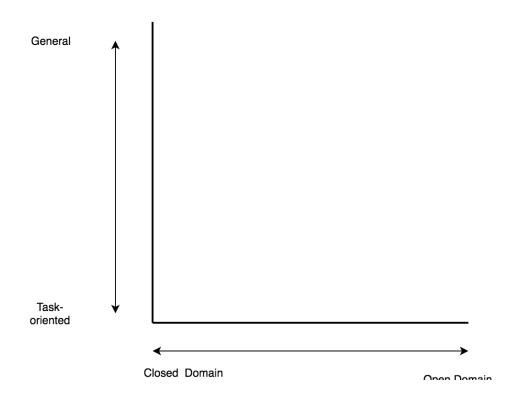
Dialog Systems and How to Score Them

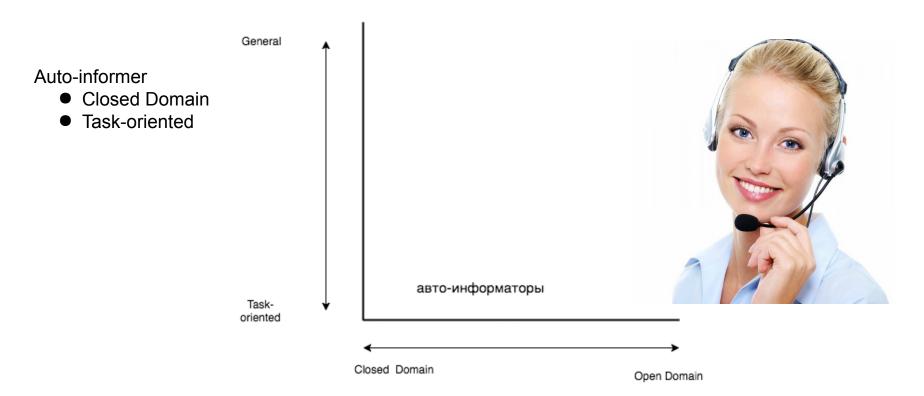
Valentin Malykh, MIPT

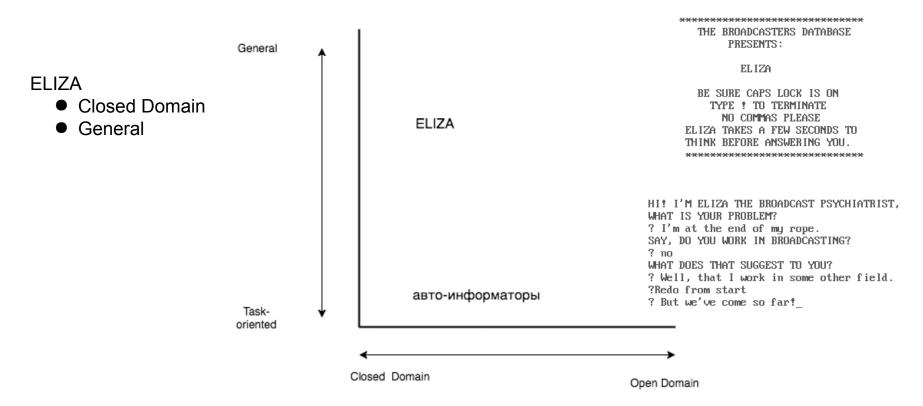
Dialog Systems: Where are they?

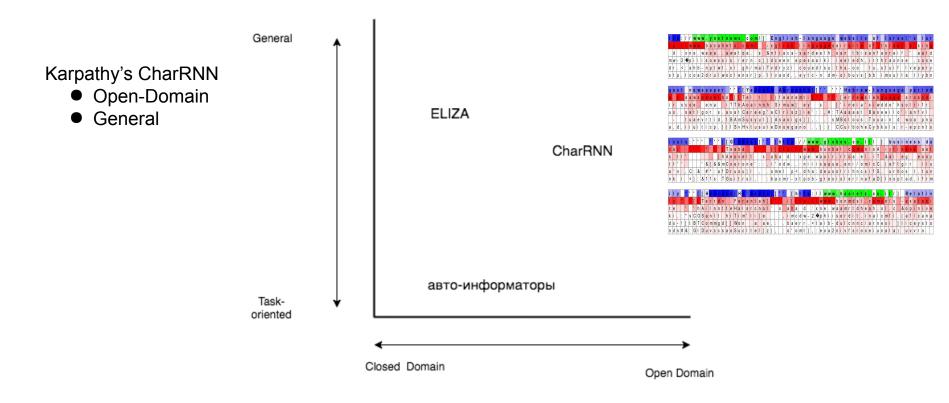


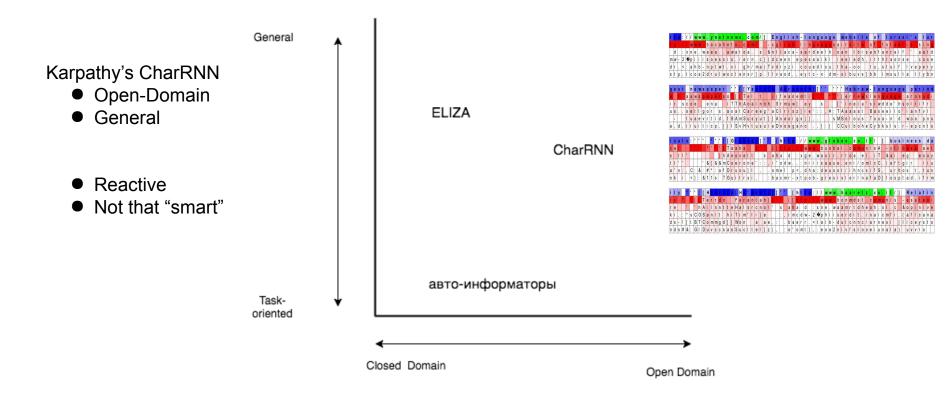


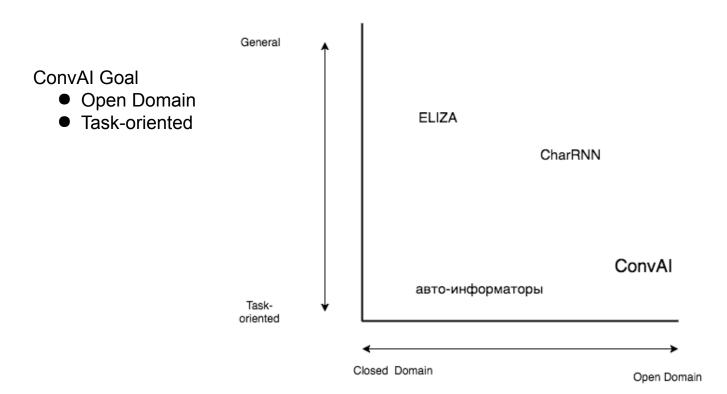


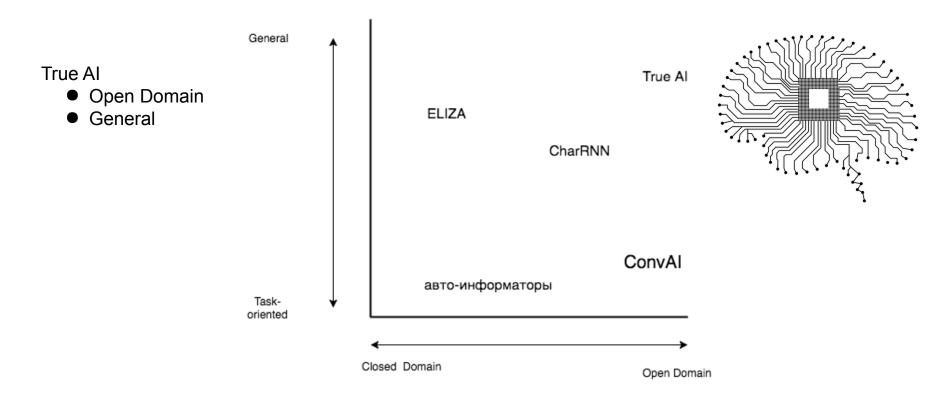


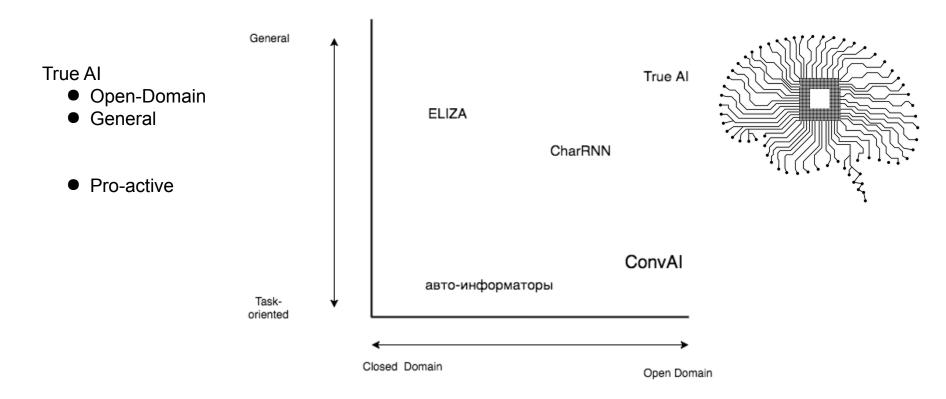












Dlalog Systems: How to Score Them?



Task-oriented Systems

Task Completion Rate (TCR)

End-to-end LSTM-based dialog control optimized with supervised and reinforcement learning

General Systems

- Word-Overlap
 - ROUGE
 - O BLEU
 - O METEOR

$$P_n(r, \hat{r}) = \frac{\sum_k \min(h(k, r), h(k, \hat{r}_i))}{\sum_k h(k, r_i)}$$

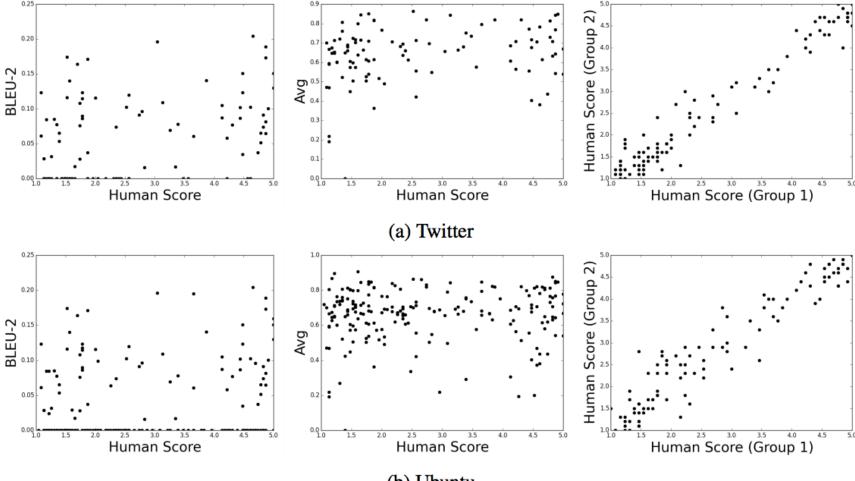
BLEU-N :=
$$b(r, \hat{r}) \exp(\sum_{n=1}^{\infty} \beta_n \log P_n(r, \hat{r}))$$

General Systems

- Word-Overlap
 - ROUGE
 - O BI FL
 - O METEOR
- Embedding-based
 - Greedy Matching
 - Embedding Average
 - Extreme Vector

$$\bar{e}_r = \frac{\sum_{w \in r} e_w}{|\sum_{w' \in r} e_{w'}|}.$$

$$\mathrm{EA} := \cos(\bar{e}_r, \bar{e}_{\hat{r}})$$



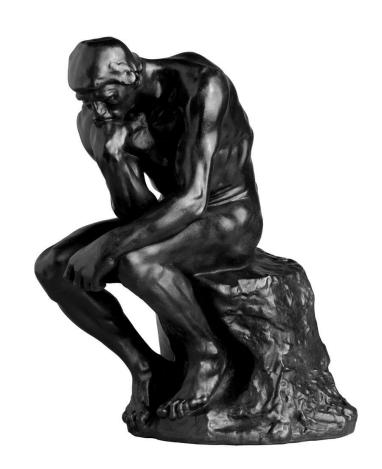
(b) Ubuntu

General Systems

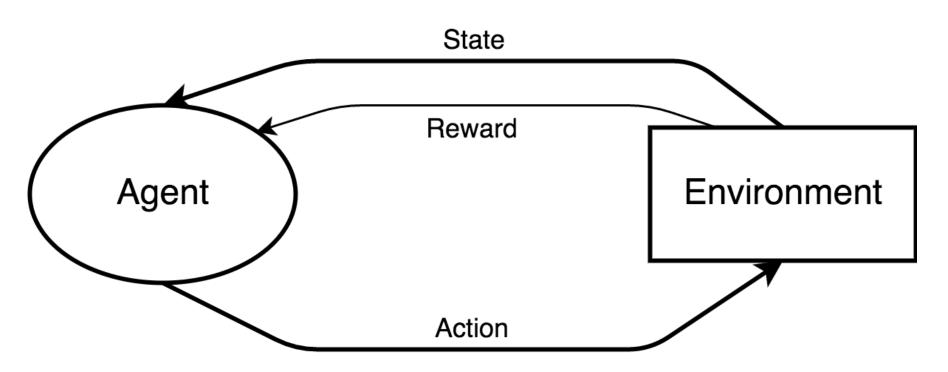
How NOT To Evaluate Your Dialogue System: An Empirical Study of Unsupervised Evaluation Metrics for Dialogue Response Generation

Chia-Wei Liu, Ryan Lowe, Iulian V. Serban, Michael Noseworthy, Laurent Charlin, Joelle Pineau, arxiv:1603.08023

How to Live with That?



How to Live with That: Reinforcement Learning



How to Live with That

Reward-based Imitation (RBI)

Forward Prediction (FP)

Dialog-based Language Learning

Jason Weston, arXiv:1604.06045

How to Live with That

Model	r = 0	r = 0.1	r = 0.5	$\mid r=1 \mid$
Reward Based Imitation (RBI)	0.333	0.340	0.365	0.375
Forward Prediction (FP)	0.358	0.358	0.358	0.358
RBI+FP	0.431	0.438	0.443	0.441

Dialogue Learning With Human-In-The-Loop

Jiwei Li, Alexander H. Miller, Sumit Chopra, Marc'Aurelio Ranzato, Jason Weston, arxiv:1611.09823

How to Live with That

hAbI Task 6: Partial Rewards

Mary went to the hallway.

John moved to the bathroom.

Mary travelled to the kitchen.

Where is Mary? kitchen

Yes, that's right!

Where is John? bathroom

Yes, that's correct! (+)

WikiMovies Task 6: Partial Rewards

What films are about Hawaii?

Correct!

Who acted in Licence to Kill?

No, the answer is Timothy Dalton.

What genre is Saratoga Trunk in?

Yes! (+)

50 First Dates

Billy Madison

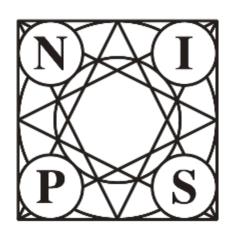
Drama

- Task-oriented
- Open Domain

NIPS 2017 Live Competition

Open Source Dataset as a Result

Presumed Dataset Size: 1000+ dialogs





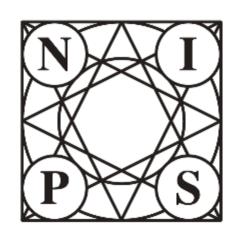
Organizers:

Mikhail Burtsev, Valentin Malykh, MIPT, Moscow

Ryan Lowe, McGill University, Montreal

Iulian Serban, Yoshua Bengio, *University of Montreal, Montreal*

Alexander Rudnicky, Alan W. Black, Shrimai Prabhumoye, *Carnegie Mellon University, Pittsburgh*





- Task-oriented
- Open Domain

Person chats with a bot (or another person)



- Task-oriented
- Open Domain

Person chats with a bot (or another person)

They are discussing a news article



- Task-oriented
- Open Domain

Person chats with a bot (or another person)

They are discussing a news article

Human judgment at the end (consistency, overall adequacy)



The Judgement Scheme

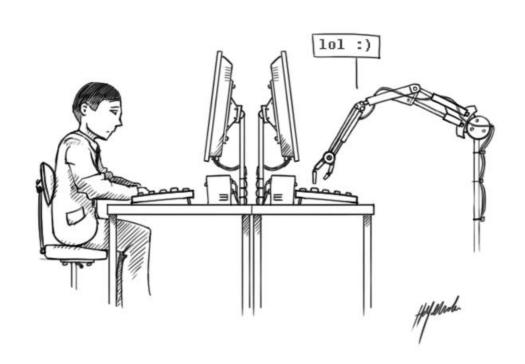
- Like/dislike for each line of a bot
- End scoring:
 - quality
 - breadth
 - engagement



Turing Test

Two persons are talking indirectly

²/₃ of persons who talked to a bot should say that it's a human



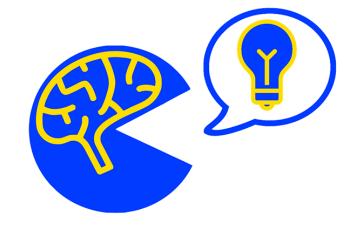
Summer School & Hackathon

The task is to determine if the dialog participant is bot or a human

Speakers from leading academia & industry labs: last time there were DeepMind, Facebook, ETHZ

Last week of July

Get the updates at deephack.me!



iPavlov Project

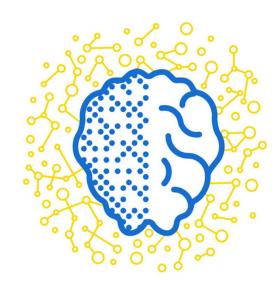
Devoted to develop an open source library with building blocks for (almost) any NLP task

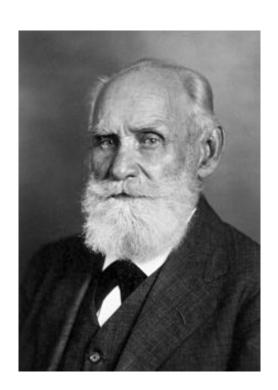
Funded by National Technology Initiative and Sberbank

3 years

Open to collaboration

iPavlov.ai





Summary

For task-oriented systems TCR is great

For any systems classical approaches are not so great

But we can get use of user models in RL

Also we invite everyone to participate in Summer School & ConvAl.io

Questions?

