#### **Section 7**

#### **Instrumental Variables**

Sooahn Shin

**GOV 2003** 

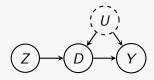
Oct 21, 2021

#### **Overview**

- Logistics:
  - Pset 6 released! Due at 11:59 pm (ET) on Oct 27
- Today's topics:
  - 1. Noncompliance in randomized experiments
  - 2. IV in observational studies using TSLS

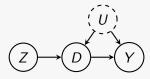
## Noncompliance in randomized experiments

- Motivation: What if there is unmeasured confounding?
- In randomized experiments: when treatment assignment is randomized but cannot intervene treatment uptake.
  - ¬ noncompliance (one- or two-sided)
- DAG example:



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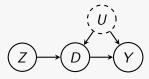
• Estimand: LATE = ITT effect on the outcome for compliers

$$\mathsf{ITT}_{Y,\mathsf{co}} = \frac{1}{n_{\mathsf{co}}} \sum_{i: C_i = \mathsf{co}} Y_i(1, D_i(1)) - Y_i(0, D_i(0))$$

• Q: Why not ITT<sub>Y</sub>?

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- Q: Why not ITT<sub>Y</sub>?
- Example (one- or two-sided)? Identification? Estimation?

One-sided example:

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canvass assignment (Z_i) - canvass recieved (D_i) - turn out (Y_i)
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  - $D_i(1) = 0$ : Noncompliers. If assigned to canvassing, I would not receive it.
  - Q: Can we identify this by observing  $Z_i$  and  $D_i$ ? What can we know (hint:  $ITT_D$ )?

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  - Q: Can we identify this by observing  $Z_i$  and  $D_i$ ? What can we know (hint:  $ITT_D$ )?
- Assumptions:
  - 1. Randomization of  $Z_i$
  - 2. Presence of some compliers  $\pi_{co} \neq 0$
  - 3. Exclusion restriction  $Y_i(z, d) = Y_i(z', d)$  (i.e.,  $Z_i$  only affects  $Y_i$  through  $D_i$ )

Identification: LATE Theorem under the previous assumptions

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  - Wald or IV estimator

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- It is biased, but consistent for  $\tau_{\text{LATE}}$
- Equivalent to the TSLS estimator under binary instrument and binary treatment
  - 1. Regress  $D_i$  on  $Z_i$  and get fitted values  $\widehat{D}_i$
  - 2. Regress  $Y_i$  on  $\widehat{D}_i$  and get the slope
  - Intuitively, TSLS retains only the variation in D<sub>i</sub> that is generated by the instrument Z<sub>i</sub> in the first stage.
  - → use AER::ivreg() in practice.

- Variance estimation:
  - Wald estimator: Use delta method to find the asymptotic variance

$$\mathbb{V}\left[\widehat{\tau}_{iv}\right] \approx \frac{1}{\mathsf{ITT}_D^2} \mathbb{V}\left[\widehat{\mathsf{ITT}}_Y\right] + \frac{\mathsf{ITT}_Y^2}{\mathsf{ITT}_D^4} \mathbb{V}\left[\widehat{\mathsf{ITT}}_D\right] - 2\frac{\mathsf{ITT}_Y}{\mathsf{ITT}_D^3} \mathsf{cov}\left[\widehat{\mathsf{ITT}}_Y, \widehat{\mathsf{ITT}}_D\right]$$

TSLS estimator: Don't use SEs from second step (see MHE section 4.6.1 2SLS Mistakes) → use ivpack::robust.se() in practice.

- Two-sided example: encouragement (Z<sub>i</sub>) - treatment (D<sub>i</sub>) - outcome (Y<sub>i</sub>)
  - Or, testing habitual voting (Coppock and Green 2016):
     GOTV canvassing (2006) turn out (2006) turn out (2008)
  - LATE: Habitual voting for those who would vote iif they are contacted by a canvasser in this election

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- Compliance type by  $(D_i(0), D_i(1))$ :
  - (0,1): Complier
  - (1,1): Always-taker
  - (0,0): Never-taker
  - (1,0): Defier
  - Q: Can we identify this by observing Z<sub>i</sub> and D<sub>i</sub>? What can we know (hint: ITT<sub>D</sub>)?

- Two-sided example:
  - encouragement  $(Z_i)$  treatment  $(D_i)$  outcome  $(Y_i)$ 
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  - Q: Can we identify this by observing  $Z_i$  and  $D_i$ ? What can we know (hint:  $ITT_D$ )?
- Assumptions: 1-3 from the previous setup, and
  - 4. Monotonicity:  $D_i(1) \ge D_i(0)$ ,  $\forall i$  (no defiers)
  - Q: What does exclusion restriction/monotonicity imply in words?

Same identification result:

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- Same estimation as before.
- Further issues:
  - What if exclusion restriction/monotonicity is violated? Can we still use IV estimand for LATE? [Pset 6 Q2]
  - Detecting weak instruments? [Pset 6 Q3 (c)]

#### In R: Wald estimator

```
# *Recall what we did in Neyman's approach*
my_data # data includes Z, D, and Y
# Proportion of compliers (using ITT_D)
pi_co <- mean(my_data$D[my_data$Z == 1]) - mean(my_data$D[my_data$Z == 0])</pre>
# Compute ITT's
ITT_Y <- mean(my_data$Y[my_data$Z == 0]) - mean(my_data$Y[my_data$Z == 0])</pre>
ITT_D <- mean(my_data$D[my_data$Z == 1]) - mean(my_data$D[my_data$Z == 0])</pre>
\# (ITT_D = pi_co)
# TODO 1: Compute Wald estimator
Wald est <- NULL
```

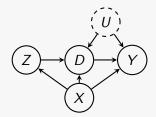
#### In R: Wald estimator

```
# TODO 2: Compute variance
# TODO 2-1: Compute variance terms using neyman estimator
Var ITT Y est <- NIII I
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# Compute covariance term
# demean
demeaned_y \leftarrow my_data\$Y[my_data\$Z == 1] - mean(my_data\$Y[my_data\$Z == 1])
demeaned_d \leftarrow my_data D[my_data = 1] - mean(my_data D[my_data = 1])
# denominator
denom <- sum(my_data$Z)*(sum(my_data$Z) - 1)
Covar_est <- (demeaned_y %*% demeaned_t)/denom
# TODO 2-2: Compute the estimate of the formula in p.6
Var Wald est <- NULL
```

#### In R: TSLS estimator

```
ivmodel <- AER::ivreg(Y ~ D | Z, data = my_data)
ivpack::robust.se(ivmodel)</pre>
```

- Motivation: What if there is unmeasured confounding?
- In observational studies: In case where
  - treatment is not randomized and there exist unmeasured confounder;
  - can find instrumental variable;
  - exogenous covariates  $(\mathbf{X}_i)$ : may exist observable confounders between  $Z_i$ ,  $D_i$ , and  $Y_i$
- DAG example:



- TSLS is the classical approach to IV
  - w/o covariates

$$D_i = \delta + \gamma Z_i + \eta_i$$
$$Y_i = \alpha + \tau D_i + \varepsilon_i$$

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w/ covariates

$$D_{i} = \delta + \gamma Z_{i} + \mathbf{X}'_{i} \beta_{d} + \eta_{i}$$

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- Recall the four canonical IV assumptions.
- Suppose we have binary treatment and binary instrument.
  - w/o covariates, TSLS estimand  $(\tau) = \text{LATE} (\tau_{\text{LATE}})$  and TSLS estimator = Wald estimator

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- Suppose we have binary treatment and binary instrument.
  - w/o covariates, TSLS estimand  $(\tau) = \text{LATE} (\tau_{\text{LATE}})$  and TSLS estimator = Wald estimator
  - w/ covariates, we need **constant effects** so that TSLS estimand  $(\tau) = \text{LATE} (\tau_{\text{LATE}})$ 
    - ullet Otherwise, au is an odd weighted function of causal effects

# In R: TSLS estimator w/ exogenous covariates

```
ivmodel <- AER::ivreg(Y ~ X1 + X2 + D | X1 + X2 + Z, data = my_data)
# Or, equivalently: Y ~ X1 + X2 + D | . -D + Z
ivpack::robust.se(ivmodel)
# For clustered error: use ivpack::cluster.robust.se()</pre>
```