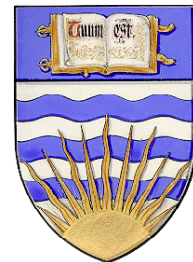




# Transition Logic

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# Idea of Logic

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- Knowledge state:  $KB \wedge K_0 \models_{\text{cog}} K_i$
- $\models_{\text{cog}}$  formally describable by  $\models$
- $\models$  studied for 2000+ years
- relationship of  $\models_{\text{cog}}$  and  $\models$  studied scientifically only for a few decades in CogSci (before through introspection and commonsense psychology)



# Dimensions of Logic Space

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- Structural explorations in a given logic
  - theorem proving, proof theory, semantics
- Problems of representation in a logic
  - eg. how to represent change in FOL
- Design of a logic for modelling cognitive phenomena
  - find  $\models$  modelling cognitive logical knowledge relations (eg. including change)



# Knowledge Processing

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- . . . for agent in an environment
- Representation for fast retrieval
- Exploiting logical relations
  - static aspect for knowledge compression
- Dynamics of knowledge state
  - dynamic aspect (need for compression)
- Both aspects fundamental for reasoning
  - eg. in planning, explanation, diagnosis etc.



# What Is a Logic?

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- A formal language for representation +
- a relationship  $\models$  :  $KB \wedge K_0 \models K_i$
- Enables reduction of KB (compression)
- But what if KB changes to  $KB'$ ?
- Natural reasoning suggests:
  - „  $KB \wedge K_0 \wedge t_0 \models K_i$  “
- Our solution:  $KB \wedge K_0 \models_{t_0} K_i$ 
  - solves compression and frame problem

# Natural Reasoning Under Changes

- Example: purse with credit card in pants pocket; put on pants at home; go to restaurant: credit card with me?
- Formally *static*:  $\text{in}(\text{cc}, \text{purse});$   
 $\text{in}(\text{purse}, \text{pants}); \text{loc}(\text{me}, \text{athome});$   
 $\text{loc}(\text{pants}, \text{athome}); \text{in}(x, y) \wedge \text{loc}(y, z) \rightarrow \text{loc}(x, z);$   
*transitions*:  $\text{loc}(\text{me}, x) \wedge \text{loc}(\text{pants}, x) \Rightarrow$   
 $\text{loc}(\text{me}, x) \wedge \text{loc}(\text{pants}, x) \wedge \text{in}(\text{pants}, \text{me});$   
 $\text{loc}(\text{me}, \text{athome}) \Rightarrow \text{loc}(\text{me}, \text{rest});$   
 $\text{loc}(\text{cc}, \text{rest})?$



# A Simple Didactic Example $E_1$

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- $U, U \rightarrow F \vdash F \ / \ H, H \rightarrow A \vdash A \ / \ D, D \rightarrow O \vdash O$ 
  - U: block is uncovered
  - F: block is free
  - H: hand holds block
  - A: block is airborne
  - D: block is put down
  - O: block is on table
- $U, U \rightarrow F$  is short for  $U \wedge (U \rightarrow F)$



# Transitional Problems

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- A *transition* is a pair  $(E, F)$  of conjunctions of atoms
- A *transitional problem*  $(W, T, I, G)$ 
  - $W$ : world knowledge (definite nonrec. cls.)
  - $T$ : set of transitions
  - $I$ : initial state (set of atoms)
  - $G$ : goal state (set of atoms)(finite sets; set, conjunction interchangeable)





# Source informally

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- $\sigma(F) = \{\{U\}\}$  in example
- for  $U_1 \wedge U_2 \rightarrow F$ ,  $\sigma(F) = \{\{U_1\}, \{U_2\}\}$ 
  - $U_1$  musty,  $U_2$  lack of oxygen,  $F$  stuffy
- for  $U_1 \rightarrow F$ ,  $U_2 \rightarrow F$ , ie.  $U_1 \vee U_2 \rightarrow F$ ,  
 $\sigma(F) = \{\{U_1, U_2\}\}$
- disjunction of conjunctions of ...
- nf: normal form, ie. nesting depth is 2
- $\text{subs}\{S_1, S_2\} = S_i$  if  $S_i \subseteq S_j$  else identical



# Source Definition

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- For  $W$ ,  $I$ , and  
atom  $A$  (without restricting generality):
- $\sigma(A) = \{\{A\}\}$  if  $A \in I$
- $\sigma(A) = \text{subs} [ \text{nf} \{ \{ \sigma(B_{1j_1}), \dots, \sigma(B_{nj_n}) \} \mid 1 \leq j_1 \leq m_1, \dots, 1 \leq j_n \leq m_n \} ]$  if  
 $B_{11} \wedge \dots \wedge B_{1m_1} \vee \dots \vee B_{n1} \wedge \dots \wedge B_{nm_n} \rightarrow A$
- $\sigma(A) = \perp$  else



# Illustration of Definition

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- Recursive replacement of atoms by defining bodies, form dual formula, transform to DNF, remove subsumed clauses, interpret as set of sets of atoms
- Semantically,  $\sigma(A)$  is set of minimal sets  $M$ :  $\neg M$  does no more entail  $A$  under  $W$
- $U_1 \wedge U_2 \rightarrow F$ :  $\sigma(F) = \text{subs}[\text{nf}\{\{\sigma(U_1)\}, \{\sigma(U_2)\}\}] = \text{subs}[\text{nf}\{\{\{\{U_1\}\}\}, \{\{\{U_2\}\}\}\}] = \{\{U_1\}, \{U_2\}\}$
- $U_1 \vee U_2 \rightarrow F$ :  $\sigma(F) = \text{subs}[\text{nf}\{\{\sigma(U_1), \sigma(U_2)\}\}] = \text{subs}[\text{nf}\{\{\{\{U_1\}\}, \{\{U_2\}\}\}\}] = \{\{U_1, U_2\}\}$



# Inference Relation

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- For  $s = \{S_1, \dots, S_m\}$  and  $t = (\{P, D\}, \{P, A\})$ :  
$$s' = \bigcup_{i=1}^m \{(S_i \setminus D') \cup A \mid D' \in \sigma(D)\}$$
- $S = S_1 \vee \dots \vee S_m$  state set formula,  
whereby  $S_i$  conjunction of atoms in it
- Inductive definition of  $\vdash_{T^n}$  for *sequences*
  - $\vdash_{()} = \vdash_{T^0} = \vdash$
  - step  $n-1$  to  $n$  :  $W, I \vdash_{(t_1, \dots, t_m)} F$  iff  $W, S' \vdash F$



# Deductions Modulo Transitions

- $W_1, U \vdash_{(t_1, t_2)} O$  in example  $E_1$
- $E_2$  like  $E_1$  but additional  $t_3 = U \Rightarrow H$  :  
 $W_1, U \vdash_{(t_3, t_2)} O$  , ie. inference absorbable by additional transitions (STRIPS)
- Similar for *sets* of transitions: resulting plans (transitions) are partially ordered
- General case:  $\vdash_{(T, \leq)}$  for partial order  $\leq$  on set  $T$



# Lifting to FOL

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- $C(x) \wedge O(x, y) \wedge C(z) \Rightarrow C(x) \wedge O(x, z) \wedge C(y)$
- $I = \{U(b), \exists y O(b, y), C(c)\}$
- $W = \{U(x) \rightarrow C(x), \dots\}$
- Variables in transitions treated as parameters, recursion and negation by stratification
- Generalization to more general formulas is harder, left open for future research



# Historical Background

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- Leibniz conceived „possible worlds“
- Wittgenstein's „state of affairs“
- Carnap's „state descriptions“ (1946)
- Kripke's semantics for modal logic (1959ff)
- but modal logic studies global truths
  - quasi top-down (instead of bottom-up)
- and originated with different intuition



# Recent History

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- STRIPS 1971
  - classical deduction was never clarified and is not contained in modern systems
  - Thiébaux et al. 2003 (FF planner) introduced  $\vdash$  within states with exponential gains but not beyond transitions as here
  - TL shares Lifschitz' semantics with STRIPS
- linear connection method 1986, linear logic 1987, transition logic 1998



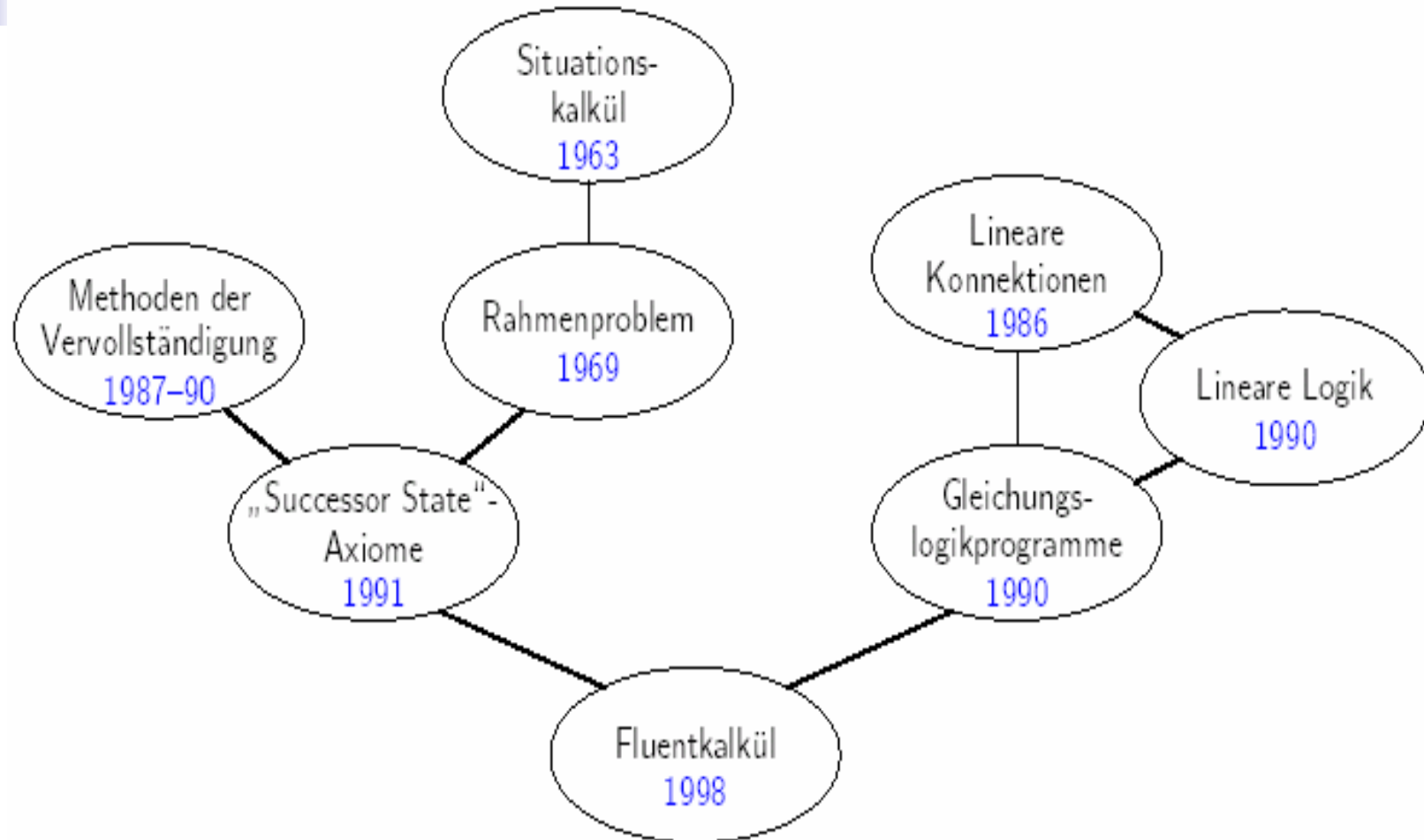


# Recent History ctd.

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- Situation calculus 1963
  - extra situation parameter
  - suffers from inferential frame problem
- Fluent calculus with language FLUX
  - like TL and its predecessors solves inferential frame problem
  - transitions on term level;  $\vdash$  not considered
- Modal approaches, active logics etc.

# A Partial History Tree



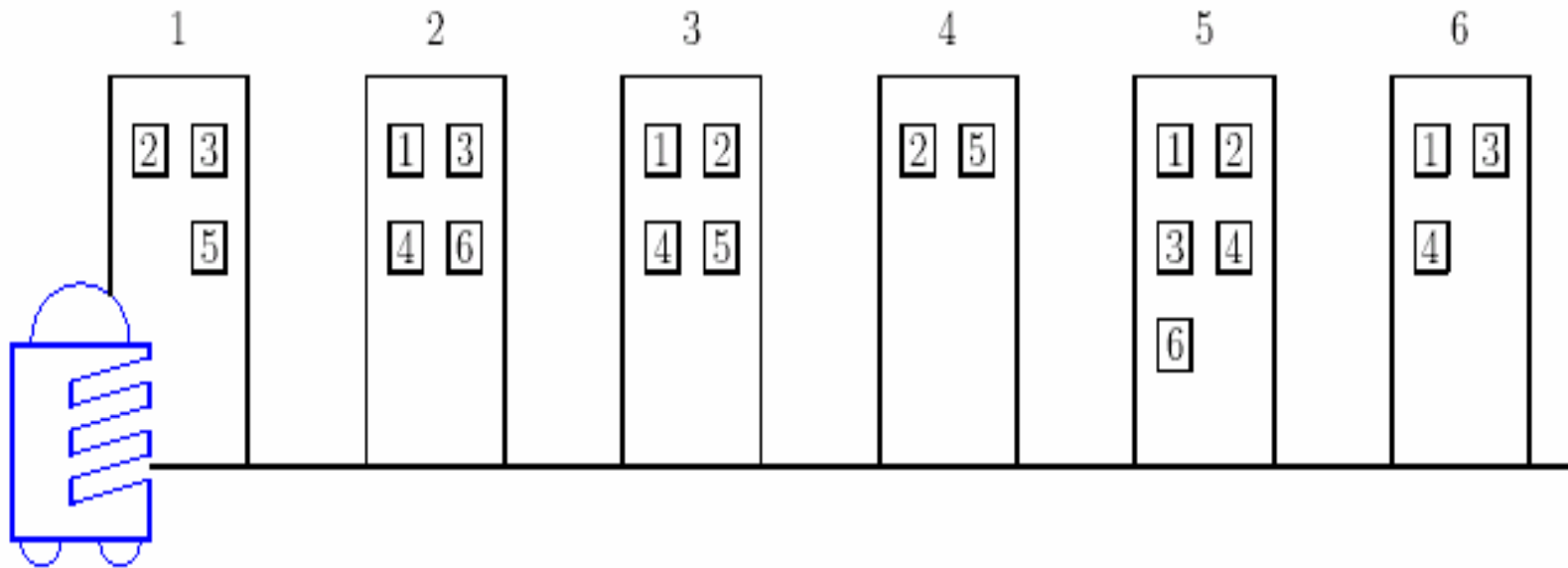


# Fluent Calculus (FC)

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- state represented as term
- axioms and specification of state and actions imply constraints on solution/action and new state
- deductive plan generation
- language FLUX (Fluent Executor)
- realised in Prolog with constraints
- includes many features from KR

# A Simple Office Robot



Aufgabe des Roboters sei es, mit seinen 3 Postfächern die Hauspost einzusammeln und auszuteilen.

Elementaraktionen des Roboters sind:

- $\text{fülle}(x, y)$   $x \in \{1, 2, 3\}, y \in \{1, \dots, 6\}$
- $\text{leere}(x)$   $x \in \{1, 2, 3\}$
- $\text{gehe}(x)$   $x \in \{\text{vor}, \text{zurück}\}$



# Simple FLUX Program

```
main :- init(Z), main_loop(Z).
```

```
main_loop(Z) :-
```

```
    poss(leere(X),Z)    -> execute(leere(X),Z,Z1),    main_loop(Z1) ;
```

```
    poss(fuelle(X,Y),Z) -> execute(fuelle(X,Y),Z,Z1), main_loop(Z1) ;
```

```
    weiter(X,Z)        -> execute(gehe(X),Z,Z1),    main_loop(Z1) ;
```

```
    true.
```

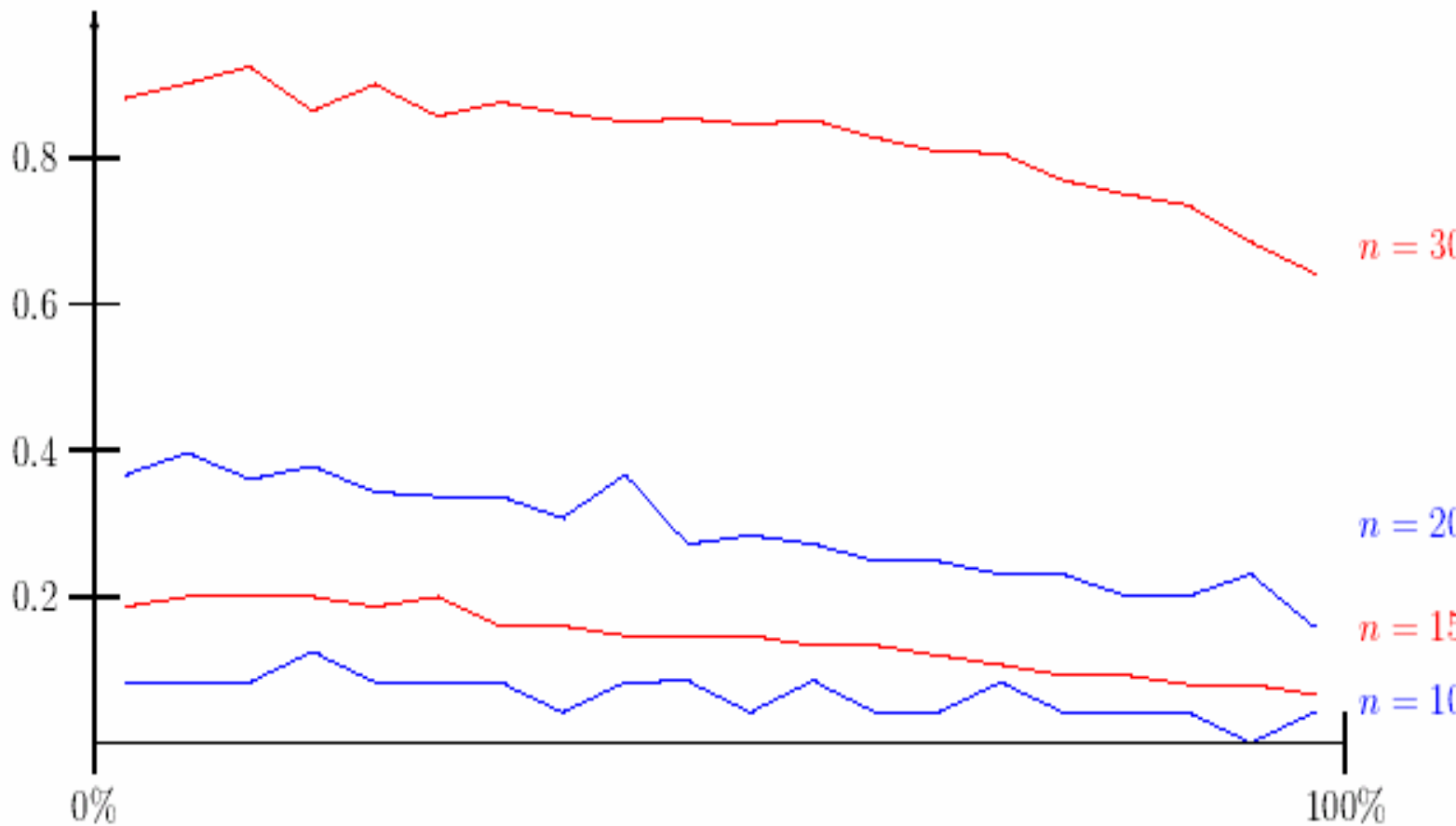
```
weiter(X,Z) :-
```

```
    ( holds(leer(F),Z), holds(sendung(R1,R2),Z) ; holds(traegt(F,R1),Z) )
```

```
    holds(position(R),Z), ( R < R1 -> X = vor ; X = zurueck ).
```

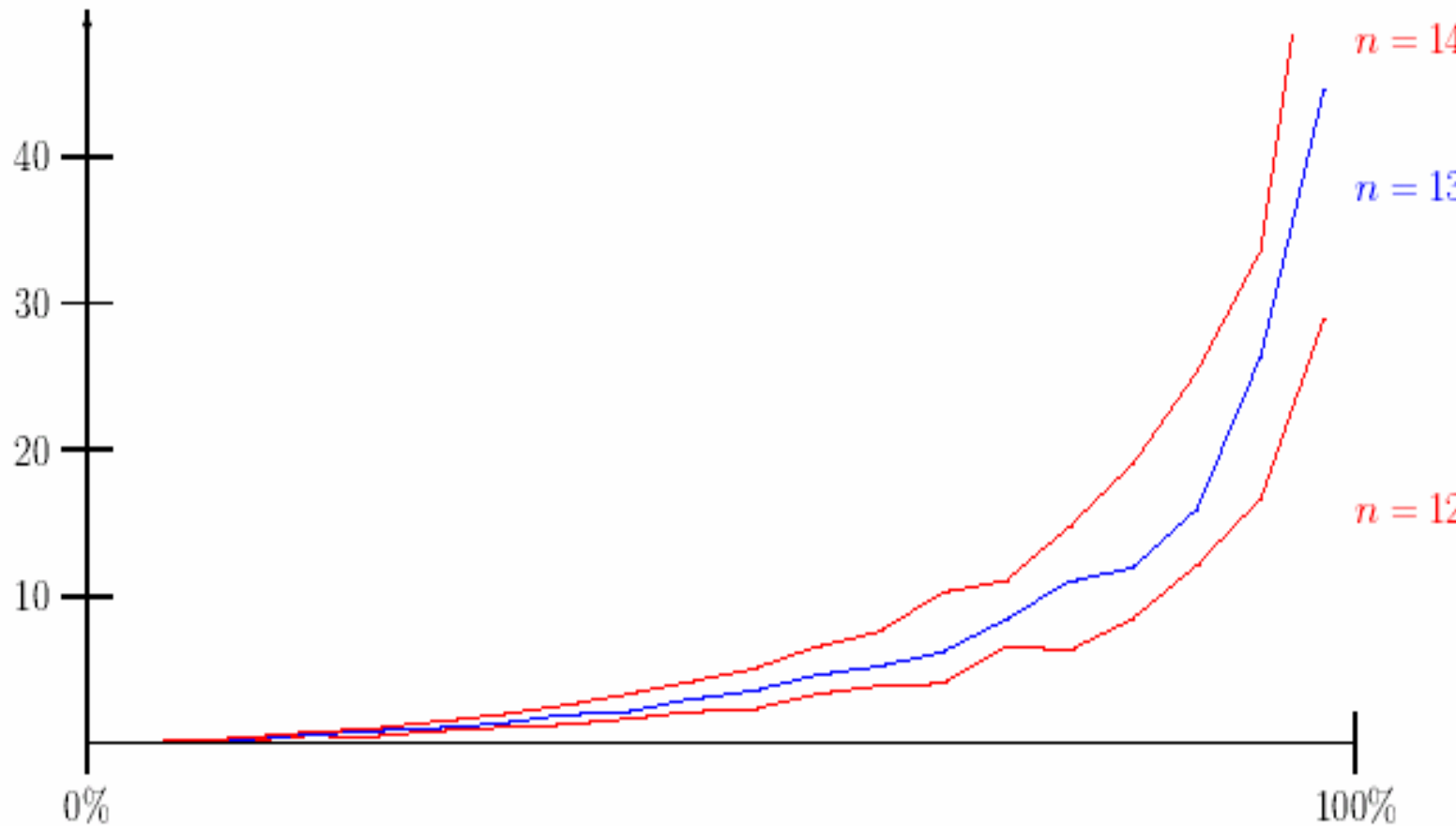
# FLUX Runtime Behavior (n,3)

Sek / 100 Aktionen



# Golog Runtime Behavior (n,3)

Sek / 100 Aktionen





# Conclusions

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- Deductive approach extremely attractive
- Only competitive with a solution for both the representational and inferential frame problem (FC) and with an integration of classical  $\vdash$  for compression (TL, partially FF)
- Efficient integration of TL into a theorem prover yet to be done





# Midterm Perspective

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- Hundreds of millions of facts in brain
- Goal: KBs with 100 mio. facts
- CYC so far 1.5 mio. facts
- Open Mind Common Sense database:
  - everyone can enter knowledge facts
  - input in natural language possible
  - within 2 years 0.5 mio. facts
- Deductive planning system on top



# Trend in Full Swing . . .

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- CYC (100k concepts, 10k predicates)
- Wordnet 1.6: Englisch, word/meaning
- Enterprise Ontology (modelling)
- Gene Ontology (biological concepts)
- Process Ontology (engineering)
- Cancer Ontology (100k concepts/terms)
- IEEE Standard Upper Ontology



# A Practical Example

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- Problem specification
  - given a standard laptop under worm attack
  - given an address for a patch program
  - goal: protected machine
  - find plan to achieve goal
- Requires several (static) reasoning steps in order to determine transitions