

Klækken 2013

Martin Jullum

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Statistical  
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Solution/app-  
roximation  
methods

Illustration

# Approximate Bayesian Inference for Geophysical Inverse Problems

Martin Jullum

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# Outline

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- 3 Solution/approximation methods
- 4 Illustration

# Oil and gas exploration

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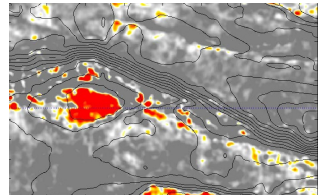
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Illustration

- Hard to determine where oil and gas are located
- Costs 200 - 800 million NOK to drill a exploration well
- Massive profit if one finds hydrocarbon reservoirs - large loss if not
  - Needs to estimate the probability of hydrocarbons



# Seismic survey

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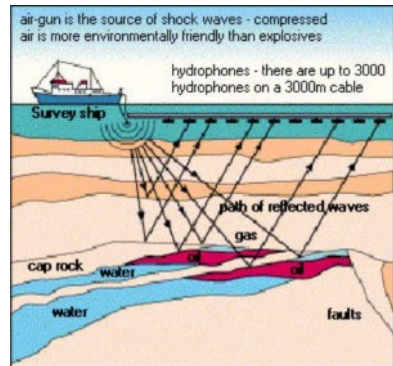
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- A source sends out shock waves
- Shock waves are reflected in the contrasts between the different facies (rock types)
- Receivers measure properties of smoothed reflected wave signals: Seismic data



# Problem setup

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- The behavior of the reflected waves depends on the contrast facies
- Seismic data can be processed to tell us about the material properties
- Different facies have different material properties
- We would like to estimate the facies probability distribution at various locations below the seabed

## Relations:

- $Z = XY + \epsilon$ , for some error term  $\epsilon$ 
  - $Z$ : Seismic Data
  - $X$ : Data link (design matrix/dynamics)
  - $Y$ : Rock material characteristics
- $\theta$ : Facies categories

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# Hierarchical model setup

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- $p(Z|Y)$ : Seismic data model
- $p(Y|\theta)$ : Latent rock material physics model
- $p(\theta)$ : Categorical facies model
- The forward problem: Determine  $Z$  from  $\theta$
- The inverse problem we are interested in: Determine  $\theta$  from  $Z$ : I.e. the standard Bayesian problem of finding the posterior  $p(\theta|Z)$ .
- **Main problem**
  - Great number of surface locations  $m$ , each with a large number of vertical positions - massive amounts of data
  - The wavelet smoothen the reflected signal data
  - $\dim(\theta)$  is enormous



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# How do we solve this?

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- The simplest reasonable assumptions:
  - $p(Z|Y, \theta) = p(Z|Y)$  is Gaussian
  - $p(Y|\theta)$  is Gaussian and  $p(Y_i|\theta) = p(Y_i|\theta_i)$  for some location  $i$  is also Gaussian
  - $p(\theta)$  is categorical

How to find/approximate  $p(\theta|Z)$ :

- Exact calculation - possible in theory, but not in practice
  - $p(\theta|Z) \propto p(Z|\theta)p(\theta)$  which means we need to calculate  $p(Z|\theta)$
  - $p(Z|\theta) = \int p(Z|y)p(y|\theta)dy$
  - The calculation requires summation over  $2^J$  - impossible (e.g. for large  $J$ )
- MCMC - similar problem as exact computation
- INLA - assumptions are not completely fulfilled
  - $p(Z|y)$  is Gaussian
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  - $p(Y|\theta)$  Gaussian: OK
  - $p(Z|Y, \theta) = \prod_{i=1}^n p(Z_i|\eta_i, \theta)$ , for linear predictor  $\eta_i$  of the  $Y_i$ s: Almost OK
  - $\dim(\theta)$  small: NO!

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# Locally focused approximation

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Let us focus on  $p(\theta_i|Z)$ , that is the posterior in one location only.

- Let  $p_G$  denote distributions under the Gaussian assumption.
- If  $p(Y) = p_G(Y)$ , then  $p(Y_i) = p_G(Y_i)$  and  $p(Y_i|Z) = p_G(Y_i|Z)$  as well. Then

$$\begin{aligned} p(\theta_i|Z) &\propto \int p(Z, Y_i, \theta_i) dY_i = p(\theta_i) \int p(Z|Y_i) p(Y_i|\theta_i) dY_i \\ &\propto p(\theta_i) \int \frac{p_G(Y_i|Z)}{p_G(Y_i)} p(Y_i|\theta_i) dY_i \end{aligned}$$

- The integrand consist of only Gaussians, so this is easy.
- $p(Y) = p_G(Y)$  is convenient, but generally incorrect

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# Locally focused approximation from a different perspective

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Illustration

We have exactly that

$$p(Y|Z) \propto p_G(Y|Z) \frac{p(Y)}{p_G(Y)}.$$

Thus, it follows that

$$\begin{aligned} p(\theta_i|Z) &\propto p(\theta_i) \int p(Y|Z) p(Y) p(Y|\theta_i) dY \\ &\propto p(\theta_i) \int \frac{p_G(Y|Z)}{p_G(Y)} p(Y|\theta_i) dY \\ &= \dots = p(\theta_i) \int \frac{p_G(Y_i|Z)}{p_G(Y_i)} p(Y_i|\theta_i) K(Y_i) dY_i \end{aligned}$$

where

$$K(Y_i) = \int \frac{p_G(Y_{-i}|Z, Y_i)}{p_G(Y_{-i}|Y_i)} p(Y_{-i}|\theta_i, Y_i) dY_{-i}$$

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# Locally focused approximation - with adjustment

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Illustration

By approximating  $K(Y_i)$  by a constant, which holds e.g. when  $p(Y_{-i}|\theta_i, Y_i) = p_G(Y_{-i}|Y_i)$ , we once again get

$$p(\theta_i|Z) \propto p(\theta_i) \int \frac{p_G(Y_i|Z)}{p_G(Y_i)} p(Y_i|\theta_i) dY_i.$$

- Even when relaxing the assumption of  $p(Y|\theta) \sim \text{Gaussian}$  this can be calculated by numerical integration since the dimension of  $Y_i$  is typically  $\leq 3$ .

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# Simple example

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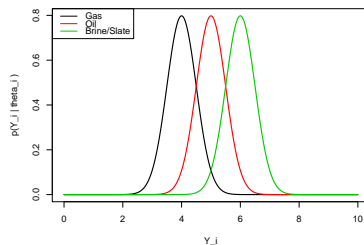
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- One surface location with  $n = 5$  vertical positions
- $\dim(Y_i) = 1$  and  $Y$  denotes acoustic impedance
- 4 possible facies: Slate, Brine, Oil and Gas
- Ignore wavelet smoothing
- Observe  $n - 1$  contrasts (Seismic data)



# Two basic situations

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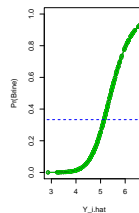
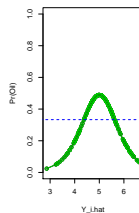
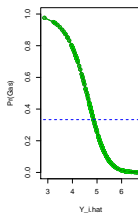
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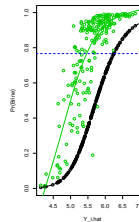
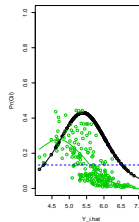
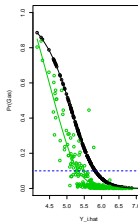
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Illustration

Slate
Slate
?
Slate
Slate



Slate
?
?
?
Slate



# Summary

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Illustration

- The approximation can be rough, but is very fast.
- Do not need to specify the whole categorical distribution  $p(\theta)$ , but only  $p(\theta_i)$

Further work:

- Need to address in which situations  $K(Y_i)$  is approximately constant
- Alternative approximations (ideas!)
  - Naïve Laplace approximation for  $p(Y_i)$ ,  $p(Y_i|Z)$
  - Simplified Gaussian mixture approximation for  $p(Y_i)$ ,  $p(Y_i|Z)$
  - Weighted local neighborhood approximation
  - Exact integration with single weight shared over all  $Y_i$
  - Dimension reduction
  - Other approximations?

## Summary

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  - Simplified Gaussian mixture approximation for  $p(Y_i), p(Y_i|Z)$
  - Wider local neighborhood approximation
  - Exact computation with simple neighborhood structure on  $Y$ .
  - Dimension reduction?
  - Other alternatives?



# Summary

Klækken 2013

Martin Jullum

The practical  
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Statistical  
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Solution/app-  
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methods

Illustration

- The approximation can be rough, but is very fast.
- Do not need to specify the whole categorical distribution  $p(\theta)$ , but only  $p(\theta_i)$

Further work:

- Need to address in which situations  $K(Y_i)$  is approximately constant
- Alternative approximations (ideas!)
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  - Simplified Gaussian mixture approximation for  $p(Y_i), p(Y_i|Z)$
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