

$$\boxed{u_1, v_1, d_1 \Rightarrow u_2, v_2}$$

$$\begin{aligned} ⑥ \quad \begin{pmatrix} x_w \\ y_w \\ z_w \end{pmatrix} &= (R \ t)^{-1} \begin{pmatrix} x_c \\ y_c \\ z_c \end{pmatrix} \\ &= (R \ t)^T (K^{-1}) \begin{pmatrix} z_c u \\ z_c v \\ z_c \end{pmatrix} \\ &= P^{-1} \begin{pmatrix} d_u \\ d_v \end{pmatrix} \end{aligned}$$

$$2. \ P_1, P_2, \begin{pmatrix} u_1 \\ v_1 \end{pmatrix}, \text{depth}_1 = d_1 \Rightarrow \begin{pmatrix} u_2 \\ v_2 \end{pmatrix}$$

①

$$\begin{aligned} \begin{pmatrix} d_2 u_2 \\ d_2 v_2 \\ d_2 \end{pmatrix} &= P_2 \begin{pmatrix} x_w \\ y_w \\ z_w \end{pmatrix} = P_2 P_1^{-1} \begin{pmatrix} d_1 u_1 \\ d_1 v_1 \\ d_1 \end{pmatrix} \\ &= (K_2) (R \ t) \begin{pmatrix} K_1^{-1} \\ 1 \end{pmatrix} \begin{pmatrix} d_1 u_1 \\ d_1 v_1 \\ d_1 \end{pmatrix} \\ &= \begin{pmatrix} K_2 R K_1^{-1} & K_2 t \\ 1 & 1 \end{pmatrix} \begin{pmatrix} d_1 u_1 \\ d_1 v_1 \\ d_1 \end{pmatrix} \end{aligned}$$

$$② \quad \begin{pmatrix} d_2 u_2 \\ d_2 v_2 \\ d_2 \end{pmatrix} = (K_2 R K_1^{-1}) \begin{pmatrix} d_1 u_1 \\ d_1 v_1 \\ d_1 \end{pmatrix} + K_2 t = H \begin{pmatrix} d_1 u_1 \\ d_1 v_1 \\ d_1 \end{pmatrix} + b$$

$$③ \quad (R \ t) = (R_2 \ t_2) (R_1 \ t_1)^{-1} \Rightarrow P = P_2 P_1^{-1}, \ t = t_2 - R t_1$$

$$\begin{aligned} 1. \ P, d, \begin{pmatrix} u \\ v \end{pmatrix} &\Rightarrow \begin{pmatrix} x_w \\ y_w \\ z_w \end{pmatrix} \\ ① \quad \begin{pmatrix} x_c \\ y_c \\ z_c \end{pmatrix} &= (R \ t) \begin{pmatrix} x_w \\ y_w \\ z_w \end{pmatrix} \end{aligned}$$

$$d = \text{depth} = z_c$$

$$② \quad \begin{pmatrix} x_c \\ y_c \\ z_c \end{pmatrix} \xrightarrow{\text{project}} \begin{pmatrix} x_c \\ y_c \\ z_c \end{pmatrix}$$

$$③ \quad \begin{pmatrix} x_c \\ y_c \\ z_c \end{pmatrix} \rightarrow \begin{pmatrix} x_c / z_c \\ y_c / z_c \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} u \\ v \\ 1 \end{pmatrix} = K \begin{pmatrix} x_c / z_c \\ y_c / z_c \\ 1 \end{pmatrix}$$

$$④ \quad \begin{pmatrix} x_c \\ y_c \\ z_c \end{pmatrix} = z_c K^{-1} \begin{pmatrix} u \\ v \\ 1 \end{pmatrix}$$

$$⑤ \quad \begin{pmatrix} x_c \\ y_c \\ z_c \end{pmatrix} = \begin{pmatrix} z_c K^{-1}(u) \\ 1 \end{pmatrix} = (K^{-1}) \begin{pmatrix} z_c u \\ z_c v \\ z_c \end{pmatrix}$$