# **Module 9: Panel Data**

Fall 2021

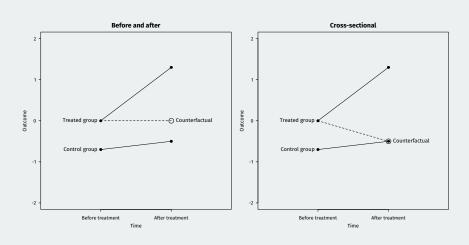
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Gov 2003 (Harvard)

### Where are we? Where are we going?

- · Where we have found good controls:
  - · Units randomized to receive control
  - · Units with similar values of covariates
  - Units with opposite value of some instrument
  - · At a discontinuity in treatment assignment
- · What if we have repeated measurements of the same units?
- · Now there are two possible sources of variation to exploit:
  - Exploit cross-sectional variation in treatment.
  - Exploit variation in treatment within a unit over time (before/after)

### **Cross-sectional vs before/after**



1/ Difference in differences

### Minimum wages (Card & Krueger, 1994)

- Does increasing the minimum wage affect employment?
- · Classical economic theory tends to point to negative effects.
- · But difficult to randomize changes to the minimum wage.
- In 1992, NJ minimum wage increased from \$4.25 to \$5.05
  - · Neighboring PA stays at \$4.25
  - We observe employment in both states before and after increase
- Look at eastern PA and NJ fast food restaurants.
  - · Similar prices, wages, products, etc.
  - Most likely to be affected by the change.

### **Differences-in-differences design**

- Basic setup: two groups, two time periods.
  - Pre-period (t = 0): neither group is treated.
  - Post-period (t = 1): one group is treated, other remains untreated.
- · Groups defined by treatment status in post-period:
  - $G_i = 1$  are those that are treated at t = 1
  - $G_i = 0$  for those that are always untreated
- · Treatment status in each period:
  - No treatment in the first period for either group:  $D_{i0} = 0$
  - In treated group,  $G_i = 1 \rightsquigarrow D_{i1} = 1$
  - In control group,  $G_i = 0 \rightsquigarrow D_{i1} = 0$

	Time period	
	Pre-period $(t = 0)$	Post-period $(t=1)$
Control group $(G_i = 0)$	$D_{i0} = 0$	$D_{i1} = 0$
Treated group $(G_i = 1)$	$D_{i0} = 0$	$D_{i1} = 1$

### Potential outcomes approach to DID

- $Y_{it}(d)$  is the potential outcome under treatment d at time t.
- Again, the individual causal effect is just  $Y_{it}(1) Y_{it}(0)$ .
- Consistency:  $Y_{it} = D_{it}Y_{it}(1) + (1 D_{it})Y_{it}(0)$ 
  - Observe control p.o. for all units in first period:  $Y_{i0}(0) = Y_{i0}$
  - In treated group:  $G_i = 1 \rightsquigarrow Y_{i1} = Y_{i1}(1)$
  - In control group:  $G_i = 0 \rightsquigarrow Y_{i1} = Y_{i1}(0)$

#### **Identification problem**

· Average treatment effect on the treated:

$$\begin{split} \tau_{ATT} &= \mathbb{E}[Y_{i1}(1) - Y_{i1}(0)|G_i = 1] \\ &= \mathbb{E}[Y_{i1}(1)|G_i = 1] - \mathbb{E}[Y_{i1}(0)|G_i = 1] \\ &= \underbrace{\mathbb{E}[Y_{i1}|G_i = 1]}_{\text{(a)}} - \underbrace{\mathbb{E}[Y_{i1}(0)|G_i = 1]}_{\text{(b)}} \end{split}$$

- Part (a) is just a conditional average of observed data → identified.
- Part (b) is a counterfactual: what would the average outcome in the treated group have been if it have been in control?

### **Three control strategies**

#### · Cross-sectional design

· Assumption: mean independence of treatment

$$\mathbb{E}[Y_{i1}(0)|G_i = 1] = \mathbb{E}[Y_{i1}(0)|G_i = 0]$$

· Use post-treatment control group:

$$\tau_{ATT} = \mathbb{E}[Y_{i1}|G_i = 1] - \mathbb{E}[Y_{i1}|G_i = 0]$$

### **Three control strategies**

#### · Before-and-after design

· Assumption: no trends

$$\mathbb{E}[Y_{i1}(0)|G_i=1] = \mathbb{E}[Y_{i0}(0)|G_i=1]$$

· Use pre-period outcome in treated group:

$$\tau_{ATT} = \mathbb{E}[Y_{i1}|G_i = 1] - \mathbb{E}[Y_{i0}|G_i = 1]$$

### **Three control strategies**

#### Difference-in-differences:

· Assumption: parallel trends

$$\mathbb{E}[Y_{i1}(0) - Y_{i0}(0)|G_i = 0] = \mathbb{E}[Y_{i1}(0) - Y_{i0}(0)|G_i = 1]$$

Use pre-period treated outcome plus trend in control group:

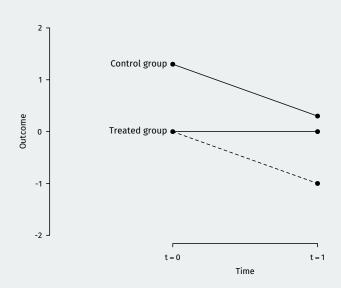
$$\begin{split} \tau_{ATT} = & (\mathbb{E}[Y_{i1}|G_i = 1] - \mathbb{E}[Y_{i0}|G_i = 1]) \\ & - (\mathbb{E}[Y_{i1}|G_i = 0] - \mathbb{E}[Y_{i0}|G_i = 0]) \end{split}$$

#### **Parallel trends**

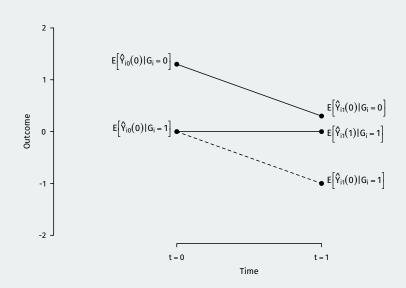
$$\mathbb{E}[Y_{i1}(0) - Y_{i0}(0)|G_i = 0] = \mathbb{E}[Y_{i1}(0) - Y_{i0}(0)|G_i = 1]$$

- · Key assumption of differences-in-differences: parallel trends
- · Interpretation:
  - Secular trend in the control group is a good proxy how the treated group would have changed over time without treatment.
- · Why is this weaker than other assumption?
  - Allows for time-constant unmeasured confounding between  $Y_{it}$  and  $G_i$
  - Allows for (common) secular trends in the outcome over time (unlike FE).
- · Not invariant to nonlinear transformations!
  - Parallel trends for  $Y_{it}$  implies non-parallel trends for  $\log(Y_{it})$  and vice versa.

## Parallel trends in a graph



### Parallel trends in a graph



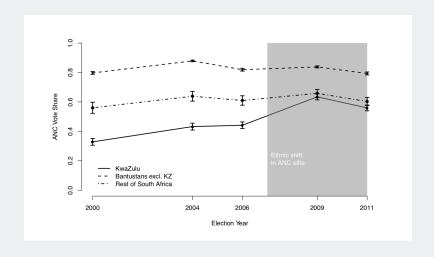
#### Identification

· Identification result:

$$\begin{split} \tau_{ATT} &= (\mathbb{E}[Y_{i1}|G_i = 1] - \mathbb{E}[Y_{i0}|G_i = 1]) \\ &- (\mathbb{E}[Y_{i1}|G_i = 0] - \mathbb{E}[Y_{i0}|G_i = 0]) \end{split}$$

- · Threat to identification: non-parallel trends
  - · unmeasured time-varying confounding
  - Ashenfelter's dip: empirical finding that people who enroll in job training programs see their earnings decline prior to that training.
- Falsification test: check pre-treatment parallel trends.
  - Doesn't imply parallel trends hold for the post-period however!

### Checking parallel trends (de Kadt/Larreguy, 2018)



#### **Estimation**

· Estimation with panel data:

$$\widehat{\tau}_{\text{ATT}} = \underbrace{\frac{1}{n_1} \sum_{i=1}^{n} G_i \left\{ Y_{i1} - Y_{i0} \right\}}_{\text{average trend in treated group}} - \underbrace{\frac{1}{n_0} \sum_{i=1}^{n} (1 - G_i) \left\{ Y_{i1} - Y_{i0} \right\}}_{\text{average trend in the control group}}$$

- Standard errors from standard difference in means.
- · Regression implementation:
  - Regress  $\Delta Y_i = Y_{i1} Y_{i0}$  on  $G_i$ .
  - · Use (cluster) robust SEs
- Also possible to use DID on repeated cross sections.

### **DID and linear two-way fixed effects**

• Linear two-way (group and time) fixed effect model:

$$Y_{it} = \alpha + \gamma G_i + \beta t + \tau D_{it} + \varepsilon_{it}$$

- Fixed effect for group and time.
- Be sure to cluster by unit (or level of treatment assignment)
- Coefficient on  $D_{it}$  equivalent to DID estimation.
- Only holds for the 2 group, 2 period case!
  - Large new literature on interpretation of TWFE in more general cases.
  - Basically, TWFE is an odd weighted average of DID effects with sometimes negative weights.

#### DID vs lagged dependent variable

· Alternative identification assumption:

$$Y_{i1}(0) \perp \!\!\! \perp G_i \mid Y_{i0}$$

- · Doesn't imply and isn't implied by parallel trends.
- · Benefit over parallel trends: it is scale-free.
- Equivalent to parallel trends if  $\mathbb{E}[Y_{i0} \mid G_i = 1] = \mathbb{E}[Y_{i0} \mid G_i = 0]$
- · Different ideas about why there is imbalance on the LDV:
  - · DID: time-constant unmeasured confounder creates imbalance.
  - LDV: previous outcome directly affects treatment assignment.

#### **DID/LDV** bracketing

• Estimator: estimate CEF  $\mathbb{E}[Y_{i1} \mid Y_{i0}, G_i] = \alpha + \rho Y_{i0} + \tau G_i$ 

$$\widehat{\tau}_{LDV} = \underbrace{\frac{1}{n_1} \sum_{i=1}^n G_i Y_{i1} - \frac{1}{n_0} \sum_{i=1}^n (1 - G_i) Y_{i1}}_{\text{difference in post period}} \\ - \widehat{\rho}_{LDV} \underbrace{\left\{ \frac{1}{n_1} \sum_{i=1}^n G_i Y_{i0} - \frac{1}{n_0} \sum_{i=1}^n (1 - G_i) Y_{i0} \right\}}_{\text{difference in pre-period}}$$

- If  $\hat{
  ho}_{LDV}=1$  then  $\widehat{ au}_{DID}=\widehat{ au}_{LDV}$  and if  $0\leq \hat{
  ho}_{LDV}<1$ :
  - If  $G_i=1$  has higher baseline outcomes  $\leadsto \widehat{ au}_{LDV}>\widehat{ au}_{DID}$ .
  - If  $G_i=1$  has lower baseline outcomes  $\leadsto \widehat{ au}_{DID}>\widehat{ au}_{LDV}.$
- Bracketing relationship: if you willing to assume parallel trends or LDV,

$$\mathbb{E}[\widehat{\tau}_{LDV}] \geq \tau_{\mathrm{att}} \geq \mathbb{E}[\widehat{\tau}_{DID}]$$

Holds nonparametrically as well.

### **Nonparametric identification**

- Up until now, we assumed unconditional parallel trends. What if this doesn't hold?
- Alternative identification: conditional parallel trends

$$E[Y_{i1}(0) - Y_{i0}(0) \mid \mathbf{X}_i, G_i = 1] = E[Y_{i1}(0) - Y_{i0}(0) \mid \mathbf{X}_i, G_i = 0]$$

- What does this assumption say? It says that the potential trend under control is the same for the control and treated groups, conditional on covariates.
  - Units that are similar at baseline will follow similar paths under no treatment.
- **Matching**: conduct DID analysis on units with similar values of  $X_i$

### **Semiparametric estimation with repeated outcomes**

- · How to estimate regression DID without strong linearity assumptions?
- Abadie (2005) derives weighting estimators in this setting:

$$\mathbb{E}[Y_{i1}(1) - Y_{i1}(0) \mid G_i = 1] = \mathbb{E}\left[\frac{(Y_{i1} - Y_{i0})}{\mathbb{P}(G_i = 1)} \cdot \frac{G_i - \mathbb{P}(G_i = 1 \mid \mathbf{X}_i)}{1 - \mathbb{P}(G_i = 1 \mid \mathbf{X}_i)}\right]$$

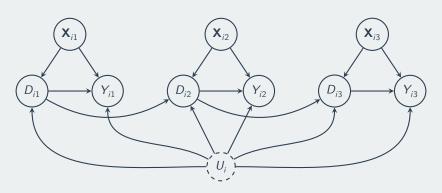
- Reweights control group to have the same distribution of X<sub>i</sub> as treated group.
- Have to estimate the **propensity score**  $\mathbb{P}(G_i = 1 \mid \mathbf{X}_i)$ 
  - · Possible model misspecification!

# 2/ Fixed effects

#### **Basic idea of fixed effects**

- "One way" fixed effects generalizes the before/after design.
  - Arbitrary treatment timing, covariates, etc.
  - Units: i = 1, ..., n
  - Causal ordering with time: covariates  $\mathbf{X}_{it}$ , treatment  $D_{it}$ , outcome  $Y_{it}$
  - History of a variable:  $\overline{D}_{it} = (D_{i1}, \dots, D_{it})$  and  $\overline{D}_i \equiv \overline{D}_{iT}$
- Linear fixed effects model:  $Y_{it} = \alpha_i + \tau D_{it} + \mathbf{X}_i' \boldsymbol{\beta} + \varepsilon_{it}$ 
  - Key assumption: **strict exogeneity**  $\mathbb{E}[\varepsilon_{it} \mid \overline{\mathbf{X}}_i, \overline{D}_i, \alpha_i] = 0$
  - Implies **no feedback** between outcome and treatment  $(Y_{it} \nrightarrow D_{i,t+1})$
  - → LDV cannot be a confounder!
  - Imai and Kim (2019, AJPS) give clarification on these identification issues.
- Implicit assumption of **no carryover**?  $Y_{it}(d_1, ..., d_t) = Y_{it}(d_t)$ 
  - More a choice of estimand: focuses on contemporaneous effect.
  - Treatment history follows observed path through t-1:  $Y_{it}(d_t) = Y_{it}(D_{i1}, \dots, D_{i-t-1}, d_t)$
  - $\rightsquigarrow$  lags of treatments become part of time-varying confounders.

### **Strict exogeneity DAG**



Strict exogeneity implied by strict ignorability  $Y_{it}(d) \perp \!\!\! \perp \overline{D}_i \mid \overline{X}_i, U_i$ 

#### **FE** estimation

- With linear models, two transformations can purge the fixed effects.
- Within/FE transformation:  $\ddot{Z}_{it} = Z_{it} T^{-1} \sum_{s=1}^{T} Z_{is}$

$$\ddot{Y}_{it} = \ddot{X}'_{it}\beta + \tau \ddot{D}_{it} + \ddot{\varepsilon}_{it}$$

- Time-demeaning  $Y_{it}$  purges the time constant fixed effect.
- But they retain the same coefficients as the original model.
- First differences:  $\Delta Z_{it} = Z_{it} Z_{i,t-1}$

$$\Delta Y_{it} = \Delta \mathbf{X}_{it}' \boldsymbol{\beta} + \tau \Delta D_{it} + \Delta \varepsilon_{it}$$

- Estimation: pooled OLS of either specification,  $\widehat{\tau}_{\rm fe}, \widehat{\tau}_{\rm fd}$ 
  - · Both consistent under strict exogeneity.
  - FE more efficient if original errors,  $\varepsilon_{it}$ , are serially uncorrelated.
  - FD more efficient if differences,  $\Delta \varepsilon_{it}$ , are serially uncorrelated.
  - Latter allows for substantial serial dependence in the original errors.

#### **Estimation notes**

• Within estimator can be implemented by adding unit dummy variables.

$$\operatorname*{arg\,max}_{\alpha,\beta,\tau,\gamma} \sum_{i=1}^{n} \sum_{t=1}^{T} \left( Y_{it} - \alpha - \mathbf{X}_{it}'\beta - \tau D_{it} - \sum_{k=2}^{n} \gamma_{k} \mathbb{1}(i=k) \right)^{2}$$

- Least squares dummy variable estimator reasonable for moderate n
- Computationally inefficient for large n (number of dummies grows with n)
- Best practice: cluster variances at the unit level.
  - · With CR variance estimators, LSDV "double counts" degrees of freedom
  - · Better to use within estimator in that case.
- · Best choice: use canned packages.
  - {fixest} in R, -reghdfe- in Stata

#### Non-constant treatment effects

- LFE models assume constant treatment effects. What happens if not?
  - OLS typically biased because nonconstant effects induce correlation between treatment and error.
- With no covariates and no only treated/control units:

$$\widehat{\tau}_{\mathsf{fe}} \overset{p}{\to} \frac{\mathbb{E}\left[\left(\frac{\sum_{t} D_{it} Y_{it}}{\sum_{t} D_{it}} - \frac{\sum_{t} (1 - D_{it}) Y_{it}}{\sum_{t} (1 - D_{it})}\right) S_{i}^{2}\right]}{\mathbb{E}[S_{i}^{2}]} \neq \tau$$

- $S_i^2$  is the within-unit treatment variance.
- Units with even treatment/control split upweighted.
- Imai, Kim & Wang (2019, AJPS): use a matching to target the ATE.
  - · Match treated and control periods within units (also weakens linearity).
  - {PanelMatch} R package.

### Strict vs. sequential exogeneity/ignorability

- Strict exogeneity/ignorability is very strong.
  - · Remember: rules out all outcome-treatment feedback.
- · Weaker assumption: Sequential ignorability:

$$Y_{it}(d) \perp \!\!\! \perp D_{it} \mid \overline{\mathbf{X}}_{it}, \overline{D}_{i,t-1}, \alpha_i$$

- Allow  $Y_{it}$  to be related to future  $D_{i,t+s}$
- This implies sequential exogeneity of the errors:  $\mathbb{E}[\varepsilon_{it} \mid \overline{\mathbf{X}}_{it}, \overline{D}_{it}, \alpha_i] = 0$ .
- Estimation to these dynamic panel models:
  - instrumental variables (Arellano and Bond) using lagged difference and levels as instruments (only valid for linear models).
  - bias correction: estimate the bias and subtract it off (valid for nonlinear models too).

#### **Effect of lagged treatments**

- Focused on the contemporaneous effect of  $D_{it}$ .
- What about treatment histories  $Y_{it}(d_{t-1}, d_t)$ ?
- Very difficult, if not impossible with fixed effects models.
  - · Complicated by the effect of treatment on time-varying confounders.
  - Pathways involving  $\mathbf{X}_{it}(d_{t-1})$  difficult to identify.
- Possible approach: propensity score FEs (Blackwell & Yamauchi, 2021)
  - · Include unit dummies in propensity score model.
  - Bias from incidental parameters, but disappears as  $T o \infty$