

Assumptions	Commitments
Assumptions	cnt = 3
(b_in.sig[status] == in_frame)	$m_{\text{out.sig}} = 3$
	msg.data = b_in.sig[data]
b_in.sync()	msg.status = b_in.sig[status]
	s out.sig = true

Assumptions	Commitments
	cnt = cnt
not(b_in.sync())	msg.data = msg.data
	msg.status = msg.status
	s_out.sig = s_out.sig

Assumptions  not((b_in.sig[status] == in_frame))	Commitments
	cnt = cnt
	msg.data = b_in.sig[data]
b_in.sync()	msg.status = b_in.sig[status]
	s_out.sig = false

Assumptions

Commitments cnt = 15 msg.data = msg.data msg.status = msg.status  $s_out.sig = s_out.sig$ 

Assumptions	Commitments
	cnt = (-1 + cnt)
	$m_{out.sig} = (-1 + cnt)$
not((cnt == 1))	msg.data = msg.data
	msg.status = msg.status
	s_out.sig = s_out.sig

frame\_data\_0

Assumptions	Commitments
	cnt = cnt
b_in.sync()	msg.data = b_in.sig[data]
b_in.sync()	$msg.status = b_in.sig[status]$
	s_out.sig = s_out.sig

frame\_start\_2

Assumptions	Commitments	
	cnt = (-1 + cnt)	
not((cnt == 0))	m_out.sig = msg.data	
	msg.data = msg.data	
not(b_in.sync())	msg.status = msg.status	
	s_out.sig = s_out.sig	

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Assumptions	Commitments
	cnt = (-1 + cnt)
(cnt == 0)	m_out.sig = msg.data
	msg.data = msg.data
not(b_in.sync())	msg.status = msg.status
	s_out.sig = false