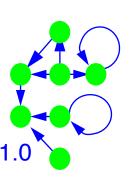
## **Deterministic Actions:**

T: S × A → S For each state and action we specify a new state.



## Stochastic Actions:

•  $T: S \times A \rightarrow Prob(S)$  For each state and action we specify a probability distribution over next states. Represents the distribution  $P(s' \mid s, a)$ .