

## Solution:

### Model Selection:

It is very hard to have a fair comparison among different object detector algorithms. There is no straight answer on which model is the best. We make choices by trading off between accuracy and speed. The most commonly available object detection algorithms can be broadly divided into two categories:

1. Region-based Convolution Neural Networks with two shot detections
3. Single Shot Detectors



Figure 1: RCNN vs. SSD vs. YOLO Comparison

The two-shot detection models like Fast R-CNN and Faster R-CNN have two stages: region proposal and then classification of those regions and refinement of the location prediction. Single-shot detection skips the region proposal stage and yields final localization and content prediction at once. I found this excellent [article](#) on Medium and a [paper](#) by Google comparing different types of models.

While two-shot detection models achieve better performance, and YOLO the most speed, single-shot detection is in the sweet spot of performance and speed. Since the focus was on the most optimal solution and not the most accurate one, I went ahead with YOLO.

Within YOLO, there are various different versions with speed and accuracy trade-offs.

### A YOLO History

"YOLO" refers to "You Only Look Once," a family of models that Joseph Redmon introduced in his May 2016 paper, "[You Only Look Once: Unified, Real-Time Object Detection](#)."

Redmon subsequently introduced YOLOv2 and v3 before announcing that he was stepping away from computer vision research.

Then, on April 23, 2020, Alexey Bochkovskiy [published YOLOv4](#), and on June 9, 2020, Glenn Jocher added [released YOLOv5](#).

A YOLOv5 Colab notebook, running a Tesla P100, could achieve a speed of 140 frames per second. By contrast, YOLOv4 achieved 50 FPS. Also, YOLOv5 is small weighing just 27 MB in comparison to ~270 MB for YOLOv4.

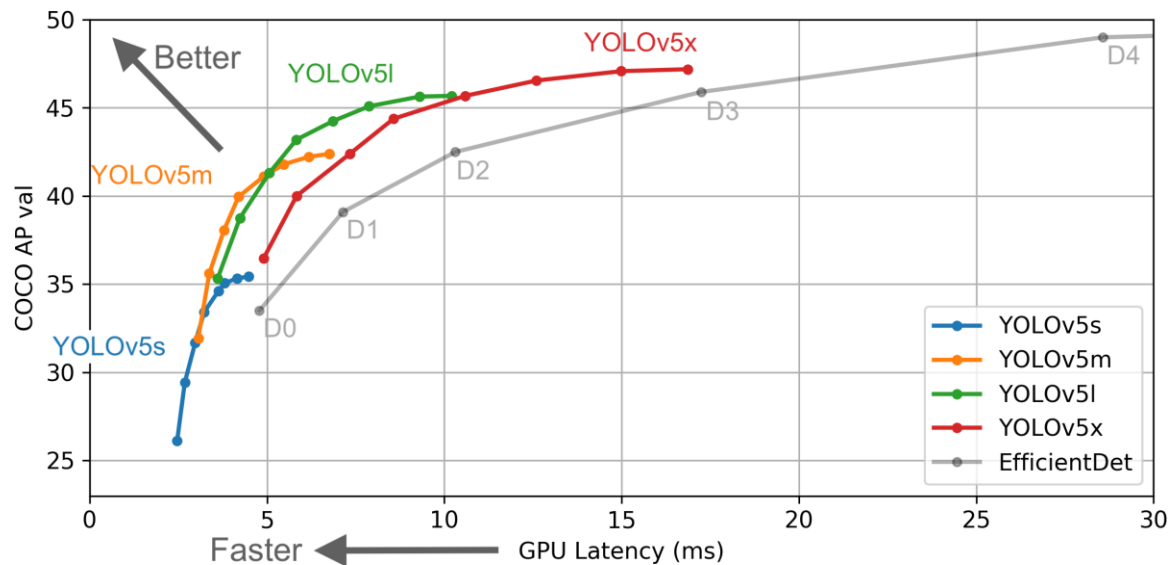


Figure 2: YOLOv5 Performance

## Model Training

I initially ran the model training for 5 epochs and then again for 15 more epochs. Making a total of 20 epochs.

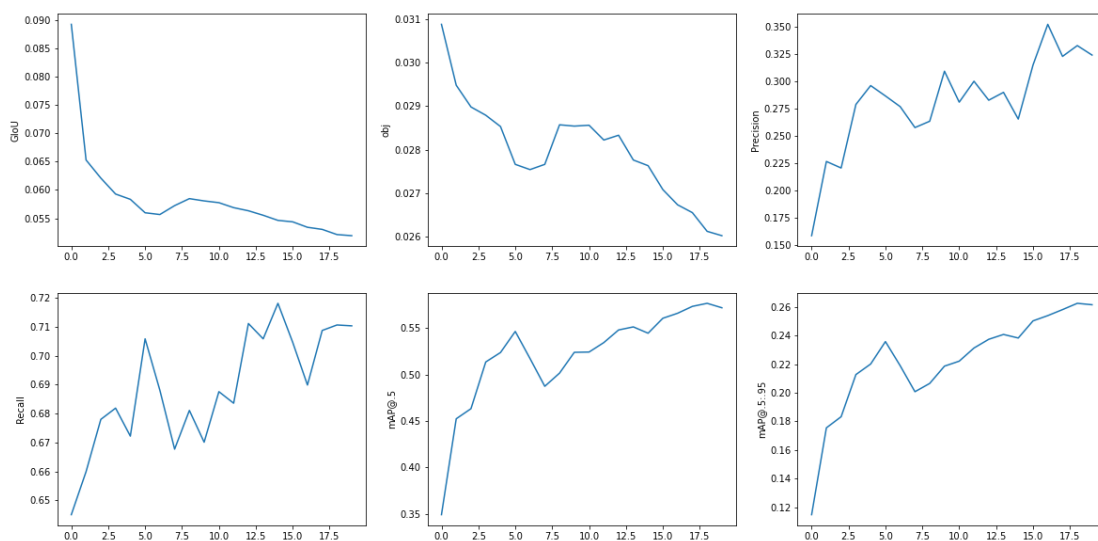


Figure 3: Results on 20 epochs

The metrics used are:

- GloU loss gain
- Objective loss gain
- Precision
- Recall
- Mean Average Precision at 50% IOU
- Mean Average Precision at 95% IOU

### **Inference:**

The average metrics for the test dataset were:

- Precision: 0.34
- Recall: 0.704
- mAP@0.5: 0.58
- mAP@0.95: 0.265

The inference time for each image was 4.5 milliseconds.

You can watch this [video](#) to watch the inference in real time.

### **Conclusion:**

At around 60% mAP@0.5, the model is certainly not the best model in the world. But at just 14 MB, it's a very small model which can be easily used on mobile and embedded devices. Also, depending on the actual application, the precision might improve even more as YOLO is not great at detecting very small objects, a lot of which were present in the dataset, which brought down the accuracy.