

Factor	Situation(s)	Context(s)	Base Distance = 57cm Estimated Adjustment for Factor (± 0.5cm)
Attribute or Factor of Robot			
Mechanoid Robot	RH Approach	All	-3
	HR Approach		-7
Humanoid Robot	RH Approach	All	+3
	HR Approach		-1
Verbal Communication	RH Approach	Verbal Interaction	+3
Giving object	RH Approach	Physical Interaction	-7
Taking object	RH Approach	Physical Interaction	-7?
Passing	RH Approach	No Interaction	+4
Direction from:	RH Approach	Front	+2
		Right/Left	-2
Attribute or Factor of Human			
Preferred Robot Humanoid	RH Approach	All Private	-3
Preferred Robot Mechanoid	RH Approach	All	+3
Preferred Height Tall	RH Approach	All	-1
Preferred Height Short	RH Approach	All	+2
Uncertainty or perceived inconsistency	HR Approach	Initial Encounter	+13
Verbal Communication	HR Approach	Verbal Interaction	+3
Giving object	HR Approach	Physical Interaction	-7?
Taking object	HR Approach	Physical Interaction	-7?
Passing	HR Approach	No Interaction	+4