# Geometry, Algebra and Computation

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# Introduction

#### Geometry and Algebra

#### Geometry

- Points, lines, triangles, circles, conic sections...
- Collinear, concurrent, parallel, perpendicular. . .
- Distances, angles, areas, quadrance, spread, quadrea...
- Midpoint, bisector, orthocenter, pole/polar, tangent. . .

#### Algebra

- Addition, multiplication, inverse. . .
- Elementry algebra: integer/rational/real/complex... numbers.
- Abstract algebra: rings, fields...
- Linear algebra: vector, matrix, determinant, dot/cross product...
- Two subjects are related by coordinates.

# Key points

- Our earth is not flat and our universe is non-Euclidean.
- Non-Euclidean geometry is much easier to learn than you might think.
- Our curriculum in school is completely wrong.
- Euclidean geometry is non-symmetric. Three sides determines a triangle, but three angles does not determines a triangle. It might not be true in general geometries. Euclidean geometry is just a special case.
- Yet Euclidean geometry is more computational efficient and is still useful in our small-scale daily life.
- Incidenceship promotes integer arithmetic; non-oriented measurement promotes rational aritmetric; oriented measurement promotes floating-point arithmetric. Don't kill a chicken with cow knife.

Projective Geometry

Projective Plane's Basic Elements

## Projective Plane Concept

- Only involve "Points" P and "Lines" L.
- "Points" (or lines) are assumed to be distinguishable (Equality-Comparable).
- Unless mention specifically, objects in different names are assumed to be distinct, i.e.  $A \neq B$ .

#### Incidence

- A point either lies on a line, or not.
- If a point A lies on a line a, then  $a \cdot A$  is true.
- For convenience, we also define  $A \cdot a$  such that  $A \cdot a = a \cdot A$
- In C++, define a boolean function incident(P,L)->bool.

# Projective Point

- Exactly one line passes through two distinct points.
- In C++, define a function L(P,P) → L that returns a line joined by two points.
- Denote join(A,B), or simply AB as a line joined by A and B.
- We have:
  - AB = BA
  - $\blacksquare$   $A \cdot AB$  and  $B \cdot AB$  are always true.

#### Projective Line

- Exactly one point met by two distinct lines.
- In C++, define a function P(L,L) -> P that returns a point met by two lines.
- Denote meet(a,b), or simply ab as a point met by a and b.
- We have:
  - ab = ba
  - $\blacksquare$   $a \cdot ab$  and  $b \cdot ab$  are always true.

#### Relations with other Geometries:

- In Euclidean Geometry, parallel lines are met at points in *infinity*.
- In Hyperbolic Geometry, parallel lines are met at points outside the *null circle*.
- There is no parallel line in Elliptic/Spherical Geometry.

## Example 1: Euclidean Geometry

■ Point: projection of 3D vector [x, y, z] to 2D plane z = 1:

$$(x', y') = (x/z, y/z)$$

- Vector [x, y, z] and  $[\lambda x, \lambda y, \lambda z]$  for all  $\lambda \neq 0$  are representing the same point (x', y').
- For instance, [1,5,6] and [10,50,60] are representing the same point (1/6,5/6)
- [p] = [x, y, 0] is a point at *infinity*.
- Line:  $a \cdot x' + b \cdot y' + c = 0$ , denoted by a vector [a, b, c].
- [a, b, c] and  $[\lambda a, \lambda b, \lambda c]$  for all  $\lambda \neq 0$  are representing the same line.
- [l] = [0,0,1] is the line at *infinity*.
- [0,0,0] is not a valid point or line.

## Calculation by Vector Operations

- Let  $v_1 = [x_1, y_1, z_1]$  and  $v_2 = [x_2, y_2, z_2]$ .
- The dot product  $v_1 \cdot v_2 = x_1 x_2 + y_1 y_2 + z_1 z_2$ .
- The cross product  $v_1 \times v_2 = [y_1z_2 z_1y_2, -x_1z_2 + z_1x_2, x_1y_2 y_1x_2].$
- lacksquare A point p lies on a line l if and only if  $[p] \cdot [l] = 0$
- $lacksquare join(p_1, p_2) = [p_1] \times [p_2].$
- lacksquare meet $(l_1, l_2) = [l_1] \times [l_2]$ .
- Two lines are parallel if and only if  $a_1b_2 = b_1a_2$
- Exercise: calculate the line equation that joins the points (5/8, 7/8) and (-5/6, 1/6).

#### Example 2: Spherical/Elliptic Geometry

- It turns out that the vector notations and operators can also represent other geometries such as spherical/Elliptic geometry.
- "Point": projection of 3D vector [x, y, z] to the unit sphere.

$$(x', y', z') = (x/r, y/r, z/r)$$

where  $r^2 = x^2 + y^2 + z^2$ .

- Two points on the opposite poles are considered the same point here.
- "Line": [a, b, c] represents the *great circle* intersected by the unit sphere and the plane  $a \cdot x + b \cdot y + c \cdot z = 0$ .
- [x, y, z] is called *Homogeneous Coordinates*.

## Example 3: Poker Card Geometry

- "coordinates" is **not** a necessary requirement of projective geometry.
- A "line" may contain finite number of "points".
- Consider the poker cards in the following arrangement:

$\overline{l_1}$	$l_2$	$l_3$	$l_4$	$l_5$	$l_6$	$l_7$	$l_8$	$l_9$	$l_{10}$	$l_{11}$	$l_{12}$	$l_{13}$
A	2	3	4	5	6	7	8	9	10	J	Q	K
2	3	4	5	6	7	8	9	10	J	Q	K	Α
4	5	6	7	8	9	10	J	Q	K	Α	2	3
10	J	Q	K	Α	2	3	4	5	6	7	8	9

- For example,  $meet(l_2, l_5) = 5$ ,  $join(J, 4) = l_8$ .
- We call this *Poker Card Geometry* here.

## Concept in C++17

```
template <class P>
concept bool ProjectivePlaneH =
    Equality_comparable<P> &&
    requires { typename P::dual; } &&
    requires (P p, P q, typename P::dual 1) {
        { incident(p, 1) } -> bool; // incidence
        { (p, q) } -> typename P::dual; // join or meet
   }:
template <class P, class L=typename P::dual>
concept bool ProjectivePlane =
    ProjectivePlaneH<P> && ProjectivePlaneH<L>;
```

#### Collinear, Concurrent and Coincidence

- Three points are called *collinear* if they all lie on the same line.
- Three lines are called *concurrent* if they all meet at the same point.
- In C++, define a boolean function coI(P,P,P)->bool.
- ullet col(A, B, C) is true if and only if  $AB \cdot C$  is true.
- Similarly, col(a, b, c) is true if and only if  $ab \cdot c$  is true.
- In general,  $\operatorname{col}(\{A_1, A_2, ..., A_n\})$  is true if and only if  $A_1A_2 \cdot X$  is true for all X in the rest of points  $\{A_3, A_4, ..., A_n\}$ .
- Unless mention specifically, *ABCD*... is assumed to be coincidence.

# Pappus Theorem

- Given A, B, C and D, E, F are collinear. Let G=meet(AE, BD), H=meet(AF, CD), I=meet(BF, CE). Then G, H, I are collinear.
- Note: this theorem is only true for real projective geometry.
- Exercise: verify that this theorem holds for the poker card geometry.

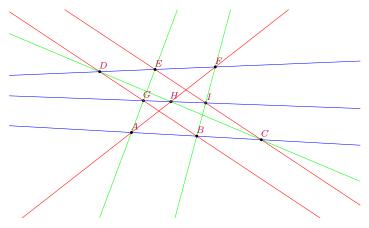


Figure 1: An instance that Pappus' theorem holds

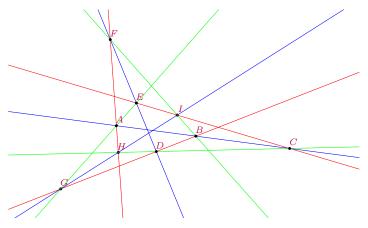


Figure 2: Another instance that Pappus' theorem holds

#### Triangles and Trilaterals

- If three points A, B, and C are not collinear, they form a triangle, denoted as  $\{ABC\}$ .
- If three lines *a*, *b*, and *c* are not concurrent, they form a trilateral, denoted as {*abc*}.
- Triangle  $\{ABC\}$  and trilateral  $\{abc\}$  are dual if A=bc, B=ac and C=ab.

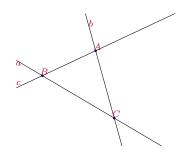


Figure 3: Triangle

Projectivities and Perspectivities

# **Projectivities**

- An ordered set (A, B, C) (either collinear or not) is called a projective of a concurrent set abc if and only if  $A \cdot a$ ,  $B \cdot b$  and  $C \cdot c$ .
- Denote Projectivity as  $(A, B, C) \land abc$ .
- An ordered set (a, b, c) (either concurrent or not) is called a projective of a collinear set ABC if and only if  $A \cdot a$ ,  $B \cdot b$  and  $C \cdot c$ .
- Denote Projectivity as  $(a, b, c) \overline{\wedge} ABC$ .
- If each ordered set is coincident, we may write:
  - $\blacksquare$   $ABC \overline{\wedge} abc \overline{\wedge} A'B'C'$
  - Or simply  $ABC \bar{\wedge} A'B'C'$

#### Perspectivities

- An ordered set (A, B, C) is called a perspectivity of an ordered set (A', B', C') if and only if  $(A, B, C) \bar{\wedge} abc$  and  $(A', B', C') \bar{\wedge} abc$  for some concurrent set abc.
- Denote Perspectivity as  $(A, B, C) \stackrel{=}{\wedge} (A', B', C')$ .
- An ordered set (a, b, c) is called a perspectivity of an ordered set (a', b', c') if and only if  $(a, b, c) \bar{\wedge} ABC$  and  $(a', b', c') \bar{\wedge} ABC$  for some collinear set ABC.
- Denote Perspectivity as  $(a, b, c) \stackrel{=}{\wedge} (a', b', c')$ .

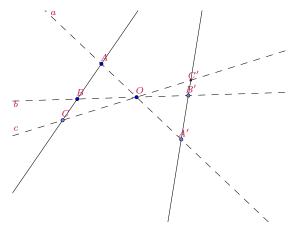


Figure 4: An instance of perspectivity

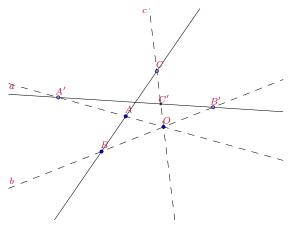


Figure 5: Another instance of perspectivity

## Perspectivity

- Similar definition for more than three points:
  - $(A_1, A_2, A_3, ... A_n) \stackrel{=}{\wedge} (A'_1, A'_2, A'_3, ... A'_n).$
- To check perspectivity:
  - First construct a point  $O := meet(A_1A'_1, A_2A'_2)$ .
  - For the rest of points, check if X, X', O are collinear.
- Note that (A,B,C)  $\bar{\wedge}$  (D,E,F) and (D,E,F)  $\bar{\wedge}$  (G,H,I) does not imply (A,B,C)  $\bar{\wedge}$  (G,H,I).

# Desargues's Theorem

- Let trilateral  $\{abc\}$  be the dual of triangle  $\{ABC\}$  and trilateral  $\{a'b'c'\}$  be the dual of triangle  $\{A'B'C'\}$ . Then,  $\{ABC\}$   $\overline{\wedge}$   $\{A'B'C'\}$  if and only if  $\{abc\}$   $\overline{\overline{\wedge}}$   $\{a'b'c'\}$ .
- Note: this theorem is only true for real projective geometry.

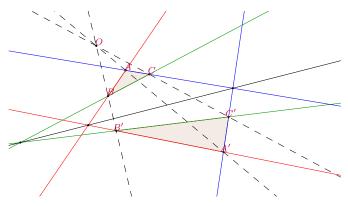


Figure 6: An instance that Desargues theorem holds

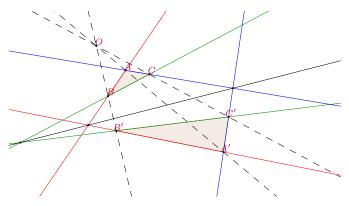


Figure 7: Another instance that Desargues theorem holds

## Quadrangles

- If four points P, Q, R and S none of three are collinear, they forms a quadrangle, denoted as  $\{PQRS\}$ .
- Totally there are six lines formed by  $\{PQRS\}$ .
- Note that Quadrangle here does not needed to be convex.

#### Quadrilateral Sets

- Assume they meet another line l at A, B, C, D, E, F, where
  - $\blacksquare$  A = meet(PQ, l), D = meet(RS, l)
  - $lacksquare B = \operatorname{meet}(QR, l), E = \operatorname{meet}(PS, l)$
  - lacksquare C = mett(PR, l), F = meet(QS, l)
- We call the six points as a quadrilateral set, denoted as (AD)(BE)(CF).

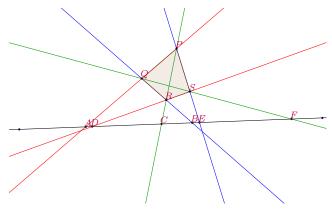


Figure 8: quadrilateral set

#### Harmonic Sets

- In a quadrilateral set (AD)(BE)(CF), if A=D and B=E, then it is called a harmonic set.
- The Harmonic relation is denoted by H(AB, CF).
- Then C and F is called a harmonic conjugate.
- Theorem: If  $ABCF \stackrel{=}{\wedge} A'B'C'F'$ , then H(AB, CF) = H(A'B', C'F').
- In other words, perspectivity preserves harmonic relation.
- Theorem: If  $ABCF \bar{\wedge} A'B'C'F'$ , then H(AB, CF) = H(A'B', C'F').
- In other words, projectivity preserves harmonic relation.

#### **Polarities**

- A polarity is a projective correlation of period 2.
- We call a the *polar* of A, and A the pole of a.
- Denote  $a = A^{\perp}$  and  $A = a^{\perp}$ .
- Hence,  $A = (A^{\perp})^{\perp}$  and  $a = (a^{\perp})^{\perp}$ .
- It may happen that A and a are incident, so that each is self-conjugate.

# The Use of a Self-Polar Triangle

- Any projective correlation that relates the three vertices of one triangle to the respectively opposite sides is a polarity.
- Thus, any triangle  $\{ABC\}$ , any point P not on a side, and any line p not throughout a vertex, determine a definite polarity (ABC)(Pp).

## The Conic

- Historically *ellipse* (including *circle*), *parabola*, and *hyperbola*.
- The locus of self-conjugate points is a *conic*.
- Their polars are its *tangents*.
- Any other line is called a secant or a nonsecant according as it meets the conic twice or not at all, i.e., according as the involution of conjugate points on it is hyperbolic or elliptic.

## Construct the polar of a point

■ To construct the polar of a given point C, not on the conic, draw any two secants PQ and RS through C; then the polar joins the two points meet(QR, PS) and meet(RP, QS).



Figure 9: Construct the polar of a point



Figure 9: Construct the polar of a point

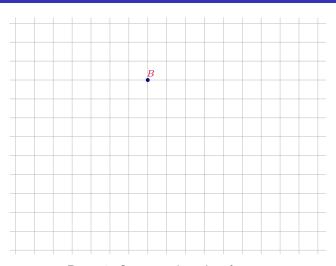


Figure 9: Construct the polar of a point

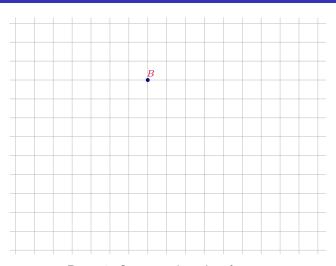


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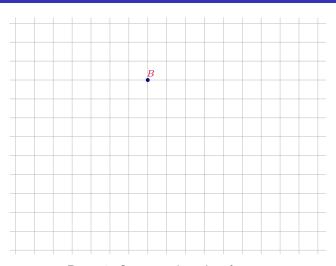


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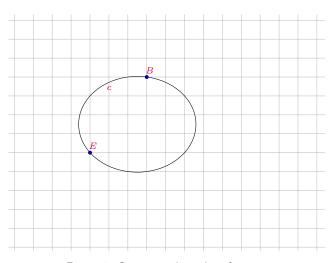


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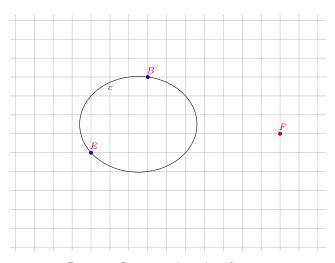


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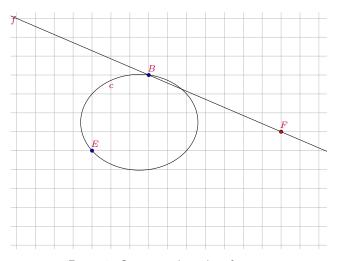


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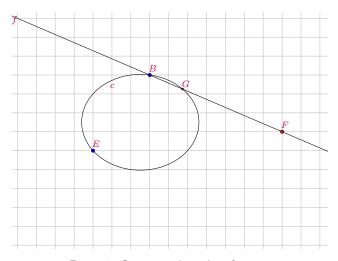


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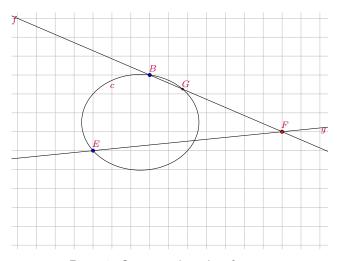


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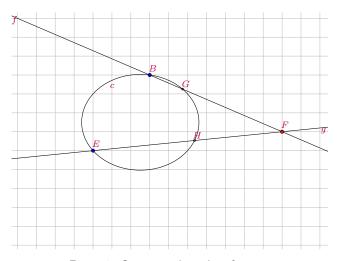


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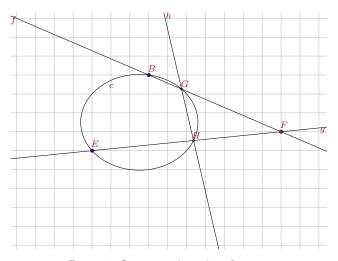


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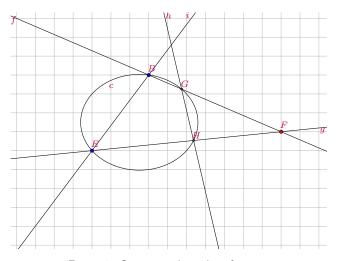


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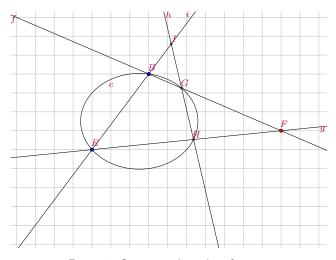


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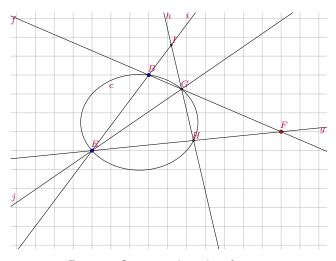


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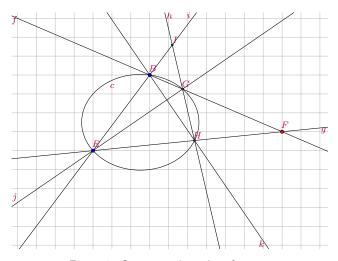


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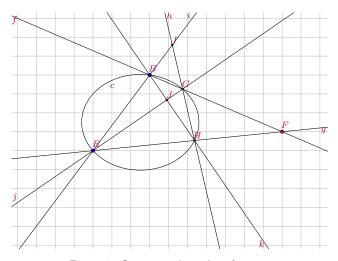


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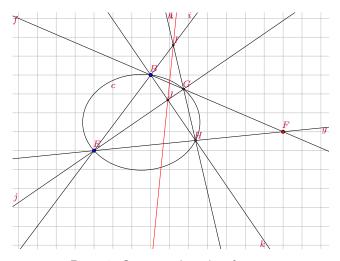


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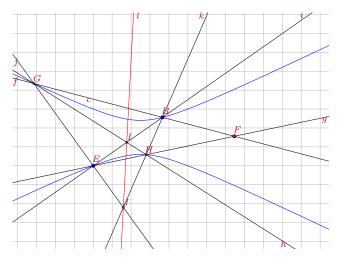


Figure 10: Another example of constructing the polar of a point

## Construct the pole from a line

■ To construct the pole of a given secant *a*, draw the polars of any two points on the line; then the common point of two polars is the pole of *a*.

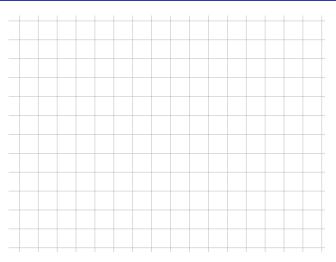


Figure 11: Constructing the pole of a line

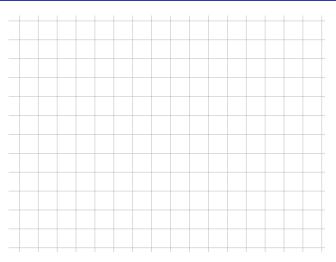


Figure 11: Constructing the pole of a line

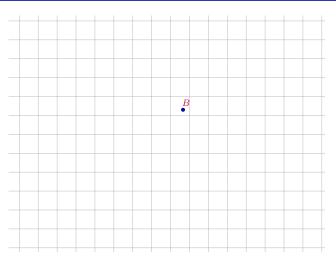


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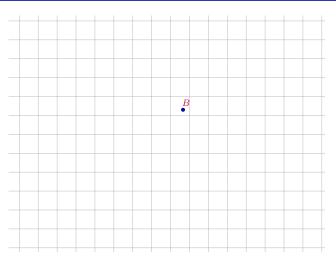


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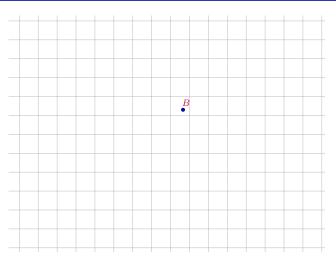


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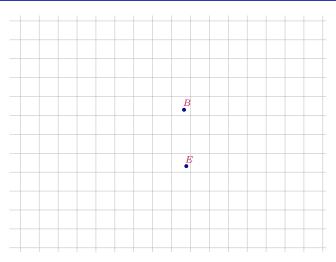


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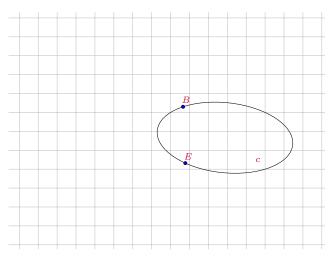


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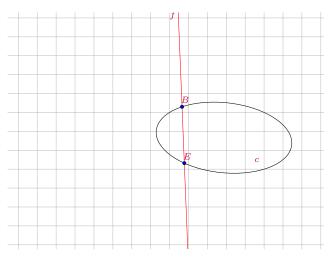


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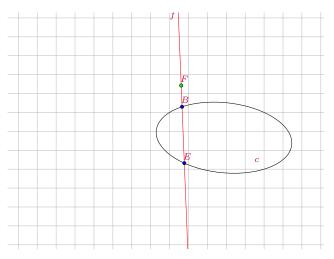


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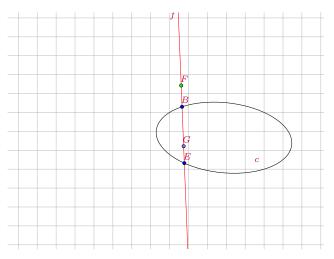


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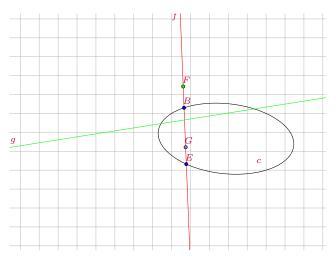


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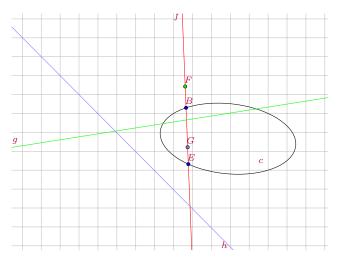


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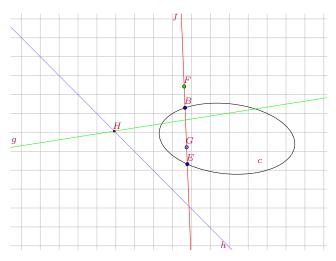


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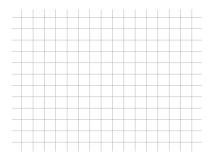


Figure 12: Another example of constructing the pole of a line

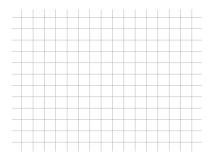


Figure 12: Another example of constructing the pole of a line

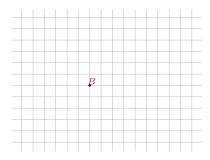


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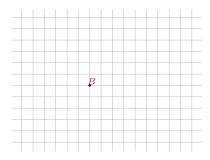


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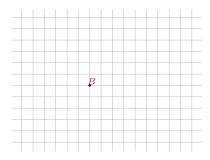


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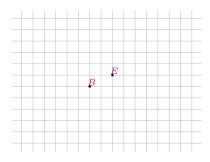


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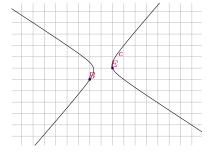


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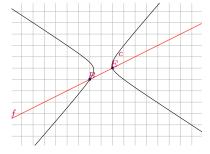


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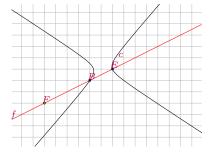


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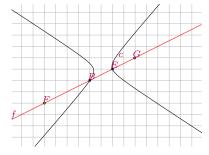


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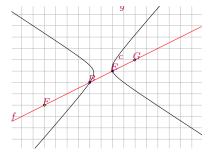


Figure 12: Another example of constructing the pole of a line

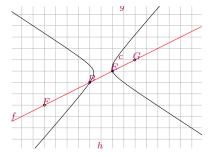


Figure 12: Another example of constructing the pole of a line

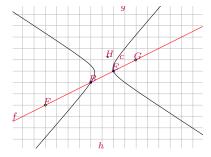


Figure 12: Another example of constructing the pole of a line

## Construct the tangent of a point on a conic

■ To construct the tangent at a given point P on a conic, join P to the pole of any secant through P.

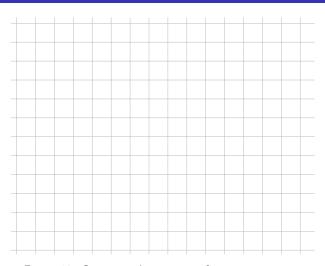


Figure 13: Construct the tangent of a point on a conic

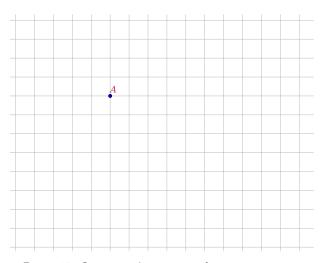


Figure 13: Construct the tangent of a point on a conic

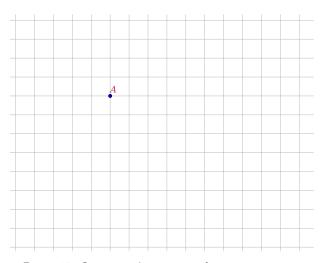


Figure 13: Construct the tangent of a point on a conic

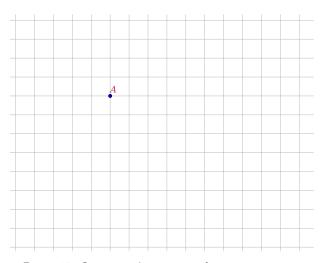


Figure 13: Construct the tangent of a point on a conic

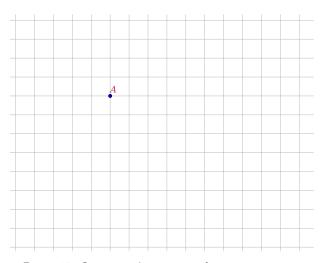


Figure 13: Construct the tangent of a point on a conic

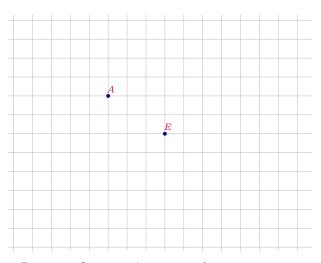


Figure 13: Construct the tangent of a point on a conic

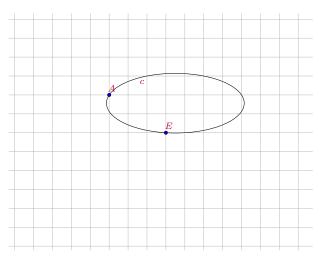


Figure 13: Construct the tangent of a point on a conic

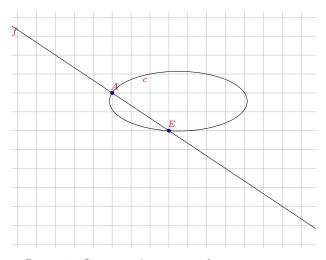


Figure 13: Construct the tangent of a point on a conic

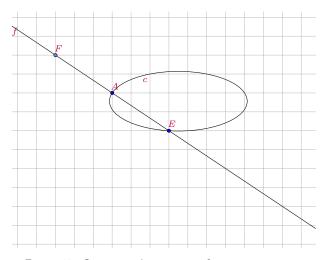


Figure 13: Construct the tangent of a point on a conic

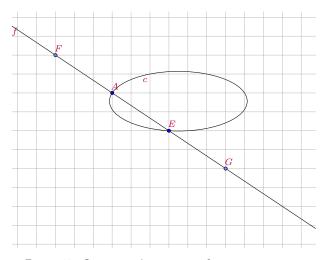


Figure 13: Construct the tangent of a point on a conic

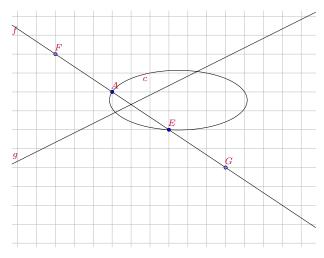


Figure 13: Construct the tangent of a point on a conic

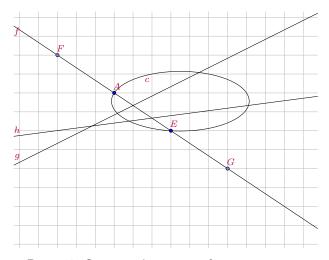


Figure 13: Construct the tangent of a point on a conic

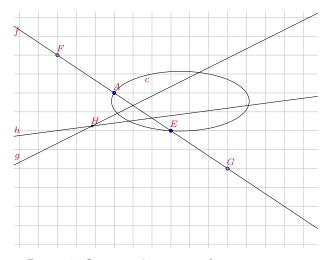


Figure 13: Construct the tangent of a point on a conic

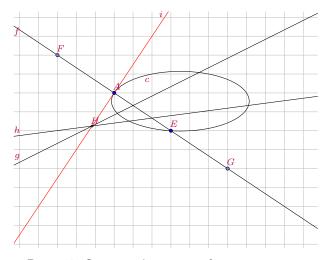


Figure 13: Construct the tangent of a point on a conic



Figure 14: Another example of constructing the tangent of a point on a conic

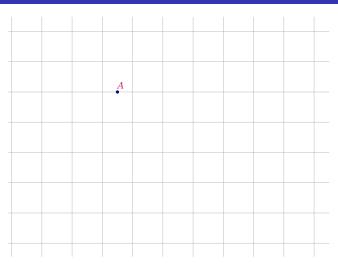


Figure 14: Another example of constructing the tangent of a point on a conic

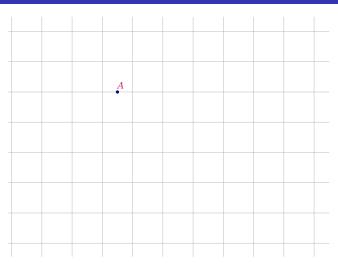


Figure 14: Another example of constructing the tangent of a point on a conic

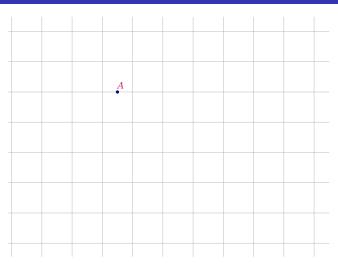


Figure 14: Another example of constructing the tangent of a point on a conic

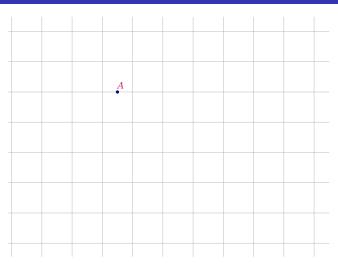


Figure 14: Another example of constructing the tangent of a point on a conic

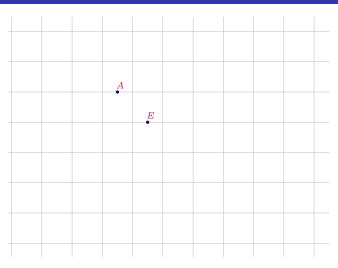


Figure 14: Another example of constructing the tangent of a point on a conic

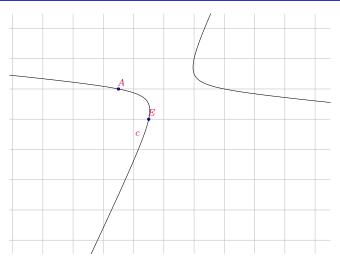


Figure 14: Another example of constructing the tangent of a point on a conic

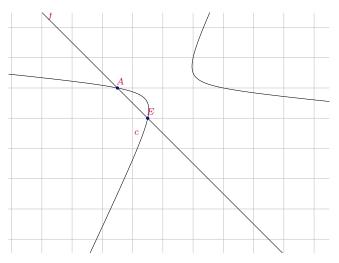


Figure 14: Another example of constructing the tangent of a point on a conic

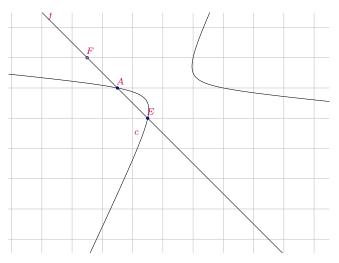


Figure 14: Another example of constructing the tangent of a point on a conic

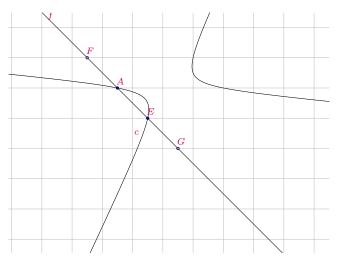


Figure 14: Another example of constructing the tangent of a point on a conic

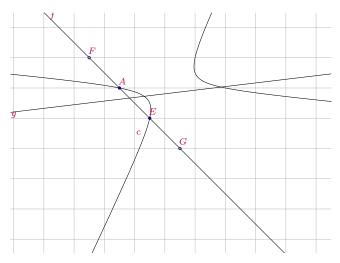


Figure 14: Another example of constructing the tangent of a point on a conic

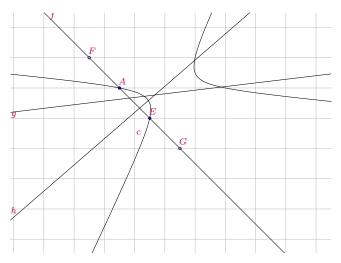


Figure 14: Another example of constructing the tangent of a point on a conic

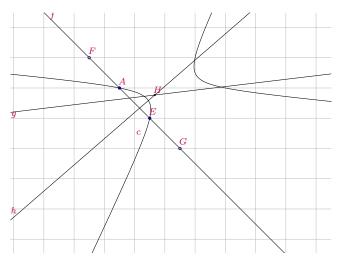


Figure 14: Another example of constructing the tangent of a point on a conic

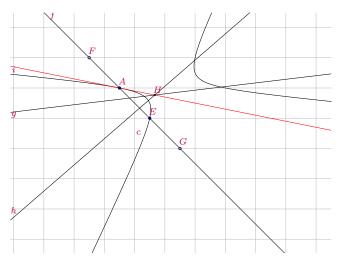


Figure 14: Another example of constructing the tangent of a point on a conic

## Pascal's Theorem

• If a hexagon is inscribed in a conic, the three pairs of opposite sides meet in collinear points.

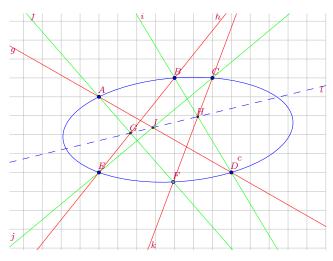


Figure 15: Pascal's theorem

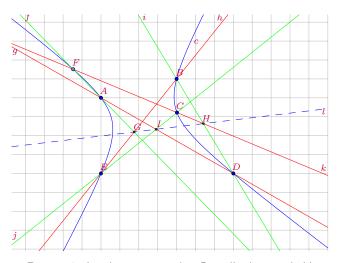


Figure 16: Another instance that Pascal's theorem holds

## Backup

```
> pandoc -s --mathjax -t revealjs -V theme=default -o proj_geo
```

- > pandoc -t beamer -o proj\_geom.pdf proj\_geom.md beamer.yaml
- > pandoc -o proj\_geom.docx proj\_geom.md