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1 Introduction

Cells are one of the fundamental units of life. They show an immense complexity and diversity. Their identity and function is determined by environmental stimuli, the physical environment, the cell cycle and neighbouring cells (Wagner et al., 2016). Only recently has it been possible to investigate the full transcriptome of a single cell. Single-cell RNA sequencing (scRNA-seq) was first published by Tang et al. (2009). This method addresses new biological issues, such as the identification of rare cell populations, and allows us to measure the frequency of cell types in tissues, characterise differences in similar cell types and investigate the heterogeneity of cell states or cell lineages (Andrews and Hemberg, 2017).

A typical scRNA-seq workflow consists of the isolation of single cells, the extraction of RNA, cDNA library preparation, and the amplification and sequencing of the libraries (see Figure 1). A wide variety of scRNA-seq protocols exists, differing in throughput, full transcript or 3' sequencing, costs and automatisation. Small-scale protocols are standard PCR plate-based methods or methods in which cell isolation and library preparation are combined into one protocol. A typical small-scale method is the PCR plate-based SMART-seq2 (Picelli et al., 2013). Full-transcripts are sequenced using a standard Illumina approach. Typically, hundreds of cells are processed and spike-ins from the External RNA Control Consortium (ERCC) is used for normalisation. On the other side of the spectrum are droplet-based methods such as Drop-seq and 10xChromium, which allow the processing of thousands of cells.

The differences between scRNA-seq and bulk experiments are the lower sequencing depth (100,000–5 million reads per cell) compared to bulk experiments, higher variability and more outliers in the scRNA-seq data. scRNA-seq data suffers from technical noise, batch effects and low capture efficiency. Confounding occurs when different biological conditions are processed in different batches, making the deconvolution of technical noise and biological effect impossible. This should be avoided by an appropriate experimental design that allows for the statistical deconvolution between unwanted and wanted variation. In scRNA-seq the single experimental unit is the cell, making it not always possible to use this approach. Different cells in an experiment may need different sample processing, or their biological differences may affect the downstream analyses.

The starting amounts of the library preparation can be as low as ten picogrammes of total RNA (Picelli et al., 2013). Two main issues arising due to the low starting amount are overamplification and low capture efficiency. Low and moderate expressed genes are not captured during the reverse transcription, which leads to dropouts of genes and a zero-inflated gene expression. scRNA-seq data has an excess of zero counts, which can be split into systematic, semi-systematic and stochastic zeros (Lun et al., 2016a). Systematic zeros and semi-systematic zeros come from genes that are silent in a subpopulation or across all cells, respectively. Stochastic zeros are zero counts that have been obtained due to a low capture efficiency during the library preparation. They affect genes with a count distribution near zero and have to be dealt with the normalisation steps.

To deal with technical noise Unique Molecular Identifiers (UMI) or spike-ins are used. UMI are short random barcodes attached to the single-stranded cDNA in the reverse transcriptase process. By counting the unique UMI reads aligned to the genome an estimated tag count is obtained. Spike-in are added before amplification. Under the assumption that the amplification of the endogenous and exogenous RNA is similar, they can be used for library size normalisation and to remove technical noise.

In general, scRNA-seq experiments consist of high-dimensional data. High-dimensional data suffers from the curse of dimensionality (Wagner et al., 2016), which means the distances in high-dimensional data become unstable and subpopulations cannot be separated (Andrews and

Hemberg, 2017). Additionally, computational requirements are high. Reduction of the dimension is made by two approaches. Using linear or non-linear projections of the data from the original high-dimensional to a lower-dimensional space, or by feature selection, in which uninformative genes are removed.

The characterizing of the composition in a sample is one of the most common aims for scRNA-seq data. Lately, a broad spectrum of clustering methods have been specifically developed for the clustering of single cells. The aim of this study is to evaluate clustering methods for scRNA-seq data.

Single Cell RNA Sequencing Workflow

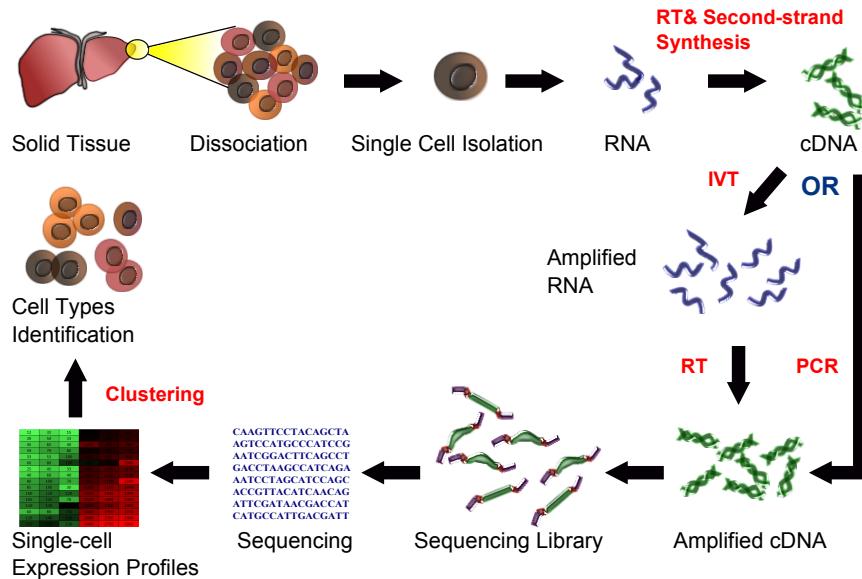


Figure 1: scRNA-seq workflow. Taken from Wikipedia.

2 Methods

2.1 Dimension reduction

All methods require a dimension reduction step before clustering. Commonly used methods are either Principal Component Analysis (PCA) (Hotelling, 1933) or t-distributed Stochastic Neighbour Embedding (tSNE). Given a data matrix $X(nxp)$ with n measurements and p random variables, and we want to reduce the dimension from p to q random variables. Then, PCA finds the linear combinations $a_1x^T, a_2x^T, \dots, a_qx^T$ which have the successive maximum variance, subject to the constraint that its sample correlations with previous a_kx^T equals zero. Or in other words, PCA finds a rotation of the original data in which the newly obtained first coordinates have the highest possible variance, the second coordinates the second-greatest variance etc. The linear combinations are the so called principal components. Practically, PCA is computed by spectral decomposition of the correlation R or covariance matrix S . The vectors a_1, a_2, \dots, a_q are the eigenvectors of S corresponding to the q largest eigenvalues (Jolliffe, 1986). Dimension reduction is achieved either by selecting only the first few PCs whose eigenvalues are above the average, or by determining the number graphically by plotting the eigenvalues (scree plot). PCA is deterministic and relatively fast but restricted to linear spaces.

In contrast, tSNE is a non-linear mapping (Van Der Maaten, 2013). Stochastic neighbour embedding (SNE) transforms Euclidean distances to conditional probabilities $p_{j|i}$. That is the probability that x_j is the nearest neighbour of x_i under a Gaussian centred at x_i . The low-dimensional counterpart $q_{i|j}$ is similar with a Gaussian centered at y_i and variance of $1/\sqrt(2)$. SNE minimises the divergence between $p_{j|i}$ and $q_{j|i}$ using the Kullback-Leibler divergence. tSNE implements a Student's t-distribution for the low dimensional space and a symmetric version of the cost function to simplify optimisation and to overcome the crowding problem. In tSNE, the cost function uses the joint probabilities p_{ij} and q_{ij} instead of conditional probabilities. To deal with large datasets, the Barnes-Hut implementation uses random walks on the nearest neighbour network with a PCA step to reduce the dimensionality of the high-dimensional data. tSNE is stochastic, depends on a perplexity parameter and distances between clusters are not preserved.

2.2 Clustering methods

Identifying unknown cell populations is one of the main uses of scRNA-seq data (Andrews and Hemberg, 2017). Eleven clustering methods have been evaluated for this study. These methods and algorithms can be roughly classified into three groups: K-means, graph-clustering and hierarchical-based clustering. SC3, SIMLR, Linnorm and RaceID use k-means in different fashions, while pcaReduce and CIDR are based on hierarchical clustering. The graph-based methods are SNN-Cliq and Seurat. An overview of the methods is given in Table ...

K-means K-means clustering finds a predefined number of centres k and cell assignments, such that their within-group sum of squares is minimised (Hartigan and Wong, 1979). k cluster centres are randomly assigned. Each data point is then assigned to the nearest centre using Euclidean distances. The centres are then recomputed using the average of the data points that are assigned to each of the k centres. This procedure is iterated until the algorithm converges. The assigning of the centres is random. Also, it's not guaranteed to find the global minimum. The drawbacks of the method are that it assumes spherical clusters and this is sensitive to scaling.

pcaReduce pcaReduce uses k-means clustering to find the number of clusters in the reduced dimension given by PCA (Yau et al., 2016). The main assumption is that large classes of cells

Table 1: Add caption

Method	Description	dimension reduction	re-clustering	dropout	normalization	unsupervised
tSNEkmeans	tSNE dimension reduction and kmeans clustering	tSNE	kmeans	no	no	no
pcaReduce	PCA dimension reduction and kmeans clustering through an iterative process. Step wise merging of cluster by joint probabilities and reducing the number of dimension by PC with lowest variance	PCA	kmeans, hierarchical clustering	no	no	yes
SC3	PCA dimension reduction or Laplacian graph. Kmeans clustering on different dimensions. Hierarchical clustering on consensus matrix obtained by kmeans	PCA	repeated kmeans, hierarchical clustering on similarity matrix of kmeans	no	no	yes
SNNCliq	Shared nearest neighbor graph based on similarities. Clustering through forming of cliques and subsequent merging.	graph based	merging of cliques	no	no	no
dbscan	Density based clustering	none	density based clustering	no	no	yes
SIMLR		tSNE	kmeans	yes	no	yes
CIDR	PCA dimension reduction based on zero imputed similarities. Hierarchical clustering on a number of PC determined by variation of scree method.	PCA	hierarchical clustering	yes	no	yes
Seurat	Nearest neighbor graph based on PCA latent space	HVG and PCA		no	yes	yes
TSCAN		PCA	graph based	no	yes	no
Linnorm	Normalisation using a subset of genes and clustering through tSNE/PCA and kmeans	tSNE and kmeans	kmeans	yes	yes	yes
RaceID	-		kmeans	no	yes	yes

are contained in low-dimension PC representation and more refined subsets of these cells types are contained in higher-dimensional PC representations. Given a gene expression matrix, the clustering algorithm starts with a k-means clustering on the PCA projections $Y_{n \times q}$ with $q + 1$ clusters, where n is the number of cells and q are the number of PCs. The number of initial clusters k is typically around 30, guaranteeing that most cell types are captured. For all pairs of clusters, the joint probabilities are computed. Two clusters are merged by selecting the pair with the highest joint probability or by sampling proportionally by the joint probabilities. The number of clusters is now decreased to $k - 1$. Next, the PC with the lowest variance is deleted and a k-means clustering with $k - 2$ centers is performed. This process is repeated until only one single cluster remains. When using `pcaReduce` q cluster partitions with $k - 1$ clusters are obtained. The user can than choose the clustering with the desired number of clusters.

SC3 Implemented in the SC3 method is gene- and cell-filtering, as well as a log transformation step of the expression matrix (Kiselev et al., 2017). The filtered expression matrix is then used to compute Euclidean, Pearson and Spearman dissimilarity measures. By PCA or Laplacian graphs a lower-dimensional representation of the data is obtained. K-means clustering is then performed on the different dimensions. Next, a consensus matrix of the different clustering results is computed. The consensus matrix is a binary similarity matrix with entry one if two cells belong to the same cluster and zero otherwise. The consensus matrix is obtained by averaging the individual clustering. The last step is a hierarchical clustering step with complete linkage. The cluster is inferred by the k level of hierarchy, where k can be supplied by the user. The method allows for the estimation of k . (Using the covariance matrix of the expression matrix the function finds the eigenvalues. The Tracy-Widom test is used for estimating the number of significant eigenvalues, which represent the number of estimated k .) To reduce runtime, SC3 changes the clustering method when supplied with more than 5'000 cells. Randomly selected cells are then used for the clustering approach described above. These subpopulations are then used to train a support vector machine to infer the cluster labels of the remaining cells.

SNNcliq SNNcliq computes a shared nearest-neighbour-graph based on the high-dimensional data (Xu and Su, 2015). The nodes are the data points and the weighted edges are the similarities between the data points. Cells are defined as a cluster if they have a defined number of edges between them, forming a "clique".

A similarity matrix using Euclidean or other similarity measures is then computed. Using this similarity matrix, the k-nearest-neighbours (KNN) for each data point are listed. The number of nearest neighbours has to be supplied by the user. Edges between data points are assigned if they share at least one KNN. The weights of the edges are defined by a function of the number of nearest neighbours and their respective ranks. Identification of clusters is made by finding quasi-cliques associated with each node and merging them to unique clusters by the use of a greedy algorithm. A node induces a subgraph, which consists of all neighbour nodes and edges. For each node, a local degree is computed and a node is removed from the subgraph if its degree is lower than a given threshold which is proportional to the size of the clique. The threshold is supplied by the user and is typically set to 0.7. Next, the degrees between the nodes are recomputed and the process is repeated until no more nodes can be removed. A subgraph is assigned to a quasi-clique if it contains more than three nodes. To reduce redundancy, quasi-cliques that are completely included in other cliques are removed as well. Clusters are then identified by merging the quasi-cliques. For each pair, an overlapping rate is computed. If it exceeds a predefined threshold m the subgraphs are merged. Merging in different orders leads to different results, so pairs with larger sizes are prioritized.

SIMLR Most clustering methods rely on standard similarity metrics like Euclidean distances (Wang et al., 2017). SIMLR uses a weighted function of multiple kernels to compute a distance matrix. The assumptions is that the matrix has a block-diagonal structure, where the blocks represent the clusters c . The kernels are Gaussian kernels with a range of hyperparameters defining the variance of each kernel. The similarities are then used for data visualisation with tSNE or clustering using k-means on the latent space representations of the similarities.

CIDR Clustering through Imputation and Dimensionality Reduction (CIDR) takes the high dropout rate in scRNA-seq data into account (Lin et al., 2017). The method splits the squared Euclidean distance into three terms. These consist of one term in which both genes k for the cell pairs i an j are non-zero, a second term in which one gene is zero and a third where both are zero. The authors state that only the cases where one gene is zero have a strong influence on the distances and the subsequent dimension reduction and clustering. To reduce the dropout-induced zero inflation, the method imputes the third term by its expected value given the distribution of the dropouts. The algorithm works basically in five steps: (i) Find features that are dropout candidates. That is genes that show an expression level below a threshold T . (ii) Find the empirical dropout probability $\hat{P}(u)$ using the whole data set. (iii) Calculate the dissimilarity using Euclidean distances together with a pairwise imputation process. Features that fall below the threshold T are imputed using a weighting function. The weighting is based on the probability of being a dropout. (iv) Perform dimension reduction using PCA on the imputed distance matrix. (v) Perform hierarchical clustering using the first few PCs. The number of PCs can be determined by several methods. Here, we use an implemented variation of the scree method.

Linnorm Linnorm is a normalisation and transformation method for count data (Yip et al., 2017). The main assumption is that a homogeneously expressed gene-set exists. Using this gene subset, and by ignoring zero counts, the normalisation and transformation parameters are calculated. After normalisation, the expression values should show both homoscedasticity and normality. Linnorm includes functions for subpopulation analysis by t-SNE or PCA dimension reduction and subsequent k-means or hierarchical clustering.

First, the values are scaled according to library size. Low count genes and genes that show high technical noise are filtered out. By default, genes showing a non-zero expression in at least 75 % of the cells are retained. Note that this threshold is set to maintain at least three non-zero cells per gene, in order to calculate the skewness of the gene distributions. By gradually increasing this threshold only genes that show a negative correlation between the mean and the standard deviation (SD) is assured. A locally weighted scatterplot smoothing (LOWESS) curve is fitted on the mean versus SD relationship. The SD is scaled and outliers based on the SD are removed. Next, genes that show a high skewness are filtered out. The data is then transformed using a modified log transformation. The dimensions are reduced by PCA or tSNE and clustering using the k-means algorithm. The R packages fpc, vegan, mclust and apcluster are used to determine the number of clusters.

TSCAN TSCAN uses a pseudo-time algorithm for cell ordering (Ji and Ji, 2015). PCA dimension reduction on the preprocessed gene expression data is performed. Preprocessing is done by log transformation and by adding a pseudo-count. Low expressed genes are filtered out based on the zero-proportion and their covariance. Clustering is done by model-based clustering. The travelling salesman problem (TSP) is then solved by a minimum spanning tree. The user can then define the start/end point through the available biological information and compute a pseudo-time ordering score.

RaceID Rare Cell Type IDentification (RaceID) is a algorithm developped for the dat prepro-
cessing, detection of outlier cells, kmeans clustering and the inference of rare subpopulations.
Cells are filtered based on a minimum number of transcripts. The expression matrix is nor-
malised by scaling by the library size. To ensure non-zero values a pseudocount of 0.1 is added
to the expression data. Using genefilter genes with a high zero-proportion are filterd out as well.
The implelanted clustering function uses k–means and the clusterboot function from the R pack-
age fpc for clustering. In contrast to the originial k–means clustering in clusterboot, the newly
developped function can use not only euclidean distances. The number of clusters is determined
by the use of the gap statistic implemented in the clusterboot function.

The authors state that the algorithm is based on absolute transcript counts and is not tested
for datasets containing other expression values than counts. With respect datasets other than
the Zheng data the results should be interpreted carefully.

Seurat Seurat uses raw counts, where filtering is both done gene- and cell-wise. A user-
specified threshold for the minimum number of expressed features per cell and the minimum
number of the gene-wise expression per cell has to be defined. The counts from each cell are
normalised by their total counts, scaled by a factor of 10000 and log-transformed. A set of
high-variable genes (HVG) is found by calculationg the average expression and dispersion for
each gene. Based on the average expression the genes are divided into bins. Within each bin
z-scores for the dispersion is calculated. The HVG are then selected by their standart deviation.
Dimension reduction is done by PCA. The number of PCs is deterimed by a permutation test or
graphically by plotting the eigenvalues of the PCs. Clustering is graph-based using a KNN-graph
of the euclidean distances in the PCA space. Clustering of cells is done by SLM ??.

2.3 Datasets

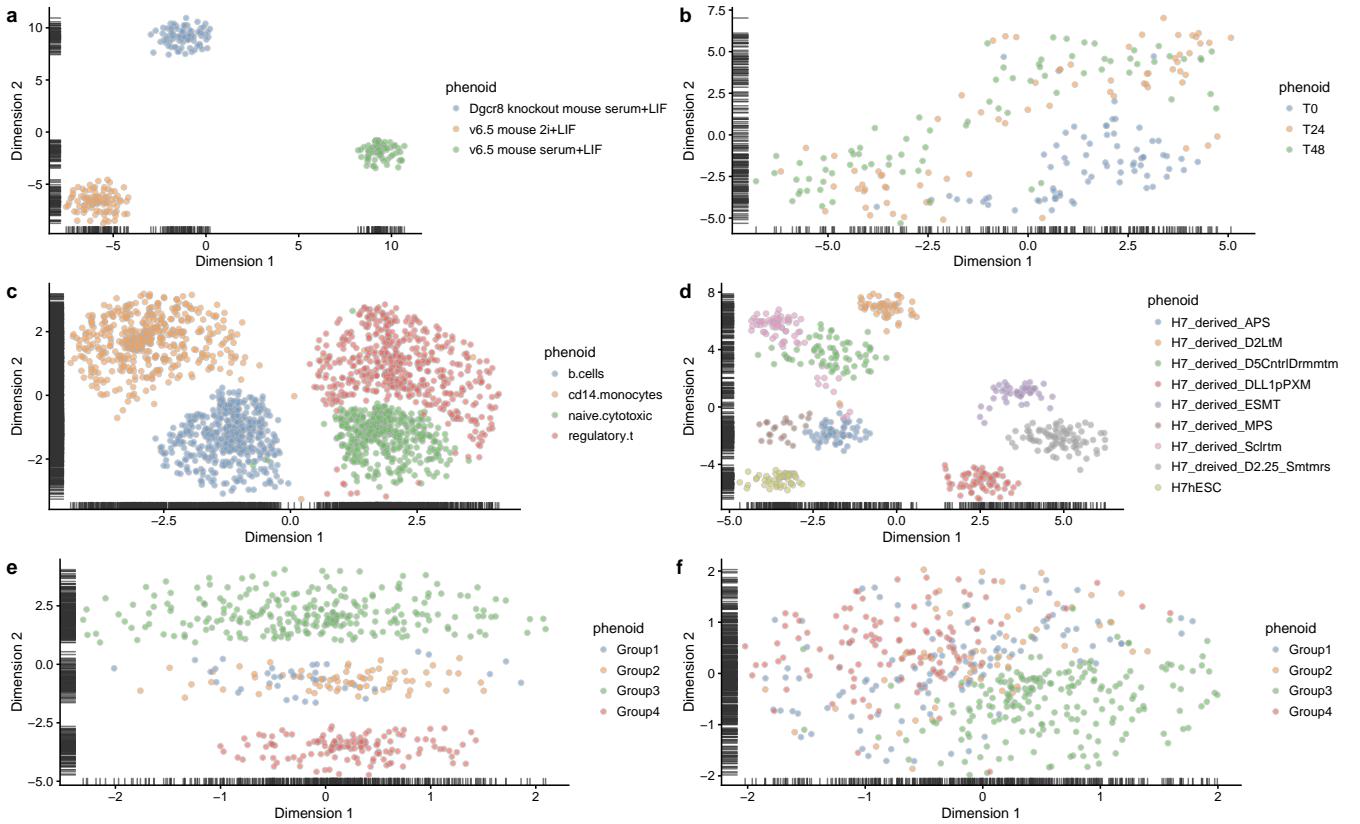


Figure 2: tSNE representation of the datasets (a) Kumar , (b) Trapnell, (c) Zheng, (d) Koh, (e) simDatKumar and (f) simDataKumar2 . The subpopulations in the datasets are color coded.

The datasets Kumar, Trapnell and Koh were downloaded from the *conquer* repository <http://imlspenticton.uzh.ch:3838/conquer>. The Zheng data was downloaded from the 10xChromium repository: <https://support.10xgenomics.com/single-cell-gene-expression/datasets>. For the Kumar, Trapnell and Koh data count-scale Transcripts Per kilobase Million (TPM) are used. These are on a count-scale and are independent from the average length of the transcript (Soneson et al., 2015). The Zheng data consists of UMI counts. Figure ??fig:datatsne) shows the datasets in the tSNE space. Table ?? shows several summary statistic of the datasets. To have a measure of the compactness and difficulty of the datasets the silhouette width were computed. Reported are the average silhouette widths for each dataset.

Kumar et al. (2014) The Kumar dataset consists of *Dgcr8*-knockout and V6.5 variotypes from mouse embryonic stem cells (mESCs). Cells were cultured on a serum with a Leukaemia Inhibitory Factor (LIF) or under Erk and GSK3 signalling inhibition (2Li). The authors investigated the expression of pluripotency factors and their involvement in the heterogeneity of pluripotent stem cells. Sample preparation and whole transcriptome amplification was done using a Fluidigm C1 system and following a SMARTer protocol. Sequencing was done using the Illumina system with paired-end reads. Sequencing depth was 1 million reads per cell.

Trapnell et al. (2014) Trapnell et al. (2014) used human skeletal muscle myoblast cells to investigate temporal differentiation. Cells were expanded under high-mitogen conditions.

Differentiation was induced by switching to low-serum medium. Cells were captured before switching to low-serum medium (T0), after 24 h (T24) and 48h (T48). Between 49 and 77 cells were isolated at each time point and used for single mRNA-Seq library preparation by the use of a Fluidigm C1 system and following a SMARTer protocol. Libraries were sequenced with paired-end sequencing on a HiSeq 2500 (Illumina) platform. Sequencing depth was 4 million reads per library. The authors excluded libraries that contained fewer than 1 million reads.

Koh et al. (2016) H7 human embryonic stem cells (hESCs) were used to study human mesoderm development. Starting from undifferentiated stem cells, several differentiation stages, sorted by time point and further refined by fluorescence-activated cell sorting (FACS) were isolated. Finally, nine different cell lines were obtained: undifferentiated H7 hESCs (H7hESC), anterior primitive streak populations (APS), mid primitive streak populations (MPS), lateral mesoderm (D2LtM), FACS-purified DLL1+ paraxial mesoderm populations (DLL1pPXM), early somite progenitor populations (ESMT), PDGFR+ sclerotome populations (Sclrtm) and two different dermomyotome populations (D5CntrlDRmmmtm). In total, ten different cell types were then sequenced on a Fluidigm C1 system and following a SMARTer protocol. Libraries were sequenced through paired-end sequencing on a HiSeq 2500 (Illumina) platform. Sequencing depth was 1 – 2 million reads per cell.

Zheng et al. (2017) FACS-purified fresh peripheral blood mononuclear cells (PBMCs) were used to assess the performance of the 10xChromium system. Sample preparation and library construction were done with a 10xChromium system. The libraries were sequenced using an Illumina system. For this study, the datasets for CD19+B, CD8+CD45RA+ naive cytotoxic, CD14+ monocytes and CD4+/CD25+ regulatory T cells were used to construct an artificial population. From each library, 200 cells were sampled before being merged to obtain a single expression matrix.

Simulated datasets Using the Splatter package, expression data were simulated (Oshlack et al., 2017). Parameters for the simulation were estimated from a subpopulation of the Kumar dataset. Embryonic stem cell variotypes V6.5 with signalling inhibition and LIF were used for the estimation. SimDataKumar consists of 500 cells with four subpopulations. The fractions per subpopulations were 0.1, 0.15, 0.5 and 0.25 of the total cell population. The probability that a gene is differentially expressed is 0.05, 0.1, 0.2 and 0.4 in the four different groups. Similarly, SimDataKumar2 consists of four subgroups with fractions of 0.2, 0.15, 0.4 and 0.25 of a total of 500 cells. The fractions of differentially-expressed genes were lower, with a probability of 0.01, 0.05, 0.05 and 0.08. The spike-in RNA is excluded before the parameter estimation.

	ncells	nclusters	median library size	median total counts (M)	avg. silhouette
Kumar	268	3	25894	2.0	0.53
Trapnell	288	3	13616	2.0	0.04
Zheng	2000	4	486	0.0	0.10
Koh	651	10	13765	1.0	-0.04
simDataKumar	500	4	29861	2.0	0.15
simDataKumar2	500	4	29974	2.0	0.03

Table 2: Summary statistics of the datasets. Shown are the number of cells, the number of subpopulations, the median library size, the median total read counts and the average silhouette widths.

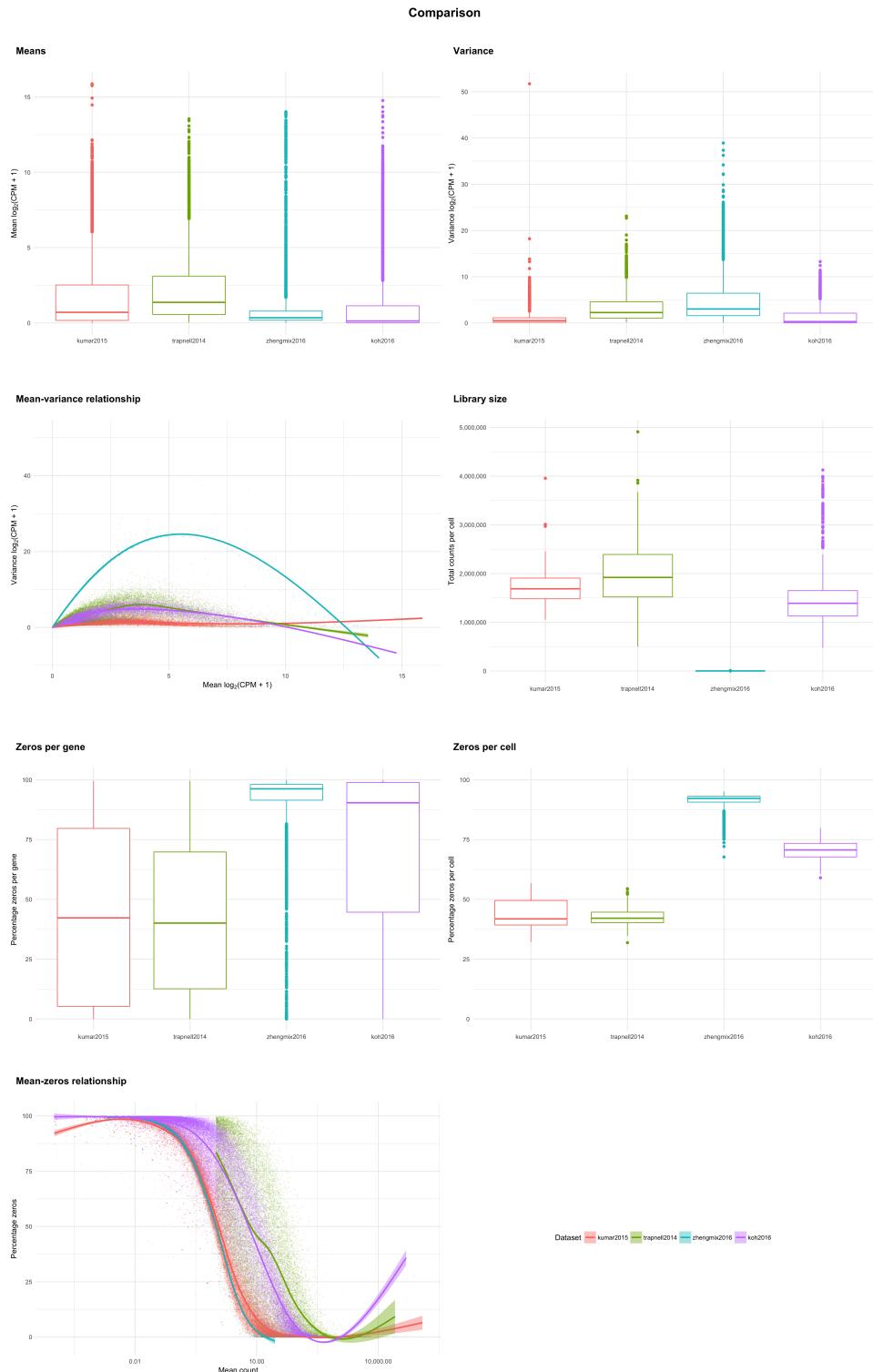


Figure 3: Comparison between the data sets. Based on compare function of Splatter.

2.4 Data transformation and normalisation

Data transformation RNA-seq data may suffer from heteroscedasticity and skewness (Zwiener et al., 2014). Genes with higher mean have on average a higher variance across cells leading

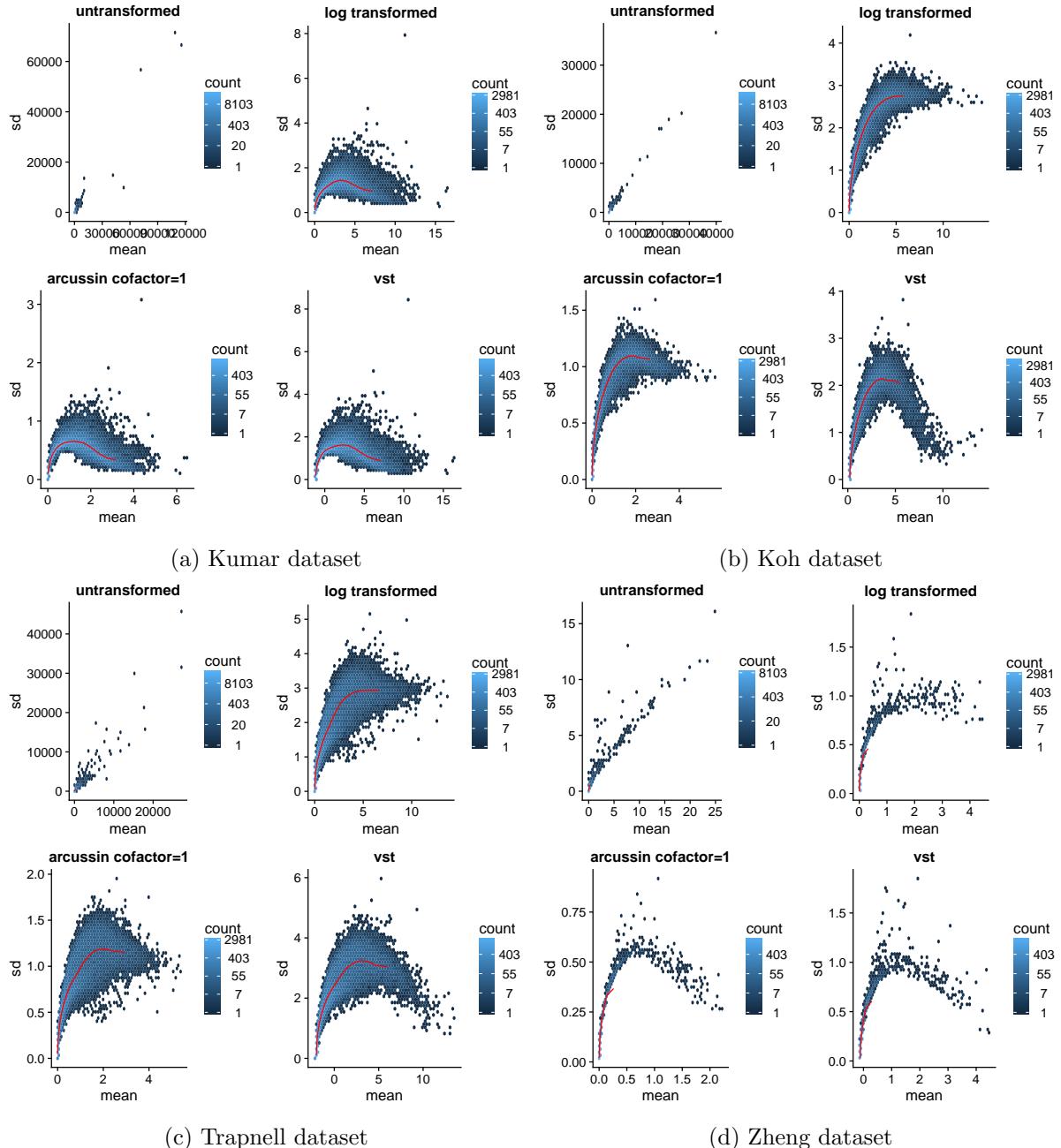


Figure 4: Shown is the genewise standard deviation versus the mean for the datasets Kumar (a), Koh (b), Trapnell (c) and Zheng (d). Different transformations were considered; log, arcus sin and VST transformations.

to unequal variances between different genes. To handle this property different transformation were considered. Namely, a binary logarithmic transformation with a pseudo-count of one, arcus sinus transformations and a variance-stabilising transformation (VST) from the DESeq package (Anders and Huber, 2010).

Log transformations are often used when dealing with skewed data and is a standard approach for normalising RNA-seq data. A pseudocount of one is added to avoid taking the log of zero, and the transformation is defined as:

$$x_{ij}^{log} = \log_2(x_{ij} + 1) \quad (1)$$

Where x_{ij} are the counts of gene i and cell j . Log transformations will have an impact on extreme values. However, they will not address the problem of heteroscedasticity. Arcus sinus transformation should deal with extreme values and equalise the variances.

$$x_{ij}^{arcsin} = \arcsin \frac{\sqrt{x_{ij}}}{c} \quad (2)$$

After transformation, the mean and the variances should be independent.

VST addresses the problem of extreme values and unequal variances across genes.

$$x_{ij}^{vst} = \int_0^{x_{ij}} \frac{1}{\nu(\mu_j)} d\mu_j \quad (3)$$

After such transformation, the mean and the variances of the genes should be independent. For the study, a binary logarithmic transformation plus a pseudo-count of one is used. The mean-SD dependence for different transformations is shown in Figure 4.

Filtering and normalisation The quality control of the data sets follows Lun et al. (2016b). In the first step, genes that are not expressed in any cell (systematic-zeros) are removed in order to reduce the size of the expression matrix. To find potential outliers, PCA can be used on the phenotype characteristic of each cell (Figure 20, 21, 22, 23; a). Cells were filtered based on the library size and the total number of genes. Cells with log₁₀ library sizes that are more than three median absolute deviations (MADs) below the median log-library size were filtered out (Figure 16, 17, 18 and 19). The same filter was used with respect to the total number of genes per cell. For the Kumar and the Zheng dataset, ERCCs and mitochondrial counts were available. Cells with large proportions of ERCC or mitochondrial RNA are seen as low-quality cells. In the Kumar dataset, cells with a median ERCC proportion above three MADs are as well removed. The same filter was used for mitochondrial RNA in the Zheng data.

The metadata for the Trapnell dataset contained information about the cell quality. In this dataset, cells that were marked as debris and any single libraries consisting of more than one cell were filtered out. After filtering, 531 cells in the Koh dataset, 246 in the Kumar dataset and 222 in the Trapnell dataset were retained. The filtering was less strict in the Koh dataset compared to the original analysis where they retained 498 cells.

Low-abundance genes influence the mean-variance trend. Here low-abundance genes are filtered by their average counts (see Figures 20, 21, 22 and 23; d). For the Kumar, Trapnell, simDataKumar and Zheng data genes with average counts less than one are removed. The Zheng data set had a shallower sequencing depth. A different filter is used, and features which are not expressed in at least two cells are excluded. To find batch effects, a linear model regressing the PC values against the total features was used (Lun et al., 2016b).

Another examination of the technical variation was done using the marginal variances (Lun et al., 2016b). For that, a linear model with the expression values per gene as response variables and a chosen explanatory variable is fitted. The correlation coefficient can then be seen as the marginal explained variance for the explanatory variables.

A wide variety of normalisation methods exist based on bulk RNA methods. These methods are usually not designed for dealing with the zero-inflated nature of scRNA-seq data (Lun et al., 2016a). Methods for normalisation of scRNA-seq data are based on spike-ins or RNA counts. Spike-in RNA is added before the library preparation. Any changes in the spike-in coverage are assumed to be due to technical factors. The normalisation is done by scaling the counts to level the spike-in. However, this approach is not feasible as none or only a limited number of spike-in counts were present in the datasets.

Here, normalisation through pooled cells is used, where the problem of excess zero counts is reduced by the pooling of multiple cells (Lun et al., 2016a). The normalisation procedure can briefly be described as follows: (i) Different pools of cells are defined. (ii) The expression values are summed across the cell pools. (iii) The cell pool is normalised against an average of the summed expression values. (iv) This step is repeated several times to construct a linear system. The summed count size is then used to estimate the corrected size factor. The size factors for the pooled cells are then deconvoluted” into cell-based factors.

2.5 Optimal number of clusters

Methods to determine the optimal number of clusters are subjective methods as elbow or silhouette plots. In the Elbow plots, the within-cluster sum of square is plotted against a range of clusters. The silhouette plot is a standardized measure of distances between each point inside and outside of the respective cluster. Less subjective is the gap statistic. Here the log within sum of squares is compared to its expectation. The null distribution is expected to be uniformly distributed, it is not clear if this is correct for high dimensional data (Tibshirani et al., 2001). Other possible methods are the calinsky criterion, hierarchical clustering.... Here the optimal

number of clusters is determined by Elbow plots, clustering is based on kmeans clustering and the within-cluster sum of square thereof. The elbow plots suggest three clusters for the Kumar dataset, 2 - 5 in the Trapnell data, 3 in in the Zhengmix data (see Figure ??). The optimal number of clusters is unclear for the Koh data set. Minimization of within sum of squares was also done in the tSNE latent space with 30 dimensions. Here the optimal number of clusters are 3,3, 4 and 6 to 8 in the Kumar, Trapnell, Zheng and the Koh data sets, respectively.

2.6 Evaluation of the clustering methods using different run modes

Using filtered and normalised data, the methods were operated in the default mode, with the number of clusters given by the ground truth and under a range of parameters. Additionally, the methods were also run with the unfiltered datasets.

Many users will use these methods in the default mode, hence it was seen as important that the results were provided without any fine-tuning of the parameters. The run parameters in the default mode were given either according to the packages default settings or by using examples from the package vignettes. If the method was able to detect the number of subpopulations, this auto-detection function was used to infer the number of clusters. When the number of clusters had to be provided, the number of clusters given by authors of the datasets were used. Clustering results have to be evaluated using some sort of "ground truth". Here, the cell annotation provided by the authorsof the datasets or the the given truth from the simulations were used.

Seurat, TSCAN, RaceID, SC3 and Linnorm each have their own filtering and/or normalisation procedures. In order to test these methods preprocessing capabilities, the methods were tested with the unprocessed raw counts. The methods tSNEkmeans, pcaReduce, SNN-Cliq, SIMLR, ZinbWaVE and CIDR do not include filtering and normalisation steps. For these methods filtered, normalised and log-transformed counts, detailed in section 2.4, were used. An overview of the filtering and normalisation steps used by the methods is given in Table 4.

In a further analysis, the clustering methods were tested for different values of the number of clusters k . Seurat does not allow the number of clusters to be set. Hence, Seurat was run under a range of the parameters of the number of neighbors and the resolution parameter.

Based on the evaluation by the Adjusted Rand Index (ARI), the parameter k , which maximises the ARI score was used to compare the methods in an optimal setting. To assess the stability of the clustering methods, a random subsample of cells without replacement was drawn from the Kumar dataset. The size of the subsample was 100 and the subsampling was repeated 30 times. The clusterings for each method were then compared using the overlapping samples and the ARI scores.

2.7 Parameter settings

The number of clusters k is the main parameter used for most of the methods. Except for Seurat, the clustering functions for each of the methods allow for the number of subpopulations to be directly controlled. Seurat allows the setting of k only indirectly through a resolution parameter. The other important parameters were the number of kNN, the number or the type of latent space dimensions used for the clustering algorithms and the settings of the filtering and normalisation steps. The methods pcaReduce, SC3, Linnorm, RaceID and TSCAN can be run in an unsupervised mode, and no parameters have to be provided. Although it is possible to run these the methods unsupervised, fine-tuning of the parameters is highly recommended. CIDR, RtSNEkmeans and SIMLR need the specification of the number of clusters k . For Seurat the number of PCs or the number of the kNN have to be defined. An overview of the chosen parameter settings is given in Table 3. Next, a brief overview of the chosen parameter setting and the rationale behind it is given.

RtSNEkmeans To reduce the run time the Barnes-Hut tSNE implementation from the R package Rtsne was used. Perplexity was set to 30 for all datasets. Different values of the perplexity can give different tSNE representations; however, here the default setting with the perplexity parameter set to 30 was chosen. tSNE is performed on the first 20 dimensions in the PCA latent space.

Table 3: Add caption

Method	Parameter	default	unfiltered	filtered	optimal k
CIDR	k	NULL	3, 3, 4, 10, 4, 4	3, 3, 4, 9, 4, 4	3,3,5,13,4,4
	nPC	4	5,10,8, 8, 3,3	5,10,8, 8, 3,3	5,10,8, 8, 3,3
	cMethod	Ward.D2	Ward.D2	Ward.D2	Ward.D2
tSNEkmeans	k	3,3,4,9,4,4	3, 3, 4, 10, 4, 4	3,3,4,9,4,4	3,3,4,12,3,3
	perplexity	30	30	30	30
	nPC	50	20	20	20
pcaReduce	k	3,3,4,9,4,4	3, 3, 4, 10, 4, 4	3,3,4,9,4,4	5,3,5,11,4,4
	nbt	100	100	100	100
	method	S	S	S	S
Linnorm	k	range 1 to 20	3, 3, 4, 10, 4, 4	3,3,4,9,4,4	3,2,5,11,3,3
	minNonZeroPercent	0.1,0.75,0.75,0.75	0.75,0.75,0.1,0.75,0.75,0.75	0.75,0.75,0.1,0.75,0.75,0.75	0.75,0.75,0.1,0.75,0.75,0.75
	BE_strength	0.5	0.5	0.5	0.5
SIMLR	k	3,3,4,9,4,4	3, 3, 4, 10, 4, 4	3,3,4,9,4,4	3,2,4,10,3,3
	normalize	FALSE	TRUE	TRUE	TRUE
SIMLRlarge	k	3,3,4,9,4,4	3, 3, 4, 10, 4, 4	3,3,4,9,4,4	3,2,4,10,3,3
SC3	ks	range from 2 to 15	NULL	NULL	NULL
	k	NULL	3, 3, 4, 10, 4, 4	3,3,4,9,4,4	3,2,4,11,4,4
	pct_dropout_max	90,90,99,99,90,90	90,90,99,99,90,90	90,90,99,99,90,90	90,90,99,99,90,90
TSCAN	k	range from 2 to 10	3, 3, 4, 10, 4, 4	3, 3, 4, 9, 4, 4	3,2,3,10,4,4
	minexpr_percent	0.5,0.5,0.1,0.5,0.1,0.1	0	0	0
Seurat	resolution	0.6, 0.6, 0.6, 0.7, 0.6, 0.6	0.6,0,6,0,6,0,7,0,6,0,6	0.6,0,6,0,6,0,7,0,6,0,6	0,6,0,6,0,6,0,7,0,6,0,6
	neighbors	30	10 percent of dataset	10 percent of dataset	10 percent of dataset
	mincell	0	2	0	0
	mingenes	0	0	0	0
	dimuse	NULL	9, 12,10,15,10,10	9, 12,10,15,10,10	9, 12,10,15,10,10
ZINBWaVE	k	3,3,4,9,4,4	3,3,4,10,4,4	3,3,4,9,4,4	3,3,4,9,4,4
	ngenes	1000 , except Zheng =200			

pcaReduce For pcaReduce, the range of clusters cannot be specified. Instead, the number of dimension q in the PCA latent space are to be specified. The results are $q - 1$ different clustering solutions, with $k - 2$ clusters. For all data sets, 30 dimensions were chosen, and the evaluation was based on the respective number of clusters in the subsequent analysis. The method is stochastic and has to be run several times in order to give stable results. Here, 100 samples were chosen and the merging of clusters was done by sampling that was proportional to the joint probabilities.

SC3 A gene-filtering step is implemented in this method. Based on the dropout distribution, genes that are below the 10th and above the 90th percentile are filtered out. However, for the Koh and Zheng datasets the upper threshold is set to the 99th percentile. Due to the high dropout rate in these datasets, it was otherwise not possible to run the method . When running under the default mode, a range of clusters from 2 to 10 are given, and the number of subpopulations is automatically inferred by the method. Otherwise, k is set to the number of annotated subpopulations.

SIMLR A gene-wise mean normalisation step is implemented by the method. When running in the default mode, no normalisation was used. However, in the other run modes normalisation was included. Without normalisation, the method fails in the spectral decomposition of the similarity matrix. The tuning parameter k was set to the default value of 10 on all runs. The number of clusters is set according to the run mode that is being used.

CIDR CIDR uses three parameter settings: the number of clusters, the number of PCs (nPCs) and the method for hierarchical clustering. By default, Ward linkage are used in the hierarchical clustering. CIDR is able to automatically detect the the number of clusters n . By default, n is

set to $nPC * 2 + 2$ and the parameter nPC is set to 4 by default. When run in a mode other than the default, the parameter nPC was chosen by a variation of the scree-plot and the number of clusters was set accordingly to the respective dataset. The number of PCs used for the datasets Kumar, Trapnell, Koh, Zheng, simDataKumar and simDataKumar2 are 5, 10, 8, 8, 3, and 3, respectively.

Seurat Implemented in the method is a normalisation and a gene-filtering step. The filtering criteria are based on how many cells show an expression of a certain gene and the number of total features per cell. By default, no cell-filtering step is included when preprocessed datasets are used.

When running with unfiltered data, genes that are expressed in less than two cells were filtered out. When using the Zheng data, the threshold is set to one, according to the filtering detailed in section 2.4.

The default log normalisation is used, which is currently the only option. The scale factor for cell-level normalisation was set to the default of 10'000. As a default, no explanatory variables were chosen to be regressed out. The experimental batch would be a natural choice as a covariate, but it cannot be used as the datasets containing this information are completely confounded.

The clustering parameters to be defined were a resolution parameter and the number of PCs. The resolution parameter was set to 0.7 for the Koh dataset and 0.6 for the other datasets. The number of PCs was determined according to the methods recommended by the authors. Namely, through the use of a scree plot and a jackknife permutation test the number of PCs was determined. In terms of the datasets, Kumar, Trapnell, Zheng, Koh, simDataKumar and simDataKumar2 were used, with the number of PCs being 9, 12, 10, 15, 10, and 10, respectively. Ten percent of the total cells were used as the number of neighbours in the k-nearest neighbour algorithm. A range from 0.5 % to 40 % of the total number of cells is used to infer the optimal number for the kNN parameter.

TSCAN TSCAN adds a pseudo-count of one with the data being log-transformed; this setting is used for all run modes. In the default run-mode, genes that show zero expression in at least half of the cells are filtered out. In order to be able to run the method using the unfiltered data, this threshold was changed to 0.1 for the Zheng, simDataKumar and simDataKumar2 data.

This filter was switched off when working with the prefiltered datasets. By default, the method infers the number of clusters from a range of 2 to 9 clusters. Here, a range from 2 to 10 was used in the default mode. If run semi-supervised, the respective number of clusters is given. By default, "ellipsoidal, varying volume, shape, and orientation" is used for the model.

SNNCliq The connectivity of the quasi-cliques was set to the default value 0.7. Likewise, the merging threshold parameter was set to the default of 0.5. The method was run using normalised, filtered data and the number of clusters was set to a range from 3 to 10 in all datasets. SNNCliq works on different distance metrics; here, the default Euclidean distances were used.

RaceID In default mode, cells with a minimum total library size of 3'000 are retained. The gene filter is set to filter out all genes with less than five transcripts in at least one cell. Over-saturated genes, that have over 500 transcripts per cell, are also filtered out. Here, we only use this filter with the Zheng data, as it is the only set that contains UMI counts. Otherwise, the filter is turned off. The gap statistic is used to determine the number of clusters. The default setting from the clusterboot function is set to a range from 2 to 20 clusters.

When using the run mode with unfiltered datasets, the minimum total library size was set to 1'000, 500, 400, 420, 1'200 and 1200 for the datasets Kumar, Trapnell, Koh, Zheng, simDataKumar, and simDataKumar2, respectively. These thresholds were chosen so that they corresponded with the thresholds based on the MADs. The filters for oversaturated genes and minimum gene expression were turned off as well, corresponding to the filtering steps in section 2.4. Filtering, based on the original analysis, was done using mean counts. To set the gene filter, we retained those genes that showed at least one transcript for two cells in the count-based datasets. The exception to this was the Zheng dataset, where genes are retained that show at least five counts in two cells.

When the method is run with prefiltered datasets, the filters are turned off and the appropriate number of clusters is provided. In all run modes, the Pearson metric is used as the distance measure.

Linnorm Except for the Zheng data, the filtering thresholds are set to the default in all run methods. Due to the low sequencing depth of the Zheng dataset, the minimum non-zero expression had to be set to a proportion of 0.1. tSNE and k-means are used for dimension reduction and clustering, respectively. In the default run mode, a range of k from 2 to 20 was provided in order to allow us infer k .

2.8 Evaluation metrics

One of the evaluation criteria used was the Hubert-Arabje Adjusted Rand Index (ARI), which is used to compare two partitions (Hubert and Arabie, 1985). The metric is adjusted for chance by subtracting the uncorrected index by its expectation, and divided by a scale factor. Independent clusterings have an expected value of zero and are one if there is full agreement between the partitions. The index can take on negative values.

Another metric is the F1 score. It is the weighted average mean between precision and recall. The weights are defined as the inverse of the precision and recall. F1 scores can take on values between zero and one. The predicted clusters and the "ground truth" were matched by the Hungarian algorithm. Some of the clustering methods are unsupervised and the partitions do not need to have the same sizes (non-bipartite). This causes problems with the Hungarian algorithm. As a solution to this issue, the assignment matrix was augmented with dummy columns that had the maximum matrix value as their entries.

2.9 Software and environment

All analyses were performed in R (version 3.4.2 (2017-09-28)) (R Core Team, 2013), a free software environment for statistical computing and graphics which is available at <http://www.r-project.org/>. The following model-specific packages were used: surveillance (version 1.13.1), hhh4predict (version 0.1.0.7), and hhh4contacts (version 0.12.1). In addition to base packages, ggplot2 (2.2.1), knitr (1.15.1), and parallel (3.3.3) were used in analysis and reporting. The computing environment had the following specifications: macOS Sierra (Version 10.12.6) and 2.7 GHz Intel Core i5 Processor with 8 GB RAM.

	cellfiltering	genefiltering	normalization	autodetect	expressionvalues
tSNEkmeans	no	no	no	no	normcounts
pcaReduce	no	no	no	no	normcounts
SC3	no	yes	no	yes	normcounts
SNNCliq	no	no	no	no	normcounts
dbscan	no	no	no	no	normcounts
SIMLR	no	no	yes	no	normcounts
CIDR	no	no	no	yes	normcounts
Seurat	yes	yes	yes	no	counts
TSCAN	no	yes	yes	no	counts
ZINBWaVEkmeans	no	no	yes	no	counts
RACEID	yes	yes	yes	yes	counts
Linnorm	no	yes	yes	no	counts

Table 4: Overview of filtering and normalization steps by method

3 Results

3.1 Transformation and normalisation

Transformation The data still shows heteroscedasticity. There are only subtle differences between the arcus sinus and log transformations in all the datasets. The Compared with the Arcus sinus transformation.

Normalisation In Kumar similar amount of the variance is explained by the total number of genes, the proportion of ERCC and the phenotype. This indicates that the data set is heavily influenced by batch effects. The same holds in the Trapnell data, but on a lower scale. Variance in Koh data is primarily influenced by the phenotype and to a lesser extent by the total number of genes and the top 200 features. Zheng is primarily dominated by the biological variation with the other explanatory factors contribution only marginally to the total variances. (Different methods exist to normalize RNA-seq data like TMM normalization, DEseq normalization and by library size. However, none of these methods is designed to deal with the zero-inflated nature of scRNA-seq data Lun et al. (2016a). Another often used approach for scRNA-seq data is the normalization by spike-inn. This approach is not feasible as no or only a limited number of spike-inn counts were present in the data sets.)

3.2 Evaluation of the clustering results

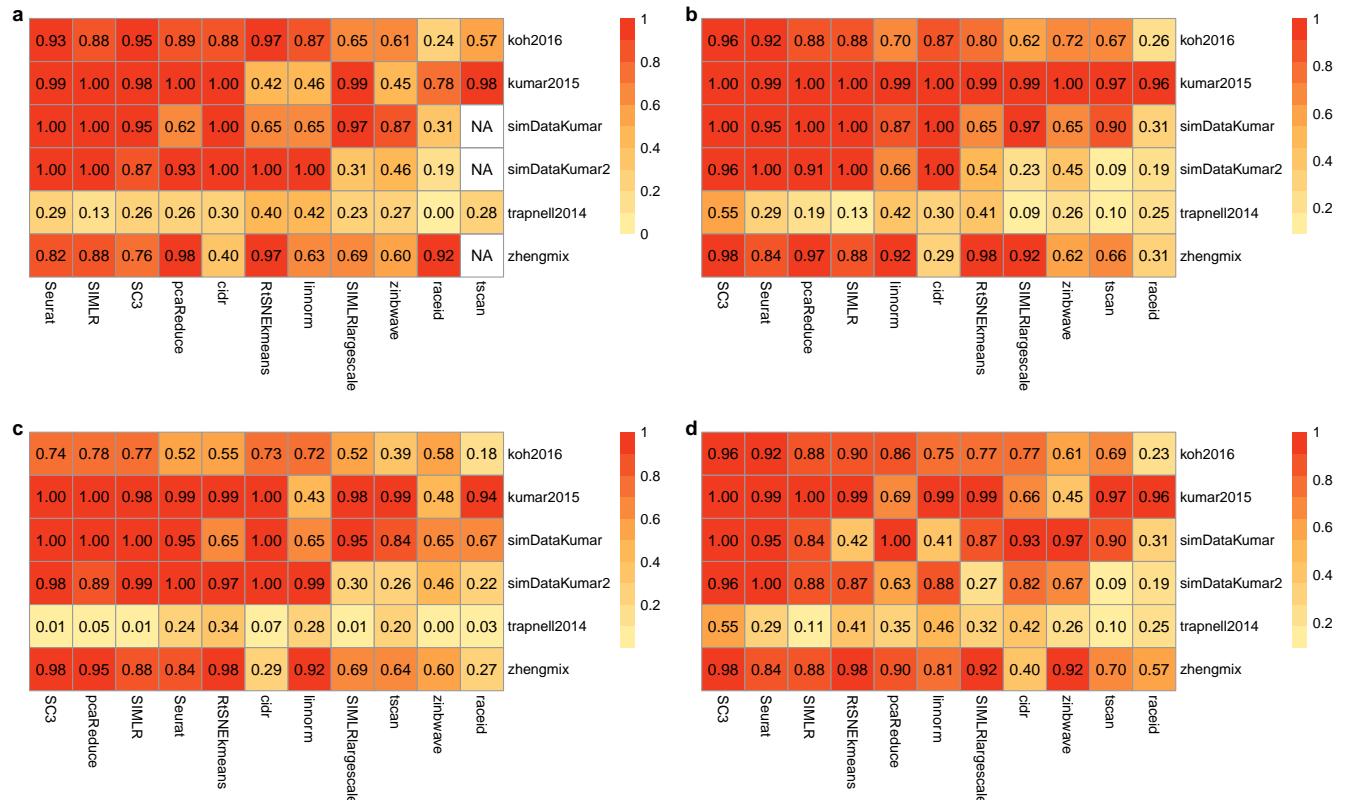


Figure 5: ARI scores for the datasets Koh, Kumar, Trapnell, Zheng and the simulations simDataKumar and simDataKumar2. Shown are the ARI scores for the runmodes (a) default, (b) filtered, (c) unfiltered and (d) optimalk.

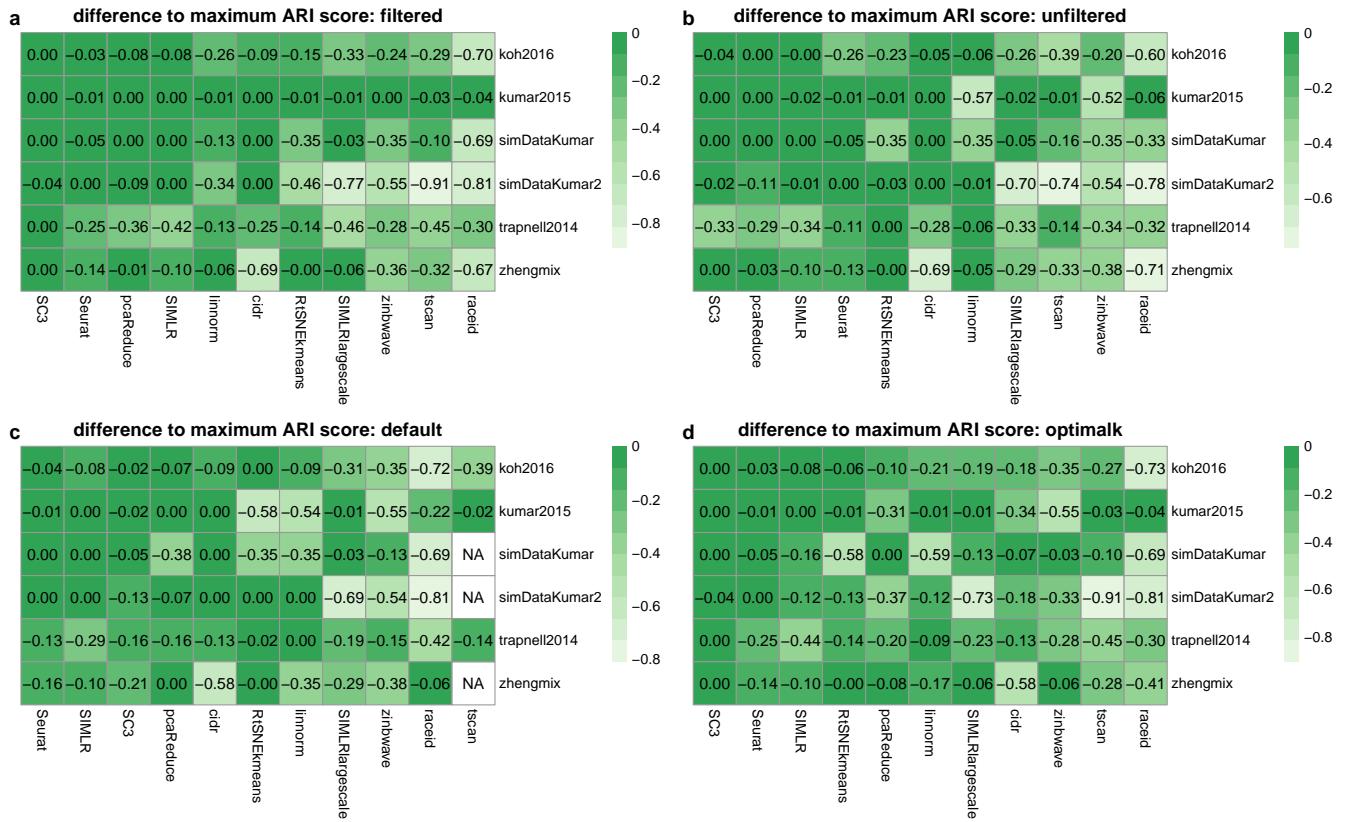


Figure 6: Differences between maximum ARI scores.

3.3 Evaluation of the clustering results

For this study, the methods were evaluated using six different datasets and were tested in four different run modes. By running the clustering methods using the unfiltered and filtered datasets, we can (to some extent) investigate the effect of the filtering and normalisation steps on the clustering. RaceID, Linnorm, TSCAN and Seurat each have their cell or gene-wise filters implemented; and these were included when run using the unfiltered datasets.

By running the methods under the default mode, we can investigate the performances with a minimum required user effort. The methods were then run with a refined parameter setting. Note that the number of parameters varied considerably between the methods; in this study, we chose only the parameter that is regarded as the most important.

The clusterings of the methods were assessed by the use of the ARI and F1 metrics. The ARI scores for the different run modes are shown in Figure 5 and ???. Figure 6 shows the differences in ARI scores between the method with the highest ARI score and the other methods, according to the dataset used. The differences between the ARI scores of the different run modes are shown in Figure ???. The comparison of the different run modes is strictly speaking only possible for deterministic methods as CIDR, and unstable methods (e.g. tSNEkmeans) is not possible.

Dataset

The datasets and simulations used varied in the number of cells, the library sizes, the number of subpopulations, the zero-fractions per gene and the type of the expression values (see Table ??). To assess the accuracies of the methods some ground truth of the type of subpopulations is needed. Here, we used the annotation given by the authors of the datasets. This may not be correct; the cell types could be wrongly annotated, or the annotated cluster consists of more refined unknown subpopulations. However, here we used this annotation because it was seen as

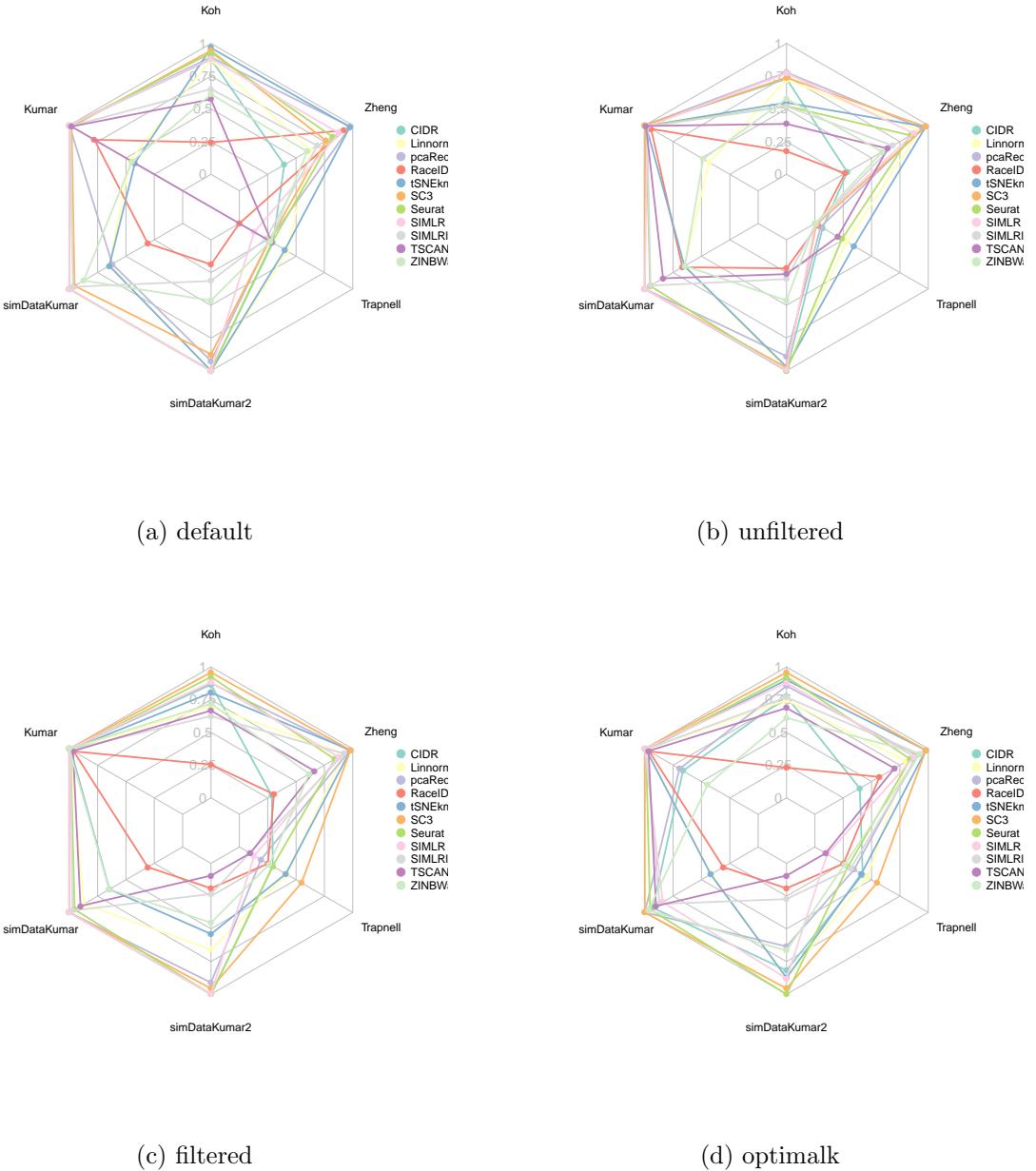


Figure 7: Radarplots showing the ARI scores for the runmodes

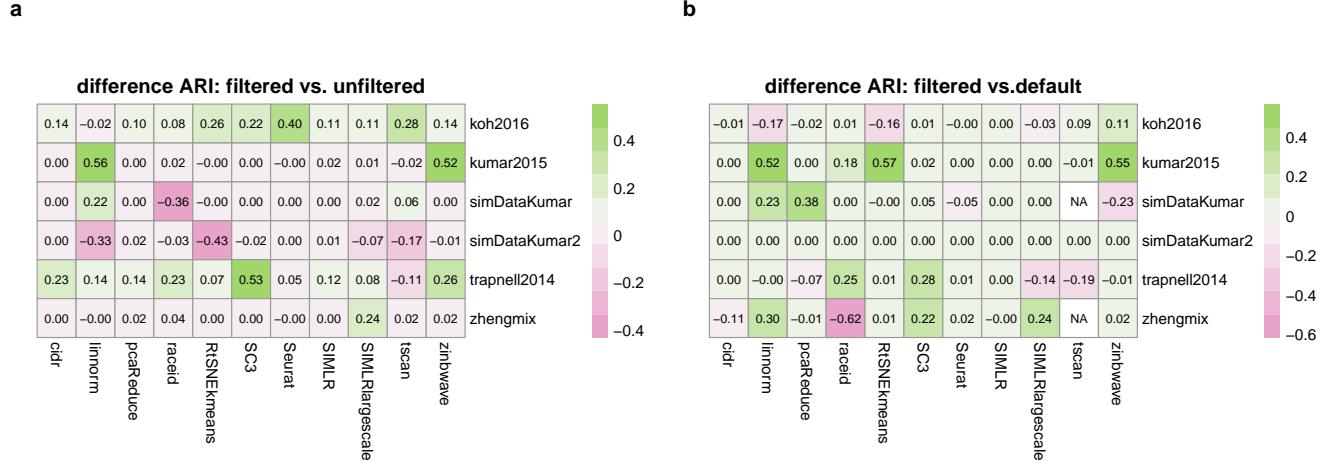


Figure 8: Differences in ARI scores for the datasets Kumar Trapnell, Zheng, Koh, simDataKumar and simDataKumar2 for the runmodes default versus annotated k and filtered versus unfiltered.

the best possible information available. The datasets were chosen such that there was a range in clustering difficulty. As an objective measure of the clustering difficulty, the average silhouette coefficient is used.

The average silhouette width of the Kumar dataset is with 0.53 the highest for all datasets. It consists of three distinct cell populations and is the simplest of all the datasets. A high proportion of the variance is explained by the cell type or the batch effect, as this two are not separable (see Figure ??e). The number of expressed genes in cell population ... is substantially higher than in the other two cell types. This dataset can be seen as a benchmark for the dataset as no method should have problems in clustering this dataset. Using the filtered datasets the methods SC3, pcaReduce, SIMLR, CIDR and ZINBWave achieved a correct partition of the cells. The other methods also achieved high accuracies with scores between 0.97 and 0.99.

The simDataKumar simulation has an average silhouette width of 0.15. Three out of four subpopulations in the dataset are distinct, with a high proportion of DE genes. Only 5 percent of the subpopulation Group 1 are DE genes and based on the tSNE representation of the dataset the two subpopulations Group1 and Group2 are not distinguishable (see Figure ??). For the filtered data the methods SC3, Seurat, pcaReduce SIMLR and CIDR had ARI scores between 0.95 and 1.00. Whereas tSNEkmeans, TSCAN and RaceID failed to correctly cluster the dataset.

The more difficult simulation simDataKumar2 has an average silhouette width of 0.3. For this dataset, the proportions of DE genes are relatively low with five to eight percent. The subpopulation Group3 is distinguishable from the other three in the tSNE representations. Group1, Group2 and Group4 form a single non-separable cluster in the tSNE representation. Whereas SC3, SIMLR, Seurat, CIDR and pcaReduce were mostly able to correctly cluster the cells, with ARI scores between 0.90 and 1.00, the remaining methods showed profoundly different performances.

The Zheng dataset is a mixture of four populations of PBMC cells. The two subpopulations CD19+B and CD14+monocytes are distinct cell populations, whereas the naive cytotoxic and regulatory T cells are overlapping populations. The tSNE representations show that CD19+B and CD14+monocytes form two separate clusters, with a third cluster that consists of the two

nested populations naive cytotoxic and regulatory T cells. The dataset has a medium difficulty with an average silhouette width of 0.1. The dataset has a low sequencing depth and a high dropout rate. (The performances given by the different methods were highly variable on the different run modes. Overall, the methods Linnorm, SC3, tSNEk-means and SIMLR performed well on this dataset; whereas RaceID and CIDR had low accuracies. They both failed to detect one of the subpopulations. In contrast to its performances on the other datasets, pcaReduce achieved the highest score for this dataset in the default run mode.)

The dataset Koh had the highest number of subpopulations; ten clusters were annotated by the authors of the original study (cite). During the cell filtering of the Koh dataset one subpopulations was wrongly detected as outlier cells and was removed during the filtering steps (D3GARPpCrdcM). The average silhouette width is -0.04. In the tSNE representation, some cell types are easily distinguishable, whereas other are nested. On average ten % of the variance is explained by the cell type. Similar to the Zheng dataset the Koh data have a low sequencing depth and a high dropout rate. (For this data, only SC3 was able to correctly identify all the nine subpopulations. pcaReduce, RaceID and tSNEkmeans failed to partition the data in general. CIDR, Seurat, and ZINBWAVE failed to identify one particular subpopulation.)

The Trapnell dataset is not a mixture of distinct cell populations, and the development of the populations followed a time-dependent trajectory. The non-differentiated cells form a distinct cell cluster. However, the more differentiated cells later on the time axis are, at least in tSNE space, non-separable. Notable is also that the batch explains a higher proportion of the variance than the cell type. The average silhouette width is 0.04 and its one of the more difficult datasets. The methods showed the lowest ARI scores for this dataset, and the maximum score achieved SC3 with 0.55, showing the difficulty to cluster this dataset. The other methods all had ARI scores below 0.5. TSCAN is specially developed for this scenario (Ji and Ji, 2015). However, the method did not perform any better than the other methods. To improve the clustering results for TSCAN, it is possible to provide a starting point for the trajectory. However, this was not done in this study.

3.4 Results clustering

SC3 showed higher or similar high ARI scores for most of the run modes. The only exceptions are seen in the default and unfiltered setting when using the Trapnell and the Zheng datasets. A pre-filtering step and a fine tuning of the parameters for this method is recommended, as this improved the accuracy of the method. It is noteworthy that the method was able to correctly classify more than 95% percent of the cells for the Kumar, Koh, simDataKumar, simDataKumar2 and Zheng datasets. It had low scores for the Trapnell data. However, when running with filtered datasets, it achieved the highest accuracies for all methods. SC3 can detect the numbers of clusters automatically and did so correctly for the simulated datasets. For the other datasets, the number of clusters was higher than in the annotation. If this due to the existence of more refined subpopulations is unknown.

Similar to SC3, Seurat achieved high accuracies. However, Seurats performance levels dropped when used with the Koh and Zheng datasets. The filtering of the Koh dataset led to an improvement in the accuracies, but otherwise, using the filtered datasets, only small changes were detected. According to (Butler and Satija, 2017), the resolution parameter for the function is crucial to the ability to determine the number of clusters, and it is recommended that the method is tested using different values of this parameter. In this study, we were only able to run the methods on a small range of values in the parameter, as else it was not possible to run the method. However, Seurat was able to detect the correct number of subpopulations in most of the datasets. The exception is in the Zheng dataset where an additional cluster was detected. The default for the number of neighbours for the kNN is set to 30, and no differences

in the clustering are achieved when this parameter was set to 10 percent of the dataset.

Although CIDR showed an overall high level of accuracy, it had one of the lowest performances for the Zheng dataset of all the methods tested. A possible reason for its low performance is that the expression values are UMI counts and the data has a low sequencing depth, leading to a wrong model fit in the imputation procedure. Filtering of the datasets improved this methods performance. We attempted to further improve this methods performance by selecting an appropriate number of PCs; however, no improvements in accuracy were achieved. Except for the Zheng dataset, it was able to identify the correct number of subpopulations.

In comparison to the other well-performing methods, SIMLR had similar or higher scores for the Koh, Kumar, simDataKumar and the simulated datasets. However, it dropped in performance for the Trapnell, Zheng and Trapnell data. Filtering the datasets led to an improvement for the Trapnell and Koh datasets. Mean scaling of the dataset, one of the parameter settings, had no impact on the performances.

The method tSNEkmeans achieved similar accuracies compared to the high-performing methods when used with the simple Kumar, simDataKumar, and Zheng datasets, but it showed consistently low accuracies for the Koh dataset. The influence of a reduced number of PCs as input for the tSNE dimension reduction was dependent on the datasets. Whereas this improved the performance of the Kumar data, it had a negative impact on the Koh dataset. However, no changes in ARI scores were detected for the other datasets. Also depends on the used data was the influence of the gene filtering. Here, it leads to an improvement for the Koh dataset, but a lower ARI scores for the simDataKumar2. This shows that the number of the PCs and the need for a gene filtering is dependent on the actual dataset. However, the method is unstable, and the changes in the performances could also be due to the stochasticity of the method. When running under the optimal setting with the optimal number of clusters, the method achieved similar accuracies than SC3 but failed to correctly cluster the Koh dataset. The k-means algorithm assumes spherical clusters, which, in the tSNE representation of the dataset Koh, are not given. When comparing the different results achieved when using tSNEkmeans in the different run modes, the method gives unstable results. A possible reason for this is the stochastic nature of the k-means and tSNE algorithms. Due to the stochasticity showed an unstable behaviour when running the method repeatedly. However, it achieved high Ari scores for the Kumar, Zheng and the simulated datasets. Whereas the ARI scores for the Koh datasets where generally medium, it achieved the highest score for this dataset when running under with the unfiltered dataset. Filtering improved the ARI score of the method. However, the method is highly unstable, and a direct comparison between the different runs is not possible.

Linnorms performance is in the medium range. It was able to cluster the Kumar and the Zheng datasets correctly but had was in medium range for the other dataset when compared to well-performing methods as SC3 and Seurat. Changes in the filtered parameters seemed crucial and led to an improvement in the clustering results for the Zheng, Kumar and simDataKumar datasets. However, the score for the Koh dataset was worse. The minimum zero fraction was set to 0.75, which is probably too high if the high dropout rate in the Koh data is considered. However, note that the method was highly unstable, and the results for the different run modes may not be comparable. Linnorm had relatively high accuracies for the unfiltered Trapnell and Zheng datasets. This could be due to the filtering functions that are implemented in the method.

The methods ZINBWave and TSCAN only had high accuracies for the Kumar datasets. Filtering of the data improved the accuracies for ZINBWave, whereas for TSCAN it only improved the performance for the Koh dataset. Otherwise, the ARI scores didn't change or were worse for the data. The method TSCAN is designed to find trajectories. This type of data is given in the Trapnell data. Here the method achieved ARI scores between 0.6 and 0.7, which isn't better than other methods. In this study, a start and end point of the trajectory could be given which

according to t the authors(cite) could improve the results. In this study, however, this was not done. Tscan not possible to run in default, why?

RaceID had the lowest performance and returned only a high ARI score when used with the simple Kumar dataset. The method allows for changes to the filters parameter settings, and the results show that the fine-tuning of these filters can improve the performance (compared to that achieved with their default settings). However, running the method with the pre-filtered data or with unfiltered data had only a slight impact on its performance. The method is based on absolute transcript counts which can explain the bad performance in the non-UMI based datasets. It performed well for the Zheng dataset with the default setting but otherwise failed. This indicates that the parameter ... was badly chosen or due to the stochasticity of the method It achieved the highest accuracy for the Zheng dataset under the setting with the optimal number of clusters but otherwise had low accuracies. The filtering of the datasets led to a decrease in accuracy; however, it was not clear whether this was due to the filtering or as a result of the unstable behaviour.

Overall, the methods with high accuracies are SC3, Seurat and SIMLR. Also, CIDR performed comparable to the before mentioned methods, except when running with UMI counts. Due to the stochasticity of pcaReduce and tSNEkmeans, the results are unstable, and the performance was depending on the run. Linnorm, TSCAN, ZINBWAVE and in particular RaceID showed overall low ARI scores. As stated above, the accuracies varied between the run modes. Using filtered data improved the results for the Koh and the Trapnell dataset, with only two exceptions. For the other datasets, the genewise filtering had different effects on the clustering results. Note that for example for the Kumar data most methods had already an ARI score of one or near one of the filtered sets, and it's not possible to see an increase in ARI scores. A hint on the effect of using the unfiltered data is seen when looking at the stable methods for datasets TRapnell and Koh, where the ARI score was not near one. Here we see that filtering the data lead to an improvement of the clustering. If we investigate the more or less stable methods Seurat, CIDR, SIMLR, TSCAN and SC3 we see that filtering Generally, the filtering had a lesser impact on the simple datasets, (If filtering lead to an improvement in the clustering accuracy was highly dependent on the method and the dataset. For most of the methods, this had no or only a small impact on the clustering accuracies. However, the filtering led to improvement for the Koh and Trapnell dataset.)

All methods showed differing ARI scores for at least one dataaset when comparing the default mode and run under the annotaed k. If the methods perform better under the default settings or with a changed parameter setting is not clear. As stated above, especially for tSNEKmeans, pcaREduce, RaceID and Linnorm any changes in the clustering could be due to the stochasticity of the methods. It was also highly dependent on the dataset, and for the most methods, it had only a slight impact, negative or positive, on the ARI score.

(However, we note that for SC3 the ARI scores were higher when setting the number of clusters is given and. Also for the methods Seurat, SIMLR of the methods it had no or only a low impact on the methods performances. However. First, it is highly dependent on the datasets. For example in the Kumar datasets the SC3, and ZINB-WaVE all showed an improvement or similar results when running with changed parameters. In the case of pcaReduce, RaceIDLinnorm, and tSNEkmeans, the results were not so clear, probably due to the stochasticity of these methods. Seurat, no effect In the default mode, the methods SIMLR, TSCAN and RaceID failed to cluster some of the datasets. SIMLR no effect parameter change. The clustering methods showed highly varying accuracies, depending not only on the datasets but also based on the run modes. The methods SC3, SIMLR, ZINB-WaVE and CIDR all show higher ARI scores when the filtered datasets are used. No definite statement can be made about the performance of tSNEkmeans, as this method gives unstable results. Linnorm, Seurat and RaceID showed similar or higher

ARI scores when the pre-filtered datasets were used. Especially for the Koh dataset, the filters or the parameter settings seemed insufficient.)

3.5 F1 scores and overall dataset difficulty

The F1 scores for filtered dataset are shown in the Figures 28,29,30,31 and 32. The Kumar dataset consists of three distinct cell populations and all methods can partition the three subpopulations in the filtered Kumar dataset correctly with F1 scores between 0.98 to 1.00. This was different when run in default mode and with filtered datasets. Running with the default setting, and automatically detecting the number of clusters, the methods RaceID, SC3 and TSCAN failed to detect the correct number of cluster. RaceID and TSCAN partitioned the cells into four clusters and SC3 into five clusters, additionally TSCAN failed to correctly partition the cells into three subgroups. Note that for SC3 and TSCAN the additional cluster consists only of a few cells and had only a marginal effect on the final clustering. ZINBWave, tSNEkmeans and LinNorm failed in clustering the three populations correctly.

The simDataKumar simulation consists of four subpopulations. Three out of four subpopulations in the simDataKumar dataset are distinct, with a high proportion of DE genes. F

The more difficult simulation simDataKumar2 was again no challenge for SC3, Seurat and CIDR, whereas the remaining methods showed profoundly different performances. On the filtered dataset SC3, SIMLR, Seurat, LinNorm and CIDR were able to mostly correctly identify these four subpopulations. SC3 and RaceID detected only three of the clusters when using the autodetect function of the methods. Write more

The Zheng dataset is a mixture of four populations of PBMC cells. The two subpopulations CD19+B and CD14+monocytes are distinct cell populations, whereas the naive cytotoxic and regulatory T cells are overlapping populations. The performances given by the different methods were highly variable on the different run modes. Overall, the methods LinNorm, SC3, tSNEk-means and SIMLR performed well on this dataset; whereas RaceID and CIDR had low accuracies. They both failed to detect one of the subpopulations. In contrast to its performances on the other datasets, pcaReduce achieved the highest score for this dataset in the default run mode.

The dataset Koh had the highest number of subpopulations; ten clusters were annotated. One subpopulation was removed during the filtering steps (D3GARPpCrdcM). For this data, only SC3 was able to correctly identify all the nine subpopulations. pcaReduce, RaceID and tSNEkmeans failed to partition the data in general. CIDR, Seurat, and ZINBWave failed to identify one particular subpopulation. Compared to other run modes, the clustering was the overall worst for each method when running with the unfiltered datasets.

The Trapnell dataset was the most challenging dataset. Both pcaReduce and RaceID failed to cluster the dataset entirely, and otherwise properly performing methods (such as SC3 and Seurat) had problems when partitioning the cells. Note that the Trapnell dataset is not a mixture of distinct cell populations, and that the development of the populations followed a time-dependent trajectory. TSCAN is specially developed for this scenario (Ji and Ji, 2015). However, the method did not perform any better than the other methods. To improve the clustering results for TSCAN, it is possible to provide a starting point for the trajectory. However, this was not done in this study.

Overall, the dataset Kumar provided no difficulties for most of the methods. Most methods also achieved high scores for the SimDataKumar2 and the Zheng datasets. The Trapnell dataset was a challenge for the methods, and only low accuracies were achieved.

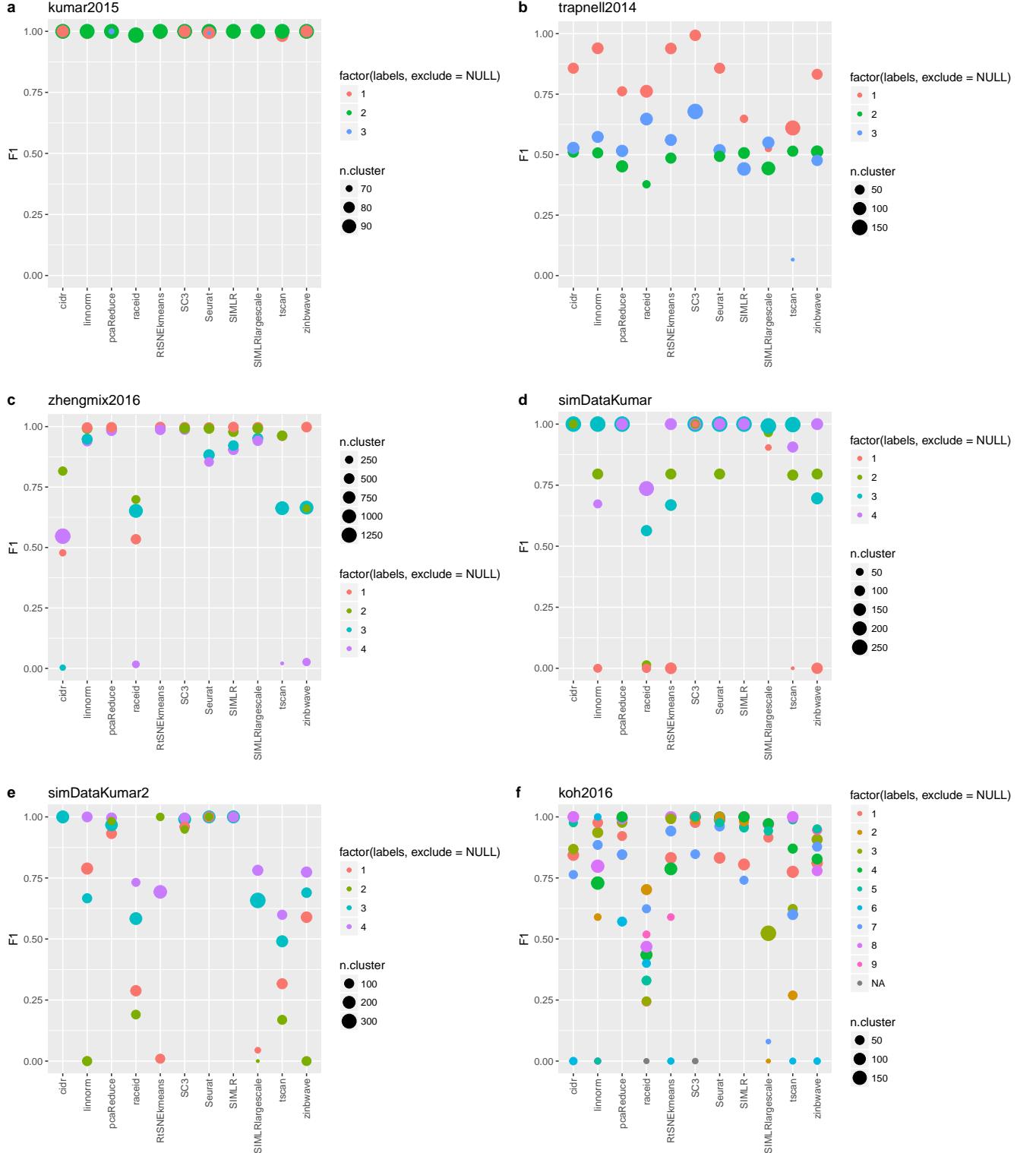


Figure 9: F1 scores for the filtered dataset

3.6 Range of clusters

The methods were run under a range of the number of clusters, and for each clustering result, the ARI score was computed. The results are shown in Figure 10. For the Kumar dataset, all tested

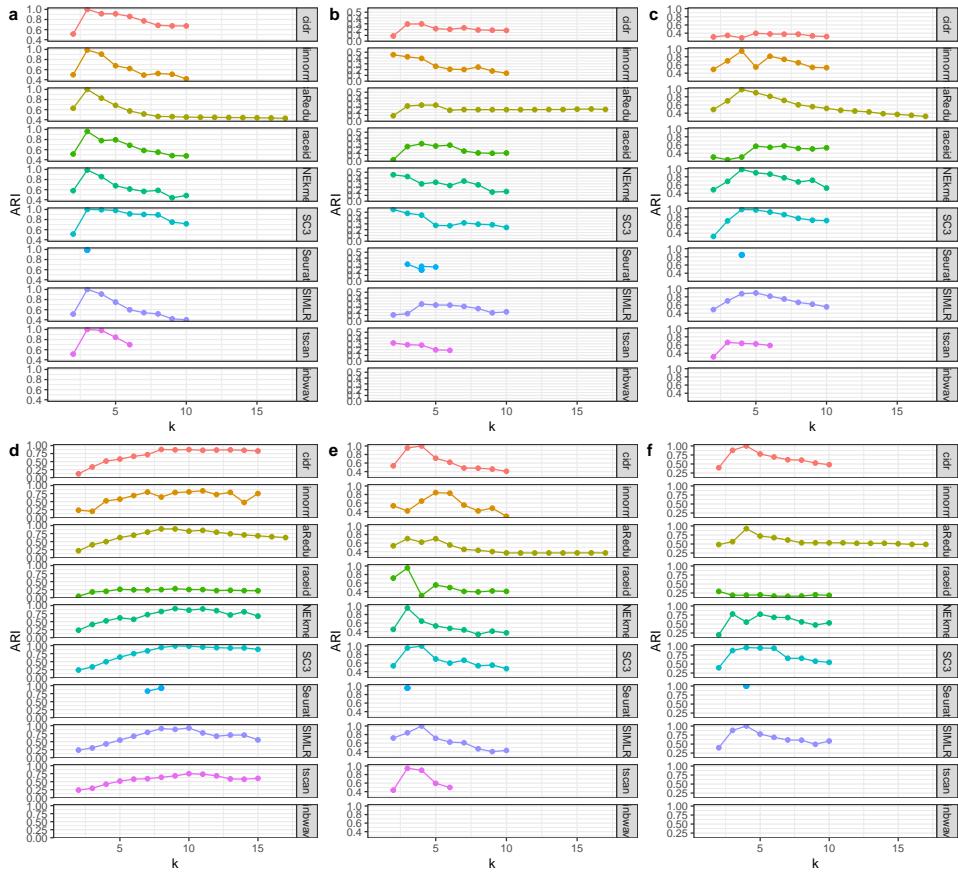


Figure 10: ARI scores for range of parameters for the datasets Kumar (a), Trapnell (b), Zhengm (c), Koh (d) and simDataKumar (e). Shown are the methods where the number of cluster could be defined. Seurat didnt allow the direct control of the number clusters. The Kumar, Trapnell, Zhengmix, Koh and simDataKumar and simDataKumar2 had 3, 3, 4, 10, and 4, respectively.

methods showed a similar behaviour, with a clear maximum with three clusters. The exception to this is pcaReduce, which had similarly high values with five and six clusters. For the Zheng data, only pcaReduce and tSNEkmeans had clear maximums with four clusters. SIMLR and SC3 had similarly high values between five and seven clusters. When using the Trapnell data, SC3, SIMLR, and TSCAN showed their maximum values with two clusters. pcaReduce showed its maximum value with four clusters and similarly high values for higher numbers of clusters. The maximum values for tSNEkmeans and RaceID were with three and four clusters, respectively.

The methods behaved differently depending on the difficulty of the datasets and the number of subpopulations. For example, most of the methods had clear maximums when used with the simple Kumar dataset. Whereas, when used with the more difficult Trapnell dataset, the methods showed a monotonic increase in the ARI and a not-so-clear maximum. Seurat did not allow for the direct control of the number of clusters, and it was only possible to run the method on a small range of the number of clusters.

3.7 Stability analysis

Subsampling without replacement was used to assess the stability of the methods. Based on the wide range of algorithms for the methods, the methods showed results with vaying levels

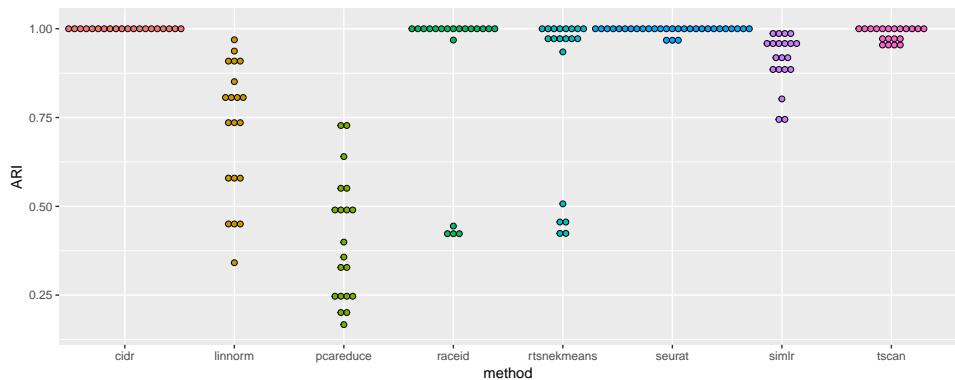


Figure 11: Stability analysis results with 20 subsamples ($n=100$) for the Kumar dataset.

of stability (see Figure 11). The deterministic method, CIDR, is stable. Seurat, TSCAN, and SIMLR all produce mostly the same results. pcaReduce and RaceID are very unstable, and the assignment of the cells to the respective cluster varied greatly. It is assumed that this affects the same cells most of the time. However, this was not investigated. Also, RaceID and tSNEKmeans behave similarly; the method can mostly reproduce its results, assigning each cell to the same cluster in the different run modes. Here, the simple Kumar dataset is used, and it can be expected that the methods will behave even more unstable with a more difficult dataset.

3.8 Runtime

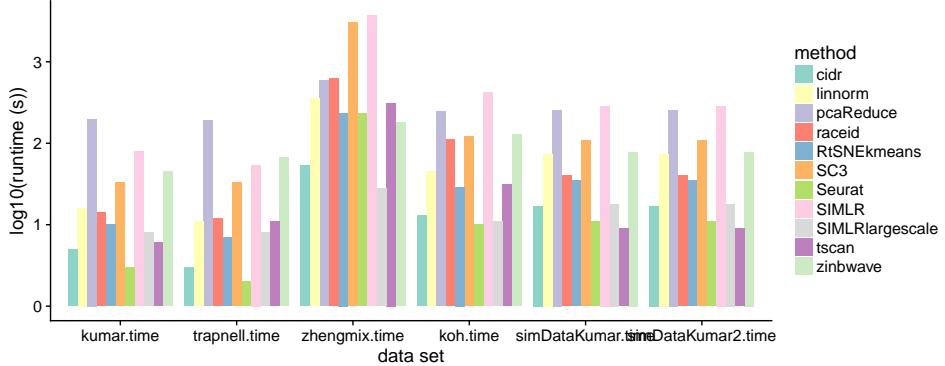


Figure 12: Runtime (s) for the methods on the datasets Kumar Trapnell, Zheng, Koh, simDataKumar and simDataKumar2. The datasets are filtered and the number of clusters based on the ground truth is used.

The runtimes for each method can be seen in Figure 12. They were highly different, ranging across two magnitudes for the studied methods. The fastest methods were Seurat, CIDR, and SIMLR(large scale), whereas the methods pcaReduce, SIMLR, RaceID, and SC3 showed the highest runtimes.

Notable is also that SC3 and SIMLR both have a non-linear increase in runtime, making their use infeasible with a larger dataset consisting of thousands of cells. For small-scale datasets, Seurat is one of the fastest methods. However, when used with the larger Zheng dataset (with 2,000 cells), its runtime lies in the middle ground. Butler and Satija (2017) recommend the use of the VLM algorithm for improved runtime with bigger datasets. A personal laptop was used for the computations in the study.

4 Conclusion and Outlook

We note that the medium and high performing methods achieved ARI scores near one for the datasets Kumar, Koh and Simdatakaumar. Only for more difficult datasets the range was greater. For future analyses more difficult datasets could give better results. regression with scores, with filtered data etc.. has the filtering an effect. Also for unstable methods resampling would give better insight, then report Cis.NMI as a other metric. refined parametersetting is always worth investigated as it is not clear if the maximum performance , best parameter setting was found. Several more methods to test sincera dropseq etc. Of interest could also be differnt types of expression values. testing with unfiltered data and filter switched off , to test the core clustering function of the methods. Several methods can correct for confounder here not tested , worth investigating. Also simulations that are nearer to real world datasets. for example as in new package with overlapping DE. MAin findings SC3 seurat best, use this for small use that for Big data. pca reduce, Rtsne and Linnorm unstabbel. Only useable if repeatdly run. Methods with poor performance like RaceID not clear a based on UMi counts. Gene filtering can have impact, but less than expected. Default mode generally not better most methods need fuiine tuning. a lot of methods based on PCA or tSNE ,can not say which better. kmeans hierarchical and graph based, cannot say which better although wee see it as a improvement deterimnistic from hirerarchical or repeated runs kmeans like SC3.

Generally performance wide range , mostly dependent on dataset in combo with method.

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Additional information

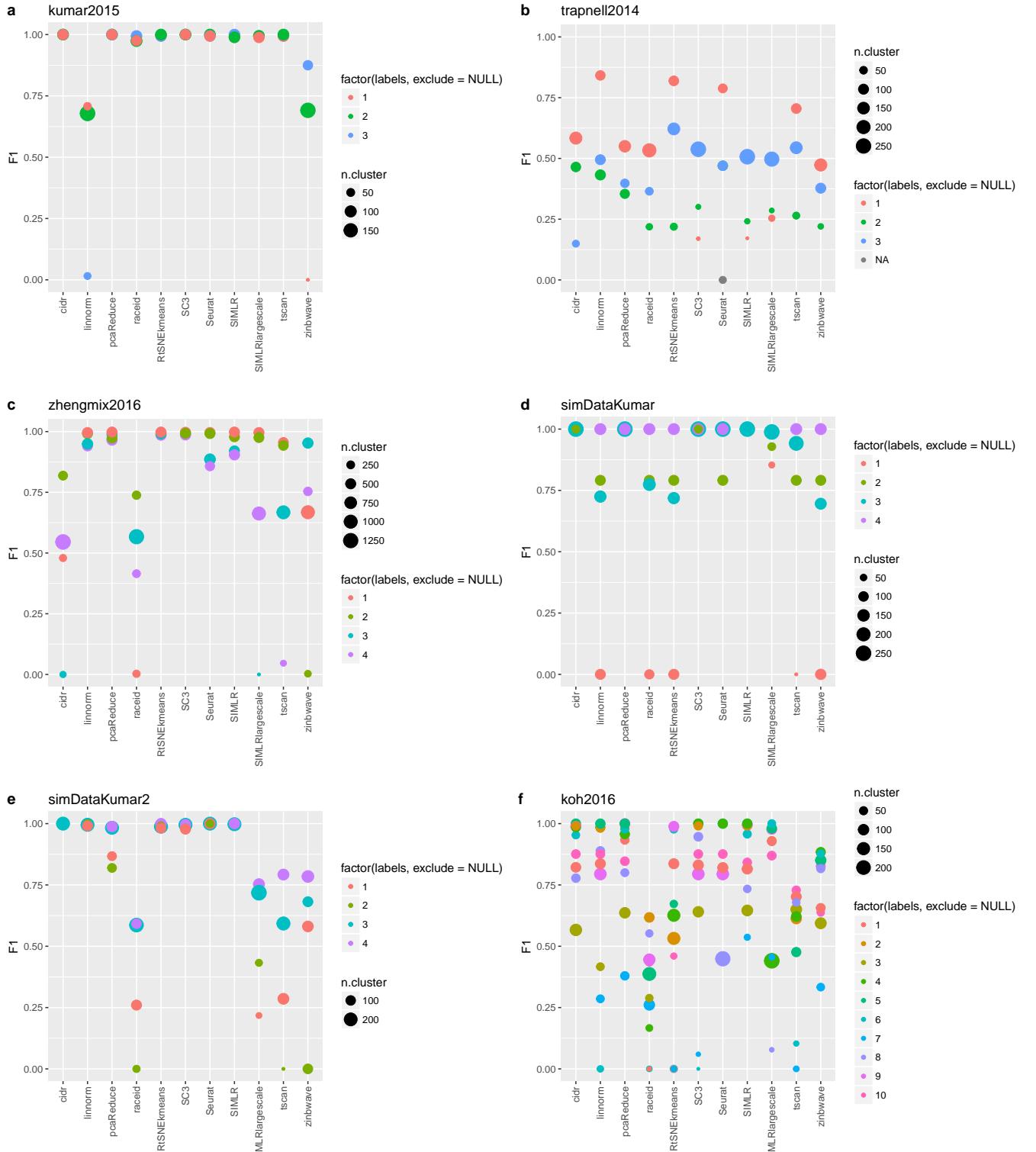


Figure 13: F1 scores for the unfiltered dataset

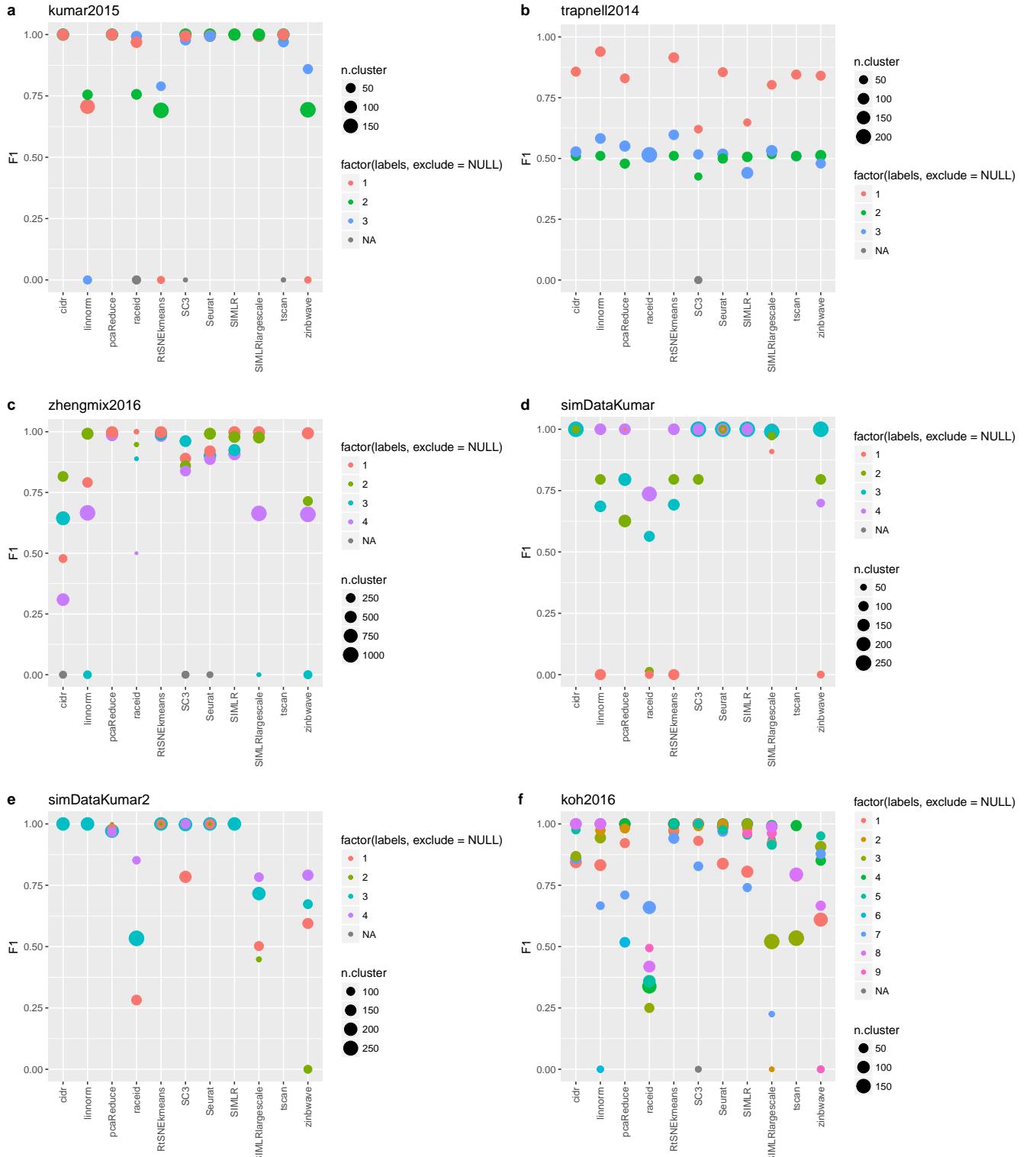


Figure 14: F1 scores for the default dataset

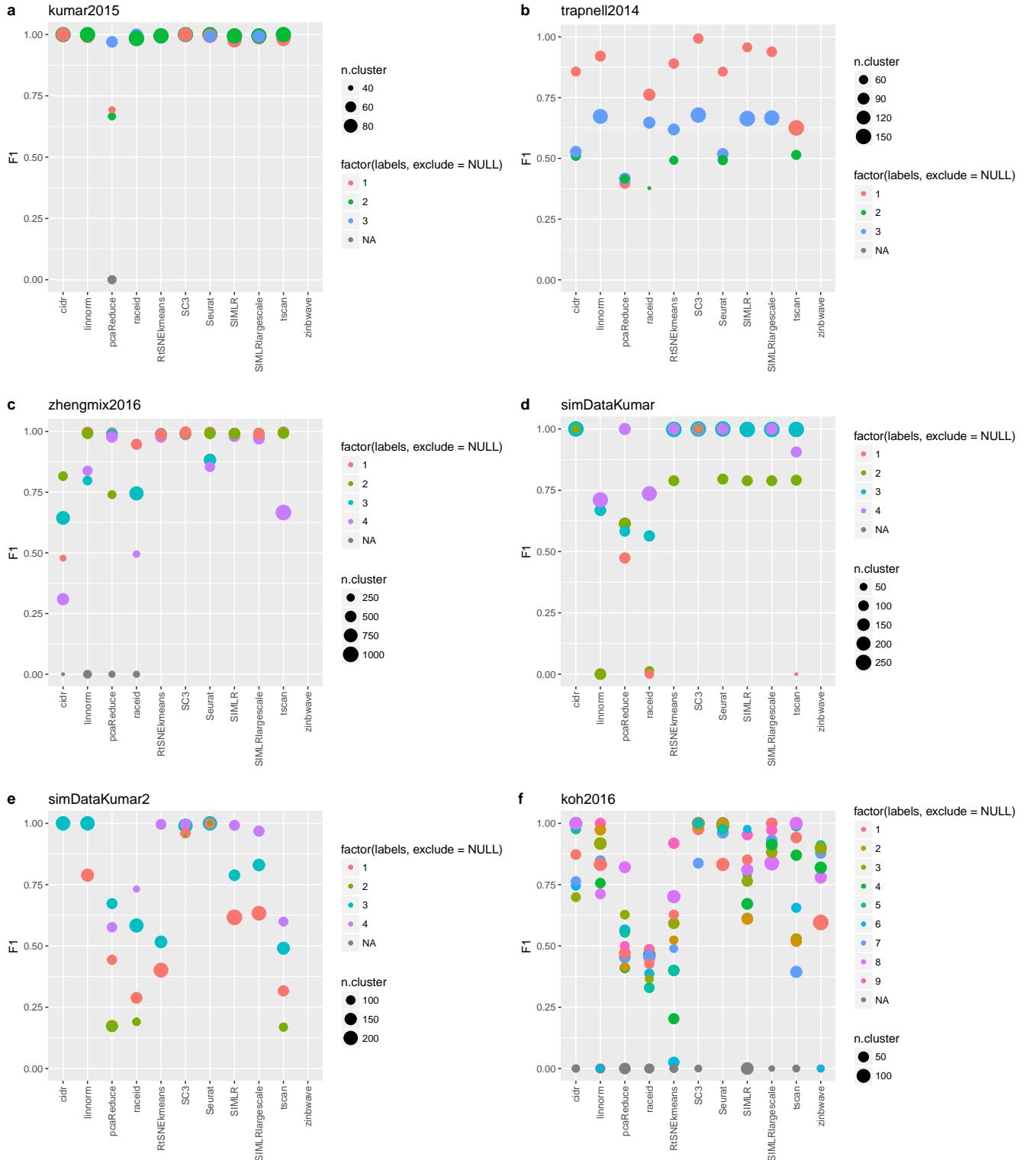


Figure 15: F1 scores for the otimalk dataset

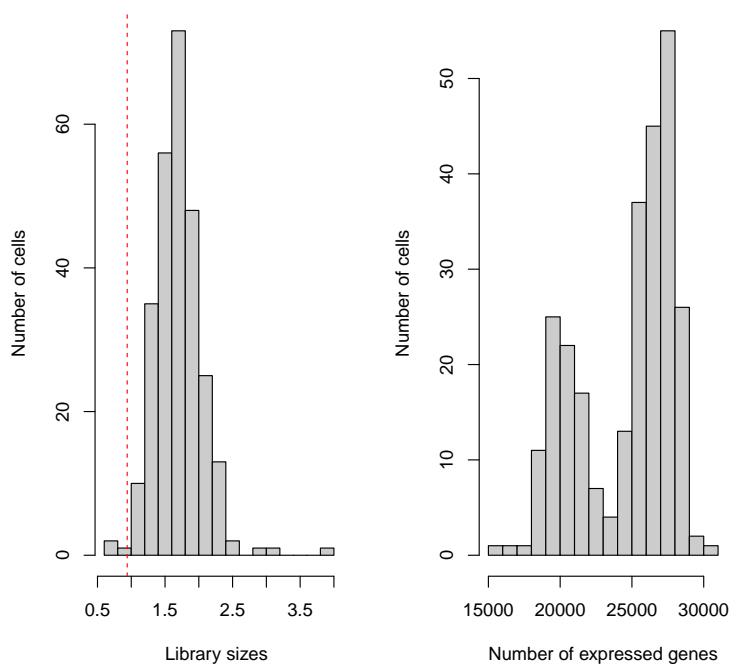


Figure 16: Histogram of Kumar 2014.

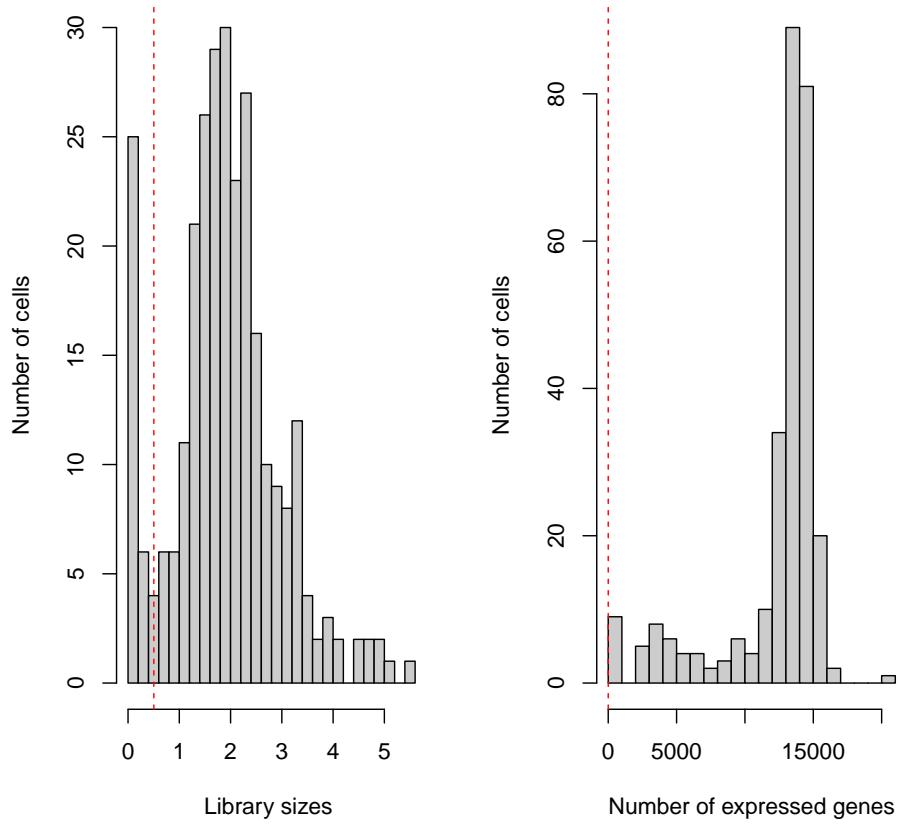


Figure 17: Histogram of Trapnell 2014.

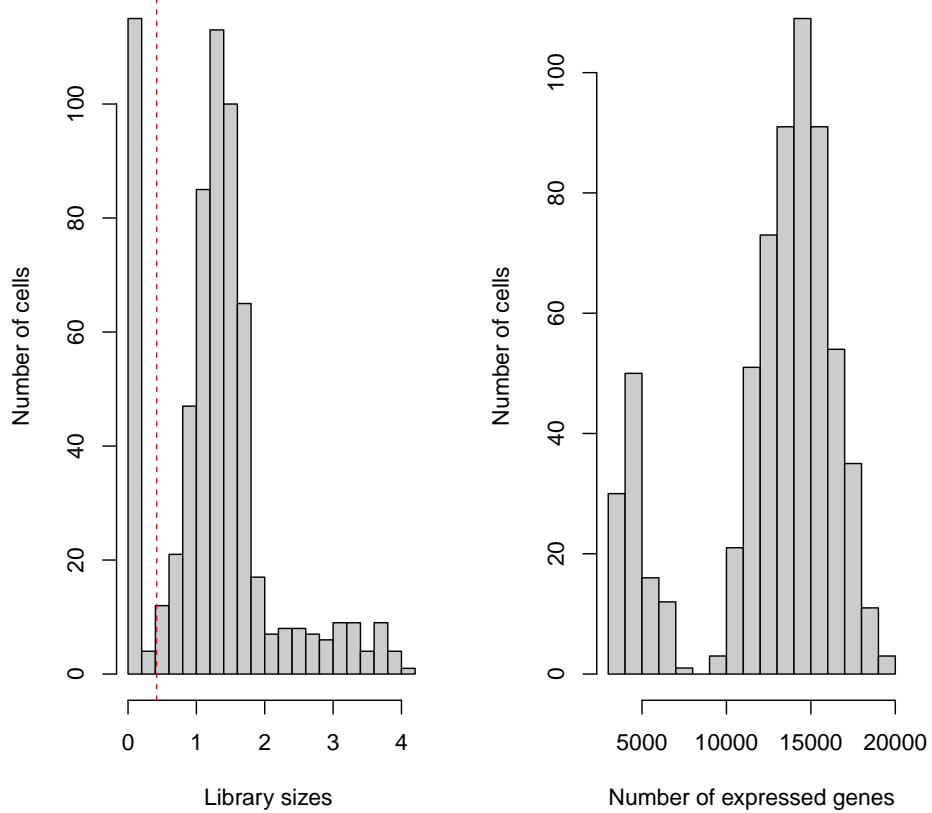


Figure 18: Histogram of Koh 2016.

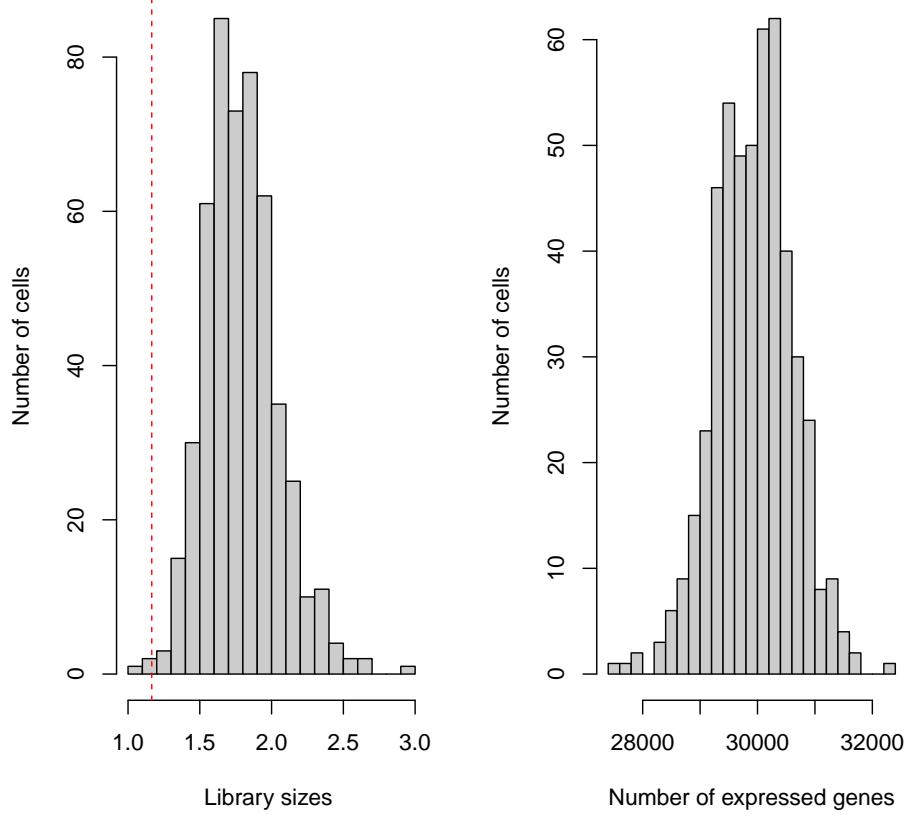


Figure 19: Histogram of simDataKumar.

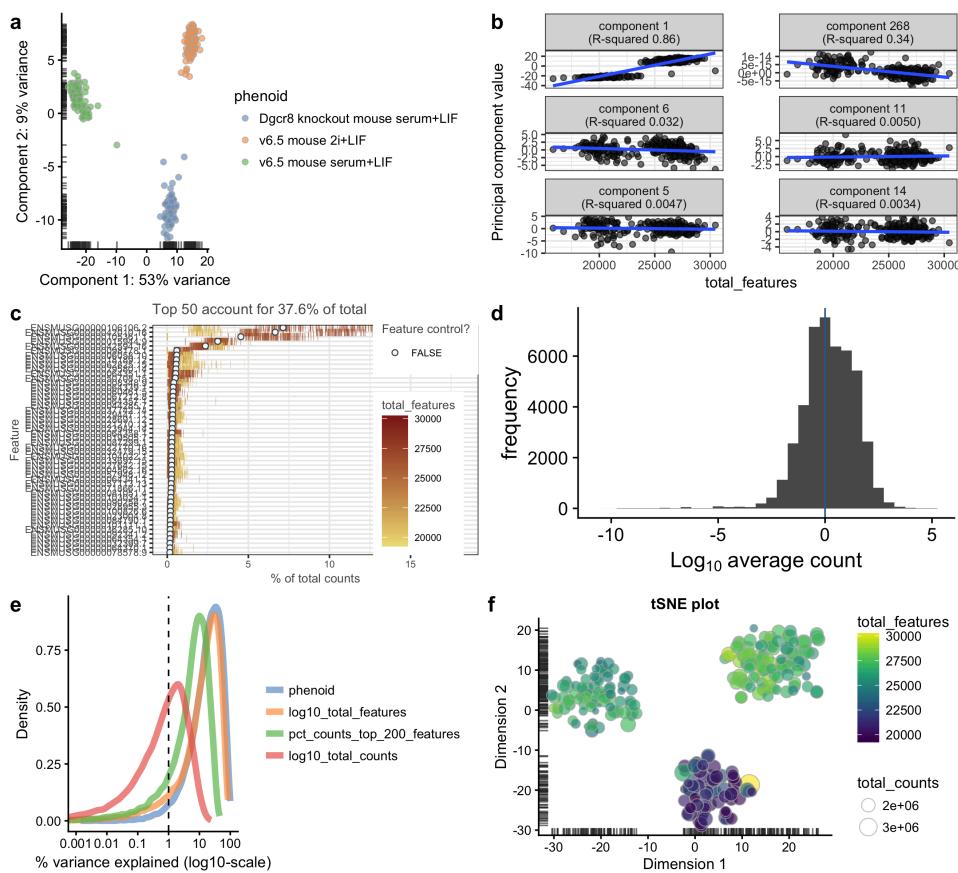


Figure 20: QC summary of Kumar 2015.

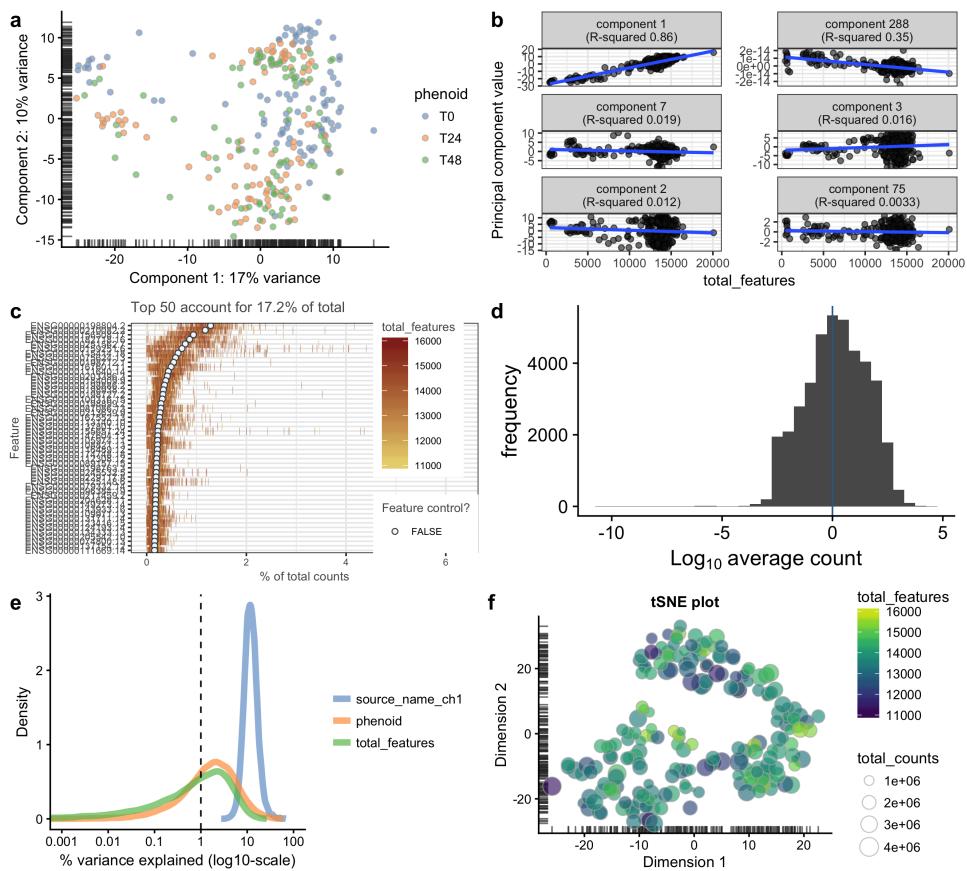


Figure 21: QC summary of Trapnell 2014.

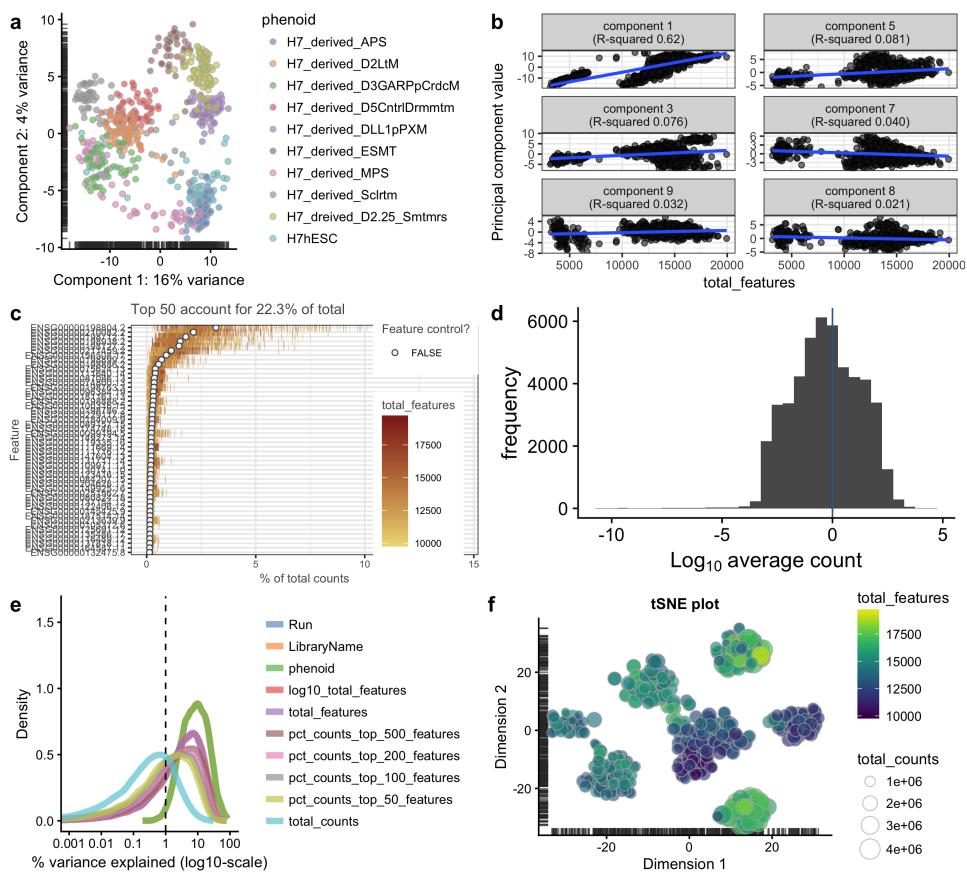


Figure 22: QC summary of Koh 2016.

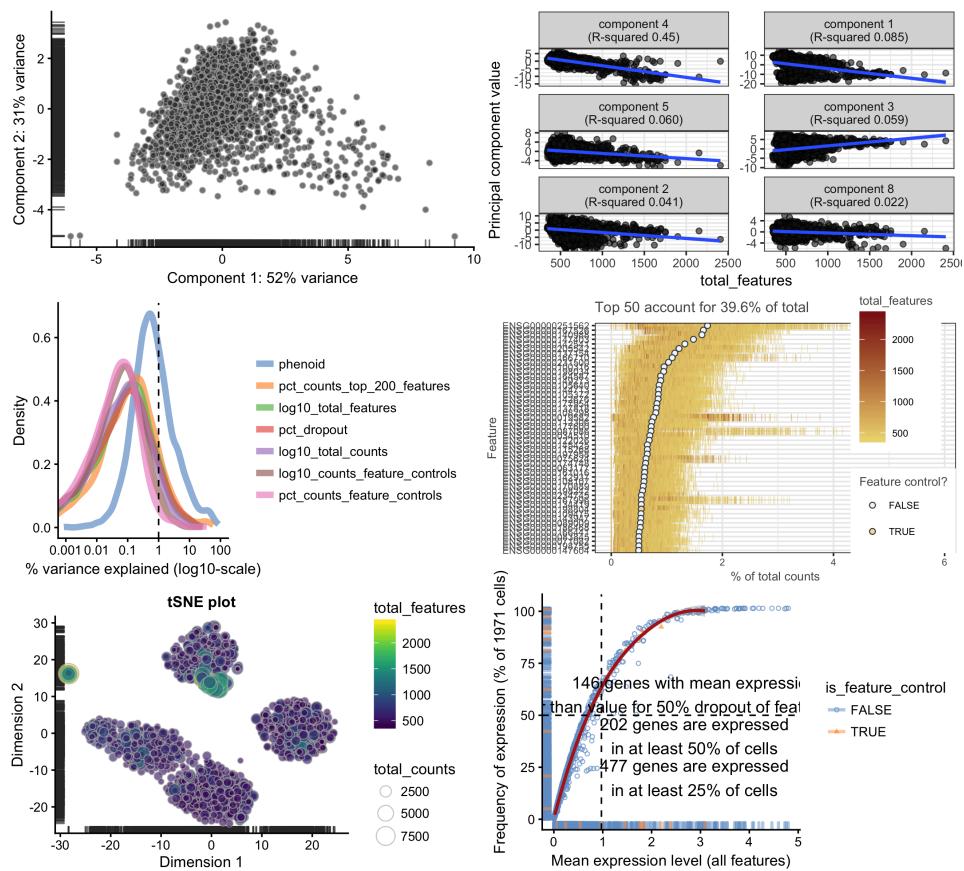


Figure 23: QC summary of Zheng 2016.

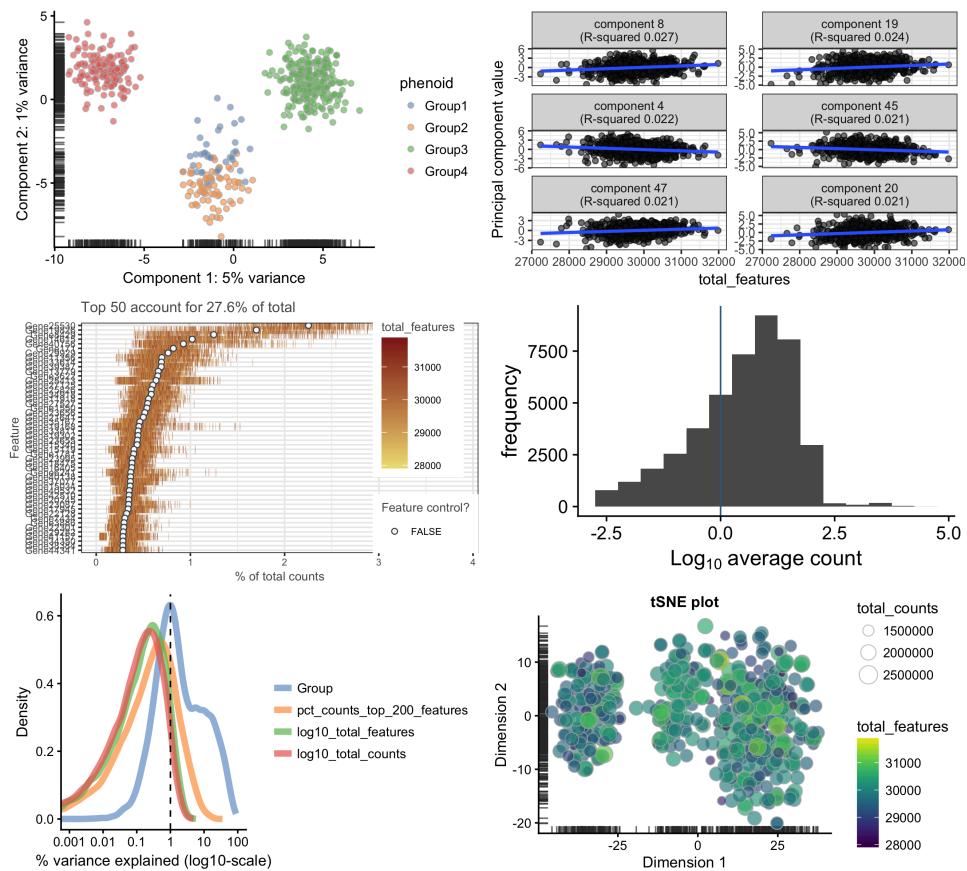


Figure 24: QC summary of simDataKumar.

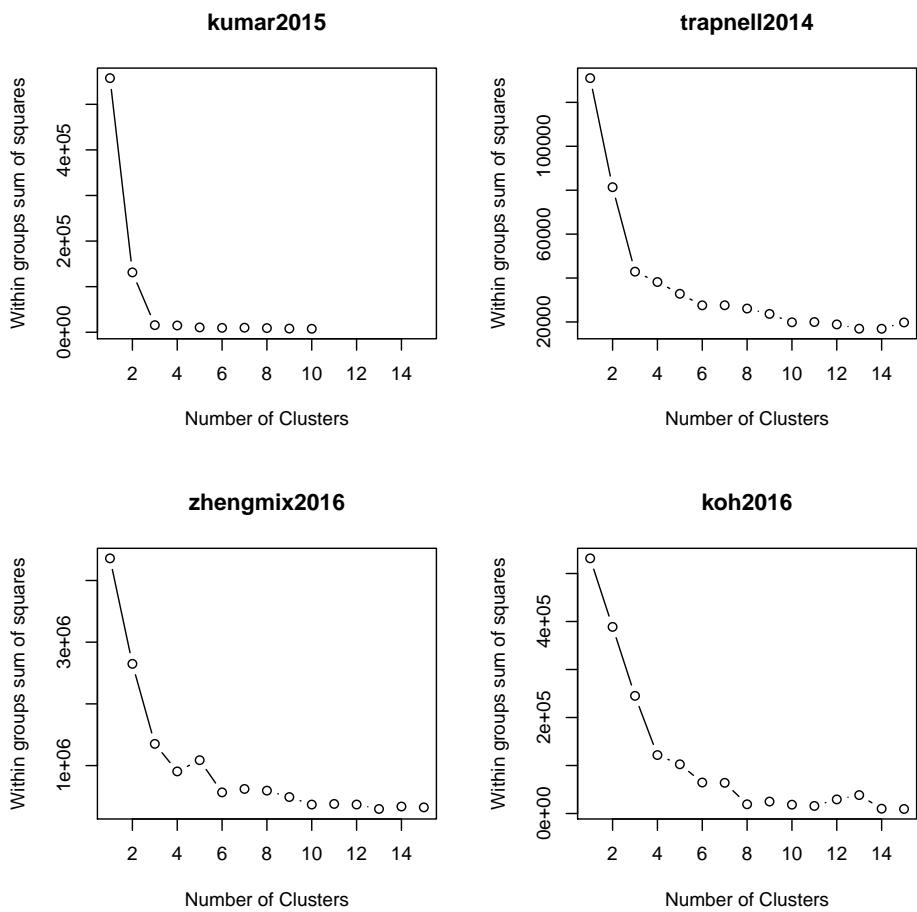


Figure 25: Optimal number of clusters by minimizing within sum of squares based on the latent space of tSNE (30 dimensions)

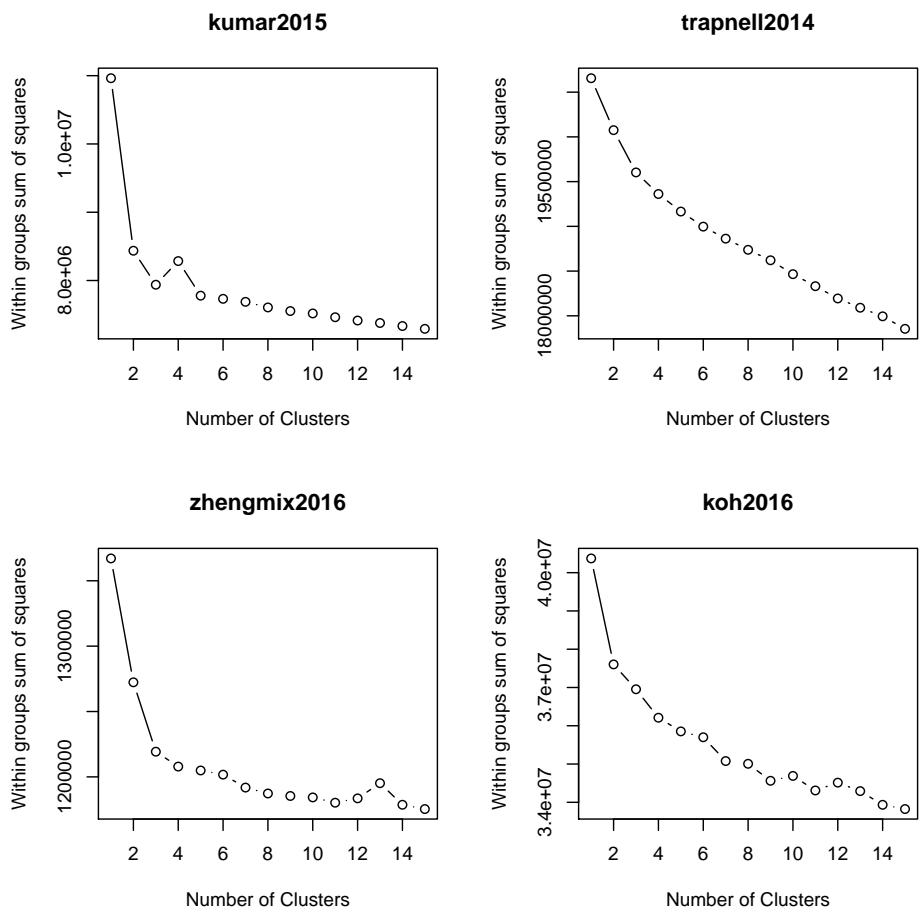


Figure 26: Optimal number of clusters by within sum of squares based on the full dimensions

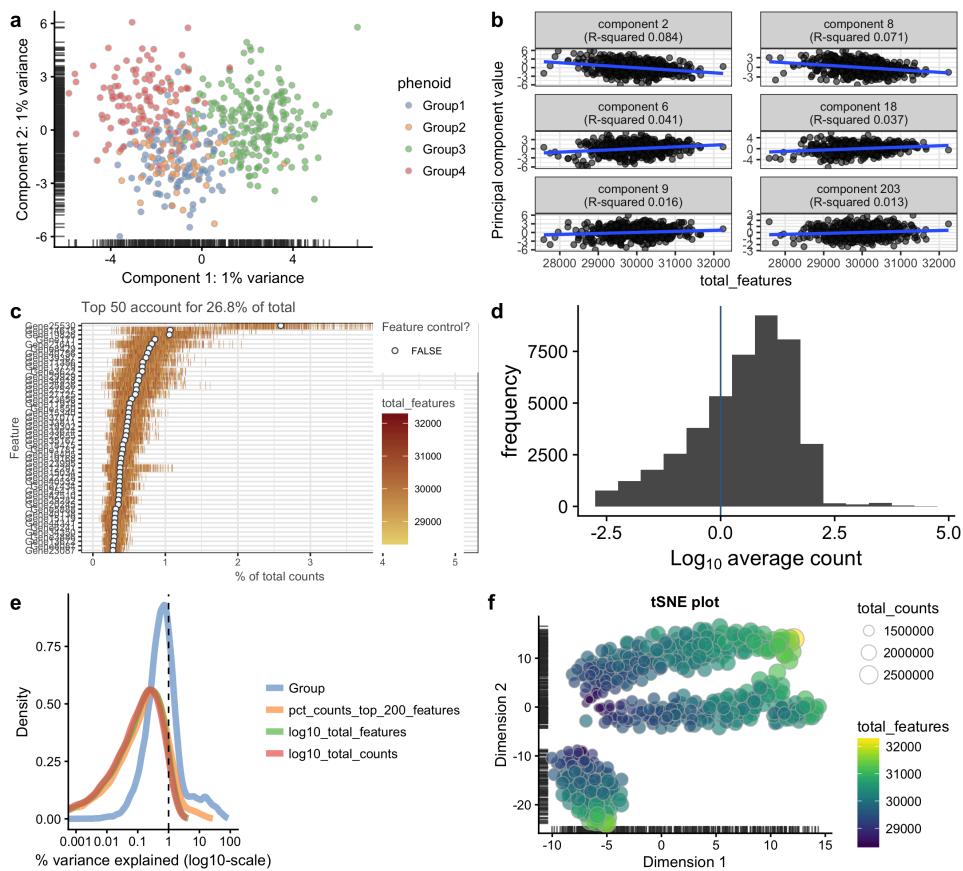


Figure 27: QC summary of simDataKumar2.

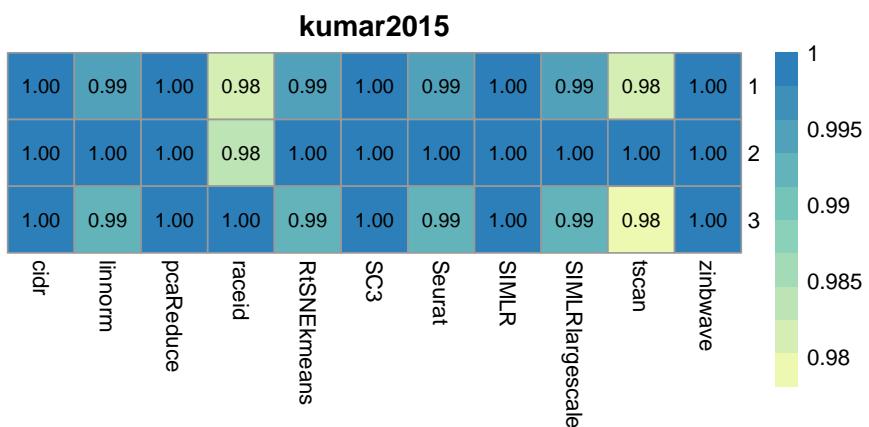


Figure 28: F1 scores for the filtered Kumar dataset

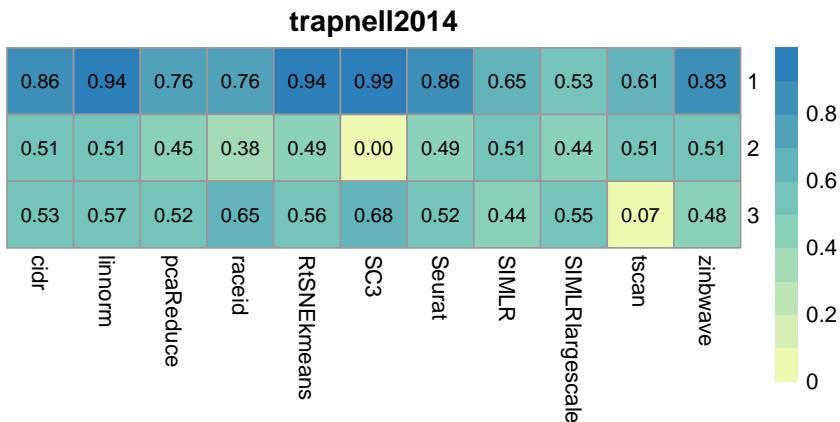


Figure 29: F1 scores for the filtered Trapnell dataset

Only the methods SC3, and SIMLR (for large-scale data) were able to identify cell population 1. The proportions of differentially expressed genes are relatively low for three out of the four subgroups, and these populations are relatively distinct. However, RaceID and pcaReduce had substantially lower ARI scores in the default setting. It is unclear why pcaReduce and RaceID performed badly under the default setting. Most methods were able to identify these three clusters correctly. Most methods achieved high F1 scores for subpopulation 1. The scores were substantially lower for the subpopulations 2 and 3. TSCAN failed to identify the subpopulation 3. The Koh dataset had the highest number of clusters of the studied datasets. Here, only the methods SC3 and Seurat achieved an almost perfect partition of the cells.

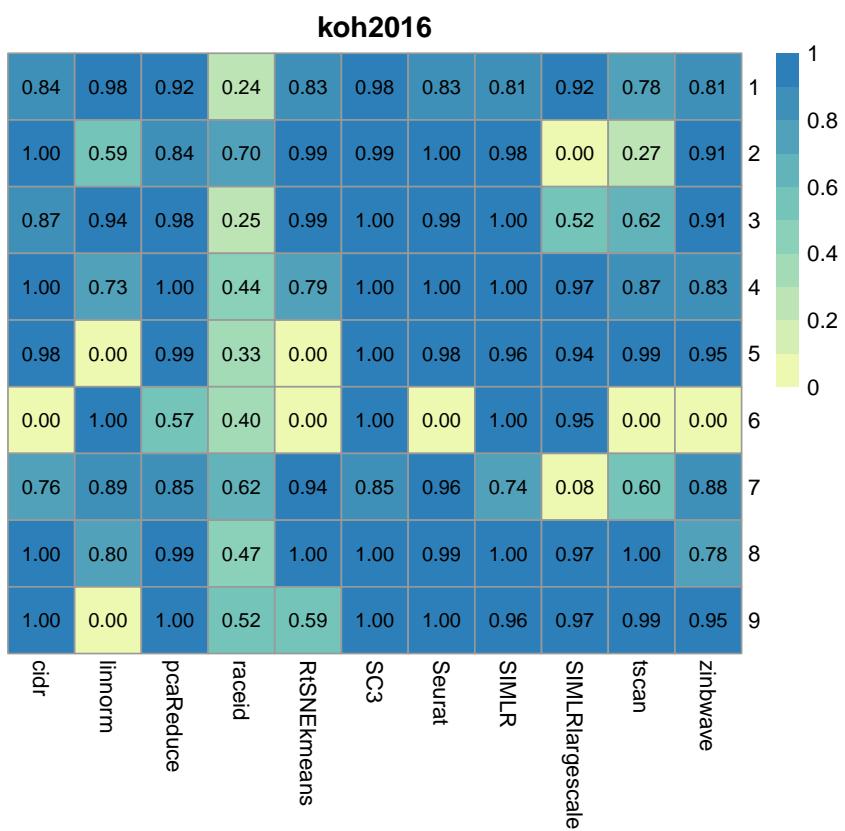


Figure 30: F1 scores for the filtered Koh dataset

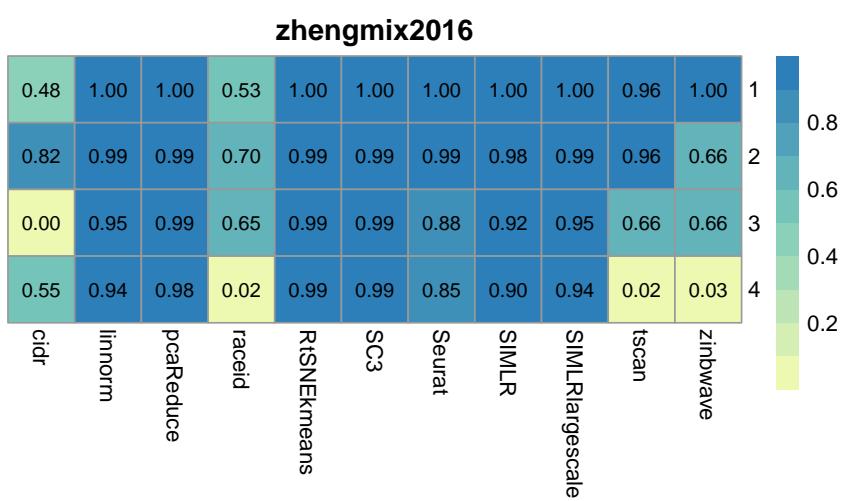


Figure 31: F1 scores for the filtered Zheng mix dataset

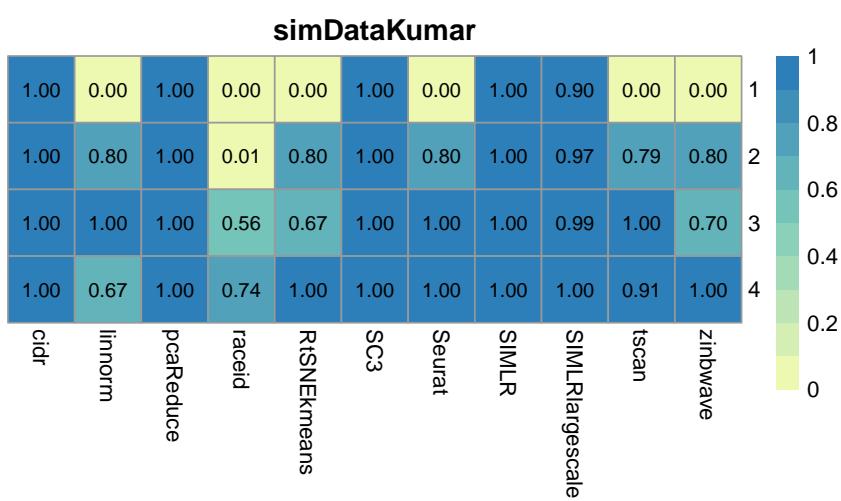


Figure 32: F1 scores for the filtered simDataKumar.

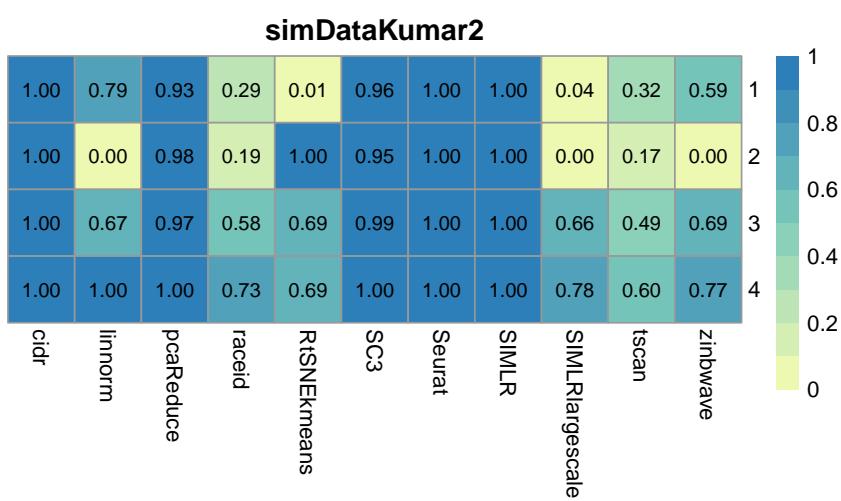


Figure 33: F1 scores for the filtered simDataKumar2.

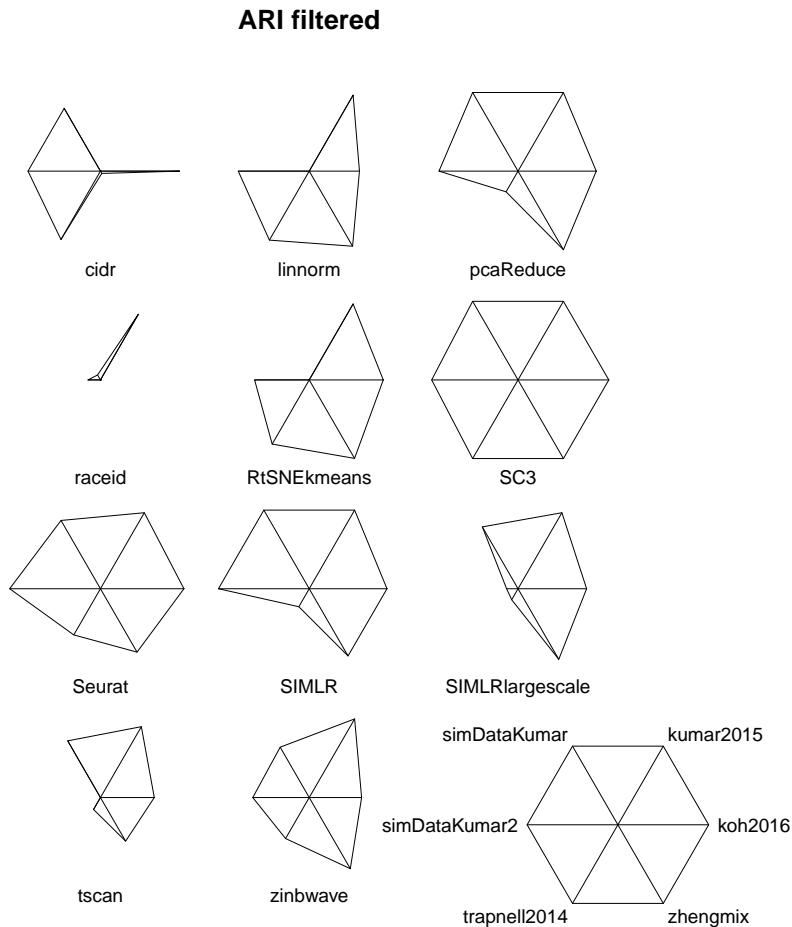


Figure 34: Starplot of ARI scores.

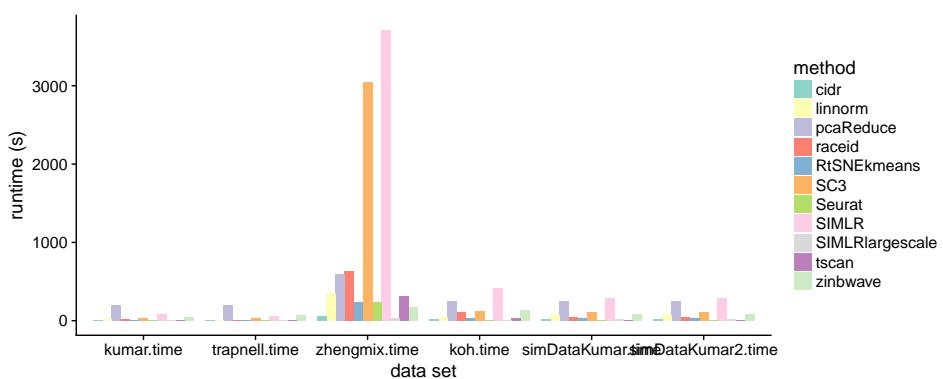


Figure 35: Runtime (s) for the methods on the datasets Kumar Trapnell, Zheng, Koh, simDataKumar and simDataKumar2. The datasets are filtered and the number of clusters based on the ground truth is used.

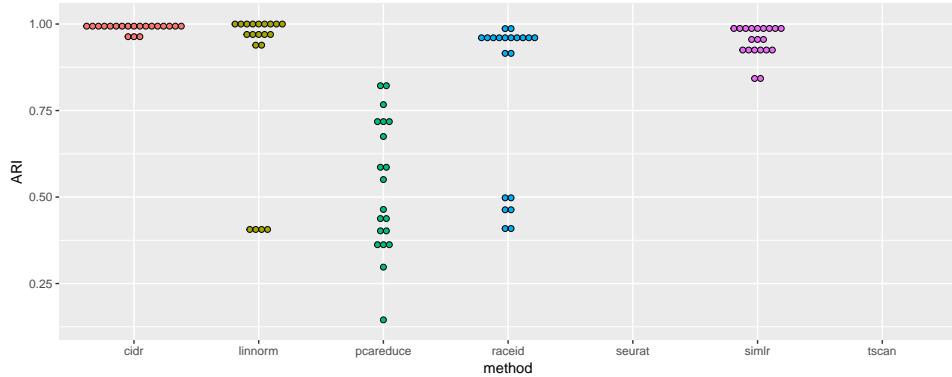


Figure 36: Stability analysis results with (20) bootstrap samples for the Kumar dataset.

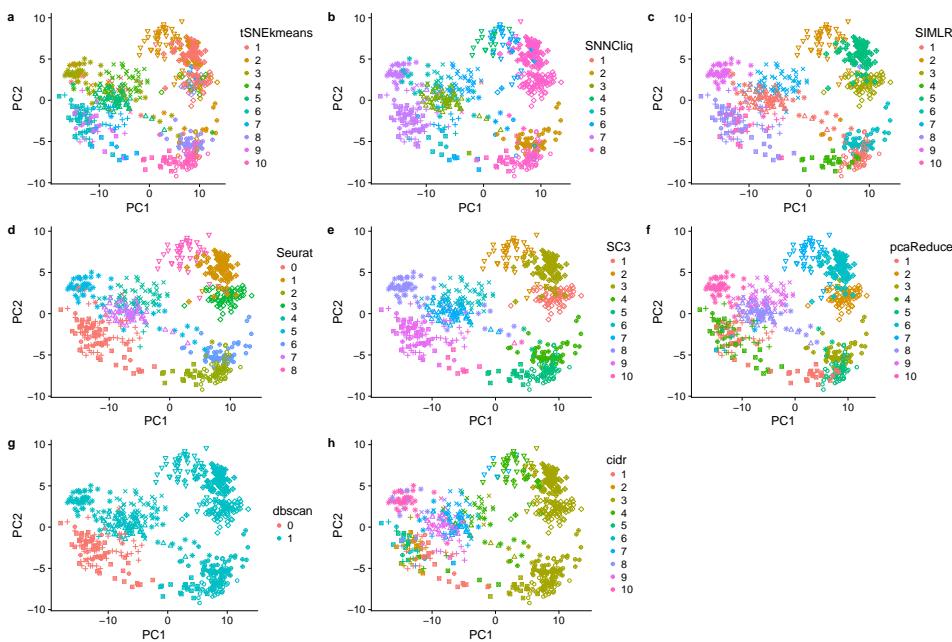


Figure 37: Clusters koh2016 on PC representations.

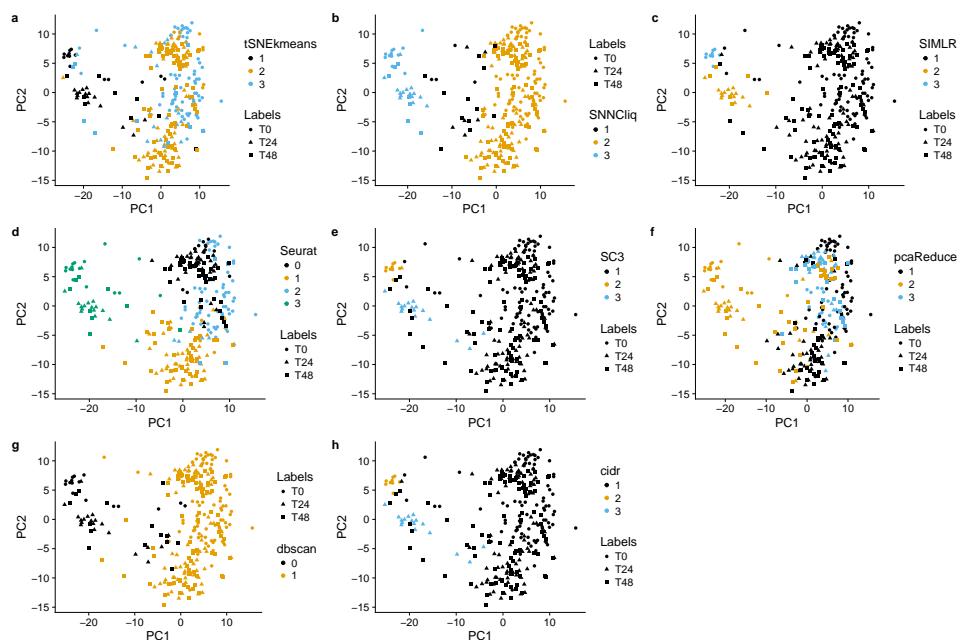


Figure 38: Clusters Trapnell 2014 on PC representations.