

# Homework 5

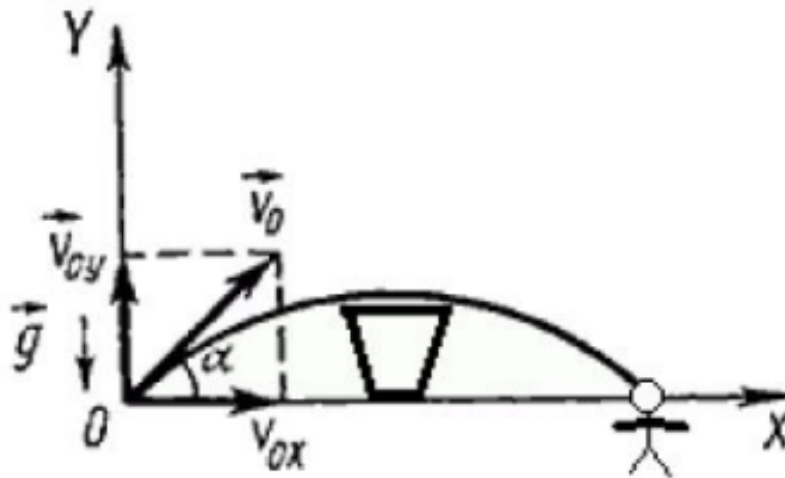
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September 2022

Source code

## Task 1

Too lazy to draw in tikz, so here you are.



**Part 1: find the angle to shoot the officer**

1. RO: particle - planar motion
2. Condition:

	<i>initial</i>	<i>final</i>
$t$	0	?
$x$	0	$L$
$x'$	$v_0 \cdot \cos(\alpha)$	$v_0 \cdot \cos(\alpha)$
$x''$	0	0
$y$	0	0
$y'$	$v_0 \cdot \sin(\alpha)$	?
$y''$	$-g$	$-g$

3. Force analysis:  $\vec{G}$

4. Solution:

(a) Equations by axis:

$$\begin{cases} mx'' = 0 \\ my'' = -mg \end{cases} \quad (1)$$

Integration yields:

$$\begin{cases} x' = c_1 \\ y' = -gt + c_3 \end{cases} \quad (2)$$

Another integration:

$$\begin{cases} x = c_1 t + c_2 \\ y = -\frac{1}{2}gt^2 + c_3 t + c_4 \end{cases} \quad (3)$$

(b) Substitution of initial values:

$$\begin{cases} c_1 = v_0 \cdot \cos(\alpha) \\ c_2 = 0 \\ c_3 = v_0 \cdot \sin(\alpha) \\ c_4 = 0 \end{cases} \quad (4)$$

(c) Combining:

$$\begin{cases} L = v_0 \cdot \cos(\alpha)t \\ 0 = -\frac{1}{2}gt^2 + v_0 \cdot \sin(\alpha)t \end{cases} \quad (5)$$

(d) Result: Python says there are two solutions:  $\alpha = 0.0097$  and  $\alpha = 1.561$ . And I have no doubts to not trust Python.

**Part 2: find the max height of the cargo ship can be to make this shot**

1. As there are two angles that satisfy the first part, we need to find the max height for each of them.
2. Analysis of equation for y-axis:

$$y = -\frac{1}{2}gt^2 + v_0 \cdot \sin(\alpha)t \quad (6)$$

3. As y is parabola, we can simply find its maximum height by finding extrema:

$$t_{max} = \frac{v_0 \cdot \sin(\alpha)}{g} \quad (7)$$

$$y_{max} = y(t_{max}) \quad (8)$$

4. Result:

For the first case:  $y_{max} = 3.64555853045729$

For the second case:  $y_{max} = 38574.3360928457$

**Part 3: find an angle  $\alpha$ , if you take into consideration the air resistance**

1. RO: particle - planar motion
2. Condition:

	<i>initial</i>	<i>final</i>
$t$	0	?
$x$	0	$L$
$x'$	$v_0 \cdot \cos(\alpha)$	?
$x''$	0	0
$y$	0	0
$y'$	$v_0 \cdot \sin(\alpha)$	?
$y''$	$-g$	$-g$

3. Force analysis:  $\vec{G}, \vec{F}_c$

4. Solution:

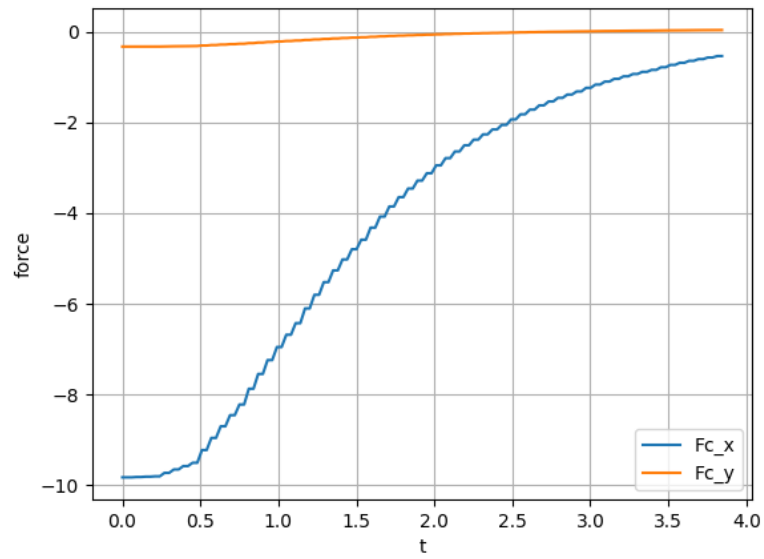
(a) Equations by axis:

$$\begin{cases} mx'' = -k\sqrt{x'^2 + y'^2}x' \\ my'' = -mg - k\sqrt{x'^2 + y'^2}y' \end{cases} \quad (9)$$

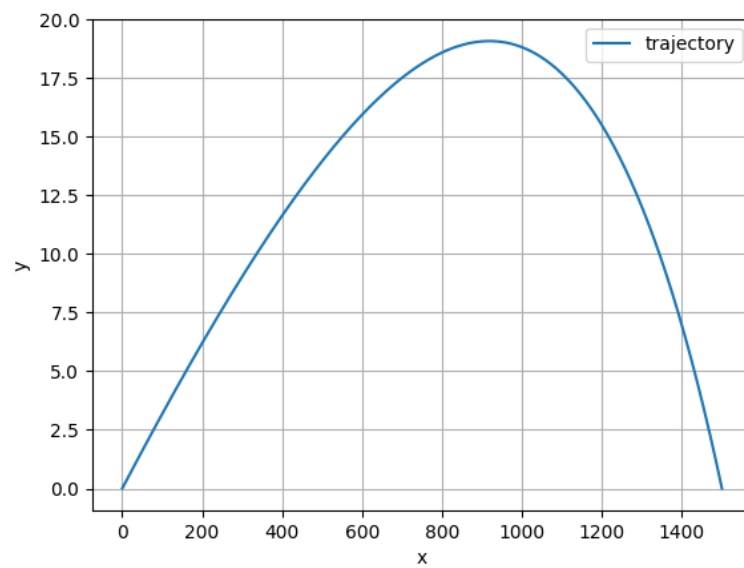
- (b) Too hard to integrate by hands, so I'll use Python. Everthing is the same as in part 1, but with different result.

(c) Result:  
An angle to shoot officer is  $\approx 0.0324$

5. Air resistance force:



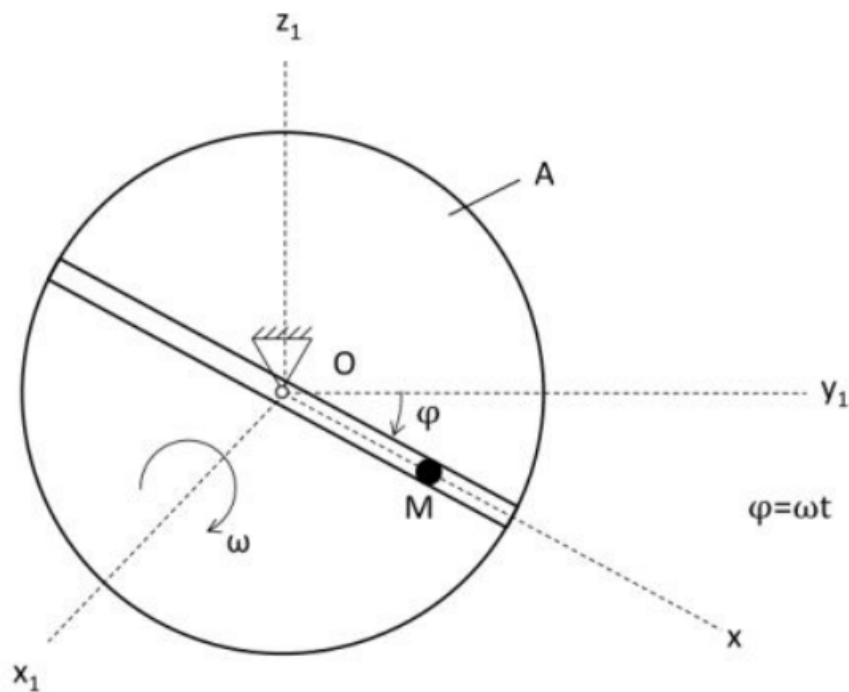
6. Trajectory with resistance:



1.  $\alpha = 0.0097,$   
 $\alpha = 1.561$
2.  $y_{max} = 38574.336$
3.  $\alpha = 0.0324$

## Task 2

simulation



1. RO: particle M - translatory motion, disk A - rotation
2. Condition:

	<i>initial</i>	<i>final</i>
$t$	0	?
$x$	0	$r$
$x'$	0.4	?
$x''$	0	0

3. Force analysis:  $\vec{G}$ ,  $\vec{N}$

4. Solution:

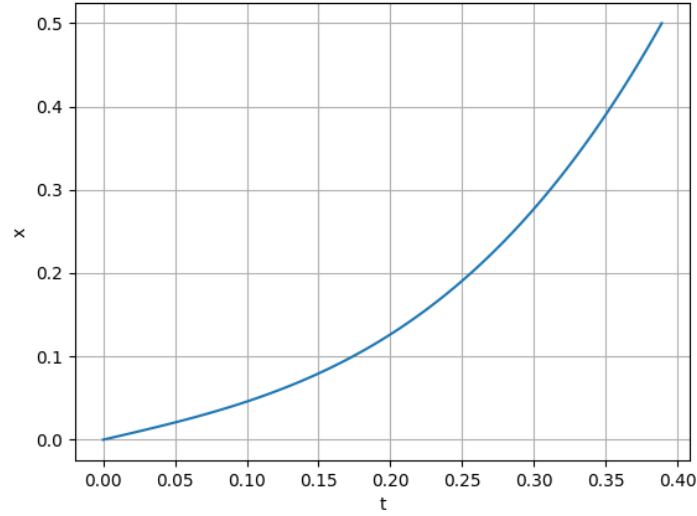
(a) Equation on x(not static) axis:

$$mx'' = \sum F_x + \Phi_{trx} + \Phi_{corx} \quad (10)$$

$$mx'' = mg \sin(\omega t) + m\omega^2 x \quad (11)$$

As coriolis acceleration is  $\vec{a}_{cor} = 2(\vec{\omega}_{tr} \times \vec{v}_{rel})$ , we see that its projection on x axis is 0.

- (b) I will not directly solve this equation here, because it just a matter of math (wolfram) solution



- (c) At next point we will find  $t$  until which we have to simulate everything:

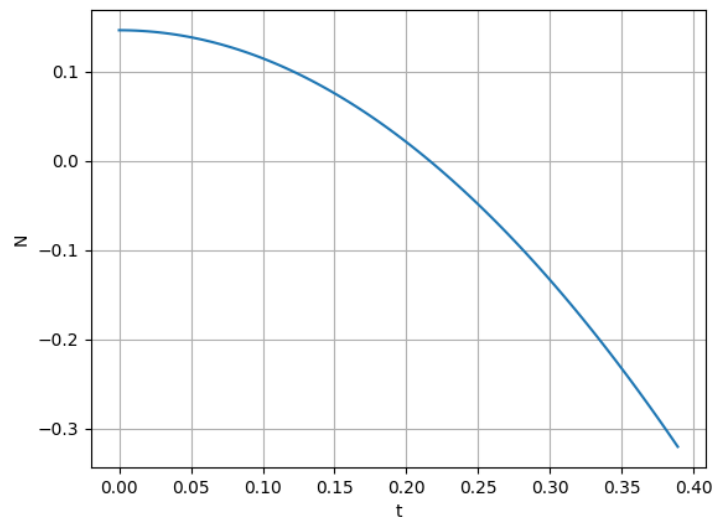
$$x(t) = r \quad (12)$$

- (d) Equation on  $y$ (not static) axis:

$$ma_{cor} + N - mg \sin(\omega t) = 0 \quad (13)$$

$$(14)$$

This equation is enough to find  $N$  for each moment of time.

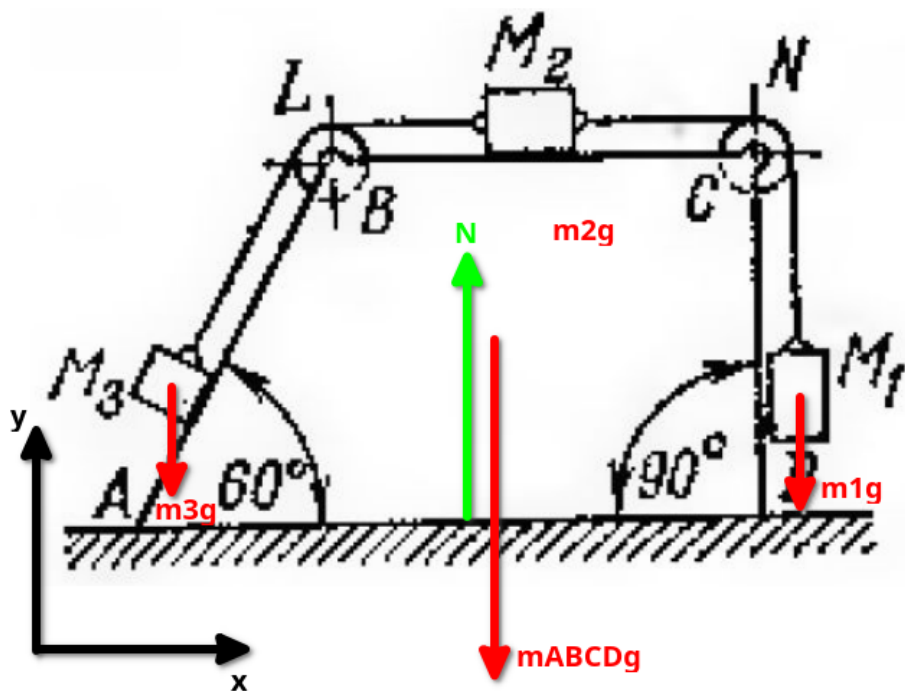


Answer:

$$t_{final} \approx 0.38s$$



### Task 3



1. I will solve the task as it was supposed by "Meshcherskiy", so mass of  $ABCD$  will be 100.
2. RO - system of 4 bodies,  $ABCD$ , body 1, body 2, body 3 - translatory motion.
3. Method: CoM
4. Conditions:  
I will write only for x axis as it is enough to complete this task

	initial	final
$x_{ABCD}$	$x_0$	$x_0 + s$
$x_{body1}$	$x_1$	$x_1 + s$
$x_{body2}$	$x_2$	$x_2 + s + d$
$x_{body3}$	$x_3$	$x_3 + s + d \cos(\pi/3)$
$x'$	0	0
$x''$	0	0

5. Forces analysis:  $\vec{G}_{ABCD}$ ,  $\vec{G}_{body1}$ ,  $\vec{G}_{body2}$ ,  $\vec{G}_{body3}$ ,  $\vec{N}$  (of the whole system)
6. Solution:

(a) Writing this equation for x axis:

$$Mx_c'' = 0 \quad (15)$$

$$Mx_c' = 0 \quad (16)$$

$$Mx_c = 0 \quad (17)$$

$$(18)$$

Which means that between initial and final position center of mass did not move.

(b) Equation connecting initial and final position:

$$Mx_c^{init} = Mx_c^{final} \quad (19)$$

(c) Using CoM:

$$\sum m_i x_i^{init} = \sum m_i x_i^{final} \quad (20)$$

$$m_1 s + m_2 d + m_2 s + m_3 d \cos(\pi/3) + m_3 s + m_{ABCD} s = 0 \quad (21)$$

**Answer:**

$$s = -\frac{4}{29}$$