Lecture #10 Product Operator Formalism I

- Topics
 - Coherence space
 - The three basic rotations
 - Examples
- Handouts and Reading assignments
 - van de Ven: Chapter 2.3 and 2.6
 - Sorenson, et al, "Product Operator Formalism for the Description of NMR Pulse Experiments", *Progress in NMR Spectroscopy*, **16**:163-192, 1983.

The Spin Density Operator

- Spin density operator, $\hat{\sigma}(t)$, completely describes the state of the system and the expectation of an observable: $\langle \hat{A} \rangle = \text{Tr} \{ \hat{\sigma} \hat{A} \}$.
- Time evolution of $\hat{\sigma}(t)$: $\frac{\partial}{\partial t}\hat{\sigma} = -i\hat{H}\hat{\sigma} \implies \hat{\sigma}(t) = e^{-i\hat{H}t}\hat{\sigma}(0)$ (\hat{H} time independent)
- Hence, if \hat{H} is piecewise constant: $\underbrace{ \hat{H_1} \quad \hat{H_2} \quad \hat{H_3} \dots }_{0 \longleftarrow t_1 \longrightarrow t_2 \longrightarrow t_2 \longrightarrow t}$

$$\hat{\sigma}(0) \xrightarrow{\hat{H}_1} \xrightarrow{\hat{H}_2} \xrightarrow{\hat{H}_3} \hat{\sigma}(t_1 + t_2 + t_3) \cdots$$
evolves under \hat{H}_1

or
$$\hat{\sigma}(0) \xrightarrow{\hat{H}_1(\omega t_1)} \xrightarrow{\hat{H}_2(\omega t_2)} \xrightarrow{\hat{H}_3(\omega t_3)} \hat{\sigma}(t_1 + t_2 + t_3) \cdots$$
rotates round \hat{H}_1 for duration t_l (or through an angle ωt_l). Aside: actually rotates around $-\hat{H}_1$

• NMR Rotations, Rotations!

Single-Spin Coherence Space

• $\underline{\sigma}$ for a one-spin system can be expressed as:

$$\underline{\sigma} = L_1 \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} + I_1 \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} + I_2 \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} + L_2 \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$

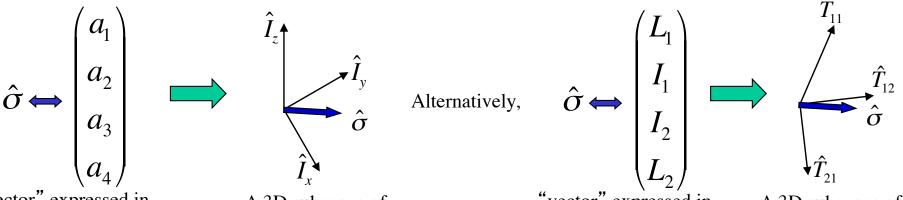
In operator form: $\hat{\sigma} = L_1 \hat{T}_{11} + I_1 \hat{T}_{12} + I_2 \hat{T}_{21} + L_2 \hat{T}_{22}$

"vector" in a 4D Liouville space called "coherence space"

$$\hat{\sigma} \Longleftrightarrow \begin{bmatrix} L_1 \\ I_1 \\ I_2 \\ L_2 \end{bmatrix}$$

• Alternatively...
$$\underline{\sigma} = a_1 \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} + a_2 \begin{pmatrix} 0 & \frac{1}{2} \\ \frac{1}{2} & 0 \end{pmatrix} + a_3 \begin{pmatrix} 0 & -\frac{i}{2} \\ \frac{i}{2} & 0 \end{pmatrix} + a_4 \begin{pmatrix} \frac{1}{2} & 0 \\ 0 & -\frac{1}{2} \end{pmatrix}$$

$$\hat{\sigma} = a_1 \hat{E} + a_2 \hat{I}_x + a_3 \hat{I}_y + a_4 \hat{I}_z \Longrightarrow \left\{ \hat{E}, \hat{I}_x, \hat{I}_y, \hat{I}_z \right\} \text{"product operator" basis set}$$



"vector" expressed in product operator basis

A 3D subspace of coherence space

"vector" expressed in transition operator basis

A 3D subspace of coherence space

The Master Equation

• Starting with the identity we derived for cyclically commuting operators:

 $e^{i\theta \, \hat{A}} \hat{B} = \hat{B} \cos \theta + i[\hat{A}, \hat{B}] \sin \theta \implies \text{Rotation about } \hat{A} \text{ axis}$ $\text{in } \hat{B} \times [\hat{A}, \hat{B}] \text{ plane}$

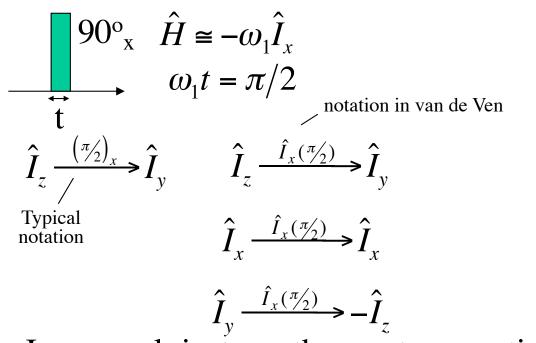
• Noting that \hat{I}_x , \hat{I}_y , and \hat{I}_z cyclically commute...

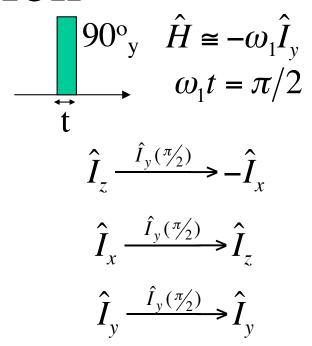
$$[\hat{I}_x, \hat{I}_y] = i\hat{I}_z \qquad [\hat{I}_y, \hat{I}_z] = i\hat{I}_x \qquad [\hat{I}_z, \hat{I}_x] = i\hat{I}_y$$

Then, ignoring relaxation, all possible rotations of $\hat{\sigma}$ during a typical MR experiment can be fully described by the following equation:

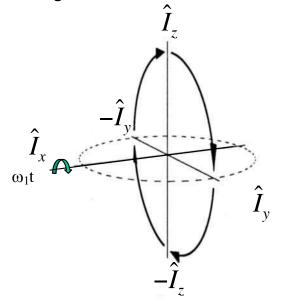
$$\hat{I}_{p} \xrightarrow{\hat{I}_{q}(\theta)} \begin{cases} \hat{I}_{p} & \text{if } [\hat{I}_{q}, \hat{I}_{p}] = 0 \\ \hat{I}_{p} \cos \theta - i[\hat{I}_{q}, \hat{I}_{p}] \sin \theta & \text{if } [\hat{I}_{q}, \hat{I}_{p}] \neq 0 \end{cases}$$

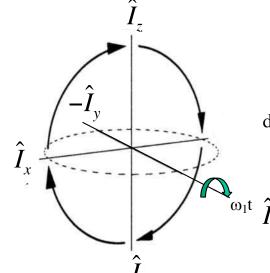
RF Excitation





• In general, just use the master equation:





Note, Sorenson uses a different sign convention $(\omega_0 = -\gamma B_0)$.

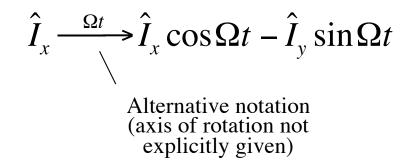
Free Precession

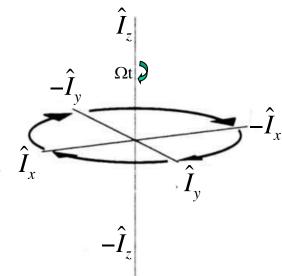
• Using the Master Equation and $\hat{H} = -\Omega \hat{I}_z$

$$\hat{I}_{x} \xrightarrow{\hat{I}_{z}(\Omega t)} \hat{I}_{x} \cos \Omega t - \hat{I}_{y} \sin \Omega t$$

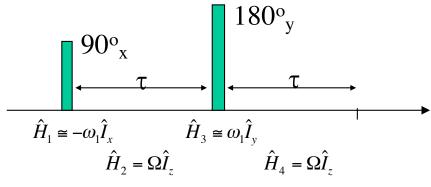
$$\hat{I}_{y} \xrightarrow{\hat{I}_{z}(\Omega t)} \hat{I}_{y} \cos \Omega t + \hat{I}_{x} \sin \Omega t$$

$$\hat{I}_{z} \xrightarrow{\hat{I}_{z}(\Omega t)} \hat{I}_{z}$$





A Spin Echo



$$\hat{\sigma}(0) \xrightarrow{\hat{H}_1} \hat{\sigma}(0^+) \xrightarrow{\hat{H}_2} \hat{\sigma}(\tau) \xrightarrow{\hat{H}_3} \hat{\sigma}(\tau^+) \xrightarrow{\hat{H}_4} \hat{\sigma}(2\tau)$$

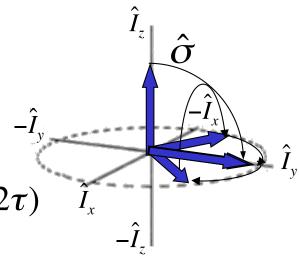
$$\hat{I}_{z} \xrightarrow{\hat{I}_{x}(\frac{\pi}{2})} \hat{I}_{y}$$

$$\xrightarrow{\hat{I}_{z}(\Omega\tau)} \hat{I}_{y} \cos \Omega\tau + \hat{I}_{x} \sin \Omega\tau$$

$$\xrightarrow{\hat{I}_{y}(\pi)} \hat{I}_{y} \cos \Omega\tau - \hat{I}_{x} \sin \Omega\tau$$

$$\stackrel{\hat{I}_z(\Omega\tau)}{\longrightarrow} (\hat{I}_y \cos \Omega \tau + \hat{I}_x \sin \Omega \tau) \cos \Omega \tau
-(\hat{I}_x \cos \Omega \tau - \hat{I}_y \sin \Omega \tau) \sin \Omega \tau
= \hat{I}_y \cos^2 \Omega \tau + \hat{I}_y \sin^2 \Omega \tau = \hat{I}_y$$

Coherence Space



I thought we really cared not about the operators themselves but the physical quantities $\langle \hat{I}_x \rangle$, $\langle \hat{I}_y \rangle$, and $\langle \hat{I}_z \rangle$?

Two-spin Coherence Space

• Product operators form an orthonormal basis in coherence space.

$$\hat{\sigma} = \sum_{j} \sigma_{j} \hat{C}_{j}, \quad \operatorname{Tr}(\hat{C}_{j}, \hat{C}_{k}) = \delta_{jk}, \quad \hat{C}_{j} \in \{\frac{1}{2} \hat{E}, \hat{I}_{x}, \hat{S}_{x}, \hat{I}_{y}, \hat{S}_{y}, \dots, 2\hat{I}_{z} \hat{S}_{z}\}$$
16 terms for a two-spin system

• Remembering that for any physical quantity $C \Rightarrow \langle \hat{C} \rangle = \text{Tr}(\hat{\sigma}\hat{C})$

$$\hat{\sigma} = \sum_{j} \overline{\langle \hat{C}_{j} \rangle} \hat{C}_{j} \iff \begin{pmatrix} \frac{1}{\langle I_{x} \rangle} \\ \frac{\langle S_{x} \rangle}{\langle S_{x} \rangle} \end{pmatrix}$$
 "vector" in a 16-D coherence (Liouville) space of the corresponding operators!

- MR is all about rotations of $\hat{\sigma}$ in coherence space.
- Given that coherence space is 16-D for a 2-spin system, life can get pretty complicated (not to mention higher-order spin systems).
- Fortunately, we'll only need to deal with sequential rotations in 3-D subspaces.

The Master Equation, revisited

• Once again, we start with our favorite relation for cyclically commuting operators:

$$e^{i\theta \hat{A}}\hat{B} = \hat{B}\cos\theta + i[\hat{A},\hat{B}]\sin\theta$$

• Examination of the Appendix listing two-spin product operator commutators (see end of lecture) reveals that the commutators for *all* two-spin product operators are cyclical!

i.e. in superoperator notation:
$$\hat{A}\hat{A}\hat{B} = \hat{B}$$

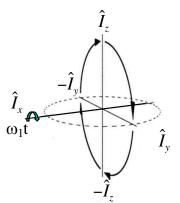
• Hence, ignoring relaxation, all possible rotations of $\hat{\sigma}$ can be fully described by the following equation:

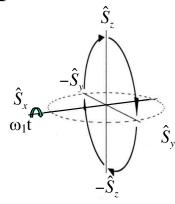
$$\hat{C}_{p} \xrightarrow{\hat{C}_{q}(\theta)} \begin{cases} \hat{C}_{p} & \text{if } [\hat{C}_{q}, \hat{C}_{p}] = 0 \\ \hat{C}_{p} \cos \theta - i[\hat{C}_{q}, \hat{C}_{p}] \sin \theta & \text{if } [\hat{C}_{q}, \hat{C}_{p}] \neq 0 \end{cases}$$
where \hat{C}_{p} and \hat{C}_{q} are any pair of product operators.

The 3 Basic Rotations: RF Excitation

• Rotation axes the same as before for both the *I* and *S* spins.

For an x pulse: $\hat{H} = -\omega_1^I \hat{I}_x - \omega_1^S \hat{S}_x$ rotation axes (note $[\hat{I}_x, \hat{S}_x] = 0$)





Examples

$$\hat{I}_{z} \xrightarrow{\hat{I}_{x}(\frac{\pi}{2})} \hat{I}_{y}$$

$$\hat{S}_{z} \xrightarrow{\hat{S}_{x}(\pi)} -\hat{S}_{z}$$

$$\hat{I}_{z} \xrightarrow{\hat{S}_{x}(\frac{\pi}{2})} \hat{I}_{z}$$

$$\hat{I}_{z}\hat{S}_{z} \xrightarrow{\hat{S}_{x}(\frac{\pi}{2})} \Rightarrow \hat{I}_{z}\hat{S}_{y}$$

$$\hat{I}_{x}\hat{S}_{z} \xrightarrow{\hat{S}_{x}(\frac{\pi}{2})} \Rightarrow \hat{I}_{y}(\frac{\pi}{2}) \Rightarrow \hat{I}_{z}\hat{S}_{y}$$

$$\hat{I}_{x}\hat{S}_{z} \xrightarrow{\hat{I}_{y}(\pi)} \Rightarrow \hat{I}_{y}(\frac{\pi}{2}) \Rightarrow \hat{I}_{z}\hat{S}_{y}$$
Does the order of the RF pulses matter?

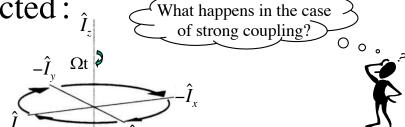
What if the RF pulses are simultaneous?

The 3 Basic Rotations: Chemical Shift

$$\hat{H} = -\Omega_I \hat{I}_z - \Omega_S \hat{S}_z + 2\pi J \hat{I}_z \hat{S}_z$$
rotation axes

• $\hat{H} = -\Omega_{I}\hat{I}_{z} - \Omega_{S}\hat{S}_{z} + 2\pi\hat{I}_{z}\hat{S}_{z}$ Note: $[\hat{I}_{z},\hat{S}_{z}] = 0$ $[\hat{I}_{z},\hat{I}_{z}\hat{S}_{z}] = 0$ $[\hat{S}_{z},\hat{I}_{z}\hat{S}_{z}] = 0$...hence, rotations can be treated independently. The if $[\hat{A}.\hat{B}] = 0$ then $e^{\hat{A}+\hat{B}} = e^{\hat{A}}e^{\hat{B}} = e^{\hat{B}}e^{\hat{A}}$

- $\{\hat{I}_x, \hat{I}_y, \hat{I}_z\}$ and $\{\hat{S}_x, \hat{S}_y, \hat{S}_z\}$ behave as expected: $\hat{I}_{r} \xrightarrow{\hat{I}_{z}(\Omega_{I}t)} \hat{I}_{r} \cos \Omega_{I}t - \hat{I}_{v} \sin \Omega_{I}t$
 - $\hat{S}_x \xrightarrow{\hat{S}_z(\Omega_S t)} \hat{S}_x \cos \Omega_S t \hat{S}_y \sin \Omega_S t$



• Product operators, such as $\hat{I}_x \hat{S}_x$, behave similarly. For example, under $\hat{H} = -\Omega_I \hat{I}_z$, $\hat{I}_x \hat{S}_n$ rotates in the $\hat{I}_x \hat{S}_n$, $\hat{I}_y \hat{S}_n$ plane where p is x, y, or z.

$$\hat{I}_{x}\hat{S}_{x} \xrightarrow{\hat{I}_{z}(\Omega_{I}t)} \hat{I}_{x}\hat{S}_{x}\cos\Omega_{I}t - \hat{I}_{y}\hat{S}_{x}\sin\Omega_{I}t$$

$$\hat{I}_{x}\hat{S}_{x} \xrightarrow{\hat{S}_{z}(\Omega_{S}t)} \hat{I}_{x}\hat{S}_{x}\cos\Omega_{S}t - \hat{I}_{x}\hat{S}_{y}\sin\Omega_{S}t$$

$$\hat{I}_{x}\hat{S}_{x} \xrightarrow{\hat{I}_{z}(\Omega_{I}t)} \hat{S}_{z}(\Omega_{S}t) \Rightarrow \hat{S}_{z}(\Omega_{S}t) \Rightarrow ?$$

The Three Basic Rotations: J coupling

$$\hat{H} = -\Omega_I \hat{I}_z - \Omega_S \hat{S}_z + 2\pi J \hat{I}_z \hat{S}_z$$

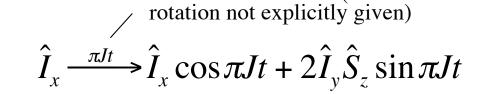
$$[\hat{I}_z, \hat{S}_z] = 0 \quad [\hat{I}_z, \hat{I}_z \hat{S}_z] = 0 \quad [\hat{S}_z, \hat{I}_z \hat{S}_z] = 0$$

$$\dots \text{hence, rotations can be treated independently.}$$

$$[\hat{I}_z, \hat{S}_z] = 0$$
 $[\hat{I}_z, \hat{I}_z, \hat{S}_z] = 0$ $[\hat{S}_z, \hat{I}_z, \hat{S}_z] = 0$

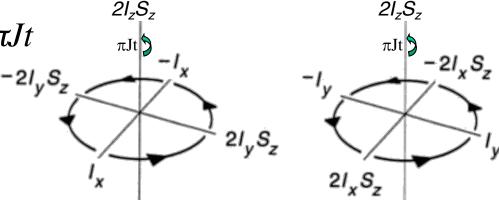
Using the Master Equation:

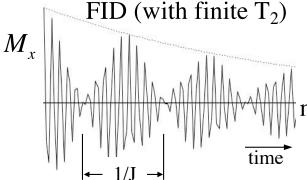
$$\hat{I}_{x} \xrightarrow{2\hat{I}_{z}\hat{S}_{z}(\pi Jt)} \hat{I}_{x} \cos \pi Jt + 2\hat{I}_{y}\hat{S}_{z} \sin \pi Jt$$



Alternative notation (axis of

$$\hat{I}_{y} \xrightarrow{2\hat{I}_{z}\hat{S}_{z}(\pi Jt)} \hat{I}_{y} \cos \pi Jt - 2\hat{I}_{x}\hat{S}_{z} \sin \pi Jt$$





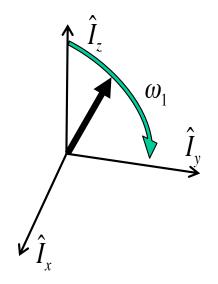
Under J-coupling, transverse magnetization oscillates between inphase/anti-phase coherences (plot shown with chemical shift Ω_I)

Much easier than direct matrix computations

Sign Conventions

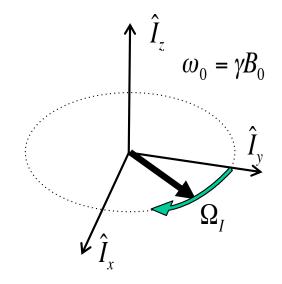
Given:
$$\hat{\sigma}(t) = e^{-i\hat{H}t}\hat{\sigma}(0)$$
 and $\hat{H} = -\Omega_I\hat{I}_z - \Omega_S\hat{S}_z + 2\pi J\hat{I}_z\hat{S}_z$

RF excitation



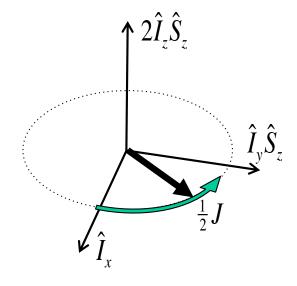
Left-handed rotation

Chemical shift



Left-handed rotation

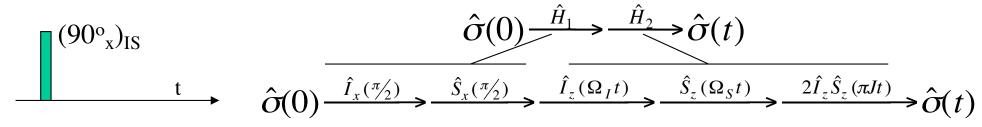
J coupling



Right-handed rotation

(or left-handed rotation with frequency –J/2)

Example 1: 90-acquire



• Starting with the *I* spin...

$$\hat{I}_{z} \xrightarrow{\hat{I}_{x}(\pi/2)} \hat{I}_{y} \xrightarrow{\hat{S}_{x}(\pi/2)} \hat{I}_{y} \xrightarrow{\hat{I}_{z}(\Omega t)} \hat{I}_{y} \cos \Omega_{I} t + \hat{I}_{x} \sin \Omega_{I} t \xrightarrow{\hat{S}_{z}(\Omega t)} \hat{I}_{y} \cos \Omega_{I} t + \hat{I}_{x} \sin \Omega_{I} t$$

$$\xrightarrow{2\hat{I}_{z}\hat{S}_{z}(\pi J t)} \hat{I}_{y} \cos \Omega_{I} t + \hat{I}_{x} \sin \Omega_{I} t) \cos \pi J t + \left(2\hat{I}_{y}\hat{S}_{z} \sin \Omega_{I} t - 2\hat{I}_{x}\hat{S}_{z} \cos \Omega_{I} t\right) \sin \pi J t$$
"in-phase coherence"
"anti-phase coherence"
"observable"
"unobservable"

• Similarly for the *S* spin...

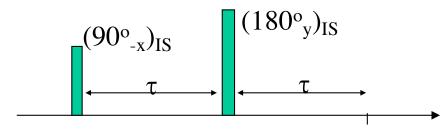
$$\xrightarrow{\hat{H}_1} \xrightarrow{\hat{H}_2} (\hat{S}_y \cos \Omega_S t - \hat{S}_x \sin \Omega_S t) \cos \pi J t + (2\hat{I}_z \hat{S}_y \sin \Omega_S t - 2\hat{I}_z \hat{S}_x \cos \Omega_S t) \sin \pi J t$$

• With all the constants, the recorded spectrum would look like:

$$M_{y}^{I} = \gamma_{I}^{2} \frac{\rho \hbar^{2} B_{0}}{8kT}$$
Spectrum
$$M_{y}^{S} = \gamma_{S}^{2} \frac{\rho \hbar^{2} B_{0}}{8kT}$$

$$M_{y}^{S} = \gamma_{S}^{2} \frac{\rho \hbar^{2} B_{0}}{8kT}$$

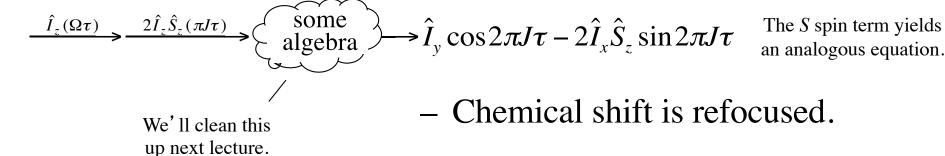
Example 2: Spin Echo



• Continuing from Example 1, the *I* spin term prior to the 180 is:

$$(\hat{I}_y \cos \Omega_I \tau + \hat{I}_x \sin \Omega_I \tau) \cos \pi J \tau + (2\hat{I}_y \hat{S}_z \sin \Omega_I \tau - 2\hat{I}_x \hat{S}_z \cos \Omega_I \tau) \sin \pi J \tau$$

$$\xrightarrow{\hat{I}_y(\pi)} (\hat{I}_y \cos \Omega_I \tau - \hat{I}_x \sin \Omega_I \tau) \cos \pi J \tau + (2\hat{I}_y \hat{S}_z \sin \Omega_I \tau + 2\hat{I}_x \hat{S}_z \cos \Omega_I \tau) \sin \pi J \tau$$



 J-coupling continues to evolve over the entire 2τ time period.

Summary

- The three basic rotations define a set of algebraic rules for product operators (weakly coupled spin 1/2 systems).
 - Step 1: Write down the Hamiltonian

RF excitation:
$$\hat{H} = -\omega_1^I \hat{I}_x - \omega_1^S \hat{S}_x$$
 (x pulse)

Free precession:
$$\hat{H} = -\Omega_I \hat{I}_z - \Omega_S \hat{S}_z + 2\pi J \hat{I}_z \hat{S}_z$$

- Step 2: Compute the product operator rotations.
- If you want, you can now forget all about quantum mechanics, kets, bras, operators, etc...and just systematically following these algebraic rules to find out what happens in any number of MR pulse sequences. Then use the orthogonal expansion property of $\hat{\sigma}$ to write down M_x , M_y , and M_z .

Next Lecture: Product Operator Formalism II

Appendix 2-spin Product Operator Commutators

	\hat{I}_x	\hat{I}_{y}	\hat{I}_z	\hat{S}_x	\hat{S}_y	\hat{S}_z	$2\hat{I}_x\hat{S}_x$	$2\hat{I}_x\hat{S}_y$	$2\hat{I}_x\hat{S}_z$	$2\hat{I}_y\hat{S}_x$	$2\hat{I}_{y}\hat{S}_{y}$	$2\hat{I}_y\hat{S}_z$	$2\hat{I}_z\hat{S}_x$	$2\hat{I}_z\hat{S}_y$	$2\hat{I}_z\hat{S}_z$
\hat{I}_x	0	$i\hat{I}_z$	$-i\hat{I}_{y}$	0	0	0	0	0	0	$i2\hat{I}_z\hat{S}_x$	$i2\hat{I}_z\hat{S}_y$	$i2\hat{I}_z\hat{S}_z$	$-i2\hat{I}_y\hat{S}_x$	$-i2\hat{I}_{y}\hat{S}_{y}$	$-i2\hat{I}_y\hat{S}_z$
\hat{I}_{y}	$-i\hat{I}_z$	0	$i\hat{I}_x$	0	0	0	$-i2\hat{I}_z\hat{S}_x$	$-i2\hat{I}_z\hat{S}_y$	$-i2\hat{I}_z\hat{S}_z$	0	0	0	$i2\hat{I}_x\hat{S}_x$	$i2\hat{I}_x\hat{S}_y$	$i2\hat{I}_x\hat{S}_z$
\hat{I}_z	$i\hat{I}_{y}$	$-i\hat{I}_x$	0	0	0	0	$i2\hat{I}_{y}\hat{S}_{x}$	$i2\hat{I}_{y}\hat{S}_{y}$	$i2\hat{I}_{y}\hat{S}_{z}$	$-i2\hat{I}_x\hat{S}_x$	$-i2\hat{I}_x\hat{S}_y$	$-i2\hat{I}_x\hat{S}_z$	0	0	0
\hat{S}_x	0	0	0	0	$i\hat{S}_z$	$-i\hat{S}_{y}$	0	$i2\hat{I}_x\hat{S}_z$	$-i2I_xS_y$	0	$i2\hat{I}_y\hat{S}_z$	$-i2\hat{I}_y\hat{S}_y$	0	$i2\hat{I}_z\hat{S}_z$	$-i2\hat{I}_z\hat{S}_y$
\hat{S}_{y}	0	0	0	$-i\hat{S}_z$	0	$i\hat{S}_x$	$-i2\hat{I}_x\hat{S}_z$	0	$i2\hat{I}_x\hat{S}_x$	$-i2\hat{I}_y\hat{S}_z$	0	$i2\hat{I}_y\hat{S}_x$	$-i2\hat{I}_z\hat{S}_z$	0	$i2\hat{I}_z\hat{S}_x$
$\frac{\hat{S}_{y}}{\hat{S}_{z}}$ $\frac{2\hat{I}_{x}\hat{S}_{x}}{2\hat{I}_{x}\hat{S}_{x}}$	0	0	0	iŜ _y	$-i\hat{S}_x$	0	$i2\hat{I}_x\hat{S}_y$	$-i2\hat{I}_x\hat{S}_x$	0	$i2\hat{I}_{y}\hat{S}_{y}$	$-i2\hat{I}_y\hat{S}_x$	0	$i2\hat{I}_z\hat{S}_y$	$-i2\hat{I}_z\hat{S}_x$	0
$2\hat{I}_x\hat{S}_x$	0	$i2\hat{I}_z\hat{S}_x$	$-i2\hat{I}_y\hat{S}_x$	0	$i2\hat{I}_x\hat{S}_z$	$-i2\hat{I}_x\hat{S}_y$	0	$i\hat{S}_z$	$-i\hat{S}_{y}$	$i\hat{l}_z$	0	0	$-i\hat{I}_{y}$	0	0
$2\hat{I}_{r}\hat{S}_{v}$	0	$i2\hat{I}_z\hat{S}_y$	$-i2\hat{I}_{y}\hat{S}_{y}$	$-i2\hat{I}_x\hat{S}_z$	0	$i2\hat{I}_x\hat{S}_x$	$-i\hat{S}_z$	0	$i\hat{S}_x$	0	$i\hat{I}_z$	0	0	$-i\hat{I}_{y}$	0
$\frac{\hat{2}\hat{I}_x\hat{S}_z}{2\hat{I}_x\hat{S}_z}$	0	$i2\hat{I}_z\hat{S}_z$	$-i2\hat{I}_y\hat{S}_z$	$i2\hat{I}_x\hat{S}_y$	$-i2\hat{I}_x\hat{S}_x$	0	iŜ _y	$-i\hat{S}_x$	0	0	0	$i\hat{I}_z$	0	0	$-i\hat{I}_{y}$
$\frac{2\hat{I}_{y}\hat{S}_{x}}{2\hat{I}_{y}\hat{S}_{x}}$	$-i2\hat{I}_z\hat{S}_x$	0	$i2\hat{I}_x\hat{S}_x$	0	$i2\hat{I}_y\hat{S}_z$	$-i2\hat{I}_{y}\hat{S}_{y}$	$-i\hat{I}_z$	0	0	0	$i\hat{S}_z$	$-i\hat{S}_{y}$	$i\hat{I}_x$	0	0
$2\hat{I}_{y}\hat{S}_{y}$	$-i2\hat{I}_z\hat{S}_y$	0	$i2\hat{I}_x\hat{S}_y$	$-i2\hat{I}_y\hat{S}_z$	0	$i2\hat{I}_y\hat{S}_x$	0	$-i\hat{I}_z$	0	$-i\hat{S}_z$	0	$i\hat{S}_x$	0	$i\hat{I}_x$	0
$2\hat{I}_y\hat{S}_z$	$-i2\hat{I}_z\hat{S}_z$	0	$i2\hat{I}_x\hat{S}_z$	$i2\hat{I}_{y}\hat{S}_{y}$	$-i2\hat{I}_y\hat{S}_x$	0	0	0	$-i\hat{I}_z$	$i\hat{S}_{y}$	$-i\hat{S}_x$	0	0	0	$i\hat{I}_x$
$2\hat{I}_z\hat{S}_x$	$i2\hat{I}_y\hat{S}_x$	$-i2\hat{I}_x\hat{S}_x$	0	0	$i2\hat{I}_z\hat{S}_z$	$-i2\hat{I}_z\hat{S}_y$	$i\hat{I}_{y}$	0	0	$-i\hat{I}_x$	0	0	0	$i\hat{S}_z$	$-i\hat{S}_{y}$
$\frac{2I_{y}S_{y}}{2\hat{I}_{z}\hat{S}_{z}}$ $\frac{2\hat{I}_{z}\hat{S}_{x}}{2\hat{I}_{z}\hat{S}_{y}}$ $\frac{2\hat{I}_{z}\hat{S}_{y}}{2\hat{I}_{z}\hat{S}_{z}}$	$i2\hat{I}_{y}\hat{S}_{y}$	$-i2\hat{I}_x\hat{S}_y$	0	$-i2\hat{I}_z\hat{S}z$	0	$i2\hat{I}_z\hat{S}_x$	0	$i\hat{I}_{y}$	0	0	$-i\hat{I}_x$	0	$-i\hat{S}_z$	0	$i\hat{S}_x$
$2\hat{I}_z\hat{S}_z$	$i2\hat{I}_y\hat{S}_z$	$-i2\hat{I}_x\hat{S}_z$	0	$i2\hat{I}_z\hat{S}_y$	$-i2\hat{I}_z\hat{S}_x$	0	0	0	$i\hat{I}_{y}$	0	0	$-i\hat{I}_x$	$i\hat{S}_{y}$	$-i\hat{S}_x$	0