

Parametric or Nonparametric: The FIC Approach for time series

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Modelling time series

Working class

- Zero-mean stationary Gaussian time series, $Y_t, t = 1, \dots, n$
- The model is fully specified by the covariance function:

$$C_G(k) = \text{Cov}(Y_t, Y_{t+k}) = \int_{-\pi}^{\pi} \exp(i\omega k) \, dG(\omega) = 2 \int_0^{\pi} \cos(\omega k) \, dG(\omega)$$

- Spectral measure G with spectral density g unknown, how should we model it?
- Parametric approach: Use a spectral measure F_θ with spectral density f_θ , parameterized by some θ
 - AR(p), MA(q), ARMA(p, q), etc.
- Nonparametric approach: Periodogram based $\tilde{G}_n = 2 \int_0^\omega I_n(u) \, du$,
for $I_n(\omega) = \frac{1}{2\pi n} \left| \sum_{t \leq n} y_t \exp(i\omega t) \right|^2$ the periodogram

Model selection for time series

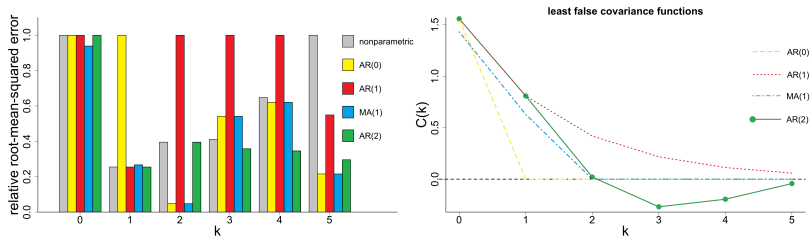
- Classical model selection
 - Information criteria: AIC, BIC, AICc, FPE, HQ-criterion, ...
 - Goodness-of-fit/ badness-of-fit test: Testing 'whiteness' of fitted residuals with Portmanteau tests, frequency domain tests, etc.
- No particularly well-suited criterion for model selection among parametrics and nonparametrics
- Different models have strengths and weaknesses at different parts of the data space
- What you want to learn should reflect your choice of model

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Proof of concept – estimate $C_G(k)$

- Simulate AR(2) with $n = 100$ where $\sigma = 1, \rho = (0.7, -0.6)^t$
- Performance for 5 different candidate models: AR(0), AR(1), AR(2), MA(1), Nonparametric



- Left panel: Root-MSE of model based estimators for different lags (relative to worst estimate)
- Right panel: Limiting covariance functions for different models
- Different models are best for different lags

Focus parameter

- A general population quantity μ of interest

Examples

- Covariance/correlation lag k :
 $C_G(k) = \text{Cov}(Y_t, Y_{t+k}), \quad \rho_G(k) = \text{corr}(Y_t, Y_{t+k})$
- Conditional expectation k step ahead $E_G[Y_{t+k} | Y_t, \dots, Y_{t-m}]$
- Threshold probabilities: $\Pr_G\{Y_{t+k} > y_0 | Y_t, \dots, Y_{t-m}\}$
- A functional of the spectral measure G , for simplicity assumed to be on the form

$$\mu(G, s, h) = s \left(\int_{-\pi}^{\pi} h(\omega) \, dG(\omega) \right),$$

where $h^t = (h_1, \dots, h_m)$, with the h_j are univariate functions bounded on $[-\pi, \pi]$ with a finite number of discontinuities and s is smooth function from \mathbb{R}^m to \mathbb{R}

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Criterion idea

- Model selection problem \rightarrow Best estimator for μ
- Estimate μ by plug-in estimation for each model M :
 $\hat{\mu}_M = \mu(\hat{G}_M, s, h)$
- Performance measure:

$$\text{mse}(\hat{\mu}_M) = \text{E}[(\hat{\mu}_M - \mu_{\text{true}})^2] = \text{bias}^2(\hat{\mu}_M) + \text{Var}(\hat{\mu}_M)$$

Basic idea

- Estimate the mean squared error (mse) as squared bias + variance:

$$\text{FIC}(M) = \widehat{\text{mse}}(\hat{\mu}_M) = \widehat{\text{bias}}^2(\hat{\mu}_M) + \widehat{\text{Var}}(\hat{\mu}_M)$$

- Choose the model and estimator with the smallest estimated mse

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Estimation and limit theory

Parametric estimation (Maximum likelihood):

- ML-estimator: $\hat{\theta}_n = \arg \max_{\theta} \ell_n(\theta)$, for $\ell_n(\theta)$ Gaussian log-likelihood of parametric spectral measure class F_{θ}
- No θ_{true} exists outside model conditions. Rather θ_0 least false parameter minimizing $d(g, f_{\theta}) = -\frac{1}{4\pi} \int_{-\pi}^{\pi} \left(\log \frac{g(\omega)}{f_{\theta}(\omega)} + 1 - \frac{g(\omega)}{f_{\theta}(\omega)} \right) d\omega$
- Asymptotic distribution: $\sqrt{n}(\hat{\theta}_n - \theta_0) \rightarrow_d N(0, \Sigma_0)$, with $\Sigma_0 = \Sigma_0(g, f_{\theta_0})$
 $\Rightarrow \sqrt{n}(F_{\hat{\theta}_n}(\omega) - F_{\theta_0}(\omega)) \rightarrow_d X(\omega),$

for $\omega \in [0, \pi]$ and $X(\cdot)$ a zero-mean Gaussian process

Nonparametric estimation

- Estimator of spectral measure G : $\tilde{G}_n(\omega) = 2 \int_0^{\omega} I_n(u) du$
- Asymptotic distribution:

$$\sqrt{n}(\tilde{G}_n(\omega) - G(\omega)) \rightarrow_d W_2 \left(2\pi \int_0^{\omega} g(u)^2 du \right),$$

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MSE approximation

- $\hat{\mu}_{\text{pm}} = \mu(F_{\hat{\theta}_n}, s, h) = s(\int_{-\pi}^{\pi} h(\omega) f_{\hat{\theta}_n}(\omega) d\omega)$
- $\hat{\mu}_{\text{np}} = \mu(\tilde{G}_n, s, h) = s(\int_{-\pi}^{\pi} h(\omega) I_n(\omega) d\omega)$
- Continuous mapping theorem, delta method etc gives:

$$\sqrt{n} \begin{pmatrix} \hat{\mu}_{\text{pm}} - \mu_0 \\ \hat{\mu}_{\text{np}} - \mu_{\text{true}} \end{pmatrix} \rightarrow_d N_2 \left(\begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} v_{\text{pm}} & v_c \\ v_c & v_{\text{np}} \end{pmatrix} \right),$$

where $\mu_0 = \mu(F_{\theta_0}, s, h)$ and $\mu_{\text{true}} = \mu(G, s, h)$

- First order approximations:

$$\text{mse}_{\text{pm}} \approx b^2 + v_{\text{pm}}/n \quad \text{and} \quad \text{mse}_{\text{np}} \approx 0^2 + v_{\text{np}}/n,$$

for $b = \mu_0 - \mu_{\text{true}}$

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MSE estimation and the FIC

Estimate unknown quantities by empirical analogues

$$v_{pm} \approx \hat{v}_{pm}, \quad v_{np} \approx \hat{v}_{np},$$

and

$$b^2 \approx \max\{0, \hat{b}^2 - \hat{v}_b/n\},$$

where

$$\hat{b} = \hat{\mu}_{pm} - \hat{\mu}_{np} \quad \text{and} \quad \hat{v}_b = \hat{v}_{pm} + \hat{v}_{np} - 2\hat{v}_c$$

Mse estimates: FIC scores

$$\text{FIC}(\hat{\mu}_{pm}) = \max\{0, \hat{b}^2 - \hat{v}_b\} + \hat{v}_{pm}/n$$

$$\text{FIC}(\hat{\mu}_{np}) = \hat{v}_{np}/n$$

- Compute for all parametric candidates + nonparametric
- Choose the model and estimator with the smallest FIC-score

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Theoretic properties

- Estimation outside model conditions
- Consistent variance and squared bias estimators

FIC asymptotics

- Parametrics biased: $Pr \{\text{Select pm}\} \rightarrow 0$
- Parametrics correct: $Pr \{\text{Select pm}\} \rightarrow \chi_1^2(2) \approx 0.843$
- Implicit focused hypothesis test of parametric model with significance level 0.157

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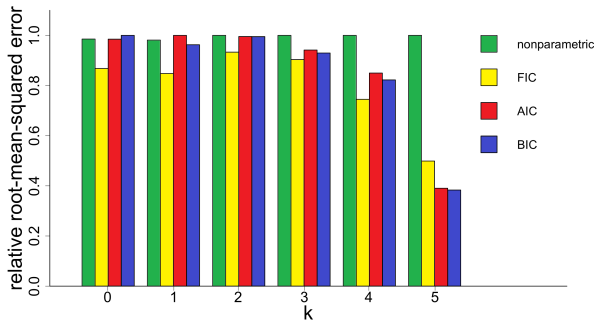
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Performance comparison

- Revisit the lagged covariance example
- Compare empirical root mean squared error of the estimators selected by FIC, AIC, BIC and Nonparametric



- The FIC works as intended choosing models with smaller risk for estimation of the different lags

Concluding remarks

- AFIC: Consider a weighted set of focus parameters simultaneously
 - Minimize risk = $\int \text{mse}(\hat{\mu}(t)) dW(t)$
 - Conceptually solved using $\int \text{FIC}(\hat{\mu}_M(t)) dW(t)$
- Time series with trends and covariates: $Y_t = m(t; \beta) + x_t^\top \gamma + \varepsilon_t$, with ε_t a zero-mean Gaussian stationary time series process

Origin:

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- Jullum and Hjort (2015): Parametric or Nonparametric: The FIC Approach

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