

Section 5

Observational Studies 1

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Overview

- Logistics:
 - **No pset this week!**
- Today's topics:
 1. Review session
 2. No unmeasured confounding + regression

What we learned so far

- Fisher's approach to inference: randomization inference
- Neyman's approach to inference for the ATE: diff-in-means estimator
- Analyzing experiments with regression
 - Simple OLS estimator + robust variance estimator
 - + Covariates
 - + Block design
 - + Cluster design
- This week: observational studies
 - Before we move on, let's quickly review experimental designs!

Experimental design

- Types of experiments by their assignment mechanism
 - **Bernoulli randomization:** Each unit is assigned $D_i = 1$ with prob. p independently (coin flips)
 - **Completely randomized experiment:** Randomly sample n_1 units from the population to be treated
 - **Block/stratified randomized experiment:** Completely randomized experiment in each block \leadsto always efficient for PATE
 - **Cluster randomized experiment:** Treatment assignment at a higher level \leadsto allows for interference within clusters
- Exercise: comparing experimental designs through simulation
 1. Assume true potential outcomes
 2. Select one assignment mechanism
 3. Randomly generate treatment assignment
 4. Estimate SATE (using diff-in-means estimator)
 5. Repeat 3-4 multiple times
 6. Draw a distribution of estimates

Experimental design

- Setup:

- $SATE = \frac{1}{16} \sum_{i=1}^{16} \tau_i = 8.5$
- Design is balanced (except for Bernoulli)

Unit	$Y_i(0)$	$Y_i(1)$	τ_i	Block/Cluster
1	0	1	1	A
2	0	2	2	A
3	0	3	3	A
4	0	4	4	A
5	0	5	5	B
\vdots	\vdots	\vdots	\vdots	\vdots
16	0	16	16	D

- Q: Which design would have the largest (smallest) variance?
- Check the results here

Observational studies

- Problem:
 - Non-randomized treatment
 - $\leadsto \{Y_i(1), Y_i(0)\} \not\perp D_i$
 - \leadsto selection bias = unidentified ATT

$$\underbrace{\mathbb{E}[Y_i|D_i = 1] - \mathbb{E}[Y_i|D_i = 0]}_{\text{diff-in-means}} = \underbrace{\tau_t}_{\text{ATT}} + \underbrace{\mathbb{E}[Y_i(0)|D_i = 1] - \mathbb{E}[Y_i(0)|D_i = 0]}_{\text{selection bias}}$$

- What can we do for the **identification**?
 - Assume no unmeasured confounding with positivity
 - Partial identification: analysis of bounds for the ATE
 - Sensitivity analysis ...

Identification: No unmeasured confounding

- Identification
 - Let's begin with most common set of assumptions:
 1. **Overlap/Positivity:** $0 < \Pr[D_i = 1 | \mathbf{X}_i] < 1$
 2. **No unmeasured confounding:** $\{Y_i(1), Y_i(0)\} \perp\!\!\!\perp D_i \mid \mathbf{X}_i$
 - This will identify the PATE:

$$\begin{aligned}\tau &= \mathbb{E}[Y_i(1) - Y_i(0)] \\&= \mathbb{E}_{\mathbf{X}} \{E[Y_i(1) - Y_i(0) \mid \mathbf{X}_i]\} \\&= \mathbb{E}_{\mathbf{X}} \{E[Y_i(1) \mid \mathbf{X}_i] - E[Y_i(0) \mid \mathbf{X}_i]\} \\&= \mathbb{E}_{\mathbf{X}} \{E[Y_i(1) \mid D_i = 1, \mathbf{X}_i] - E[Y_i(0) \mid D_i = 0, \mathbf{X}_i]\} \\&= \mathbb{E}_{\mathbf{X}} \{E[Y_i \mid D_i = 1, \mathbf{X}_i] - E[Y_i \mid D_i = 0, \mathbf{X}_i]\}\end{aligned}$$

- Estimation
 - Regression
 - Matching/Weighting (Module 7)

Estimation: Regression-based estimators

- Treated and control conditional expectation functions (CEFs):

$$\mu_1(\mathbf{x}) = \mathbb{E}[Y_i(1) \mid \mathbf{X}_i = \mathbf{x}], \quad \mu_0(\mathbf{x}) = \mathbb{E}[Y_i(0) \mid \mathbf{X}_i = \mathbf{x}]$$

- By consistency and no unmeasured confounding:

$$\underbrace{\mu_1(\mathbf{x})}_{\text{counterfactual}} = \underbrace{\mathbb{E}[Y_i \mid D_i = 1, \mathbf{X}_i = \mathbf{x}]}_{\text{observational}}, \quad \mu_0(\mathbf{x}) = \mathbb{E}[Y_i \mid D_i = 0, \mathbf{X}_i = \mathbf{x}]$$

- Estimate CEFs using regression estimators $\hat{\mu}_1(\mathbf{x})$ and $\hat{\mu}_0(\mathbf{x})$.
 - Might be linear or nonlinear models (e.g., GAMs)
 - \leadsto Regression estimator of the ATE:

$$\hat{\tau}_{\text{reg}} = \frac{1}{n} \sum_{i=1}^n \hat{\mu}_1(\mathbf{X}_i) - \hat{\mu}_0(\mathbf{X}_i)$$

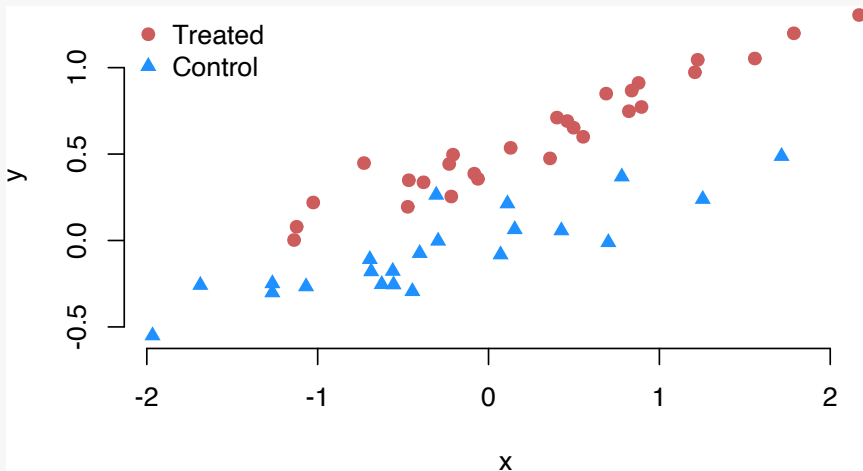
Estimation: Regression-based estimators

$$\widehat{\tau}_{\text{reg}} = \frac{1}{n} \sum_{i=1}^n \widehat{\mu}_1(\mathbf{X}_i) - \widehat{\mu}_0(\mathbf{X}_i)$$

- General procedure:
 - Obtain predicted values for all units when $D_i = 1$.
 - Obtain predicted values for all units when $D_i = 0$.
 - Take the average difference between these predicted values.
- Safest practice:
 - Estimate separate regression in each treatment group.
 - Sometimes called an imputation estimator.
 - Procedure:
 - Regress Y_i on X_i in the treatment group and get predicted values for all units (treated or control).
 - Regress Y_i on X_i in the control group and get predicted values for all units (treated or control).
 - Take the average difference between these predicted values.

Toy example

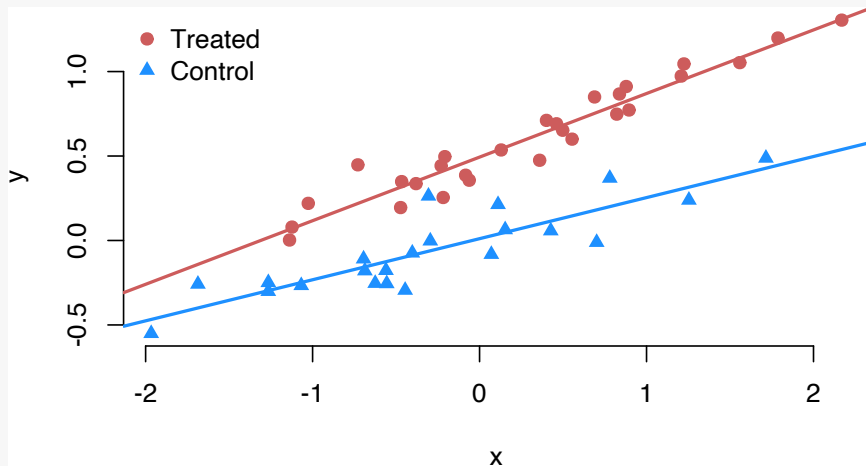
- Data is as follows and we will use linear regression to estimate CEFs



Imputation estimator visualization

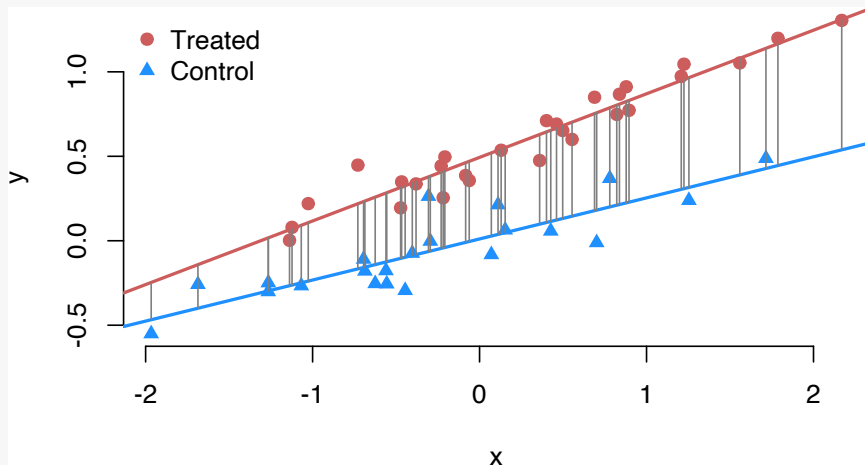
```
mod0 <- lm(y~x, data = toy_data, subset = d==0)
```

```
mod1 <- lm(y~x, data = toy_data, subset = d==1)
```



```
mu0.imps = predict(mod0, toy_data); mu1.imps = predict(mod1, toy_data)
cat("Estimate of ATE:", mean(mu1.imps - mu0.imps))
```

```
## Estimate of ATE: 0.4873975
```



Fully interacted OLS visualization

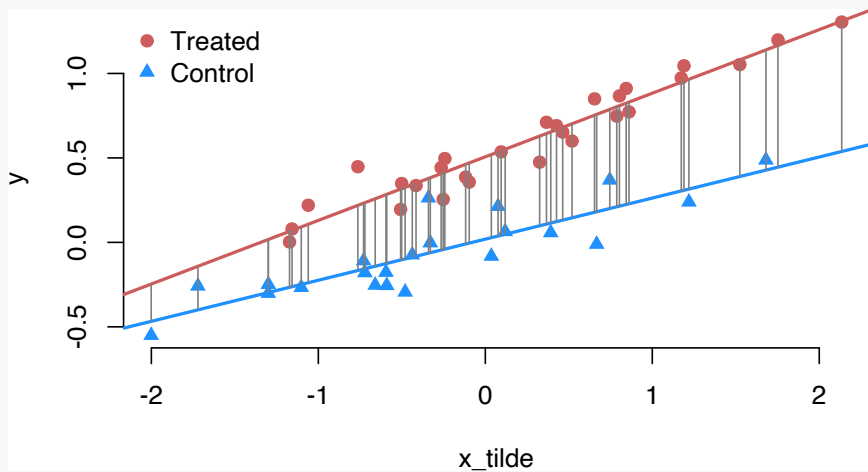
- What if $\hat{\mu}_1(\mathbf{x})$ and $\hat{\mu}_0(\mathbf{x})$ are from fully interacted OLS with centered covariates?
 - Equivalent to running separate models for $\hat{\mu}_1(\mathbf{x})$ and $\hat{\mu}_0(\mathbf{x})$
 - $\hat{\tau}_{\text{reg}} \equiv$ estimated coefficient on D_i
 - Recall: Under linear models, $\hat{\tau}_{\text{reg}}$ is **sometimes** equivalent to a coefficient.

```
toy_data$x_tilde <- toy_data$x - mean(toy_data$x)
mod_full <- lm(y~d+x_tilde+d*x_tilde, data = toy_data)
dat0 <- toy_data %>% mutate(d = 0); dat1 <- toy_data %>% mutate(d = 1)
mu0.full = predict(mod_full, dat0); mu1.full = predict(mod_full, dat1)
cat("Estimate of ATE (Fully interacted):", mean(mu1.full - mu0.full),
    "\nEstimate of ATE (Imputation):", mean(mu1.imps - mu0.imps),
    "\nEstimated coefficient on Di", mod_full$coefficients["d"])
```

```
## Estimate of ATE (Fully interacted): 0.4873975
```

```
## Estimate of ATE (Imputation): 0.4873975
```

```
## Estimated coefficient on Di 0.4873975
```

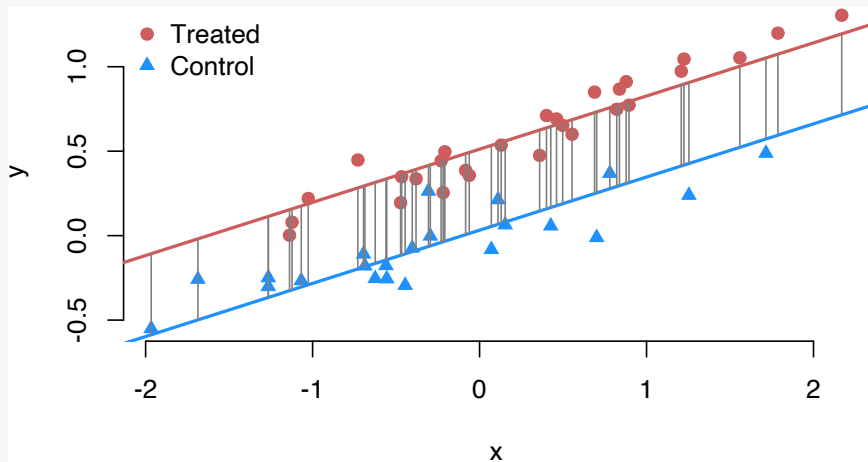


Uninteracted OLS visualization

- What if $\hat{\mu}_1(\mathbf{x})$ and $\hat{\mu}_0(\mathbf{x})$ are from the same OLS model $Y \sim D + X$?
 - $\hat{\tau}_{\text{reg}} \equiv$ estimated coefficient on D_i

```
mod <- lm(y~d+x, data = toy_data)
mu0 = predict(mod, dat0); mu1 = predict(mod, dat1)
cat("Estimate of ATE (Uninteracted):", mean(mu1 - mu0),
    "\nEstimated coefficient on Di", mod$coefficients["d"],
    "\nEstimate of ATE (Fully interacted):", mean(mu1.full - mu0.full),
    "\nEstimate of ATE (Imputation):", mean(mu1.imps - mu0.imps))

## Estimate of ATE (Uninteracted): 0.479676
## Estimated coefficient on Di 0.479676
## Estimate of ATE (Fully interacted): 0.4873975
## Estimate of ATE (Imputation): 0.4873975
```



Variance estimation

- How do we get estimates of the variance of $\hat{\tau}_{\text{reg}}$?
- **Nonparametric bootstrap**
 - Recall: Source of variance is due to **sampling**
 - Idea: View sample (data) as “population” → in-sample “sampling”
- Procedure:
 - Randomly resample n rows of the data with replacement
 - Refit the regressions on the bootstrapped data.
 - Calculate $\hat{\tau}_{\text{reg}}$ in each bootstrap
 - Repeat several times and use empirical variance of the bootstraps

Bootstrap sample codes

```
set.seed(02138); sims<-500; tau_hat_draws<-rep(NA, sims)
for (i in 1:sims) { # Repeat the following several times
  # 1. Randomly resample n rows of the data with replacement
  sample_boot <- dplyr::slice_sample(toy_data, n = nrow(toy_data),
                                     replace = TRUE)

  # 2. Refit the regressions on the bootstrapped data
  model <- lm(y ~ d + x_tilde + d*x_tilde, data = toy_data)
  dat1 <- sample_boot; dat1$d <- 1
  dat0 <- sample_boot; dat0$d <- 0
  mu1_hat <- predict(model, newdata = dat1)
  mu0_hat <- predict(model, newdata = dat0)
  # 3. Calculate tau_hat in each bootstrap
  tau_hat_draws[i] <- mean(mu1_hat - mu0_hat)
}

# 4. Use empirical variance of the bootstraps
var(tau_hat_draws)

## [1] 0.0003247686
```

DAG

- How do we know if no unmeasured confounders holds?
 - One way: use DAGs and look at back-door paths.
- **D-separation**
 - Can we determine conditional independence from our causal DAG?
 - Yes! To verify that $A \perp\!\!\!\perp B \mid C$ where each is a set of nodes:
 1. Find all paths between A and B .
 2. Check if each path is **blocked**.
 3. If all paths are blocked, then A is **d-separated** from B by C
- Ways to block $A \rightarrow B$ (each is a node):
 1. $A \rightarrow C \rightarrow B$, C is observed (conditioned)
 2. $A \leftarrow C \leftarrow B$, C is observed
 3. $A \rightarrow C \rightarrow B$, C is observed
 4. $A \rightarrow C \leftarrow B$, C is **not** observed
 - If C observed \leadsto collider bias
 - e.g., A =bicycle accident, B =stomachache, C =hospitalization; Sackett (1979)