Automatic Dynamic Relevance Determination for Gaussian process regressions with functional inputs

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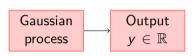
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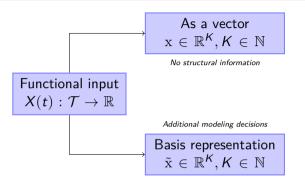
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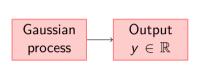
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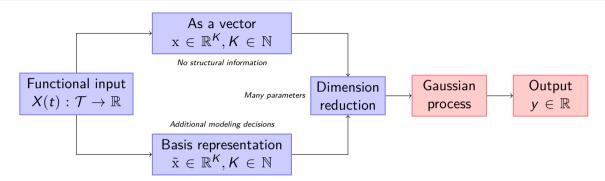
Overview & motivation

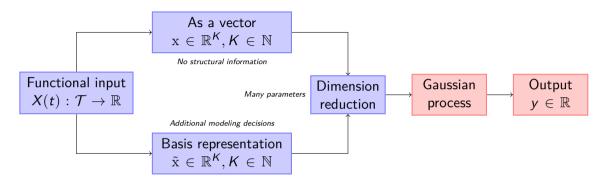
Functional input $X(t): \mathcal{T} o \mathbb{R}$



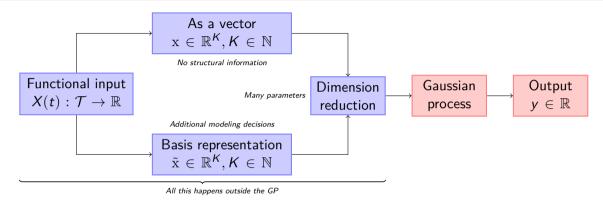




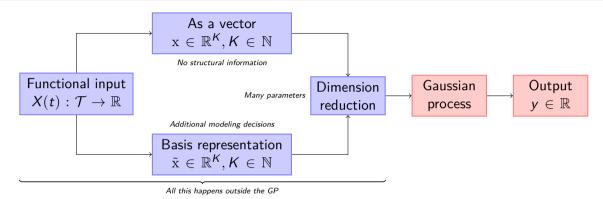




■ Can we connect the functional input structure to a physical mechanism?



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- Can we incorporate the functional input structure into the GP?



- Can we connect the functional input structure to a physical mechanism?
- Can we incorporate the functional input structure into the GP?
- Can we circumvent input dimension reduction?

Output	$egin{aligned} Input \ X(t): \mathcal{T} ightarrow \mathbb{R} \end{aligned}$	$Index \\ t \in \mathcal{T}$		Mechanism
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Plant growth	Phosphorus	Depth	Soil layers	Root biomass

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	Precipitation	Time	Cycles, seasons	Germination photosynthesis nutrient absorption

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Index subspaces can provide a meaningful representation of the physical process

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Index subspaces can provide a meaningful representation of the physical process

Can we establish an explicit link $X(t) \xrightarrow{f} y$ for UQ?

Automatic Oynamic Relevance Determination for Gaussian process regressions with functional inputs

From relevance to dynamic relevance

April 13th, 2022

Some inputs matter more than others

 x_1 vs x_2

Screening

(exploration

& diagnostics)

Permutation Feature

Importance

Model tuning (learning)

Automatic Relevance Determination

^[1] Forthcoming paper

Some inputs matter more than others $x_1 \ \textit{vs} \ x_2$

Some index subspaces \rightarrow matter more than others $X(t_1)$ vs $X(t_2)$

Screening (exploration

& diagnostics)

Feature Importance

Permutation

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Some inputs matter more than others x_1 vs x_2

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Screening (exploration & diagnostics)

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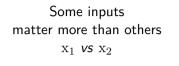
 \rightarrow

Permutation Feature *Dynamic Importance*^[1]

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Automatic Relevance Determination

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Some index subspaces \rightarrow matter more than others $X(t_1)$ vs $X(t_2)$

Screening (exploration & diagnostics)

Permutation Feature Importance Permutation
→ Feature

Dynamic Importance[1]

Model tuning (learning)

Automatic Relevance Determination

Automatic

Dynamic Relevance

Determination

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Model tuning (learning)

Automatic Relevance Determination

Distance $d(X_i, X_i)$

$$\sum_{k=1}^{K} \frac{\left(x_{i,k} - x_{j,k}\right)^2}{\ell_k^2}$$

$$\ell_1^{-2},\cdots,\ell_{\mathsf{K}}^{-2} > 0$$

Model tuning (learning)

Automatic Relevance Determination \longrightarrow

Automatic

Dynamic Relevance

Determination

Distance $d(X_i, X_j)$

$$\sum_{k=1}^{K} \frac{\left(x_{i,k} - x_{j,k}\right)^2}{\ell_k^2}$$

Weights (relevance)

$$\ell_1^{-2},\cdots,\ell_{\mathit{K}}^{-2}\,>\,0$$

Model tuning (learning)

Automatic Relevance Determination → Automatic

→ Dynamic Relevance

Determination

Distance $d(X_i, X_j)$

$$\sum_{k=1}^{K} \frac{\left(x_{i,k} - x_{j,k}\right)^2}{\ell_k^2}$$

$$\int_{\mathcal{T}} \omega(t) (X_i(t) - X_j(t))^2 \mathrm{d}t$$

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Automatic Relevance Determination Automatic

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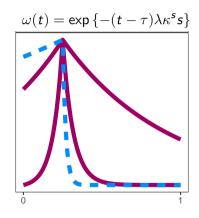
Weights (relevance)

$$\ell_1^{-2}, \cdots, \ell_K^{-2} > 0$$

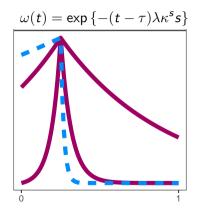
$$\omega(t) : \mathcal{T} \to \mathbb{R}^+$$

$$\omega(t) = \exp\left\{-(t-\tau)\lambda \kappa^{s} s\right\}$$

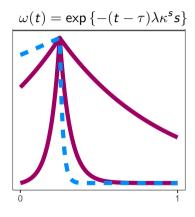
$$s = \operatorname{sign}(t - \tau), \ \tau > 0, \ \lambda > 0, \ \kappa > 0, \ \mathcal{T} = [0, 1]$$



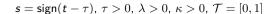
■ The input is most relevant at τ (relevance peak)

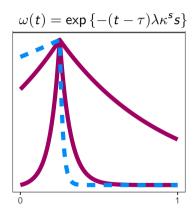


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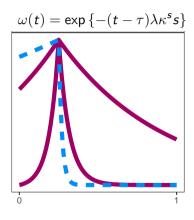


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- Relevance decreases at a $\lambda_2 = \lambda \kappa$ rate from the peak to t=1
- To predict the output, look for input profiles that are similar everywhere but especially near τ circumvent input dimension reduction

$$\mathbf{y} \sim \mathcal{N} \left(0, \sigma_f^2 \ \mathbf{R}_f + \sigma_\varepsilon^2 \mathbf{I} \right) \tag{1}$$
$$\mathbf{r}_{ii} = \exp \left\{ -0.5 \phi^{-2} \ d_f(\mathbf{X}_i, \mathbf{X}_i) \right\} \tag{2}$$

$$(R_f)_{ij} = \exp\left\{-0.5\phi^{-2} \ d_f(X_i, X_j)\right\}$$

(3)

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$$d_f(X_i, X_j) = \int_{\mathcal{T}} \omega(t) (X_i(t) - X_j(t))^2 dt$$

$$(X_i(t) - X_j(t))^2 dt$$

(1)

(2)

(3)

$$\sigma_{\varepsilon}^2 > 0$$
, $\sigma_f^2 > 0$, $\phi > 0$, $i, j = 1, \dots, N$
 $\omega(t) : \mathcal{T} \to (0, \infty)$

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$$(t)(X_i(t)-X_j(t))^{-}dt$$

$$\omega(t) = \exp\left\{-(t-\tau)\lambda\kappa^{s}s\right\}$$

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$$\int_{-\infty}^{\infty} (-0.5\varphi - \mathbf{u}_f(X_i, X_j))^2 dx$$

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Weak priors
$$\phi \sim \text{InvGamma}(\cdot, \cdot)$$
, $\tau \sim \text{Beta}(\cdot, \cdot)$, $\lambda \sim \text{N}^+(\cdot, \cdot)$, $\log(\kappa) \sim \text{N}(\cdot, \cdot)$

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(1)

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(4)

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 $d_f(X_i, X_j) = \int_{\mathcal{T}} \omega(t) (X_i(t) - X_j(t))^2 dt$

 $\omega(t) = \exp\{-(t-\tau)\lambda\kappa^{s}s\}$

 $\mathbf{v} \sim \mathcal{N} \left(0, \sigma_{\mathbf{f}}^2 \mathbf{R}_{\mathbf{f}} + \sigma_{\mathbf{c}}^2 \mathbf{I} \right)$

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Multiple inputs e.g., correlation product

Complex index spaces e.g., spatio-temporal spectral structures AKA tesseract

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(1)

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(3)

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Functional Input Gaussian Process (fiGP)

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Multiple inputs e.g., correlation product

Complex index spaces e.g., spatio-temporal spectral structures AKA tesseract

Flexibility no need to match input-output structure nor index space $\frac{\sigma_{\varepsilon}^2 > 0, \ \sigma_f^2 > 0, \ \phi > 0, \ i,j=1,\ldots,N}{\sigma_{\varepsilon}^2 > 0, \ \sigma_f^2 > 0, \ \phi > 0, \ i,j=1,\ldots,N}$

 $\omega(t): \mathcal{T} \to (0, \infty)$

$$j, j = 1, \dots, N$$

(1)

(2)

(3)

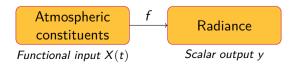
(4)

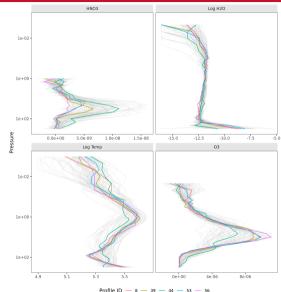
NASA's Microwave Limb Sounder

Data structure



Credit: NASA Aura

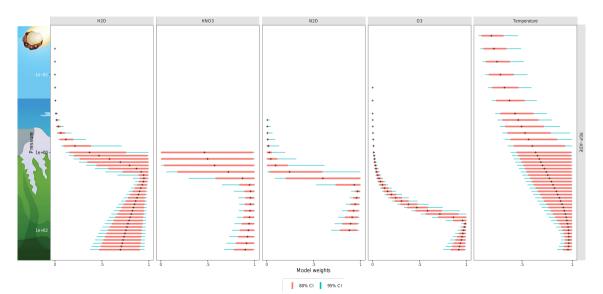




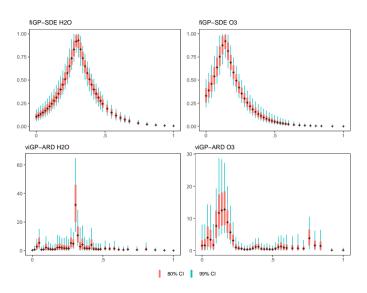
Implementation

- 8 training, 8 test complementary sets
- 1,000 soundings each
- One model fit separately per input-output pair
- Fully Bayesian inference
- Hamiltonian Monte Carlo using Stan
- 1 long chain
- Extensive search for an initial value
- 500 post-warmup iterations
- 1,500 posterior samples

Weight function posterior samples



fiGP vs a vector-input GP



- + High dimensional inputs with no dimension reduction
 - ► Reduce unknowns 3 << K
 - \triangleright Scales up for applications with higher input resolution $\uparrow K$

^[1] Forthcoming paper

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- + Explicit link between output correlation and input functional structure
 - Can incorporate domain-specific knowledge
 - Tangible for prior elicitation
 - Interpretation \rightarrow insight?
 - Smooths out erratic relevance patterns

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 - Tangible for prior elicitation
 - Interpretation \rightarrow insight?
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- Similar predictive power as vector-input GP in the case study^[1]
- Extensible to complex index spaces, e.g., spatio-temporal spectral inputs^[2]

[1] Forthcoming paper

Acknowledgments

The MLS team at JPL, California Institute of Technology

Thank you!

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repo https://github.com/luisdamiano/SIAMUQ22

Appendix

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References

Trapezoidal approximation

$$\int_{\mathcal{T}} \omega(t) (X_i(t) - X_j(t))^2 dt \approx \sum_{k=2}^{K} (t_k - t_{k-1}) \frac{\Delta_{i,j,k} + \Delta_{i,j,k-1}}{2}$$
 (5)

$$\Delta_{i,j,k} = \omega(t_{k-1})(x_{i,k} - x_{j,k})^2$$
 (6)

Out-of-sample prediction

	H2O	HNO3	N2O	О3	Temp	Mean		H2O	HNO3	N2O	О3	Temp	Mean
SE	.34	.48	.44	.32	.25	.37	SE	273	614	585	138	-7	323
ARD	.31	.47	.43	.30	.25	.35	ARD	196	619	581	92	-13	295
FPCA	.67	.91	.99	.46	.54	.71	FPCA	1024	1320	1406	637	802	1038
FFPCA	.46	.54	.46	.38	.33	.44	FFPCA	535	646	630	295	268	475
Edn	.33	.47	.44	.29	.25	.36	E_{DN}	261	623	585	90	4	312
SDE	.31	.47	.44	.29	.25	.35	SDE	202	623	585	85	4	300
ADE	.31	.47	.43	.29	.25	.35	ADE	202	610	581	87	2	297
Mean	.39	.55	.52	.33	.31	.42	Mean	385	722	708	204	152	434

Mean validation statistics: RMSE (left) and negative posterior predictive log-density (right). Smaller values are better. Bold: best in column. EDN $\tau=0, \kappa=1$; SDE $\tau=0$; ADE τ,κ,λ all free; ARD as many free parameters as measurements per vertical profile.