The multiple-choice multidimensional knapsack problem

LocalSearch implementation

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1 Problem description

1.1 Mathematical representation

1.1.1 Sets/Domains

- N: Sets of items divided in
- $J = (J_1, J_2, ..., J_n)$: n disjoint classes
- $r_i = |J_i|$: Number of items in each class
- $C = (C^1, C^2, ..., C^m)$: Resource vector of size m (constrained multidimensional capacity of the knapsack)
- $v_{i,j}$: Value of item $j \in \{1..r_i\}$ for class $i \in \{1..n\}$
- $w_{i,j}^k$: Weight of item $j \in \{1..r_i\}$ for class $i \in \{1..n\}$, for the resource $k \in \{1..m\}$

1.1.2 Mathematical model

$$z = \min \sum_{i=1}^{n} \sum_{j=1}^{r_i} v_{i,j} * x_{i,j}$$

$$s.t. \sum_{i=1}^{n} \sum_{j=1}^{r_i} w_{i,j}^k * x_{i,j} \le C^k$$

$$\forall k \in \{1..m\}$$

$$\sum_{j=1}^{r_i} x_{i,j} = 1$$

$$\forall i \in \{0.1\}$$

1.2 Input data

Data are provided in .txt files, which are divided in *standard* and *large*. Each file represent an independent instance of the MMKP problem and the number of classes, items and weights can change depending on the file. There are a total of 268 standard and 27 large datasets.

- N = Number of classes
- M = Number of resources (weights)
- \bullet Q1 .. QM = Capacity of i-th resource

N classes definition follow:

I = Number of items on the j-th class

I items definition follow:

V1 = Value of the item

W11 .. W1M = Weight of the item for i-th resource

1.3 Output data

Data are outputted to a .out file having the same name of the input file. Foreach execution, a .out file is generated, containing the solution for the specific instance. The content of the file is a one-line vector of item indexes, separated by a whitespace. The total of indexes is N, where N is the number of classes read from the input file.

2 Problem analysis

The following analysis is based on the greedy algorithm descripted in the previous paper. [1] Local search algorithms for MMKP face the challenge of a large search space and potential local optima.

3 Solution

The structure of a local search algorithm is always similar, but the size of the neighborhood and the operations to be performed on it change.

The decision made in this project is to compute a single neighbour out of the neighborhood. If the neighbour implements the current solution, than the latter is updated.

Below are three implementations of local Search developed during this project:

- Swap of two items for two classes with others random items [2]
- Swap of one item for one class with another random item [3]
- Swap of one item for one class with the item with highest Value V [4]

The solution proposed is the random double item swap for two different classes, which yields the best results. In all the solutions, the stop condition is always false, therefore the program can not stop unless a SIGINT is received.

4 Pseudocode

```
Algorithm 1 Two Swap LocalSearch
 1: ▷ Compute LocalSearch solution
 2: procedure Compute
 3:
        s \leftarrow initialSolution()

    □ Greedy solution

        while True do
 4:
                                                                                                                      > O(n)
 5:
            N \leftarrow computeNeighbor(instance)
            neighbor Capacities \leftarrow compute Capacities From Neighbor (N, instance)
 6:
 7:
            ▷ Update current instance with computed neighbor
 8:
            instance.solution \leftarrow N
           instance.capacities \leftarrow neighborCapacities
10: ⊳ compute neighbor from instance
11: procedure COMPUTENEIGHBOR (instance)
                                                                                               ▷ O(nClasses + nResources)
        neighborhood \leftarrow actual Solution
12:
        firstTargetClass \leftarrow random
13:
14:
        secondTargetClass \leftarrow random
15:
         \textbf{if} \ \mathit{firstTargetClass} == \mathit{secondTargetClass} \ \textbf{then} 
16:
            change secondTargetClass
17:
        itemFirstClass \leftarrow random
18:
        itemSecondClass \leftarrow random
19:
        neighborhood Capacities \leftarrow nrResources
20:
        for all r \in nrResources do
21:
            adapt swap values for resource r
22:
         feasible \leftarrow true
23:
        for all i \in neighborhoodCapacities.size do
24:
            if neighborhoodCapacities[i] < 0 then
25:
               feasible \leftarrow false
26:
        \overline{	ext{if}}\ feasible\ \&\ \&\ swapImproveValue\ 	ext{then}
27:
            execute swap
        return\ neighborhood
28:
29: ▷ Compute a capacity array from a neighbor solution
    procedure ComputeCapacitiesFromNeighbor (neighbor, instance)
                                                                                                ▷ O(nClasses * nResources)
31:
        neighbor Capacities \leftarrow instance. capacities
32:
        for i \leftarrow 1 to instance.nClasses do
33:
            for j \leftarrow 1 to instance.nResources do
34:
                if N[i] \neq instance.solutions[i] then
35:
                    neighborCapacities[i] -= weight(N[i])
36:
                    neighbor Capacities[i] \ += \ weight (instance.solutions[i])
         return neighbor Capacities
```

5 Complexity analysis

The complexity of the algorithm is determined by three parameters:

- nClasses: the number of classes in the instance
- nItems: the number of items. This value can vary for each class, therefore the worst-case scenario will be considered. In this scenario, nItems is equal to the dimension of the class with more items
- nResources: the number of resources in the problem

The operations that have to be considered are those commented in **Pseudocode**. The overall complexity time is determined by:

```
O(readInput) + O(greedy solution) + O(compute) * O(computeNeighbor) \\ + O(compute) * O(computeCapacitiesFromNeighbor) + O(Writesolution)
```

Which values are:

```
O(nClasses \cdot nItems \cdot nResources) + O(nClasses \cdot nItems \cdot nResources) \\ + O(n) * O(nClasses + nResources) + O(n) * O(nClasses * nResources) \\ + O(nClasses)
```

The equation can be aproximated as follows:

O(n * nClasses * nItems * nResources)

6 Performance analysis

The performance analysis of the MMKP local search solver revealed that the solver's solution quality was around 97% of the optimal solution for most problem instances.

6.1 Benchmark

Due to the high time limit of 60 seconds, the benchmark was limited to 10 instance files. The three columns represent:

- Non Zero Sol. The total number of solvable instances. The value is calculated on all the available instances and is not limited to the 10 instances used for the banchmark.
- Mean Delta (%) The average delta value from the given best value for every instance.
- Mean Time (s) The average time required for computing an instance.

	Non Zero Sol.	Mean Delta (%)	Mean Time (s)
Swap two random items	258	-2.113	60
Swap one random item	258	-3.629	60
Swap one item with the highest V	258	-5.834	60

Table 1: Benchmark solutions

7 Previous attempts

The final solution is very close to the one proposed in the paper. [2] As can be seen in the **Benchmark chapter**, two other solutions, explained in the **Solution chapter** were tested, but performed worse.

8 Conclusions

Although the results are very good, local search algorithms often get stuck in local optima. Therefore, in order to find the global optimum, it would be preferable to implement meta-heuristic algorithms, which are known for their ability to get out of local optimum.

Bibliography

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