, who communicate exterior light levels back to a blind controller.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: time-triggered and upon lux sensor reading change of more than a few percent

Communication interval: A telegram is transmitted every 1 minute in "day mode" and every 1 hour in "night mode". If the measured light is below a certain threshold for several minutes the sensor goes to night mode.

Trigger event: Heartbeat, change of lux reading

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: 4BS teach-in 2

Security

Encryption supported: no Security level format: -

Offset Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit

0	8	DB3.7DB3.0	Temperature	TEMP	Ambient Temperature	0255	-20+60	°C	
8	16	DB2.7DB1.0	Illuminance	ILL	Illuminance (linear)	065535	065535	lx	
24	4	DB0.7DB0.4	Energy Storage	SV	Energy Storage	015	0100	%	
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:			
						0: Teach-ii	n telegram		
						1: Data te	legram	_	
29	1	DB0.2	Not Used (= 0)	ot Used (= 0)					
30			Temperature	TMPAV	Valid temperature data	Enum:			
	Availability	Availability		available on DB3	0: Temper	ature data is able			
					1: Temper availabl	ature data is e			
31	1	DB0.0	Energy Storage	ENAV	Valid energy storage data	Enum:			
	Availability		Availability		available on DB0	0: Energy storage data is unavailable			
					1: Energy availabl	storage data e	is		

A5-07: Occupancy Sensor

RORG	A5	4BS Telegram
FUNC	07	Occupancy Sensor
TYPE	01	Occupancy with Supply voltage monitor

Submitter: Lutuo Technology

The transmission of "PIR off" telegrams is optional.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage (OPTIONAL)		Supply voltage / super cap. (linear); 251 - 255 reserved for error code	0250	05.0	V
8	8	DB2.7DB2.0	Not Used (= 0)					
16	8	DB1.7DB1.0	PIR Status	PIRS	PIR Status	Enum: 0127: PII 128255: PI	R off R on	
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	0: Teach-in 1: Data tele	telegram egram	_
29	2	DB0.2DB0.1	Not Used (= 0)	•				
31	1		Supply voltage availability	SVA	Supply voltage availability at DB_3		oltage is	not

RORG	A5	4BS Telegram			
FUNC	07	Occupancy Sensor			
TYPE	02	Occupancy with Supply voltage monitor			

Submitter: Lutuo Technology

The transmission of "PIR off" telegrams is optional.

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Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit		
0	8		Supply voltage (REQUIRED)		Supply voltage / super cap. (linear); 251 – 255 reserved for error code	0250	05.0	V		
8	16	DB2.7DB1.0	DB2.7DB1.0 Not Used (= 0)							
24	1	DB0.7	PIR Status	PIRS	PIR Status	Enum: 0: Uncertai occupan 1: Motion c	cy status			
25	3	DB0.6DB0.4	Not Used (= 0)							
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in 1: Data tele	telegram egram			
29	3	DB0.2DB0.0	Not Used (= 0)							

RORG	A5				4BS Telegram
FUNC	07				Occupancy Sensor
TYPE	03	Occupa	ncy v	vith :	Supply voltage monitor and 10-bit illumination measurement

Submitter: Lutuo Technology

The transmission of "PIR off" telegrams is optional.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8		Supply voltage (REQUIRED)	SVC	Supply voltage (linear); 251 – 255 reserved for error code	0250	05.0	V
8	10	DB2.7DB1.6	Illumination		Illumination (linear); DB2 = 8 MSB, DB1 = 2 LSB 1001: over range, 10021024: reserved	01000	01000	lx
18	6	DB1.5DB1.0	Not Used (= 0)					
24	1	DB0.7	PIR Status	PIRS	PIR Status	Enum:		
						1: Motion detected		
						0: Uncerta status	in of occupa	ancy
25	3	DB0.6DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-ir	telegram	
						1: Data tel	egram	
29	3	DB0.2DB0.0	Not Used (= 0)					

A5-08: Light, Temperature and Occupancy Sensor

RORG	A5	4BS Telegram
FUNC	08	Light, Temperature and Occupancy Sensor
TYPE	01	Range Olx to 510lx, 0°C to +51°C and Occupancy Button

E.g. for ceiling suspended sensor.

Office Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0 8 DE	33.7DB3.0	Supply voltage	SVC	Supply voltage (linear)	0255	05.1	V

8	8	DB2.7DB2.0	Illumination	ILL	Illumination (linear)	0255 0510 lx		
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0255 0+51 °C		
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-in telegram		
						1: Data telegram		
29	1	DB0.2	Not Used (= 0)	Not Used (= 0)				
30	1	DB0.1	PIR Status	PIRS	PIR Status	Enum:		
						0: PIR on		
						1: PIR off		
31	1	DB0.0	Occupancy Button	осс		Enum:		
						0: Button pressed		
						1: Button released		

RORG	A5	4BS Telegram
FUNC	08	Light, Temperature and Occupancy Sensor
TYPE	02	Range Olx to 1020lx, 0°C to +51°C and Occupancy Button

E.g. for wall mounted sensor.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage	SVC	Supply voltage (linear)	0255	05.1	V
8	8	DB2.7DB2.0	Illumination	ILL	Illumination (linear)	0255	01020	lx
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0255	0+51	°C
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegrai	m
						1: Data te	elegram	
29	1	DB0.2	Not Used (= 0)					
30	1	DB0.1	PIR Status	PIRS	PIR Status	Enum:		
						0: PIR on		
						1: PIR off		
31	1	DB0.0	Occupancy Button	occ		Enum:		
						0: Button	pressed	
						1: Button	released	-

RORG	A5	4BS Telegram
FUNC	08	Light, Temperature and Occupancy Sensor
TYPE	03	Range 0lx to 1530lx, -30°C to +50°C and Occupancy Butto

E.g. for outdoor sensor.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage	SVC	Supply voltage (linear)	0255	05.1	V
8	8	DB2.7DB2.0	Illumination	ILL	Illumination (linear)	0255	01530	lx
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0255	-30+50	°C/
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegra	n
						1: Data t	elegram	
29	1	DB0.2	Not Used (= 0)					
30	1	DB0.1	PIR Status	PIRS	PIR Status	Enum:		
						0: PIR or		
						1: PIR of		

31	1	DB0.0	Occupancy Button	occ	 Enum	:
					0:	Button pressed
					1:	Button released

A5-09: Gas Sensor

RORG	A5	4BS Telegram			
FUNC	09	Gas Sensor			
TYPE	02	CO-Sensor 0 ppm to 1020 ppm			

Submitter: Unitronic AG

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage		Supply voltage (linear)	0255	05.1	V
8	8	DB2.7DB2.0	Concentration	Conc	Gas concentration	0255	01020	ppm
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0255	0+51	°C
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-in telegram		
						1: Data telegran	า	
29	1	DB0.2	Not Used (= 0)					
30	1	DB0.1	T-Sensor	TSN		Enum:		
						0: Temperature available	Sensor not	
						1: Temperature	Sensor availal	ole
31	1	DB0.0	Not Used (= 0))			<u> </u>	

RORG	A5	4BS Telegram
FUNC	09	Gas Sensor
TYPE	04	CO2 Sensor

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Humidity	HUM	Rel. Humidity (linear), 0.5 % = 1 bit	0200	0100	%
8	8	DB2.7DB2.0	Concentration	Conc	Concentration (linear), increment = 10 ppm	0255	02550	ppm
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear), increment = 0.2 °C	0255	0+51.0	°C
24	4	DB0.7DB0.4	Not Used (= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-ir 1: Data tel	n telegram egram	_
29	1	DB0.2	H-Sensor	HSN		availabl	y Sensor	
30	1	DB0.1	T-Sensor	TSN		Enum: 0: Tempera availabl	ature Sensor e	not

				1:	Temperature Sensor available
31	1	DB0.0	Not Used (= 0)		

RORG	A5	4BS Telegram
FUNC	09	Gas Sensor
TYPE	05	VOC Sensor

Submitter: NanoSense

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0		DB3.7DB2.0	VOC	Conc	VOC Concentration		065535	ppb
16	8	DB1.7DB1.0	VOC ID	VOC_ID	VOC identification	Enum:		
						0: VOCT (to	tal)	
		`				1: Formalde	hyde	
						2: Benzene		
						3: Styrene		
						4: Toluene		
						5: Tetrachlo	roethylene	
						6: Xylene		
						7: n-Hexane		
						8: n-Octane		
						9: Cyclopen	tane	
						10: Methanol		
						11: Ethanol		
						12: 1-Pentan	ol	
				//		13: Acetone		
				`		14: ethylene		
						15: Acetaldel	iyde ue	
						16: Acetic Ac		
						17: Propionic		
						18: Valeric Ad		
						19: Butyric A		
						20: Ammonia		
						22: Hydroger		
						23: Dimethyl:		
					\	24: 2-Butano	<u> </u>	nol)
						25: 2-Methylp		
						26: Diethyl et	her	
						255: ozone		
24	4		Not Used (= 0)	I				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-in t		
						1: Data tele	gram	
29	1	DB0.2	Not Used (= 0)					
30	2	DB0.1DB0.0	Scale Multiplier	SCM	Scale Multiplier	Enum:		
						0: 0.01		
						1: 0.1		
						2: 1		
						3: 10		

RORG	A5	4BS Telegram
FUNC	09	Gas Sensor
TYPE	06	Radon

Submitter: NanoSense

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Rang	Scale	Unit
0	10	DB3.7DB2.6	Radon		Radon activity (regulation is an average of 100 Bq/m3/24h)	01023	01023	Bq/m3
10	18	DB2.5DB0.4	Not Use	ed (= 0)		_		
28	1		LRN Bit	LRNB	LRN Bit	t	each-in elegram Data telegran	n
29	3	DB0.2DB0.0	Not Use	ed (= 0)				

RORG	A5	4BS Telegram
FUNC	09	Gas Sensor
TYPE	07	Particles

Submitter: NanoSense

Offset	Size	Bitrange	Data	ShortCut	Description	Valid R	ange	Scale	Unit
0	9	DB3.7DB2.7	Particles_10	PM10	Dust less than 10 µm (PM10)	0511		0511	µg/m3
9	9	DB2.6DB1.6	Particles_2.5	PM2.5	Dust less than 2.5 µm (PM2.5)	0511		0511	µg/m3
18	9	DB1.5DB0.5	Particles_1	PM1	Dust less than 1 µm (PM1)	0511		0511	μg/m3
27	1	DB0.4	Not Used (=	0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:			
						0: T	ēach-i	in telegr	am
						1: [Data te	elegram	
29	1	DB0.2	PM10 active	PM10a		Enum:			
						0: P	M10 r	not activ	e
						1: PM10 active			
30	1	DB0.1	PM2.5 active	PM2.5a		Enum:			
						0: P	PM2.5	not acti	ve
						1: P	PM2.5	active	,
31	1	DB0.0	PM1 active	PM1a		Enum:			
						0: P	M1 nc	t active	_
						1: P	M1 ac	tive	_

RORG	A5	4BS Telegram
FUNC	09	Gas Sensor
TYPE	08	Pure CO2 Sensor

Submitter: Afriso / EnOcean

Description

Pure CO2 sensor with 8 bit resolution and 0 – 2000ppm.

<u>Data exchange</u> <u>Direction: unidirectional</u> Addressing: broadcast

Communication trigger: event- & time-triggered Trigger event: change of value over threshold, heartbeat

Teach-in method: 4BS teach-in 2

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Use	ed (= 0)				
16	8	DB1.7DB1.0	CO2	CO2	CO2 measurement	0255	02000	ppm
24	4	DB0.7DB0.4	Not Use	ed (= 0)	_			

2	8	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum	:
							0:	Teach-in telegram
							1:	Data telegram
2	9	3	DB0.2DB0.0	Not Use	ed (= 0)			

RORG	A	5	4BS Telegram
FUNC	0.9	9	Gas Sensor
TYPE	09	9	Pure CO2 Sensor with Power Failure Detection

Submitter: Afriso / EnOcean

Descriptior

Pure CO2 sensor with 8 bit resolution and 0 – 2000ppm.

1 digital Input - Power failure detection.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Trigger event: change of value over threshold, heartbeat, change of digital Input

Teach-in method: 4BS teach-in 2

Remark

Power failure detection expresses that the device was cut from power source (unplugged / general power failure) and the device will probably stop functioning very soon. In this case the measured value CO2 is the last valid value.

Offset	Size	Bitrange	Data	ShortCut	Description	Val Ran		Scale	Unit
0	16	DB3.7DB2.0	Not Used (= 0)						
16	8	DB1.7DB1.0	CO2	CO2	CO2 measurement	0255	5	02000	ppm
24	4	DB0.7DB0.4	Not Used (= 0)						
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:			
						0: Teach-in telegram			am
						1:	Data	telegram	
29	1	DB0.2	Power Failure	PFD	Indicates if power supply has a	Enum:			
			detection		failure / is not available	0:	Power	r failure no	ot
							detec	ted	
								r failure	
							detec	ted	
30	2	DB0.1DB0.0	Not Used (= 0)						

RORG	A5	4BS Telegram
FUNC	09	Gas Sensor
TYPE	0A	Hydrogen Gas Sensor

Submitter: SiMICS

Description

Hydrogen Gas Sensor with 16 bit resolution and 0-2000 ppm

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication interval: -

Trigger event: change in gas concentration and temp

Tx delay: -Rx timeout: -

Teach-ir

Teach-in method: 4BS teach-in 2



<u>Security</u> Encryption supported: yes

Security level format: PSK, RLC, AES128

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Concentration	Conc	Gas concentration	065535	065535	ppm
16	8	DB1. <mark>7</mark> .DB1.0	Temperature	TEMP	Temperature (linear)	0255	-20+60	°C
24	4	DB0.7DB0.4	Supply voltage	SV	Supply voltage / super cap.	015	2.05.0	V
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		_
						0: Teach-in	telegram	
						1: Data tele	egram	
29	1	DB0.2	Not Used (= 0)					
30	1	DB0.1	Temp sensor	TSA	Temp sensor availability	Enum:		
			availability		at TMP	0: Temp sensor is not supported		
						1: Temp se supporte		
31	1	DB0.0	Supply voltage	SVA	Supply voltage	Enum:		
			availability		availability at SV	0: Supply v supporte	oltage is not ed	
						1: Supply v supporte	oltage is ed	

RORG	A5	4BS Telegram		
FUNC	09	Gas Sensor		
TYPE	0B	Radioactivity Sensor		

Submitter: SiMICS

Description

Radioactivity Sensor

<u>Data exchange</u> <u>Direction: unidirectional</u> Addressing: broadcast

Communication trigger: event- & time-triggered

Communication interval: -

Trigger event: change in radioactivity level

Tx delay: -Rx timeout: -

 $\frac{\underline{\text{Teach-in}}}{\text{Teach-in}} \ \underline{\text{method: 4BS teach-in 2}}$

Security

Encryption supported: yes

Security level format: PSK, RLC, AES128

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	DB3.7DB3.4	Supply voltage		Supply voltage / super cap.	015	2.05.0	V
4	4	DB3.3DB3.0	Not Used (= 0)					
8	16	DB2.7DB1.0	Radioactivity	Ract	Radiation level	065535	06553	According to
24	4	DB0.7DB0.4	Scale Multiplier	SCM	Scale Multiplier	Enum: 0: 0.001 1: 0.01 2: 0.1 3: 1 4: 10 5: 100		

						6: 1000 7: 10000 8: 100000
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram 1: Data telegram
29	2	DB0.2DB0.1	Value unit	VUNIT	The unit of the radiation level	Enum: 0: μSv/h 1: cpm 2: Bq/L 3: Bq/kg
31	1	DB0.0	Supply voltage availability	SVA	Supply voltage availability at SV	Enum: 0: Supply voltage is not supported 1: Supply voltage is supported

A5-10: Room Operating Panel

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	01	Temperature Sensor, Set Point, Fan Speed and Occupancy Control

Submitter: Kieback + Peter GmbH

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Turn-switch for fan	FAN	Turn-switch for fan speed	Enum:		
			speed				Stage	
				\			Auto	
				`			Stage 0	
						190209:	CI 1	
						165189:	Stage 1	
							Stage 2	
						145164:	Stage 2	
						0144:	Stage 3	
							J	
8	8	DB2.7DB2.0	Set point	SP	Set point (linear) Min Max+	0255	0255	N/A
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40	°C
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach	-in	
						telegr		
						1: Data t	elegram	
29	2	DB0.2DB0.1	Not Used (= 0)					
31	1	DB0.0	Occupancy	occ	Occupancy button	Enum:	1	
						1: Buttor	released	d
						0: Buttor	n pressed	

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	02	Temperature Sensor, Set Point, Fan Speed and Day/Night Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Turn-switch for fan	FAN	Turn-switch for fan speed	Enum:		
			speed			210255:	Stage Au	to
						190209:	Stage 0	
						165189:	Stage 1	
						145164:	Stage 2	
						0144:	Stage 3	
8	8	DB2.7DB2.0	Set point	SP	Set point (linear) Min Max+	0255	0255	N/A
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40	°C
24	4	DB0.7DB0.4	Not Used (= 0)					•
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegra	am
						1: Data t	elegram	
29	2	DB0.2DB0.1	Not Used (= 0)					
31	1	DB0.0	Slide switch 0/I	SLSW	Slide switch or Slide switch	Enum:		
					Day/Night	0: Positio Off	n I / Nigh	nt /
						1: Positio On	n O / Day	//

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	03	Temperature Sensor, Set Point Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used (=	0)				
8	8	DB2.7DB2.0	Set point	SP	Set point (linear) Min Max+	0255	0255	N/A
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-ii	n telegra	m
						1: Data te	legram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	04	Temperature Sensor, Set Point and Fan Speed Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	æ		Turn-switch for fan speed	FAN		Enum: 210255: 190209: 165189: 145164:	Stage Auto Stage 0 Stage 1 Stage 2	

						0144:	Stage 3	
8	8	DB2.7DB2.0	Set point	SP	Set point (linear) Min Max+	0255	0255	N/A
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40	°C
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach telegi		
							telegram	
29	3	DB0.2DB0.0	Not Used (= 0)	·			•	

RORG	A5	//			4BS Telegram
FUNC	10			7	Room Operating Panel
TYPE	05		Temp	erat	ure Sensor, Set Point and Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used (=	0)				
8	8	DB2.7DB2.0	Set point	SP	Set point (linear) Min Max+	0255	0255	N/A
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-i	n telegra	m
						1: Data te	legram	
29	2	DB0.2DB0.1	Not Used (=	0)				
31	1	DB0.0	Occupancy	occ	Occupancy button	Enum:		
						1: Button	released	
						0: Button	pressed	_

RORG	A5	4BS Telegram	
FUNC	10	Room Operating Panel	
TYPE	06	Temperature Sensor, Set Point and Day/	Night Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale Unit
0	8	DB3.7DB3.0	Not Used (= 0)				
8	8	DB2.7DB2.0	Set point	SP	Set point (linear) Min Max+	0255	0255 N/A
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40 °C
24	4	DB0.7DB0.4	Not Used (= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	0: Teach-ir 1: Data tel	telegram egram
29	2	DB0.2DB0.1	Not Used (= 0)				
31	1		Slide switch 0/I		Slide switch or Slide switch Day/Night	Off	I / Night / O / Day /

RORG A5 4BS Telegram	7.5	RORG	A5	4BS Telegram
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FUNC	10	Room Operating Panel
TYPE	07	Temperature Sensor, Fan Speed Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale Un	nit
0	8	DB3. <mark>7</mark> .DB3.0	Turn-switch for fan speed	FAN		Enum:		
	//					210255: 9	Stage Auto	
						190209: 9	Stage 0	
	`					165189: 9	Stage 1	
						145164: 9	Stage 2	
						0144: 9	Stage 3	
8	8	DB2.7DB2.0	Not Used (= 0)					
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40 °C)
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-i	n telegram	
						1: Data te	legram	
29	3	DB0.2DB0.0	Not Used (= 0)		_			

	_	
RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	08	Temperature Sensor, Fan Speed and Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Turn-switch for fan speed	FAN		Enum:		
						210255: S	Stage Aut	0
						190209: 5	Stage 0	
						165189: 5	Stage 1	
						145164: 9	Stage 2	
						0144: 5	Stage 3	
8	8	DB2.7DB2.0	Not Used (= 0)					
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40	°C
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-i	n telegra	m
						1: Data te	legram	
29	2	DB0.2DB0.1	Not Used (= 0)					
31	1	DB0.0	Occupancy	occ	Occupancy button	Enum:		
						1: Button	released	
						0: Button	pressed	

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	09	Temperature Sensor, Fan Speed and Day/Night Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range Scale Un	nit
0	8	DB3.7DB3.0	Turn-switch for fan	FAN		Enum:	
			speed			210255: Stage Auto	
						190209: Stage 0	
						165189: Stage 1	

						145164: Stage 2 0144: Stage 3
8	8	DB2.7DB2.0	Not Used (= 0)			_
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550 0+40 °C
24	4	DB0.7DB0.4	Not Used (= 0)			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram 1: Data telegram
29	2	DB0.2DB0.1	Not Used (= 0)	•		
31	1	DB0.0	Slide switch 0/I	SLSW	Slide switch or Slide switch Day/Night	Enum: 0: Position I / Night / Off 1: Position O / Day / On

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	0A	Temperature Sensor, Set Point Adjust and Single Input Contact

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used (= 0	0)				
8	8	DB2.7DB2.0	Set point	SP	Set point (linear) Min Max+	0255	0255	N/A
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40	°C
24	4	DB0.7DB0.4	Not Used (= 0))				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-ii	n telegra	m
						1: Data te	legram	
29	2	DB0.2DB0.1	Not Used (= 0))				
31	1	DB0.0	Contact State	CTST	Contact state	Enum:		
						0: closed		
						1: open		

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	0B	Temperature Sensor and Single Input Contact

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale L	Jnit
0	16	DB3.7DB2.0	Not Used (= 0))				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40 °	С
24	4	DB0.7DB0.4	Not Used (= 0))				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach	-in telegram	
						1: Data t	elegram	
29	2	DB0.2DB0.1	Not Used (= 0))				
31	1	DB0.0	Contact State	CTST	Contact state	Enum:		
						0: closed	 [
						1: open		

RORG A5 4BS Telegram

FUNC	10	Room Operating Panel
TYPE	0C	Temperature Sensor and Occupancy Contro

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3. <mark>7</mark> .DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-i	n telegra	m
						1: Data te	legram	
29	2	DB0.2DB0.1	Not Used (=	0)				
31	1	DB0.0	Occupancy	occ	Occupancy button	Enum:		
						1: Button	released	
						0: Button	pressed	_

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	0D	Temperature Sensor and Day/Night Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid	l Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)					
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	255	0	0+40	°C
24	4	DB0.7DB0.4	Not Used (=	0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum 0: 1:		telegran	<u>n</u>
29	2	DB0.2DB0.1	Not Used (=	0)					
31	1	DB0.0	Slide switch		Slide switch <mark>0</mark> /I or Sli <mark>de s</mark> witch Day/Night	Enum 0: 1:	Position Off	I / Night	

RORG	A5	4BS Telegram		
FUNC	10	Room Operating Panel		
TYPE	10	Temperature and Humidity Sensor, Set Point and Oc	cupanc	y Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Set point	SP	Set point (linear) Min Max+	0255	0255	N/A
8	8	DB2.7DB2.0	Humidity	HUM	Rel. Humidity (linear)	0250	0100	%
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0250	0+40	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-i	n telegra	m
						1: Data te	legram	
29	2	DB0.2DB0.1	Not Used (=	0)				
31	1	DB0.0	Occupancy	occ	Occupancy button	Enum:		
						1: Button	released	
						0: Button	pressed	

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	11	Temperature and Humidity Sensor, Set Point and Day/Night Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Set point	SP	Set point (linear) Min Max+	0255	0255	N/A
8	8	DB2.7DB2.0	Humidity	HUM	Rel. Humidity (linear)	0250	0100	%
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0250	0+40	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-ir	n telegran	n
						1: Data tel	egram	
29	2	DB0.2DB0.1	Not Used (=	0)				
31	1	DB0.0	Slide switch	SLSW	Slide switch 0/I or Slide switch	Enum:		
			Day/Night	0: Position	I / Night	/		
						Off		
					1: Position	O / Day ,	/	
						On		

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	12	Temperature and Humidity Sensor and Set Point

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Set point	SP	Set point (linear) Min Max-	- 0255	0255	N/A
8	8	DB2.7DB2.0	Humidity	HUM	Rel. Humidity (linear)	0250	0100	%
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0250	0+40	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-i 1: Data te	n telegra legram	m
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	13	Temperature and Humidity Sensor, Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used (=	0)				
8	8	DB2.7DB2.0	Humidity	HUM	Rel. Humidity (linear)	0250	0100	%
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0250	0+40	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-i	n telegra	m
						1: Data te	legram	
29	2	DB0.2DB0.1	Not Used (=	0)				

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31	1	DB0.0	Occupancy	occ	Occupancy button	Enum:
						1: Button released
						0: Button pressed

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	14	Temperature and Humidity Sensor, Day/Night Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used (=	0)				
8	8	DB2.7DB2.0	Humidity	HUM	Rel. Humidity (linear)	0250	0100	%
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0250	0+40	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram 1: Data telegram		
29	2	DB0.2DB0.1	Not Used (=	0)				
31	1	DB0.0	Slide switch		Slide switch 0/I or Slide switch Day/Night	Off	I / Night	

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	15	10 Bit Temperature Sensor, 6 bit Set Point Control

Offset	Size	Bitrange	Data	ShortCut	Description		Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used (=	0)					
8	6	DB2.7DB2.2	Set point		Set point (6 bit, linear) Min Max+		063	063	N/A
14	10	DB2.1DB1.0	Temperature	TMP	Temperature 10 bit (linear)		10230	-10+41.2	°C
24	4	DB0.7DB0.4	Not Used (=	0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit			in telegram elegram	_
29	3	DB0.2DB0.0	Not Used (=	0)		/			

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	16	10 Bit Temperature Sensor, 6 bit Set Point Control; Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used (=	0)			•	
8	6	DB2.7DB2.2	Set point	SP	Set point (linear) Min Max+	063	063	N/A
14	10	DB2.1DB1.0	Temperature	TMP	Temperature 10 bit (linear)	10230	-10+41.2	°C

24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-in telegram		
						1: Data telegram		
29	2	DB0.2DB0.1	Not Used (=	0)				
31	1	DB0.0	Occupancy	occ	Occupancy button	Enum:		
						1: Button released		
						0: Button pressed		

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	17	10 Bit Temperature Sensor, Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	14	DB3.7DB2.2	Not Used (=	0)				
14	10	DB2.1DB1.0	Temperature	TMP	Temperature 10 bit (linear)	10230	-10+41.2	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegram	
						1: Data t	elegram	
29	2	DB0.2DB0.1	Not Used (=	0)				
31	1	DB0.0	Occupancy	occ	Occupancy button	Enum:		
						1: Buttor	released	
						0: Buttor	pressed	

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	18	Illumination, Temperature Set Point, Temperature Sensor, Fan Speed and Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Illumination		Illumination (linear), 251: Over range, 252-255: reserved	0250	01000	lx
8	8	DB2.7DB2.0	Temp Setpoint	TMPSP	Temperature Set point (linear)	2 500	0+40	°C
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2500	0+40	°C
24	1	DB0.7	Not Used (= 0)					
25	3	DB0.6DB0.4	Fan Speed	FAN	Fan Speed	1: S 2: S 3: S 4: S 5: S 6: S	peed 0 peed 1 peed 2 peed 3 peed 4 peed 5	
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	1: D	each-in elegram ata elegram	
29	1	DB0.2	Not Used (= 0)	•				

30	1		Occupancy enable/disable		Occupancy enable/disable; if occupancy is disabled ignore DB0.0 (occu. button)	Enum: 0:	: Occupancy enabled
						1:	Occupancy disabled
31	1	DB0.0	Occupancy button	ОВ		Enum	
						0:	Button
							pressed
						1:	Button
							released

RORG	A5		4BS Telegram
FUNC	10		Room Operating Panel
TYPE	19	Humidity,	Temperature Set Point, Temperature Sensor, Fan Speed and Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Humidity	HUM	Rel. Humidity (linear)	0250	0100	%
8	8	DB2.7DB2.0	Temp Setpoint	TMP Sp	Temperature Set point (linear)	2500	0+40	°C
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2500	0+40	°C
24	1	DB0.7	Not Used (= 0)					
25	3	DB0.6DB0.4	Fan speed	FAN	Fan Speed	Enum: 0: Auto 1: Speed 2: Speed 3: Speed 4: Speed 5: Speed 6: Speed 7: Off	1 2 3 4	
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach- telegra		
29	1	DB0.2	Not Used (= 0)					
30	1	DB0.1	Occupancy button	ОВ			pressed released	<u> </u>
31	1	DB0.0	Occupancy enable/disable	OED		Enum: 0: Occupa enable 1: Occupa disable	d ancy	

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	1A	Supply voltage monitor, Temperature Set Point, Temperature Sensor, Fan Speed and Occupancy Control

Offset Size B	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
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0	8	DB3.7DB3.0	Supply Voltage	SV	0 5.0 V linear (super cap); 251-255 reserved for error code	0250	05	V
8	8	DB2.7DB2.0	Temp Setpoint	TMP Sp	Temperature Set Point (linear)	2500	0+40	°C
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2500	0+40	°C
24	1	DB0.7	Not Used (= 0)					
25	3	DB0.6DB0.4	Fan speed	FAN	Fan Speed	1: Sr 2: Sr 3: Sr 4: Sr 5: Sr	peed 0 peed 1 peed 2 peed 3 peed 4 peed 5	
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	te	ach-in legram ata telegra	m
29	1	DB0.2	Not Used (= 0)					
30	1	DB0.1	Occupancy enable/disable	OED		1: Od	ccupancy abled ccupancy sabled	
31	1	DB0.0	Occupancy button	OB		1: Bu	itton essed itton leased	

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	1B	Supply Voltage Monitor, Illumination, Temperature Sensor, Fan Speed and Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply Voltage	SV	(super cap) 251 – 255 reserved for error code	0250	05	V
8	8	DB2.7DB2.0	Illumination	ILL	Illumination (linear), 251: Over range, 252-255: reserved	0250	01000	lx
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2500	0+40	°C
24	1	DB0.7	Not Used (= 0)					
25	3	DB0.6DB0.4	Fan speed	FAN	Fan Speed	2: Spe 3: Spe 4: Spe 5: Spe	ed 0 ed 1 ed 2 ed 3 ed 4 ed 5	
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	tele	ch-in gram a telegran	n

29	1	DB0.2	Not Used (= 0)			
30	1	DB0.1	Occupancy enable/disable	OED	Enum 0:	: Occupancy enabled
					1:	Occupancy disabled
31	1	DB0.0	Occupancy button	ОВ	Enum 0:	: Button pressed
					1:	Button released

RORG	A5	4BS Telegram	
FUNC	10	Room Operating Panel	
TYPE	1C	Illumination, Illumination Set Point, Temperature Sensor, Fan Speed and Occupanc Control	У

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Illumination	ILL	Illumination (linear), 251: Over range, 252-255: reserved	0250	01000	lx
8	8	DB2.7DB2.0	Illumination Set Point	ILLSP		0250	01000	
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2500	0+40	°C
24		DB0.7	Not Used (= 0)		1			
25		DB0.6DB0.4	Fan speed	LRNB	LRN Bit	2: Spe 3: Spe 4: Spe 5: Spe 6: Spe 7: Off Enum: 0: Tea tele	ed 0 ed 1 ed 2 ed 3 ed 4 ed 5 ch-in gram a telegrar	
						1. 540	a to.og.a.	
29		DB0.2	Not Used (= 0)					
30	1	DB0.1	Occupancy enable/disable	OED		ena 1: Occ	upancy bled upancy abled	
31	1	DB0.0	Occupancy button	ОВ		1: But	ssed	

RORG	A5	4BS Telegram	
FUNC	10	Room Operating Panel	
TYPE	1D	Humidity, Humidity Set Point, Temperature Sensor, Fan Speed and Occupancy Co	ntrol

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Humidity	HUM	Rel. Humidity (linear)	0250	0100	%
8	8	DB2.7DB2.0	Humidity Set Point	HUMSP	Humidity Set Point (linear)	0250	0100	%
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2500	0+40	°C
24	1	DB0.7	Not Used (= 0)					
25	3	DB0.6DB0.4	Fan speed	FAN	Fan Speed	Enum: 0: Auto 1: Speed 0 2: Speed 1 3: Speed 2 4: Speed 3 5: Speed 4 6: Speed 5 7: Off	1 2 3 4	
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-ii 1: Data te	n telegrar legram	n
29	1	DB0.2	Not Used (= 0)					
30	1	DB0.1	Occupancy enable/disable	OED		Enum: 0: Occupa enabled 1: Occupa disabled	ncy	
31	1	DB0.0	Occupancy button	ОВ			pressed released	_

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	1E	see A5-10-1B

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	1F	Temperature Sensor, Set Point, Fan Speed, Occupancy and Unoccupancy Control

Submitter: Distech Controls

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	æ		Turn-switch for fan speed	FAN	Turn-switch for fan speed	Enum: 210255: S 190209: S 165189: S 145164: S 0144: S	Stage 0 Stage 1	0
8	8	DB2.7DB2.0	Set Point	SP	Set point (linear) Min Max+	0255	0255	N/A
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40	°C 🛕
24	1	DB0.7	Not Used (= 0)					
25	1	DB0.6	Temperature flag	TMP_F	Temperature flag	Enum: 1: Temper present		

						0:	Temperature absent
26	1	DB0.5	Set point flag	SP_F	Set point flag	Enum	:
						1:	Set point present
						0:	Set point absent
27	1	DB0.4	Fan speed flag	FAN_F	Fan speed flag	Enum	:
						1:	Fan speed present
						0:	Fan speed absent
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum	:
	1					0:	Teach-in telegram
						1:	Data telegram
29	1	DB0.2	Not Used (= 0)				
30	1	DB0.1	Unoccupancy	UNOCC	Unoccupancy button	Enum	:
						0:	Button pressed
						1:	Button released
31	1	DB0.0	Occupancy	occ	Occupancy button	Enum	:
						0:	Button pressed
						1:	Button released

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	20	Temperature and Set Point with Special Heating States

Submitter: MSR-Solutions GmbH, Wangen i.Allg.

Description:

Set Point for Heating Control, Temperature, User Activity.

This EEP defines a Room Operating Panel that contains a sensor for temperature measurement. The set point selector knob determines the desired room temperature with the ability to set special set point modes for heating control. User activity and the sensor's battery state are indicated in the telegram.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication intervall: 1200 s

Trigger event: change of any input signal

Tx delay: n/a

Rx timeout: 0 ms (minimum time between two received messages)

Teach-in method: 4BS teach-in 2 / Universal teach-in

Security Encryption supported: no

Security level format: -

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Set Point	SP	Set point (linear) Min Max+	0255	0255	N/A
8	8	DB2.7DB2.0	Not Used (= 0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0250	0+40	°C
24	1	DB0.7	Not Used (= 0)				
25	2	DB0.6DB0.5	Set point mode		Selection of heating mode	SP 1: Frost protect	ontrol (e.g. de	
27	1	DB0.4	Battery state	BATT	Battery change needed	Enum: 0: Battery ok 1: Battery low	_	

28	1	Ļ	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:
							0: Teach-in telegram
							1: Data telegram
29	2	2	DB0.2DB0.1	Not Used (= 0)	-	
31	1		DB0.0	User activity	ACT	User intervention action	Enum:
						on device	0: No user action
							1: User interaction

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	21	Temperature, Humidity and Set Point with Special Heating States

Submitter: MSR-Solutions GmbH, Wangen i.Allg.

Description:

Set Point for Heating Control, Temperature, Humidity, User Activity.

This EEP defines a Room Operating Panel that contains sensors for temperature and humidity. The set point selector knob determines the desired room temperature with the ability to set special set point modes for heating control. User activity and the sensor's battery state are indicated in the telegram.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication intervall: 1200 s

Trigger event: change of any input signal

Tx delay: n/a

Rx timeout: 0 ms (minimum time between two received messages)

Teach-in method: 4BS teach-in 2 / Universal teach-in

Security Encryption required: no

Security level format: -

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Set Point	SP	Set point (linear) Min Max+	0255	0255	N/A
8	8	DB2.7DB2.0	Humidity	HUM	Rel. humidity (linear)	0250	0100	%
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0250	0+40	°C
24	1	DB0.7	Not Used $(= 0)$)				
25	2	DB0.6DB0.5	Set point mode	SPM	Selection of heating mode	Enum: 0: Room temp by SP 1: Frost prote 2: Automatic (e.g. define program) 3: Reserved	control	ined
27	1	DB0.4	Battery state	BATT	Battery change needed	0: Battery ok 1: Battery low		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in te 1: Data telegr		
29	2	DB0.2DB0.1	Not Used (= 0))				
31	1	DB0.0	User activity	ACT	User intervention action on device	Enum: 0: No user act 1: User intera		

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	22	Temperature, Setpoint, Humidity and Fan Speed

Submitter: Thermokon Sensortechnik GmbH

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication interval: time-triggered (configurable at the device) & event-triggered

Trigger event: setpoint change, fan speed change

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: 4BS teach-in 2

Security

Encryption supported: no Security level format: -

Product Description

The device represented by this EEP is a "Room Operating Panel with Display". It is powered by solar cell.

It is equipped with the following features:

- Temperature Sensor
- Humidity Sensor
- Temperature Setpoint Adjustment
- Fanspeed Adjustment

For pairing the unidirectional "4BS Teach-In Variation 2" method is used.

The device transmits the actual sensor values periodically (Default: 1000s) or on an event like "Temperature Setpoint Adjustment" or "Fanspeed Adjustment".

Temperature Sensor, Humidity Sensor:

The environmental sensors are updated periodically (adjustable, default: 100s) and, if there is a change, the updated values will be send immediately.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Relative Setpoint	SP	Setpoint (linear) Min Max	+ 0255	0255	N/A
8	8	DB2.7DB2.0	Humidity	HUM	Rel. Humidity (linear)	0250	0100	%
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0250	0+40	°C
24	3	DB0.7DB0.5	Fanspeed	FAN	Fanspeed	Enum:		
						0: Auto		
						1: Spec	d 0 / OFF	=
						2: Spee	ed 1	
						3: Spee	ed 2	
					\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	4: Spee	ed 3	
						5 7: Rese	rved	
27	1	DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-i	n telegra	m
						1: Data te	legram	
29	3	DB0.2DB0.0	Not Used (= 0)					

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	23	Temperature, Setpoint, Humidity, Fan Speed and Occupancy

Submitter: Thermokon Sensortechnik GmbH

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication interval: time-triggered (configurable at the device) & event-triggered

Trigger event: setpoint change, fan speed change, change of occupancy-state

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: 4BS teach-in 2

Security

Encryption supported: no Security level format: -

Product Description

The device represented by this EEP is a "Room Operating Panel with Display". It is powered by solar cell.

It is equipped with the following features:

- Temperature Sensor
- Humidity Sensor
- Setpoint Adjustment
- Fanspeed Adjustment
- Occupancy-State Adjustment

For pairing the unidirectional "4BS Teach-In Variation 2" method is used.

The device transmits the actual sensor values periodically (Default: 1000s) or on an event like "Setpoint Adjustment" or "Fanspeed Adjustment".

Temperature Sensor, Humidity Sensor:

The environmental sensors are updated periodically (adjustable, default: 100s) and, if there is a change, the updated values will be send directly.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Relative Setpoint	SP	Setpoint (linear) Min Max+	0255	0255	N/A
8	8	DB2.7DB2.0	Humidity	HUM	Rel. Humidity (linear)	0250	0100	%
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0250	0+40	°C
24	3	DB0.7DB0.5	Fanspeed	FAN	Fanspeed	Enum:		
						0: Auto		
						1: Spee	d 0 / OFF	=
						2: Spee	d 1	
						3: Spee	d 2	
						4: Spee	d 3	
						5 7: Rese	rved	
27	1	DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-i	n telegra	m
						1: Data te	legram	
29	2	DB0.2DB0.1	Not Used (= 0)					
31	1	DB0.0	Occupancy	occ	Occupancy	Enum:		
					`	0: Unoccu	pied	
						1: Occupie	ed	

A5-11: Controller Status

RORG	A5	4BS Telegram	
FUNC	11	Controller Status	
TYPE	01	Lighting Controller	

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Illumination	ILL	Illumination (linear)	0255	0510	lx
8	8	DB2.7DB2.0	Illumination Set Point	ISP	Illumination Set Point (Min Max.) (linear)	0255	0255	N/A
16	8	DB1.7DB1.0	Dimming Output Level	DIM	Dimming Output Level (Min Max.) (linear)	0255	0255	N/A
24	1	DB0.7	Repeater	REP	Repeater	Enum:		
						0: disab	led	
	,					1: enab	led	
25	1	DB0.6	Power Relay Timer	PRT	Power Relay Timer	Enum:		
						0: disab	led	
						1: enab	led	
26	1	DB0.5	1 3	DHV	Daylight Harvesting	Enum:		
			Harvesting			0: disab		
						1: enab	led	
27	1	DB0.4	Dimming	EDIM	Dimming	Enum:		
							hing load	
							ning load	
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-in telegram		
							telegran	1
29	1	DB0.2	Magnet Contact	MGC	Magnet Contact	Enum:		
						0: open		
			`			1: close	d	
30	1	DB0.1	Occupancy	OCC	Occupancy	Enum:		
						0: unoc	cupied	
						1: occup	oied	
31	1	DB0.0	Power Relay	PWR	Power Relay	Enum:	_	
						0: off	_	
						1: on		

RORG	A5	4BS Telegram
FUNC	11	Controller Status
TYPE	02	Temperature Controller Output

Submitter: Thermokon Sensortechnik GmbH

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Control Variable	CVAR	Actual value of controller	0255	0100	%
8	8	DB2.7DB2.0	FanStage	FAN	Actual value of fan	1: Stage 2: Stage 3: Stage 16: Stage 17: Stage 18: Stage	0 Manual 1 Manual 2 Manual 3 Manual 0 Automati 1 Automati 2 Automati 3 Automativailable	ic
16	8	DB1.7DB1.0	Actual Setpoint	ASP	Occupied: Basic setpoint occupied + Setpoint shift + Sensor offset StandBy:	0255	0+51.2	°C

					Basic setpoint standBy + Setpoint shift Unoccupied: Basic setpoint unoccupied + setpoint shift	
24	1	DB0.7	Alarm	ALR	In case of internal error alarm is set	Enum: 0: No alarm 1: Alarm
25	2	DB0.6DB0.5	Controller mode	СТМ	Actual state of controller	Enum: 1: Heating 2: Cooling 3: Off
27	1	DB0.4	Controller state	CST	Automatic control, or is controlled from another device	Enum: 0: Automatic 1: Override
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram 1: Data telegram
29	1	DB0.2	Energy hold-off	ERH	Stop control if window is opened	Enum: 0: Normal 1: Energy hold-off/
30	2	DB0.1DB0.0	Room occupancy	RO	Actual room occupancy	Enum: 0: Occupied 1: Unoccupied 2: StandBy 3: Frost

RORG	A5	4BS Telegram
FUNC	11	Controller Status
TYPE	03	Blind Status

Submitter: PEHA / infratec

This controller status is specific for blinds, awning and shutter modules. All modules can use this 4BS telegram to send all information about the status, the position and errors of the module, if these data are available.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Blind/shutter pos.	BSP		0100	0100	%
8	1	DB2.7	Angle sign	AS		0: Positive sign 1: Negative sig		
9	7	DB2.6DB2.0	Angle	AN	Angle in 2° steps (e.g. 0 = 0°, 90 = 180°)	0180	0360	0
16	1		Position value flag	PVF		Enum: 0: No Position value 1: Position value		ble
17	1		Angle value flag	AVF		Enum: 0: No Angle va 1: Angle value		
18	2	DB1.5DB1.4	Error state	ES		Enum: 0: No error pre 1: End-position configured 2: Internal failu	s are not	

						3:	Not used
20	2	DB1.3DB1.2	End-position	EP		Enum: 0: 1: 2: 3:	No End-position available No End-position reached Blind fully open Blind fully closed
22	2	DB1.1DB1.0	Status	ST		Enum: 0: 1: 2: 3:	No Status available Blind is stopped Blind opens Blind closes
24	1	DB0.7	Service Mode	SM		Enum: 0: 1:	Normal mode Service mode is activated (For example for maintenance)
25	1	DB0.6	Mode of the position	МОТР		Enum: 0: 1:	Normal mode: 0% Blind fully open / 100% Blind fully close Inverse mode: 100% Blind fully open / 0% Blind fully close
26	2	DB0.5DB0.4	Not Used $(= 0)$				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: 1:	: Teach-in telegram Data telegram
29	3	DB0.2DB0.0	Not Used (= 0)				

RORG	A5	4BS Telegram			
FUNC	11	Controller Status			
TYPE	04	Extended Lighting Status			

Submitter: PEHA / infratec

This status is an extended answer of new lighting-controllers. All modules can use this 4BS telegram to send all information about the status and errors of the module, if these data are available.

Offset	Cino	Ditropgo	Data	Ch ortCut	Description	Valid Dange	Scale	Unit		
					Description		Scale	Unit		
0	8	DB3.7DB3.0	Parameter 1	P1		Mode 1: R - Red (0	rgy metering value (MSB			
8	8	DB2.7DB2.0	Parameter 2	P2		Enum: Mode 0: Lamp ope 15 8) Mode 1: G - Green Mode 2: Energy me LSB) Mode 3: Not used	(0 255)			
16	8	DB1.7DB1.0	Parameter 3	P3		Enum: Mode 0: Lamp ope LSB) Mode 1: B - Blue (Mode 2: Unit for er Enum: 0 = mW 1 = W 2 = kW	0 255)			

						3 = MW 4 = Wh 5 = kWh 6 = MWh 7 = GWh 8 = mA 9 = 1/10 A 10 = mV 11 = 1/10 V 12 15 Not used Mode 3: Not used
24	1	DB0.7	Service Mode	SM		Enum: 0: Normal mode 1: Service mode is activated. (For example for maintenance)
25	1	DB0.6	Operating hours flag	OHF	For Mode 0	Enum: 0: No lamp operating hours available 1: Lamp operating hours available
26	2	DB0.5DB0.4	Error state	ES		Enum: 0: No error present 1: Lamp-failure 2: Internal failure 3: Failure on the external periphery
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram 1: Data telegram
29	2	DB0.2DB0.1	Parameter Mode	PM	2	Enum: 0: 8 Bit Dimmer Value and Lamp operating hours 1: RGB Value 2: Energy metering value 3: Not used
31	1	DB0.0	Status	ST		Enum: O: Lighting off 1: Lighting on

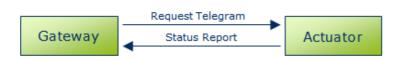
RORG	A5	4BS Telegram				
FUNC	11	Controller Status				
TYPE	05	Dual-Channel Switch Actuator (BI-DIR)				

Submitter: Nanjing Putian Telecommunications CO., Ltd.,

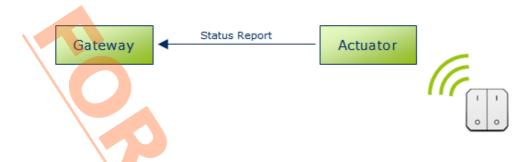
Description

This EEP is used for sending the latest relay status (including current working mode) of a dual-channel switch actuator. The telegram is sent when the relay status changes or a gateway request is received. Each time the gateway is powered on, it will send a request telegram to request that the actuator reports its latest relay status, while in normal working state, it won't send any telegram to the actuator and only receive the relay status from the actuator.

1) Gateway first power on:



2) When the actuator receives a switch telegram and its status changes:



Data exchange

Direction: bi-directional Addressing: broadcast

Communication trigger: event & request

Communication interval: -

Trigger event: change of relay status

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: 4BS teach-in 2

Security

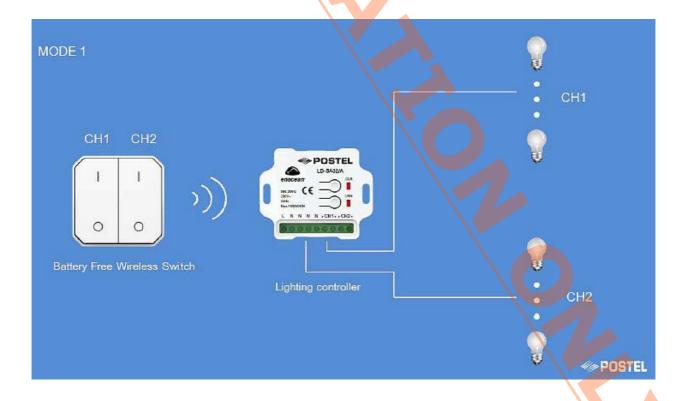
Encryption supported: no Security level format: -

Appendix Operation mode description:

Mode 1:

One switch controls one dual-channel actuator. Each rock controls one channel.

I: power ON, O: power OFF

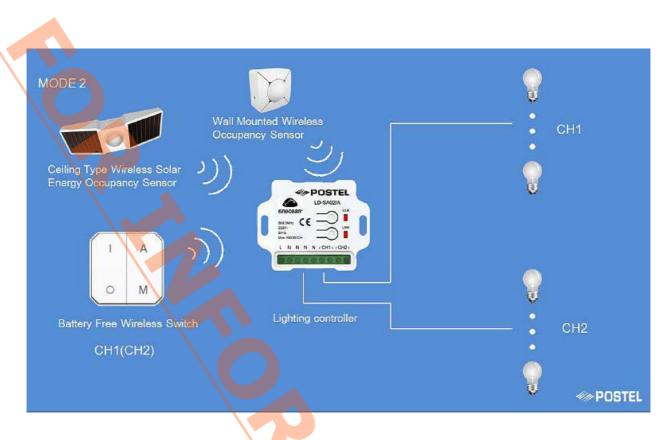


Mode 2:

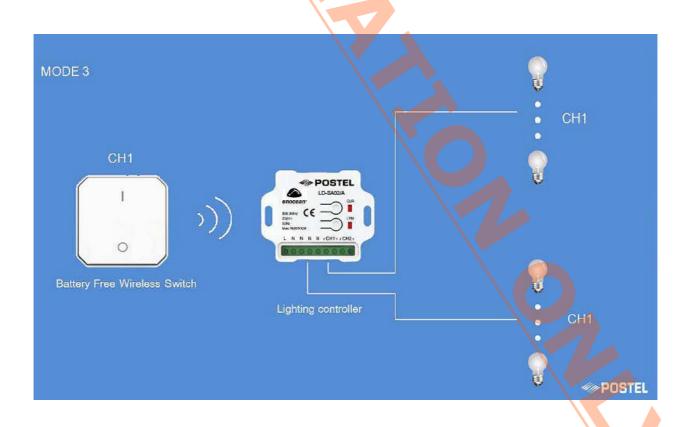
In this mode, actuator can be controlled by both switch and occupancy sensor, also can be set "Auto" control by occupancy sensor or "Manual" control by switch through button "A" or "M". Each channel can be controlled

EEP 2.6.4 Specification © EnOcean Alliance

independently.

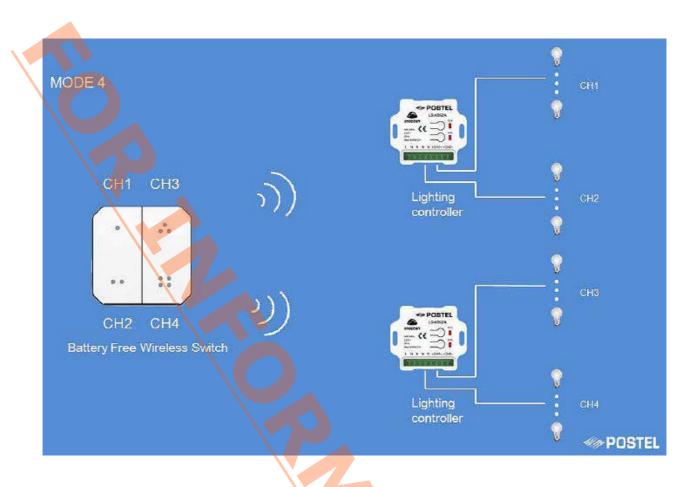


Mode 3:
A bit like mode 1, but single rocker button controls two channels one time.



Mode 4:
One dual rock switch button can control two dual channel actuators as 4 channel

One dual-rock switch button can control two dual-channel actuators as 4 channel lighting in all. We can control one channel only through trigger the rock angle.



DIRECTION-1 = Gateway request telegram; from gateway to actuator DIRECTION-2 = Actuator status report; from actuator to gateway

DIRECTION-1

DIKLCI	1011	<u> </u>							
Offset	Size	Bitrange	Data	ShortCut	Description		ılid nge	Scale	Unit
0	28	DB3.7DB0.4	Not Used (=	0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum 0:	Teach- telegra		n
29 31		DB0.2DB0.1 DB0.0	Message	MT	Defines if the telegram is a request or	Enum			
			Туре		contains data	0:	Reque	st	

DIRECTION-2

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range Scale Unit
0	25	DB3.7DB0.7	Not Used (=	0)		
25	3	DB0.6DB0.4	Working Mode	WM	Actuators current working mode	Enum: 0b001: mode 1 0b010: mode 2 0b011: mode 3 0b100: mode 4
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram 1: Data telegram

	29	2	DB0.2DB0.1	Relay Status	RS	Actuators current relay status	Enum:	
						Bit 0.1: CH1 Bit 0.2: CH2	0b00:	CH1 off, CH2 off
							0b01:	CH1 on, CH2 off
							0b10:	CH1 off, CH2 on
							0b11:	CH1 on, CH2 on
Ī	31	1	DB0.0	Message	MT	Defines if the telegram is a request or contains data	Enum:	
				Туре			1:	Status Report

A5-12: Automated Meter Reading (AMR)

The meter reading is represented by 3 data bytes, a divisor and a flag that indicates it as a cumulative or a current value. A 4 bit info field gives additional information and is TYPE specific.

RORG	A5	4BS Telegram
FUNC	12	Automated Meter Reading (AMR)
TYPE	00	Counter

Submitter: EnOcean GmbH

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit		
0	24	DB3.7DB1.0	Meter reading		Current value or cumulative counter value	016777215		according to DT		
24	4	DB0.7DB0.4	Measurement channel	СН		015	015	1		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram 1: Data telegram				
29	1	DB0.2	Data type (unit)		Current value or cumulative counter value	Enum: 0: Cumulative value 1 1: Current value 1/s				
30	2	DB0.1DB0.0	Divisor (scale)		Divisor for counter value	Enum: 0: x/1 1: x/10 2: x/100 3: x/1000	0167772 0167772 0167772	.15		

RORG	A5	4BS Telegram
FUNC	12	Automated Meter Reading (AMR)
TYPE	01	Electricity

Submitter: EnOcean GmbH

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	24	DB3.7DB1.0	Meter	MR	current value in W or	016777215	according to	according to
			reading		cumulative value in kWh		DIV	DT

24	4	DB0.7DB0.4	Tariff info	TI		015		015	1
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum	:		
						0:	Teach-	in telegram	
						1:	Data t	elegram	
29	1		, ,	DT	Current value or cumulative	Enum	:		
			(unit)		value	0:	Cumul	ative value	kWh
						1:	Currer	nt value	W
30	2	DB0.1DB0.0	Divisor	DIV	Divisor for value	Enum	:		
			(scale)		0:	x/1			
								0167772	15
						1:	x/10		
								0167772	1.5
						2: x/1		0 467770	4.5
						0167772.15			.15
						3:	x/1000	016777.2	215

RORG	A5	4BS Telegram
FUNC	12	Automated Meter Reading (AMR)
TYPE	02	Gas

Submitter: EnOcean GmbH

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	24	DB3.7DB1.0	meter reading		Cumula <mark>tive valu</mark> e in m³ or Current value in liter/s	016777215	according to DIV	according to DT
24	4	DB0.7DB0.4	Tariff info	TI		015	015	1
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		in telegram elegram	_
29	1	DB0.2	data type (unit)		Current value or cumulative value	0: Cumul	ative value nt value	liter/s
30	2	DB0.1DB0.0	divisor (scale)	DIV	Divisor for value	Enum: 0: x/1 1: x/10 2: x/100 3: x/1000	0167772 0167772 0167772	1.5

RORG	A5	4BS Telegram
FUNC	12	Automated Meter Reading (AMR)
TYPE	03	Water

Submitter: EnOcean GmbH

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	24	DB3.7DB1.0	Meter	MR	Cumulative value in m ³ or	016777215	according to	according to
			reading		Current value in liter/s		DIV	DT

24	4	DB0.7DB0.4	Tariff info	TI		015		015	1
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum	:		
						0:	Teach-	in telegram	
						1:	Data t	elegram	
29	1		Data type	DT	Current value or cumulative	Enum	:		
			(unit)		value	0:	Cumul	ative value	m³
	//					1:	Curren	it value	Liter/s
30	2	DB0.1DB0.0		DIV	Divisor for value	Enum	:		
			(scale)			0:	x/1		
								0167772	15
						1:	x/10		
								0167772	1.5
						2:	x/100		
							0167772	.15	
						x/1000)		
								016777.2	215

RORG	A5	4BS Telegram
FUNC	12	Automated Meter Reading (AMR)
TYPE	04	Temperature and Load Sensor

Submitter: SIMICS, NTT East

Description

Temp and Load Sensor aimed for fridge and other application.

E.g. milk carton puts on this sensor in fridge. The sensor sends a signal of temp and remaining amount of milk (in gram). Since this sensor is battery-powered, battery level information is transmitted with Temp and Load information, too.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication interval: -Trigger event: load changed

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: 4BS teach-in 2

Security

Encryption supported: yes

Security level format: RLC + AES128

Offset	Sizo	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	14	DB3.7DB2.2	Meter reading	MR	Current value in gram	016383	016383	gram
14	2	DB2.1DB2.0	Not Used $(= 0)$)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0255	-40+40	°C
24	4	DB0.7DB0.4	Not Used (= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegrar	n
						1: Data t	elegram	∇
29	1	DB0.2	Not Used (= 0)				
30	2	DB0.1DB0.0	Battery Level	BL	Battery level	Enum:		
						0: 100-7	5%	
						1: 75-50	%	
						2: 50-25	%	
						3: 25-0%)	

RORG	A5	4BS Telegram
FUNC	12	Automated Meter Reading (AMR)
TYPE	05	Temperature and Container Sensor

Submitter: SIMICS, NTT East

Description

Temp and Container Sensor aimed for fridge and other application.

E.g. eggs or egg carton puts on the Container Sensor in fridge. The sensor sends a signal of temp and remaining of eggs. Since this sensor is battery-powered, battery level information is transmitted with other information, too.

<u>Data exchange</u> <u>Direction: unidirectional</u> Addressing: broadcast

Communication trigger: event- & time-triggered

Communication interval: -Trigger event: load changed

Tx delay: -Rx timeout: -

Teach-in

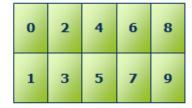
Teach-in method: 4BS teach-in 2

Encryption supported: yes

Security level format: RLC + AES128

Appendix

Location 0 - 9 are assigned as follows:



Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range Scale Unit
0	1	DB3.7	Position Sensor 0		Location 0	Enum: 0: not possessed 1: possessed
1	1	DB3.6	Position Sensor 1	PS1	Location 1	Enum: 0: not possessed 1: possessed
2	1	DB3.5	Position Sensor 2	PS2	Location 2	Enum: 0: not possessed 1: possessed
3	1	DB3.4	Position Sensor 3	PS3	Location 3	Enum: 0: not possessed 1: possessed
4	1	DB3.3	Position Sensor 4	PS4	Location 4	Enum: 0: not possessed 1: possessed
5	1	DB3.2	Position Sensor 5	PS5	Location 5	Enum: 0: not possessed 1: possessed

6	1	DB3.1	Position Sensor 6	PS6	Location 6	Enum:
						0: not possessed
						1: possessed
7	1	DB3.0	Position Sensor 7	PS7	Location 7	Enum:
						0: not possessed
						1: possessed
8	1	DB2.7	Position Sensor 8	PS8	Location 8	Enum:
	//					0: not possessed
						1: possessed
9	1	DB2.6	Position Sensor 9	PS9	Location 9	Enum:
						0: not possessed
			_			1: possessed
10	6	DB2.5DB2.0	Not Used (= 0)			
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0255 -40+40 °C
24	4	DB0.7DB0.4	Not Used (= 0)			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:
		\				0: Teach-in telegram
						1: Data telegram
29	1	DB0.2	Not Used (= 0)			
30	2	DB0.1DB0.0	Battery Level	BL	Battery level	Enum:
						0: 100-75%
						1: 75-50%
						1: 75-50% 2: 50-25%

RORG	A5	4BS Telegram
FUNC	12	Automated Meter Reading (AMR)
TYPE	10	Current meter 16 channels

Submitter: Ewattch

Description

This profile is used for up to 16 channels current meters.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered Communication interval: can be defined by user Trigger event: 10 or 20 % delta for observed value

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: 4BS teach-in 2

Security

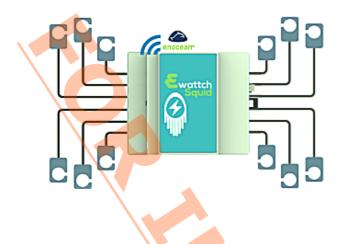
Encryption supported: no Security level format: -

Recommendation

Channels not used should not be transmitted.

Appendix

Our new product is a 12 channels current meter. It is able to measure, using a maximum of 12 current transformers, the current (mA) or cumulative current (mAh) of all of his channels. It is however not sending data for not configured channels (e.g. channels 12 to 15). The meter is sending values every 5 or 10 seconds, and in order to improve accuracy, a current fluctuation of more than 10 or 20 % will trigger a new transmission of the corresponding channel.



Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	24	DB3.7DB1.0	Meter reading	MR	Current value in mA or cumulative value in A.h	016777215	_	according to DT
24	4	DB0.7DB0.4	Measurement channel	СН	Channel no.	015	015	
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		in telegram elegram	_
29	1	DB0.2	Data type (unit)	DT	Current value or cumulative value		nt value	A.h mA
30	2	DB0.1DB0.0	Divisor (scale)	DIV	Divisor for value	Enum: 0: x/1 1: x/10	0167772 0167772	
						2: x/100	0167772) 016777	

A5-13: Environmental Applications

RORG	A5	4BS Telegram
FUNC	13	Environmental Applications
TYPE	01	Weather Station

A receiver that accepts EEP A5-13-01 at teach-in automatically needs to accept telegrams from the same ID that comply to the definitions of EEP A5-13-02 thru EEP A5-13-06. Different telegrams received from that ID need to be distinguished by their 4 bit identifiers.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Dawn sensor	DWS	Dawn sensor	0255	0999	lx
8	8	DB2.7DB2.0	Temperature	TMP	Outdoor Temp	0255	-40+80	°C
16	8	DB1.7DB1.0	Wind speed	WND	Wind speed	0255	070	m/s
24	4	DB0.7DB0.4	Identifier	ID	Identifier	Enum:		
						0x1:		

28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:	,
						0: Te	ach-in telegram
						1: Da	ata telegram
29	1	DB0.2	Day / Night	D/N	Day / Night	Enum:	
						0: Da	ау
						1: Ni	ght
30	1	DB0.1	Rain Indication	RAN	Rain Indication	Enum:	
	//					0: No	Rain
						1: Ra	ain
31	1	DB0.0	Not Used (= 0)			·	

RORG	A5	4BS Telegram
FUNC	13	Environmental Applications
TYPE	02	Sun Intensity

Submitter: Elsner electronics

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Sun - West	SNW	Sun - West,linear	0255	0150	klx
8	8	DB2.7DB2.0	Sun – South	SNS	Sun - South,linear	0255	0150	klx
16	8	DB1.7DB1.0	Sun – East	SNE	Sun - East,linear	0255	0150	klx
24	4	DB0.7DB0.4	Identifier	ID	Identifier	Enum:	_	
						0x2:	_	
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
							ich-in egram	
						1: Da		
							egram	
29	1	DB0.2	Hemisphere	HEM	0 = north / 1 = south, then swith Sun	Enum:		
					south to Sun North when in southern	0: No	rth	
					hemisphere	1: So	uth	
30	2	DB0.1DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	13	Environmental Applications
TYPE	03	Date Exchange

Submitter: Elsner electronics

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	3	DB3.7DB3.5	Not Used	(= 0)				
3	5	DB3.4DB3.0	Day	DY	Day	131	131	N/A
8	4	DB2.7DB2.4	Not Used	(= 0)				
12	4	DB2.3DB2.0	Month	MTH	Month (1->January)	112	112	N/A
16	1	DB1.7	Not Used	(= 0)				
17	7	DB1.6DB1.0	Year	YR	Year (0->Year 2000)	099	20002099	N/A
24	4	DB0.7DB0.4	Identifier	ID	Identifier	Enum: 0x3:		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in teleg 1: Data telegran		
29	2	DB0.2DB0.1	Not Used	(= 0)				

31	1	DB0.0	Source	SRC	Source	Enum:
						0: Real Time Clock
						1: GPS or equivalent (e.g. DCF77, WWV)

RORG	A5	4BS Telegram
FUNC	13	Environmental Applications
TYPE	04	Time and Day Exchange

Submitter: Elsner electronics

Recommendation: always transmit time in 24 hrs format

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	3	DB3.7DB3.5	Weekday	WDY	Weekday (1 ->	Enum:		
					Monday)	1: Monday		
						2: Tuesday		
						3: Wednesday		
						4: Thursday		
						5: Friday		
						6: Saturday		
						7: Sunday		
3	5	DB3.4DB3.0	Hour	HR	Hour	023	023	N/A
8	2	DB2.7DB2.6	Not Used (=	: 0)				
10	6	DB2.5DB2.0	Minute	MIN	Minute	059	059	N/A
16	2	DB1.7DB1.6	Not Used (=	: 0)				
18	6	DB1.5DB1.0	Second	SEC	Second	059	059	N/A
24	4	DB0.7DB0.4	Identifier	ID	Identifier	Enum:		
						0x4:		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-in telegra	m	
						1: Data telegram		
29	1	DB0.2	Time	TMF	Time Format	Enum:		
			Format			0: 24 hours		
						1: 12 hours		
30	1	DB0.1	AM/PM	A/PM	AM or PM	Enum:		
						0: AM		
						1: PM		
31	1	DB0.0	Source	SRC	Source	Enum:		
						0: Real Time Clock		
						1: GPS or equivale	nt (e.g. DCF	77,
						WWV)		

RORG	A5	4BS Telegram
FUNC	13	Environmental Applications
TYPE	05	Direction Exchange

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Elevation	ELV	Elevation (0° -> horizon)	0180	-90+90	0
8	7	DB2.7DB2.1	Not Used	(= 0)				
15	9	DB2.0DB1.0	Azimut	AZM	Azimuth (0° -> True north; clockwise)	0359	0359	0
24	4	DB0.7DB0.4	Identifier	ID	Identifier	Enum:		
						0x5:		

28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum	:
						0:	Teach-in telegram
						1:	Data telegram
29	3	DB0.2DB0.0	Not Used	(= 0)			

RORG	A5	4BS Telegram
FUNC	13	Environmental Applications
TYPE	06	Geographic Position Exchange

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit	
0	4	DB3.7DB3.4	Latitude(MSB)	LAT(MSB)	Latitude MSB	_	according to LAT(LSB)	according to LAT(LSB)	
4	4	DB3.3DB3.0	Longitude(MSB)		_	_	according to LOT(LSB)	according to LOT(LSB)	
8	8	DB2.7DB2.0	Latitude(LSB)	LAT(LSB)	Latitude LSB	04095	-90+90	0	
16	8	DB1.7DB1.0	Longitude(LSB)	LOT(LSB)	Longitude LSB	04095	-180+180	o	
24	4	DB0.7DB0.4	Identifier	ID	Identifier	Enum: 0x6:			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram			
						1: Data tele	gram		
29	3	DB0.2DB0.0	Not Used (= 0)						

RORG	A5	4BS Telegram
FUNC	13	Environmental Applications
TYPE	10	Sun position and radiation

Submitter: NanoSense

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	7	DB3.7DB3.1	Sun Elevation		Sun Elevation (linear); 91 - 127: reserved	090	090	o
7	1	DB3.0	Day / Night	D/N	Day / Night	Enum: 0: Day 1: Night		
8	8	DB2.7DB2.0	Sun Azimuth	SNA	Sun Azimuth 181 - 255: reserved	0180	-90+90	o
16	8	DB1.7DB1.0		SRA (MSB)	Solar Radiation (MSB)	according to SRA (LSB)	according to SRA (LSB)	according to SRA (LSB)
24	4	DB0.7DB0.4	Identifier	ID	Identifier	Enum: 0x7:		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-ir 1: Data tel	n telegram egram	
29	3	DB0.2DB0.0		SRA (LSB)	Solar Radiation (LSB) (Linear); 20012048: reserved	02000	02000	W/m2

A5-14: Multi-Func Sensor

RORG	A5	4BS Telegram
FUNC	14	Multi-Func Sensor
TYPE	01	Single Input Contact (Window/Door), Supply voltage monitor

Submitter: Lutuo Technology

Purpose (eg): Ventilation, Lighting, Alarm

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage		Supply voltage / super cap. (linear); 251 – 255 reserved for error code	0250	05.0	V
8	20	DB2.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-ir telegrar 1: Data tel	n	
29	2	DB0.2DB0.1	Not Used $(= 0)$					
31	1	DB0.0	Contact	CT		Enum: 0b0: Contact 0b1: Contact		_

RORG	A5	4BS Telegram
FUNC	14	Multi-Func Sensor
TYPE	02	Single Input Contact (Window/Door), Supply voltage monitor and Illumination

Submitter: Lutuo Technology

Purpose (eg): Ventilation, Lighting, Alarm

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage		Supply voltage / super cap. (linear); 251 – 255 reserved for error code	0250	05.0	V
8	8	DB2.7DB2.0	Illumination		Illumination (linear); 251 – over range, 252 - 255 reserved	0250	01000	lx
16	12	DB1.7DB0.4	Not Used (= 0))				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teachtelegra 1: Data to		
29	2	DB0.2DB0.1	Not Used (= 0))				
31	1	DB0.0	Contact	СТ		Enum: 0b0: Contac 0b1: Contac		_

RORG	A5	4BS Telegram
FUNC	14	Multi-Func Sensor
TYPE	03	Single Input Contact (Window/Door), Supply voltage monitor and Vibration

Submitter: Lutuo Technology

Purpose (eg): Ventilation, Lighting, Alarm, Intrusion (breakage of glass), Calling system

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage		Supply voltage / super cap. (linear);	0250	05.0	V
					251 – 255 reserved for error code			
8	20	DB2.7DB0.4	Not Used (= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
	//					0: Teach-in	telegram	1
						1: Data tele	gram	
29	1	DB0.2	Not Used (= 0)				
30	1	DB0.1	Vibration	VIB		Enum:		
						No vibrat	ion	
						0b0: detected		
						Vibration	detected	t
						0b1:		
31	1	DB0.0	Contact	CT		Enum:		_
						0b0: Contact	closed	_
						0b1: Contact	open	

RORG	A5				4BS Telegram
FUNC	14		//		Multi-Func Sensor
TYPE	04	Single Inpu	it Co	ontact (Window/Door), Supply voltage monitor, Vibration and Illumination

Submitter: Lutuo Technology

Purpose (eg): Ventilation, Lighting, Alarm, Intrusion (breakage of glass), Calling system

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage		Supply voltage / super cap. (linear); 251 - 255 reserved for error code	0250	05.0	V
8	8	DB2.7DB2.0	Illumination	ILL	Illumination (linear); 251 – over range, 252 - 255 reserved	0250	01000	lx
16	12	DB1.7DB0.4	Not Used (= 0))		_		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-ii 1: Data te	n telegram legram	
29	1	DB0.2	Not Used (= 0))				
30	1	DB0.1	Vibration	VIB		No vibra 0b0: detecte Vibratio		i
31	1	DB0.0	Contact	СТ		Enum: 0b0: Contact 0b1: Contact		-

RORG	A5	4BS Telegram
FUNC	14	Multi-Func Sensor
TYPE	05	Vibration/Tilt, Supply voltage monitor

Submitter: Lutuo Technology

Purpose (eg): Intrusion (breakage of glass), Calling system

	Offset Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
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0	8	DB3.7DB3.0	Supply voltage		Supply voltage / super cap. (linear); 251 - 255 reserved for error code		05.0	V
8	20	DB2.7DB0.4	Not Used (= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in 1: Data tele		1
29	1	DB0.2	Not Used (= 0)				
30	1	DB0.1	Vibration	VIB		Enum: No vibration 0b0: detected Vibration 0b1:		d
31	1	DB0.0	Not Used (= 0)				

RORG	A5	4BS Telegram
FUNC	14	Multi-Func Sensor
TYPE	06	Vibration/Tilt, Illumination and Supply voltage monitor

Submitter: Lutuo Technology

Purpose (eg): Intrusion (breakage of glass), Calling system

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage		Supply voltage / super cap. (linear); 251 - 255 reserved for error code		05.0	V
8	8	DB2.7DB2.0	Illumination	`	Illumination (linear); 251 – over range, 252 - 255 reserved	0250	01000	lx
16	12	DB1.7DB0.4	Not Used (= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-ii 1: Data te	n telegram legram	<u> </u>
29	1	DB0.2	Not Used (= 0)				
30	1	DB0.1	Vibration	VIB		Enum: No vibro Ob0: detecte Vibratio 0b1:		d
31	1	DB0.0	Not Used (= 0)				

A5-20: HVAC Components

RORG	A5	4BS Telegram
FUNC	20	HVAC Components
TYPE	01	Battery Powered Actuator (BI-DIR)

Submitter: Kieback + Peter GmbH

 ${\tt DIRECTION-1 = Transmit\ mode:\ Message\ from\ the\ actuator\ to\ the\ controller}$

DIRECTION-2 = Receive mode: Commands from the controller to the actuator; max. reponse time 1 sec.

Offset Size Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
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0	8	DB3.7DB3.0	Current Value	CV	Current value	0100 0100 %
8	1	DB2.7	Service On	SO	Service On	Enum: 1: on
9	1	DB2.6	Energy input enabled	ENIE	Energy input enabled	Enum: 1: true
10	1	DB2.5	Energy Storage	ES	Energy storage sufficiently charged	Enum: 1: true
11	1	DB2.4	Battery capacity	BCAP	Battery capacity; change battery next days	Enum: 0: true
12	1	DB2.3	Contact, cover open	cco	Contact, cover open	Enum: 1: true
13	1	DB2.2	Failure temperature sensor, out off range	FTS	Failure Temperature sensor, out off range	Enum: 1: true
14	1	DB2.1	Detection, window open	DWO	Detection, window open	Enum: 1: true
15	1	DB2.0	Actuator obstructed	ACO	Actuator obstructed	Enum: 1: true
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0255 0+40 °C
24	4	DB0.7DB0.4	Not Used (= 0)			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram 1: Data telegram
29	3	DB0.2DB0.0	Not Used (= 0)			

DIKECI	ION								
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit	
0	8	DB3.7DB3.0	Valve position or Temperature Setpoint	SP	· ·	0100 or 255	0100 or +40	% or °C	
8	8	DB2.7DB2.0	Temperature from RCU	ТМР	Temperature actual from RCU = 0b0 (Room controller-unit), see DB1.0 Maintenance mode ('service on'): DB_2.BIT_5: energy memory sufficiently charged =1 DB_2.BIT_4: battery capacity changing battery in the next days, need changing batteries = 0 Status feedback signal (service on, DB_2.BIT_7	2550	0+40	°C	
16	1	DB1.7	Run init sequence	RIN	The limit switching measures the travel and signals when an end position has been reached. This end position (valve zero point) in the actuator is stored.	Enum: 1: tru	е		
17	1	DB1.6	Lift set	LFS	Initialization, adjustment to the valve stroke. The Initialization is switched after receiving the	Enum: 1: tru	e		

					command. The valve is completely opened and closed during initialization.	
18	1	DB1.5	Valve open / maintenance	VO	After receiving an operation command, the actuator moves the valve in direction open or close. when reaching the end position, an automatic switch-off procedure is started. In service mode the valve can be set to open or closed always.	Enum: 1: true
19	1	DB1.4	Valve closed	VC	valve closed	Enum: 1: true
20	1	DB1.3	Summer bit, Reduction of energy consumption	SB	The radio communication between the actuator and the controller is restricted, sleep mode is extended. This functionality can be used for battery powered actuators.	Enum: 1: true
21	1	DB1.2	Set Point Selection	SPS	Set Point Selection for DB3	Enum: 0: Valve position (0-100%). Unit respond to controller. 1: Temperature set point 040°C. Unit respond to room sensor and use internal PI loop.
22	1	DB1.1	Set point inverse	SPN	Valve set point can be sent to the actuator normal or inverted. The selection is done by DB_1.Bit1. The implementation is done and is controlled in the actuator with DB_3. This function is used in dependence on the type of valve.	Enum: 1: true
23	1	DB1.0	Select function		RCU or 'Service on': After transmitting the command to the actuator, it can be send from the controller or a service device, the actuator sends a status feedback signal (service on, DB_2.BIT_7).	Enum: 0: RCU 1: service on
24	4		Not Used (= 0)			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram 1: Data telegram
29	3	DB0.2DB0.0	Not Used (= 0)			

RORG	A5	4BS Telegram
FUNC	20	HVAC Components
TYPE	02	Basic Actuator (BI-DIR)

Submitter: Spartan Peripheral Devices

Basic Actuator can be used by any manufacturer for linear or rotary actuator.

DIRECTION-1 = Transmit mode: Message from the actuator to the controller.

DIRECTION-2 = Receive mode: Commands from the controller to the actuator. To use with a BAS/Gateway system; max. reponse time 1 sec.

OffsetS	ize	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit	
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0	8	DB3.7DB3.0	Actual Value		Actual value (linear); can be a linear or rotation motion.	0100	0100 %
8	14	DB2.7DB1.2	Not Used	(= 0)			
22	1		Set point inverse		Set point inverse (Needs to be defined by manufacturer what zero(0) is equal to, and one(1) is equal to. Default state to be define as per product manufacturer	Enum: 1: 1	true
24	4	DB0.7DB0.4	Not Used	(= 0)			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	1:	Teach-in telegram Data
29	2	DB0.2DB0.0	Not Used	(= 0)		1	telegram

DIRECTION-2

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Valve Set point	VSP	Valve set Point (linear)	0100	0100	%
8	8	DB2.7DB2.0	Not Used	d (= 0)				
16	6	DB1.7DB1.2	Not Used	d (= 0)				
22	1	DB1.1	Set point inverse	VSP	'Set point inverse' needs to be defined by manufacturer what zero(0) is equal to, and one(1) is equal to. Default state to be define as per product manufacturer. It can send a command to invert functionality of the unit. In some instance some equipment might need 100% to represent fully extracted, in other fully retracted.	Enum: 1: t	rue	
23	5	DB1.0DB0.4	Not Used	d (= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	1: [Teach-in elegram Data elegram	
29	3	DB0.2DB0.0	Not Used	d (= 0)				

RORG	A5	4BS Telegram
FUNC	20	HVAC Components
TYPE	03	Line powered Actuator (BI-DIR)

Submitter: Spartan Peripheral Devices

DIRECTION-1 = Transmit mode: Message from the actuator to the controller.

DIRECTION-2 = Receive mode: Commands from the controller to the actuator; max. reponse time 1 sec.

DIRECTION-1

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Actual valve	AV	Actual valve	0100	0100	%
8	8	DB2.7DB2.0	Not Used (=	0)	-			
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0255	0+40	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-ii	n telegra	m
						1: Data te	legram	
29	3	DB0.2DB0.0	Not Used (=	0)				

Offset	Size	Bitrange	Data	ShortCut	Description	Valid	Scale	Unit	ı
--------	------	----------	------	----------	-------------	-------	-------	------	---

						Range		
0	8	DB3.7DB3.0	Actuator or Temperature Setpoint	ATS	Actuator Setpoint: in combination with BAS/Gateway controllers. Temperature Setpoint: The actuator can be used as self-sufficient room controller (pi controller) without integration in automation systems. Wherever the user wants room conditions to be individually controlled, the actuator can work in combination with a wireless room device (RCU).	255	r 0100 or +40	% or °C
8	8	DB2.7DB2.0	Temperature from RCU	TMPRC	Temperature actual from RCU = 0b0 (Room controller-unit)	2550	0+40	°C
16	5	DB1.7DB1.3	Not Used (= 0)				
21	1	DB1.2	Selection	SPS	Set Point Selection for DB3	1: Te Se 0. re	tuator Setp -100%); Ur spond to ntroller. mperature etpoint+40°C; Ur spond to roonsor and us ternal PI loo	nit om se
22	1	DB1.1	Set Point Inverse		Valve set point can be sent to the actuator normal or inverted through BAS/Gateway controller. The selection is done by DB_1.Bit1. in the actuator with DB_3. This function is used in dependence on the type of valve.	Enum: 1: tr	ue	
23	5	DB1.0DB0.4	Not Used $(= 0)$)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	te	ach-in legram ata telegram	1
29	3	DB0.2DB0.0	Not Used (= 0)				

RORG	A5	4BS Telegram							
FUNC	20	HVAC Components							
TYPE	04	Heating Radiator Valve Actuating Drive with Feed and Room Temperature Measurement, Local Set Point Control and Display (BI-DIR)							

Submitter: Holter Regelarmaturen GmbH & Co. KG

Description

The following document describes the communication between a controller and an intelligent heating radiator valve actuating drive with the following features:

- Feed temperature measurement
- Room temperature measurement
- Current position feedback
- Display
- Button
- On device temperature set point selection

In order to be able to process this information and control the actuator, every command has been included in this document. Each customer can use his own controller by implementing the EEP of this document.

Data exchange

Direction: bidirectional Addressing: unicast (ADT)

Communication trigger: event- & time-triggered

Communication interval: can be configured by the controller

Trigger event: a trigger event occurs when the button is pressed or the local set point is used

Tx delay: 550 ms is the maximum response time for Smart-Ack Devices and 1100 ms for devices which use the 4BS

teach-in method

Rx timeout: just 1 message per wake-up cycle

Teach-in

Teach-in method: Smart-Ack teach-in and 4BS teach-in Variation 3

Security

Encryption supported: no Security level format: -

Telegram Description of Direction 1 (Transmit mode / Message from the actuator to the controller)

This direction initializes the communication, shares the needed data and waits for an answer from the controller. This allows the device to work in deep sleep mode the rest of the time.

Each message from the actuator contains the following information:

Current Position (CP)

The current position is a feedback value from the actuator. It indicates the actual per cent position of the valve. The value 0 % means that the valve is completely closed and 100 % completely open. The controller can use this information for the room temperature regulation.

- Temperature Set Point OR Feed Temperature (FTS)*
 - * This byte is shared by the Temperature Set Point and the Feed Temperature value. Only one of these values is sent in the same message. Which value is transmitted is indicated by DB0.1 (TS bit).

The feed temperature is the water temperature in the radiator input, which can be useful for implementing several features in the home automation system.

The temperature set point is only sent when the user specifies a new room temperature by using the local temperature set point on the device.

- Room Temperature (TMP) OR Failure Code (FC)*
 - * This byte is shared by the Room Temperature and Failure Code Value. Only one of these values is sent in the same message. The value transmitted is indicated by DB0.0 (FL). By default it is the room temperature. The room temperature is the ambient temperature of the place in which the device is used and is measured by the actuator. This value is transmitted if no error occurred.

The Failure Code is transmitted instead of the Room Temperature if an error occurs.

• Measurement Status (MST)

The temperature measurements (room and feed temperature) can be deactivated in order to reduce the energy consumption. This can be specified only by the controller i.e. to implement summer mode or to replace the internal room temperature measurement of the actuator by an external one.

• Status Request (SRT)

The status request bit can be used to ask the controller about its status. If the controller does not send back the correct reply, the actuator will start its own room temperature regulation. With this feature, a frozen actuator would not interrupt the room temperature regulation.

Teach-in Bit (LRNB)

For establishing the radio link between the controller and the actuator, a teachin message has to be sent from the actuator to the controller. If the binary value 0 is transmitted, the message will be identified as a teach-in one and will allow the controller to receive the EnOcean-ID of the actuator.

• Button Lock Status (BLS)

The button lock status can be set by the controller. This enables or disables the manual room temperature selection. If locked, the manual room temperature selection on the actuator will be disabled and the user will be notified with a symbol on the display.

• Temperature Selection (TS)

If the user specifies a temperature set point manually on the device, this will be sent to the controller and indicated on the temperature selection field (TS). It can indicate that the field FTS contains the temperature set point (binary value = 1) or the feed temperature (binary value = 0).

• Failure (FL)

Indicates the occurrence of a failure. The room temperature value is replaced by the failure code if the bit FL has the binary value 1.

Telegram Description of Direction 2 (Receive mode / Commands from the controller to the actuator)

The messages from the controller to the actuator are sent in this direction. A message in this direction has to be sent after receiving a message from the actuator, in order to achieve a successful communication. If the controller message is not received by the actuator in a specific time after a direction 1 message, no information will be received by the actuator. The time that the actuator will wait for a reply is defined by the Smart-Ack Teach-In process. For controllers which cannot use Smart-Ack, the 4BS Teach-in Variation 3 has to be used, with a maximum response time

of 1100 ms.

Each message from the controller contains the following information:

Valve Position (POS)

The valve position is a set point position for the valve. It indicates the per cent position of the valve, which the actuator has to reach. The value 0 % means that the valve is completely closed and 100 % completely open. The controller should be able to regulate the room temperature by adjusting this value.

• Temperature Set Point (TSP)

The controller can send the temperature set point to the actuator in order to allow the user to see the actual specified temperature in the device display. This value does not affect room temperature regulation.

Measurement Control (MC)

The temperature measurements (room and feed temperature) can be deactivated in order to reduce energy consumption. This can be specified only by the controller i.e. to implement summer mode or to replace the internal room temperature measurement by the device with an external one. The measurement control bit enables the controller to activate or deactivate the measurements.

Wake-up Cycle (WUC)

To save energy, the actuator works in deep sleep mode the most of the time. Nevertheless it has to wake up to communicate with the controller and to reach the valve position specified by the controller. The longer the actuator remains in deep sleep mode, the more energy efficient will be your batteries. If fast response is required, the actuator has to communicate more frequently with the controller and that is why it should use a shorter wake-up cycle. If a fast room temperature control is not required, the wake-up cycle should be set by the controller as long as possible.

• Display Orientation (DSO)

The heater valves can be installed in different directions. That is why it can be useful to have the option to choose the fitting display orientation. This feature makes reading the display easier.

• Teach-in Bit (LRNB)

For establishing a radio link between the controller and the actuator, a teach-in telegram has to be sent from the controller to the actuator. If the binary value 0 is transmitted, the message will be identified as a teach-in one and will allow the device to receive the EnOcean-ID from the controller.

Button Lock Control (BLS)

The button lock status can be set by the controller. This enables or disables the manual room temperature selection. If locked, the manual room temperature selection on the actuator will be disabled and the user will be notified with a symbol on the display.

• Service Command (SER)

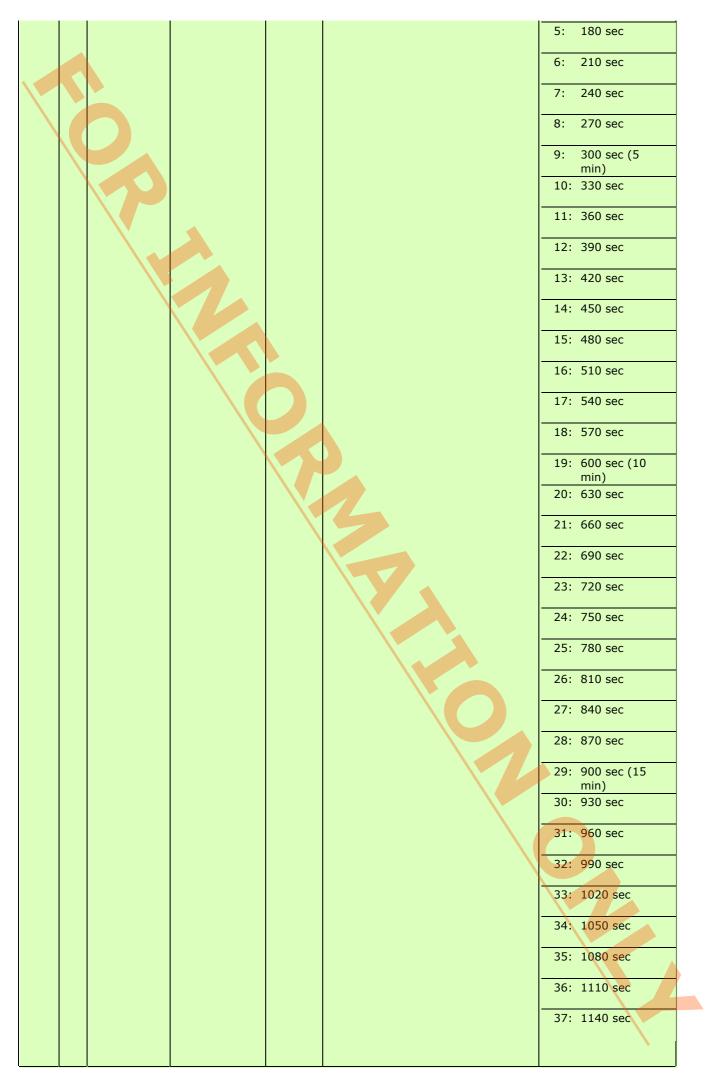
In order to adapt the actuator to a new valve, the controller can order the execution of some functions of the actuator:

- run initialisation: This function has to be executed for adapting the actuator to the length of the valve stroke.
- open valve: To facilitate the installation or maintenance of the valve, the actuator can open the valve completely. After completely opening the valve it is necessary to run the initialisation.
- close valve: Completely close the valve.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Current Position	CP	Current valve position	0100	0100	%
8	8	DB2.7DB2.0	Feed Temperature OR Temperature Set Point	FTS	Either current feed temperature value or temperature set point (defined by DB0.1)	0255	20 80 or 10 30	°C
16	8	DB1.7DB1.0	Room Temperature OR Failure Code	TMPFC	Current room temperature value (1030°C) OR Failure Code (Enum)	18: Batt 19: Reso 20: Fros	surement r tery empty erved	0 °C

1						1
						33: Blocked valve
						34 Reserved
						35:
						36: End point
						detection error
						37 Reserved
						39:
•						40: No valve
						41 Reserved
						48:
						49: Not taught in
						50 Reserved
			_			52:
						53: No response
						from controller
						54: Teach-in error
						55 Reserved
						255:
24	1	DB0.7	Measurement	MST	Shows if the	Enum:
			Status		temperature	0: Active
					measurement (feed	1: Inactive
					temperature and room temperature) is active	
25	1	DB0.6	Status Request	STR	Request for status from	Enum
23	1	DB0.0	Status Request	311	the controller	Enum:
					the controller	0: No change
						1: Status requested
26	2		Not Used (= 0)			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:
						0: Teach-in telegram
						1: Data telegram
29	1	DB0.2	Button Lock	BLS	Shows if all buttons on	Enum:
			Status		the actuator are locked	0: Unlocked
						1: Locked
30	1	DB0.1	Temperature	TS	Defines which	Enum:
	_	250.1	Selection	.5	temperature value is	0: Feed temperature
					transmitted in DB2	<u> </u>
24	_	5500	E 11			1: Temperature set point
31	1	DB0.0	Failure	FL	A failure occurred, see	Enum:
					DB1.7-DB1.0 for Failure Code	0: No failure (TMP is
					Code	transmitted)
						1: failure (FC is transmitted)

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Valve Position	POS	Valve position	0100	0100	%
8	8		Temperature Set Point	TSP	Temperature set point	0255	1030	°C
16	1	DB1.7	Not Used (= 0)					
17	1		Measurement Control	MC	Control the temperature measurement (feed temperature + room temperature)	Enum: 0: Ena 1: Disa		
18	6	DB1.5DB1.0	Wake-up Cycle	WUC	Defines the cyclic wake-up time		sec	



						38: 1170 sec
						39: 1200 sec (20 min) 40: 1230 sec
						41: 1260 sec
						42: 1290 sec
	`	199				43: 1320 sec
						44: 1350 sec
						45: 1380 sec
						46: 1410 sec
						47: 1440 sec
						48: 1470 sec
						49: 1500 sec (25 min)
						50: 3 hrs
						51: 6 hrs
						52: 9 hrs
						53: 12 hrs
					5	54: 15 hrs
				·		55: 18 hrs
						56: 21 hrs
						57: 24 hrs
						58: 27 hrs
						59: 30 hrs
						60: 33 hrs
						61: 36 hrs
						62: 39 hrs
						63: 42 hrs (max)
24	2	DB0.7DB0.6	Not Used (= 0)			
26	2	DB0.5DB0.4		DSO	Adjusts the display orientation	Enum: 0: 0° 1: 90° 2: 180° 3: 270°
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:
						0: Teach-in telegram
						1: Data telegram
29	1	DB0.2	Button Lock Control	BLC	Set the button lock status	Enum: 0: Unlocked
						1: Locked

30	2	DB0.1DB0.0		, ,	Enum	:
			Command	operations	0:	No change
					1:	Open valve
					2:	Run initialisation
					3:	Close valve

RORG	A5	4BS Telegram		
FUNC	20	HVAC Components		
TYPE	10	Generic HVAC Interface (BI-DIR)		

Submitter: Intesis Software SL

Functions: Mode, Vane Position, Fan Speed, Sensors and On/Off: With this EEP plus the already existing EEP A5-10-03 and A5-20-11 all the information of AC indoor unit can be sent and received allowing a much easier and complete control of these units.

DIRECTION-1 = Receive mode: Commands received by the HVAC interface. DIRECTION-2 = Transmit mode: Commands sent by the HVAC interface.

Offset	Size	Bitrange	Data	Short	Cut	Description	Valid Ra	ange	Scale Unit
0	8	DB3.7DB3.0	Mode	MD		The modes are the same as in KNX	Enum:		
						and LON allowing a more transparent	0:	Auto	
						integration with this protocols and it has plenty of free positions for future			
						expansion	1:	Heat	
						EXPENSION	_		
							2:	Morni	ng Warmup
							3:	Cool	
							٥.	COOI	
							4:	Niaht	Purge
								J	. 5.
							5:	Preco	ol
							6:	Off	
							7:	Toot	
							/:	Test	
							8:	Fmer	gency Heat
								Liner	geney meac
							9:	Fan o	nly
							10:	Free	cool
						· ·			
							11:	Ice	
							12:	Max h	neat
							12.	Max	leat
							13:	Econo	omic
								heat/	cool
							14:		midification
								(dry)	
							15:	Calibr	ation
							16:	Emer	gency cool
							10.	Liller	gency cool
							17:	Emer	gency
								steam	
							18:	max	cool

						19:	Hvc load
						20:	no load
							reserved
						2130	
						31:	Auto Heat
						32:	Auto Cool
							reserved
						3325	
						255:	N/A
8	4	DB2.7DB2.4		VPS		Enum:	
			position			0:	Auto
						1:	Horizontal
						2:	Pos2
						3:	Pos3
						4:	Pos4
						5:	Vertical
						6:	Swing
						710:	Reserved
						11:	Vertical swing
						12:	Horizontal swing
						13:	Horizontal and vertical swing
						14:	Stop swing
						15:	N/A
12	4	DB2.3DB2.0	Fan Speed	FANSP	fan speed value goes from 1 to 14. 1	Enum:	
					is the lowest fan speed allowed by the AC and from there it increments with	0:	Auto
					the value of this variable. Typically AC		Up to 14 fan
					units have up to 5-6 speeds. Any speed higher than the maximum the	114:	speeds being 1 the
					AC allows would set it to the higher	15:	lowest N/A
					speed. 0 is auto and 15 is N/A	13.	14/ 🔼
16	8	DB1.7DB1.0	variable	CVAR	Control variable; value 255 = auto	0100	, 255 0100 %
24	4	DB0.7DB0.4					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:	Tanah in Lalas
							Teach-in telegram Data telegram
29	2	DB0.2DB0.1	Room	RO	The interfaces can automatically	Enum:	Data telegram
			occupancy		control the behaviour of the AC without integration in automation		Occupied
					systems when linked to presence/movement sensors.		StandBy (waiting to perform action)
						2:	Unoccupied (action performed)
						3:	Off (no occupancy
							and no action)

(*)	1	1	DB0.0	On/Off	O/I	On/Off	Enum	:
							1:	off (the unit is not running)

DIREC			ı	ı					
Offset			Data	ShortCut		Valid R	ange	Scale	Unit
0	8	DB3.7DB3.0	Mode	MD	The modes are the same as in KNX and LON allowing a more transparent	Enum:			
					integration with this protocols and it has plenty of free positions for future	0:	Auto		
					expansion	1:	Heat		
						2:		ng Warm	iup
						3:	Cool		
		,				4:		Purge	
						5:	Preco	ol ———	
						6:	Off		
						7:	Test		
						8:		gency He	at
						9:	Fan o		
				· ·		10:	Free o	001	
						11:	Ice		
						12:	Max h		
						13:	heat/	cool	
						14:	(dry)	midificati	on
						15:	Calibr		ol.
						17:		gency co	OI .
						18:	steam	1	
						19:	max o		
						20:	no loa		
						20.	reserv		
						2130: 31:	Auto		
						32:	Auto		
							reserv		
						33254 255:			
8	4	DB2.7DB2.4	Vane	VPS		Enum:	.,		
			position				Auto		
						1: I	Horizon	tal	

						2:	Pos2		
						3:	Pos3		
						4:	Pos4		
						5:	Vertica	ı	
						6:	Swing		
	`	(2)				710:	Reserv	ed	
						11:	Vertica	l swing	
						12:	Horizo	ntal swing	9
						13:		ntal and I swing	
						14:	Stop s	wing	
						15:	N/A		
12	4	DB2.3DB2.0	Fan Speed	FANSP	fan speed value goes from 1 to 14. 1	Enum:			
					is the lowest fan speed allowed by the AC and from there it increments	0:	Auto		
					with the value of this variable. Typically AC units have up to 5-6	114:		4 fan spe L the lowe	
					speeds. Any speed higher than the maximum the AC allows would set it to the higher speed. 0 is auto and 15 is N/A	15:			
16	8	DB1.7DB1.0	Control variable	CVAR	Control variable (linear); value 255 = auto	0100	, 255	0100	%
24	4	DB0.7DB0.4		= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:			
			_,,	_,			Teach-ir	n telegran	<u> </u>
							Data tel		
29	2	DB0.2DB0.1	Room	RO	Room occupancy	Enum:		-9111	
			occupancy				Occupie	d	
							StandBy perform	(waiting action)	to
							Unoccup perform	oied (actioned)	on
						3:	Off (no and no a	occupance action)	У
31	1	DB0.0	On/Off	O/I	On/Off	Enum:			
							off		
						1:	on		

RORG	A5	4BS Telegram
FUNC	20	HVAC Components
TYPE	11	Generic HVAC Interface – Error Control (BI-DIR)

Submitter: Intesis Software SL

Error Control: AC Error Code, Error States and Disablements. With this EEP plus the already existing EEP A5-10-03 and A5-20-10 all the information of AC indoor unit can be sent and received allowing a much easier and complete control of these units.

DIRECTION-1 = Receive mode: Commands received by the HVAC interface. DIRECTION-2 = Transmit mode: Commands sent by the HVAC interface.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	23	DB3.7DB1.1	Not Used (= 0)					
23	1	DB1.0	External disablement	EXDS	External disablement		lot disable Disabled	<u>d</u>
24	4	DB0. <mark>7</mark> .DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	1: D	each-in elegram oata elegram	
29	1	DB0.2	Disable remote controller		Disable remote controller (When in receive mode it controls if the interface overwrites the remote controller commands.)	1: D	nable Remontroller Disable Lemote ontroller	note
30	1	DB0.1	Window contact	WC	Window contact	1: V	Vindows pened Vindows losed	
31	1	DB0.0	Not Used (= 0)					

DIKECI	ION	_						
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Error Code	ERR	Error Code (DB3 HI,DB2 LO); generated by A.C.	065535	065535	N/A
16	4	DB1.7DB1.4	Reserved	RES	Reserved (0b0000)	Enum:		
						: Res	erved	
20	1	DB1.3	Other	OD	Manufacturer defined. It is just to	Enum:		
			disablement		provide an extra "disablement signal"	0: Not	disabled	
					that could be used for other devices. People would not have to change anything then as this is already an	1: Dis	abled	
					established "signal"			
21	1	DB1.2	Window	WCD	Window contact disablement	Enum:		
			contact			0: Not	disabled	
			disablement			1: Dis	abled	
22	1	DB1.1	Key card	KCD	Key carddisablement	Enum:		
			disablement			0: Not disabled		
						1: Dis	abled	
23	1	DB1.0	External	ED	External disablement	Enum:		
			disablement				disabled	
						1: Dis	abled	
24			Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
							ch-in	
							gram	
							a telegram	
29	1	DB0.2	Remote	RCD	Remote controller Disablement	Enum:		
			controller Disablement		(In transmit it sends the status of this parameter. If the manufacturer		note	
			Disablement		doesn't support this option, it will		troller bled	
					send allways 0, no matter what it		note	
					receives.)	con	troller abled	
30	1	DB0.1	Window	WC	Window contact	Enum:		
			contact				idows ined	

						1: Windows closed
31	1	DB0.0	Alarm State	AS	Alarm State	Enum: 0: Ok 1: Error

RORG	A5	4BS Telegram
FUNC	20	HVAC Components
TYPE	12	Temperature Controller Input

Submitter: Thermokon Sensortechnik GmbH

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit		
0	8	DB3.7DB3.0	Control Variable override	CV	Actual value for controller	0255	0100	%		
8	8	DB2.7DB2.0	FanStage override	FANOR	FanStage override	Enum:				
						0: Stage 0				
						1: Stage 1				
						2: Stage 2				
						3: Stage 3	3			
						31: auto				
						255: not ava	1			
16	8	DB1.7DB1.0		SPS	Actual set point could be shifted	0255	-10+10	°K		
24	1	DB0.7	Fan override	FANOR		Enum:				
						0: Automa				
						1: Overrid	e Fan DB2			
25	2	DB0.6DB0.5	Controller mode	CTM		Enum:				
				CST		0: Auto mode				
						1: Heating				
						2: Cooling				
						3: Off				
27	1	DB0.4	Controller state		ST Controller state	Enum:				
						0: Automa				
						1: Overrid variable	e control e DB3			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:				
							n telegram			
						1: Data te	legram			
29	1	DB0.2	Energy hold-off /	ERH	Energy hold-off / Dew	Enum:				
			Dew point		point	0: Normal				
						1: Energy point	hold-off/ De	ew		
30	2	DB0.1DB0.0	Room occupancy	RO	Actual room occupancy	Enum:				
			,		, , ,	0: Occupie	ed			
						1: Unoccupied				
						2: StandB				
						3: Frost				

A5-30: Digital Input

RORG	A5	4BS Telegram
FUNC	30	Digital Input

TYPE 01 Single Input Contact, Battery Monitor

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used (= 0)					
8	8	DB2.7DB2.0	Supply voltage	SVC	Supply voltage (linear)		tery LOW tery OK	
16	8	DB1.7DB1.0	Input State	IPS	Input State	Enum: 0195: Cor 196255: Cor	ntact close	
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in to the control of		
29	3	DB0.2DB0.0	Not Used $(= 0)$					

RORG	A5	4BS Telegram
FUNC	30	Digital Input
TYPE	02	Single Input Contact

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	28	DB3.7DB0.4	Not Used (=	= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-in	telegra	m
						1: Data tel	egram	
29	2	DB0.2DB0.1	Not Used (=	= 0)				
31	1	DB0.0	Input State	IPS	Input State	Enum:		
						0: Contact	closed	
						1: Contact	open	

RORG	A5	4BS Telegram			
FUNC	30	Digital Input			
TYPE	03	4 Digital Inputs, Wake and Temperature			

Submitter: Afriso / EnOcean

Description:

This is used for universal modules with 4 digital inputs and a room temperature. The wake input signal of the device is provided to show the telegram transmission trigger. The application meaning and exact data interpretation of the digital channels depends on the end application and is not defined in this profile documentation.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered Trigger event: wake event – application dependent

Teach-in method: 4BS teach-in 2

Appendix:

D1.4 – The Status of Wake signalizes the status of the WAKE PIN which has a special meaning in an ultra low application. Usually, by a status change of this input the module is triggered to perform a predefined operation.

Applications using this profile:

• water sensor conductive – Wake Status = 0 (water detected)

- pressure gauge with minimum or maximum (wake signal, configurable if min or max)
- indication and individual switching points (digital channels show different areas)

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale Unit
0	8	DB3.7DB3.0	Not Used (= 0)				
8	8	DB2.7DB2.0	Temperature	TMP	Temperature (linear)	2550	040 °C
16	3	DB1.7DB1.5	Not Used (= 0)				
19	1	DB1.4	Status of Wake	WA0	Value of wake signal	Enum:	
						0: Low	
						1: High	
20	1	DB1.3	Dig <mark>it</mark> al Input 3	DI3	Digital Input 3	Enum:	
						0: Low	
						1: High	
21	1	DB1.2	Digital Input 2	DI2	Digital Input 2	Enum:	
						0: Low	
						1: High	
22	1	DB1.1	Digital Input 1	DI1	Digital Input 1	Enum:	
						0: Low	
						1: High	
23	1	DB1.0	Digital Input 0	DI0	Digital Input 0	Enum:	
						0: Low	
						1: High	
24	4	DB0.7DB0.4	Not Used $(= 0)$				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:	
							telegram
						1: Data tel	egram
29	3	DB0.2DB0.0	Not Used $(= 0)$				

RORG	A5	4BS Telegram					
FUNC	30	Digital Input					
TYPE 04		3 Digital Inputs, 1 Digital Input 8 Bits					

Submitter: Afriso / EnOcean

Description:

This profile is used for universal module with 1 analog input (= 8 bits resolution digital) and 3 digital inputs. The application meaning and exact data interpretation of the input channels depends on the end application and is not defined in this profile documentation.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Trigger event: values have changed Teach-in method: 4BS teach-in 2

Offset	Size	Bitrange	Data	ShortCut	Description	Valid	Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (= 0)						
16	8	DB1.7DB1.0	Digital value-input	DV0	Digital value 1 byte	025	5	0255	N/A
24	4	DB0.7DB0.4	Not Used (= 0)						
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:			
						0:	Teach-ii	n telegra	m
						1:	Data te	legram	
29	1	DB0.2	Digital Input 2	DI2	Measured digital Input 2	Enum:			
						0:	Low	_	
						1:	High		

	30	1	DB0.1	Digital Input 1	DI1	Measured digital Input 1	Enum:	
							0: Low	
							1: High	
	31	1	DB0.0	Digital Input 0	DI0	Measured digital Input 0	Enum:	
							0: Low	
L							1: High	

RORG	A5	4BS Telegram
FUNC	30	Digital Input
TYPE	05	Single Input Contact, Retransmission, Battery Monitor

Submitter: ITEC

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication interval:

- retransmission: 5 ... 255 seconds (one time configuration)

- number of retransmission times: 0 ... 127 times (one time configuration)

- heartbeat: 60 ... 65535 seconds (one time configuration) Trigger event: digital input, retransmission, heartbeat

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: 4BS teach-in 2

Security

Encryption supported: no Security level format: -

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used (= 0)					
8	8	DB2.7DB2.0	Supply voltage		Supply voltage	0255	03.3	V
16	1	DB1.7	Signal type	ST	Signal type	Enum: 0: Normal signal 1: Heart beat signal	_	
17	7	DB1.6DB1.0	Index of Signals	IOS	Ordinal count	Increment a co	unter by new	
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram 1: Data telegram		
29	3	DB0.2DB0.0	Not Used (= 0)	•	•			

A5-37: Energy Management

RORG	A5	4BS Telegram
FUNC	37	Energy Management
TYPE	01	Demand Response

Submitter: Echoflex Solutions Inc.

Purpose of EEP:

Demand Response is a developing standard to allow utility companies to send requests for reduction in power consumption during peak usage times. It is also used as a means to allow users to reduce overall power consumption

as energy prices increase. Having an EEP for this will allow ease of integration with EnOcean products to this standard. The EEP was designed with a very flexible setting for the level (0-15) as well as a default level whereby the transmitter can specify a specific level for all controllers to use (0-100% of either maximum or current power output, depending on the load type). This EEP also includes a timeout setting to indicate how long the DR event should last if the DR transmitting device does not send heartbeats or subsequent new DR levels.

Description:

This EEP is included under a new function of Energy Management. Additional types could be added in future for power, voltage, and current data. The proposed EEP type 01 only deals with demand response activation at this point. Data Byte 3 is the default DR value for devices that implement a control algorithm that uses a set-point. It will be used for any controllers not supporting the current DR Level in the message and having an adjustable set-point.

Data Byte 2 is the default DR Level for any controllers not supporting the current DR Level in the message and having an adjustable control. It can be defined as either a percentage of the maximum power or a percentage of the current power, depending on the value of bit 7 in Data Byte 2. Bits 0 through 6 contain the percentage of power (either relative or absolute) that should be used. A value of 0 corresponds to 0% and a value of 100 corresponds to 100%. Any value higher that n100 should be interpreted as 100%. For example, if the current DR level is not supported by the controller and Data Byte 2 bit 7 is 0 and Data Byte 2 bits 0 through 6 are set to 55, then the controller should try to use 55% of its maximum power usage. In the case of a lighting load with 0-10V dimming, this would correspond to 5.5V on the dimming line. In the case of a heating controller with a maximum set back of 5 degrees C, this would correspond to a set back of 2.75 degrees C (this would most likely be rounded to 3).

Data Byte 1 is the timeout for this DR event. After this command is sent the controller will stay at the DR level for Data Byte 1 multiplied by 15 minutes. Once this time has elapsed the controller will return to normal operation. If Data Byte 1 is 0 then the controller will remain in the DR event until the next DR command is received. This timeout allows DR devices to leave or turn off after setting controllers into a DR state, thus the DR transmitter is not needed to take the devices out of the DR state and the controllers will automatically recover. For example a DR transmitter that only sends messages when a DR event is active could be used with the timeout to create a successful DR system.

Data Byte 0, Bits 7 through 4 make up a nibble that will be used as the DR level. Levels 0 through 15 will be possible using these bits. Bit 4 will be the lowest bit in this nibble and bit 7 will be the highest. If any level is not supported by a controller then that controller should use the default settings sent in this message or map the level to one that it supports.

Data Byte 0 Bits 2 and 1 indicate whether the power adjustment at start and end of the DR event should be randomized or not. This feature is intended to minimize rapid changes on the power distribution equipment by delaying each controller's response. If random start or end is enabled, each controller will delay starting or ending the DR event by a random time that will vary uniformly over a specific time period (for example, 5 seconds, 60 seconds, or 15 minutes).. The maximum length of these random delays will depend on the implementation in the controller.

Data Byte 0, Bit 0 is the state for loads that are not adjustable for the default DR level. If a controller does not support the current DR level and does not have adjustable control then it should use this bit. The two states of this bit are defined as follows: 1 = maximum power usage by controller, 0 = minimum power usage by the controller. If for example lights are being controlled, then a setting of 1 will mean the lights should be ON, where as a setting of 0 will mean the lights should be OFF. For a thermostat application with non adjustable set back, a setting of 1 will mean that no set back should be applied, whereas a setting of 0 will mean that the full set back should be applied. This setting only applies to the maximum power usage of the controller, if for example the lights are currently off and the controller receives a DR event with this bit set, then the lights should not turn ON as the DR event has only set the maximum power usage for the device.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Temporary default	TMPD	New Temporary default DR set point Min Max. (linear)	0255	0255	N/A
8	1		Absolute/relative power usage	SPWRU		percentage power use. 1: Relative pow DB_2.BIT_6	wer usageDB_2.BIT_0 of the maximu wer usage. InteDB_2.BIT_0 of the current	m erpret
9	7	DB2.6DB2.0	Power Usage	PWRU	0% to 100% power usage in 1% increments; 101127 = interpreted as 100%	0100	0100	N/A

16	8	DB1.7DB1.0	Timeout Setting	TMOS	Time in 15 min. intervals; 0 = No time specified; 1255 = increasing 15 min. intervals. Max value: 3825 = 255*15	1255	153825	min
24	4	DB0.7DB0.4	DR Level	DRL	DR Level	015	015	N/A
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
					0: Teach-in tel	egram		
						1: Data telegra	am	
29	1	DB0.2	Random start	RSD		Enum:		
			delay			0: False		
						1: True		
30	1	DB0.1	Randomized end	RED		Enum:		
			delay			0: False		
						1: True		
31	1	DB0.0	Max/Min Power	MPWRU		Enum:		
			Usage for Default			0: Minimum Po	wer usage	
			DR State			1: Maximum P	ower usage	

A5-38: Central Command

RORG	A5	4BS Telegram
FUNC	38	Central Command
TYPE	08	Gateway

Communication between gateway and actuator uses byte DB $_3$ to identify Commands. Commands 0x01 to 0x7F shall be common to all types belonging to this profile. Commands 0x80 to 0xFE can be defined individually for each device type.

0x01 Switching

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Command	СОМ	Command ID	Enum: 0x01:	_	
8	16	DB2.7DB1.0	Time	TIM	Time in $1/10$ seconds. $0 = no$ time specifed	165535	0.16553.5	s
24	4	DB0.7DB0.4	Not Used (= 0	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	tele	egram ta telegram	
29	1	DB0.2	Lock/Unlock	LCK	Lock for duration time if time >0, unlimited time of no time specified. Locking may be cleared with "unlock". During lock phase no other commands will be accepted or executed	Enum: 0: Uni 1: Loc	ock k	>
30	1	DB0.1	Delay or duration	DEL	Delay or duration (if Time > 0); 0 = Duration (Execute switching command immediately and switch back after duration) 1 = Delay (Execute switching command after delay)	Enum: 0: Du 1: Del	ration lay	

31	1	DB0.0	Switching	SW	Switching Command ON/OFF	Enum:
			Command			0: Off
						1: On

0x02 Dimming

REMARK:

Ramp time is the time needed to transition from minimum to maximum dimming levels.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Command	СОМ	Command ID	Enum: 0x02:	_	
8	8	DB2.7DB2.0	Dimming value	EDIM	Dimming value (absolute [0255] or relative [0100])	0255	0100	%
16	8	DB1.7DB1.0	Ramping time	RMP	Ramping time in seconds, $0 = no$ ramping, $1 255 = seconds to 100\%$	0255	0255	S
24	4	DB0.7DB0.4	Not Used $(= 0)$			_		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Te te 1: De	each-in legram ata legram	
29	1	DB0.2	Dimming	EDIM R	Dimming Range	Enum:		
			Range			1: Re	osolute alue elative alue	
30	1	DB0.1	Store final	STR	Store final value	Enum:		
			value			0: N		
						1: Ye	es	
31	1	DB0.0	Switching	SW	Switching Command ON/OFF	Enum:		
			Command			0: 0	ff	
						1: 0	n n	

0x03 Setpoint shift

Submitter: Thermokon Sensortechnik GmbH

Used for changing set point, for example summer / winter compensation

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Command	СОМ	Command ID	Enum: 0x03:		
8	8	DB2.7DB2.0	Not Used ((= 0)				
16	8	DB1.7DB1.0	Setpoint	SP	Setpoint shift	0255	-12.712.8	K
24	4	DB0.7DB0.4	Not Used ((= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-in telegram		
						1: Data t	elegram	
29	3	DB0.2DB0.0	Not Used ((= 0)				

0x04 Basic Setpoint

Submitter: Thermokon Sensortechnik GmbH

Send a new basic set point via DDC to an actuator

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Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Command	СОМ	Command ID	Enum:		
						0x04:		
8	8	DB2.7DB2.0	Not Used (= 0)				
16	8	DB1.7DB1.0	Basic Setpoint	BSP	Basic Setpoint	0255	0+51.2	°C
24	4	DB0.7DB0.4	Not Used (= 0)	_			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegrar	n
						1: Data to	elegram	
29	3	DB0.2DB0.0	Not Used (= 0)				

0x05 Control variable

Submitter: Thermokon Sensortechnik GmbH

Set occupancy, energy holdoff and control directly actuator

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Command	СОМ	Command ID	Enum: 0x05:		
8	8	DB2.7DB2.0	Not Used (= 0)					
16	8		Control variable override	cvov	Control variable override	0255	0100	%
24	1	DB0.7	Not Used (= 0)					
25	2	DB0.6DB0.5	Controller mode	СМ	Controller Mode	Enum: 0: Automatic selection 1: Heating 2: Cooling 3: Off	c mode	
27	1	DB0.4	Controller state	CS	Controller state	Enum: 0: Automation 1: Override	<u> </u>	
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in t 1: Data teles		_
29	1	DB0.2	Energy hold off	ENHO	Energy Hold Off	Enum: 0: Normal 1: Energy hopoint	oldoff/ Dew	ı
30	2	DB0.1DB0.0	Room occupancy	RMOCC	Room occupancy	Enum: 0: Occupied 1: Unoccupie 2: Standby	ed ed	

0x06 Fan stage

Submitter: Thermokon Sensortechnik GmbH

Set directly fan stage

O	ffset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0		8	DB3.7DB3.0	Command	СОМ	Command ID	Enum:		
							0x06:		
8		8	DB2.7DB2.0	Not Used (= 0)					

16	8	DB1.7DB1.0	FanStage override	FO	FanStage override	Enum:
						0: Stage 0
						1: Stage 1
						2: Stage 2
						3: Stage 3
						255: Auto
24	4	DB0.7DB0.4	Not Used (= 0)			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:
						0: Teach-in telegram
	\					1: Data telegram
29	3	DB0.2DB0.0	Not Used (= 0)	•		

0x07 Blind Central Command

Submitter: PEHA / infratec

With this central command all blinds, awnings and shutters can be manipulated.

Remarks for data table:

REMARK 1:

The angle is usually available in blinds and awning modules.

Normally, in shutter modules the angle value is ignored.

The angle value can be set from -180° (e.g. maximum slat angle at the fully SHUT position) to 180° (e.g. maximum slat angle at the fully OPEN position).

The byte is set with following rule:

Bit7: Sign of the slat angle (0 = positive value, 1 = negative value)

Bit6..0: Slat angle value in 2° steps (e.g. $50 = 100^{\circ}$)

REMARK 2:

If this function (Blind drives to position with angle value) is not supported or not configured, use following rule:

- Position is 0 to 49% -> The blind opens
- Position is 50 to 100% -> The blind closes.

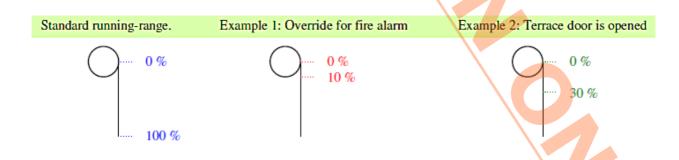
REMARK 3:

Conventional blinds and shutters can be configured with these 3 parameters to calculate the sufficiently accurate position and angle of the blind.

REMARK 4:

With this command you can adjust the minimal and maximal position of the blinds. So it's possible to override the running-range of blinds via a central control unit. Local operations are restricted and increase safety (e.g. to open blinds in case of wind or fire).

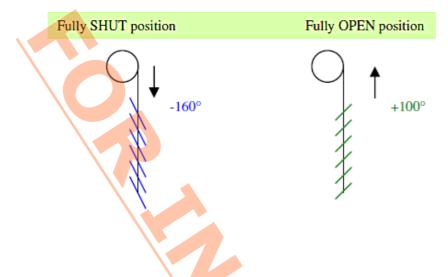
Condition: The Minimal value must be smaller or equal the maximal value.



Example to lock the local functionality: Drive the shutters to a define position and set the minimal and maximal values to this position.

REMARK 5:

These to angle values describe the maximum slat angle at the fully SHUT position and the maximal slat angle at the fully OPEN position. With the time parameter, e.g.:



REMARK 6: Set the position logic for the blind control and visualization.



Note: If the mode is changed, the minimum and maximal values (function 9) are converted as well!

REMARK 7:

For important central commands, it's not necessary to send directly the statefeedback, e.g. when many modules are activated simultaneously.

Note: Special functionality is in function "Status request (0)", the status is always sent.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Command	СОМ	Command ID	Enum: 0x07: Shutters / Blinds		
8	8	DB2.7DB2.0	Parameter 1		Function defined parameter value	Enum: Func. 00: not use Func. 01: not use Func. 02: not use Func. 03: not use Func. 04: 0% 10 e.g.: 0% = Blind fu Blind fully closed Func. 05: 0 255 Func. 06: 0 255 Func. 07: Runtime blind 0 255 seconds	ed ed 00% ally open / 100 seconds seconds	

8	DB1.7DB1.0		P2 FUNC	Function defined parameter value	
					1: Blind stops 2: Blind opens
					2: Blind opens
					3: Blind opens
		· discion			0: Do nothing, status request 1: Blind stops

							Blind drives to position with angle value (see remark 2) Blind opens for time (position value) and angle (angle value) Blind closes for time (position value) and angle (angle value) Set Runtime parameters (see remark 3) Set angle configuration (see remark 3) Set Min, Max values (see remark 4) Set slat angle for SHUT and OPEN position (see remark 5) Set position logic (see remark 6)
							cot position (occ ramant o)
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum	:
						0:	Teach-in telegram
				- 4		1:	Data telegram
29	1	DB0.2	Send status	SSF	see remark 7	Enum	
			flag			0:	Send new status of device
						1:	Send no status (e.g. Global central commands)
30	1	DB0.1	Pos. and	PAF		Enum	:
			Angle flag			0:	No Angle and position value available
						1:	Angle and position value available
31	1	DB0.0	Service	SMF		Enum	:
	M	Mode Flag			0:	Normal operation	
						1:	Service mode: The module disables all senders, except this sender, which has set the service mode. (For example for maintenance)

RORG	A5	4BS Telegram		
FUNC	38	Central Command		
TYPE	09	Extended Lighting-Control		

Submitter: PEHA / infratec

With this central command all lighting actors can be manipulated.

Remarks for data table:

REMARK 1:

Set the RGB level for corresponding lighting-control. Devices without this feature ignore this command.

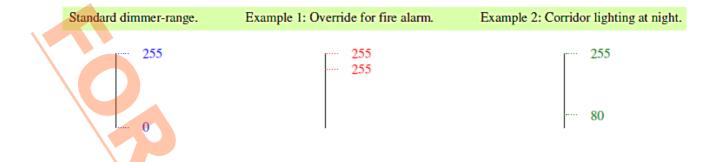
REMARK 2:

Up to 16 different scenes can be selected and configured.

REMARK 3:

Change the minimal and maximal dimmer-value. Example:





General for switchers:

The values 0 .. 127 are defined to "Off".

The values 128.. 255 are defined to "On".

REMARK 4

Example: If the lamp was replaced, the operating hours are reset to 0.

REMARK 5:

This function blocks all other commands from the other taught-in transmitters. The transmitter, which has called this function, must delete the blocking state, before the other transmitters can use the device again.

REMARK 6:

For important central commands, it's not necessary to send directly the statefeedback, e.g. when many modules are activated simultaneously.

Note: Special functionality is in function "Status request (0)", the status is always sent.

REMARK 7:

Ramp time is the time needed to transition from minimum to maximum dimming levels.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit		
0	8	DB3.7DB3.0	Parameter	P1	Function defined	Enum:				
			1		parameter value	Func. 00: not used				
						Func. 01: not use	ed			
						Func. 02: not use	ed			
						Func. 03: not use	ed			
						Func. 04: not use	ed			
						Func. 05: not use	ed			
						Func. 06: Dimm-Va	lue (0 255)		
						Func. 07: R - Red (0 255)			
						Func. 08: not use	ed			
						Func. 09: Dimm-Va	lue (0 255)		
						Func. 10: Lamp ope 158)	erating hours	(MSB		
						Func. 11: not use	ed			
						Func. 12: Energy m 158)	netering value	(MSB		
8	8	DB2.7DB2.0	Parameter	P2		Enum:				
			2		parameter value	Func. 00: not use	ed			
						Func. 01: not use	ed	1		
						Func. 02: not use	ed			
						Func. 03: Ramping	time (MSB 15	58)		

							(65525 a)
							(65535 s)
							Func. 04: Ramping time (MSB 158) (65535 s)
							Func. 05: not used
							Func. 06: Ramping time (MSB 158) (65535 s)
	/						Func. 07: G - Green (0 255)
							Func. 08: not used
							Func. 09: Dimm-Value (0 255)
							Func. 10: Lamp operating hours (70 LSB)
							Func. 11: not used
		·					Func. 12: Energy metering value (70 LSB)
16	8	DB1.7DB1.0	Parameter 3	P3	Function defined parameter value	Enum:	Func. 00: not used
							Func. 01: not used Func. 02: not used
							Func. 03: Ramping time (70 LSB) (65535 s)
							Func. 04: Ramping time (70 LSB) (65535 s)
							Func. 05: not used
							Func. 06: Ramping time (70 LSB) (65535 s)
							Func. 07: B - Blue(0 255)
							Func. 08:
						1	Bit7: 0 = Drive to scene-value Bit7: 1 = Stores actual value in the
							scene Bit30: Scene number 0 15
							Func. 09: not used
							Func. 10: not used
							Func. 11: Blocks the local operations
							Enum: 0 = Unlock local operations
							1 = Locking switch on commands 2 = Locking switch off commands
							3 = Locking local operations
							Func. 12: Unit of energy metering value Enum:
							0 = mW 1 = W
							2 = kW 3 = MW
							4 = Wh 5 = kWh
							6 = MWh
							7 = GWh 8 = mA
							9 = 1/10 A 10 = mV
						L	

							11 = 1/10 V
							11 = 1/10 V 12 15 Not used
24	4	DB0.7DB0.4	Function	FUNC		Enum:	
24		DB0.7DB0.4	Tanction	10146		0:	Do nothing, status request
						1:	Switched off
	1					2:	Switched on (Memory value)
						3:	Dimming up with ramping time
						4:	Dimming down with ramping time
						5:	Dimming stops
						6:	Set dimmer-value and ramping time
						7:	Set RGB values (see remark 1)
						8:	Scene function (see remark 2)
						9:	Set minimal and maximal dimmer-value (see remark 3)
						10:	Set the operating hours of the lamp (see remark 4)
						11:	Locking local operations (see remark 5)
						12:	Set a new value for the energy metering (overwrite the actual value with the selected unit)
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:	·
						0:	Teach-in telegram
						1:	Data telegram
29	1	DB0.2	Send status	SSF	see remark 6	Enum:	
			flag			0:	Send new status of device
						1:	Send no status (e.g. Global central commands)
30	1	DB0.1	Store final value	SFV		Enum:	
			value			0:	No
31	1	DB0.0	Service	SMF		1: Enum:	Yes
31	1	250.0	Mode Flag	J.11		0:	Normal operation
						1:	Service mode: The module disables all senders, except this sender, which has set the service mode. (For example for maintenance)
							maintenance)

A5-3F: Universal

RORG	A5	4BS Telegram		
FUNC	3F	Universal		
TYPE	00	Radio Link Test (BI-DIR)		

Submitter: PROBARE

Units supporting the EEP Radio Link Test shall offer a functionality that allows for radio link testing between them (Position A to Position B, point-to-point only). Testing shall be possible without the need for prior teach-in and as an option it shall cover two way communications.

Further, testing shall be backward compatible to existing EnOcean installations that support at least 1BS

(RORG=0xD5) and 4BS (RORG=0xA5) EnOcean messages.

The main area of RLT application are in-field testing of radio links between portable test equipment placed at different locations as well as between portable test equipment and fixed installation, e.g. an EnOcean Gateway.

Functional description of RLT:

When two units perform radio link testing one unit needs to act in a mode called RLT Master and the other unit needs to act in a mode called RLT Slave. On a RLT enabled unit one or both modes may be supported. The mode(s) supported shall require explicitly activation at run time.

After activation a RLT Master listens for RLT_Query messages. On reception of at least one RLT_Query message a RLT Master responds with an RLT_Response message. Following that it starts transmission of RLT_MasterTest messages within a maximum time frame of 250ms and awaits the response from the RLT Slave for each RLT_MasterTest message sent. A radio link test communication consists of a minimum of 16 and a maximum of 256 RLT_MasterTest messages. Timing distance between individual RLT_MasterTest messages shall not exceed 250ms. When the radio link test communication is completed the RLT Master gets deactivated automatically.

After activation a RLT Slave periodically transmits RLT_Query messages (1 message / 2s). It stops transmission of RLT_Query messages as soon as it has received at least one RLT_Response message. It then waits for RLT_MasterTest messages from the same EnOcean ID and replies to them within a maximum delay of 100ms thru RLT_SlaveTest messages. If it does not receive RLT_MasterTest messages from the same EnOcean ID for a time period of 5s, the RLT Slave restarts periodic transmission of RLT_Query messages. The RLT Slave requires explicit deactivation.

RLT_Query Message

This Message is a "4BS Teach-In Query" message with FUNC, Type and Manufacturer ID set properly. For details please refer to the description of the 4BS teach-in process.

RLT_Response Message

This Message is a "4BS Teach-In Response" message with FUNC, Type and Manufacturer ID set properly. For details please refer to the description of the 4BS teach-in process. As a RLT Master does accept teach-in of a RLT Slave only for the time period required by a single RLT communication it shall indicate the EEP to be supported but the EnOcean ID of the RLT Slave not to be stored permanently.

RLT_MasterTest_4BS

This is the 4BS message sent by the RLT Master during a radio link test communication

DIRECTION-1

DIKECI	TOIN	<u> </u>				
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range Scale Unit
0	28	DB3.7DB0.4	Not Used (=	0)		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram 1: Data telegram
29	2	DB0.2DB0.1	MSG_ID	MSGID	Message ID	Enum: 2:
31	1	DB0.0	MSG-Source	MSGS	Message Source	Enum: 0: RLT-Master

RLT_SlaveTest_4BS

This is the 4BS message sent by the RLT Slave in reply to an RLT_MasterTest_4BS message. DIRECTION- 2

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale Unit
0	2	DB3.7DB3.6	Sub-Telegram Counter	STCNT	related to RLT_MasterTest_4BS message received Repeater level 2	1: 1 s tele 2: 2 s	egram

						2. > 2	
						3: ≥ 3 sub telegram	
2	C	DD2 F DD2 0	DCCI I avval in Alban	DCI V	undertail to DIT MantauTant ADC	Ť	
2	6	0.5.303.0	RSSI Level in dBm	KSLV	related to RLT_MasterTest_4BS message received Repeater level 1	Enum:	
					linessage received Repeater level 1	not	
						0x00: supported	
						≥-31	dD.ss
						0x01:	dBm
						-32 0x02:	dPm
						±-93	dBm
						≤-93 0x3F:	dBm
0	0	DD2 7 DD2 0	Cula Tala susua	DCI V	Deleted to DIT MeeterTeet 4DC		ubili
8	8	DB2.7DB2.0	Counter/RSSI	RSLV	Related to RLT_MasterTest_4BS message received Repeater level 1	Enum:	_
			Level in dBm		(for details see DB3)	: See prev	
16	8	DB1.7DB1.0		RSLV	Related to RLT_MasterTest_4BS	Enum:	
10	0	001.7001.0	Counter/RSSI	KJLV	message received direct link	-	_
			Level in dBm		message received an eet mix	: See prev	
24	4	DB0.7DB0.4	RSSI Level in dBm	RSLV	Non-EnOcean signal detection since	Fnum:	
_		2311112231	5		last RLT_MasterTest message RSSI	not	
					Level with 6dB quantization steps	0x00: supported	
						≥ -31	
						0x01:	dBm
						-3237	
						0x02:	dBm
						-3843	
						0x03:	dBm
						-4449	
						0x04:	dBm
						-5055	
						0x05:	dBm
						-5661	
						0x06:	dBm
						-6267	dD
				\		0x07:	dBm
						-6873 0x08:	dPm
						-7479	dBm
						-/4/9 0x09:	dBm
						-8085	ubili
						0x0A:	dBm
						≤ -92	
						0x0B:	dBm
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:	
				5		0: Teach-in	
						telegram	
						1: Data telegr	am
						1. Data telegi	J.11
29	2	DB0.2DB0.1	MSG ID	MSGID		Enum:	
		2301211122011		. 10010		2:	
31	1	DBO O	MSG-Source	MSGS			
31	1	DB0.0	M3G-30urce	כטכויו		Enum:	_
						1: RLT-Slave	

RLT_MasterTest_1BS

This is the 1BS message sent by the RLT Master during a radio link test communication.

REMARK: The column 'Bitrange' is automatically generated from the telegram type and the offset. The column Bitrange shows currently DB_3 instead of DB_0. This isn't a bug in the XML, only a weakness of the formatting. AT THIS POINT, DB_0 WOULD BE CORRECT.

DIRECTION- 1

Offset Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
-------------	----------	------	----------	-------------	----------------	-------	------

0	4		RLT MSG-Counter MSB	MC-MSB	Round-trip, covering all RLT_x_1BS messages 4 bit MSB	Enum: :
4	1	DB3.3	LRN Bit	LRNB LRN Bit		Enum: 0: Teach-in telegram 1: Data telegram
5	2		RLT MSG-Counter LSB	MC-LSB	Round-trip, covering all RLT_x_1BS messages 2 bit LSB	Enum: :
7	1	DB3.0	MSG-Source	MSGS	Message Source	Enum: 0: RLT Master

RLT_SlaveTest_1BS

This is the 1BS message sent by the RLT Slave in reply to an RLT_MasterTest_1BS message.

REMARK: The column 'Bitrange' is automatically generated from the telegram type and the offset. The column Bitrange shows currently DB_3 instead of DB_0. This isn't a bug in the XML, only a weakness of the formatting. AT THIS POINT, DB_0 WOULD BE CORRECT.

DIRECTION-2

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Jnit
0	4		RLT MSG-Counter MSB		Round-trip, covering all RLT_x_1BS messages 4 bit MSB	Enum: :		
4	1	DB3.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach telego 1: Data telego	ram	
5	2		RLT MSG-Counter LSB	· · · · · · · · · · · · · · · · · · ·	Round-trip, covering all RLT_x_1BS messages 2 bit LSB	Enum: :		
7	1	DB3.0	MSG-Source	MSGS	Message Source	Enum: 1: RLT-S	Slave	-

RORG	A5	4BS Telegram
FUNC	3F	Universal
TYPE	7F	Universal

Submitter: EnOcean GmbH

Description

This profile was intended for manufacturer specific applications. Every manufacturer may independently define the types within this profile.

This profile was replaced by the use of MSC-Telegrams with the advantage of more payloads and the manufacturer Id as identification. For future applications only use MSC-Telegrams.

This description is only necessary for legacy reasons.

Data exchange

Direction: unidirectional / bidirectional Addressing: unicast (ADT) / broadcast

Communication trigger: event- & time-triggered Communication interval: application specific

Trigger event: application specific

Tx delay: not specified Rx timeout: not specified

Teach-in

Teach-in method: 4BS teach-in

Security

Encryption supported: no Security level format: -

Off	set	Size	Bitrange		Data	ShortCut	Description	Valid	Range	Scale	Unit
0		28	DB3.7	DB0.4	undefined	undef	undefined				
28		1	DB0.3		LRN Bit	LRNB	LRN Bit	Enum:			
								0: Teach-in telegram		m	
								1:	Data tele	egram	
29		3	DB0.2	DB0.0	undefined	undef	undefined				

D2: VLD Telegram

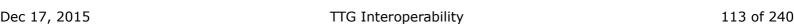
D2-00: Room Control Panel (RCP)

The Communication is based on the Smart Ack concept. Some basics related hereto are included in this document for convenience but for details please consult the Smart Ack specification.

A Room Control Panel (RCP) compliant to this EEP offers the following features:

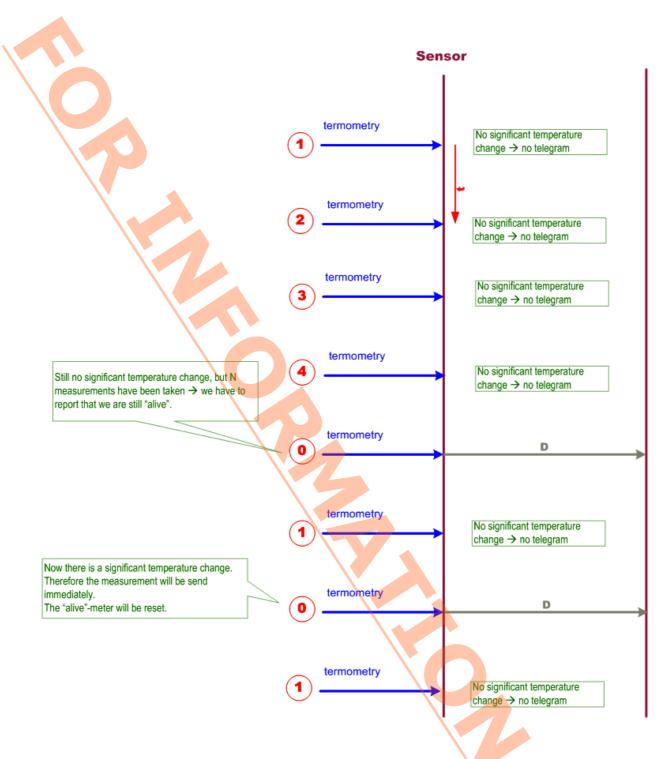
- Multi symbol, multi segment LC display (or equivalent)
- 1 temperature measurement channel, remote configurable
- 1 temperature set point control (e.g. key pad based)
- 1 fan speed control (e.g. key pad based)
- 1 presence control (e.g. key pad based)

Repeater operation shall work in compliance with the Smart Ack specification.



EEP 2.6.4 Specification © EnOcean Alliance

Use Case: Temperature Measurement

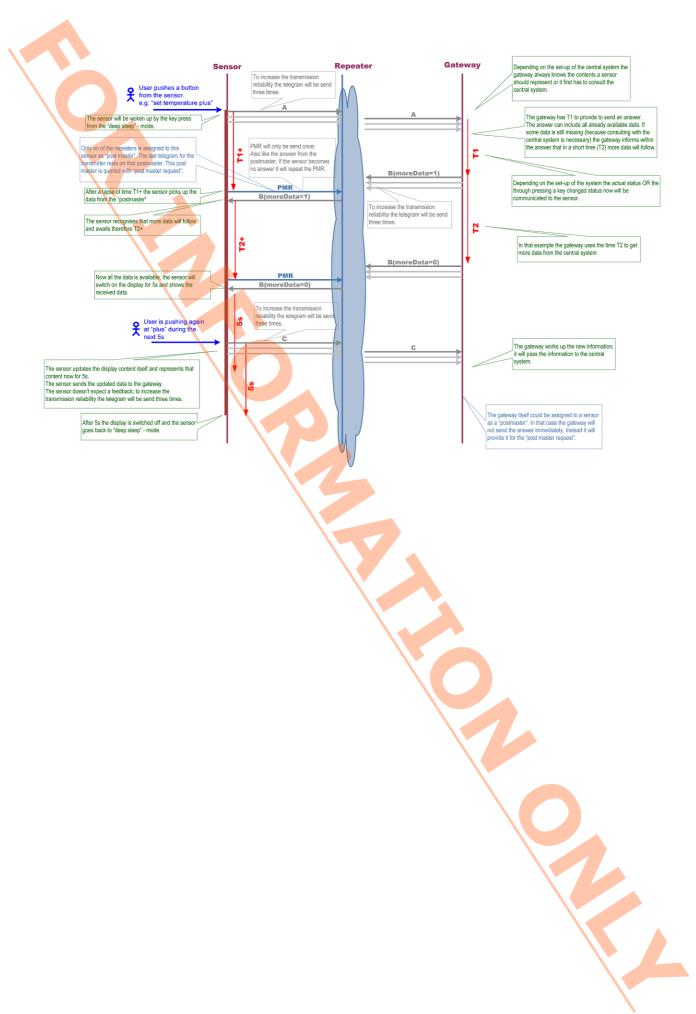


REMARK:

Temperature measurement may be configured by the Gateway, see chapter "Message Type E - RCP Configuration".

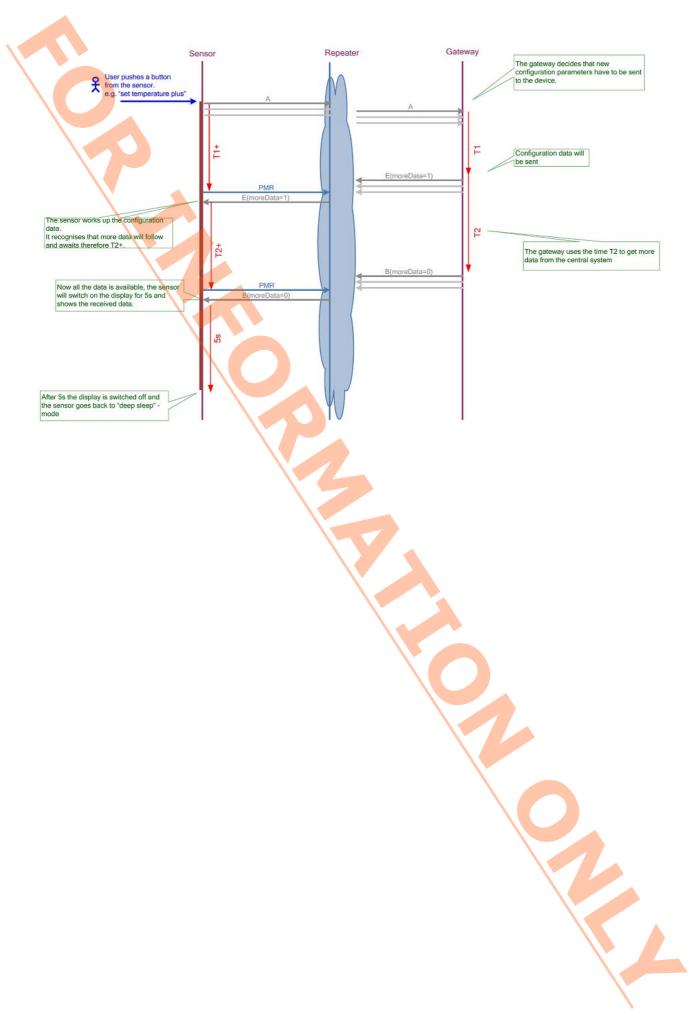
EEP 2.6.4 Specification © EnOcean Alliance

Use Case: User Interaction



EEP 2.6.4 Specification © EnOcean Alliance

Use Case: User Interaction including transfer of configuration data



RORG	D2	VLD Telegram
FUNC	00	Room Control Panel (RCP)
TYPE	01	RCP with Temperature Measurement and Display (BI-DIR)

Submitter: Fr. Sauter AG

Note: EEP Release 2.1, 2.5, and 2.6 reflected a wrong byte-order for all messages of this EEP!

Example Message Type A:

Instead of $DB_1 = 0x01 DB_0 = 0x81$ (which is correct for KP=1 and CV=1)

by mistake $DB_1 = 0x81 DB_0 = 0x11$ (which is wrong) was printed.

We apologize for the mistake.

Message type A / ID 01 (First User Action on RCP)

Direction: Sensor -> Gateway

Transaction Response: Message Type B or Type E

Chaining: No

Timing: T1+ = 170ms

Message A / ID 01

Original Identifier: Data[0] Data[1]

DB_1.BΠ_7 ← 0
Bit Offset: 0 → 15

DB_1

DB_1

DB_0

DB_0

DB_1

DB_0

DB_1

DB_0

DB_1

DB_0

DB_1

DB_1

DB_1

DB_0

DB_1

DB_1

DB_0

DB_1

DB_1

DB_1

DB_1

DB_0

DB_1

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	5	Not Used (=	= 0)				
5	3	MsgId		Message Id; 0x01	Enum: 1: Message Id		
8	1	ConfigValid	CV		Configuration data not valid 0x00: message of type E) Configuration data valid 0x01:	(e.g. never receiv	ved
9	2	Not Used (=	= 0)				
11	_	User Action	KP		Enum: 0x00: not used 0x01: Presence 0x02: Temperature Set Poir 0x03: not used 0x04: not used 0x05: Temperature Set Poir 0x06: Fan 0x070x1F: Not Used		

Message Type B / ID 02 (Display Content)

Direction: Gateway -> Sensor Reply to Message Type A

Response: None

Chaining: Up to 2 messages per chain

Timing: T2+ = 300ms

Data[4]		
DB_0		
4 3 2 1 0		
35 36 37 38 39		
. 8 Se Sd Sc Sb Sa		

IMPORTANT NOTE:

The symbols Sa, Sb, Sc, Sd, Se are optional. One or more of those symbols are available on the display only if the manufacturer of a RCP implements them in a specific design. Thus, they are NOT mandatory for a RCP in order to comply with this EEP.

Offset	Size	Data	ShortCut	Description	Valid	Range	Scale	Unit
0	1	Fan manual	M	·	Enum:			
					0: Auto			
					1: Fan ma	anual		
1	3	Fan	F		Enum:			
					0x00:	Do not display		
					0x01:	Speed Level 0	_	
					0x02:	Speed Level 1	_	
					0x03:	Speed Level 2	_	
					0x04:	Speed Level 3	_	
					0x050x07	': not used		
4	1	MoreData	MD		Enum:			
					0x00: no mo	ore data		
					0x01: more	data will follow	after T2+	
5	3	MsgId	MI	Message Id; 0x02	Enum:			
					2: Messag	ge Id		
8	3	Presence	PR		Enum:			
					0x00:	Do not display		
					0x01:	Present		
					0x02:	Not present		
					0x03:	Night time red	uction	
					0x040x07			
11	5	Figure A Type	TA		Enum:			
					0x00:	Do not display		
					0x01:	Room Temperat	ure	°C
					0x02:	Room Temperat		٥F
					0x03:	Nominal Tempe	rature	°C
					0x04:	Nominal Tempe	rature	٥F
					0x05:	Delta Temperat	ure Set Point	°C
					0x06:	Delta Temperat	ure Set Point	°F
					0x07:	Delta Temperat	ure Set	
						Point(graphic)		
					0x08:	Time 00:00 to 3		
					0x09:	Time 00:00 to		
					0x0A:	Time 00:00 to		
					0x0B:	Date 01.01 to 3		
					0x0C:	Date 01.01 to 1		
					0x0D:	Illumination (lir		lx
					0x0E:	Percentage 0 to		%
					0x0F:	Parts per Million		ppm
					0x10:	Relative Humid	ity 0 to 100	% rH
						not used		111
					0x110x1F:	not useu		
16	16	Figure A Value	ZA	Format according to	Enum:			
		J		TA:		7: 0 4000	0.01°	
				Byte-Order: Little-		A: Time 0000 :		
				Endian!	-	C: Date 0101 3		
					UNODITIONOC	J. Dutte OTOT III		

32	3	Not Used (= 0)			0x0D: 0 99 0x0E0x10: 0 10 0x0F: 0 99	0000	0.01% ppm
35		User Notification	Se	optional	Enum: 0x0: Off 0x1: On		
36	1	Window	Sd	optional	Enum: 0x0: Closed 0x1: Opened		
37	1	Dew-Point	Sc	optional	Enum: 0x0: Warning 0x1: No warning		
38	1	Cooling	Sb	optional	Enum: 0x0: Off 0x1: On		
39	1	Heating	Sa	optional	Enum: 0x0: Off 0x1: On		

Message Type C / ID 03 (Repeated User Action on RCP)

Direction: Sensor -> Gateway

Fire and Forget Response: None Chaining: No

Timing: may only be sent within 5s from latest receipt of a Message Type B

Offset	Size	Data	ShortCut	Description	Valid Rang	e Scale Unit
0	1	Not Used (= 0)				
1	3	Fan	F		Enum:	
					0x00:	no change
					0x01:	Speed Level 0
					0x02:	Speed Level 1
					0x03:	Speed Level 2
					0x04:	Speed Level 3
					0x05:	Speed Level Auto
					0x060x07	': not used
4	1	Not Used (= 0)				
5	3	MsgId	MI	Message Id; 0x03	Enum:	
					3: Messag	je Id
8	3	Presence	PR		Enum:	
					0x00:	no change
					0x01:	Present
					0x02:	Not present
					0x03:	Night time reduction
					0x040x07	': not used

11	5	Set Point A Type	TA		Enum: 0x00: r	o change	
	1				0x010x04:	ot used	
						emperature Set Point °1	:
					0x060x1F: r	ot used	
16	16	Set Point A Value	ZA	Format according to TA: 0x05 [0.01°]	-1270+1270	-12.70+12.70	0
				Byte-Order: Little-Endian!			

Message Type D / ID 04 (Measurement Result)

Direction: Sensor -> Gateway

Fire and Forget Response: None Chaining: No Timing: None

Message D / ID 04

Original Identifier:				Dat	a[0]]		1				at	a[1]						Dat	a[2]		
				DB	_2			/			DB_1									DB	_0			
DB_3.BIT_7 ← 0			5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset: 0 🔿 23	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23
							MI		7				VA			0		T.	A		11	3	/Α.	8

Offset	Size	Data	ShortCut	Description	Valid Range	Scale Unit
0	5	Not Used (= 0)				
5	3	MsgId	MI	Message Id;0x04	Enum: 4: Message Id	
8	8	Channel A Value	VA (LSB)	Format according to TA: LSB (Bit 7 0)	04000	040.00
16	4	Channel A Type	TA		0x010x0E: not use	ature [°C] d ement result not valid
20	4	Channel A Value	, ,	See: VA (LSB) MSB (Bit 11 8)		

Message Type E / ID 05 (Sensor Configuration)

Direction: Gateway -> Sensor Reply to Message Type A

Response: None

Chaining: Up to 2 messages per chain

Timing: T2+ = 300ms



Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Not Used (= 0)					
4		MoreData	MD		Enum: 0x0: no more data 0x1: more data will for	ollow after T2+	
5	3	MsgId	MI	Message Id; 0x05	Enum: 5: Message Id		
8	1	Not Used (= 0)					
9		Set Point Range Limit		Limit of Set Point Range, absolute value: REMARK: Set Point Range shall be symmetrical to 0°	Enum: 0x00: Set Poin 0,1° 1 0x010x7F: [0,1°]		.12.7°
16	1	Not Used (= 0)					
17	7	Set PointSteps		Number of Set Point Steps: REMARK: Specifies the number of equidistant steps between 0 and Set Point Range Limit	Enum: 0x00: Set Poin 0x010x7F: 1 127	t disabled	27
24		Temperature Measurement Timing	TT (LSB)	Time between two subsequent Temperature measurements LSB (Bit 3 0)	Enum: 0x00: Temperat measurer disabled 10 600 0x010x3C:	ment s [10s]	600 s
28	4	Not Used (= 0)					
32	3	Presence	PR	Number of Presence Levels available to user	Enum: 0x0: Presence c 0x10x7: 1 7	lisabled	-
35	3	Fan	F	Number of Fan Speed Levels available to user:	Enum: 0x0: Fan Speed 0x10x7: 1 7	disabled 17	_
38		Temperature Measurement Timing	TT (MSB)	Time between two subsequent Temperature measurements MSB (Bit 5 4)			
40		Significant Temperature Difference	ST	Difference between two subsequent temperature measurements to trigger a Message Type D [0.2°]	0x00xF	0.03.0	0
44	1	Not Used (= 0)					
45		Keep Alive Timing	KA	Number of measurements (without trigger of a message Type D) between two subsequent "Keep Alive messages":	OXO: ITALISTINISSIO	nt result with rature nt asurements	1070

D2-01: Electronic switches and dimmers with Energy Measurement and Local Control

This EEP family shall be used for bidirectional actuators that control electric loads, e.g. for lightning purposes. Switching and dimming is controlled and high-resolution energy measurement is supported. Local Control, either thru a user interface or thru other measures shall be supported on the actuator. This may include other EnOcean enabled devices taught-in to a device belonging to the EEP family, e.g. a simple rocker switch or more sophisticated devices like occupancy sensors with timing control. The proposed EEP family serves up to 30 output channels and allows controlling them either individually or as a bulk. Extension of this EEP family is possible in different ways:

- 1. A new device with a different feature mix creates a new TYPE within this EEP family
- -> new column in following table
- 2. An additional feature is added and a new device with a new TYPE is created
- -> new column and new line in following table
- 3. Like 2, but EnOcean communication of the EEP family needs to be extended
- -> new column and new line in following table
- -> one or more additional messages need to be defined

For teach-in and teach-out UTE (Universal Uni- and Bidirectional Teach-In Procedure for EEP based Communication) shall be used.

Supported	Туре	Туре	Туре	Туре	Type	Туре	Туре	Туре											
function														0x0D					
No. of output channels	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	2	2	2
Switching	Χ	Χ		Χ	X		X	Χ	Χ		Χ	Χ	Χ	Χ	Χ	Χ	Χ	Χ	Χ
Dimming	-	-	Χ	Χ	X	X		}	-	Χ	-	-	-	-	-	-	-	-	-
Dimming configurable	-	-	-	-	Х	X		-	-	X	-	-	-	-	-	-	-	-	-
Pilot wire	-	-	-	-	-	-		7		-	-	-	Χ	-	-	-	-	-	-
Local control	Χ	Χ	Χ	Χ	Χ	Χ	-		X	Χ	Χ	Χ	Χ	Χ	Χ	Χ	Χ	Χ	Χ
Local control enable/disable	_	-	-	-	Х	Х	- \		X	-	X	Х	Х	X	X	Х	-	-	Х
External Switch / Push Button Control	-	-	-	1	-	-	1				-	-	-	-	-	Х	1	-	Х
External Switch / Push Button Type	-	-	-	1	-	-	I	_		-		-	_	-	-	X	1	-	X
Auto OFF Timer	-	-	-	-	-	-	ı	_	-			-	-	-	_	Х	-	-	Х
Delay OFF Timer	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	Х	-	-	Х
Taught-in devices enable/disable 2)	-	-	-	1	X	X	ı	-	X	X	X	X	X	X	X	X	1	-	X
User interface day/night mode	_	_	-	-	-	X	-	_	X	-	X	X	Х	X	X	X	-	-	X
Over current reporting	-	_	-	-	Х	Х	-	-	X	X	-	-	X	-		-	-	-	-
Over current configurable	-	_	-	ı	Х	Х	ı	-	X	ı	-	-	Х		-		-	-	-
Energy measurement	Х	-	Х	-	Х	Х	X	-	X	X	-	Х	Х	-	X		X	-	-
Power measurement	-	-	-	-	Х	Х	-	_	X	X	_	Х	Х	-	X	-		-	_
Measurement Roll Over 1)	Х	-	Х	-	_	-	X	_	-	_	_	Х	_	-	X	-	X	_	_
Measurement Auto Scaling 1)	-	-	-	-	Х	Х	_	-	Х	X	-	-	Х	-	-		- / /	-	-
Measurement configurable	-	-	_	=	-	Х	=	-	Х	X	-	Х	Х	-	Х	-		-	_

Measurement report on query	Х	-	X	-	X	X	X	-	X	X	-	X	X	-	X	-	X	1	-
Measurement auto reporting		-	i	ı	X	X	i	i	X	X	-	X	X	ı	Х	ı	ı	ı	-
Default state configurable	1	-	-	-	-	X	-	i	X	X	Х	X	X	X	X	X	-	-	Х
Error level reporting	-	-	-	-	-	Х	-	ı	X	X	-	-	X	ı	_	-	-	-	-
Power Failure Detection			-	-	-	-	-	ı	-	ı	Х	X	-	-	-	-	-	-	-
Power Failure Detection enable/disable		-	-	-	-	-	-	-	-	-	X	X	-	-	-	-	-	-	-

- 1) A device may either support Measurement Roll Over or Measurement Auto Scaling.
- 2) Enable / disable only effects devices that are taught-in to a device belonging to this EEP family; it does not effect communication between a device belonging to this EEP family and any other entity where this device has been taught-in by itself.

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	00	Type 0x00

Submitter: Team

CMD 0x1 - Actuator Set Output

This message is sent to an actuator. It controls switching / dimming of one or all channels of an actuator.

Command ID 01 (CMD)

				DΒ	_2	_2 DB_1											DB	_0						
DB_2.BIT_7 ← 0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset: 0 → 23	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23
,						a	4D		dim) Va	ue		1/0	cha	nne				0	υφυ	t Va	lue	96	

REMARK:

In case an Actuator Set Output message specifies a parameter that is not supported by the device being addresses, such device shall react as following:

- channel not supported by device -> ignore message
- dimming command to switching device -> no change of status
- dimming command with non supported speed -> dim with regular speed

RECOMMENDATION:

Dimmers should take things like phase shifting into account to provide dimming based on power consumption (results in brightness for lamps) rather than interpreting percentage values as phase angle only.

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Not Used (=	0)	_			
4		Command ID	_	command identifier	Enum: 0x01: ID 01		
8	3	Dim value	DV		Enum: 0x00: Switch to new ou 0x01: Dim to new output	•	mer 1

				ti-	
				0x02:	Dim to new output value – dim timer 2
				0x03:	Dim to new output value – dim timer 3
				0x04:	Stop dimming
				0x050x07	: not used
11	5	I/O channel	I/O	Enum:	
				0x000x1D:	Output channel (to load)
	1			0x1E:	All output channels supported by the device
				0x1F:	Input channel (from mains supply)
16	1	Not Used (=)	0)		
17	7	Output value	OV _	Enum:	
				0x00:	Output value 0% or OFF
				0x010x64	: Output value 1% to 100% or ON
				0x650x7E	: Not used
				0x7F:	Output value not valid / not applicable

CMD 0x2 - Actuator Set Local

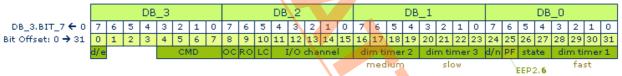
This message is sent to an actuator. It configures one or all channels of an actuator.

Response Timing: None

RECOMMENDATION:

In case the device implements an internal order for dim timers, this order should be from "dim timer 1" (fast) to "dim timer 3" (slow). The configured time shall always be interpreted for a full range (0 to 100%) dimming.

Command ID 02 (CMD)



Offset	Size	Data	ShortCut	Description		Valid Range	Scale	Unit
0	1	Taught-in devices	d/e		Enum:			
					0b0:	Disable taught-in dev EEP)	rices (with diffe	erent
					0b1:	Enable taught-in devi EEP)	ices (with diffe	rent
1	3	Not Used (= 0)						
4	4	Command ID	_	Command identifier	Enum: 0x02	2: ID 02		
8	1	Over current shut down	ОС		Enum:	Over current shut do	wn: static off	
					0b0:	Over current shut do	WIT. Static off	
					0b1:	Over current shut do restart	wn: automatic	
9		reset over current shut	RO		Enum:			
		down			0b0:	Reset over current sh	nut down: not	active
					0b1:	Reset over current sh signal	nut down: trigg	jer

10	1	Local control	LC	Enum:	
				0b0: Disable	e local control
				0b1: Enable	local control
11	5	I/O channel	I/O	Enum:	
				0x000x1D:	Output channel (to load)
				0x1E:	All output channels supported by the device
				0x1F:	Input channel (from mains supply)
16	4	Dim timer 2	DT2	Enum:	
				0x00:	Not used
				0x010x0F:	Dim timer 2 [0,5 7,5s / steps 0,5s]
20	4	Dim timer 3	DT3	Enum:	
				0×00:	Not used
				0x010x0F:	Dim timer 3 [0,5 7,5s / steps 0,5s]
24	1	User interface	d/n	Enum:	
		indication		0b0: User in	terface indication: day operation
		`		0b1: User in	terface indication: night operation
25	1	Power Failure	PF	Enum:	
				0b0: Disable	Power Failure Detection
				0b1: Enable	Power Failure Detection
26	2	Default state	DS	Enum:	
				0b00: Defau	Ilt state: 0% or OFF
				0b01: Defau	llt state: 100% or ON
				0b10: Defau	Ilt state: remember previous state
				0b11: Not u	sed
28	4	Dim timer 1	DT1	Enum:	
				0×00:	Not used
				0x010x0F:	Dim timer 1 [0,5 7,5s / steps 0,5s]

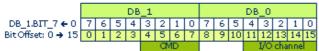
CMD 0x3 - Actuator Status Query

This message is sent to an actuator. It requests the status of one or all channels of an actuator.

Response Timing:

An Actuator Status Response message shall be received within a maximum of 300ms from the time of transmission of this message. In case no such response is received within this time frame the action shall be treated as completed without result.

Command ID 03 (CMD)



Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Not Used (=	0)				
4		Command ID	_	Command identifier	Enum: 0x03: ID 03		

8	3	Not Used (=	0)		
11	5	I/O channel	I/O	Enum:	
				0x000x1D:	Output channel (to load)
				0x1E:	All output channels supported by the device
				0x1F:	Input channel (from mains supply)

CMD 0x4 - Actuator Status Response

This message is sent by an actuator if one of the following events occurs:

- Status of one channel has been changed locally
- Message Actuator Status Query has been received

Response Timing:

This message shall be sent within a maximum of 50ms from the time of reception of the Actuator Status Query message.

Command ID 04 (CMD) DB_2.BIT_7 ← 0 Bit Offset: 0 → 23 DB_2 DB_2 DB_1 DB_0 DB_0 DB_0 DB_1 DB_0 DB_0 DB_0 DB_0 DB_1 DB_0 DB_

REMARK 1:

In case an Actuator Status Query message specifies a parameter that is not supported by the device being addresses, such device shall ignore the message and shall not answer using the Actuator Status Response message.

REMARK 2:

In case an Actuator Status Query message queries all output channels supported by a device being addresses, such device shall answer per each output channel by using an individual Actuator Measurement Response message.

Offset	Size	Data	ShortCut	Description	Valid Range Scale	Unit
0	1	Power Failure	PF		Power Failure Detection disabled/10b0: supported Power Failure Detection enabled 0b1:	not
1	_	Power Failure Detection	PFD		Power Failure not detected/not 0b0: supported/disabled Power Failure Detected 0b1:	
2	2	Not Used (= 0)				
4	4	Command ID	CMD	Command identifier	Enum: 0x04: ID 04	
8		Over current switch off	OC		Enum: Over current switch off: ready / n 0b0: supported Over current switch off: executed 0b1:	ot
9	2	Error level	EL		Enum: 0b00: Error level 0: hardware OK 0b01: Error level 1: hardware warning 0b10: Error level 2: hardware failure 0b11: Error level not supported	

11	5	I/O channel	I/O	Enum:
				0x000x1D: Output channel (to load)
				0x1E: Not applicable, do not use
				0x1F: Input channel (from mains supply)
16	1	Local control	LC	Enum:
				0b0: Local control disabled / not supported
				0b1: Local control enabled
17	7	Output value	OV	Enum:
				0x00: Output value 0% or OFF
	`			0x010x64: Output value 1% to 100% or ON
				0x650x7E: Not used
				0x7F: output value not valid / not set

CMD 0x5 - Actuator Set Measurement

The command defines values at offset 32 and at offset 40 which are the limits for the transmission periodicity of messages. MIT must not be set to 0, MAT >= MIT.

Response Timing: None

Command ID 05 (CMD)

			D	B_5						- [DB_	_4						- [DB_	3						DB	_2							DB.	_1							DB	_0			
DB_5.BIT_7 ← 0	7	6 5	4	- 3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7 (5 5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset: 0 → 47	0	1 2	3	4	5	6	7	8	9 :	10	11	12 :	13	14	15	16	17	18 1	19 2	20 2	21 2	22 2	23 2	24 2	5 2	6 27	28	29	30	31	32	33	34	35	36	37	38	39	40	41	42	43	44	45 4	46	47
CMD		ИD		RM	RE e	/p	Į,	/O cl	han	nel	П	7	LSE	3	Т		Ü	Jnit	т			M	SB				ma	8. t	ime	Res	spor	ice i	mes	s.	m	in, t	ime	Res	spon	ce m	ness	5.				

Measurement delta to be reported

Offset	Size	Data	ShortCut	Description	Valid Rang	e Scale	Unit
0	4	Not Used (= 0)					
4	4	Command ID	CMD	Command identifier	Enum:	<u></u>	
					0x05: ID 05		
8	1	Report measurement	RM		Enum:		
					Report n 0b0: only	neasurement: que	ry
					Report n 0b1: auto rep	neasurement: que orting	ry /
9	1	Reset measurement	RE		Enum:		
					Reset m	easurement: not a	ictive
					Reset model of the control of the co	easurement: trigg	er
10	1	Measurement mode	e/p		Enum:		
					0b0: Energy r	measurement	
					0b1: Power m	neasurement	
11	5	I/O channel	I/O		Enum:		
					0x000x1D: le	Ou <mark>tput channel (to</mark> oad)	
						All output channels supported by the d	
						nput channel (from	n
16		Measurement delta to be reported (LSB)	MD_LSB		04095	04095	N/A
20	1	Not Used (= 0)					
21	3	Unit	UN		Enum:		
					0x00:	Energy [Ws]	
					0x01:	Energy [Wh]	

					0x03: P	nergy [KWh] ower [W] ower [KW] ot used	- - -
24		Measurement delta to be reported (MSB)	MD_MSB		04095	04095	N/A
32		Maximum time between two subsequent actuator messages		Measurement Response messages [10s]	Enum: 1255: 0: Reserv	102550	5
40	_	Minimum time between two subsequent actuator messages	MIT	Measurement Response messages [s]	Enum: 1255: 0: Reserv	s 1255	

CMD 0x6 - Actuator Measurement Query

This message is sent to an actuator. The actuator replies with an Actuator Measurement Response message.

Response Timing:

An Actuator Message Response message shall be received within a maximum of 300ms from the time of transmission of this message. In case no such response is received within this time frame the action shall be treated as completed without result.

	Co	mr	na	nd	ID	0	6	(CI	МD)	V.					
				DΒ	_1							DÉ	_0	_		
DB_1.BIT_7 \leftarrow 0		6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset: 0 → 15	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
						a١	1D				qu		Į/O	chá	nne	

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Not Used (=	0)				
4		Command ID	_	Command identifier	Enum: 0x06: ID 06		
8	2	Not Used (=	0)				
10	1	Query	qu		Enum: 0b0: Query energy 0b1: Query power		
11	5	I/O channel	I/O		Enum: Output channel (to 0x000x1D: Ox1E: All output channed device Ox1F: Input channel (from	ls supported by t	

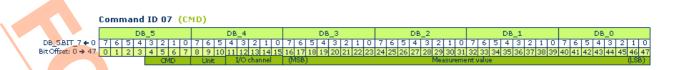
CMD 0x7 - Actuator Measurement Response

This message is sent by an actuator if one of the following events occurs:

- Measurement results trigger an automated transmission (see Actuator Set Measurement message)
- Message Actuator Measurement Query has been received

Response Timing:

This message shall be sent within a maximum of 50ms from the time of reception of the Actuator Measurement Query message.



REMARK 1

In case an Actuator Measurement Query message specifies a parameter that is not supported by the device addressed, such device shall ignore the message and shall not answer using the Actuator Measurement Response message.

REMARK 2:

In case an Actuator Measurement Query message queries all output channels supported by a device being addresses, such device shall answer per each output channel by using an individual Actuator Measurement Response message.

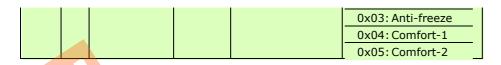
Offset	Size	Data	ShortCut	Description	Valid F	Range	Scale	Unit
0	4	Not Used (= 0)		•	•			
4	4	Command ID	CMD	Command identifier	Enum: 0x07: ID 07			
8	3	Unit	UN		Enum: 0x00: 0x01: 0x02: 0x03: 0x04: 0x050x07	Energy [Ws] Energy [Wh] Energy [KW] Power [W] Power [KW] : Not used]	
11	5	I/O channel	I/O		0x000x1D: 0x1E: 0x1F:	Output chan Not applicab Input channesupply)	le, do not ι	ıse
16		Measurement value (4 bytes)	MV	DB3 = MSB / DB0 = LSB	0429496729)5		N/A

CMD 0x8 - Actuator Set Pilot Wire Mode

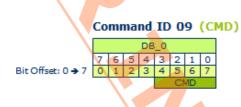
Command ID 08 (CMD)

				DB	_1							DB	_0			
	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset: 0 → 15	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
						CN	/ID								PM	

Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit
0	4	Not Used $(= 0)$)		
4	4	Command ID	CMD	Command identifier	Enum:
					0x08: ID 08
8	5	Not Used (= 0)			
13	3	Pilotwire mode	PM		Enum:
					0x00: Off
					0x01: Comfort
					0x02: Eco

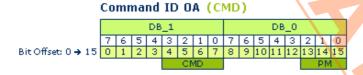


CMD 0x9 - Actuator Pilot Wire Mode Query



Offset	Size	Data	ShortCut	De	escriptio	n	Valid Range	Scale	Unit
0	4	Not Used (= (0)						
4	4	Command ID	CMD	Comm	nand ider	tifier	Enum:		
							0x09: ID 09)	

CMD 0xA - Actuator Pilot Wire Mode Response



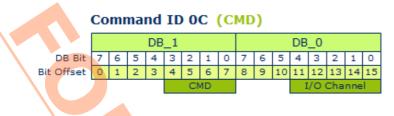
Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit
0	4	Not Used (= 0))		
4	4	Command ID	CMD	Command identifier	Enum:
					0x0A: ID 0A
8	5	Not Used (= 0))		
13	3	Pilotwire mode	PM		Enum:
					0x00: Off
					0x01: Comfort
					0x02: Eco
					0x03: Anti-freeze
					0x04: Comfort-1
					0x05: Comfort-2

CMD 0xB - Actuator Set External Interface Settings



Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Not Used (= 0)					
4	4	Command ID	CMD	Command identifier	Enum:		
		No.			0x0B: ID 0B		
8	3	Not Used (= 0)					
11		I/O channel	I/O		Enum:		
						nnel (to load)
					0x000x1D:	(,
					0x1E: All output c	hannels supp	oorted
					by the device	ce	
						nel (from ma	ins
					supply)		
16	16	Auto OFF Timer	AOT	Timer to automatically set	Enum:		
			\	OFF output channel when it	0x0000: Timer		
			· ·	is set ON	deactiva	ted	
					0 0001 0 5555		4550.4
					0x00010xFFFE:		6553.4 s
					0xFFFF: Does no	~	
					modify s value	saved	
32	16	Delay OFF	DOT	Delay timer before setting	Enum:		
32	10	Timer	DOT	output channel to OFF	0x0000: Timer		
				value received by radio	deactiva	ted	
				cmd			
					0x00010xFFFE:	0.1	6553.4 s
					0xFFFF: Does no	t	
					modify s	saved	
				· ·	value		
48	2	External	EBM	External interface mode	Enum:		
		Switch/Push			0b00: Not applicable		
		Button			0b01: External Switch		
					0b10: External Push Butt	on	
					0b11: Auto detect		
50	1	2-state switch	SWT	Switching state	Enum:		
					0b00: Change of key sta	te sets ON o	r OFF
					0b01: Specific ON/OFF p	ositions.	
					ON when contacts		
					OFF when contacts	s are open.	
51	5	Not Used (= 0)					

CMD 0xC - Actuator External Interface Settings Query



Offset	Size	Data	ShortCut	Description	Vali	d Range	Scale	Unit
0	4	Not Used (=	0)					
4	1	Command ID		Command identifier	Enum: 0x0C: ID 0C	_		
8	3	Not Used (=	0)					
11	5	I/O channel	I/O		Enum:			
					0x000x1D:	Output channel (to	o load)	
					0x1E:	All output channel device	s supported by t	he
					0x1F:	Input channel (fro	m mains supply))

CMD 0xD - Actuator External Interface Settings Response

	Co	mn	ıan	d I	D O	D	(C	MD)													//																													
	DB_6									//		[DB_	3						DB_	2						D	B_1							DB_	0															
DB Bit	7	6	5 4	1 3	2	1	0	7	6	5	4	3	2 :	1 (7	(5	4	3	2	1	0	7	6	5	4	3	2 1	0	7	6	5	4	3	2	1	0 :	7 6	5	4	3	2	1	0	7	6	5	4	3 2	2 1	0
Bit Offset	0	1	2 3	3 4	5	6	7	8	9	10 :	11 1	12 1	3 1	4 1	5 1	6 1	7 18	19	20	21	22	23	24	25 2	26 2	27 2	28 :	29 3	31	32	33	34	35	36	37	38 3	9 4	0 4	1 4:	2 43	44	45	46	47	48	49	50 :	51 5	52 5	3 54	4 55
	CMD I/O Channel						AC	т							Г							DOT	- "							EM	В	TW																			

Offset	Size	Data	ShortCut	Description	Valid R	ange	Scale	Unit
0	4	Not Used (= 0)						
4	4	Command ID	CMD	Command identifier	Enum: 0x0D: ID 0D			
8	3	Not Used (= 0)						
11	5	I/O channel	I/O		Enum: 0x000x1D: 0x1E: 0x1F:	Output channel Not applicable Input channel (supply)		
16	16	Auto OFF Timer	_	Timer to automatically set OFF output channel when it is set ON	Enum: 0x0000: 0x00010xFFF 0xFFFF:	Timer deactivated		.6553.4 s
32	16	Delay OFF Timer		Delay timer before setting output channel to OFF value received by radio cmd	Enum: 0x0000:	Timer deactivated		

					0x00010xFFFE: 0xFFFF: Does not modify saved value	0.16553.4 s
48	2	External Switch/Push Button	ЕВМ	External interface mode	Enum: 0b00: Not applicable 0b01: External Switch 0b10: External Push Button 0b11: Auto detect	- - -
50	1	2-state switch	SWT	Switching state	Enum: 0b00: Change of key state set 0b01: Specific ON/OFF position ON when contacts are contacts are	ns. losed.
51	5	Not Used $(= 0)$				

RORG	D2	VLD Telegram	
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Conf	trol
TYPE	01	Type 0x01 (description: see table)	

See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	02	Type 0x02 (description: see table)

See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	03	Type 0x03 (description: see table)

See profile: D2-01-00

RORG	D2	VLD Telegram		
FUNC	01	Electronic switches and dimmers with Energy Measurement	and Local	Control
TYPE	04	Type 0x04 (description: see table)		

See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	05	Type 0x05 (description: see table)

See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	06	Type 0x06 (description: see table)

See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	07	Type 0x07 (description: see table)

See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	08	Type 0x08 (description: see table)

See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	09	Type 0x09 (description: see table)

See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	0A	Type 0x0A (description: see table)

See profile: D2-01-00

RORG	D2	VLD Telegram			
FUNC	01	Electronic switches and dimmers with Energy Measurement and	d Lo	cal Con	trol
TYPE	0B	Type 0x0B (description: see table)	1/		

See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	0C	Type 0x0C

Submitter: AVIDSEN

Description

Intended for heating module with Pilotwire command and Energy Measurement.

Pilot wire includes 6 different modes:

- Off
- Comfort
- Eco
- Anti-freeze
- Comfort-1°C
- Comfort-2°C

Data exchange

Direction: bidirectional Addressing: broadcast

Communication trigger: event-triggered

Communication interval: at each state change / every 5 minutes Trigger event: actuator status change, consumption information change

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: Universal teach-in (UTE)

Security

Encryption supported: no Security level format: -

Supported command	Type 0x0C
0x1 - Actuator Set Output	X
0x2 - Actuator Set Local	Χ
0x3 - Actuator Status Query	X
0x4 - Actuator Status Response	X
0x5 - Actuator Set Measurement	Х
0x6 - Actuator Measurement Query	Х
0x7 – Actuator Measurement Response	X
0x8 - Actuator Set Pilot Wire Mode	Χ
0x9 – Actuator Pilot Wire Mode Query	Χ
0xA - Actuator Pilot Wire Mode Response	X

Telegram Definition

The telegrams corresponding to Command IDs: 0x1, 0x2, 0x3, 0x4, 0x5, 0x6 and 0x7 are already defined in EEP V2.6.2 and do not change.

See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	0D	Type 0x0D

Submitter: ID-RF

Description for TYPE 0x0D, 0x0E, 0x0F, 0x12

Add three commands:

- CMD 0xB Actuator Set External Interface Settings
- CMD 0xC Actuator External Interface Settings Query
- CMD 0xD Actuator External Interface Settings Response

Supported functions:

- External Switch/Push Button Control
- External Switch/Push Button Type (Bi-stable or Mono-stable / 2-state switch)
- Auto OFF Timer
- Delay OFF Timer

Add D2-01-0D profile – Micro smart plug with 1 channel, no metering capabilities Add D2-01-0E profile – Micro smart plug with 1 channel, and metering capabilities

Add D2-01-0F profile – Slot-in module with 1 channel, no metering capabilities Add D2-01-12 profile – Slot-in module with 2 channels, no metering capabilities

These new profiles are modifications of the existing ones, please find below a listing:

- Profile D2-01-0D is all same as D2-01-0A but with one modification
- Profile D2-01-0E is all same as D2-01-0B but with one modification
- Profiles D2-01-0F is all same as D2-01-0A but with three modifications
- Profiles D2-01-12 is all same as D2-01-0A but with four modifications

Description of new supported functions

External Switch/Push Button Control

As for "Local Control" function, it indicates if the product can be controlled using an additional physical interface, as an external push button or wall switch. This interface is not directly integrated to the product, but can be connected using wires.

External Switch/Push Button Type

- Bi-stable or Mono-stable:
 - External interface can be composed of bi-stable button (switch) or mono-stable button (push button). Depending of the type selected, the product will have different reactions when switch/push button actions are detected.
 - If bi-stable button type selected, each change of state (open or close) toggle the output.
 - If mono-stable button type selected, first change of state (open or close) toggle the output, second change (close or open) is ignored, and output remains unchanged.

NOTE: If the product has more than one output, the external interface type is applied for all outputs.

• 2-state switch:

This parameter is effective only if external switch/push button type is set as "bi-stable". When this setting is enabled, the device will turn ON output(s) when contacts are closed and turn OFF output(s) when contacts are open. When this setting is disabled (default mode), a change of contacts state will toggle the output(s).

Auto OFF Timer

This functions turns OFF the output when time elapsed.

Use case: In corridor, when you turn ON the light, you want it to be turned OFF automatically after a certain time.

Delay OFF Timer

When the device receives a valid radio command, setting an output state to OFF, instead of setting immediately the new output state, this function set the new output state when time elapsed.

Use Case: In hotel room, when you send a radio command (removing card from card switch) to turn OFF the light, instead, turn OFF light after a certain time, to allow people to leave the room.

The addition of these functions required three new commands:

- CMD 0xB Actuator Set External Interface Settings
- CMD 0xC Actuator External Interface Settings Query
- CMD 0xD Actuator External Interface Settings Response

Data exchange

Direction: bidirectional Addressing: broadcast

Communication trigger: event triggered Communication interval: no fix interval

Trigger event: actuator status change, consumption information

Tx delay: -Rx timeout: -

<u>leach-in</u>

Teach-in method: Universal teach-in (UTE)

Security

Encryption supported: no Security level format: -

Supported command	Type 0x0D	Type 0x0E	Type 0x0F	Type 0x12
0x1 - Actuator Set Output	X	Χ	Χ	X
0x2 - Actuator Set Local	X	X	X	X
0x3 - Actuator Status Query	X	X	X	X
0x4 - Actuator Status Response	Х	Χ	Χ	Х
0x5 – Actuator Set Measurement	-	Χ	_	-

0x6 – Actuator Measurement Query	_	Х	-	-
0x7 – Actuator Measurement Response	-	Χ	-	-
0x8 - Actuator Set Pilot Wire Mode	_	_	_	_
0x9 - Actuator Pilot Wire Mode Query	-	-	-	-
0xA – Actuator Pilot Wire Mode Response	-	-	-	-
0xB – Actuator Set External Interface Settings	-	-	Χ	Χ
0xC – Actuator External Interface Settings Query	-	-	Χ	Χ
0xD - Actuator External Interface Settings Response	-	-	Х	Х

See profile: D2-01-00

RORG	D2		VLD Telegram
FUNC	01	Electronic	switches and dimmers with Energy Measurement and Local Control
TYPE	0E		Type 0x0E

Submitter: ID-RF

Description see TYPE 0x0D

See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	0F	Type 0x0F

Submitter: ID-RF

Description see TYPE 0x0D

See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	10	Type 0x10 (description: see table)

See profile: D2-01-00

RORG	D2	VLD Telegram			
FUNC	01	Electronic switches and dimmers with Energy Measurement a	and L	ocal Co	ontrol
TYPE	11	Type 0x11 (description: see table)			

See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	12	Type 0x12

Submitter: ID-RF

Description see TYPE 0x0D

See profile: D2-01-00

D2-02: Sensors for Temperature, Illumination, Occupancy And Smoke

This EEP family shall be used for bidirectional sensors that measure temperature, illumination, and detect room occupancy and smoke presence.

The EEP may be used in conjunction with the Smart Acknowledge protocol.

For teach-in and teach-out the "Universal Uni- and Bidirectional Teach-In Procedure for EEP based Communication" shall be used. Alternatively the Smart Acknowledge Teach-In Procedure is used for those sensors supporting Smart Acknowledge.

\$	Supported function	Type 0x00	Type 0x01	Type 0x02
1	Temperature Sensor	X	X	X
1	Illumination Sensor	X	X	-
(Occupancy Detector	Х	-	-
9	Smoke Detector	Χ	X	X

RORG	D2	VLD Telegram
FUNC	02	Sensors for Temperature, Illumination, Occupancy And Smoke
TYPE	00	Type 0x00

Submitter: MSR-Office

CMD 0x1 - Sensor Measurement

This message is sent by a sensor if one of the following events occurs:

- Measurement results trigger an automated transmission (see Actuator Set Measurement message)
- Message Actuator Measurement Query has been received

Response Timing: None

Command ID 01 (CMD)

	DB_3							DB_2							DB_1							DB_0										
DB_3.BIT_7 ← 0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset: 0 → 31	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31
QMD							1	ype							MS	В				me	easu	ire n	nent	: val	ue				L	SB		

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Not Used (= 0)					
4	4	Command ID	CMD	command identifier	Enum:		
					0x01: ID 01		

8	3	Measurement type	type		Enum:			
					0x00:	Temperature (06 +120°C)	5535: -40 to	
					0x01:	Illumination (065	535: 0 to 204	17lx)
					0x02:	Occupancy (0: not detected)	detected; 1:	
					0x03:	Smoke The following contervalue in DB_0 and 0x00 - No smoke of 0x01 - Smoke detectamber 0x02 - Smoke detectamber 0x03 - Smoke detectamber	DB_1: letected ected via ioniz ected via optic	ation
11	5	Not Used (= 0)						
16	16	Measurement value (2 bytes)	MV	DB_0 = LSB / DB_1 = MSB	0655	335		N/A

CMD 0x2 - Sensor Test/Trigger

This message is sent to a sensor. It causes the sensor to enter self-test mode or trigger an alarm (if supported).

Response Timing: None

Command ID 02 (CMD)

		DB_1					DB_0									
DB_1.BIT_7 ← 0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset: 0 → 15	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
						a,	4D		ST	TA					\mathcal{I}	$\overline{}$

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Not Used (= 0	0)				
4	4	Command ID	CMD	Command identifier	Enum:		
					0x02: ID 02	_ /	
8	1	Self-test	ST		Enum:		
					0b0: Self-test mode 0b1: Normal operation		
9	1	Trigger alarm	TA		Enum:		
					0b0: Trigger a	alarm	
					0b1: Normal	operatio	on
10	6	Not Used (= 0	0)				

CMD 0x3 - Actuator Set Measurement

This message is sent to a sensor. It configures the measurement behaviour of the sensor.

Response Timing: None



Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Not Used (= 0)					
4	4	Command ID	CMD	Command identifier	Enum: 0x03: ID 03		
8	1	Report measurement	RM		0b0: only	asurement: quasurement: quasurement: quasi	
9	7	Not Used (= 0)			•		
16		Measurement delta to be reported (LSB)	MD_LSB		04095	04095	N/A
20	1	Not Used (= 0)					
21	3	Unit	UN	3		mperature (°C umination (lx) t used)
24	_	Measurement delta to be reported (MSB)	MD_MSB		04095	04095	N/A
32	_	Maximum time between two subsequent Actuator	MAT	Measurement Response messages [10s]	0255	102550	s
40	_	Minimum time between two subsequent Actuator	MIT	Measurement Response messages [s]	0255	0255	S

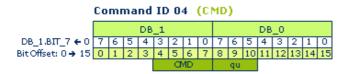
CMD 0x4 - Sensor Measurement Query

This message is sent to a sensor. The sensor replies with an Sensor Measurement message.

Response Timing:

A Sensor Measurement message shall be received within a maximum of 300ms from the time of transmission of this message.

In case no such response is received within this time frame the action shall be treated as completed without result.



Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Not Used (= 0	0)				
4	4	Command ID	CMD	Command identifier	Enum: 0x04: ID 04	-	
8	3	Query	qu			ry temperat ry illuminat	

		0x2:	Query occupancy
		0x3:	Query smoke
		0x40	x7: Not used
11 5	Not Used (= 0)		

RORG	D2	VLD Telegram
FUNC	02	Sensors for Temperature, Illumination, Occupancy And Smoke
TYPE	01	Type 0x01 (description: see table)

See profile: D2-02-00

RORG	D2	VLD Telegram
FUNC	02	Sensors for Temperature, Illumination, Occupancy And Smoke
TYPE	02	Type 0x02 (description: see table)

See profile: D2-02-00

D2-03: Light, Switching + Blind Control

The EEP family D2-03-xx provides different telegram types for switches, light and blind control. The purpose is to support secure communication and other functional aspects of applications extending the possibilities given by existing profiles (1BS, RPS, 4BS). Transmitting information in the status field of a telegram is not necessary with this EEP family.

RORG	D2	VLD Telegram
FUNC	03	Light, Switching + Blind Control
TYPE	00	Type 0x00

Submitter: EnOcean GmbH

EEP Properties: DATA EXCHANGE Direction: unidirectional

Addressing: broadcast

Communication trigger: event-triggered

Communication interval: N/A

Trigger event: N/A Tx delay: N/A Rx timeout: N/A

TEACH-IN

Teach-in method: Universal teach-in (UTE) + Secure Teach-in (for secure communication)

Encryption supported: yes

EEP Family Table:

Supported function	Type 00
2 Rocker Switch	Χ

The encrypted telegram has the R-ORG 0x30. The payload (4 bits) is encrypted. That telegram can be repeated. After decryption and the authentication of the CMAC, the telegram turns into a non-encrypted EnOcean telegram with the R-ORG 0x32. The payload will be expanded to 8 bits (4 MSB set to zero) and can then be interpreted as described in

the telegram definition table.

The decrypted telegram may not be repeated as the information is not secure anymore. The following table provides information about the conversion between the profiles D2-03-00 and F6-02-01:

D2-03-00 DATA	F6-02-01 DATA	F6-02-01 STATUS
04	_	=
5	0x17	0x30
6	0x70	0x20
7	0x37	0x30
8	0x10	0x20
9	0x15	0x30
10	0x35	0x30
11	0x50	0x30
12	0x70	0x30
13	0x10	0x30
14	0x30	0x30
15	bxxx0xxxx	0x20

Offset	Size	Data	ShortCut	Description	Val	lid Range	Scale	Unit
0	4	Not Used (= 0)						
	4		RI2	Information about pressed rockers (similar to RPS profiles)	Fnum: 04: 5: 6: 7: 8: 9: 10: 11: 12:	Reserved Button A1 + energy bow p 3 or 4 button energy bow p Button A0 + energy bow p No buttons p bow pressed Button A1 + energy bow p Button A0 + energy bow p Button B1 pro bow pressed Button B0 pro bow pressed Button A1 pro	B0 pressed pre	rgy , , rgy
					14:	Button A0 probow pressed Energy bow r		-gy

RORG	D2	VLD Telegram				
FUNC	03	Light, Switching + Blind Contro				
TYPE	10	Mechanical Handle				

Submitter: Eltako

This document contains the description of <u>decrypted</u> mechanical handle data. The mechanical handle profile must be redefined because there is no status field in EnOcean security available.

EEP Properties:

DATA EXCHANGE
Direction: unidirectional
Addressing: broadcast

Communication trigger: event-triggered

Communication interval: N/A

Trigger event: rotate mechanical handle

Tx delay: N/A Rx timeout: N/A

TEACH-IN

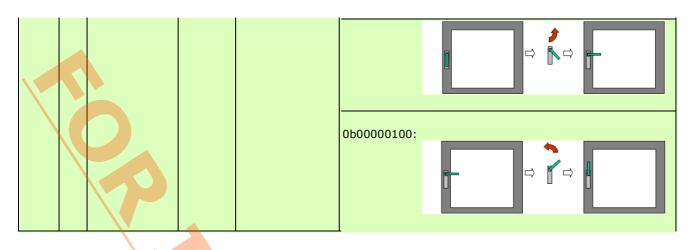
Teach-in method: Secure Teach-in, followed by special RPS teach-in sequence: Mechanical handle (closed => opened

=> closed within 2s)

SECURITY

Encryption supported: yes Security level format:

Offset	Size	Data	ShortCut		Valid Range Scale Unit			
0	8	Window handle, decrypted data	WIN	Movement of the window handle	Enum:			
		deci ypted data		Willdow Hallale	0ь00000001:			
					n			
					Ľ			
					0b00000010:			
			· ·					
					Ĭ			
					0b00000011:			
					0ь00000100:			
					0b00000011:			
					1			
					Ŭ V			
					0b00000010:			
					4			
					U			
					0b00000011:			
					050000011.			



D2-04: CO2, Humidity, Temperature, Day/Night and Autonomy

CO2 sensor with 8 bits resolution (0 – 2000ppm or 0-5000ppm range) 8 bits temperature and relative humidity with Day / Night and battery autonomy.

Day / Night is based on illumination not on clock

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: time-triggered

Communication interval: According to remaining autonomy and day or night

Trigger event: heartbeat, ...

Teach-in method: Universal teach-in, Smart Ack

Encryption required: no Security level format: 0

EEP Family Table

Each TYPE has to support every parameter that is marked in its column!

TYPE	0x00	0x01	0x02	0x03	0x04	0x05	0x06	0x07	0x08	0x0	0x10	0x1A	0x1B	0x1C	0x1D	Ox1E
CO2 Sensor 0-2000	Χ	Χ	Χ	Χ	Χ	Χ	Χ	X	-	-	-	-	-	-	-	-
ppm range																
CO2 Sensor 0-5000	-	-	-	-	-	-	-	-	X	X	Χ	Χ	Χ	Χ	Χ	Χ
ppm range																
Humidity Sensor	Χ	X	-	-	-	-	-	-	X	X	1-	-	-	-	-	-
Temperature Sensor	Χ	-	Χ	Χ	Χ	Χ	-	-	Х		X	Χ	Χ	Χ	-	-
Day/Night Sensor	Χ	Χ	Χ	-	-	Χ	Χ	Χ	Χ	X	Χ		-	Χ	Χ	Χ
Battery Autonomy	Χ	Χ	Χ	Χ	-	-	-	Χ	Χ	X	X	Χ	-	-	-	Χ

RORG	D2	VLD Telegram					
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy					
TYPE	00	Type 0x00					

Submitter: NanoSense

The manufacturer will indicate emission rates versus battery autonomy and day night status.

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	CO2		Concentration (linear), 1 LSB = 7.84 ppm Or Concentration (linear), 1 LSB = 19.6 ppm		02000 (or 5000)	ppm

8	8	Humidity	HUM	Rel. Humidity (linear), 1 LSB = 0.5 %	0200 01	100	%
16	8	Temperature	TMP	Temperature (linear), 1 LSB = 0.2 °C	0255 0	+51	°C
24	1	Day/Night	DN		Enum:		
					0: Day		
					1: Night		
25	3	Battery	ВА	Battery autonomy	Enum:		
		autonomy			0: 100 - 87.5	5 %	
	//				1: 87.5 - 75	%	
					2: 75 - 62.5 °	%	
	`				3: 62.5 - 50 °	%	
					4: 50 - 37.5 °	%	
					5: 37.5 - 25 °	%	
		N N			6: 25 - 12.5 °	%	
					7: 12.5 - 0 %	, 0	
28	4	Not Used (= 0)					

RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
TYPE	01	Type 0x01 (description: see table)

See profile: D2-04-00

RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
TYPE	02	Type 0x02 (description: see table)

See profile: D2-04-00

RORG	D2	VLD Telegram	
FUNC	04	CO2, Humidity, Temperature, Day/Night	and Autonomy
TYPE	03	Type 0x03 (description: see to	able)

See profile: D2-04-00

RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
TYPE	04	Type 0x04 (description: see table)

See profile: D2-04-00

RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
TYPE	05	Type 0x05 (description: see table)

See profile: D2-04-00

RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
TYPE	06	Type 0x06 (description: see table)

See profile: D2-04-00

RORG	D2	✓ VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
TYPE	07	Type 0x07 (description: see table)

See profile: D2-04-00

RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
TYPE	08	Type 0x08 (description: see table)

See profile: D2-04-00

RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
TYPE	09	Type 0x09 (description: see table)

See profile: D2-04-00

RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
TYPE	10	Type 0x10 (description: see table)

See profile: D2-04-00

RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
TYPE	1A	Type 0x1A (description: see table)

See profile: D2-04-00

RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
TYPE	1B	Type 0x1B (description: see table)

See profile: D2-04-00

RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
TYPE	1C	Type 0x1C (description: see table)

See profile: D2-04-00

RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
TYPE	1D	Type 0x1D (description: see table)

See profile: D2-04-00

RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
TYPE	1E	Type 0x1E (description: see table)

See profile: D2-04-00

D2-05: Blinds Control for Position and Angle

Submitter: AWAG Elektrotechnik AG

Description

The protocol is intended for commissioning as well as for operation of a single channel blind actuator that supports control of the vertical position as well as the rotation angle of the slats.

Data exchange

Direction: bidirectional

Addressing: unicast (ADT) & broadcast

Communication trigger: event-triggered or upon query Communication interval: heartbeat (off or 30 s or 3 min)

Trigger event:

a) status change (alarm, blockage, deblockage)

b) position change > 10 % of range

c) end position reached (0% or 100%)

d) heartbeat

Tx delay: n/a Rx timeout: n/a

Teach-in

Teach-in method: Universal teach-in

Security

Encryption supported: no Security level format: n/a

EEP Family Table

Each TYPE has to support all telegrams and parameters marked in its column.



No. of output channels	1
Go to Position and Angle	Χ
Stop	Χ
Query Position and Angle	Χ
Reply Position and Angle	Χ
Set parameters	Χ

Parameter	Type 0x00
Vertical position	Χ
Rotation angle	Χ
Repositioning	Χ
Blockage mode	Χ
Alarm mode	X
Set vertical, 5 sec 5 min	X
Set rotation, 0 2.54 sec	Χ
Set Alarm Action	X

RORG	D2	VLD Telegram
FUNC	05	Blinds Control for Position and Angle
TYPE	00	Type 0x00

Submitter: AWAG Elektrotechnik AG

CMD 1 - Go to Position and Angle

Once the actuator is configured either by the "Set Parameters" command or through manual configuration (using local buttons) the position of the blinds can be controlled with this command.

When the actuator is set to "blockage" mode, neither local nor central positioning and configuration commands will be executed. This mode is intended for putting the device temporarily out of service, e.g. for a maintenance operation. When the actuator is set to the "alarm" mode neither local nor central positioning and configuration commands will be executed. Before entering the "alarm" mode, the actuator will execute the "alarm action" as configured by the "Set parameter" command.

When this command is sent with the "deblockage" option, the actuator terminates the "alarm" or "blockage" mode and enters the normal mode.

Exemplary illustration of data bytes 0 ... 3:

Command ID 01 (CMD)

	DB_3				DB_2				DB_1					DB_0																		
DB_3.BIT_7 ← 0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset: 0 🗲 31	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31
POS				ANG				REPO LOC				ОC	K	CHN CMD																		

Offset	Size	Data	ShortCut	Description	Valid	Range	Scale	Unit
0	1	Not Used (= 0))					
1	7	Position	POS	Vertical position	Enum:			
					0100: 127:	Do not change	01	00%
8	1	Not Used (= 0)					

9	7	Angle	ANG	Rotation angle	Enum:
					0100: 0100 % 127: Do not change
16	1	Not Used (= 0))		
17	3	Repo <mark>sit</mark> ioning	REPO	How to adjust the internal positioning tracker before going to the new position	Enum: 0: Go directly to POS/ANG
		P			1: Go up (0%), then to POS/ANG
					2: Go down (100%), then to POS/ANG
					3 Reserved 7:
20	1	Not Used $(= 0)$)		
21		Locking modes	LOCK	Set/reset locking modes	Enum: 0: Do not change 1: Set blockage mode 2: Set alarm mode 3 6: Reserved 7: Deblockage
24	4	Channel	CHN	Channel address	Enum: 0: Channel 1
28	4	Command ID	CMD	Command identifier	Enum: 1: Goto command

CMD 2 - Stop

This command immediately stops a running blind motor. It has no effect when the actuator is in "blockage" or "alarm" mode, i.e. it will not stop an eventual "go up" or "go down" alarm action.

Offset	Size	Data	ShortCut	Description	Valid	Range	Scale	Unit
0	4	Channel	CHN	Channel address	Enum 0:	: Channe	el 1	
4	4	Command ID	CMD	Command identifier		: Stop co	mman	d

CMD 3 - Query Position and Angle

This command requests the actuator to return a "reply" command.

Offset	Size	Data	ShortCut	Description	Valid	l Range	Scale	Unit
0	4	Channel	CHN	Channel address	Enum	:		
					0:	Channe	l 1	
4	4	Command ID	CMD	Command identifier	Enum	:		
					3:	Query c	ommar	nd

CMD 4 - Reply Position and Angle

Either upon request ("Query" command) or after an internal trigger (see EEP Properties) the actuator sends this command to inform about its current state.

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	1	Not Used (= 0))				

1	7	Position	POS	Current vertical position	Enum: 0100: 127: Position unknown, will be known after the next goto cmd
8	1	Not Used (= 0)			
9	7	Angle	ANG	Current rotation angle	Enum:
					0100: % 0100
					127: Angle unknown, will be known after the next goto cmd
16	5	Not Used (= 0))		
21	3	Locking modes	LOCK	Current locking mode	Enum: 0: Normal (no lock) 1: Blockage mode 2: Alarm mode 3 7: Reserved
24	4	Channel	CHN	Channel address	Enum: 0: Channel 1
28	4	Command ID	CMD	Command identifier	Enum: 4: Reply command

CMD 5 - Set parameters

This command sets one or multiple configuration parameters of the actuator. When a parameter value is set to "-> no change" this parameter will not be modified. The VERT and ROT parameters describe the duration needed by the motor for a full run of the blind, or for a complete turn of the slats, respectively. They have to be measured on site and assigned to the actuator.

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	1	Not Used (=	0)				
1	15	Set vertical	VERT	Measured duration of a vertical	Enum:		
				run	50030000: 0 499: Reserved 32767 -> No (0x7FFF): change	500030	0000 ms
16	8	Set rotation	ROT	Measured duration of rotation	Enum: 1254: 0: No rotation 255: -> No change	r 102540	ms
24	5	Not Used (=	0)				
29	_	Set alarm action	AA	Besides locking all other commands entering the alarm mode results in	Enum: 0: No action 1: Immediate stop 2: Go up (0%) 3: Go down (100%) 4 6: Reserved 7: -> No change		
32	4	Channel	CHN	Channel address	Enum: 0: Channel 1		
36		Command ID	CMD	Command identifier	Enum: 5: Set parameters cor	mmand	

D2-06: Multisensor Window Handle

EEP Family Table

Each TYPE has to support all telegrams and parameters marked in its column.

Type 01
Х
Х
Χ
Х
Х
Х
Х

The list of parameters could be structured following the features that always include a certain group of parameters.

RORG	D2			VLD Telegram
FUNC	06			Multisensor Window Handle
TYPE	01	Ala	rm, Po	osition Sensor, Vacation Mode, Optional Sensors

Submitter: SODA GmbH

Data exchange

Direction: bidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication interval: Time-Triggered: Default is 20 Minutes; Event-Triggered Trigger event: Alarm, Handle Movement, Window Movement, Button Presses

Tx delay: 500 ms Rx timeout: 100 ms

Teach-in

Teach-in method: Universal teach-in (UTE)

Security

Encryption supported: no Security level format: -

Product Description

The device represented by this EEP is a "Multi-Sensor Window Handle with Alarm Functionality". It is powered by two 1.5V AA batteries.

It can be equipped with the following set of features:

- Alarm Sensor
- Handle Position Sensor
- Window Position Sensor
- Two General Purpose Buttons
- Temperature Sensor
- Humidity Sensor
- Illumination Sensor
- Motion Sensor
- Vacation Mode
- Battery Level Measurement
- Buzzer
- Two I FDs

Details to all features are listed below.

For pairing the bidirectional UTE method is used.

The device transmits the actual sensor values periodically (dDefault: 20 minutes) or on an event like "Handle Movement" or "Alarm".

After each transmission of a packet the radio part of the handle is in receive mode for a certain amount of time (default: 500 ms) and accepts then messages from a paired Controller/Gateway/... . For normal operation it is not necessary to send data to the handle. It is just needed to make some configurations, get log data or control some parts of the handle.

Because it is possible to have all possible permutations of the handle features out in the market, the EEP approach presented in this document is used. The variety of handle-products with different equipped features does not fit well

to the EEP family approach preferred in the EnOcean world.

Feature Description

The handle may have all or a subset of the features described here. If a feature is not available (e.g. the sensor is not equipped), then this will be marked in the radio telegram (see detailed tables below).

Burglary Alarm Sensor

The handle can detect if someone tries to commit burglary on the window the handle is mounted on. The Burglary Alarm Sensor is automatically enabled/disabled each time the window is closed/opened. If an alarm is detected, a radio packet is send with "Burglary Alarm Triggered" flag set and (if handle is equipped with a buzzer) a local alarm sound is generated by the internal buzzer for a certain amount of time (180 s). During the alarm time a repeated "Burglary Alarm On" is send every 15 seconds + Random Offset (0...7 seconds).

Protection Plus Alarm Sensor

Protection Plus is a feature, which generates an alarm every time the handle is moved. Due to security reasons, the detailed documentation about this feature is available from SODA GmbH only under NDA.

Handle Position

The position of the handle is detected and transmitted on every change.

Window Position

It is possible to detect if the window is tilted or not tilted. A packet is send on every change.

General Purpose Buttons

There are two buttons on the handle which can be used as general purpose buttons to control blinds/shutters, lights, etc.

A packet is send when a button is pressed and again when it is released.

Temperature Sensor, Humidity Sensor, Brightness Sensor

The environmental sensors are updated periodically (adjustable, default: 20 minutes) and after this a packet with the updated values is send.

Motion Sensor

The handle can be equipped with a PIR Motion sensor which triggers a packet every time a motion change is detected.

Vacation Mode

If the Vacation Mode is enabled, the red LEDs on the sides of the handle light up every few seconds. This signalizes that the alarm monitoring is active and should be daunting for potential burglars.

The Vacation Mode can be enabled/disabled by a radio command or by a button press locally on the handle. If it is activated locally, a radio packet is sent out to signalize the change to a paired gateway.

Battery Monitor

The handle monitors its battery level and transmits the state of the battery.

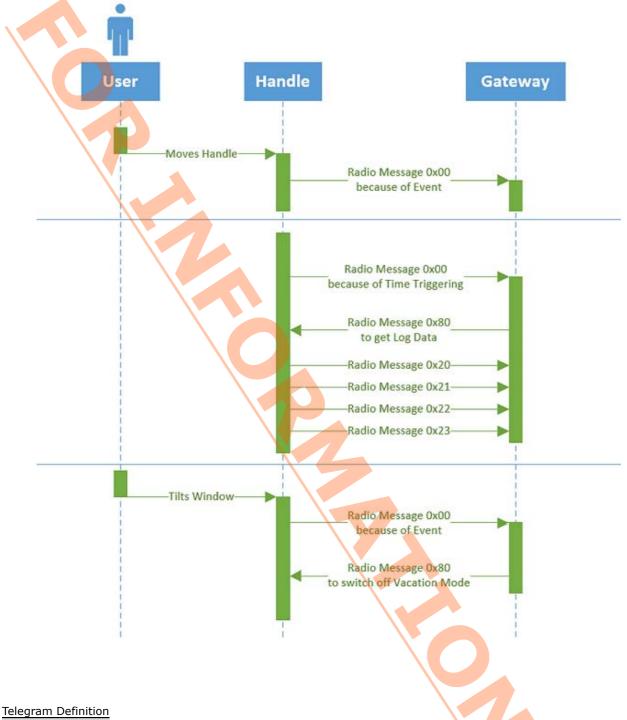
Battery Low Click

If enabled, the handle also makes some click noises when the battery level is critical.

Handle Closed Click

The handle generates a click sound every time the handle is closed (put in downward position). This signalizes the activation of the alarm monitoring and gives an acoustic feedback to the user. This click sound can be enabled or disabled by a radio command.

Communication Example



The device uses different types of messages for bidirectional communication. The MSB of the VLD payload defines the type of message as shown below in the first table. The different message types are listed in the second table. A detailed description of each message type is then followed in separate tables.

RORG			Payload	Sender ID	Status	CRC8	
D2	Message Type (MT) 1 Byte	(Content of Message as described below 0 13 Bytes	4 Bytes	1 Byte	1 Byte	
	Message Type		Message Type Descript	tion		Encoding	Receive/Transmit
Sensor V	/alues		Standard package which contains the actua values of the integrated sensors.	al		0x00	Transmit
Configur	ration Report		There are some settings which can be influe This package is send on request and contai	0x10	Transmit		
Log Data	a 01		Some Log Data which can be read from the	handle upon r	equest.	0x20	Transmit
Log Data	a 02		Log Data Packet 02			0x21	Transmit
Log Data	a 03		Log Data Packet 03			0x22	Transmit
Log Data	a 04		Log Data Packet 04			0x23	Transmit
Control	and Settings		This package can be send to handle to trigg	ger some action	ns.	0x80	Receive

Message Type 0x00: Sensor Values



Offset	Size	Data	ShortCut	Description	Valid	Range	Scale	Unit
0	8	Message Type	MT	Descriptor of this message	Enum:			
					0x00: Mes	ssage Type Sei	nsor Values	
8	4	Burglary Alarm	BAL	Burglary Alarm Trigger	Enum:			
				Signal	0x0:	Burglary Alai	m Not Trigg	ered
					0x1:	Burglary Alai	m Triggered	_
					0x20xD	: Reserved		
					0xE:	Supported +	Invalid	
					0xF:	Not Supporte	ed	
12	4	Protection Plus	PPAL	Protection Plus Alarm Trigger	Enum:			
		Alarm		Signal	0x0:	Protection Plu Triggered	ıs Alarm Not	
					0x1:	Protection Plu	ıs Alarm Triç	gered
					0x20xD:	Reserved		
					0xE:	Supported +	Invalid	
					0xF:	Not Supporte	d	

1.0	4	Hondle Desire	LID	Desition of the dis	F
16	4	Handle Position	HP	Position of Handle	Enum:
					0x0: Handle Position Undefined
					0x1: Handle Up
					0x2: Handle Down
					0x3: Handle Left
					0x4: Handle Right
					0x50xD: Reserved
					0xE: Supported + Invalid
					0xF: Not Supported
20	4	Window State	WS	State of Window	Enum:
20		Wildow State		State of William	0x0: Window State Undefined
					0x1: Window Not Tilted
					0x2: Window Tilted
					0x30xD: Reserved
					0xE: Supported + Invalid
					0xF: Not Supported
24	4	Button Right	BR	Button Right Activities	Enum:
		\			0x0: No Change
					0x1: Button Pressed
					0x2: Button Released
					0x30xD: Reserved
2.5		.			0xF: Not Supported
28	4	Button Left	BL	Button Left Activities	Enum:
					0x0: No Change
					0x1: Button Pressed
					0x2: Button Released
					0x30xD: Reserved
					0xE: Supported + Invalid
					0xF: Not Supported
32	4	Motion	М	Motion sensing like typical	Enum:
32	l '	11001011		PIR sensors	0x0: Motion Not Triggered
					-
					0x1: Motion Triggered
					0x20xD: Reserved
					0xE: Supported + Invalid
					0xF: Not Supported
36	4	Vacation Mode	V	If Vacation Mode is active,	Enum:
				the LEDs of	0x0: No Change
				the handle light up every	
				few seconds.	0x1: Vacation Mode Locally Switched
				Vacation Mode can be	On
				activated remotely	0x2: Vacation Mode Locally Switched
				by a radio command or	Off
				locally by a	Reserved
				button press at the handle	0x30xD:
					0xE: Supported + Invalid
					0xF: Not Supported
40	8	Temperature	Т	Measurement of	Enum:
				Temperature in linear	0250:
				0.32 °C steps	-20+60 °C
					Reserved
					251253:
					251253. 254: Supported +
					Invalid
					255: Not Supported
48	0	Llumidit.	Ш	Monguement of Deletine	
40	8	Humidity	Н	Measurement of Relative Humidity in	Enum:
				linear 0.5 % steps	0200:
				са. 515 70 Зсерз	0100
					201253: Reserved
					254: Supported + Invalid

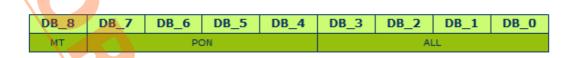
					255: No	t Supported	
56	16	Illumination	I	Illumination linear in 1 lx	Enum:		
				steps	060000:		
							060000 lx
					60001:	Over Range	
						Reserved	
					6000265533:		
	/ =				65534:	Supported +	
						Invalid	
					65535:	Not Supported	
72	5	Battery State	BS	State of the battery charge	Enum:		
				in 5 % steps	020:	%	
						0100	
					2131: Rese	ved	
77	3	Not Used (= 0)					

Message Type 0x10: Configuration Report

							_		_																															
	DB_4							DB	3_3							DE	3_2							DB	_1							DB	_0_							
DB Bit	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39
				N	ήT.																			SU	IR											VB	IR.			
	MT							INO.	CO S	SICP.	-	/																												

Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit								
0	8	Message Type	MT	Descriptor of this message	Message Type Co 0x10: Report	onfiguration							
8	1	Vacation Mode	VMR	Status of Vacation Mode	Enum: 0x0: Vacation Mode is Off 0x1: Vacation Mode is On								
9		Handle Closed Click	HCCR	Status of Handle Closed Click Feature	Handle Closed Clic 0x0: Disabled Handle Closed Clic 0x1: Enabled								
10		Battery Low Click	BLCR	Status of Battery Low Click Feature	Battery Low Click 0x0: Disabled Battery Low Click 0x1: Enabled								
11	5	Not Used (= 0)											
16		Sensor Update Interval		Interval in seconds between the update of the environmental sensors. After each update period a Sensor Value packet (Message Type 0x00, see above) is transmitted	Enum: 0x00000x0004: Rese 0x00050xFFFF:	5655	s 35						
32		Vacation Blink Interval	VBIR	Interval in seconds between the LED blinks when Vacation Mode is activated	Enum: 0x000x02: Reserved 0x030xFF:	s 3255							

Message Type 0x20: Log Data 01



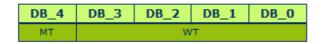
Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit		
0	8	Message Type	MT	Descriptor of this message	Enum:				
					0x20: Message Typ	e Log Data	01		
8	32	Power Ons	PON	Number of Power Ons	ns Enum:				
					0x000000000xFF	FFFFFF:	_		
40	32	Alarms	ALL	Number of Alarms	Enum:				
				0x00000000xFFFFFFF					

Message Type 0x21: Log Data 02

DB_12	DB_11	DB_10	DB_9	DB_8	DB_7	DB_6	DB_5	DB_4	DB_3	DB_2	DB_1	DB_0
MT	нмс			НМ	10		нмт					

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	Message Type	MT	Descriptor of this message	Enum:		
					Message Ty 0x21: 02	ta	
8	_	Handle Movements Closed	_	Number of Handle Movements Closed	Enum: 0x000000000xF	FFFFFFFF:	_
40		Handle Movements Opened		Number of Handle Movements Opened	Enum: 0x0000000000xF	FFFFFFF:	
72		Handle Movements Tilted	НМТ	Number of Handle Movements Tilted	Enum: 0x0000000000xF	FFFFFFF:	

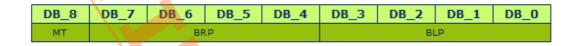
Message Type 0x22: Log Data 03



Offset Size	Data	ShortCut	Description	Valid Range	Scale	Unit
-------------	------	----------	-------------	-------------	-------	------

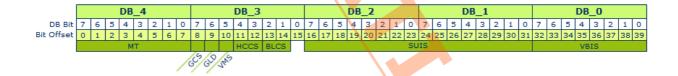
0	8	Message Type	MT	Descriptor of this message	Enum:
					0x22: Message Type Log Data 03
8	32	Window Tilts	WT	Number of Window Tilts	Enum:
					0x000000000xFFFFFFFF:

Message Type 0x23: Log Data 04



Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	Message Type	MT	Descriptor of this message	Enum:	Enum:	
					0x23: Message Type Log Data 04		a 04
8	32	Button Right Presses	BRP	Number of Button Right Presses	Enum:		
					0x000000000xFF	FFFFFF:	
40	32	Button Left Presses	BLP	Number of Button Left Presses	Enum:		
					0x000000000xFF	FFFFFFF:	

Message Type 0x80: Control and Settings



Notes:

The following settings are stored non volatile inside the handle and only need to be send on a change request:

- Handle Closed Click Feature
- Battery Low Click Feature
- Sensor Update Interval
- Vacation Blink Interval

It is possible to trigger several of the actions in one message; e.g. if DB3.7 and DB3.6 both are set, the handle will transmit the messages with the message types: 0x10, 0x20, 0x21, 0x22 and 0x23

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	Message Type	MT	Descriptor of this message	Enum:		
					Message Type Cor 0x80: Settings	ntrol and	
8		Get Configuration Settings	GCS	Start Transmission of the Configuration Settings (Message Type 0x10, see above)	Enum: 0x0: No Change 0x1: Start Transmission		
9	1	Get Log Data	GLD	Start Transmission of the Log Data Packets (Message Type 0x2x, see above)	g Enum: 0x0: No Change 0x1: Start Transmission		

	10	1	Vacation Mode	VMS	Set Vacation Mode	Enum: 0x0: Switch Vacation Mode Off 0x1: Switch Vacation Mode On		
	11	2	Handle Closed Click	HCCS	Set Handle Closed Click Feature	Enum: No Change 0x0:		
						Disable Handle Closed Click 0x1: Feature		
		/				Enable Handle Closed Click 0x2: Feature		
						Reserved 0x3:		
	13	2	Battery Low Click	BLCS	Set Battery Low Click	Enum:		
					Feature	0x0: No Change		
						0x1: Disable Battery Low Click Feature		
						0x2: Enable Battery Low Click Feature		
L						0x3: Reserved		
_	15	1	Not Used (= 0)					
	16	16	Sensor Update	SUIS	Set Sensor Update Interval	Enum:		
			Interval			0x0000: No Change		
						Reserved 0x00010x0004:		
						0x00050xFFFF: 565535 s		
ŀ	32	8	Vacation Blink	VBIS	Set Vacation Blink Interval	Enum:		
			Interval			0x00: No Change		
						0x010x02: Reserved		
						0x030xFF: s		
L						3255		

D2-10: Room Control Panels with Temperature & Fan Speed Control, Room Status Information and Time Program

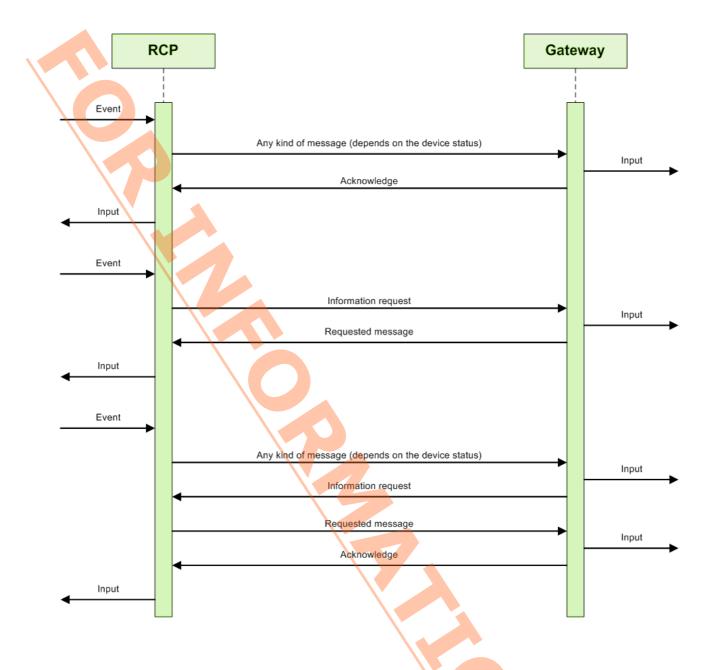
Submitter: Kieback&Peter GmbH & CO KG

Description

This VLD family consists of several profiles for a group of different room control panels with various functions and measurements (see following table of parameters for a feature list).

The profiles are designed to establish a communication between a battery-powered room control panel and a line-powered (and therefor always receiving) gateway. It also allows a gateway-to-gateway communication.

Due to the high energy consumption while powering the receiver, the room control panel will always be the initiator of a data exchange. It cannot be triggered by the gateway as it is not in a receiving mode most of the time.



Data exchange

Direction: bidirectional

Addressing: unicast (ADT) & broadcast

Communication trigger: event- & time-triggered Communication interval: can be defined during runtime

Trigger event: device status change

Tx delay: 1 s Rx timeout: N/A

Teach-in

Teach-in method: UTE

Security

Encryption required: no Security level format: -

EEP Family Table:

Telegram	Type 00	Type 01	Type 02
General Message	Χ	Χ	Χ
Data Message	Χ	Χ	Χ
Configuration Message	Х	Х	Х
Room Control Setup	Χ	Χ	Χ
Time Program Setup	Х	Х	-

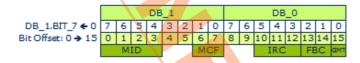
Parameter	Type 00	Type 01	Type 02
Parameter Message Identifier	X	X	X
Message Identifier Message Continuation Flag	X	X	X
	X	X	X
Information Request Classifier Feedback Classifier	X	X	X
	X	X	X
General Message Type	X	^	^
Humidity		-	-
Humidity Validity Flag	X X	-	-
Fan Speed Control		-	-
Fan Speed Validity Flag	X X	-	-
Fan Speed Mode		-	-
Custom Warning 2	X	X	X
Custom Warning 1	X	X	Х
Mold Warning	X	-	-
Window Open Detection	X	X	X
Battery Status	X	Х	X
Solar-power Status	X	- 	X
PIR Status	X	-	X
Occupancy Button Status	X	Х	Х
Cooling Operation Status	X	-	-
Heating Operation Status	X	-	-
Room Control Mode	X	Х	Х
Temperature Set Point Validity	X	Х	Х
Temperature Validity	Х	Х	Х
Temperature Set Point	X	Х	Х
Room Temperature	Х	Х	Х
PIR Status Lock	X	-	Х
Temperature Scale Lock	Х	Х	-
Display Content Lock	X	X	Χ
Date / Time Lock	X	Χ	Χ
Time Program Lock	X	Χ	X
Occupancy Button Lock	X	X	Х
Temperature Set Point Lock	X	X	-
Fan Speed Lock	X	-	-
Radio Communication Interval	Х	X	X
Key Lock	X	X	-
Display Content	Х	X	X
Temperature Scale	Χ	X	X
Daylight Saving Time Flag	X	X	Χ
Time Notation	Χ	Х	X
Day	Χ	Χ	X
Month	Χ	Χ	X
Year	Χ	Χ	X
Minute	Χ	Χ	Х
Hour	Х	Х	Х
Date / Time Update Flag	Х	Х	Х
Temperature Set Point Building Protection Mode	Х	Х	-
Temperature Set Point Pre-comfort Mode	Х	-	-
Temperature Set Point Economy Mode	Х	Х	Х
Temperature Set Point Comfort Mode	Х	Х	Х
Temperature Set Point Flag Building Protection Mode	Х	Х	-
Temperature Set Point Flag Pre-comfort Mode	Х	-	-
Temperature Set Point Flag Economy Mode	X	Х	Х
Temperature Set Point Flag Comfort Mode	X	X	X
End Time: Minute	X	X	-
End Time: Hour	X	X	-
Start Time: Minute	X	X	-
Start Time: Hour	X	X	_
Period	X	X	_
Time Program Deletion	X	X	_
s / rogium scietion	l <u>. ,</u>	l. ,	1

RORG	D2	VLD Telegram
FUNC	10	Room Control Panels with Temperature & Fan Speed Control, Room Status Information and Time Program
TYPE	00	Type 0x00

Submitter: Kieback&Peter GmbH & CO KG

General Message

exemplary illustration of data bytes 0/1:



Offset	Sizo	Data	ShortCut	Description	Valid	Range	Scale	Unit
		Message identifier	MID	Defines the type of message	Enum:		Jeale	Jint
O	5	riessage identifier	חווט	Defines the type of message	0:	General	Massaga	
	_				0.	General	Message	
		Not Used (= 0)						
6		Message	MCF	Indicates if another telegram has to be	Enum:			
		continuation flag		expected or if the message is complete	3:	Reserve	d	
					2:	Automat control	ic messa	ge
					1:	Incomple	ete	
					0:	Complet	е	
8	2	Not Used (= 0)						
		Information request	IRC	Defines the type of information request	Enum:			
		classifier			7:	Reserve	d	
					6:	Reserve	t	
					5:	Reserve	t	
					4:	Time pro	gram	
					3:	Room co	ntrol set	up
					2:	Configur request	ation	
					1:	Data rec		
					0:	Acknowl request	edge	
13	2	Feedback classifier	FBC	Defines the type of feedback	Enum:			
					3:	Reserved	1	
					2:	Message request	repetitio	on
					1:	Telegran request	repetiti	on
					0:	Acknowl heartbea	edge / it	

15	1	General message	3	Enum:	
		type	feedback or an information request	1:	Information request
				0:	Feedback

Data Message

Section Sect	Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit			
3	0	3	Message identifier	MID					
Reserved September Reserved Respected or if the message is complete Respected						1: Data Message			
a continuation flag expected or if the message is complete 3: Reserved 2: Automatic message control 1: Incomplete 0: Complete 0: No change	3	3	Not Used (= 0)						
2: Automatic message control 1: Incomplete 0: Complete 8	6			MCF		Enum:			
Control			continuation flag		expected or if the message is complete	3: Reserved			
8 8 Humidity HUM Measured humidity 0255 0100 % 16 1 Humidity validity flag HVF Indicates if the value for humidity is valid Enum: 1: Valid value 0: No change 17 7 Fan speed control FS Fan speed 0100 0100 % 24 1 Fan speed validity flag FSV Indicates if the fan speed value is valid Enum: 1: Valid value 0: No change 25 1 Fan speed mode FSM Defines the mode the fan runs in Enum: 1: Individual fan speed control 0: Central fan speed control 0: Central fan speed control 0: Central fan speed control 0: False 28 1 Custom warning 1 CW1 Flag for an application specific warning Enum: 1: True 0: False Enum: 1: True 1: True 1: Tru	ı					_			
8 8 Humidity HUM Measured humidity 0255 0100 % 16 1 Humidity validity flag 17 7 Fan speed control FS Fan speed 18 Fan speed validity flag 19 FSV Indicates if the value for humidity is valid flag 10 Fan speed validity flag 11 Fan speed validity flag 12 FSV Indicates if the fan speed value is valid flag 13 Fan speed validity flag 14 Fan speed mode FSM Defines the mode the fan runs in 15 Valid value flag 16 O: No change 17 Fan speed mode FSM Defines the mode the fan runs in 18 Individual fan speed control flag for an application specific warning flag for an application specific warning flag flag flag for an application specific warning flag flag flag for an application specific warning flag flag flag flag flag flag flag fla						1: Incomplete			
1						0: Complete			
flag			-	HUM	Measured humidity	0255 0100 %			
17 7 Fan speed control FS Fan speed	16			HVF	Indicates if the value for humidity is valid	Enum:			
7 Fan speed control FS Fan speed 0100 0100 %			flag						
24 1 Fan speed validity FSV Indicates if the fan speed value is valid Enum: 1: Valid value 0: No change									
flag		_	·			0100 0100 %			
25 1 Fan speed mode FSM Defines the mode the fan runs in Enum: 1: Individual fan speed control 0: Central fan speed control 0: False 0: Fa	24			FSV	Indicates if the fan speed value is valid	Enum:			
Fan speed mode FSM Defines the mode the fan runs in			flag						
26 1 Not Used (= 0) 27 1 Custom warning 2 CW2 Flag for an application specific warning						0: No change			
Control	25	1	Fan speed mode	FSM	Defines the mode the fan runs in	Enum:			
26 1 Not Used (= 0) 27 1 Custom warning 2 CW2 Flag for an application specific warning Enum: 1: True 0: Central fan speed control Enum: 1: True 0: False 28 1 Custom warning 1 CW1 Flag for an application specific warning Enum: 1: True 0: False									
26 1 Not Used (= 0) 27 1 Custom warning 2 CW2 Flag for an application specific warning									
27 1 Custom warning 2 CW2 Flag for an application specific warning Enum: 1: True 0: False 28 1 Custom warning 1 CW1 Flag for an application specific warning Enum: 1: True 1: True 1: True 0: False									
28 1 Custom warning 1 CW1 Flag for an application specific warning Enum: 1: True 0: False Enum: 1: True 0: False				1					
28 1 Custom warning 1 CW1 Flag for an application specific warning Enum: 1: True 0: False 0: False	27	1	Custom warning 2	CW2	Flag for an application specific warning				
28 1 Custom warning 1 CW1 Flag for an application specific warning Enum: 1: True 0: False									
1: True 0: False						0: False			
0: False	28	1	Custom warning 1	CW1	Flag for an application specific warning				
20 It Maid						0: False			
	29	1	Mold warning	MW	Flag for an application depending mold	Enum:			
warning 1: True					warning				
0: False						0: False			
30 2 Window open WOD Indicates if an open window is detected Enum:	30			WOD	Indicates if an open window is detected				
detection 3: Reserved			detection						
2; Open									
1: Closed									
0: No change						0: No change			
32 1 Not Used (= 0)			` /	ln c	In				
33 2 Battery status BS Battery status Enum:	33	2	Battery status	BS	Battery status				
3: Critical									
2: Low									
1: Good									
0: No change				000					
35 1 Solar-powered SPS Indicates if the device is powered by its Enum:	35	1		SPS					
1. Not solar powered			Status		solar cell	1: Not solar-powered			
0: Solar-powered									

36	2	PIR status	PIR	Indicates if the PIR detected a movement	Enum:				
					3:	Locked			
					2:	Movem	ent detect	ted	
					1:	detected			
	//				0:	No cha	nge		
38	2	Occupancy button	OBS	Indicates if the occupancy button was	Enum:				
	,	status		pressed and its occupancy status	3:	Reserv	ed		
					2:	Button unoccu	pressed a pied	nd	
					1:	Button occupie	pressed a ed	nd	
					0:	No cha	nge		
40	2	Cooling	C00	Recent cooling operation status	Enum:				
					3:	Automa	atic		
					2:	Off			
					1:	On			
					0:	No cha	nge		
42	2	Heating	HEA	Recent heating operation status	Enum:	•			
					3:	Automa	atic		
					2:	Off			
					1:	On			
					0:	No cha	nge		
44	2	Room control mode	RCM	Recent room control mode	Enum:				
					3:		g protection	on .	
					2: Pre-comfort				
					1: Economy				
					0:	Comfo			
46	1	Temperature set	SPV	Indicates if the temperature set point	Enum:	:			
		point validity		value is valid	1: Valid value				
					0:	No cha			
47	1	Temperature validity	TPV	Indicates if the temperature value is valid	Enum:				
		,			1:	Valid v	alue		
					0:	No cha			
48	8	Temperature set point	TSP	Recent temperature set point	025		0+40	°C	
56	8	Temperature	TMP	Recent room temperature	025!	5	0+40	°C	

Configuration Message

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	3	Message identifier	MID	Defines the type of message	Enum: 2: Co	nfiguration	
					Me		
3	3	Not Used (= 0)					
6		Message continuation flag	MCF	Indicates if another telegram has to be expected or if the message is complete		served	ge
						ntrol	
					1: Inc	complete	
					0: Co	mplete	

8	1	PIR status lock	PSL	Indicates if the PIR status is transmitted or kept inside the room control panel	Enum: 1: Unlocked 0: Locked
9	1	Temperature scale lock	TSL	Indicates if the temperature scale can be changed at the room control panel	Enum: 1: Unlocked 0: Locked
10	1	Display content lock		Indicates if the display content can be changed at the room control panel	Enum: 1: Unlocked 0: Locked
11	1	Date / time lock	DTL	Indicates if date and time can be changed at the room control panel	Enum: 1: Unlocked 0: Locked
12	1	Time program lock	TPL	Indicates if the time program can be changed at the room control panel	Enum: 1: Unlocked 0: Locked
13	1	Occupancy button lock	OBL	Indicates if the occupancy status can be changed at the room control panel	Enum: 1: Unlocked 0: Locked
14	1	Temperature set point lock	SPL	Indicates if the temperature set point can be changed at the room control panel	Enum: 1: Unlocked 0: Locked
15	1	Fan speed lock	FSL	Indicates if the fan speed can be changed at the room control panel	Enum: 1: Unlocked 0: Locked
16	6	Radio communication interval	RCI	Defines the longest time between two consecutive telegrams (clock-based communication)	Enum: 63: 24 hours
					62: 12 hours 61: 3 hours
					160 min 160: 0: No communication
					0: No communication interval
22	1	Key lock	KL	Indicates if all buttons on the device are	Enum:
				locked	1: Unlocked
22	1	Not Used (= 0)			0: Locked
23 24	3	Display content	DC	Defines the main display content	Enum:
24		Display Content	DC	Defines the main display content	7: Humidity
					6: Display off
					5: Temperature set point
					4: Room temperature (external)
				· ·	3: Room temperature (internal)
					2: Time
					1: Default
					0: No change
27	2	Temperature scale	TS	Defines the used temperature scale for the	
				room control panel display and menus	3: ° Fahrenheit
					2: ° Celsius 1: Default
					0: No change
•					

29	1	Daylight saving	DST	Indicates if daylight saving time is	Enum:				
		time flag		supported	1: Not	supported			
					0: Sup	ported			
30	2	Time notation	TN	Defines the used time notation	Enum:				
					3: 12	<u>h</u>			
					2: 24				
					1: Def				
					0: No				
32	5	Day	DAY	Date format: YYYY/MM/DD	131	131	day		
37	4	Month	MON	Date format: YYYY/MM/DD	112	112	mon		
41	7	Year	YR	Date format: YYYY/MM/DD year = 2000 + x	0127	20002127	year		
48	6	Minute	MIN	Time format: hh:mm	059	059	min		
54	2	Not Used (= 0)							
56	5	Hour	HR	Time format: hh:mm	023	023	h		
61	2	Not Used (= 0)							
63	1	Date / time update	DTU	Indicates if an update of date or time is	Enum:				
		flag		provided	1: Update				
					0: No	update			

Room Control Setup

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit		
0	3	Message identifier	MID	Defines the type of message	Enum: 3: Roon Setu	n Control			
3		Not Used (= 0)	1		1				
6	2	Message continuation flag	MCF	Indicates if another telegram has to be expected or if the message is complete	Enum: 3: Rese	rved			
					2: Automatic message control				
					1: Incor	nplete			
					0: Com	plete			
8		Temperature set point building protection mode	SPB	Temperature set point building protection mode	0255	0+40	°C		
16		Temperature set point pre-comfort mode	SPP	Temperature set point pre-comfort mode	0255	0+40	°C		
24		Temperature set point economy mode	SPE	Temperature set point economy mode	0255	0+40	°C		
32	8	Temperature set point comfort mode	SPC	Temperature set point comfort mode	0255	0+40	°C		
40	4	Not Used (= 0)							
44		Temperature set point flag building protection mode	SFB	Indicates if a temperature set point for the building protection mode is provided	1: Valid	value nange	-		
45		Temperature set point flag pre-comfort mode	SFP	Indicates if a temperature set point for the pre-comfort mode is provided	1: Valid	value nange	-		
46		Temperature set point flag economy mode	SFE	Indicates if a temperature set point for the economy mode is provided	1: Valid	value nange			
47	1	Temperature set point flag comfort mode	SFC	Indicates if a temperature set point for the comfort mode is provided	1: Valid	value nange			

Time Program Setup

Offset	Sizo	Data	ShortCut	Description	Valid Range Scale Unit
0		Message identifier	MID	Defines the type of message	Enum:
3		message identifier	, 11 <i>D</i>	Defines the type of filessage	4: Time Program
					Setup
3	3	Not Used (= 0)			Cottap
		Message	MCF	Indicates if another telegram has to be	Enum:
		continuation flag	1101	expected or if the message is complete	3: Reserved
					J. Reserved
					2: Automatic message
		\\			control
					1: Incomplete
					0: Complete
_	_				
8		Not Used (= 0)			l l l.
10		End time: Minute	ETM	Time format: hh:mm	059 059 1
16		Not Used (= 0)			
		End time: Hour	ETH	Time format: hh:mm	023 023 1
		Not Used (= 0)	CTM	The Court like	0 50
		Start time: Minute	SIM	Time format: hh:mm	059 059 1
		Not Used (= 0)	СТИ		
		Start time: Hour	STH	Time format: hh:mm	023 023 1
40	4	Period	PER	Assigned period of time (weekdays) for the provided schedule time	Enum:
				provided scriedule tille	15: Friday - Monday
					14: Friday - Sunday
					14. Friday - Suilday
					13: Thursday - Friday
					131 marsaa, maa,
					12: Wednesday -
					Friday
					11: Tuesday -
					Thursday
					10: Monday -
					Wednesday
					9: Sunday
					8: Saturday
					or sataraay
					7: Friday
					6: Thursday
					5: Wednesday
					1. Tuesday
					4: Tuesday
					3: Monday
					2: Saturday - Sunday
					1: Monday - Friday
					0: Monday - Sunday
11	2	Poom control	DCM	Assigned room control mode for the presided	Гиши
44		Room control mode	RCM	Assigned room control mode for the provided schedule time	
		mode		School Carrie	3: Building protection
					2: Pre-comfort
					1: Economy
4.6	4	Nice III - III - C			0: Comfort
46	1	Not Used (= 0)		-	

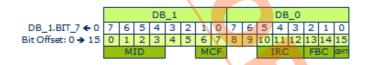
47	,	1	Time program	TPD	Deletes the stored time program	Enum	:
			deletion			1:	Deletion
						0:	No deletion

RORG	D2	VLD Telegram
FUNC	10	Room Control Panels with Temperature & Fan Speed Control, Room Status Information and Time Program
TYPE	01	Type 0x01

Submitter: Kieback&Peter GmbH & CO KG

General Message

exemplary illustration of data bytes 0/1:



Offset	Size	Data	ShortCut	Description	Valid	Range	Scale	Unit		
0	3	Message identifier	MID	Defines the type of message	Enum:					
					0:	General	Message	<u>۽</u>		
3		Not Used (= 0)								
6			MCF	Indicates if another telegram has to be	Enum:	:				
		continuation flag		expected or if the message is complete	3:	Reserved	t t			
					2:	Automatic message control				
					1:	Incomple	ete			
					0:	Complet	е			
8		Not Used (= 0)								
10		Information request	IRC	Defines the type of information request	Enum:					
		classifier			7:	: Reserved				
					6:	Reserved	d			
					5: Reserv					
					4:	Time pro				
					3:	Room co request	ntrol set	:up		
					2:	Configur request	ation			
					1:	Data req	uest			
						Acknowlerequest	edge			
13	2	Feedback classifier	FBC	Defines the type of feedback	Enum:					
					3:	Reserved	t			

					2:	Message repetition request
					1:	Telegram repetition request
					0:	Acknowledge / heartbeat
1	5	1	General message		Enum	:
	`		type	feedback or an information request	1:	Information request
					0:	Feedback

Data Message

Offset	Size	Data	ShortCut	Description	Valid	Range	Scale	Unit	
0	3	Message identifier	MID	Defines the type of message	Enum	:			
					1:	Data Me	essage	_	
3	3	Not Used (= 0)							
6		Message	MCF	Indicates if another telegram has to be	Enum	:			
		continuation flag		expected or if the message is complete	3:	Reserve	ed		
					2:		tic messa	ige	
			\			control	1.1.		
					1:	Incomp	iete		
					0.	0: Complete			
					0.				
8	8	Not Used (= 0)							
16	1	Not Used (= 0)							
17	7	Not Used (= 0)							
24	1	Not Used (= 0)							
25		Not Used (= 0)							
26	1	Not Used (= 0)	1						
27	1	Custom warning 2	CW2	Flag for an application specific warning	Enum	:	_		
					1:	True	_		
					0:	False			
28	1	Custom warning 1	CW1	Flag for an application specific warning	Enum	:	_		
					1:	True	_		
					0:	False			
29		Not Used (= 0)	1						
30		Window open	WOD	Indicates if an open window is detected	Enum	:			
		detection			3:	Reserve	ed		
					2:	Open			
					1:	Closed			
					0:	No char	nge		
32		Not Used (= 0)	n.c	le					
33	2	Battery status	BS	Battery status	Enum				
					3:	Critical			
					2:	Low			
					1:				
25	4	Nat Haad (O)			0:	No char	ige		
35 36		Not Used (= 0) Not Used (= 0)							
38		,	OBS	Indicates if the occupancy button was	Fn			A	
36		Occupancy button status	OBS	pressed and its occupancy status	Enum 3:	: Reserve	od .		
				, , , , , , , , , , , , , , , , , , , ,	٥.	Reserve	eu		
					2:	Button	pressed a	ind	
						unoccuj			
					1:		pressed a	ind	
						occupie	d		
						occupie	u		

					0:	No cha	nge		
40	2	Not Used (= 0)			_				
42	2	Not Used (= 0)							
44	2	Room control mode	RCM	Recent room control mode	Enum	:			
					3:	on			
					2:	Pre-comfort			
				1:	Economy				
					0:	Comfo	rt		
46	1	Temperature set	SPV	Indicates if the temperature set point	Enum	:			
		point validity		value is valid	1:	1: Valid value			
					0:	No change			
47	1	Temperature validity	TPV	Indicates if the temperature value is valid	Enum	:			
					1:	Valid v	alue		
					0:	No cha	nge		
48	8	Temperature set point	TSP	Recent temperature set point	025	5	0+40	°C	
56	8	Temperature	TMP	Recent room temperature	025	5	0+40	°C	

Configuration Message

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit	
0	3	Message identifier	MID	Defines the type of message	Enum: 2: Configuration Message			
3	3	Not Used (= 0)						
6	2	` '	MCF	Indicates if another telegram has to be expected or if the message is complete	2: Auto	erved pmatic mess crol pmplete pplete	age	
8	1	Not Used (= 0)			•			
9		Temperature scale lock	TSL	Indicates if the temperature scale can be changed at the room control panel	Enum: 1: Unio	ocked ked		
10	1	Display content lock	DCL	Indicates if the display content can be changed at the room control panel	Enum: 1: Unio 0: Lock	ocked ked		
11	1	Date / time lock	DTL	Indicates if date and time can be changed at the room control panel	Enum: 1: Unio	ocked ked		
12	1	Time program lock	TPL	Indicates if the time program can be changed at the room control panel	Enum: 1: Unio 0: Lock	ocked ked		
13		Occupancy button lock	OBL	Indicates if the occupancy status can be changed at the room control panel	Enum: 1: Unio 0: Lock	ocked ked		
14		Temperature set point lock	SPL	Indicates if the temperature set point can be changed at the room control panel	Enum: 1: Unlo 0: Lock	ocked ked		
15	1	Not Used (= 0)						
16		Radio communication interval	RCI	Defines the longest time between two consecutive telegrams (clock-based communication)	Enum: 63: 24	hours		

					62:	12	hours		
					61:	3 h	ours		
					160:		60 min		
					0:		communication	on	
22	1	Key lock	KL	Indicates if all buttons on the device are	Enum:		zi vai		
				locked	1:	Unlo	cked		
	· ·				0:	Lock	ed		
23	1	Not Used (= 0)							
24	3	Display content	DC	Defines the main display content	Enum:				
					7:	Hum	idity		
							lay off		
						poin			
					4: Room temperature (external)				
						(inte	n temperatur ernal)	e	
					2:	Time	2		
					1:	Defa	ult		
					0:	No c	hange		
27	2	Temperature scale	TS	Defines the used temperature scale for the	Enum:				
				room control panel display and menus	3: ° Fahrenheit				
					2: ° Celsius				
					1: Default				
					0:	No c	hange		
29	1	Daylight saving	DST	Indicates if daylight saving time is supported	Enum:				
		time flag			1: Not supported				
					0:	Supp	ported		
30	2	Time notation	TN	Defines the used time notation	Enum:				
						12 h			
						24 h			
						Defa	_		
22	Е	Day	DAY	Data formati WWW/MM/DD	131		hange	day	
32 37	5 4	Day Month	DAY MON	Date format: YYYY/MM/DD Date format: YYYY/MM/DD	131		131 112	day mon	
41	7	Year	YR	Date format: YYYY/MM/DD	0127		20002127	year	
41	,	i cai	TK	year = 2000 + x	0127		2000212/	year	
48	6	Minute	MIN	Time format: hh:mm	059		059	min	
54	2	Not Used (= 0)							
56	5	Hour	HR	Time format: hh:mm	023		023	h	
61	2	Not Used (= 0)							
63	1		DTU	Indicates if an update of date or time is	Enum: 1:				
			provided		Upda				
					0:	No u	ipdate		

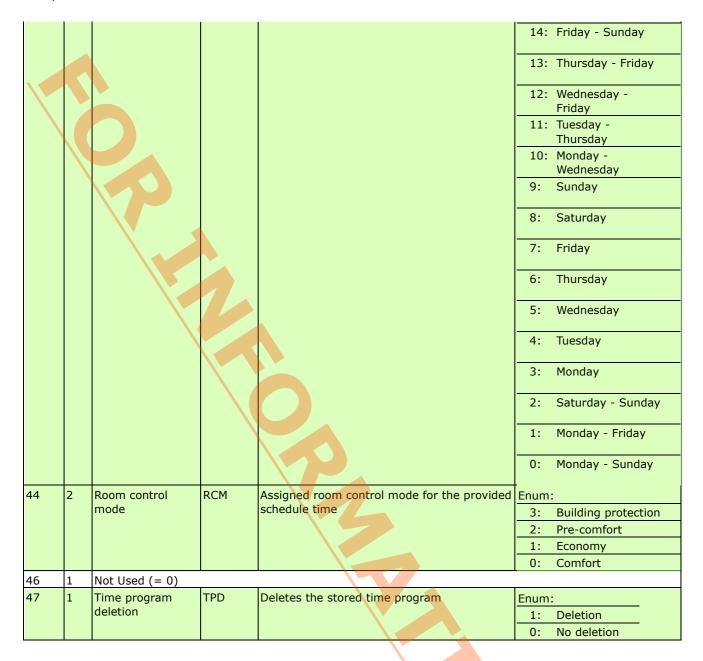
Room Control Setup

Offset Size Data ShortCut Description Valid Range Scale	Unit	ŀ
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0	3	Message identifier	MID	Defines the type of message	Enum:				
					3: Roor Setu	n Control			
3	3	Not Used (= 0)			octa	<u> </u>			
6	2	Message continuation flag	MCF	Indicates if another telegram has to be	Enum:				
				expected or if the message is complete	3: Rese	rved			
					2: Automatic message control				
					1: Incomplete				
					0: Com	plete	ete		
8	8	Temperature set point building protection mode	SPB	Temperature set point building protection mode	0255	0+40	°C		
16	8	Not Used (= 0)							
24	8	Temperature set point economy mode	SPE	Temperature set point economy mode	0255	0+40	°C		
32	8	Temperature set point comfort mode	SPC	Temperature set point comfort mode	0255	0+40	°C		
40	4	Not Used (= 0)							
44	1	Temperature set point flag	SFB	Indicates if a temperature set point for	Enum:		_		
		building protection mode		the building protection mode is provided	1: Valid	l value	_		
				provided	0: No c	hange			
45	1	Not Used (= 0)		7	1				
46	1	Temperature set point flag	SFE	Indicates if a temperature set point for	Enum:		_		
		economy mode		the economy mode is provided		l value	_		
					0: No c	hange			
47	1	Temperature set point flag	SFC	Indicates if a temperature set point for the comfort mode is provided	Enum:				
		comfort mode			1: Valid	l value			
					0: No c	hange			

Time Program Setup

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit		
0	3	Message identifier	MID	Defines the type of message	Enum:				
					4: Time Pro				
					Setup	Setup			
3	3	Not Used (= 0)			I				
6	2	J -	MCF	Indicates if another telegram has to be	Enum:				
		continuation flag		expected or if the message is complete	3: Reserve	d			
				2: Automatic message control					
				1: Incomplete					
					0: Complet	e			
8	2	Not Used (= 0)							
10	6	End time: Minute	ETM	Time format: hh:mm	059	059	1		
16	3	Not Used (= 0)							
19	5	End time: Hour	ETH	Time format: hh:mm	023	023	1		
24	2	Not Used (= 0)							
26	6	Start time: Minute	STM	Time format: hh:mm	059	059	1		
32	3	Not Used (= 0)	•						
35	5	Start time: Hour	STH	Time format: hh:mm	023	023	1		
40	4	Period	PER	Assigned period of time (weekdays) for the	Enum:				
				provided schedule time	15: Friday -	Monday			

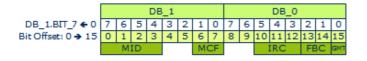


RORG	D2	VLD Telegram
FUNC	10	Room Control Panels with Temperature & Fan Speed Control, Room Status Information and Time Program
TYPE	02	Type 0x02

Submitter: Kieback&Peter GmbH & CO KG

General Message

exemplary illustration of data bytes 0/1:



Offset	Size	Data	ShortCut	Description	Valid	Range Scale Unit
0	3	Message identifier	MID	Defines the type of message	Enum:	:
					0:	General Message
3	3	Not Used (= 0)	•			
6		Message	MCF	Indicates if another telegram has to be	Enum:	
		conti <mark>nu</mark> ation flag		expected or if the message is complete	3:	Reserved
					2:	Automatic message control
					1:	Incomplete
					0:	Complete
8		Not Used (= 0)		<u></u>		
10		Information request	IRC	Defines the type of information request	Enum:	
		classifier			7:	Reserved
					6:	Reserved
					5:	Reserved
					4:	Time program request
					3:	Room control setup request
					2:	Configuration request
					1:	Data request
					0:	Acknowledge request
13	2	Feedback classifier	FBC	Defines the type of feedback	Enum:	
					3:	Reserved
					2:	Message repetition request
					1:	Telegram repetition request
					0:	Acknowledge / heartbeat
15	1	General message	GMT	Indicates if the general message is a	Enum:	
		type		feedback or an information request	1:	Information request
					0:	Feedback

Data Message

Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit
0	3	Message identifier	MID	Defines the type of message	Enum: 1: Data Message
3	3	Not Used (= 0)			
6		Message continuation flag	MCF	Indicates if another telegram has to be expected or if the message is complete	Enum: 3: Reserved 2: Automatic message control 1: Incomplete 0: Complete

8	8	Not Used (= 0)			
16	1	Not Used (= 0)			
17	7	Not Used (= 0)			
24	1	Not Used (= 0)			
25	1	Not Used (= 0)			
26	1	Not Used (= 0)			
27	1	Custom warning 2	CW2	Flag for an application specific warning	Enum:
2,	1	Custom warning 2	CWZ	Trug for an application specific warriing	1: True
					0: False
28	1	Custom warning 1	CW1	Flag for an application specific warning	Enum:
20	1	Custom warning 1	CVVI	Triag for an application specific warning	
					1: True
20	_	1 (0)			0: False
29	1	Not Used (= 0)	WOD.		-
30	2	Window open detection	WOD	Indicates if an open window is detected	Enum:
		detection			3: Reserved
					2: Open
					1: Closed
					0: No change
32	1	Not Used (= 0)			1
33	2	Battery status	BS	Battery status	Enum:
					3: Critical
					2: Low
					1: Good
					0: No change
35	1	Solar-powered	SPS	Indicates if the device is powered by its	Enum:
		status	· ·	solar cell	1: Not solar-powered
					0: Solar-powered
36	2	PIR status	PIR	Indicates if the PIR detected a movement	Enum:
	_	. 1.1 00000			3: Locked
					3. Edeked
					2: Movement detected
					1: No movement
					detected
					0: No change
38	2	Occupancy button	OBS	Indicates if the occupancy button was	Enum:
	_	status		pressed and its occupancy status	3: Reserved
					Si Reserved
					2: Button pressed and
					unoccupied
					1: Button pressed and
					occupied
					0: No change
40	2	Not Used (= 0)			
42	2	Not Used (= 0)			
44	2	Room control mode	RCM	Recent room control mode	Enum:
					3: Building protection
					2: Pre-comfort
					1: Economy
					0: Comfort
46	1	Temperature set	SPV	Indicates if the temperature set point	Enum:
		point validity		value is valid	1: Valid value
					0: No change
47	1	Temperature validity	TPV	Indicates if the temperature value is valid	Enum:
		, , , , , , , , , , , , , , , , , , , ,			1: Valid value
					0: No change
48	8	Temperature set	TSP	Recent temperature set point	0255 0+40 °C
.0		point	. 5.	Todane temperature set point	0140
56	8	Temperature	TMP	Recent room temperature	0255 0+40 °C
	-				

Configuration Message

Offset	Size	Data	ShortCut	Description	Valid Range Scale		Scale	Unit	
0	3	Message identifier	MID	Defines the type of message		•			
			טוויו	Defines the type of message	Enum: 2:	Configu Message			
	_	Not Used (= 0)	1						
6		Message	MCF	Indicates if another telegram has to be	Enum:				
		contin <mark>uation</mark> flag		expected or if the message is complete	3: Reserved				
					2:	control	tic mess	age	
					1: Incomplete				
					0:	Comple	te		
8	1	PIR status lock	PSL	Indicates if the PIR status is transmitted or kept inside the room control panel					
				Rept hisiae the room control panel	1:	Unlocke	<u>a</u>		
	4	No. House			0:	Locked			
9		Not Used (= 0) Display content lock	DCI	Indicates if the display content can be	Enum:				
10	1	Display Content lock	DCL	changed at the room control panel	Enum: 1:	Unlocke	d.		
				changed at the room control panel		Locked	<u>u</u>		
11	1	Date / time lock	DTL	Indicates if date and time can be changed	0: Enum:				
11	1	buce / time lock		at the room control panel	1:	Unlocke			
					0:	Locked	<u>u</u>		
12	1	Time program lock	TPL	Indicates if the time program can be	Enum:				
	_	rine program lock		changed at the room control panel	1:	Unlocke	d		
					0:	Locked	<u></u>		
13	1	Occupancy button	OBL	Indicates if the occupancy status can be	Enum:				
		lock		changed at the room control panel	1:	Unlocke	d		
					0:	Locked			
14	1	Not Used (= 0)							
15	1	Not Used (= 0)							
16		Radio	RCI	Defines the longest time between two	Enum:				
		communication interval		consecutive telegrams (clock-based communication)	63:	24 hou	ırs		
					62:	12 hou			
					61:	3 hour			
					160:				
					0:	No con interva	nmunicat ıl	lion	
22		Not Used (= 0)							
		Not Used (= 0)	D.C.	D.C					
24	3	Display content	DC	Defines the main display content	Enum: 7:	Humidit	У		
					6:	Display	off		
					5:		ature set		
					4:	Room to	emperatu	ire	
					3:	-	emperatu	ire	
					2:	Time			

					1:	Defa	ault	
					0:	No d	change	
27	2	Temperature scale	TS	Defines the used temperature scale for the	Enum:			
				room control panel display and menus	3: ° Fahre		hrenheit	
					2:	° Ce	° Celsius	
,					1:	Default		
					0:	No o	change	
29	1	Daylight saving	DST	Indicates if daylight saving time is	Enum:			_
		time flag		supported	1:	Not supported		
					0:	Supported		
30	2	Time notation	TN	Defines the used time notation	Enum:			
					3: 12 h			
					2: 24 h			
				1: Default				
						0: No change		
	5	Day	DAY	Date format: YYYY/MM/DD	131		131	day
37	4	Month	MON	Date format: YYYY/MM/DD	112		112	mon
41	7	Year	YR	Date format: YYYY/MM/DD	0127	7	20002127	year
	_			year = 2000 + x			0 50	
48	6	Minute	MIN	Time format: hh:mm	059		059	min
54	2	Not Used (= 0)						
56		Hour	HR	Time format: hh:mm	023		023	h
61	2	Not Used (= 0)			_			
63	1	/	DTU		Enum:			
	flag		provided	1:	Upd			
					0: No update			

Room Control Setup

Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit				
0	3	Message identifier	MID	Defines the type of message	Enum: 3: Room Control Setup				
3	3	Not Used (= 0)							
6		Message continuation flag	MCF	Indicates if another telegram has to be expected or if the message is complete	Enum: 3: Reserved 2: Automatic message control 1: Incomplete 0: Complete				
8	8	Not Used (= 0)							
16	8	Not Used (= 0)							
24	8	Temperature set point economy mode	SPE	Temperature set point economy mode	0255 0+40 °C				
32	8	Temperature set point comfort mode	SPC	Temperature set point comfort mode	0255 0+40 °C				
40	4	Not Used (= 0)							
44	1	Not Used (= 0)							
45	1	Not Used (= 0)							
46	1	Temperature set point flag economy mode	SFE	Indicates if a temperature set point for the economy mode is provided	Enum: 1: Valid value 0: No change				

4	47	1	Temperature set point	SFC	Indicates if a temperature set point for	Enum:
			flag comfort mode		the comfort mode is provided	1: Valid value
						0: No change

D2-20: Fan Control

The EEP family D2-20-xx provides different telegram types for fan control and fan supervision messages using various parameters and variables.

Devices using this EEP family may include a master-slave function (for further description see subheading 'Master-slave function').

EEP Properties:

DATA EXCHANGE
Direction: bidirectional

Addressing: unicast (ADT) + broadcast Communication trigger: event-triggered

Communication interval: N/A Trigger event: query / polling

Tx delay: N/A Rx timeout : N/A

TEACH-IN

Teach-in method: Universal teach-in (UTE)

SECURITY

Encryption supported: no Security level: none

EEP Family Table:

Supported function	Type 00	Type 01	Type 02
Fan Speed	Χ	Χ	X
Fan Speed Status	Χ	Χ	Χ
Humidity	Χ	ı	i
Humidity Control	Χ	ı	i
Humidity Control Status	Χ	ı	Χ
Humidity Threshold	Χ	ı	i
Message Type	Χ	Χ	Χ
Operating Mode	Χ	ı	i
Operating Mode Status	Χ	Χ	
Room Size	Χ	Χ	Χ
Room Size Reference	Χ	Χ	Χ
Room Size Reference Status	Χ	Χ	Χ
Room Size Status	Χ	Χ	Χ
Service Information	Х	-	_
Temperature Level	Х	_	_

Each TYPE has to support every parameter that is marked in its column!

Master-slave function:

A device using this EEP may be able to work as a master or a slave fan. Master fans control slave fans. Slave fans are controlled by master fans. These roles are defined during the teach-in process. A slave fan will always be taught-in to a master. A master fan will accept teach-in requests from slave fans. A fan that is taught-in to another device will from now on work as a slave. A fan that accepted the teach-in of another device will go on working as a master. Combining master fans is not possible. Not every device is able to work as a master and a slave. Certain fans might only be able to be used as slaves.

RORG	D2	VLD Telegram
FUNC	20	Fan Control
TYPE	00	Type 0x00

Submitter: Maico Elektroapparate-Fabrik GmbH

Telegram Definition: 'Fan Control Message'

* Devices with discrete fan speed levels instead of a continuous fan speed range should divide the full range linearly and match values beside those discrete levels to the next lower fan speed level.

Offset			ShortCut	vels to the next lower fan speed level. Description	Valid Range Scale Unit
0	_	Operating Mode	OM	Sets the operating mode	Enum:
U	4	Operating Houe	OM	Sets the operating mode	0: Disabled 1: Standard compliant Reserved
			1/>		214: 15: No change
4	1	Not Used (= 0)			
5	2	Temperature Level	TL	Status of the temperature supervision	Enum: 0: Too low 1: Normal 2: Too high 3: No change
7	1	Message Type	MT	Defines the message type	Enum: 0: Fan control
8	2	Humidity Control	НС	Activates the humidity control	Enum: 0: Disabled 1: Enabled 2: Default 3: No change
10		Room Size Reference	RSR	Defines if the provided room size has to be considered	Enum: 0: Used 1: Not used 2: Default 3: No change
12		Room Size	RS	Defines the room size	Enum: 0: < 25 m² 1: 2550 m² 2: 5075 m² 3: 75100 m² 4: 100125 m² 5: 125150 m² 6: 150175 m² 7: 175200 m² 8: 200225 m² 9: 225250 m² 10: 250275 m² 11: 275300 m² 12: 300325 m² 13: 325350 m² 14: > 350 m² 15: No change
16		Humidity Threshold	HT	Sets the humidity threshold	Enum: 0100: 0100% 101252: Reserved 253: Auto 254: Default 255: No change

24	8	Fan Speed *	FS	Sets the fan speed	Enum:	_
					0100:	0100%
					101252	: Reserved
					253:	Auto
					254:	Default
					255:	No change

Telegram Definition: 'Fan Status Message'

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit	
0		Operating Mode	OMS	Provides the recent operating mode	Enum:			
		Status			0: Disabled			
			1					
					compliant			
					Reserved 214:			
						ported		
					15. 100 50	эрогсса		
4	3	Service Information	SI	Service information	Enum:			
					0: Nothing to report			
					1: Air filter error			
			\		2: Hardware error			
					36: Reserve	d		
					7: Not sup	ported		
7	1	Message Type	MT	Defines the message type	Enum:			
					1: Fan statu	ıs		
8	2	Humidity Control	HCS	States if the humidity control is active	Enum:			
		Status			0: Disabled		-	
					1: Enabled		_	
					2: Reserved		-	
					3: Not supp	orted	-	
10	2	Room Size	RSR	States if the provided room size has to be	Enum:			
		Reference		considered	0: Used	Jsed		
					1: Not used	<u></u>		
					2: Reserved			
					3: Not supp	orted		
12	4	Room Size Status	RSS	Room size status	Enum:			
					0: < 25 m ²		_	
					1; 2550 r	n²		
					2: 5075 r	n²		
					3: 75100			
					4: 10012		_	
				V	5: 12515		_	
					6: 15017		_	
					7: 17520	25 m²		
					8: 20022			
					9: 22525		_	
					10: 25027	_	_	
					11: 27530		-	
					12: 30032		-	
					13: 32535			
					14: > 350 m 15: Not supp		-	
16	8	Humidity	ым	Humidity manageroment		orted		
10	0	Humidity	HUM	Humidity measurement	Enum: 0100: 0	1000/		
					0100: 0	.100%		
					Re	served		
					101254:	2		

					255:	Not supported
24	8	Fan Speed Status	FSS	Fan speed	Enum:	
					0100:	0100%
					101 254	Reserved
					101254:	
· ·					255:	Not
						supported

RORG	D2	VLD Telegram
FUNC	20	Fan Control
TYPE	01	Type 0x01

Submitter: Maico Elektroapparate-Fabrik GmbH

Telegram Definition: 'Fan Control Message'

* Devices with discrete fan speed levels instead of a continuous fan speed range should divide the full range linearly and match values beside those discrete levels to the next lower fan speed level.

Offset			ShortCut	Description	Valid Range Scale Unit
0	7	Not Used (= 0)	Shortcut	Description	Valid Karige Scale Offic
7	1	Message Type	MT	Defines the message type	Enum:
/	1	Message Type	IMI	Defines the message type	
0	2	Nat Haad (O)			0: Fan control
8 10	2	Not Used (= 0)	DCD	D.C	_
10	2	Room Size Reference	RSR	Defines if the provided room size has to be considered	Enum:
		Reference		considered	0: Used
					1: Not used
					2: Default
					3: No change
12	4	Room Size	RS	Defines the room size	Enum:
					0: < 25 m ²
					1: 2550 m ²
					2: 5075 m ²
					3: 75100 m ²
					4: 100125 m ²
					5: 125150 m ²
					6: 150175 m ²
					7: 175200 m ²
					8: 200225 m ²
					9: 225250 m ²
					10: 250275 m ²
					11: 275300 m ²
					12: 300325 m ²
					13: 325350 m ²
					14: > 350 m ²
					15: No change
16	8	Not Used (= 0)			
24	8	Fan Speed *	FS	Sets the fan speed	Enum:
					0100: 0100%
					Reserved
					101252:
					253: Auto

	254:	Default
	255:	No change

Telegram Definition: 'Fan Status Message'

Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit
0	4	Operating Mode Status	OMS	Provides the recent operating mode	Enum: 0: Disabled
					1: Standard compliant Reserved 214:
					15: Not supported
4	3	Not Used (= 0)			
7	1	Message Type	MT	Defines the message type	Enum: 1: Fan status
8	2	Not Used (= 0)			
10	2	Room Size Reference	RSR	States if the provided room size has to be considered	Enum: 0: Used 1: Not used 2: Reserved 3: Not supported
12		Room Size Status	RSS	Room size status	Enum: 0: < 25 m² 1: 2550 m² 2: 5075 m² 3: 75100 m² 4: 100125 m² 5: 125150 m² 6: 150175 m² 7: 175200 m² 8: 200225 m² 9: 225250 m² 10: 250275 m² 11: 275300 m² 12: 300325 m² 13: 325350 m² 14: > 350 m² 15: Not supported
16 24		Not Used (= 0) Fan Speed Status	FSS	Fan speed	Enum: 0100: 0100% Reserved 101254: 255: Not supported

RORG	D2	VLD Telegram
FUNC	20	Fan Control
TYPE	02	Type 0x02

Submitter: Maico Elektroapparate-Fabrik GmbH

Telegram Definition: 'Fan Control Message'

* Devices with discrete fan speed levels instead of a continuous fan speed range should divide the full range linearly and match values beside those discrete levels to the next lower fan speed level.

Offset	Size		ShortCut	Description	Valid Range Scale Unit
0	7	Not Used (= 0)			
7	1	Message Type	MT	Defines the message type	Enum: 0: Fan control
8	2	Not Used (= 0)			•
10	2	Room Size Reference	RSR	Defines if the provided room size has to be considered	Enum: 0: Used 1: Not used 2: Default 3: No change
12	4	Room Size	RS	Defines the room size	Enum: 0: < 25 m ² 1: 2550 m ² 2: 5075 m ² 3: 75100 m ² 4: 100125 m ² 5: 125150 m ² 6: 150175 m ² 7: 175200 m ² 8: 200225 m ² 9: 225250 m ² 10: 250275 m ² 11: 275300 m ² 12: 300325 m ² 13: 325350 m ² 14: > 350 m ² 15: No change
16	8	Not Used (= 0)			13. No change
24	8	Fan Speed *	FS	Sets the fan speed	Enum:

Telegram Definition: 'Fan Status Message'

Off	set Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	7	Not Used (= 0)					
7	1	Message Type	MT	Defines the message type	Enum: 1: Fan statu	IS	
8	2	Humidity Control Status	HCS	States if the humidity control is active	Enum: 0: Disabled 1: Enabled 2: Reserved 3: Not supp		

10	2	Room Size	RSR	States if the provided room size has to be	Enum:
		Reference		considered	0: Used
					1: Not used
					2: Reserved
					3: Not supported
12	4	Room Size Status	RSS	Room size status	Enum:
					0: < 25 m ²
	14				1: 2550 m ²
					2: 5075 m ²
	1				3: 75100 m ²
					4: 100125 m ²
					5: 125150 m ²
		\'			6: 150175 m ²
					7: 175200 m ²
					8: 200225 m ²
					9: 225250 m ²
					10: 250275 m ²
					11: 275300 m ²
					12: 300325 m ²
					13: 325350 m ²
					14: > 350 m ²
					15: Not supported
16	8	Not Used (= 0)			
24	8	Fan Speed Status	FSS	Fan speed	Enum:
					0100: 0100%
					Reserved 101254:
					255: Not
					supported

D2-30: Floor Heating Controls and Automated Meter Reading

Floor heating controls and automated meter reading gateway may appear combined in one device, but the metering functionality can also be absent.

The floor heating control unit controls a number of valves for separate heating circuits (e.g. for separate heating of single rooms). It measures the common hot water supply temperature as well as the return water temperatures of each single circuit.

The automated meter reading gateway is a device that connects to various counters such as heating, water, gas or electrical energy meters. The meters may be connected to the gateway by one or several of these interface types: M-Bus, D0, S0 (see appendix). The gateway reports the continuous energy or flow volume meter reading of each of the connected metering devices. Typically the measured variables consist of a momentary value and an accumulated value. The transmission of separated consumption import and export values is supported, too.

Data exchange

Direction: bidirectional

Addressing: ADT inbound, broadcast outbound Communication trigger: event- & time-triggered

Communication interval: minimum 1-1000 s, maximum 1000 s

Trigger event: heartbeat 1000 s, value change in "Position", "Return Temperature", "Status/Error", "Supply

Temperature", "Meter Reading" while respecting the minimum reporting interval

Tx delay: 500 ms (maximum response time, first telegram)

Rx timeout: 0 ms (minimum time between two received messages)

Teach-in method: Universal teach-in (outbound)

Encryption required : no Security level format : 0

EEP Family Table

Туре	0x00	0x01	0x02	0x03	0x04	0x05	0x06
Number of heating channels/valves	4	8	8	8	8	6	12
Channel return temperature	Χ	Χ	Χ	Χ	Χ	-	-
Global return temperature	Χ	Χ	Χ	Χ	Χ	-	-
Global supply temperature	Χ	Χ	Χ	Χ	Χ	-	-
Number of supported MBUS meters	0	0	8	10	10	0	0
Number of supported S0 meters	0	0	0	0	1	0	0
Number of supported D0 meters	0	0	0	0	0	0	0

Description of the meter interfaces

S0-Interface:

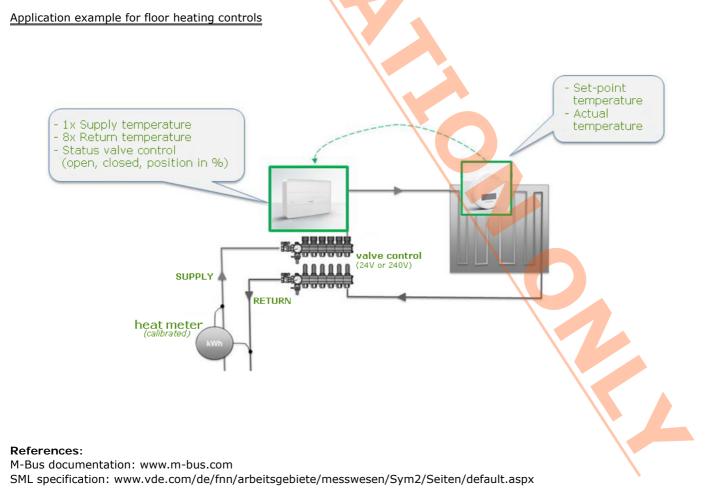
The S0-Interface is a two-wire connection designed for the transmission of monotonously rising measurement data. The standard is defined in EN 62053-31. The meter device transmits a fixed number of pulses per physical meter unit. The number of pulses per unit is defined by the meter manufacturer and depends on the necessary precision of the meter system. The pulses are output as currency variations, where a value lower than 3 mA corresponds to a logical 0. The sender output is mostly realized by a transistor or an opto-coupler, which needs to be supplied by a voltage of 27-30 V. Polarity must be respected.

D0-Interface:

The D0-interface is an optical metering interface defined in EN62056-61. It allows the unidirectional readout of metering data at a rate of 9600 Baud, using telegrams with start bit, 7 data bits, parity and a stop bit. One of the protocols SML (Smart Message Language) or DLMS (Device Language Message Specification, EN62056-21) can be used for coding the data. A D0-Meter can deliver consumption data as well as various system data. The source and type of a data point is indicated by the standardized OBIS-codes.

MBUS-Interface:

The M-Bus (Meter-Bus) is a bidirectional field bus for the communication with consumption meters. It is described in standard EN13757. Typically there can be connected up to 250 devices in one M-Bus network. There is a common master in the network, who periodically collects the meter data from its slaves. The network may be implemented either as two-wire cable network allowing remote powering of the slaves or as wireless network. The protocol operates at 300 to 9600 Baud and codes the data bytes with start bit, 8 data bits, parity and a stop bit. The data records sent by a metering slave deliver in their header field the coding information of the following data field (value size, measurement medium, unit, multiplier). The master can address a single slave by its primary address (1...250), which must be assigned during network configuration, or by its secondary address, which is a unique device identification number assigned by the device manufacturer.



EEP 2.6.4 Specification © EnOcean Alliance

DLMS User Association: www.dlms.com

RORG	D2	VLD Telegram
FUNC	30	Floor Heating Controls and Automated Meter Reading
TYPE	00	Type 0x00

Submitter: MSR-Solutions

CMD 0x1 - Set heating controls output

This message is sent to a floor heating actuator. It controls the valve position of one channel or of all channels of the floor heating controls.

Sender: controller; send type: broadcast or addressed; expected response: CMD 0x3

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit	
0		Valve control period / PWM signal interval	PERIOD	Total on-off time for two-position valve controller (T valve open + T valve closed)	Enum: 0: Local default / no change			
					1: 1 s			
		\			2: 2 s			
					3: 5 s			
					4: 10 s			
					5: 20 s			
					6: 50 s			
					7: 100 s	5		
					8: 200 s	i		
					9: 500 s	5		
					10: 1000	S		
					Reser	ved		
4	4	Command ID	CMD	Command identifier	Enum: 0x01: ID 01	_		
8	2	Not Used (= 0)						
10		Valve type	VTYP	Type of connected valve	Enum:			
	_	valve cype		Type of commerced tarre	0: Valve no (N.C.) 1: Valve no	ormally clo		
11	5	Heating channel	НСН	The heating channel that should	(N.O.) Enum:			
11		rieating channel	TICH	be set	015: A val		l	
					Reserved 1630:			
						lid chann	els	
16	1	Run init sequence	RIN	Measure and store the valve zero point	Enum: 0: No action			
						sequence	_	
17	7	Valve position set point	POS	Valve set point 0100% (0=closed, 100=open)	0100	0100	%	

CMD 0x2 - Heating controls status query

This message is sent to a floor heating actuator. It requests the status of one channel or the status of the global control unit of an actuator.

Sender: controller; send type: broadcast or addressed; expected response: CMD 0x3

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit			
0	4	Not Used $(= 0)$)							
4	4	Command ID	CMD	Command identifier	Enum:					
					0x02: ID 02					
8	3	Not Used (= 0)								
11	5	Heating	HCH	The heating channel that should	Enum:					
		channel	be reported	015: A valid channel number						
				Reserve	d					
					29: All valid channels					
						30: All valid channels and global device status				
					31: Global d	evice status only	_			

CMD 0x3 - Heating controls status response / CH = 0...15

This message is sent by a floor heating controls if one of the following events occurs:

- Message 'status query' has been received (CMD 0x2).
- Status of one channel or temperature has changed.

Sender: actuator; send type: broadcast; maximum send delay 1 s.

If the response is for single channel data (CH = 0...15):

Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit		
0	4	Not Used (= 0)					
4	4	Command ID	CMD	Command identifier	Enum:		
					0x03: ID 03		
8	3	Status / Error	STATUS	Status / Error indication of given	Enum:		
		channel		0: No fault			
					1: General error		
					2: Init sequence running		
					3: Channel not available		
					4: Temperature sensor error		
					5: Valve error		
					6: Temperature sensor and valve error		
					7: Reserved		
11	5	Heating channel	HCH	The heating channel that is reported	Enum:		
					015: A valid channel number		
					Reserved 1631:		
16	1	Not Used (= 0)					

17	7	Valve position	Actual valve position 0100% (0=closed, 100=open)	0100	0100	%
24		Return temperature	The current return temperature of the channel	0180	090	°C

CMD 0x3 - Heating controls status response / CH = 31

If the response is for global floor heating controls unit data (CH = 31):

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit	
0	4	Not Used (= 0)						
4	4	Command ID	CMD	Command identifier	Enum:			
					0x03: ID 03			
8	3	Status / Error	STATUS	Global unit status	Enum:			
					0: No fault			
					1: General e	rror		
					2: Supply te error	mperatur	е	
					3: Return te error	mperatur	e	
					4: Error on b	oth sens	ors	
					Reserved 57:			
11	5	Heating channel	HCH	The heating channel that is reported	Enum:			
				(=global unit)	31: Unit status	only		
16		Supply temperature	TSUP	The current supply temperature of the unit	0180	090	°C	
24		Return temperature	TRET	The current common return temperature	0180	090	°C	

CMD 0x6 - Set meter configuration / MBUS (BUS = 1)

This message is sent to a metering device gateway to configure the meter settings for one channel.

Sender: controller; send type: broadcast or addressed.

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0		Report measurement		Minimum auto reporting interval	Enum: 0: No auto report 1: Min. 1 s inter 2: Min. 3 s inter 3: Min. 10 s inter 4: Min. 30 s inter 5: Min. 100 s inter 6: Min. 300 s inter 7: Min. 1000 s inter 815: Reserved	val erval erval erval erval	
4	4	Command ID	CMD	Command identifier	Enum: 0x06: ID 06		
8	1	Not Used (= 0)					
9	2	Meter bus type	BUS	The meter bus that should be configured	Enum: 0: Reserved 1: MBUS 2: S0 3: D0		

11	5	Meter channel index	MCH	The meter bus that should be configured	030		030	1
16	2	Not Used (= 0)						
18	3	Meter 1 units	UNIT1	Physical units of first measured quantity (imported value)	0: 1:	No reading (un Current value V		ed
					2:	Current value V	V, accumulate	ed
	· ·				3:	Accumulated va	alue kWh only	/
					4:	Current value n value m3	n3/h, accumu	ılated
			5: Current value dm3/h, accumulated value dm3			nulated		
					6: Accumulated value m3 only 7: Digital counter			
						Digital counter		
21	3	Meter 2 units	UNIT2	Physical units of second	Enum:			
				measured quantity (exported value)	0:	No reading (un	configured)	
					1:	Current value V value kWh	V, accumulate	ed
					2:	Current value V value Wh	V, accumulate	ed
					3:	Accumulated va	alue kWh only	/
					4: Current value m3/h, accumulated value m3			ılated
					5:	Current value of value dm3	lm3/h, accum	nulated
					6: Accumulated value m3 only			
					7:	Digital counter		
24	8	Primary Address	ADDR	The primary MBUS address of the meter	1250)	1250	1
32	40	Not Used (= 0)						

CMD 0x6 - Set meter configuration / S0 (BUS = 2)

Offset	Size	Data	ShortCut	Description	Valid Range Scale Uni	t
0		Report measurement	1	Minimum auto reporting interval	Enum: 0: No auto reporting 1: Min. 1 s interval 2: Min. 3 s interval 3: Min. 10 s interval 4: Min. 30 s interval 5: Min. 100 s interval 6: Min. 300 s interval 7: Min. 1000 s interval	
4	4	Command ID	CMD	Command identifier	815: Reserved Enum: 0x06: ID 06	
8	1	Not Used (= 0)	•			
9	2	Meter bus type		The meter bus that should be configured	Enum: 0: Reserved 1: MBUS 2: S0	

11 5 Meter channel index 16 2 Not Used (= 0) 18 3 Meter 1 units UNIT1 Physical units of quantity	onfigured
16 2 Not Used (= 0) 18 3 Meter 1 units UNIT1 Physical units of	first measured Enum:
(imported value)	o. No reading (uncomigured)
	1: Current value W, accumulated value kWh
	2: Current value W, accumulated value Wh
	3: Accumulated value kWh only
	4: Current value m3/h, accumulated value m3
	5: Current value dm3/h, accumulated value dm3
	6: Accumulated value m3 only
	7: Digital counter
21 3 Meter 2 units UNIT2 Physical units of	
measured quanti (exported value)	
	1: Current value W, accumulated value kWh
	2: Current value W, accumulated value Wh
	3: Accumulated value kWh only
	4: Current value m3/h, accumulated value m3
	5: Current value dm3/h, accumulated value dm3
	6: Accumulated value m3 only
	7: Digital counter
24 2 Factor of number of FACP The factor for the	
pulses pulses per value in UNIT	0: 1
per taide in onti	1; 0.1
	2: 0.01 3: 0.001
26 14 Number of pulses NOP The number of pulses	
in UNIT1* FACP	0: Do not change the current setting of NOP
	Number of pulses per 165535: unit
40 32 Preset value RST Preset the accum	
this value	New preset value
	04294967294:
	0xFFFFFFFF: Do not change the current value

CMD 0x6 - Set meter configuration / D0 (BUS = 3)

Offse	Size	Data	ShortCut	Description	Va	lid Range	Scale	Unit
0	4	Report	RM	Minimum auto reporting interval	Enum:		//	
		measurement			0:	No auto repor	ting	
					1:	Min. 1 s interv	val	
					2:	Min. 3 s interv	val	

4 8 9	1 2	Command ID Not Used (= 0) Meter bus type	CMD	Command identifier The meter bus that should be configured	3: Min. 10 s interval 4: Min. 30 s interval 5: Min. 100 s interval 6: Min. 300 s interval 7: Min. 1000 s interval 815: Reserved Enum: 0x06: ID 06 Enum: 0: Reserved 1: MBUS 2: S0
11	5	Meter channel	МСН	The meter number of given bus	3: D0 030 030 1
16	2	index Not Used (= 0)		that should be configured	
18	3	Meter 1 units	UNIT1	Physical units of first measured quantity (imported value)	Enum: 0: No reading (unconfigured) 1: Current value W, accumulated value kWh 2: Current value W, accumulated value Wh 3: Accumulated value kWh only 4: Current value m3/h, accumulated value m3 5: Current value dm3/h, accumulated value dm3 6: Accumulated value m3 only 7: Digital counter
21	3	Meter 2 units	UNIT2	Physical units of second measured quantity (exported value)	Enum: 0: No reading (unconfigured) 1: Current value W, accumulated value kWh 2: Current value W, accumulated value Wh 3: Accumulated value kWh only 4: Current value m3/h, accumulated value m3 5: Current value dm3/h, accumulated value dm3 6: Accumulated value m3 only 7: Digital counter
24	8	D0 Protocol Not Used (= 0)	PROT	The D0 protocol that should be used for that meter	Enum: 0: Auto detect 1: SML (Smart Message Language) 2: DLMS (Device Language Message Specification) Reserved 3255:

CMD 0x7 - Meter Status Query

This message is sent to a metering device gateway to query the status of a meter. Sender: controller; send type: broadcast or addressed; expected response: CMD 0x8.

Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit
0	4	Not Used (= 0)			
4	4	Command ID	CMD	Command identifier	Enum:
					0x07: ID 07
8	1	Not Used (= 0)			
9	2	Meter bus type	BUS	The meter bus type that is queried	Enum:
	· ·				0: Reserved
					1: MBUS
					2: S0
					3: D0
11	_				Enum:
		index		queried	Meter channel
					030:
					31: All valid
					channels

CMD 0x8 - Meter reading report / status response

This message is sent by a metering device gateway to report the meter values for each configured channel. It is sent if one of the following events occurs:

- Message 'meter status query' has been received (CMD 0x7)
- Status or meter reading of one channel has changed and auto reporting was configured by signal RM.

Sender: sensor; send type: broadcast; maximum send delay 1 s.

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	1	Not Used (= 0))				
1		Meter status / error	MSTAT	Meter channel status	6: Unknowr configura	onfigured onnected	
4	4	Command ID	CMD	Command identifier	Enum: 0x08: ID 08		
8	1	Not Used (= 0)					
9		Meter bus type	BUS	The used bus of the meter status response	Enum: 0: Reserved 1: MBUS 2: S0 3: D0		
11		Meter channel index	MCH	The meter number of given bus that status is reported	030	030	1
16	3	Not Used (= 0))				
19		Value selection	VSEL	The selection of the reported value	1: Meter 1 / 2: Meter 2 (Current value Accumulated value Current value Accumulated valu	
21	3	Value unit	VUNIT	The unit of the reported value	Enum: 0: W 1: Wh 2: kWh		

					3: m3/h 4: dm3/h 5: m3 6: dm3 7: 1 (digital counter)
24	32	Meter reading value	VAL	The reported value	04294967295 04294967295 According to VUNIT

RORG	D2	VLD Telegram
FUNC	30	Floor Heating Controls and Automated Meter Reading
TYPE	01	Type 0x01 (description: see table)

See profile: D2-30-00

RORG	D2	VLD Telegram
FUNC	30	Floor Heating Controls and Automated Meter Reading
TYPE	02	Type 0x02 (description: see table)

See profile: D2-30-00

RORG	D2	VLD Telegram
FUNC	30	Floor Heating Controls and Automated Meter Reading
TYPE	03	Type 0x03 (description: see table)

See profile: D2-30-00

RORG	D2	VLD Telegram
FUNC	30	Floor Heating Controls and Automated Meter Reading
TYPE	04	Type 0x04 (description: see table)

See profile: D2-30-00

RORG	D2	VLD Telegram
FUNC	30	Floor Heating Controls and Automated Meter Reading
TYPE	05	Type 0x05 (description: see table)

See profile: D2-30-00

RORG	D2	VLD Telegram
FUNC	30	Floor Heating Controls and Automated Meter Reading
TYPE	06	Type 0x06 (description: see table)

See profile: D2-30-00

D2-31: Automated Meter Reading Gateway

The automated meter reading gateway is a device that connects to various counters such as heating, water, gas or electrical energy meters. The meters may be connected to the gateway by one or several of these interface types: M-Bus, D0, S0 (see appendix). The gateway reports the continuous energy or flow volume meter reading of each of the connected metering devices. Typically the measured variables consist of a momentary value and an accumulated value. The transmission of separated consumption import and export values is supported, too.

Data exchange

Direction: bidirectional

Addressing: ADT inbound, broadcast outbound Communication trigger: event- & time-triggered

Communication interval: minimum 1-1000 s (configuration item), maximum 1000 s

Trigger event: heartbeat 1000 s, value change in "Status/Error", "Meter Reading" while respecting the minimum

reporting interval

Tx delay: 500 ms (maximum response time, first telegram)
Rx timeout: 0 ms (minimum time between two received messages)

Teach-in method: Universal teach-in (outbound)

Encryption required : no Security level format : 0

Telegram Definition

The telegram definition is inherited from profile D2-30-xx and thus identical to the definition there.

EEP Family Table

Supported function	Type 0x00	Тур	e 0x01
Number of supported MBUS meters	10	16	
Number of supported S0 meters	2	0	
Number of supported D0 meters	2	0	

Description of the meter interfaces

S0-Interface:

The S0-Interface is a two-wire connection designed for the transmission of monotonously rising measurement data. The standard is defined in EN 62053-31. The meter device transmits a fixed number of pulses per physical meter unit. The number of pulses per unit is defined by the meter manufacturer and depends on the necessary precision of the meter system. The pulses are output as currency variations, where a value lower than 3 mA corresponds to a logical 0. The sender output is mostly realized by a transistor or an opto-coupler, which needs to be supplied by a voltage of 27-30 V. Polarity must be respected.

D0-Interface:

The D0-interface is an optical metering interface defined in EN62056-61. It allows the unidirectional readout of metering data at a rate of 9600 Baud, using telegrams with start bit, 7 data bits, parity and a stop bit. One of the protocols SML (Smart Message Language) or DLMS (Device Language Message Specification, EN62056-21) can be used for coding the data. A D0-Meter can deliver consumption data as well as various system data. The source and type of a data point is indicated by the standardized OBIS-codes.

MBUS-Interface:

The M-Bus (Meter-Bus) is a bidirectional field bus for the communication with consumption meters. It is described in standard EN13757. Typically there can be connected up to 250 devices in one M-Bus network. There is a common master in the network, who periodically collects the meter data from its slaves. The network may be implemented either as two-wire cable network allowing remote powering of the slaves or as wireless network. The protocol operates at 300 to 9600 Baud and codes the data bytes with start bit, 8 data bits, parity and a stop bit. The data records sent by a metering slave deliver in their header field the coding information of the following data field (value size, measurement medium, unit, multiplier). The master can address a single slave by its primary address (1...250), which must be assigned during network configuration, or by its secondary address, which is a unique device identification number assigned by the device manufacturer.

References:

M-Bus documentation: www.m-bus.com

SML specification: www.vde.com/de/fnn/arbeitsgebiete/messwesen/Sym2/Seiten/default.aspx

DLMS User Association: www.dlms.com

RORG D2 VLD Telegram

FUNC	31	Automated Meter Reading Gateway
TYPE	00	Type 0x00

Submitter: MSR-Solutions

CMD 0x6 - Set meter configuration / MBUS (BUS = 1)

This message is sent to a metering device gateway to configure the meter settings for one channel.

Sender: controller; send type: broadcast or addressed.

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit	
0		Report	RM	Minimum auto reporting interval	Enum:			
		measurement		, ,	0: No auto re	portina	-	
			1		1: Min. 1 s interval			
					2: Min. 3 s interval			
					3: Min. 10 s i		-	
					4: Min. 30 s i		-	
					-		=	
					5: Min. 100 s interval 6: Min. 300 s interval			
					7: Min. 1000		-	
					815: Reserved	5 interval	-	
4	4	Command ID	CMD	Command identifier				
7	7	Command 1D	CIND	Command Identifier	Enum:			
0	4	Natiliand (O)			0x06: ID 06			
8	1	Not Used (= 0)	DUC	The second of th	_			
9	2	Meter bus type	BUS	The meter bus that should be configured	Enum:			
				comigured	0: Reserved			
					1: MBUS			
					2: S0			
					3: D0	1		
11	5	Meter channel	MCH	The meter number of given bus	030	030	1	
		index		that should be configured				
16	2	Not Used (= 0)						
18	3	Meter 1 units UNIT1	UNIT1	Physical units of first measured	Enum:			
				quantity (imported value)	0: No reading (unconfigured)			
				(imported value)	1: Current value W, accumulated			
					1: Current value value kWh	e W, accumul	ated	
						- W	atad	
					2: Current value value Wh	e w, accumui	ateu	
					3: Accumulated	value kWh c	nly	
					J. Accumulated	value kwii c	, iiiy	
					4: Current value	e m3/h.		
					accumulated			
					5: Current value	lue dm3/h,		
					accumulated	value dm3		
					6: Accumulated	value m3 or	ıly	
					7: Digital count	er		
21	3	Meter 2 units	UNIT2	Physical units of second measured	Enum:			
				quantity	0: No reading (unconfigured)	
				(exported value)				
					1: Current value	e W, accumul	ated	
					value kWh			
					2: Current value value Wh	e W, accumul	ated	
					3: Accumulated	value kWh c	nly	
					4: Current value			
					accumulated	value m3		

					Current value accumulated Accumulated Digital counter	value dm3 value m3 o	nly
24	8	Primary Address	The primary MBUS address of the meter	125	0	1250	1
32	40	Not Used (= 0)		•			·

CMD 0x6 - Set meter configuration / S0 (BUS = 2)

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Report	RM	Minimum auto reporting interval	Enum:	_	
		measurement			0: No auto repo	orting	_
					1: Min. 1 s inte	rval	_
		\			2: Min. 3 s inte	rval	
					3: Min. 10 s int	erval	-
					4: Min. 30 s int	erval	-
					5: Min. 100 s ir	nterval	=
					6: Min. 300 s ii	nterval	=
					7: Min. 1000 s	interval	-
			\		815: Reserved		-
4	4	Command ID	CMD	Command identifier	Enum:		
					0x06: ID 06		
8	1	Not Used (= 0)					
		Meter bus type	BUS	The meter bus that should be	Enum:		
		,,,,		configured	0: Reserved		
					1: MBUS		
					2: S0		
					3: D0		
11	5	Meter channel	MCH	The meter number of given bus	030	030	1
		index	11011	that should be configured	050	050	_
16		Not Used (= 0)					
18		Meter 1 units	UNIT1	Physical units of first measured	Enum:		
				quantity	0: No reading (ur	nconfigured)
				(imported value)	J.	J	•
					1: Current value value kWh	W, accumul	ated
					2: Current value	W accumul	ated
					value Wh	w, accumu	atcu
					3: Accumulated v	alue kWh o	only
					4: Current value		
					accumulated v 5: Current value		
					accumulated v		
					6: Accumul <mark>at</mark> ed v	ralue m3 on	nly
					7: Digital counter		
21	2	Makan 2	LINITTO	Dhi.a.laita afl	-		
21	3	Meter 2 units	UNIT2	Physical units of second measured quantity	Enum:	6	
				(exported value)	0: No reading (ur	nconfigured	
					1: Current value value kWh	W, accumul	ated
					2: Current value value Wh	W, accumul	ated
					3: Accumulated v	alue kWh o	inly
					J. Accumulated v	GIGC RVVII O	, i y

			4: Current value m3/h, accumulated value m3 5: Current value dm3/h, accumulated value dm3 6: Accumulated value m3 only 7: Digital counter
24	2 Factor of number of F pulses	FACP The factor for the number of pulses per value in UNIT1	Enum: 0: 1 1: 0.1 2: 0.01 3: 0.001
26	14 Number of pulses	NOP The number of pulses per value in UNIT1* FACP	Enum: 0: Do not change the current setting of NOP Number of pulses per 165535: unit
40	32 Preset value	Preset the accumulated value to this value	Enum: New preset value 04294967294: 0xFFFFFFFF: Do not change the current value

CMD 0x6 - Set meter configuration / D0 (BUS = 3)

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Report	RM	Minimum auto reporting interval	Enum:		
		measurement			0: No auto repo	rting	
					1: Min. 1 s inter	val	
					2: Min. 3 s inter	val	
					3: Min. 10 s inte	erval	
					4: Min. 30 s inte	erval	
					5: Min. 100 s in	terval	
					6: Min. 300 s in	terval	
					7: Min. 1000 s i	nterval	
					815: Reserved		
4	4	Command ID	CMD	Command identifier	Enum:		
					0x06: ID 06		
8		Not Used (= 0)					
9	2	Meter bus type	BUS	The meter bus that should be	Enum:		
				configured	0: Reserved		
					1: MBUS		
					2: S0		
					3: D0		
11	5		MCH		030	030	1
	_	index		that should be configured			
16	2	Not Used (= 0)	l	<u> </u>			
18	3	Meter 1 units	UNIT1	Physical units of first measured quantity	Enum:		
				(imported value)	0: No reading (und	configured)	
					1: Current value V value kWh	V, accumula	ted
					2: Current value V	V, accumula	ted
					value Wh	1 - 1 > 40	
					3: Accumulated va	ilue kWh or	ily
					4: Current value n		
					accumulated va	lue m3	

					t	
					5: Current value dm3/h, accumulated value dm3	
					6: Accumulated value m3 only	
					7: Digital counter	
21	3	Meter 2 units	UNIT2	Physical units of second measured	Enum:	
	1			quantity (exported value)	0: No reading (unconfigured)	
					1: Current value W, accumulated value kWh	
					2: Current value W, accumulated value Wh	
					3: Accumulated value kWh only	
					4: Current value m3/h, accumulated value m3	
					5: Current value dm3/h, accumulated value dm3	
					6: Accumulated value m3 only	
					7: Digital counter	
24	8	D0 Protocol	PROT	The D0 protocol that should be	Enum:	
				used for that meter	0: Auto detect	
					1: SML (Smart Message Language)	
					2: DLMS (Device Language Message Specification)	
					Reserved 3255:	
32	40	Not Used (= 0)				

CMD 0x7 - Meter Status Query

This message is sent to a metering device gateway to query the status of a meter. Sender: controller; send type: broadcast or addressed; expected response: CMD 0x8.

Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit
0	4	Not Used (= 0)			
4	4	Command ID	CMD	Command identifier	Enum: 0x07: ID 07
8	1	Not Used (= 0)			
9	2	Meter bus type	BUS	The meter bus type that is queried	Enum: 0: Reserved 1: MBUS 2: S0 3: D0
11		Meter channel index		The meter channel of given bus that status is queried	Meter channel 030: 31: All valid channels

CMD 0x8 - Meter reading report / status response

This message is sent by a metering device gateway to report the meter values for each configured channel. It is sent if one of the following events occurs:

- Message 'meter status query' has been received (CMD 0x7)

- Status or meter reading of one channel has changed and auto reporting was configured by signal RM.

Sender: sensor; send type: broadcast; maximum send delay 1 s.

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit			
0	1	Not Used (= 0))							
1	3	Meter status / error	MSTAT	Meter channel status	Enum: 0: No fault 1: General error 2: Bus unconfigured 3: Bus unconnected					
					6: Unknown configura	ication timeout n protocol or ation mismatch alization running	_			
4	4	Command ID	CMD	Command identifier	Enum: 0x08: ID 08	_				
8	1	Not Used (= 0)								
9	2	Meter bus type	BUS	The used bus of the meter status response	0: Reserved 1: MBUS 2: S0 3: D0					
11	5	Meter channel index	МСН	The meter number of given bus that status is reported	030	030	1			
16	3	Not Used (= 0)								
19	2		VSEL	The selection of the reported value	1: Meter 1 A 2: Meter 2 (Current value Accumulated valu Current value Accumulated valu				
21	3	Value unit	VUNIT	The unit of the reported value	Enum: 0: W 1: Wh 2: kWh 3: m3/h 4: dm3/h 5: m3 6: dm3 7: 1 (digital					
24	32	Meter reading value	VAL	The reported value	04294967295	04294967295	According to VUNIT			

RORG	D2	VLD Telegram						
FUNC	31	Automated Meter Reading Gateway						
TYPE	01	Type 0x01 (description: see table)						

See profile: D2-31-00

D2-32: A.C. Current Clamp

Description

A family of EEP's based on a central unit where up to three a.c. Current Clamps can be connected. Each one capable of energy harvesting sufficiently to enable readings of current values to be taken in amps and transmitted every 30 seconds.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: time-triggered Communication interval: 30 seconds

Trigger event: Threshold Voltage for Power Fail transmission bit

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: Universal teach-in (UTE)

Security

Encryption supported: no Security level format: -

EEP Family Table:

Supported function	Type	00	Type	01	Type 02
Channel 1	Χ		X		Χ
Channel 2	- \/		X		X
Channel 3	-		7		X

Each TYPE has to support every parameter that is marked in its column!

The list of parameters could be structured following the features that always include a certain group of parameters.

RORG	D2	VLD Telegram
FUNC	32	A.C. Current Clamp
TYPE	00	Type 0x00

Submitter: Pressac Communications Ltd

Type 00

				DB	_2							DB	_1		V					DB	_0			
DB_2.BIT_7 ← 0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset: 0 🗲 23	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23
	PF	DIV												CH	41									

Notes

- 1) If Power Fail bit is set, all channel readings will be set to zero when this final telegram is sent.
- 2) Scale/divisor is set to 0 or 1 for all channels only, not individually.

Offset	Size	Data	ShortCut	Description	Valid	Range	Scale	Unit
0	1	Power Fail	PF	See Note 1	Enum	:		
					0:	False		
					1:	True		
1	1	Divisor	DIV	Divisor for all channels	Enum	:		
					0:	x/1		
					1:	x/10	_	
2	6	Not Used ((= 0)					
8	12	Channel 1	CH1	Current value	00x	FFF	04095 (409,5)	A
20	4	Not Used ((= 0)		·	•		

RORG	D2	VLD Telegram

FUNC	32	A.C. Current Clamp
TYPE	01	Type 0x01

Submitter: Pressac Communications Ltd

Type 01

				DB	_3							DB	_2							DB	_1							DB	_0			
DB_3.BIT_7 ← 0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset: 0 -> 31	Ó	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31
	PF	DIV												CH	11											CH	12					

Notes

- 1) If Power Fail bit is set, all channel readings will be set to zero when this final telegram is sent.
- 2) Scale/divisor is set to 0 or 1 for all channels only, not individually.

Offset	Size	Data	ShortCut	Description	Valid Range	Scale Unit
0	1	Power Fail	PF	See Note 1	Enum:	
					0: False	
					1: True	
1	1	Divisor	DIV	Divisor for all channels	Enum:	
					0: x/1	
					1: x/10	_
2	6	Not Used ((= 0)			
8	12	Channel 1	CH1	Current value	00xFFF	04095 (409,5) A
20	12	Channel 2	CH2	Current value	00xFFF	04095 (409,5) A

RORG	D2	VLD Telegram
FUNC	32	A.C. Current Clamp
TYPE	02	Type 0x02

Submitter: Pressac Communications Ltd

Type 02

				DB	_5							DB_	4						D	B_3							DB	_2						E	DB_	1							B_	D		
DB_5.BIT_7 ← 0	7	6	5	4	3	2	1	0	7	6	5	4	3 :	2	1 (0 7	(5 5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5 4	4 3	3 2	2 1	L C) 7	7 (5	5 4	4 3	2	1	0
Bit Offset: 0 -> 47	0	1	2	3	4	5	6	7	8	9	10	11	2 1	3 1	4 1	5 1	6 1	7 18	3 19	9 20	21	22	23	24	25	26	27	28	29	30	31	32	33 3	4 3	35 3	6 3	7 3	8 3	9 4	0 4	1 4	42 4	13 4	4 4:	46	47
	PF	DIV												CH	1					Т					CH	12										<u> </u>	СНЗ									

Notes

- 1) If Power Fail bit is set, all channel readings will be set to zero when this final telegram is sent.
- 2) Scale/divisor is set to 0 or 1 for all channels only, not individually.

Offset	Size	Data	ShortCut	Description	Valid Range	Scale Unit
0	1	Power Fail	PF	See Note 1	Enum:	
					0: False	
					1: True	
1	1	Divisor	DIV	Divisor for all channels	Enum:	
					0: x/1	_
					1: x/10	
2	6	Not Used ((= 0)			
8	12	Channel 1	CH1	Current value	00xFFF	04095 (409,5) A
20	12	Channel 2	CH2	Current value	00xFFF	04095 (409,5) A

32	12	Channel 3 CH3	Current value	00xFFF	04095 (409,5) A
44	4	Not Used (= 0)			

D2-40: LED Controller Status

Description

This family of EEP's is used for sending handling a LED controller device. The status is send periodically, or after product specific event occurred e.g. when one of the parameters from the status message has changed. It allows other devices to monitor LED controller and react to its actions.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication interval: configurable

Trigger event: heartbeat, change of one of the parameters from the status message

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: Universal teach-in (UTE)

Security

Encryption supported: no Security level format: -

EEP Family Table:

Supported function	Type 00	Type 01
MsgId	Χ	X
LED output enabled	Χ	X
"Demand Response" mode Active	Χ	X
Daylight Harvesting	Χ	Χ
Occupancy state	Χ	Χ
Status Tx reason	Χ	Χ
Current Dim Level	Χ	ı
Current Dim Level LED R	-	Χ
Current Dim Level LED G	-	Χ
Current Dim Level LED B	-	X

Each TYPE has to support every parameter that is marked in its column!

"LED output enabled" parameter is correlated with dimming level – it is set to ENABLE if dimming level is above 0%. 0% dimming level means that the light is completely OFF.

LED controller has a "Demand Response" feature. When DR mode is triggered by external device, "Demand Response" mode Active will be set to TRUE.

Daylight Harvesting feature of the LED controller is also triggered by the external sensor.

Occupancy state is change by occupancy sensor taught in to the LED controller.

DR, Daylight Harvesting, and Occupancy will influence dimming levels, with an algorithm specific to the device that sends the status message.

RORG	D2	VLD Telegram
FUNC	40	LED Controller Status
TYPE	00	Type 0x00

Submitter: EnOcean GmbH

Msgld 0x00:Status of monocolor LED controller

MsgId 0x00

				DB	_1							DB	_0			
DB_1.BIT_7 ← 0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset: 0 → 15	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
	OUTEN	DRA	DHAR	000	1	SREAS	12					5	ו ו			

monocolor LED

Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit
0		LED output enabled	OUTEN	Driving LED enabled	Enum: 0: Disabled
					1: Enabled
1	1	"Demand	DRA	Controller is in the DR mode. It had received	Enum:
		Response" mode		a DR command from DR controller, and it is	0: False
		Active		executing it.	1: True
2		Daylight	DHAR	Daylight harvesting feature is turned on.	Enum:
		Harvesting Active		Readings from photo sensor are influencing	0: False
				the dimming level.	1: True
3	2	Occupancy State	occ	Room which controller is in charge of is	Enum:
				considered occupied.	0: Not occupied
					1: Occupied
					2: Unknown
5	1	Status Tx reason	SREAS	Reason for sending this status message	Enum:
					0: Other
					1: Heartbeat
6	2	MsgId	MI	Message Id; 0x00	Enum:
					0: LED Status
0	_	0 15: 1	D11.0	0 15 15	monocolor
8	8	Current Dim Level	DLVL	Current dim level for the monocolor LED	Enum:
					0200: 0100 %
					0xFF: If not
					used

RORG	D2	VLD Telegram
FUNC	40	LED Controller Status
TYPE	01	Type 0x01

Submitter: EnOcean GmbH

MsgId OxO1: Status of RGB LED controller

MsgId 0x01

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Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit
0		LED output	OUTEN	Driving LED enabled	Enum:
		enabled			0: Disabled
					1: Enabled
1	1	"Demand	DRA	Controller is in the DR mode. It had received	Enum:
		Response" mode Active		a DR command from DR controller, and it is executing it.	0: False
					1: True
2		Daylight	DHAR	Daylight harvesting feature is turned on.	Enum:
		Harve <mark>sti</mark> ng Active		Readings from photo sensor are influencing the dimming level.	0: False
				<u> </u>	1: True
3	2	Occupancy State	occ	Room which controller is in charge of is	Enum:
				considered occupied.	0: Not occupied
					1: Occupied
					2: Unknown
5	1	Status Tx reason	SREAS	Reason for sending this status message	Enum:
		\			0: Other
_	_				1: Heartbeat
6	2	MsgId	MI	Message Id; 0x01	Enum:
_	_				1: LED Status RGB
8	_	Current Dim Level LED R	DLVLR	Current dim level for the red LED	Enum:
		LED K	//		0200: 0100 %
			`		
					0xFF: If not used
16	8	Current Dim Level	DIVIG	Current dim level for the green LED	Enum:
	-	LED G			
					0200: 0100 %
					0xFF: If not
					used
24	8		DLVLB	Current dim level for the blue LED	Enum:
		LED B			
					0200: 0100 %
					0xFF: If not
					used

D2-50: Heat Recovery Ventilation

Submitter: Glen Dimplex

Description

The EEP family D2-50-XX provides different telegram types for heat-recovery ventilation control and status messages using various parameters and variables.

There are 4 types of messages:

- Ventilation Remote Transmission Request Message
- Ventilation Control Message
- Ventilation Basic Status Message
- Ventilation Extended Status Information Message

Data exchange

Direction: bidirectional

Addressing: unicast (ADT) + broadcast

Communication trigger: event- & time-triggered

Communication interval: min. 1s (not more than once per second on events), max. 5s (heartbeat)

Trigger event: heartbeat 5s

on reception of 'Ventilation Control Message'

query / polling by 'Ventilation Remote Transmission Request Message'

on value change at ...

- "Operating Mode Status"
- "Digital Input 0...15 Status"
- "Digital Output 0...15 Status"
- "Info Message 0...15 Status"
- "Fault 0...31 Status"

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: Universal teach-in (UTE)

Security

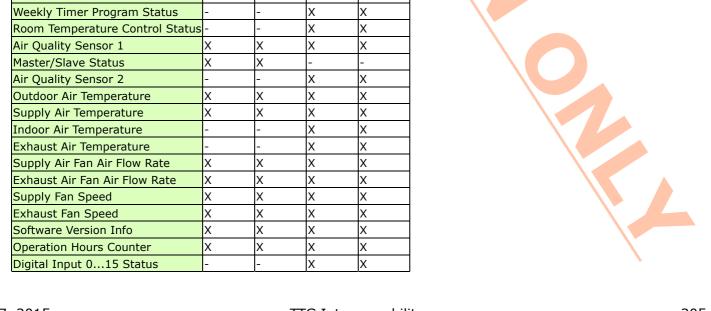
Encryption supported: no Security level format: -

EEP Family Table

TYPE 00: single room ventilation unit

TYPE 01: single room ventilation unit with pre-heater TYPE 02...09: reserved for future single room variants TYPE 10: multi room ventilation unit without bypass TYPE 11: multi room ventilation unit with bypass TYPE 12...xx: reserved for future multi room variants

Supported function	Type 00	Type 01	Type 10	Type 11
Message Type	X	Χ	X	Χ
Requested Message Type	X	Χ	X	Χ
Direct Operation Mode Control	Χ	X	X	Χ
Operation Mode Control	Х	X	X	Χ
Timer Operation Mode Control	Х	X	X	X
CO2 Threshold	Х	X	X	X
Heat Exchanger Bypass Control	-	-	-	X
Humidity Threshold	Χ	Χ	X	X
Air Quality Threshold	Χ	Χ	X	X
Room Temperature Threshold	-	-	X	X
Operation Mode Status	Χ	Χ	Х	X
Safety Mode Status	-	-	-	X
Heat Exchanger Bypass Status	-	-	-	X
Supply Air Flap Position	X	Χ	-	-
Exhaust Air Flap Position	Χ	Χ	-	-
Defrost Mode Status	Χ	Χ	Χ	X
Cooling Protection Status	Χ	Χ	Χ	X
Outdoor Air Heater Status	-	Χ	Χ	Χ
Supply Air Heater Status	-	i	Χ	X
Drain Heater Status	Χ	Χ	-	1
Timer Operation Mode Status	Χ	Χ	Χ	Χ
Filter Maintenance Status	X	Χ	Χ	X
Weekly Timer Program Status	-	•	Χ	Χ
Room Temperature Control Status	-	-	Χ	X
Air Quality Sensor 1	X	Χ	Χ	X
Master/Slave Status	Χ	Χ	-	-
Air Quality Sensor 2	-	i	Χ	X
Outdoor Air Temperature	Χ	Χ	Χ	Χ
Supply Air Temperature	X	Χ	Χ	X
Indoor Air Temperature	-	•	Χ	Χ
Exhaust Air Temperature	-	ı	Χ	Χ
Supply Air Fan Air Flow Rate	Χ	Χ	Χ	Χ
Exhaust Air Fan Air Flow Rate	Х	Χ	Х	Χ
Supply Fan Speed	Х	X	Х	X
Exhaust Fan Speed	Х	X	Х	X
Software Version Info	Х	X	Х	X
Operation Hours Counter	Х	X	Х	X
Digital Input 015 Status	-	_	Х	X



Digital Output 015 Status	_	_	Χ	X
Info Message 015 Status	Х	X	Х	Χ
Fault 031 Status	Χ	Χ	Χ	Χ

The list of parameters could be structured following the features that always include a certain group of parameters.

Each TYPE has to support every parameter that is marked in its column!

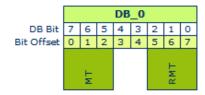
RORG	D2	VLD Telegram
FUNC	50	Heat Recovery Ventilation
TYPE	00	Type 0x00

Submitter: Glen Dimplex

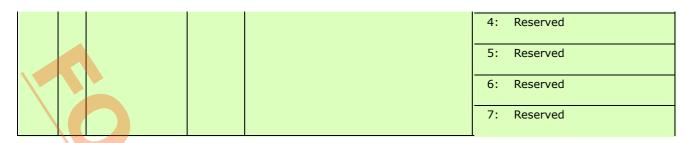
Telegram Definition: 'Ventilation Remote Transmission Request Message'

The 'Ventilation Remote Transmission Request Message' queries a particular status message from the heat-recovery ventilation unit. Thus status messages can be obtained at any time or at a higher update rate than the heartbeat rate, e.g. during commissioning.

Direction: Gateway --> Heat-recovery ventilation unit



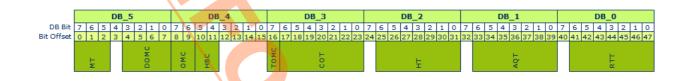
Offset	Size	Data	ShortCut	Description	Va	lid Range	Scale	Unit
Offset 0		Data Message Type	ShortCut MT		Va Enum 0: 1: 2:		remote n request control pasic statu	
					4: 5: 6: 7:	Reserved Reserved Reserved		
5	3	Not Used (= 0) Requested Message Type	RMT	Defines the message type, which is requested by the remote device	Enum 0: 1: 2:	Ventilation by Ventilation estatus Reserved Reserved		IS



Telegram Definition: 'Ventilation Control Message'

The 'Ventilation Control Message' changes the operating mode, the state of several actuators and a subset of control parameters.

Direction: Gateway --> Heat-recovery ventilation unit



Offset	Size	Data	ShortCut	Description	Valid Range	Scale Unit
Offset 0		Data Message Type		Description Defines the message type	Enum:	ote transmission trol c status
3		Not Used (= 0)			6: Reserved 7: Reserved	
4	4	Direct Operation Mode Control	DOMC	Selects ventilation mode/level	Enum: 0: Off 1: Level 1 2: Level 2 3: Level 3 4: Level 4 5: Reserved 6: Reserved 7: Reserved	
					7. Reserved	

					8:	Reserved
					9:	Reserved
					10:	Reserved
					11:	Automatic
					12:	Automatic on demand
					13:	Supply air only
					14:	Exhaust air only
					15:	no action (keep current ventilation mode/level)
8	2	Operation Mode	OMC	Selects the next resp. previous	Enum	:
		Control		available ventilation mode/level	0:	no action
					1:	select next operation mode (edge-trigger)
					2:	select previous operation mode (edge-trigger)
					3:	Reserved
10	2	Heat Exchanger	НВС	Manual override of automatic heat	Enum	
		Bypass Control		exchanger bypass control	0:	no action
					1:	close bypass (edge-trigger)
					2:	open bypass (edge-trigger)
					3:	Reserved
12	4	Not Used (= 0)			<u> </u>	1,000,100
16	1	Timer Operation	томс	Enables Timer Operation Mode,	Enum	
10		Mode Control	10110	i.e. a particular ventilation mode is activated for a defined time	0:	no action
					1:	start timer operation mode (edge-trigger)
17	7	CO2 Threshold	COT	Overrides CO2 threshold for CO2	Enum	
17	,	COZ TITICSTIOIU	COT	control in automatic mode		100: 0100 %
					0	100. 0100 %
					101	Reserved 126:
					127	
						configured in device)
24	1	Not Used (= 0)		0 11 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1		
25	7	Humidity Threshold	HT	Overrides humidity threshold for humidity control in automatic	Enum	
		THESHOLD		mode	0	100: 0100 %
						Reserved
					101	
					127	
						configured in device)
32	1	Not Used (= 0)				
33	7	Air Quality	AQT	Overrides air quality threshold for	Enum	
		Threshold		air quality control in automatic mode	0:	100: 0100 %
					101	Reserved
					127	
40	1	Not Used (= 0)				comigared in device)
41	7	Room	RTT	Overrides room temperature	Enum	
		temperature		threshold for room temperature	Litaiii	
		threshold		control mode	-63(63: -6363 °C
						33

				-64:	Default (use threshold configured in device)
--	--	--	--	------	---

Telegram Definition: 'Ventilation Basic Status Message'

The 'Ventilation Basic Status Message' provides current sensor values and internal control status information. It is triggered once at power-on and on particular value changes.

Additionally this message is available on request.

Direction: Heat-recovery ventilation unit --> Gateway



Offset	Size	Data	ShortCut	Description	Valid Range	Scale Unit
0	3	Message Type	MT	Defines the message type	Enum:	
					0: Ventila	tion remote
						nission request
					1: Ventila	tion control
					2: Ventila	tion basic status
					3: Ventila status	tion extended
					4: Reserv	red
					5: Reserv	red
					6: Reserv	red
					7: Reserv	red
3	1	Not Used (= 0)	•			
4	4	Operation Mode	OMS	Shows current Operation Mode Status	Enum:	
		Status			0: Off	
					1: Level	
					2: Level :	2
					3: Level	3
					4: Level	1
					5: Reserv	red
					6: Reserv	'ed
					7: Reserv	red
					8: Reserv	red
					9: Reserv	red
					10: Reserv	red
					11: Autom	atic
					12: Autom	atic on demand
					13: Supply	
					14: Exhau	
•						

					15:	Reserved
8	4	Not Used (= 0)			L -0.	
12	1	Safety Mode Status	SMS	Indicates if device is running in	Enum:	
				fireplace safety mode	0:	fireplace safety mode disabled
					1:	fireplace safety mode enabled
13	1	Heat Exchanger	HBS	Indicates heat exchanger bypass status	Enum:	
	/	Bypass Status			0:	bypass closed (heatrecovery active)
					1:	bypass opened (heatrecovery inactive)
14	1	Supply Air Flap Position	SFP	Supply Air Flap Position	Enum:	
		Position			0:	supply air flap closed
1 -	4	Fulsaviat Alla Eleva	FED	Fulcaset Air Flore Position	1:	supply air flap opened
15	1	Exhaust Air Flap Position	EFP	Exhaust Air Flap Position	Enum:	
		1 osition			0:	exhaust air flap closed
1.0	_	D.C. al Made	DMC	T. J	1:	exhaust air flap opened
16	1	Defrost Mode Status	DMS	Indicates if device is running in defrost mode, i.e. automatic defrosting of heat	Enum:	
		Status		exchanger is active	0:	defrost mode inactive
17	4	Cooling Date 11	CDC		1:	defrost mode active
17	1	Cooling Protection Status	CPS	Indicates if device is running in cooling protection	Enum:	
		Status		protection	0:	cooling protection mode inactive
					1:	cooling protection mode active
18	1	Outdoor Air Heater	OHS	Outdoor Air Heater Status	Enum:	
		Status			0:	inactive
					1:	active
19	1	Supply Air Heater	SHS	Supply Air Heater Status	Enum:	
		Status			0:	inactive
					1:	active
20	1	Drain Heater	DHS	Drain Heater Status	Enum:	
		Status			0:	inactive
					1:	active
21	1	Timer Operation	TOMS	Indicates timer operation mode status	Enum:	
		Mode Status			0:	timer operation mode inactive
					1:	timer operation mode active
22	1	Filter Maintenance Status	FMS	Filter Maintenance Status	Enum:	
		Status			0:	Maintenance not
					1:	required Maintenance required
					1.	ridincendrice required
23	1	Weekly Timer	WTPS	Indicates if weekly timer program is	Enum:	
		Program Status		active (i.e. if device is running according to configured program)	0:	weekly timer program disabled or not
					1:	configured weekly timer program
						active
24	1	Room Temperature	RTCS	Indicates room temperature control	Enum:	
		Control Status		status	0:	room temperature
						control inactive
					1:	room temperature control active
25	7		AQS1	Current air quality sensor 1	Enum:	
		1		measurement value	01	
					-	126: Reserved
					127	
32	1	Master/Slave Configuration	MSS	Indicates whether device is configured as master or slave unit	Enum:	
		Status		as master or slave unit	0:	Master
		Julius			1:	Slave

33	7	Air Quality Sensor 2	AQS2	Current air quality sensor 2 measurement value	101126: F	0100 % Reserved	_
40	7	Outdoor Air Temperature	OUTT	Current outdoor air temperature	-6463	-6463	°C
47	7	Supp <mark>ly Air</mark> Temperature	SPLYT	Current supply air temperature	-6463	-6463	°C
54	7	Indoor Air Temperature	INT	Current indoor air temperature	-6463	-6463	°C
61	7	Exhaust Air Temperature	EXHT	Current exhaust air temperature	-6463	-6463	°C
68	10	Supply Air Fan Air Flow Rate	SPLYFF	Current supply air fan air flow rate setpoint	01023	01023	m3/h
78	10	Exhaust Air Fan Air Flow Rate		Current exhaust air fan air flow rate setpoint	01023	01023	m3/h
88	12	Supply Fan Speed	SPLYFS	Current supply air fan speed	04095	04095	1/min
100	12	Exhaust Fan Speed	EXHFS	Current exhaust air fan speed	04095	04095	1/min

Telegram Definition: 'Ventilation Extended Status Message'

The 'Ventilation Extended Status Message' provides additional information, e.g. active failure information. It is triggered once at power-on and on particular value changes.

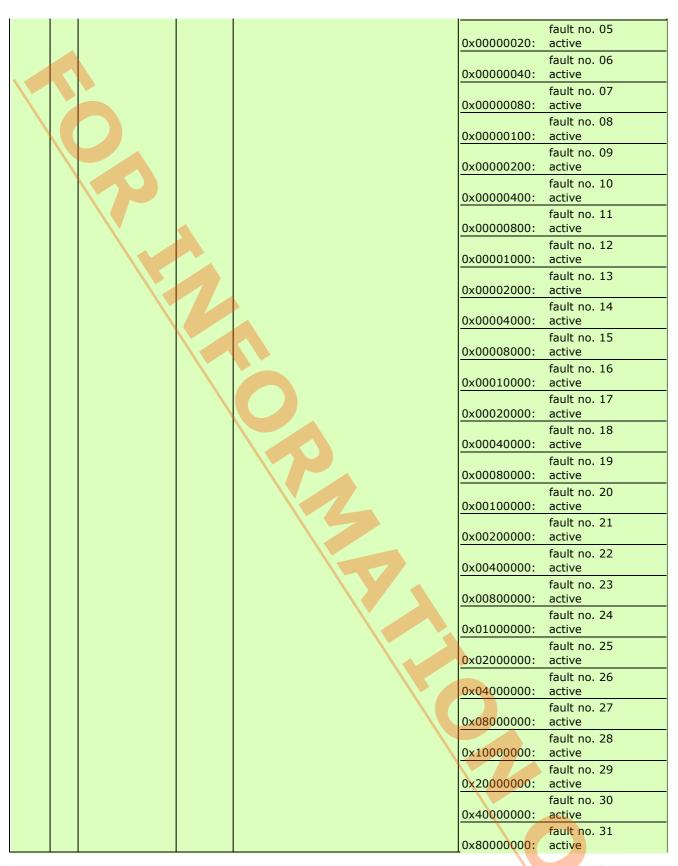
Additionally this message is available on request.

Direction: Heat-recovery ventilation unit --> Gateway

	DB_	_13		DB_12	D	B_11			OB_10		D	B_9	D	B_8		DB_7	
DB Bit	7 6 5 4	3 2 1 0	7 6 5	4 3 2 1 0	7 6 5	4 3 2 1	0 7	6 5	4 3 2	1 0	7 6 5 4	4 3 2 1 0	7 6 5 4	4 3 2 1 0	7 6 5 4	4 3 2 1 0	***
Bit Offset	0 1 2 3	4 5 6 7	8 9 10	11 12 13 14 1	5 16 17 18 1	9 20 21 22	2 23 24	25 26	27 28 29	30 31	32 33 34 3	5 36 37 38 39	40 41 42 4	3 44 45 46 47	48 49 50 5	1 52 53 54 55	`\
	MT		SVT				OHC					D	IS			DOS	1
	200							_ / _									
	<	DB_	6	DB	_5		DB_4	\rightarrow		DB_	3	DB_	2	DB_	1	DB_0	0
	DB Bit 7	DB_	6	DB	_ 5	7 6 5	DB_4 4 3 3	2 1 0	7 6	DB_	3 2 1 0	7 6 5 4	. 2	7 6 5 4 3	1 2 1 0	DB_0	0 2 1 0
		DB_ 7 6 5 4 6 57 58 59 6	6 3 2 1 0 61 62 6	DB 0 7 6 5 4 3 64 65 66 67	_ 5 3 2 1 0 68 69 70 71	7 6 5 727374	DB_4 4 3 2	2 1 (7 6 9 80 81 8	DB_ 5 4 3	3 3 2 1 0 4 85 86 87	7 6 5 4 88 89 90 91 9	2 3 2 1 0 2 93 94 95	7 6 5 4 3 96 97 98 99 10	1 3 2 1 0 00 101 102 103	7 6 5 4 3	2 1 0
	DB Bit 7	DB_ 7 6 5 4 6 57 58 59 6	3 2 1	DB 0 7 6 5 4 3 64 65 66 67	3 2 1 0 68 69 70 71	7 6 5 727374 MS	DB_4 4 3 2	2 1 0	7 6 9 80 81 8	DB_ 5 4 3	3 2 1 0 4 85 86 87	7 6 5 4 8889 90 91 9	.2 3 2 1 0 2 93 94 95 F	7 6 5 4 3 96 97 98 99 1	3 2 1 0 00 101 102 103	7 6 5 4 3	2 1 0

Offset	Size	Data	ShortCut	Description	Valid Range	Scale Unit
0	3	Message Type	МТ	Defines the message type	Enum: 0: Ventilation remote transmission request 1: Ventilation control 2: Ventilation basic status 3: Ventilation extended status 4: Reserved 5: Reserved 7: Reserved 04095 04095	
3	1	Not Used (= 0)				
4		Software Version Info	SVI	Shows Software Version Information	04095	04095 -
16		Operation Hours Counter	ОНС	Indicates device operation hours	0196605	0589815 h

					1
32	16	Digital Input	DIS	Indicates the current state of digital	Enum:
		015 Status		inputs 015 of the device	0x0001: input no. 00 active
				input assignment depends on device	0x0002: input no. 01 active
				variant and configuration	0x0004: input no. 02 active
				3,	0x0008: input no. 03 active
					0x0010: input no. 04 active
					0x0020: input no. 05 active
					0x0040: input no. 06 active
					0x0080: input no. 07 active
					0x0100: input no. 08 active
					0x0200: input no. 09 active
					0x0400: input no. 10 active
					0x0800: input no. 11 active
					0x1000: input no. 12 active
					0x2000: input no. 13 active
					0x4000: input no. 14 active
					0x8000: input no. 15 active
48	16	Digital Output	DOS	Indicates the current state of digital	Enum:
40	10	015 Status	003	outputs 015 of the device	
		25 Status		The state of the device	0x0001: output no. 00 active
				output assignment depends on device	0x0002: output no. 01 active
				variant and configuration	0x0004: output no. 02 active
					0x0008: output no. 03 active
					0x0010: output no. 04 active
					0x0020: output no. 05 active
					0x0040: output no. 06 active
					0x0080: output no. 07 active
					0x0100: output no. 08 active
					0x0200: output no. 09 active
					0x0400: output no. 10 active
					0x0800: output no. 11 active
					0x1000: output no. 12 active
					0x2000: output no. 13 active
					0x4000: output no. 14 active
					0x8000: output no. 15 active
64	16	Info Message	IMS	Indicates the current state of info	Enum:
		015 Status		message no. 015 generated by the	Ov0001 Linfo no 00 petivo
		omizo otatao			0x0001: info no. 00 active
		020 0		device	0x0001: info no. 00 active
		0.11.20 0.00.00			0x0002: info no. 01 active
					0x0002: info no. 01 active 0x0004: info no. 02 active
					0x0002: info no. 01 active 0x0004: info no. 02 active 0x0008: info no. 03 active
					0x0002: info no. 01 active 0x0004: info no. 02 active 0x0008: info no. 03 active 0x0010: info no. 04 active 0x0020: info no. 05 active
					0x0002: info no. 01 active 0x0004: info no. 02 active 0x0008: info no. 03 active 0x0010: info no. 04 active 0x0020: info no. 05 active 0x0040: info no. 06 active
					0x0002: info no. 01 active 0x0004: info no. 02 active 0x0008: info no. 03 active 0x0010: info no. 04 active 0x0020: info no. 05 active 0x0040: info no. 06 active 0x0080: info no. 07 active
					0x0002: info no. 01 active 0x0004: info no. 02 active 0x0008: info no. 03 active 0x0010: info no. 04 active 0x0020: info no. 05 active 0x0040: info no. 06 active 0x0080: info no. 07 active 0x0100: info no. 08 active
					0x0002: info no. 01 active 0x0004: info no. 02 active 0x0008: info no. 03 active 0x0010: info no. 04 active 0x0020: info no. 05 active 0x0040: info no. 06 active 0x0080: info no. 07 active 0x0100: info no. 08 active 0x0200: info no. 09 active
					0x0002: info no. 01 active 0x0004: info no. 02 active 0x0008: info no. 03 active 0x0010: info no. 04 active 0x0020: info no. 05 active 0x0040: info no. 06 active 0x0080: info no. 07 active 0x0100: info no. 08 active 0x0200: info no. 09 active 0x0400: info no. 10 active
					0x0002: info no. 01 active 0x0004: info no. 02 active 0x0008: info no. 03 active 0x0010: info no. 04 active 0x0020: info no. 05 active 0x0040: info no. 06 active 0x0080: info no. 07 active 0x0100: info no. 08 active 0x0200: info no. 09 active 0x0400: info no. 10 active 0x0800: info no. 11 active
					0x0002: info no. 01 active 0x0004: info no. 02 active 0x0008: info no. 03 active 0x0010: info no. 04 active 0x0020: info no. 05 active 0x0040: info no. 06 active 0x0080: info no. 07 active 0x0100: info no. 08 active 0x0200: info no. 09 active 0x0400: info no. 10 active 0x0800: info no. 11 active 0x1000: info no. 12 active
					0x0002: info no. 01 active 0x0004: info no. 02 active 0x0008: info no. 03 active 0x0010: info no. 04 active 0x0020: info no. 05 active 0x0040: info no. 06 active 0x0080: info no. 07 active 0x0100: info no. 08 active 0x0200: info no. 09 active 0x0400: info no. 10 active 0x0800: info no. 11 active 0x1000: info no. 12 active 0x2000: info no. 13 active
					0x0002: info no. 01 active 0x0004: info no. 02 active 0x0008: info no. 03 active 0x0010: info no. 04 active 0x0020: info no. 05 active 0x0040: info no. 06 active 0x0080: info no. 07 active 0x0100: info no. 08 active 0x0200: info no. 09 active 0x0400: info no. 10 active 0x0800: info no. 11 active 0x1000: info no. 12 active 0x2000: info no. 13 active 0x4000: info no. 14 active
80	37		FQ	device	0x0002: info no. 01 active 0x0004: info no. 02 active 0x0008: info no. 03 active 0x0010: info no. 04 active 0x0020: info no. 05 active 0x0040: info no. 06 active 0x0080: info no. 07 active 0x0100: info no. 08 active 0x0200: info no. 09 active 0x0400: info no. 10 active 0x0800: info no. 11 active 0x1000: info no. 12 active 0x2000: info no. 13 active 0x4000: info no. 14 active 0x8000: info no. 15 active
80	32	Fault 031	FS	Indicates the current state of fault no.	0x0002: info no. 01 active 0x0004: info no. 02 active 0x0008: info no. 03 active 0x0010: info no. 04 active 0x0020: info no. 05 active 0x0040: info no. 06 active 0x0080: info no. 07 active 0x0100: info no. 08 active 0x0200: info no. 09 active 0x0400: info no. 10 active 0x0800: info no. 11 active 0x1000: info no. 12 active 0x2000: info no. 13 active 0x4000: info no. 14 active 0x8000: info no. 15 active
80	32		FS	device	0x0002: info no. 01 active 0x0004: info no. 02 active 0x0008: info no. 03 active 0x0010: info no. 04 active 0x0020: info no. 05 active 0x0040: info no. 06 active 0x0080: info no. 07 active 0x0100: info no. 08 active 0x0200: info no. 09 active 0x0400: info no. 10 active 0x1000: info no. 11 active 0x1000: info no. 12 active 0x2000: info no. 13 active 0x4000: info no. 14 active 0x8000: info no. 15 active Enum:
80	32	Fault 031	FS	Indicates the current state of fault no.	0x0002: info no. 01 active 0x0004: info no. 02 active 0x0008: info no. 03 active 0x0010: info no. 04 active 0x0020: info no. 05 active 0x0040: info no. 06 active 0x0080: info no. 07 active 0x0100: info no. 08 active 0x0200: info no. 09 active 0x0400: info no. 10 active 0x1000: info no. 11 active 0x1000: info no. 12 active 0x2000: info no. 13 active 0x4000: info no. 14 active 0x8000: info no. 15 active Enum: fault no. 00 0x00000001: active
80	32	Fault 031	FS	Indicates the current state of fault no.	0x0002: info no. 01 active 0x0004: info no. 02 active 0x0008: info no. 03 active 0x0010: info no. 04 active 0x0020: info no. 05 active 0x0040: info no. 06 active 0x0080: info no. 07 active 0x0100: info no. 08 active 0x0200: info no. 09 active 0x0400: info no. 10 active 0x1000: info no. 11 active 0x1000: info no. 12 active 0x2000: info no. 13 active 0x4000: info no. 14 active 0x8000: info no. 15 active Enum: fault no. 00 0x000000001: active
80	32	Fault 031	FS	Indicates the current state of fault no.	0x0002: info no. 01 active 0x0004: info no. 02 active 0x0008: info no. 03 active 0x0010: info no. 04 active 0x0020: info no. 05 active 0x0040: info no. 06 active 0x0080: info no. 07 active 0x0100: info no. 08 active 0x0200: info no. 09 active 0x0400: info no. 10 active 0x0800: info no. 11 active 0x1000: info no. 12 active 0x2000: info no. 13 active 0x4000: info no. 14 active 0x8000: info no. 15 active Enum: fault no. 00 0x00000001: active fault no. 01
80	32	Fault 031	FS	Indicates the current state of fault no.	0x0002: info no. 01 active 0x0004: info no. 02 active 0x0008: info no. 03 active 0x0010: info no. 04 active 0x0020: info no. 05 active 0x0040: info no. 06 active 0x0080: info no. 07 active 0x0100: info no. 08 active 0x0200: info no. 09 active 0x0400: info no. 10 active 0x1000: info no. 11 active 0x1000: info no. 12 active 0x2000: info no. 13 active 0x4000: info no. 14 active 0x8000: info no. 15 active Enum: fault no. 00 0x000000001: active
80	32	Fault 031	FS	Indicates the current state of fault no.	0x0002: info no. 01 active 0x0004: info no. 02 active 0x0008: info no. 03 active 0x0010: info no. 04 active 0x0020: info no. 05 active 0x0040: info no. 06 active 0x0080: info no. 07 active 0x0100: info no. 08 active 0x0200: info no. 09 active 0x0400: info no. 10 active 0x0800: info no. 11 active 0x1000: info no. 12 active 0x2000: info no. 13 active 0x4000: info no. 14 active 0x8000: info no. 15 active Enum: fault no. 00 0x00000001: active fault no. 01 0x00000002: active fault no. 02
80	32	Fault 031	FS	Indicates the current state of fault no.	0x0002: info no. 01 active 0x0004: info no. 02 active 0x0008: info no. 03 active 0x0010: info no. 04 active 0x0020: info no. 05 active 0x0040: info no. 06 active 0x0080: info no. 07 active 0x0100: info no. 08 active 0x0200: info no. 09 active 0x0400: info no. 10 active 0x0800: info no. 11 active 0x1000: info no. 12 active 0x2000: info no. 13 active 0x4000: info no. 14 active 0x8000: info no. 15 active Enum: fault no. 00 0x00000001: active fault no. 01 0x000000004: active
80	32	Fault 031	FS	Indicates the current state of fault no.	0x0002: info no. 01 active 0x0004: info no. 02 active 0x0008: info no. 03 active 0x0010: info no. 04 active 0x0020: info no. 05 active 0x0040: info no. 06 active 0x0080: info no. 07 active 0x0100: info no. 08 active 0x0200: info no. 09 active 0x0400: info no. 10 active 0x0800: info no. 11 active 0x1000: info no. 12 active 0x2000: info no. 13 active 0x4000: info no. 14 active 0x8000: info no. 15 active Enum: fault no. 00 0x00000001: active fault no. 01 0x000000004: active fault no. 02 0x000000004: active
80	32	Fault 031	FS	Indicates the current state of fault no.	0x0002: info no. 01 active 0x0004: info no. 02 active 0x0008: info no. 03 active 0x0010: info no. 04 active 0x0020: info no. 05 active 0x0040: info no. 06 active 0x0080: info no. 07 active 0x0100: info no. 08 active 0x0200: info no. 09 active 0x0400: info no. 10 active 0x1000: info no. 11 active 0x1000: info no. 12 active 0x2000: info no. 13 active 0x4000: info no. 14 active 0x8000: info no. 15 active Enum: fault no. 00 0x00000001: active fault no. 01 0x000000004: active fault no. 02 0x00000008: active



RORG	D2	VLD Telegram
FUNC	50	Heat Recovery Ventilation
TYPE	01	Type 0x01 (description: see table)

See profile: D2-31-00

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D2-A0: Standard Valve

RORG	D2	VLD Telegram
FUNC	A0	Standard Valve
TYPE	01	Valve Control (BI-DIR)

Submitter: Afriso / EnOcean

Description:

Radio operated valve control with feedback message. Valve is controlled through the air interface to be opened or closed. The valve reports the actual status after finishing the determined operation.

Data exchange

Direction: bidirectional

Addressing: addressed (inbound) and broadcast (outbound)

Communication trigger: event- & time-triggered Trigger event: position of valve has changed

Teach-in method: UTE

DIRECTION-1 = Outbound (water valve to the controller)

Description: Valve reports its status. Report is sent after operation was executed or as a heartbeat.

DIRECTION-2 = Inbound (controller to the water valve)

Description: Operational command to the valve. After this request a feedback response will be transmitted, once the

operation is finished.

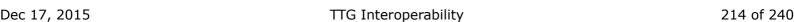
A "no change"-command will also be followed by a feedback response. Therefore, it can be used as a status request.

DIRECTION-1

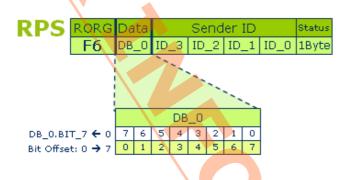
Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit
0	6	Not Used	(= 0)		
6	2	Feedback	FDB	Return	Enum:
					0b00: Not defined
					0b01: Closed
					0b10: Opened
					0b11: Not defined

DIRECTION-2

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	6	Not Use	d (= 0)				
6	2	Request	REQ	Request to operate the valve	Enum:		
					0b00: No change (requ	est of feedl	back)
					0b01: Request to close	valve	
					0b10: Request to open	valve	
					0b11: Request to close	valve	



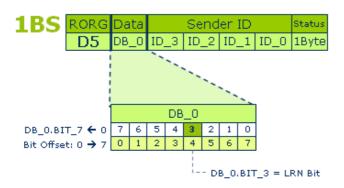
- 3) Appendix
- 3.1) RPS Teach-in



The RPS telegram can only send data and has no special telegram modification to teach-in the device. Therefore, the teach-in procedure takes place manually on the actuator/controller through a normal data telegram. The EEP profile must be manually supplied to the controller per sender ID.

In learn mode, the receiving actuator reduces the input sensitivity in order to fade out weakly received data telegrams. This helps avoid inadvertently teaching-in sensors.

3.2) 1BS Teach-in



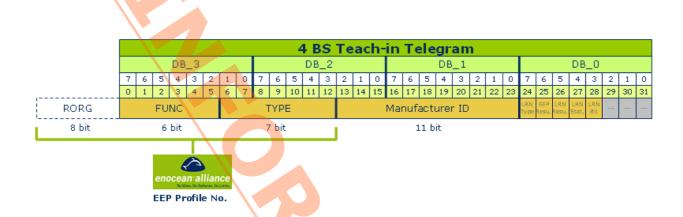
The 1BS telegram has its own teach-in telegram, which can signal the teach-in command through the DB_0.BIT_3 data bit.

Offset Size Bitrange Data Valid Range Scale Unit

4	1	DB0.3	LRN Bit	Enum:	
				0:	Teach-in telegram
				1:	Data telegram

Here, an EEP profile must also be manually allocated per sender ID.

3.3) 4BS Teach-in



The 4BS telegram also has its own teach-in telegram, however with more teach-in variations:

Variation 1

The profile-less unidirectional teach-in procedure functions according to the same principle as the 1BS telegram: if the data bit is DB_0.BIT_3 = 0, then a teach-in telegram is sent. This includes the 'LRN TYPE' DB_0.BIT_7 = 0 data bit. Then no EEP profile identifier and no manufacturer ID are transferred.

Offset	Size	Bitrange	Data		Valid Range	Scale	Unit	
24	1	DB0.7	LRN Type	Enum:				
				0:	telegram without EEP	and Manufa	cturer ID	
28	1	DB0.3	LRN Bit	Enum:				
				0:	Teach-in telegram			
				1:	Data telegram			

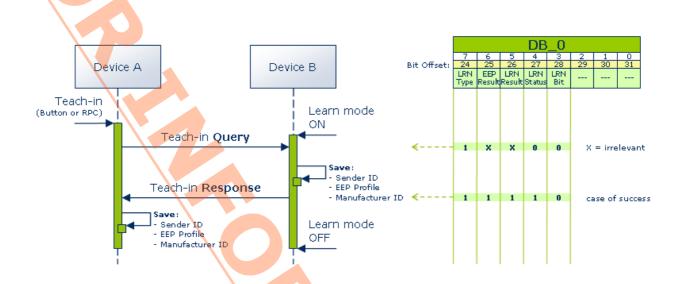
Variation 2

For the unidirectional profile teach-in procedure, it is preferred in opposite to variation 1), as the teach-in telegram contains both the complete EEP number and the manufacturer ID. The device is therefore clearly identifiable as ready-to-use and can be securely executed in a complex system environment or by foreign systems. In this case, the 'LRN TYPE' data bit is $DB_0.BIT_7 = 1$.

Size	Bitrange	Data		Valid Range	Scale	Unit
1	DB0.7	LRN Type	Enum	:		
			1:	telegram with EEP num	nber and Manufac	turer ID
1	DB0.3	LRN Bit	Enum	:		
			0:	Teach-in telegram		
			1:	Data telegram		
	1	1 DB0.7	1 DB0.7 LRN Type	1 DB0.7 LRN Type Enum 1: 1 DB0.3 LRN Bit Enum 0:	1 DB0.7 LRN Type Enum: 1: telegram with EEP num 1 DB0.3 LRN Bit Enum: 0: Teach-in telegram	1 DB0.7 LRN Type Enum: 1: telegram with EEP number and Manufact 1 DB0.3 LRN Bit Enum: 0: Teach-in telegram

Variation 3

During the bidirectional teach-in procedure, further bits are required from the DB_0, in order to develop the mutual teach-in between two communication partners. For this, the procedure is made up of 2 teach-in telegrams, which are exchanged on both sides. The following UML diagram is used to illustrate this:

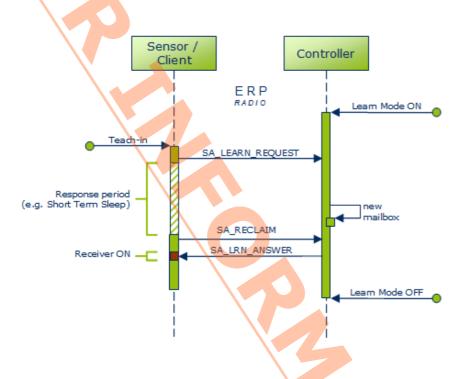


Offset	Size	Bitrange	Data		Valid Range	Scale	Unit
24	1	DB0.7	LRN Type	Enum			
				0:	telegram without EEP a	nd Manufacturer	· ID
				1:	telegram with EEP num	ber <mark>an</mark> d Manufac	cturer ID
25	1	DB0.6	EEP Result	Enum			
				0:	EEP not supported		
				1:	EEP supported		
26	1	DB0.5	LRN Result	Enum	:		
				0:	Sender ID deleted/not	stored	
				1:	Sender ID stored		
27	1	DB0.4	LRN Status	Enum	:		
				0:	Query		
				1:	Response		
28	1	DB0.3	LRN Bit	Enum	:		
				0:	Teach-in telegram		
				1:	Data telegram		

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3.4) Smart Ack Teach-in (without repeater)

Under Smart Ack (SA), the teach-in procedure is more complex as, alongside the SA client and SA controller, a Postmaster must also be established to prepare a mailbox for each taught-in SA client. The Postmaster is normally found in the controller. If a repeater is installed, then a postmaster is set up there.

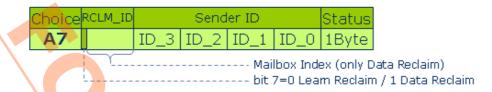


After the learn mode is activated on the controller, the teach-in procedure can be started on the client. The client sends an SA_LEARN_REQUEST telegram:

F	RORG	Req.	Manuf.ID	EE	P (3 by	te)	RSSI	I Repeater ID			1	Sender ID				Status	СНСК
	C6	5 bit	11 bit	RORG	FUNC	TYPE	dBm	ID_3	ID_2	ID_1	ID_0	ID_3	ID_2	ID_1	ID_0	1 Byte	1 Byte
	F	Request Code	t														

Data	Value	Description
Request Code	0b11111	Default value – send by sensor
Manufacturer ID	0bnnnnnnnnnn	Corresponding to the teach-in sensor
EEP No.	0xnnnnn	RORG, FUNC, TYPE
RSSI	0x00	0 = Without repeater
Repeater ID	0x00000000	0 = Without repeater
Sender ID	0xnnnnnnn	Chip ID of sensor for teach-in
Status	0x0F	0F = no repeating permitted
CHCK	0xnn	Checksum

During the 'response period' in the SA client, which is always 550 ms during the teach-in, the controller creates a new mailbox in its postmaster and leaves its first message there with an OK receipt. This entry is requested from the postmaster by the SA client with an SA_RECLAIM 'Learn' telegram:



Data	Value	Description
Message Index	0b0	Bit 7: 0 = Learn Reclaim
Sender ID	0xnnnnnnn	Chip ID of sensor for teach-in
Status	0x0F	OF = no repeating desired
CHCK	0xnn	Checksum

The final telegram sent to the SA client, SA_LRN_ANSWER, contains the 'Learn Acknowledge' message from the mailbox that the teach-in procedure has been carried out successfully:

Smart Ack Learn Answer (Learn Acknowledge)

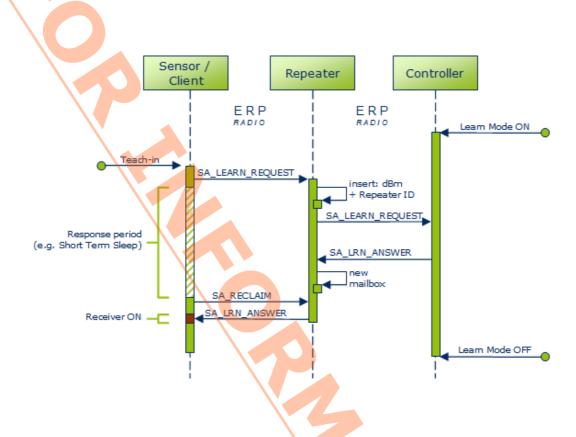
R	.ORG	RORG-EN	Index	Respor	se time	Ack	с.	Mailbox		not use	d		Postma	ster ID			Contro	oller ID		Status	CHCK
	0	1	2	3	4	5		6	7	8	9	10	11	12	13	14	15	16	17	18	19
	A6	C7	02							-	-	ID_3	ID_2	ID_1	ID_0	ID_3	ID_2	ID_1	ID_0		

Data	Value	Description
RORG	0xA6	A6 = ADR Telegram
RORG-EN	0xC7	RORG encapsulated / C7 = SA_LRN_ANSWER
Index	0x02	Message Index; 02 = Learn Acknowledge
Response time		Response time for Smart Ack Client in ms in which the controller can prepare the data and send it to the postmaster (max. value $550 \text{ ms} = 0x0226$)
Acknowledge code	0x00	First Learn In successful
Mailbox index	0xnn	Index no. of the assigned mailbox
Postmaster ID	0xnnnnnnn	Device ID of the Post master candidate
Controller ID	0xnnnnnnn	Device ID of the assigned controller
Status	0x0F	OF = no repeating permitted
CHCK	0xnn	Checksum

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3.5) Smart Ack Teach-in (with repeater)



If a repeater comes into operation, the SA_LEARN_REQUEST telegram sent by the SA client (with an EEP No., Manufacturer ID, Sender ID) is completed on the repeater with the RSSI value (in dBm) and the Repeater ID, and sent to the controller.

RORO	Req.	Manuf.ID	EE	P (3 by	te)	RSSI		Repea	ter ID	1		Send	er ID		Status	CHCK
C6	5 bit	11 bit	RORG	FUNC	TYPE	dBm	ID_3	ID_2	ID_1	ID_0	ID_3	ID_2	ID_1	ID_0	1 Byte	1 Byte
	Reques Code	t							//							

Data	Value	Description
Request Code	0b11111	Default value – send by sensor
Manufacturer ID	0bnnnnnnnnnnn	Corresponding to the teach-in sensor
EEP No.	0xnnnnn	RORG, FUNC, TYPE
RSSI	0xnn	Value added from repeater
Repeater ID	0xnnnnnnn	Device ID repeater
Sender ID	0xnnnnnnn	Chip ID of sensor for teach-in
Status	0x0F	0F = no repeating permitted
СНСК	0xnn	Checksum

From the reception strength of the RSSI, the controller can recognise which repeater is best for the task of postmaster. In the meantime, the SA client will be in its 'response period'.

The sent addressed telegram **SA_LRN_ANSWER** with the message 'Learn Reply' by the controller to the repeater ensures that the postmaster is activated and a mailbox is created.

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	_																
ROR	G R	eq.	Manuf.ID	EE	EEP (3 byte) R		RSSI	Repeater ID				Sender ID				Status	CHCK
_C6	5	bit	11 bit	RORG	FUNC	TYPE	dBm	ID_3	ID_2	ID_1	ID_0	ID_3	ID_2	ID_1	ID_0	1 Byte	1 Byte
		quest ode															

Data	Value	Description						
RORG	0xA6	A6 = ADR Telegram						
RORG-EN	0xC7	RORG encapsulated / C7 = SA_LRN_ANSWER						
Index	0x01	Message Index; 01 = Learn Reply						
Response time		Response time for Smart Ack Client in ms in which the controller can prepare the data and send it to the postmaster (max. value $550 \text{ ms} = 0x0226$)						
Acknowledge code	0x00	First Learn In successful						
Sender ID	0xnnnnnnn	Chip ID of sensor to be teach-in						
Postmaster ID	0xnnnnnnn	Device ID of the Post master candidate						
Controller ID	0xnnnnnnn	Device ID of the assigned controller						
Status	0x0F	0F = no repeating permitted						
CHCK	0xnn	Checksum						

Also, a mailbox is created for the SA client, where an initial entry with an OK message is left. This information is requested by the SA client from the repeater's postmaster with the SA_RECLAIM 'Learn' telegram.

Choice	RCLM_ID		Send	ler ID		Status	
A7		ID_3	ID_2	ID_1	ID_0	1Byte	
							Oata Reclaim) n / 1 Data Reclaim

Data	Value	Description					
Message Index	0b0	Bit 7: 0 = Learn Reclaim					
Sender ID	0xnnnnnnn	Chip ID of sensor for teach-in					
Status	0x0F	0F = no repeating desired					
CHCK	0xnn	Checksum					

The final telegram sent to the SA client, SA_LRN_ANSWER, contains the 'Learn Acknowledge' message from the mailbox that the teach-in procedure has been carried out successfully:

Smart Ack Learn Answer (Learn Acknowledge)

	RORG	RORG-EN	Index	Respor	se time	Ack C.	Mailbox		not used	I		Postma	ster ID			Contro	oller ID		Status	СНСК
Г	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19
	A6	C7	02					-	-	-	ID_3	ID_2	ID_1	ID_0	ID_3	ID_2	ID_1	ID_0		

Data	Value	Description
RORG	0xA6	A6 = ADR Telegram
RORG-EN	0xC7	RORG encapsulated / C7 = SA_LRN_ANSWER
Index	0x02	Message Index; 02 = Learn Acknowledge
Response time		Response time for Smart Ack Client in ms in which the controller can prepare the data and send it to the postmaster (max. value $550 \text{ ms} = 0x0226$)
Acknowledge code	0x00	First Learn In successful
Mailbox index	0xnn	Index no. of the assigned mailbox
Postmaster ID	0xnnnnnnn	Device ID of the Post master candidate
Controller ID	0xnnnnnnn	Device ID of the assigned controller
Status	0x0F	0F = no repeating permitted

CHCK 0xnn Checksum

3.6) UTE - Universal Uni- and Bidirectional Teach-in

General

Up to now there are teach-in procedures available for:

- RPS communication (EnOcean ID + rocker/channel information, unidirectional)
- 1BS communication (LRN telegram, w/o EEP and MID, unidirectional)
- 4BS communication (LRN telegram, w FUNC+TYPE and MID, unidirectional)
- 4BS communication (LRN telegram, w FUNC+TYPE and MID, bidirectional)
- SmartACK communication (self powered devices, bidirectional)

For uni- and bidirectional EEP communication that does not fit into SmartACK communication principles but is based on e.g. MSC and VLD messages no teach-in procedure is defined so far.

Therefore, this document proposes a universal teach-in procedure that allows handling of teach-in and teach-out requirements for EEP based communication of all different RORG. This proposal shall be understood as an alternative to SmartACK teach-in for devices where SmartACK is not applicable.

RORG to be used: OxD4 Universal Teach-in, EEP based (UTE)

FUNC and TYPE shall be represented as 8bit parameters, both with a value range from 0x00 ... 0xFF. This aligns UTE with the EEP representation defined for SmartACK teach-in.

REMARK 1:

Even though the proposed Universal Tech-In Procedure is able to cover EEPs based on RPS, 1BS and 4BS messages as well, it is not intended to replace the existing RPS, 1BS and 4BS teach-in / teach-out procedures for unidirectional and the existing 4BS teach-in / teach-out procedures for bidirectional communication.

However, it is recommended that with the acceptance of the proposed Universal Tech-In Procedure all new bidirectional 4BS applications shall use it for teach-in and teach-out as well.

REMARK 2:

The proposed Universal Tech-In Procedure is dedicated to EEP based EnOcean communication. It does neither compete with nor shall it interfere with the tech-in process of the Generic EnOcean Communication.

Communication - Principles and Definitions

BIDIRECTIONAL EEP-BASED COMMUNICATION

Bidirectional EnOcean communication means a point-to-point communication relationship between two enabled EnOcean devices. It requires all parties involved to know the unique EnOcean ID of their partners. Such point-to-point communication relationship is established with the completion of a successful teach-in process and it is deleted with the completion of a successful teach-out process.

To get a maximum reliable teach-in process with a minimum consumption of energy and resources, a simple query response mechanism is used: the device that is intended to be taught-in broadcasts a query message and gets back an addresses response message, containing its own EnOcean ID as the transmission target address.

In case there is more than one device ready to accept teach-in query messages at the same time and within the same radio range, the device with the quickest response time will be accepted by the device to be taught-in. Second and further devices will respond as well but they will not be accepted by the device to be taught-in. This will result in a configuration situation that is common to today's EEP based unidirectional teach-in processes.

UNIDIRECTIONAL EEP-BASED COMMUNICATION

Unidirectional EnOcean communication means a point-to-multipoint communication relationship between enabled EnOcean devices. In this case of broadcasting the device to be taught-in to other devices does not know the unique EnOcean ID of those communication partners.

The proposed Universal Teach-In Procedure supports unidirectional EnOcean communication thru related configuration bits in the query message.

However, for specific applications – e.g. configuration feedback - it is also possible to combine a bidirectional teach-in process with a unidirectional EEP based communication during the regular operation of a device.

EEP Teach-In Query - UTE Message (Broadcast / CMD: 0x0)

This message is sent by the EEP based EnOcean device that is intended to be taught-in to another device (which has been set into LRN-mode before either manually or thru a ReMan command).

Response Timing:

If a response is expected it shall be received within a maximum of 700ms from the time of transmission of this message. In case no such response is received within this time frame the query action shall be treated as completed with negative result. If no response is expected, each query action has to be treated as completed with positive result.

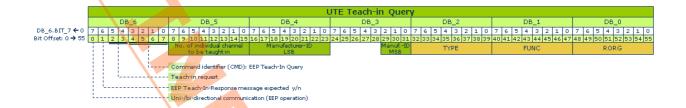


TABLE OF 7 BYTE PAYLOAD:

Offset	Size	Bitrange	Value	Description
0	1	DB6.7	0b0	Unidirectional communication (EEP operation)
11 11	=	" "	0b1	Bidirectional communication (EEP operation)
1	1	DB6.6	0b0	EEP Teach-In-Response message expected
" "	" "	" "	0b1	No EEP Teach-In-Response message expected
2	2	DB6.5 DB6.4	0b00	Teach-in request
11 11	=	" "	0b01	Teach-in deletion request
11 11	=	" "	0b10	Teach-in or deletion of teach-in, not specified
11 11	=	" "	0b11	Not used
4	4	DB6.3 DB6.0	0x0	Command identifier (CMD) / 0x0: EEP Teach-In Query
8	8	DB5.7 DB5.0	0x00 0xFE	Number of individual channel to be taught in
11 11	=	" "	0xFF	Teach-in of all channels supported by the device
16	8	DB4.7 DB4.0	MID (8LSB)	Manufacturer-ID (8LSB)
24	5	DB3.7 DB3.3	ı	Do not use
29	3	DB3.2 DB3.0	MID (3MSB)	Manufacturer-ID (3MSB)
32	8	DB2.7 DB2.0	TYPE	TYPE of EEP [0x00 0xFF]
40	8	DB1.7 DB1.0	FUNC	FUNC of EEP [0x00 0xFF]
48	8	DB0.7 DB0.0	RORG	RORG of EEP [0x00 0xFF]

EEP Teach-In Response - UTE Message (Addressed / CMD: 0x1)

This message is the reply to an EEP Teach-In Query message. It is sent by the EEP based EnOcean device that has been set into LRN-mode before (either manually by HMI or thru a ReMan command).

Response Timing:

If a response is requested this message shall be sent within a maximum of 500ms from the time of reception of the EEP Teach-In Query message. This limit shall give sufficient time to decide on the teach-in request and answer accordingly (e.g. when requests need to be processes by data base systems connected asynchronously).

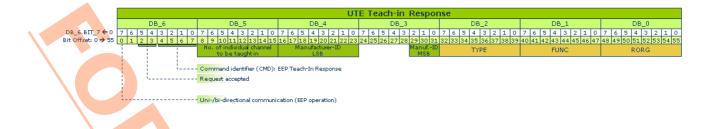
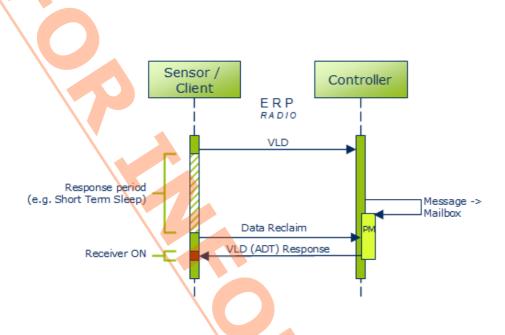


TABLE OF 7 BYTE PAYLOAD:

Offset	Size	Bitrange	Value	Description
0	1	DB6.7	0b0	Unidirectional communication (EEP operation)
11 11	11 11	" "	0b1	Bidirectional communication (EEP operation)
1	1	DB6.6	-	Not used
2		DB6.5 DB6.4	0b00	Request not accepted, general reason
11 11	" "	" "	0b01	Request accepted, teach-in successful
11 11	" "	" "	0b10	Request accepted, deletion of teach-in successful
11 11	11 11	п п	0b11	Request not accepted, EEP not supported
4	-	DB6.3 DB6.0	0x1	Command identifier (CMD) / 0x1: EEP Teach-In Response
8		DB5.7 DB0.0		Same structure as Teach-In Query message (EEP, MID and channel of requesting device is echoed back)

3.7) Smart Ack: functional principle (without repeater)



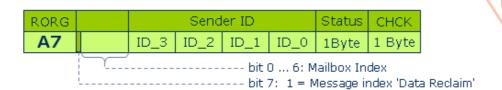
Smart Ack is a bidirectional communication protocol between a self-powered device and a line-powered controller. Data transmission in both directions is controlled by the sensor/client, as the limited energy budget requires an exact synchronization of the sent and the received messages. This pre-defined time interval allows a very short activation of the energy-intensive receiver electronics on the client.

If the teach-in procedure has already taken place as in Chapter 'Smart Ack Teach-in procedure' and the two devices already 'know each other', communication always takes place as following under Smart Ack:

The client sends its message over a VLD telegram to the controller (Manufacturer ID = optional).

VLD									
RORG	Manufacturer ID	Variable data			Send	er ID		Status	CRC8
D2	1,5 byte	1 12,5 bytes		ID_3	ID_2	ID_1	ID_0	1 byte	1 byte

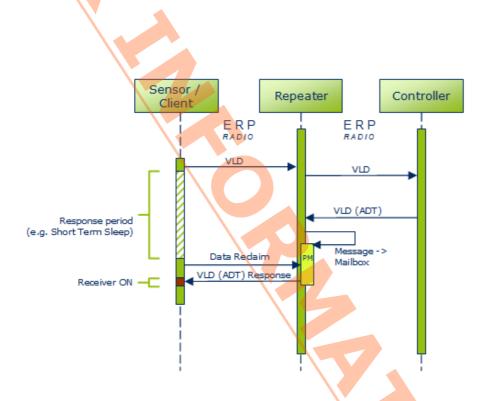
Finally, the message is processed in the controller, or forwarded to an external micro-controller over the serial interface for each use case. During the intervening period, the client is in the 'response period', which is frequently connected to an energy saving measure (like 'Short Term Sleep'). The length of this time period is agreed during the teach-in procedure between the devices as 'response time'. The feedback defined for the client is deposited in the mailbox of the postmaster (PM). When the client is active again, it requests this message containing the Smart Ack telegram DATA_RECLAIM from the responsible postmaster.



Finally, the receiver part of the client is activated and the message sent by the postmaster is accepted. In this case the VLD telegram is sent encapsulated as ADT telegram (= addressed).

	ADT / \	/LD												
4	RORG	RORG-EN	Manufacturer ID	Variable data		Destina	tion ID			Send	er ID		Status	CRC8
	A6	D2	1,5 byte	1 7,5 bytes	ID_3	ID_2	ID_1	ID_0	ID_3	ID_2	ID_1	ID_0	1 byte	1 byte

3.8) Smart Ack: functional principle (with repeater)



If a repeater is used, it takes over the task of the postmaster after the teach-in procedure. Hence, the client cannot view under operating conditions whether it is communicating directly with a controller or with a repeater.

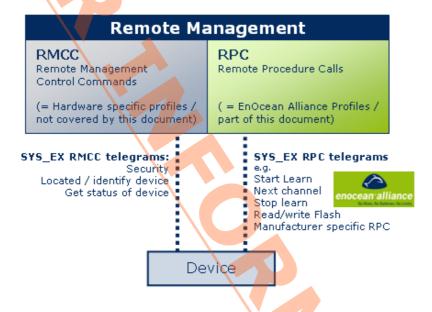
The VLD telegram of the client is forwarded by the repeater 1:1 in the direction of the controller. The feedback is transferred in the form of an addressed telegram (containing Repeater ID) to the postmaster of the repeater and stored in the mailbox.

The client then turns to the repeater with its 'Data Reclaim', instead of turning to the controller, and requests the response message from the postmaster.

EEP 2.6.4 Specification

3.9) Remote Management / RPC

Remote Management allows EnOcean devices to be configured and maintained over the air or via a serial interface. For instance sensor or switch IDs can be stored or deleted from already installed actuators or gateways that are hard to access. There is a remote management library available for Dolphin based products.



Remote management is divided into two function groups:

RMCCs are mandatory features; they are permanently defined and they have overlapping tasks. They cannot be modified devicespecifically and are therefore, not an integral part of this description.

RPCs cover optional and manufacturer-specific features, and they have a flexible number of functionalities that can be used for numerous devices. If new device properties are mapped, RPCs can be extended correspondingly. To keep the RPCs interoperable, it is in the interest of the EnOcean Alliance to standardize these procedures.

The RPCs available today with their SYS_EX structures do not have any data-technical commonalities with EEP, but are to be handled the same way in future within the framework of coordination measures.

Structure of SYS_EX for RPC

SYS_EX telegrams for RPCs are generally encapsulated in an ADT telegram (RORG = A6) and are sent addressed as such.

ADT / SYS_EX / RPC

RORG	RORG-EN			Destina							Status		
A6	C5	x bytes	ID_3	ID_2	ID_1	ID_0	ID_3	ID_	2	ID_1	ID_0	1 byte	1 byte

In the following section the SYS_EX data is described in detail. Note that Remote Management RPC commands are composed of several telegrams. That means SYS_EX data is than merged in one data block. The next section describes this datablock in detail.

For further details refer to the specification Remote Management, V1.7, Dec 16, 2010, released by EnOcean GmbH www.enocean.com/fileadmin/redaktion/pdf/tec_docs/RemoteManagement.pdf, please.

Title RPC - Remote learn

Function code	0x201
Manufacturerid	0x7FF
Datalength	0x04
Broadcast	YES
Addressable	YES
Answer	NO

Offset	Size	Data	Description	Valid I	Range	Scale	Unit
0	24		Determines the device type to learn in, all other devices learn telegrams are ignored. To ignore EEP controll the mask bits has to be set to 0)				
24	8	Flag	learn flag, determines different behaviour of the learn procedure	0x00:	RESERV Start le		
				0x02:	Next ch		
				0x04:	simple l	CK - Star learn mo	de
				0x05:		CK - Star ed learn	rt
				0x06:		CK - Sto	р

Title	RPC - Remote flash write
Function code	0x203
Manufacturerid	0x7FF
Datalength	0x04 + N
Broadcast	YES
Addressable	YES
Answer	NO

Using this command the flash of a device can be written.

Offset	Size	Data	Description
0	16	Flash Memory Address	Destination where the data should be stored
16	16	Number of Bytes	Number of bytes to be transfered and written to the flash
32	N*8	Data	data to be transfered and written to the flash

Title	RPC - Remote flash read
Function code	0x204
Manufacturerid	0x7FF
Datalength	0x04
Broadcast	NO
Addressable	YES
Answer	YES

Using this command the flash can be read from the application. The data requested data area transmitted in RPC telegrams.

l	Offset	Size	Data	Description
	16	16	Number of Bytes	Number of bytes to be transfered and written to the flash

Title	RPC - Remote flash read answer		
Function code	0x804		
Manufacturerid	0x7FF		
Datalength	N		
Broadcast	NO		
Addressable	YES		
Answer	NO		

Offset	Size	Data	Description
0	N*8	Data	data read from flash

Title	RPC - SmartACK read settings
Function code	0x205
Manufacturerid	0x7FF
Datalength	1
Broadcast	NO
Addressable	YES
Answer	YES

Using this command the SmartACK settings and learn tables can be read from the device. The Setting type filled determines what type of data is requested. The data requested data area transmitted in RPC telegrams.

Offset	Size	Data	Description	Va	alid Range	Scale	Unit	
0	8 >Setting type of settings to read		Enum: RESERVED 0x00:					
				Mailbo 0x01:	ox settings			
			0x02:		ed sensor - read the ID oller	table of sensors i	n the	

Title RPC - SmartACK read settings - Mailbox settings answ Function code 0x805 Manufacturerid 0x7FF Datalength 4
Manufacturerid 0x7FF Datalength 4
Datalength 4
NO.
Broadcast NO
Addressable YES
Answer NO

Offset	Size	Data	Description
0	16	SmartACK flash address	Address where the SmartACK settings are stored
16	16	SmartACK mailbox count	number of mailboxes stored in flash

Title	RPC - SmartACK read settings - Learned sensor answer
Title	IN C SmartAck read settings Learned sensor answer
Function code	0x806
Manufacturerid	0x7FF
Datalength	N*9
Broadcast	NO
Addressable	YES
Answer	NO

N - is the number of entries: SensorID, ControllerID, LearnCount

Offset	Size	D ata	
N*0	32	SensorID	
N*32	32	ControllerID	
N*64	8	Learned Count	

Title	RPC - SmartACK write settings				
Function code	0x206				
Manufacturerid	0x7FF				
Datalength	10				
Broadcast	NO				
Addressable	YES				
Answer	YES				

Using this command different type of data can be transmitted to the SmartACK devices. This command is useful when the SmartACK device has to be configured remotely. The structure of the data transmitted is depends on the Operation Type field.

Operation Type = 0x01: Add mailbox (only controller)

Offset	Size	Data	Value	Description
0	8	Operatian Type	0x01	Add mailbox (only controller)
8	8	Mailbox Index		
16	32	SensorID		
48	32	PostmasterID		

Operation Type = 0x02: Delete mailbox

Offset	Size	Data	Value	Description
0	8	Operation Type	0x02	Delete mailbox
8	8	Mailbox Index		
16	64	Not Used (= 0)		

Operation Type = 0x03: LearnIn - only controller

Offset	Size	Data	Value	Description
0	8	Operation Type	0x03	LearnIn - only controller
8	8	Learn Count		
16	32	SensorID		
48	32	ControllerID		

Operation Type = 0x04: LearnOut - only controller

Offset	Size	Data	Value	Description	
0	8	Operation Type	0x04	LearnOut - only controller	

8	8	Learn Count	
16	32	SensorID	
48	32	ControllerID	



3.10) Interoperability with Security of EnOcean Networks

The Specification "Security of EnOcean Networks" defines two new telegram types for secure EnOcean telegrams in operational mode:

- R-ORG = 0x30 = SEC Secure telegram
- R-ORG = 0x31 = SEC_ENCAPS Secure telegram with R-ORG encapsulation

To make sure that interoperability is warranted, both telegrams may used for telegram transmission with existing EEP's. Because the profile of the device is known, the data of the SEC or SEC_ENCAPS telegram contains the same information as described in the profile, but it may be encrypted defined by the SLF (Security level format) of the device. When the device uses more than one R-ORG's in operational mode, the SEC_ENCAPS telegram has to be applied to ensure the correct original R-ORG after converting from secure to unsecure telegram. At present, 3 different communication variants having the existing XML structure can be mapped, which approximate the principles of a bi-directional data transfer. The teach-in procedure required for this is described in the same chapter.

Example for converting a telegram from unsecure to secure and back:

Unsecure: 4BS Data of profile TX-ID Status Chk

Secure: SEC Encrypted Data of profile RLC CMAC TX-ID Status Chk

Unsecure: NON SEC Data of profile TX-ID Status Chk

The data of the known profile will be applied in the unsecure telegram after the conversion from secure to unsecure telegram.

Example for converting a telegram from unsecure to secure and back with encapsulated R-ORG:

Unsecure: 4BS Data of profile TX-ID Status Chk

Secure: SEC ENCAPS 4BS Encrypted Data of profile RLC CMAC TX-ID Status Chk

Unsecure: 4BS Data of profile TX-ID Status Chk

After conversion from secure to unsecure telegram, the encapsulated R-ORG will be applied in the telegram. The data of the profile of the encapsulated R-ORG will be applied.

3.11) Existing 'bidirectional' profile structures

At present, 3 different communication variants having the existing XML structure can be mapped, which approximate the principles of a bi-directional data transfer. The teach-in procedure required for this is described in the same chapter.

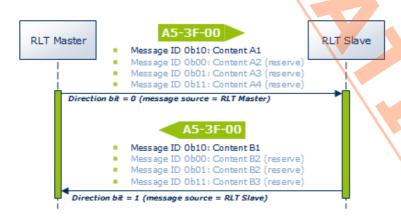
The original terminology 'transmit mode / receive mode' was not taken over, as no unique assignment to device type and hence to transmission direction can be derived there from. A neutral number (Direction 1/2) or the state of a bit should allow the required free space to the individual application.

Variant 1:



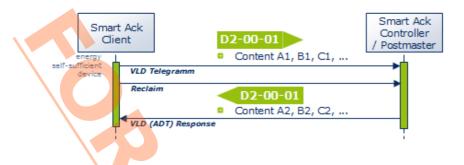
In Variant 1, there is no data-technical differentiation option in the 4BS telegram between Direction 1 and Direction 2, but only a documentation-related direction specification. No transmission direction can be detected if the telegrams are monitored on the radio stretch.

Variant 2:



In Variant 2, 3 bits are provided in the 4BS telegram, which allow up to 8 different data interpretations of the same EEP Profile No. through bit combination. 1 bit is used for direction (with the instruction text 'message source') and 2 bits for the Message ID.

Variant 3:



In Variant 3, the Smart Ack technology normally offers multiple use options of bidirectional data transmission. Smart Ack clients can therefore be energy self-sufficient devices. The used VLD telegrams allow a payload of up to 14 bytes (12.5 bytes with Manufacturer ID). Contents can thus be structured more individually.



3.12) MSC telegram - Manufacturer Specific Communication

Communication over MSC telegrams can always be used when bigger data volumes are to be transmitted, and at the same time, a closed system structure is to be created. This can be the case if e.g., the controller system backbone is expanded to include radio components, or if safety-related controls require proprietary data structures.

Such communication must not affect any interoperable EEP-based communication and should be identifiable as MSC by any Dolphin-based hardware.

Interoperability Conditions:

A device using MSC in addition to other EEPs may be marked with the EnOcean ingredient logo, as long as it complies with the rules defined by the EnOcean alliance for such markings. A device using MSC may be marked with the EnOcean ingredient logo even though the manufacturer does not disclose any or all information regarding the MSC payload. However, all other functionality of such a device shall comply with the latest EEP specification and such a device shall support at least one additional EEP. The manufacturer must clearly state which EEP(s) the device complies with. To safeguard interoperability, if there is sufficient justified doubt within the EnOcean Alliance TWG, a specific unit using MSC can be assessed by the TWG and if found to breach the interoperability intentions, the TWG may then decide (majority vote) to adapt the rules for the usage of the interoperability logo.

The MSC telegram has the same structure as a VLD telegram. The only difference is that the RORG Number is different and the payload specification is missing.

MSC

RORG Manufacturer ID		Variable data		Sender ID				CRC8
D1	1,5 byte	1 12,5 bytes	ID_3	ID_2	ID_1	ID_0	1 byte	1 byte

The following points are to be noted:

- 1. The usage of the Multi User Manufacturer ID (0x7FF) shall not be allowed.
- 2. Each user may send MSC telegrams under his own Manufacturer ID. The Manufacturer ID should not be left out.

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3.13) Manufacturer ID's

This chapter was transferred into a separate document entitled **EnOcean Manufacturer Identification (ManID)**. This document will be updated as soon as a new ManID will be allocated to a member of the EnOcean Alliance. The document **EnOcean Manufacturer Identification (ManID)** is stored in the webspace of the TWG on http://portal.enocean-alliance.org/MyWorkGroups/Documents.aspx (access only for registered members of the TWG).

3.14) XML + DOC Maintenance process

3.14.1) General

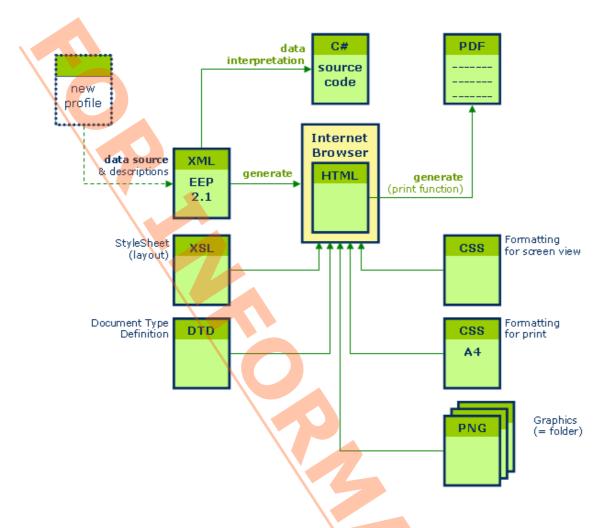
The maintenance process is descripted separately in the document: EEP2x_Maintenance_Process.pdf.

3.14.2) XML file

With EEP 2.1, a new type of documentation is introduced, which can also display logical structures next to the described contents. These can be adapted by developers into their programming environment.

XML is fully compatible with applications like C# or JAVA, and it can be combined with any application which is capable of processing XML irrespective of the platform it is being used on. If the application can work alongside XML, then XML can work on any platform and has no boundaries. It is also vendor independent and system independent.

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Only the XML data is edited and released in defined time intervals as a total release under a new version. A styles sheet file (XSL) and formatting specifications (CSS) ensure that an attractive HTML representation is possible in an internet browser. The author of the new version also creates a final PDF file.

This method ensures that the document view, as well as the software environment, remain synchronized. Errors are strongly reduced and data maintenance is optimized.

3.15) Revision

Rev.	Date	Editor	Major Changes
0.10	1	GT	Initial EnOcean Alliance Version created, based on the EnOcean GmbH document 'Standardization EnOcean Communication Profiles_v1.04'
0.90		TR	EEP for ORG = 0x05 added EEP for ORG = 0x06 added Headlines and Text formatted
0.91		TR	FUNC = 11 "Controller Status" added Proposals added: EEP 07-11-01 "Lightning Controller" (EchoFlex) EEP 07-02-0C "Temp.Sensor, Window Contact" (EchoFlex) EEP 07-10-0A "Temp. Sensor, Set-Point Adj., Window Contact" (EchoFlex) EEP 07-30-02 "Window Contact, Single Input" (EchoFlex)
0.92		TR	Manufacturer ID: Guidelines added. Definitions updated Revision History moved to a separate document chapter INPUT document for Berlin Meeting April 2009
2.0R		TR	EEP 07-02-0C shifted to Room Operating Panels -> EEP 07-10-0B EEP 06-00-00 renamed to 06-00-01 EEP 05-xx-xx (PRS telegram / PTM200) updated with results of latest discussions EEP 05-04-01 (Key Card Activated Switch) updated Proposals Added: EEP 07-10-0C "Temp. Sensor, Occupancy Control" (Termokon) EEP 07-10-0D "Temp. Sensor, Day/Night Control" (Termokon) Ratification info and period added
2.0	July 2009		Creation of final Version V2.0 EEP 05-03-02 added EEP 05-04-01 corrected EEP 06-00-01 renamed Single Input Contact EEP 07-10-0A and EEP 07-10-0B updated Single Input Contact EEP 07-30-01 and EEP 07-30-02 updated Single Input Contact 4BS teach in Telegram updated FUNC /TYPE Editorial corrections
2.1 R1	Nov 12, 2010	Ор	The EEP 2.0 document as well as all 2.1 single documents were transferred to an XML data structure and standardized. The following chapters were re-written: Introduction, Teach-in, Bi-directional profiles, Smart Ack, RPC and MSC. Profiles that are still being coordinated were also accepted. These are characterized as 'Not approved' in the document. Bidirectional profiles are labeled with 'BI-DIR'. RPS ORG 05 = RORG F6; 1BS ORG 06 = RORG D5; 4BS ORG 07 = RORG A5
2.1 R2	Dec 31, 2010	Ор	2th review
2.1	Jan 20, 2011	Ор	Final version V2.1
2.5 R1	May 20, 2012	Ор	Review version 1 Added profiles: - 1 RPS: F6-02-03 - 16 4BS: A5-07-02, A5-09-02, A5-09-05, A5-09-06, A5-09-07, A5-10-1F, A5-11-03, A5-11-04, A5-14-01, A5-14-02, A5-14-03, A5-14-04, A5-14-06, A5-38-08 - 15 VLD: D2-01-0011, D2-01-0002 Updated profiles: A5-07-01, A5-09-01, A5-09-04 Further: - Description: UTE – Universal Uni- and Bidirectional Teach-in - RPC function no. added - Manufacturer ID's added
	Nov 08, 2012	Ор	Review version 2 Significant changes: - Chapter 1.3 - Add new profiles: A5-06-03, A5-07-03, A5-13-07 - Update of profiles: A5-10-15, A5-10-16, A5-10-17, A5-13-01, A5-13-05
2.5 R3	Feb 03, 2013	Ор	Significant changes: - Add new profiles: D2-03-00, D2-20-00, D2-20-01, D2-20-02 - Update of profiles: A5-07-02, A5-13-02, D2-01-00 - Deleted Chapter 'Manufacturer ID's'

2.5	March 04, 2013	Ор	FINAL version V2.5
	Nov 26, 2013	Ор	Review version
2.6	Dec 17, 2013	Op	FINAL version 2.6
	Apr 15, 2014	Ор	Review version
	Apr 27, 2014	Ор	2nd review version / contains EnOcean checking
2.6.1	Jun 04, 2014	Ор	FINAL version 2.6.1
2.6.2 R1	Oct 15, 2014	Ор	Review version
2.6.2	Nov 19, 2014	Ор	FINAL version 2.6.2
2.6.3 R1	May 03, 2015	Ор	Review version
2.6.3 R2	May 19, 2015	Ор	2nd Review version: - New: A5-09-0A, A5-09-0B - Modified: A5-30-06 (previous A5-0B-01) submitter, encryption, security, graphic of case 2 - Modified: D2-32-xx Enum structur
2.6.3	Jun 08, 2015	Ор	FINAL version 2.6.3 - Removed: A5-30-06 (withdrawn profile)
2.6.4 R1	Oct 13, 2015	Ор	Review version
2.6.4	Dec 17, 2015	Ор	FINAL version 2.6.4