pgd

May 16, 2022

```
[1]: # import necessary dependencies
     import torch
     import torch.nn as nn
     import torch.optim as optim
     import torch.nn.functional as F
     import torch.backends.cudnn as cudnn
     from torch.autograd import *
     import torchvision
     import torchvision.transforms as transforms
     import matplotlib.pyplot as plt
     import numpy as np
     from resnet import *
     import pickle
     import datetime
[2]: # select GPU if available, else CPU
     device = 'cuda' if torch.cuda.is_available() else 'cpu'
[3]: # define transformations on training set and testing set
     transform_train = transforms.Compose([
         transforms.RandomCrop(32, padding=4),
         transforms.RandomHorizontalFlip(),
         transforms.ToTensor(),
         # CIFAR-10 normalization, check: https://stackoverflow.com/questions/
      \hookrightarrow 50710493/cifar-10-meaningless-normalization-values
         transforms.Normalize((0.4914, 0.4822, 0.4465), (0.2023, 0.1994, 0.2010)),
     ])
     transform_test = transforms.Compose([
         transforms.ToTensor(),
         transforms.Normalize((0.4914, 0.4822, 0.4465), (0.2023, 0.1994, 0.2010)),
     ])
[4]: | # get CIFAR-10 dataset and prepare train and test loaders
     trainset = torchvision.datasets.CIFAR10(root='./data', train=True, ___

→download=True, transform=transform_train)
```

Files already downloaded and verified Files already downloaded and verified

```
[5]: # classes of CIFAR-10, in order classes = ('airplane', 'automobile', 'bird', 'cat', 'deer', 'dog', 'frog', □ → 'horse', 'ship', 'truck')
```

```
[7]: # training function
     def train(epoch, net):
         111
         this function trains network on training dataset
         # set network to training mode
         net.train()
         train_loss = 0
         correct = 0
         total = 0
         for batch_idx, (inputs, targets) in enumerate(trainloader):
             # move data to device - GPU or CPU, as available
             inputs, targets = inputs.to(device), targets.to(device)
             # zero the parameter gradients
             optimizer.zero_grad()
             # forward + backward + optimize
             outputs = net(inputs)
             loss = criterion(outputs, targets)
             loss.backward()
             optimizer.step()
             # calculate training loss
             train_loss += loss.item()
             # the class with the highest energy is what we choose as prediction
             _, predicted = outputs.max(1)
             total += targets.size(0)
             correct += predicted.eq(targets).sum().item()
```

return train_loss/len(trainloader)

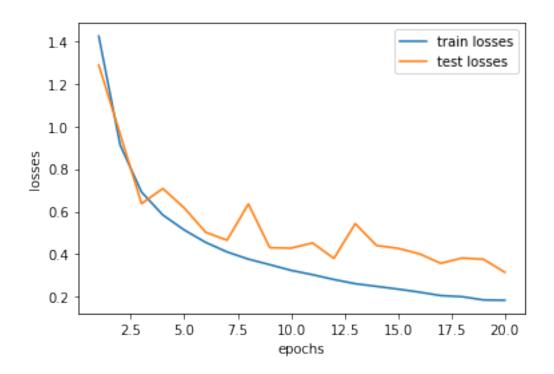
```
[6]: # testing function
     # reference: https://pytorch.org/tutorials/beginner/blitz/cifar10_tutorial.html?
      \hookrightarrow highlight = cifar
     def test(epoch, net):
         this function evaluates network on testing dataset
         # set variable for global access
         global acc
         # set network to testing mode
         net.eval()
         test_loss = 0
         correct = 0
         total = 0
         with torch.no_grad():
             for batch_idx, (inputs, targets) in enumerate(testloader):
                 inputs, targets = inputs.to(device), targets.to(device)
                 outputs = net(inputs)
                 loss = criterion(outputs, targets)
                 test_loss += loss.item()
                 _, predicted = outputs.max(1)
                 total += targets.size(0)
                 correct += predicted.eq(targets).sum().item()
         acc = 100 * correct / total
         return test_loss/len(testloader)
```

```
[8]: # build ResNet-18 model
net = ResNet18()
net = net.to(device)
# setup for data parallel operations
if device == 'cuda':
    net = torch.nn.DataParallel(net)
    cudnn.benchmark = True

# initialize loss function, optimizer and LR scheduler
lr = 0.01
criterion = nn.CrossEntropyLoss()
optimizer = optim.SGD(net.parameters(), lr=lr, momentum=0.9, weight_decay=5e-4)
```

```
scheduler = torch.optim.lr_scheduler.CosineAnnealingLR(optimizer, T_max=200)
 [9]: # train and evaluate naive network
      train losses=[]
      test_losses=[]
      epochs=20
      # get a sense of execution time
      print(datetime.datetime.now())
      # run through number of epochs
      for epoch in range(0, epochs):
          train_losses.append(train(epoch, net))
          test_losses.append(test(epoch, net))
          scheduler.step()
      print(datetime.datetime.now())
     2022-05-16 14:35:49.423222
     2022-05-16 14:45:09.193354
[10]: print(f"Accuracy of the naive network on test images: {acc} %")
     Accuracy of the naive network on test images: 90.01 %
[11]: | # plot train and test loss of naive network on CIFAR-10 images
      epochs = 20
      plt.plot(np.arange(1,epochs+1), train_losses, label='train losses')
      plt.plot(np.arange(1,epochs+1), test_losses, label='test losses')
      plt.xlabel('epochs')
      plt.ylabel('losses')
      plt.legend()
```

plt.show()



0.0.1 PGD attack function

In the PGD attack, we repeat $\delta := \mathcal{P}(\delta + \alpha \nabla_{\delta} L(\theta, x, y))$ for t iterations.

```
[12]: def PGD(net,x,y,alpha,epsilon,iter):
           111
          inputs:
               net: the network through which we pass the inputs
               x: the original example which we aim to perturb to make an adversarial \sqcup
       \hookrightarrow example
               y: the true label of x
               alpha: step size
               epsilon: perturbation limit
               iter: number of iterations in the PGD algorithm
          outputs:
               x\_adv : the adversarial example constructed from x
               h_adv: output of softmax when applying net on x_adv
               y\_adv: predicted label for x\_adv
              pert: perturbation applied to x (x_adv - x)
          delta = torch.zeros_like(x, requires_grad=True)
          for i in range(iter):
```

```
criterion = nn.CrossEntropyLoss()
    loss = criterion(net(x + delta), y)
    loss.backward()
    delta.data = (delta + x.shape[0]*alpha*delta.grad.data).clamp(-epsilon,u
epsilon)
    delta.grad.zero_()

pert = delta.detach()
    x_adv = x + pert
    h_adv = net(x_adv)
    _, y_adv = torch.max(h_adv.data, 1)

return x_adv, h_adv, y_adv, pert
```

Adversarial training with PGD

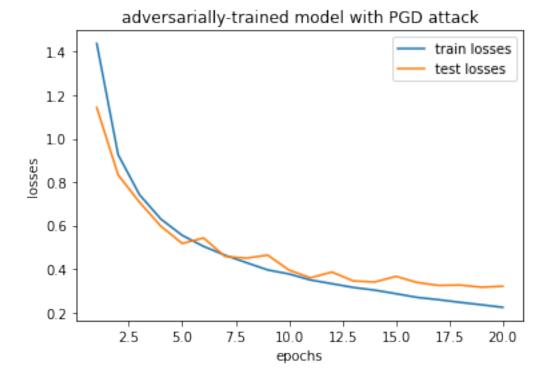
```
[13]: net_pgd = ResNet18()
    net_pgd = net_pgd.to(device)
    if device == 'cuda':
        net_pgd = torch.nn.DataParallel(net_pgd)
        cudnn.benchmark = True

criterion = nn.CrossEntropyLoss()
    optimizer_pgd = optim.SGD(net_pgd.parameters(), lr=lr, momentum=0.9, useight_decay=5e-4)
    scheduler_pgd = torch.optim.lr_scheduler.CosineAnnealingLR(optimizer_pgd, useT_max=200)
```

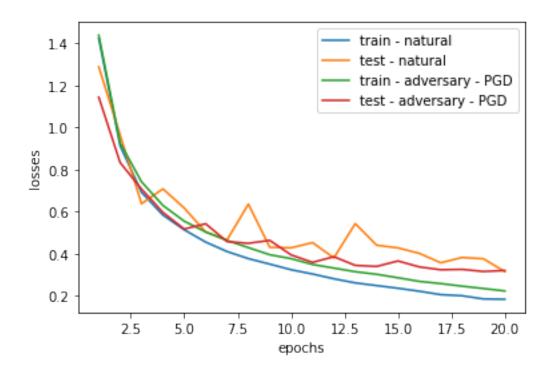
```
loss.backward()
              optimizer_pgd.step()
              train_loss += loss.item()
              _, predicted = outputs.max(1)
              total += targets.size(0)
              correct += predicted.eq(targets).sum().item()
          return train_loss/len(trainloader)
[15]: | # train and evaluate adversarially-trained network on unperturbed images
      train_losses_pgd = []
      test_losses_pgd = []
      epochs = 20
      alpha = 3.0/255
      epsilon = 8.0/255
      iter = 3
      print(datetime.datetime.now())
      for epoch in range(0, epochs):
          train_losses_pgd.append(train_pgd(epoch, net_pgd, alpha, epsilon, iter))
          test_losses_pgd.append(test(epoch, net_pgd))
          scheduler_pgd.step()
      print(datetime.datetime.now())
     2022-05-16 14:48:42.830294
     2022-05-16 15:23:55.786987
[16]: print(f"Accuracy of the adversarially-trained network on unperturbed test
       →images: {acc} %")
     Accuracy of the adversarially-trained network on unperturbed test images: 89.07
     %
 []: torch.save(net_pgd, "pgd.pth")
[17]: # plot losses
      epochs = 20
      plt.plot(np.arange(1,epochs+1), train_losses_pgd, label='train losses')
      plt.plot(np.arange(1,epochs+1), test_losses_pgd, label='test_losses')
      plt.xlabel('epochs')
      plt.ylabel('losses')
      plt.title('adversarially-trained model with PGD attack')
```

plt.legend()





```
[18]: # comparing plots
      # train - natural: training loss of the naturally-trained model
      # test - natural: loss of the naturally-trained model on original (unperturbed)_{\sqcup}
       ⇔test images
      # train - adversary - PGD: training loss of the adversarially-trained model (on_
       ⇔examples generated with PGD)
      # test - adversary - PGD: loss of the adversarially-trained model on original
       → (unperturbed) test images
      epochs = 20
      plt.plot(np.arange(1,epochs+1), train_losses, label='train - natural')
      plt.plot(np.arange(1,epochs+1), test_losses, label='test - natural')
      plt.plot(np.arange(1,epochs+1), train_losses_pgd, label='train - adversary -__
       ⇔PGD')
      plt.plot(np.arange(1,epochs+1), test_losses_pgd, label='test - adversary - PGD')
      plt.xlabel('epochs')
      plt.ylabel('losses')
      plt.legend()
      plt.show()
```



```
[19]: # Evaluating the PGD adversarially-trained model against PGD attack on test data
      # test_PGD() constructs adversarial examples from test data (with PGD using_
       →net) and evaluates net_pgd on them.
      def test_PGD(net, net_pgd, alpha, eps, iter):
          acc = 0
          net.train()
          net_pgd.eval()
          test loss = 0
          correct = 0
          total = 0
          for batch_idx, (inputs, targets) in enumerate(testloader):
              inputs, targets = inputs.to(device), targets.to(device)
              x_adv, _, _, = PGD(net, inputs, targets, alpha, eps, iter)
              with torch.no_grad():
                  outputs = net_pgd(x_adv)
                  loss = criterion(outputs, targets)
                  test_loss += loss.item()
                  _, predicted = outputs.max(1)
                  total += targets.size(0)
```

!apt-get -y update & DEBIAN_FRONTEND=noninteractive apt-get install -y_

→texlive-xetex texlive-fonts-recommended texlive-plain-generic

!apt-get -y install pandoc