Local primordial non-Gaussianity from the large-scale clustering of photometric DESI luminous red galaxies

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ABSTRACT

This paper uses the angular power spectrum of luminous red galaxies (LRGs) selected from the Dark Energy Spectroscopic Instrument (DESI) imaging surveys to constrain the local primordial non-Gaussianity parameter f_{NL}. Our sample comprises over 14 million LRG targets, spanning approximately 18,000 square degrees of the sky, with redshifts ranging from 0.2 < z < 1.35. Galactic extinction, survey depth, and astronomical seeing are identified as the primary sources of systematic error using feature selection and cross-correlation techniques. Linear regression and artificial neural networks are applied to mitigate systematics and alleviate excess clustering signals on large scales. Our treatment methods are tested and calibrated rigorously against lognormal density simulations with and without $f_{\rm NL}$ and systematic effects, indicating the neural network treatment outperforms linear regression in reducing remaining systematics in the DESI LRG sample. Assuming halo bias only depends on mass, we find $f_{\rm NL} = 47^{+14}_{-11} \, {}^{(+29)}_{(-22)}$ at 68% (95%) confidence. Applying a more aggressive systematics treatment that includes regression against the full set of imaging maps we identified, our maximum likelihood value changes only slightly to $f_{\rm NL} \sim 50$, but the uncertainty on $f_{\rm NL}$ increases due to the aggressive treatment removing large-scale clustering information. We apply a series of robustness tests (e.g., cuts on imaging, declination, or scales) that show remarkable consistency in the obtained constraints. Our fiducial result can either be interpreted as a strong detection of non-zero f_{NL} , inconsistent with what is measured from Planck, or evidence for unknown sources of variation in the observed galaxy density (e.g., from calibration errors in photometric zeropoint determination or in Galactic extinction corrections). Our results motivate follow-up studies of f_{NL} with DESI spectroscopic samples, where the inclusion of 3D clustering modes should help separate imaging systematics.

Key words: cosmology: inflation - large-scale structure of the Universe

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1 INTRODUCTION

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Inflation is a widely accepted paradigm in modern cosmology that explains many important characteristics of our Universe. It predicts that the early Universe underwent a period of accelerated expansion, resulting in the observed homogeneity and isotropy of the Universe on large scales (see, e.g., Weinberg et al. 2013, for a review). After the period of inflation, the Universe entered a phase of reheating in which primordial perturbations were generated, setting the initial seeds for structure formation (Kofman et al. 1994; Bassett et al. 2006; Lyth & Liddle 2009). Although inflation is widely accepted as a compelling explanation, the characteristics of the field or fields that drove the inflationary expansion remain largely unknown in contemporary observational cosmology. While early studies of the cosmic microwave background (CMB) and large-scale structure (LSS) suggested that primordial fluctuations are both Gaussian and scale-invariant (Tegmark et al. 2004; Guth & Kaiser 2005), some alternative classes of inflationary models predict some levels of non-Gaussianities in the primordial gravitational field. Non-Gaussianities are a measure of the degree to which the distribution of matter in the Universe deviates from a Gaussian distribution, which would have important implications for the growth of structure and galaxies in the Universe (see, e.g., Desjacques & Seljak 2010; Biagetti 2019).

In its simplest form, local primordial non-Gaussianity (PNG) is parameterised by the non-linear coupling constant $f_{NL}(Komatsu)$ & Spergel 2001):

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$$\Phi = \phi + f_{NL} [\phi^2 - \langle \phi^2 \rangle], \tag{1}$$

where Φ is the primordial curvature perturbation and ϕ is assumed to be a Gaussian random field. Obtaining reliable, accurate, and robust constraints on f_{NL} is crucial in advancing our understanding of the dynamics of the early Universe. For instance, the standard single-field slow-roll inflationary model predicts a small value of $f_{\rm NL} \sim 0.01$ (see, e.g., Maldacena 2003). On the other hand, some alternative inflationary scenarios involve multiple scalar fields that can interact with each other during inflation, leading to the generation of larger levels of non-Gaussianities. These models predict considerably larger values of $f_{\rm NL}$ that can reach up to 100 or higher (see, e.g., Byrnes et al. 2008; Peterson & Tegmark 2011). With $\sigma(f_{\rm NL}) \sim 1$, we can rule out or confirm specific models of inflation and gain insight into the physics that drove the inflationary expansion (see, e.g., Alvarez et al. 2014; de Putter et al. 2017).

Local-type PNG generates a primordial bispectrum, which 100 peaks in the squeezed triangle configuration where one of the three 101 wave vectors is much smaller than the other two. This means that one 102 of the modes is on a much larger scale than the other two, and this mode couples with the other two modes to generate a non-Gaussian signal, which then affects the local number density of galaxies. The coupling between the short and long wavelengths induces a distinct bias in the galaxy distribution, which leads to a k^{-2} -dependent feature in the two-point clustering of galaxies and quasars (Dalal et al. 2008).

Ashley: I would make the paragraph about current LSS constraints longer, adding details about forecasts for future and/or merge with the paragraph about CMB results. Basically, what 112 should come out of the text is that, at least in terms of Fisher forecasts 113 (and ignoring the assembly bias issue) LSS offers the most promise. I would add the pieces about DESI that you have later in the introduc- 115 $tion\ here.$ The current tightest bound on $f_{
m NL}$ comes from Planck's $_{
m 116}$ bispectrum measurement of CMB anisotropies, $f_{\rm NL} = 0.9 \pm 5.1$ 117 (Planck Collaboration et al. 2019). Limited by cosmic variance, 118 CMB data cannot enhance the statistical precision of $f_{\rm NL}$ measurements enough to break the degeneracy amongst various inflationary paradigms (see, e.g., Abazajian et al. 2016; Simons Observatory et al. 2019). On the other hand, LSS surveys probe a 3D map of the Universe, and thus provide more modes to limit f_{NL} . However, nonlinearities raised from structure formation pose a serious challenge for measuring f_{NL} with the three-point clustering of galaxies, and these nonlinear effects are non-trivial to model and disentangle from the primordial signal (Baldauf et al. 2011b,a).

Currently, the most precise constraints on f_{NL} from LSS reach a level of $\sigma(f_{\rm NL}) \sim 20 - 30$, with the majority of the constraining power coming from the two-point clustering statistics that utilize the scale-dependent bias effect (Castorina et al. 2019; Mueller et al. 2022; Cabass et al. 2022; D'Amico et al. 2022). Surveying large areas of the sky can unlock more modes and help improve these constraints. As an ongoing wide-area galaxy survey, the Dark Energy Spectroscopic Instrument (DESI) uses 5000 robotically-driven fibers to simultaneously collect spectra of extra-galactic objects. DESI is designed to deliver an unparalleled volume of spectroscopic data covering ~ 14,000 square degrees that promises to deepen our understanding of the energy contents of the Universe, neutrino masses, and the nature of gravity (DESI Collaboration et al. 2016). Moreover, DESI alone is expected to improve our constraints on local PNG down to $\sigma(f_{\rm NL})$ = 5, assuming systematic uncertainties are under control (DESI Collaboration et al. 2016). With multitracer techniques, cosmic variance can be further reduced to allow surpassing CMB-like constraints (Alonso et al. 2015). For instance, the distortion of CMB photons around foreground masses, which is referred to as CMB lensing, provides an additional probe of LSS, but from a different vantage point. We can significantly reduce statistical uncertainties below $\sigma(f_{NL}) \sim 1$ by cross-correlating LSS data with other tracers of matter, such as CMB-lensing and 21 cm intensity mapping (see, e.g., Schmittfull & Seljak 2018; Heinrich & Doré 2022; Jolicoeur et al. 2023; Sullivan et al. 2023).

Ashley: I think the only modeling issues that really ends up being relevant are the assembly bias and integral constraint. I would mention the assembly bias issue and probably expand on that a little and specifically say that we won't actually marginalize over it in this analysis. I don't know that the integral constraint issue needs to be discussed in the introduction, since the modeling needed to address it is fairly clear. (It should definitely be described in the modeling section.) I think the other modeling issues I wouldn't get into, especially in the introduction. Perhaps in the modeling section you can just list them all as being sub-dominant issues for our analysis that we do not worry about. Ashley: I would explain more conceptually why the observational systematics are more problematic on large scales and thus for fNL measurements. You can even cite BICEP results for general issue of low ell angular power spectra measurements being subject to contamination (essentially, we expect our background contamination to generically have large angular scale power).

However, further work is needed to fully harness the potential of the scale-dependent bias effect in constraining f_{NL} with LSS. The amplitude of the f_{NL} signal in LSS is proportional to a bias parameter b_{ϕ} . Assuming universality of the halo mass function, $b_{\phi} \sim (b-p)$, where b is the linear halo bias and p=1 is parameter that describes the response of galaxy formation to primordial potential perturbations in the presence of local PNG. The theoretical uncertainties on p is not very well constrained (Barreira et al. 2020; Barreira 2020), and Barreira (2022) showed that marginalizing over p even with wide priors leads to biased f_{NL} constraints because of parameter space projection effects. More simulation-based

studies of halo-assembly bias are necessary to properly model the galaxy power spectrum for non-zero $f_{\rm NL}$ cosmologies. For instance, Lazeyras et al. (2023) used N-body simulations to investigate secondary halo properties, such as concentration, spin and sphericity of haloes, and found that halo spin and sphericity preserve the universality of the halo occupation function while halo concentration significantly alters the halo function. Without better-informed priors on p, it is argued that the scale-dependent bias effect can only be used to constrain the $b_{\phi} f_{\rm NL}$ term (see, e.g., Barreira 2020). Nevertheless, the detection significance of local PNG remains unaffected by various assumptions regarding p. This means that a nonzero detection of $b_{\phi} f_{\rm NL}$ at a certain confidence level will still indicate a nonzero detection of $f_{\rm NL}$ at that same confidence level.

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In addition to the theoretical uncertainties, measuring f_{NL} using the scale-dependent bias effect is nonetheless incredibly challenging due to various imaging systematic effects that can modulate 193 the galaxy power spectrum on large scales. For instance, Galactic 194 extinction, astronomical seeing, stellar contamination, and photo- 195 metric calibration can induce spurious fluctuations in the observed 196 density field of targets, and thus give rise to excess clustering power 197 on large scales (Ross et al. 2011; Huterer et al. 2013), which can be 198 miss-interpreted as the signature of non-zero local PNG (see, e.g., 199 Thomas et al. 2011). The issue of imaging systematic effects has 200 proven to be a significant obstacle in the past efforts to constrain $f_{\rm NL}$ 201 using the large-scale clustering of galaxies and quasars (see, e.g., 202 Pullen & Hirata 2013; Ho et al. 2015). It is anticipated that imag- 203 ing systematic errors will be particularly problematic for wide-area galaxy surveys that observe regions of the night sky closer to the Galactic plane and that seek to incorporate more lenient selection criteria to accommodate fainter galaxies (see, e.g, Kitanidis et al. 2020).

The primary objective of this paper is to utilize the scale-dependent bias signature in the angular power spectrum of luminous red galaxies selected from DESI imaging data to constrain the value of $f_{\rm NL}$. By prioritizing the treatment of imaging systematic errors, we aim to lay the groundwork for subsequent studies of local PNG with DESI spectroscopy. To prepare our sample for such a delicate signal, we employ linear multivariate regression and neural networks to clean and refine the data from spurious density fluctuations caused by imaging systematics. With cross correlation techniques and summary statistics, we thoroughly characterize and examine potential sources of systematic error, including survey depth, astronomical seeing, photometric calibration, Galactic extinction, and local stellar density. Our findings are validated using suites of lognormal simulations featuring values of $f_{\rm NL}=0$ and $f_{\rm NL}=0$ and f

This paper is structured as follows. Section 2 describes the 221 galaxy sample from DESI imaging and lognormal simulations with, 222 or without, PNG and synthetic systematic effects. Section 3 outlines 223 the theoretical framework for modelling the angular power spectrum, strategies for handling various observational and theoretical 225 systematic effects, and statistical techniques for measuring the significance of remaining systematics in our sample after mitigation. 227 Our results are presented in Section 4, and Section 5 summarizes 228 our conclusions and directions for future work. 229

2 DATA

Luminous red galaxies (LRGs) are massive galaxies that populate massive haloes, lack active star formation, and are highly biased tracers of the dark matter gravitational field. A distinct break around 4000 Å in the LRG spectrum is often utilized to determine their redshifts accurately. LRGs are widely targeted in previous galaxy redshift surveys (see, e.g., Eisenstein et al. 2001; Prakash et al. 2016), and their clustering and redshift properties are well studied (see, e.g., Ross et al. 2020; Gil-Marín et al. 2020; Bautista et al. 2021; Chapman et al. 2022).

DESI is designed to collect spectra of millions of LRGs covering the redshift range 0.2 < z < 1.35. DESI selects its targets for spectroscopy from the DESI Legacy Imaging Surveys, which consist of three ground-based surveys that provide photometry of the sky in the optical g, r, and z bands. These surveys include the Mayall z-band Legacy Survey using the Mayall telescope at Kitt Peak (MzLS; Dey et al. 2018), the Beijing-Arizona Sky Survey using the Bok telescope at Kitt Peak (BASS; Zou et al. 2017), and the Dark Energy Camera Legacy Survey on the Blanco 4m telescope (DECaLS; Flaugher et al. 2015). As shown in Figure 2, the BASS and MzLS surveys observed the same footprint in the North Galactic Cap (NGC) while the DECaLS program observed both caps around the galactic plane; the BASS+MzLS footprint is separated from the DECaLS NGC at DEC > 32.375 degrees, although there is an overlap between the two regions for calibration purposes (Dey et al. 2018). Additionally, the DECaLS program integrates observations executed from the Blanco instrument under the Dark Energy Survey (DES Collaboration et al. 2016), which cover about 1130 deg² of the South Galactic Cap (SGC) footprint. The DESI imaging catalogues also integrate the 3.4 (W1) and 4.6 μm (W2) infrared photometry from the Wide-Field Infrared Explorer (WISE; Wright et al. 2010; Meisner et al. 2018).

2.1 DESI imaging LRGs

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Our sample of LRGs is drawn from the DESI Legacy Imaging Surveys Data Release 9 (DR9; Dey et al. 2018) using the colormagnitude selection criteria designed for the DESI 1% survey (DESI Collaboration in prep), described as the Survey Validation 3 (SV3) selection in more detail in Zhou et al. (2022). The color-magnitude selection cuts are defined in the g, r, z bands in the optical and W1 band in the infrared, as summarized in Table 1. The selection cuts are developed differently for each imaging survey to reach an almost uniform target surface density, with an average density of 800 galaxies per square degree covering around 18000 square degrees, despite different survey efficiency and photometric calibration between DECaLS and BASS+MzLS. The implementation of these selection cuts in the DESI data processing pipeline is explained in Myers et al. (2022). The redshift distribution of our galaxy sample are inferred respectively from DESI spectroscopy during the Survey Validation phase (DESI Collaboration in prep), and is shown via the solid curve in Figure 1. Zhou et al. (2021) analyzed the DESI LRG targets and found that the redfhit evolution of the linear bias for these targets is consistent with a constant clustering amplitude and varies via 1/D(z), where D(z) is the growth factor (as illustrated by the dashed red line in Figure 1).

The LRG sample is masked rigorously for foreground bright stars, bright galaxies, and clusters of galaxies¹ to further reduce stellar contamination (Zhou et al. 2022). Then, the sample is binned into HEALPIX (Gorski et al. 2005) pixels at NSIDE = 256 to construct the 2D density map (as shown in the top panel of Figure 2). The LRG

¹ See https://www.legacysurvey.org/dr9/bitmasks/ for maskbit definitions.

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Table 1. Color-magnitude selection criteria for the DESI LRG targets (Zhou et al. 2022). Magnitudes are corrected for Galactic extinction. The z-band fiber magnitude, z_{fiber} , corresponds to the expected flux within a DESI fiber.

Footprint	Criterion	Description
	$z_{\text{fiber}} < 21.7$	Faint limit
DECaLS	$z - W1 > 0.8 \times (r - z) - 0.6$	Stellar rejection
	[(g-r > 1.3) AND ((g-r) > -1.55 * (r-W1) + 3.13)] OR (r-W1 > 1.8)	Remove low-z galaxies
	[(r - W1 > (W1 - 17.26) * 1.8) AND (r - W1 > W1 - 16.36)] OR (r - W1 > 3.29)	Luminosity cut
	$z_{\rm fiber} < 21.71$	Faint limit
BASS+MzLS	$z - W1 > 0.8 \times (r - z) - 0.6$	Stellar rejection
	[(g-r > 1.34) AND ((g-r) > -1.55 * (r-W1) + 3.23)] OR (r-W1 > 1.8)	Remove low-z galaxies
	[(r - W1 > (W1 - 17.24) * 1.83) AND (r - W1 > W1 - 16.33)] OR (r - W1 > 3.39)	Luminosity cut

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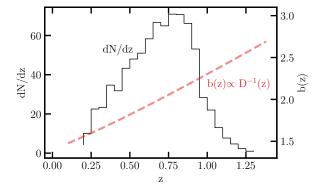


Figure 1. The redshift distribution (solid line) and bias evolution (dashed line) of the DESI LRG targets. The redshift distribution is determined from DESI spectroscopy (DESI Collaboration in prep). The redshift evolution of the linear bias is supported by HOD fits to the angular clustering of the DESI $\,\,^{274}$ LRG targets (Zhou et al. 2021), where D(z) represents the growth factor.

density is corrected for the pixel incompleteness and lost areas using a catalogue of random points, hereafter referred to as randoms, uniformly scattered over the footprint with the same cuts and masks applied. Moreover, the density of galaxies is matched to the randoms separately for each of the three data sections (BASS+MzLS, DeCALS North / South) so the density differences are removed. The DESI LRG targets are selected brighter than the imaging survey depth limits, e.g., g = 23.72, r = 23.27, and z = 22.22 for median 5σ detection in AB mag in the DECaLS region (Dey et al. 2018); and thus the LRG density map does not exhibit severe spurious density fluctuations.

2.1.1 Imaging systematic maps

Zhou et al. (2022) has previously identified nine astrophysical prop- 293 erties as potential sources of imaging systematic errors in the DESI LRG targets. The properties are mapped into HEALPIX of NSIDE= 256. As illustrated by a 3x3 grid in the bottom panel of Figure 2, the maps include local stellar density constructed from pointlike sources with a G-band magnitude in the range $12 \le G < 17$ from the Gaia DR2 (see, Gaia Collaboration et al. 2018; Myers et al. 2022); Galactic extinction E[B-V] from Schlegel et al. (1998); survey depth (galaxy depth in g, r, and z and PSF depth in W1) and astronomical seeing (psfsize) in g, r, and z. The depth maps have $_{302}$ been corrected for extinction using the coefficients adapted from 303 Schlafly & Finkbeiner (2011). In addition to these nine maps, we 304 consider two external maps for the neutral hydrogen column den- 305 sity (HI) from HI4PI Collaboration et al. (2016) and photometric 306 calibration in the z-band (CALIBZ) from CITE to further test the robustness of our analysis against unknown systematics.

Each imaging map carries its characteristic fluctuations, which correlate with the LRG density map. For instance, large-scale fluctuations can be associated with stellar density, extinction, or survey depth; while small scale-fluctuations can be related to psfsize variations. Some regions of the DR9 footprint are removed from our analysis to avoid potential photometric calibration issues. These regions are either disconnected from the main footprint (e.g., the islands in the NGC with DEC < -10) or calibrated using different catalogues of standard stars (e.g., DEC < -30 in the SGC). The potential impact of not imposing these declination cuts on the LRG sample and our f_{NL} constraints is explored in Section 4.

Figure 3 shows the Pearson correlation coefficient between the DESI LRG target density map and the imaging systematics maps for the three imaging regions (DECaLS North, DECaLS South, and BASS+MzLS) in the top panel. The horizontal curves represent the 95% confidence regions for no correlation and are constructed by cross-correlating 100 synthetic lognormal density fields and the imaging systematic maps. There are statistically significant correlations between the LRG density and depth, extinction, and stellar density. There are less significant correlations between the LRG density and the W1-band depth and psfsize in DECaLS South and DECaLS North. Figure 3 (bottom panel) shows the correlation matrix among the imaging systematics maps for the entire DESI footprint. Significant inner correlations exist among the imaging systematic maps themselves, especially between local stellar density and Galactic extinction; also, the r-band and g-band survey properties are more correlated with each other than with the z-band counterpart. To ensure the robustness of the analysis, we computed the Spearman correlation coefficient as well to evaluate the monotonic relationship between the DESI LRG target density and imaging systematic maps. However, we found no substantial differences in the correlation coefficients.

The effects of observational systematics in the DESI targets have been studied in great detail (see, e.g., Kitanidis et al. 2020; Zhou et al. 2021; Chaussidon et al. 2022). There are several approaches for handling imaging systematic errors, broadly classified into data-driven and simulation-based modeling approaches. The general idea behind these approaches is to use the available data or simulations to learn or forward model the relationship between the observed target density and the imaging systematic maps, and to use this relationship, which is often described by a set of *imag*ing weights, to mitigate spurious fluctuations in the observed target density. Another techniques for reducing the effect of imaging systematics rely on cross-correlating different tracers of dark matter to ameliorate excess clustering signals, as each tracer might respond differently to a source of systematic error (see, e.g., Giannantonio

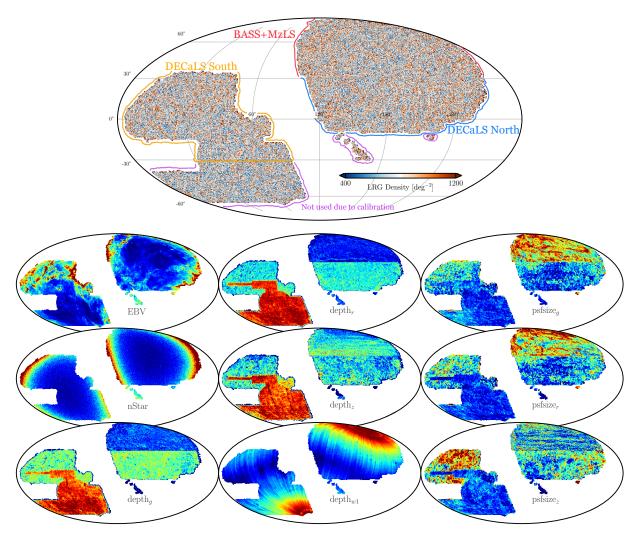


Figure 2. Top: The DESI LRG target density map before correcting for imaging systematic effects in Mollweide projection. The disconnected islands from the North footprint and parts of the South footprint with declination below –30 are removed from the sample for the analysis due to potential calibration issues (see text). Bottom: Mollweide projections of the imaging systematic maps (survey depth, astronomical seeing/psfsize, Galactic extinction, and local stellar density) in celestial coordinates. Not shown here are two external maps for the neutral hydrogen column density and photometric calibration, which are only employed for the robustness tests. The imaging systematic maps are colour-coded to show increasing values from blue to red.

et al. 2014). These methods have their limitations and strengths (see, 319 e.g., Weaverdyck & Huterer 2021, for a review). 320

2.1.2 Treatment of imaging systematics

MR: make this section clear. In this paper, data-driven approaches, including linear multivariate regression and artificial neural networks, are applied to the data to correct for imaging systematic effects. Both linear and neural network models are trained on each imaging region separately since the Pearson correlation coefficient analysis indicated the level of imaging systematic effects in each region is different, as illustrated in the top panel of Figure 3.

The linear multivariate model only uses the imaging systematic maps up to the linear power to predict the number counts of the DESI LRG targets in pixel i,

$$\rho_i = \log(1 + \exp[\mathbf{a}.\mathbf{x}_i]),\tag{2}$$

where $\mathbf{a}.\mathbf{x}_i$ represents the inner product between the parameters, \mathbf{a} , 336 and imaging systematic values for pixel i, \mathbf{x}_i . The implementation 337

of Markov Chain Monte Carlo (MCMC) random search from EMCEE (Foreman-Mackey et al. 2013) is used to explore the parameter space by minimizing the negative Poisson log-likelihood between the actual and predicted number counts of targets. No spatial coordinate is included in \mathbf{x}_i to help avoid over correction, and as a result, the predicted number counts solely reflect the spurious density fluctuations that arise from varying imaging conditions. The number of pixels is substantially larger than the number of parameters for the linear model, and thus no training-validation-testing split is applied to the data. This aligns with the methodology used for training linear models in previous analyses (see, e.g., Zhou et al. 2022). The marginalized mean of the parameters from MCMC are then utilized to compute the imaging weights.

Our neural network-based mitigation approach uses the implementation of fully connected feedforward neural networks from Rezaie et al. (2021). With the neural network approach, $\mathbf{a}.\mathbf{x}_i$ in Equation 2 is replaced with $NN(\mathbf{x}_i|\mathbf{a})$, where NN represents the fully connected neural network and \mathbf{a} denotes its parameters. The implementation, training, validation, and application of neural net-

 $psfsize_a$

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 $\mathrm{psfsize}_z$

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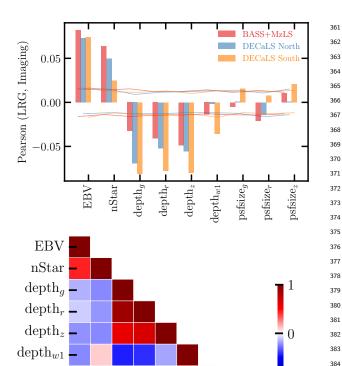


Figure 3. Top: The Pearson correlation coefficient between the DESI LRG target density and imaging properties in BASS+MzLS, DECaLS North, and DECaLS South. Solid horizontal curves represent the 95% confidence intervals estimated from simulations of lognormal density fields. Bottom: The Pearson correlation matrix of imaging properties for the DESI footprint.

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works on galaxy survey data are presented in Rezaie et al. (2021). 400 We briefly summarize the methodology here.

A fully connected feedforward neural network (also called a *multi-layer perceptron*) is a type of artificial neural network where the neurons are arranged in layers, and each neuron in one layer is connected to every neuron in the next layer. The imaging systematic information flows only in one direction, from input to output. Each neuron applies a non-linear activation function (i.e., transformation) to the weighted sum of its inputs, which are the outputs of the neurons in the previous layer. The output of the last layer is the prediction of the model for the number counts of galaxies. Our architecture consists of three hidden layers with 20 rectifier activation functions on each layer, and a single neuron in the output layer. The rectifier is defined as $\max(0, x)$ (Nair & Hinton 2010). This simple form of nonlinearity is very effective in enabling deep neural networks to learn more complex, non-linear relationships between the input imaging maps and output galaxy counts.

Unlike linear regression, neural networks are prone to fitting
noise, i.e., excellent performance on training data and poor performance on unseen data. Therefore, our analysis uses a trainingvalidation-testing split to ensure that the network is well-optimized
and generalizes well to unseen data. Specifically, 60% of the LRG
data is used for training, 20% is used for validation, and 20% is used

for testing. The split is performed randomly aside from the locations of the pixels. We test a geometrical split in which neighboring pixels beyond to the same set of training, testing, or validation, but no significant performance difference is observed. The neural network models are tested on the entirety of the LRG sample with the technique of permuting the choice of the training, validation, or testing sets (Arlot & Celisse 2010). The neural networks are trained for up to 70 training epochs with the gradient descent ADAM optimizer (Loshchilov & Hutter 2017). The neural network parameters are adjusted iteratively following the gradient of the negative Poisson log-likelihood. The step size of the parameter updates is controlled via the learning rate hyper-parameter, which is initialized with a grid search and is designed to dynamically vary between two boundary values of 0.001 and 0.1 to avoid local minima (see, also, Loshchilov & Hutter 2016). At each training epoch, the neural network model is applied to the validation set, and ultimately the model with the best performance on validation is identified and applied to the test set. With the cross-validation technique, the model predictions from the different test sets are aggregated together to form the predicted target density map into HEALPIX of NSIDE = 256. To reduce the error in the predicted number counts, we train an ensemble of 20 neural network models and average over the predictions. The imaging weights are then defined as the inverse of the predicted target density, normalized to unity.

One potential problem that can arise in the data-driven mitigation approach is *over-correction*, which occurs when the corrections applied to the data are too strong that remove the clustering signal and induce additional biases in the inferred parameter. The neural network approach is more prone to this issue compared to the linear approach, due to the increased flexibility. As illustrated in the bottom panel of Figure 3, the significant correlations among the imaging systematic maps may pose additional challenges for modeling these spurious density fluctuations. Specifically, using highly correlated imaging systematic maps increases the statistical noise in the imaging weights, which elevates the potential for over subtracting the clustering power. These over-correction effects are identified to have a negligible impact on Baryon Acoustic Oscillations and Redshift Space Distortions (Merz et al. 2021); however, they can significantly modulate the galaxy power spectrum on large scales, and thus lead to biased f_{NL} constraints (Rezaie et al. 2021; Mueller et al. 2022). Although not explored thoroughly, these issues could limit the detectability of primordial features in the galaxy power spectrum and that of parity violations in higher order clustering statistics (Beutler et al. 2019; Cahn et al. 2021; Philcox 2022). Therefore, it is crucial to develop, implement, and apply techniques to minimize and control over-correction, if possible, by reducing the dimensionality of the problem, in the hope of ensuring that the constraints are as accurate and reliable as possible. Our goal is to reduce the correlations between the DESI LRG target density and the imaging systematic maps, while minimizing the chance of over correction. To achieve this objective, we employ a series of simulations along with statistical methods that involve cross power spectrum and mean galaxy density to identify different sets of the imaging systematic maps: Santi: Elaborate how these maps are selected

- (i) Two maps: Extinction, depth in z.
- (ii) Three maps: Extinction, depth in z, psfsize in r.
- (iii) Four maps: Extinction, depth in z, psfsize in r, stellar density.
- (iv) **Five maps**: Extinction, depth in z, psfsize in r, neutral hydrogen density, and calibration in z.
 - (v) **Eight maps**: Extinction, depth in grzW1, psfsize in grz.

(vi) **Nine maps**: Extinction, depth in grzW1, psfsize in grz, stellar 477 density.

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Edmond: You can comment a bit on the different combinations; why / how do you decide which combination we want? (maybe just say that it is explained below, your sentence on visual inspection) Alex: Throughout—I think it would be clearer if you always referred to every method with 2 labels, "[linear/nonlinear] [map name]". We emphasise that these sets are established prior to examining the auto power spectrum of the LRG sample. The auto power spectrum measurements are unblinded only after our mitigation methods passed our rigorous tests for residual systematics. To start, we will use the linear model and two maps (extinction and depth in z), which is the most conservative method in terms of both the model flexibility and the number of parameters. We clean the sample using the imaging weights obtained from linear two maps. We find that the linear two maps approach mitigates most of the spurious fluctuations in the LRG density and reduces the cross-correlations between the LRG density and the imaging systematic maps, except for the trends against psfsize in the r and z bands. Adding the r-band psfsize improves the linear model performance such that the cross correlations are similar to those obtained from linear eight maps, which indicates no further information can be extracted from eight maps. Therefore, we identify extinction, depth in z, and psfsize in r (three maps) as the primary sources of systematic effects. Then, we adapt neural network three maps to model non-linear systematic effects, and find that the neural network-based weights significantly reduce the cross correlations and spurious density fluctuations. As explained in Section 3, we consider neural network with four, five, and nine maps to further test for the robustness of our cleaning methods.

2.2 Synthetic lognormal density fields

Density fluctuations of galaxies on large scales can be approximated with lognormal distributions (Coles & Jones 1991). Unlike N-body simulations, simulating lognormal density fields is not computationally intensive, and allows quick and robust validation of data analysis pipelines. These mocks are therefore considered useful for our study since the signature of local PNG appears on large-scales and small scale clustering is not used. The package FLASK (Full-sky Lognormal Astro-fields Simulation Kit; Xavier et al. 2016) is employed to generate ensembles of synthetic lognormal density maps that mimic the bias, redshift, and angular distributions of the DESI LRG targets, as illustrated in Figure 1 and 2. Two universes with $f_{\rm NL}=0$ and 76.92 are considered. A set of 1000 realizations are produced for every f_{NL} . The analysis adapts a fiducial cosmology from a flat Λ CDM universe, including one massive neutrino with $m_{\nu} = 0.06$ eV, Hubble constant h = 0.67, matter density $\Omega_M = 0.31$, baryon density $\Omega_b = 0.05$, and spectral index $n_s = 0.967$. The amplitude of the matter density fluctuations on a scale of $8h^{-1}$ Mpc is set as $\sigma_8 = 0.8225$. The same fiducial cosmology is used throughout this paper unless specified otherwise. Santi: how sensitive is the fnl signal to the choice of fiducial cosmology.

2.2.1 Contaminated mocks

The linear model is employed to introduce synthetic spurious fluctuations in the lognormal density fields. The motivation for choosing a linear contamination model is to assess how much of the clustering signal can be removed by applying more flexible and rigorous models, based on neural networks, for correcting imaging systematic effects. The parameter space of the linear model is explored using MCMC, from the relationship between the LRG sample and the imaging systematic maps. The MCMC process is executed separately on each imaging survey using only *three maps* (extinction, depth in z, and psfsize in r) as \mathbf{x}_i . The imaging selection function for contaminating each simulation is uniquely and randomly drawn from the parameter space probed by MCMC, and then the results from each imaging survey are combined to form the DESI footprint. The same contamination model is used for both the $f_{\rm NL}=0$ and 76.92 simulations.

Similar to the imaging systematic treatment analysis for the DESI LRG targets, the neural network methods with various combinations of the imaging systematic maps are applied to each simulation, with and without PNG, and with and without systematics, to derive the imaging weights. Section 3 presents how the simulation results are incorporated to calibrate $f_{\rm NL}$ biases due to overcorrection.

3 ANALYSIS TECHNIQUES

Ashley: I think somewhere in here (probably near the beginning) you need to describe how the 3 regions are combined, since I think you model their selection function separately and then combine for almost all results shown. Unless it is specified, we measure auto power spectrum, cross power spectrum, and mean density contrast for the entire footprint. However, the imaging weights are derived by regressing the observed density vs imaging systematic maps in each footprint separately.

3.1 Power spectrum estimator

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The pseudo angular power spectrum (Hivon et al. 2002) is utilized to extract information from the galaxy density contrast field, δ_g ,

$$\delta_g = \frac{\rho - \overline{\rho}}{\overline{\rho}},\tag{3}$$

by decomposing it into spherical harmonics, $Y_{\ell m}$,

$$a_{\ell m} = \int d\Omega \, \delta_g W Y_{\ell m}^*. \tag{4}$$

The mean galaxy density $\overline{\rho}$ is estimated from the entire LRG sample² and the survey window W is determined by comparing the number of randoms to the expected number. Then, the angular power spectrum is estimated by

$$\tilde{C}_{\ell} = \frac{1}{2\ell + 1} \sum_{m = -\ell}^{\ell} |a_{\ell m}|^2. \tag{5}$$

We use the implementation of anafast from the HEALPIX package (Gorski et al. 2005) to do fast harmonic transforms and estimate the pseudo angular power spectrum and cross power spectrum. When the sky coverage of a survey is incomplete, this estimator yields a biased power spectrum. Specifically, the survey mask causes correlations between different harmonic modes (Beutler et al. 2014; Wilson et al. 2017), and the measured clustering power is smoothed on scales near the survey size. Since these scales are highly sensitive to local primordial non-Gaussianity, it is crucial

² The mean galaxy density is calculated separately for each region when we fit the power spectrum from each region individually.

to account for these systematic effects in the model galaxy power 541 spectrum to obtain unbiased $f_{\rm NL}$ constraints, which we describe in 542

3.2 Modelling

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Relativistic effects also generate PNG-like scale-dependent signatures on large scales, which interfere with measuring f_{NL} with the scale-dependent bias effect (Wang et al. 2020). Similarly, matter density fluctuations with wavelengths larger than survey size, known as super-sample modes, modulate the galaxy power spectrum (Castorina & Moradinezhad Dizgah 2020). In a similar way, the peculiar motion of the observer can mimic a PNG-like scale-dependent signature through aberration, magnification and the Kaiser-Rocket effect, i.e., a systematic dipolar apparent blue-shifting in the direction of the observer's peculiar motion (Bahr-Kalus et al. 2021). However, acting radially, this effect is subdominant in angular clustering measurements. An additional potential cause of systematic error arises from the fact that the mean galaxy density used to construct the density contrast field is estimated from the available data, rather than being known a priori. This introduces what is known as an integral constraint effect, which can cause the power spectrum on modes near the size of the survey to be artificially suppressed, effectively pushing it towards zero (Peacock & Nicholson 1991; De Mattia & Ruhlmann-Kleider 2019). Accounting for these theoretical systematic effects in the galaxy power spectrum is crucial to obtain unbiased inference about f_{NL} (see, e.g., Riquelme et al. 2022).

3.2.1 Angular power spectrum

Would non-linear P(k) matter? The relationship between the linear matter power spectrum P(k) and the projected angular power spectrum of galaxies is expressed by the following equation:

$$C_{\ell} = \frac{2}{\pi} \int_0^{\infty} \frac{dk}{k} k^3 P(k) |\Delta_{\ell}(k)|^2 + N_{\text{shot}},$$
 (6)

where $N_{\rm shot}$ is a scale-independent shot noise term. The projection kernel $\Delta_\ell(k) = \Delta_\ell^{\rm g}(k) + \Delta_\ell^{\rm RSD}(k)$ includes redshift space distortions and determines the contribution of each wavenumber k to the galaxy power spectrum on mode ℓ . For more details, refer to Padmanabhan et al. (2007). The FFTLog³ algorithm and its extension as implemented in Fang et al. (2020) are employed to calculate the integrals for the projection kernel $\Delta_\ell(k)$, which includes the $\ell^{\rm th}$ order spherical Bessel functions, $j_\ell(kr)$, and its second derivatives,

$$\Delta_{\ell}^{\mathbf{g}}(k) = \int \frac{dr}{r} r(b + \Delta b) D(r) \frac{dN}{dr} j_{\ell}(kr), \tag{7}$$

$$\Delta_{\ell}^{\text{RSD}}(k) = -\int \frac{dr}{r} r f(r) D(r) \frac{dN}{dr} j_{\ell}^{"}(kr), \tag{8}$$

where b is the linear bias (dashed curve in Figure 1), D represents the linear growth factor normalized as D(z=0)=1, f(r) is the growth rate, and dN/dr is the redshift distribution of galaxies normalized to unity and described in terms of comoving distance⁴ (solid curve in Figure 1). The PNG-induced scale-dependent shift is given by (see, also, Slosar et al. 2008)

$$\Delta b = b_{\phi}(z) f_{\rm NL} \frac{3\Omega_m H_0^2}{2k^2 T(k) D(z) c^2} \frac{g(\infty)}{g(0)},\tag{9}$$

where Ω_m is the matter density, H_0 is the Hubble constant⁵, T(k) is the transfer function, and $g(\infty)/g(0) \sim 1.3$ with $g(z) \equiv (1+z)D(z)$ is the growth suppression due to non-zero Λ because of our normalization of D (see, e.g., Reid et al. 2010; Mueller et al. 2019). Assuming that only mass determines the halo occupation function, $b_{\phi} = 2\delta_{c}(b-p)$, where p=1 and $\delta_{c}=1.686$ is the critical density for spherical collapse (Fillmore & Goldreich 1984). This paper is focused on how a careful assessment of imaging systematic effects, or lack thereof, can bias our PNG constraints. Therefore, we choose p=1 for our sample of DESI LRG targets (see, also, Slosar et al. 2008; Reid et al. 2010; Ross et al. 2013), and do not marginalize over p to avoid projection effects (Barreira 2022). Santi: p=1 for galaxies assumes this on top of assuming that halos follow a universal halo mass function (only depending on peak height).

3.2.2 Survey geometry and integral constraint

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We employ a technique similar to the one proposed by Chon et al. (2004) to account for the impact of the survey geometry on the theoretical power spectrum. The ensemble average for the partial sky power spectrum is related to that of the full sky power spectrum via a mode-mode coupling matrix, $M_{\ell\ell'}$,

$$\langle \tilde{C}_{\ell} \rangle = \sum_{\ell'} M_{\ell \ell'} \langle C_{\ell'} \rangle. \tag{10}$$

We convert this convolution in the spherical harmonic space into a multiplication in the correlation function space. Specifically, we first transform the theory power spectrum (Equation 6) to the correlation function, $\hat{\omega}^{\text{model}}$. Then, we estimate the survey mask correlation function, $\hat{\omega}^{\text{window}}$, and obtain the pseudo-power spectrum,

$$\tilde{C}_{\ell}^{\text{model}} = 2\pi \int \hat{\omega}^{\text{model}} \hat{\omega}^{\text{window}} P_{\ell}(\cos \theta) d\theta.$$
 (11)

The integral constraint is another systematic effect which is induced since the mean galaxy density is estimated from the observed galaxy density. The estimate of the mean density is biased by the limited sky coverage. This issue was first raised in Peacock & Nicholson (1991). To account for the integral constraint, the survey mask power spectrum is used to introduce a scale-dependent correction factor that needs to be subtracted from the power spectrum. Finally, the pseudo power spectrum with the integral constraint correction is obtained as

$$\tilde{C}_{\ell}^{\text{model,IC}} = \tilde{C}_{\ell}^{\text{model}} - \tilde{C}_{\ell=0}^{\text{model}} \begin{pmatrix} \tilde{C}_{\ell}^{\text{window}} \\ \tilde{C}_{\ell=0}^{\text{window}} \end{pmatrix}, \tag{12}$$

where $\tilde{C}^{\text{window}}$ is the spherical harmonic transform of $\hat{\omega}^{\text{window}}$.

The lognormal simulations are used to validate our survey window and integral constraint correction. Figure 4 shows the mean power spectrum of the $f_{\rm NL}=0$ simulations (dashed) and the best-fitting theory prediction before and after accounting for the survey mask and integral constraint. The simulations are neither contaminated nor mitigated. The light and dark shades represent the 68% estimated error on the mean and one single realization, respectively. The DESI mask, which covers around 40% of the sky, is applied to the simulations. We find that the survey window effect affects the clustering power on $\ell < 200$ and the integral constraint modulates the clustering power on $\ell < 6$.

³ github.com/xfangcosmo/FFTLog-and-beyond

⁴ $dN/dr = (dN/dz) * (dz/dr) \propto (dN/dz) * H(z)$

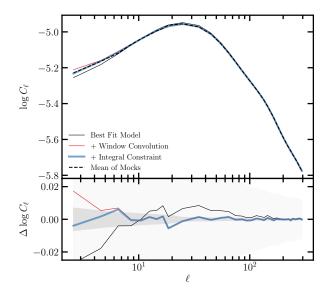


Figure 4. The mean power spectrum from the $f_{\rm NL}=0$ mocks (no contamination) and best-fitting theoretical prediction after accounting for the survey geometry and integral constraint effects. The dark and light shades represent 1σ error on the mean and one realization, respectively. Bottom panel shows the residual power spectrum relative to the mean power spectrum. No imaging systematic cleaning is applied to these mocks.

3.3 Parameter estimation

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Our parameter inference uses standard MCMC sampling. A constant clustering amplitude is assumed for the linear bias of our DESI LRG targets, b(z) = b/D(z). In MCMC, we allow f_{NL} , N_{shot} , and ⁵⁹⁶ b to vary, while all other cosmological parameters are fixed at the 597 fiducial values (see §2.2). The galaxy power spectrum is divided into a discrete set of bandpower bins with $\Delta \ell = 2$ between $\ell = 2$ and 20 and $\Delta \ell = 10$ from $\ell = 20$ to 300. Each clustering mode is weighted by $2\ell + 1$ when averaging over the modes in each bin.

With the lognormal simulations, we find that the distribution of the power spectrum at the lowest bin, $2 \le \ell < 4$, is asymmetric and its standard deviation varies significantly from the simulations with $f_{\rm NL}=0$ to those with 76.9 (Figure 5). Therefore, we attempt 605 to fit the log transformed power spectrum, $\log C_{\ell}$, to make our $f_{\rm NL}$ constraints less sensitive to the choice of covariance matrix. The 607 parameter f_{NL} is constrained by minimizing a negative likelihood defined as,

$$-2\ln \mathcal{L} = (\log \tilde{C}(\Theta) - \log \tilde{C})^{\dagger} \mathbb{C}^{-1} (\log \tilde{C}(\Theta) - \log \tilde{C}), \tag{13}$$

where Θ represents a container for the parameters $f_{\rm NL},\ b,$ and $N_{\rm shot}; \, \tilde{C}(\Theta)$ is the (binned) expected pseudo-power spectrum; \tilde{C} is the (binned) measured pseudo-power spectrum; and $\mathbb C$ is the 614 covariance matrix constructed from the lognormal simulations. Flat 615 priors are implemented for all parameters: $f_{\rm NL} \in [-1000, 1000], ^{616}$ $N_{\text{shot}} \in [-0.001, 0.001]$, and $b \in [0, 5]$. Anna: Some readers might ⁶¹⁷ wonder if the covariance estimated from the lognormal mocks is accurate enough. Could you add maybe some lines justifying this?

Characterization of remaining systematics

Santi: I feel like this section would make more sense in "2.Data" In the absence of systematic effects, a) the mean galaxy density should

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$$H_0 = 100 \text{ (km s}^{-1})/(h^{-1}\text{Mpc})$$
 and k is in unit of $h\text{Mpc}^{-1}$

be uniform across the footprint within the statistical fluctuations regardless of imaging conditions and b) the cross power spectrum between the galaxy density and the imaging systematic maps should be consistent with zero within the statistical fluctuations. In the following, two statistical tests are implemented and applied to quantify remaining systematic effects in our sample (see, also, Rezaie et al. 2021).

3.4.1 Cross power spectrum

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We characterize the cross correlations between the galaxy density and imaging systematic maps by [Could we call them something else here (maybe contaminant maps)? I first got confused and thought you were cross-correlating redshift slices in your imaging survey, but maybe our readers will read more carefully than me]

$$\tilde{C}_{X,\ell} = [\tilde{C}_{x_1,\ell}, \tilde{C}_{x_2,\ell}, \tilde{C}_{x_3,\ell}, ..., \tilde{C}_{x_9,\ell}], \tag{14}$$

where $\tilde{C}_{x_i,\ell}$ represents the normalized cross power spectrum, determined from the the square of the cross power spectrum between the galaxy density and i^{th} imaging map, x_i , divided by the auto power spectrum of x_i :

$$\tilde{C}_{x_i,\ell} = \frac{(\tilde{C}_{gx_i,\ell})^2}{\tilde{C}_{x_i,x_i,\ell}}.$$
(15)

This normalization of \tilde{C}_{x_i} estimates the contribution of systematics up to the first order to the galaxy power spectrum. Then, the χ^2 value for the cross power spectra is calculated via,

$$\chi^2 = \tilde{C}_{X,\ell}^T \mathbb{C}_X^{-1} \tilde{C}_{X,\ell},\tag{16}$$

where the covariance matrix $\mathbb{C}_X = \langle \tilde{C}_{X,\ell} \tilde{C}_{X,\ell'} \rangle$ is constructed from the lognormal mocks. These χ^2 values are measured for every clean mock realization with the leave-one-out technique and compared to the values observed in the LRG sample with various imaging systematic corrections. [Can you elaborate a more what you mean by that?] Specifically, we use 999 realizations to estimate a covariance matrix and then apply the covariance matrix from the 999 realizations to measure the χ^2 for the one remaining realization. This process is repeated for all 1000 realizations to construct a histogram for χ^2 . We only include the bandpower bins from $\ell=2$ to 20 with $\Delta \ell$ = 2, and test for the robustness with higher ℓ modes in Appendix A.

Figure 6 shows \tilde{C}_X from the DESI LRG targets before and after applying various corrections for imaging systematics. The dark and light shades show the 97.5th percentile from the $f_{\rm NL} = 0$ and 76.9 mocks, respectively. Without imaging weights, the LRG sample has the highest cross-correlations against extinction, stellar density, and depth in z (solid black curve). There is less significant correlations against depth in the g and r bands, and psfsize in the z band, which could be driven because of the inner correlations between the imaging systematic maps. First, we consider cleaning the sample with the linear model using two maps (extinction and depth in r) as identified from the Pearson correlation. With linear two maps (dot-dashed blue curve), most of the cross power signals are reduced below statistical uncertainties, especially against extinction, stellar density, and depth. However, the cross power spectra against psfsize in r and z increases slightly on $6 < \ell < 20$ and $6 < \ell < 14$, respectively. Very likely, large-scale cross correlations (ℓ < 6) are reduced using extinction and depth in the z-band, but there are some residual cross correlations on smaller scales ($\ell > 6$) which cannot be mitigated with our set of two maps. The linear three maps (dotted orange curve) approach alleviates the cross power spectrum against

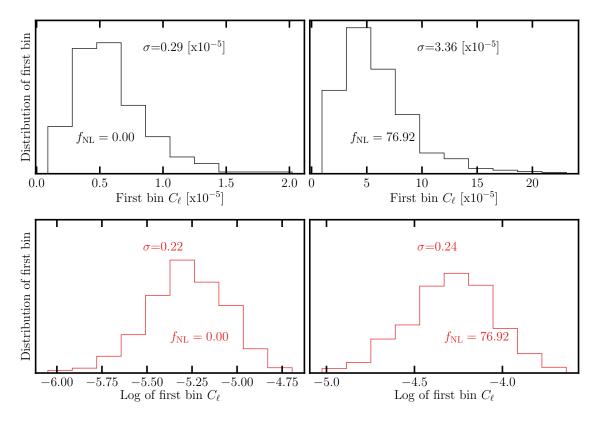


Figure 5. The distribution of the first bin power spectra and its log transformation from the simulations with $f_{\rm NL}=0$ (left) and 76.92 (right). The log transformation alleviates the asymmetry in the distributions.

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psftsize in r, but not psfsize in z. On the other hand, non-linear 640 three maps can reduce the cross correlations against both the r and 641 z-band psfsize maps, which indicates the benefit of using a non- 642 linear approach. For benchmark, we also show the normalized cross 643 spectra after cleaning the LRG sample with linear eight maps and 644 non-linear four maps.

3.4.2 Mean density contrast

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We calculate the histogram of the mean density contrast relative to the j^{th} imaging property, x_i :

$$\delta_{x_j} = (\overline{\rho})^{-1} \frac{\sum_i \rho_i W_i}{\sum_i W_i},\tag{17}$$

where $\overline{\rho}$ is the global mean galaxy density, W_i is the survey window in pixel i, and the summations over i are evaluated from the pixels in every bin of x_i . We compute the histograms against all other imaging properties (see Figure 2). We use a set of eight equal-width bins for every imaging map, which results in a total of 72 bins. Then, we construct the total mean density contract as,

$$\delta_X = [\delta_{x_1}, \delta_{x_2}, \delta_{x_3}, ..., \delta_{x_9}], \tag{18}$$

and the total residual error as,

$$\chi^2 = \delta_X^T \mathbb{C}_{\delta}^{-1} \delta_X, \tag{19}$$

where the covariance matrix $\mathbb{C}_{\delta} = <\delta_X \delta_X>$ is constructed from the lognormal mocks. Figure 7 shows the mean density contrast 666 against the imaging properties for the DESI LRG targets. The dark 667 and light shades represent the 1σ level fluctuations observed in 1000 668 lognormal density fields respectively with $f_{\rm NL} = 0$ and 76.92. The 669 DESI LRG targets before treatment (solid curve) exhibits a strong trend around 10% against the z-band depth which is consistent with the cross power spectrum. Additionally, there are significant spurious trends against extinction and stellar density at about 5 -6%. The linear approach is able to mitigate most of the systematic fluctuations with only extinction and depth in the z-band as input; however, a new trend appears against the r-band psfsize map with the linear two maps approach (dot-dashed blue curve), which is indicative of the psfsize-related systematics in our sample. This finding is in agreement with the cross power spectrum. We re-train the linear model with three maps, but we still observe around 2% residual spurious fluctuations in the low ends of depth and psfsize, in the z band, which implies non-linear systematic effects exist. We find that the imaging weights from the non-linear model trained with the three identified maps (or four maps including the stellar density) is capable of reducing the fluctuations below 2%. Even with the non-linear three maps, we have about 1% remaining systematic fluctuations against the z-band psfsize. We use the χ^2 statistics to assess how significant these fluctuations are in comparison to the clean mocks.

Figure 8 shows the χ^2 histograms from the normalized cross spectrum (top) and mean density contrast (bottom) statistics which are obtained from the $f_{NL} = 0$ and 76.9 lognormal mocks, respectively with dashed and solid lines. No mitigation is applied to these mocks, and thus the χ^2 values are expected to be unbiased. The χ^2 values observed in the DESI LRG targets are quoted for comparison, and the significance for each measurement is characterized by *p-value* with respect to the $f_{NL} = 0$ mocks without any mitigation applied to them. Before cleaning, our LRG sample has a cross power spectrum χ^2 error of 20014.8. After correction with

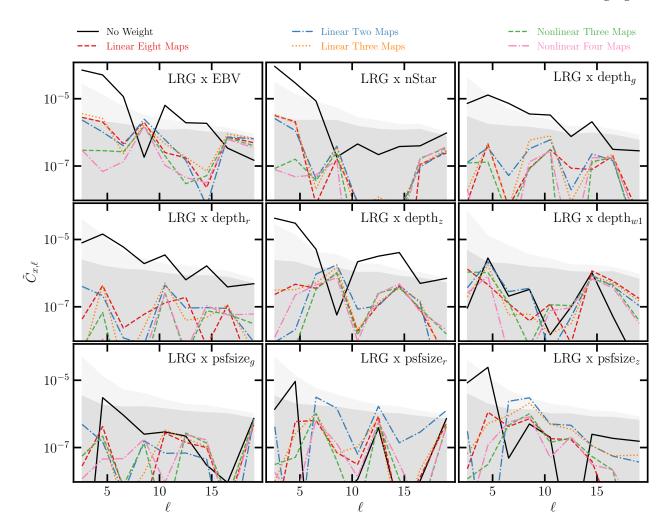


Figure 6. The normalized cross power spectra between the DESI LRG targets and imaging systematic maps: Galactic extinction (EBV), stellar density (nStar), depth in grzw1 (depthgrzw1), and seeing in grz (psfsizegrz). The black curves display the cross spectra before imaging systematic correction. The red, blue and orange curves represent the results after applying the imaging weights from the linear models trained with *eight maps*, *two maps*, and *three maps*. The green and pink curves display the results after applying the imaging weights from the non-linear models trained with *three maps* and *four maps*. The dark and light shades represent the 97.5 percentile from cross correlating the imaging systematic maps and the $f_{NL} = 0$ and 76.9 lognormal density fields, respectively.

the linear two maps approach, the cross spectrum χ^2 is reduced to 690 375.1 with p-value = 0.002. Adding the r-band psfsize, the linear 691 model reduces the χ^2 down to 195.9 with p-value = 0.044; we can 692 reject the null hypothesis that our sample with the linear three maps 693 is properly cleaned at 95% confidence. Even though training the 694 linear model with all imaging systematic maps as input gives the 695 lowest cross spectrum χ^2 of 129.2 (and p-value = 0.239), it potentially makes the analysis more prone to over-fitting and regressing 697 out the true clustering signal, given the inner correlations among the imaging properties (Figure 3). As an alternative, we apply the 699 imaging weights from the non-linear method with the extinction, z- 700 band depth, and r-band psfsize maps (non-linear three maps). The 701 cross power spectrum χ^2 is reduced to 79.3 with p-value = 0.594. 702 Adding the stellar density map reduces the cross power spectrum 703 χ^2 error to 70.9 (p-value = 0.687). Our cross power spectrum diagnostic supports the idea that a non-linear cleaning approach is 705 needed to properly regress out the remaining spurious fluctuations. 706 We investigate the test with the cross power spectrum up to higher 707 multipoles but find no evidence of remaining systematic errors (see 708 Appendix A).

Figure 8 (bottom) shows the mean density χ^2 observed in the mocks with or without $f_{\rm NL}$. We find consistent results regardless of the underlying f_{NL} , which supports that our diagnostic is not sensitive to the fiducial cosmology. The values measured in the DESI LRG targets before and after applying imaging weights are quoted for comparison. The linear two maps weights reduce the χ^2 value from 679.8 (before correction) to 178.8. The p-value = 0 indicates severe remaining systematic effects. Adding the r-band psfsize does not reduce the p-value enough (e.g., greater than 0.05) even though the cleaning method yields a lower $\chi^2 = 130$. Training the linear model with all imaging systematic maps returns a more reasonable $\chi^2 = 90$ and p-value of 0.084. However, regression with all imaging systematic maps as input can lead to the removal of the true clustering signal. With the imaging weights from the non-linear three maps approach, we obtain a χ^2 value of 74.3 with p-value = 0.392. Re-training the non-linear approach while adding the stellar density map (non-linear four maps) yields minor improvement: $\chi^2 = 73.2$ and p-value = 0.422. This indicates that the stellar density trend in the mean LRG density can be explained via the extinction map. Ashley: Add something at the end to clarify

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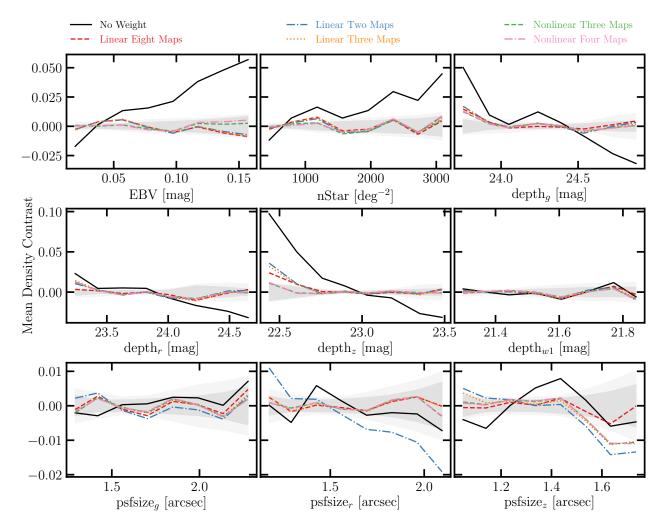


Figure 7. The mean density contrast of the DESI LRG targets as a function of the imaging systematic maps: Galactic extinction (EBV), stellar density (nStar), depth in grzw1 (depthgrzw1), and seeing in grz (psfsizegrz). The black curves display the results before imaging systematic correction. The red, blue and orange curves represent the relationships after applying the imaging weights from the linear models trained with *eight maps*, *two maps*, and *three maps*. The green and pink curves display the results after applying the imaging weights from the non-linear models trained with *three maps* and *four maps*. The dark and light shades represent the 68% dispersion of 1000 lognormal mocks with $f_{NL} = 0$ and 76.92, respectively.

the reason that the extinction map can cause the stellar density trend is that they are strongly correlated.

Ashley: I would maybe add a new subsubsection (but at least a new paragraph) to summarize the results of the subsection, as they are quite important. This is also where I would discuss the tests that were done prior to looking at the data Cell. The discussion would basically provide a strong justification for the 3 map case being the fiducial case and point out that this was decided prior to seeing the data results. (Some of the words you wrote at the beginning of section 3.5 would go instead in this summary.)

3.5 Calibration of mitigation bias

Santi: How all of this was computed did not seem very clear to 732 me. It seems that this part is what later determines that fnl!=0 from 733 the data. So I think it would be worth explaining it more. Ashley: I 734 would find a way to *strongly* emphasize that the result does not 735 depend at all on how the mocks were contaminated. Perhaps just a 736 concluding sentence or two in its own paragraph along the lines The 737 template-based mitigation of imaging systematics removes some of 738

Table 2. Linear parameters employed to de-bias the $f_{\rm NL}$ constraints to account for the over-correction issue. Ashley: You could also add the m1/m2 to the table for the clean mock case?

Cleaning Method	m_1	m_2
Non-linear Three Maps	1.17	13.95
Non-linear Four Maps	1.32	26.97
Non-linear Nine Maps	2.35	63.5

the true clustering signal, and the amount of the removed signal increases as more maps are fed to the regression. Supported by our remaining systematic test, *non-linear three maps* is therefore chosen as our default approach and is applied to the mocks (with and without contaminations) to calibrate the $f_{\rm NL}$ biases induced by over-correction. Below we describe an approach for the calibration and de-biasing of our $f_{\rm NL}$ constraints.

To calibrate for over-correction, we utilize our series of lognormal density fields with and without PNG, with and without systematic effects. The contamination model is based on the linear multivariate approach with the extinction, z-band depth, and

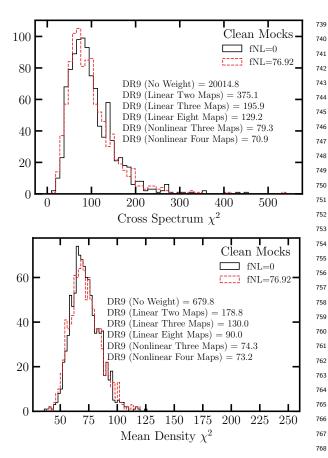


Figure 8. The remaining systematic error χ^2 from the galaxy-imaging cross power spectrum (top) and the mean galaxy density contrast (bottom). The values observed in the DESI LRG targets before and after linear and nonlinear treatments are quoted, and the histograms are constructed from 1000 realizations of clean lognormal mocks with $f_{\rm NL}=0$ and 76.92. Alex: can you show the DR9 chi2s as vertical lines rather than as text? Ashley: I think you could add one vertical dashed and/or dotted line to show the result for the Nonlinear 3 maps, which is what we adopt as the fiducial case.

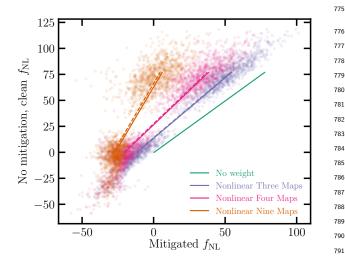


Figure 9. The *No mitigated, clean* vs *mitigated* f_{NL} values from the $f_{NL} = 0$ and 76.9 mocks. The solid (dashed) lines represent the best-fitting estimates from fitting the mean power spectrum of the clean (contaminated) mocks. The scatter points show the best-fitting estimates from fitting the individual spectra for the clean mocks.

r-band psfsize maps as input and parameters drawn from the likelihood constrained by the DESI LRG targets. The idea is to simulate systematic effects that reflect spurious fluctuations as realistic as the DESI LRG targets. For correction, the neural network model is trained and applied to the simulations with various sets of imaging systematic maps as input. Particularly, we consider non-linear three maps, non-linear four maps, and non-linear nine maps. We fit both the mean power spectrum and each individual power spectrum of 1000 realizations. The best-fitting estimates from the mocks without systematics (and no mitigation applied) are considered as the true $f_{\rm NL}$ values and the estimates from the mocks (with the mitigation procedure applied) are considered as the measured f_{NL} values. Figure 9 shows the best-fitting estimates of f_{NL} before mitigation vs the best-fitting $f_{\rm NL}$ estimates after mitigation from the mean power spectrum (solid lines) and individual spectra (points) for the mocks without systematics. The dashed lines represent the best-fitting estimates from the contaminated realizations. The best-fitting estimates for the individual contaminated mocks are not shown for visual clar-

Then, a pair of linear parameters are found to transform the $f_{\rm NL}$ values after mitigation to those before mitigation, $f_{\rm NL,no\ mitigation,clean} = m_1 f_{\rm NL,mitigated} + m_2$. These m_1 and m_2 coefficients for non-linear three, four, and nine maps are summarized in Table 2. The uncertainty in $f_{\rm NL}$ increases by m_1 – 1. We find that m_1 – 1 determines the added uncertainty in the $f_{\rm NL}$ constraints, once the correction coefficients are applied. We expect this effect to be maximum for *non-linear nine maps* and minimum for *non-linear three maps*, as the effect of over-correction is more significant when the number of imaging systematics maps as input to the neural network increases.

Emphasize that the mitigation bias or over-correction effect is the same regardless of the mocks being contaminated or not. Ashley: It is important to note that we find nearly identical results for the mitigation bias whether or not the mocks have any contamination. This can be seen by observing the solid and dashed curves displayed on Fig. 9

4 RESULTS

This section presents our f_{NL} constraints from the DESI LRG targets. The analysis is not carried out blindly. However, the cleaning methods are decided only based on the cross power spectrum and mean density contrast statistics. Alex: Might be nice to have a table listing all cleaning methods used-since there are more than just the 3 map combinations in 2.1.2 Edmond: Fig12: DESI is : you compute the Cl on all the footprint? it is not a combination of the independent measurement of the three regions? same remark for the other figures/tabs. Ashley: explain how the data is combined. Ashley: I think text on blinding could be more like "Our fiducial choice of the 3 map method and robustness tests on (list whatever would make sense at this point) were applied to the data to obtain fNL constraints with no mitigation bias correction and first without revealing the fNL values of the posterior likelihoods (only their relative shifts). After we chose the 3 map method as our fiducial method, we applied further robustness tests and derived the mitigation bias correction."

4.1 DESI imaging LRG sample

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Figure 10 shows the measured power spectrum of the DESI LRG targets before and after applying imaging weights and the best-fitting

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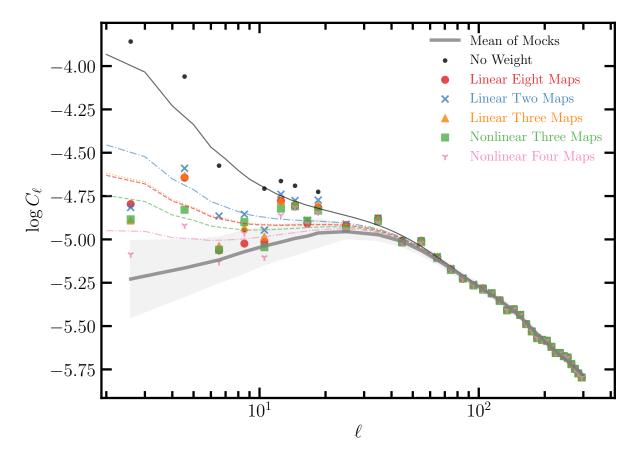


Figure 10. The angular power spectrum of the DESI LRG targets before (No weight) and after correcting for imaging systematics using the linear and non-linear methods with their corresponding best-fitting theory curves. The solid curve and grey shade respectively represent the mean power spectrum and 68% error from the $f_{\rm NL} = 0$ mocks.

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theory curves. The solid line and the grey shade represent respec- 819 tively the mean power spectrum and 1σ error, estimated from the $f_{\rm NL} = 0$ lognormal simulations. The differences between various cleaning methods are significant on large scales ($\ell > 20$), but the small scale clustering measurements are consistent. By comparing linear two maps to linear three maps, we find that the measured clustering power on modes with $6 \le \ell < 10$ are noticeably different between the two methods. We associate the differences to the additional map for psfsize in the r-band, which is included in linear three maps. On other scales, the differences between linear three maps and linear eight maps are negligible, supporting 825 the idea that our feature selection procedure has been effective in identifying the primary maps which cause the large-scale excess clustering signal. Comparing non-linear three maps to linear three maps, we find that the measured spectra on $4 \le \ell < 6$ are very different, probably indicating some non-linear spurious fluctuations with large scale characteristics due to extinction. Including stellar density in the non-linear approach (non-linear four maps) further reduces the excess power relative to the mock power spectrum, in particular on modes between $2 \le \ell < 4$. However, when calibrated on the lognormal simulations, we find that these differences are reversed after accounting for over-correction. Therefore, we associate the subtraction after *nStar* to over fitting.

4.1.1 Calibrated constraints

All f_{NL} constraints presented here are calibrated for the effect of over correction using the lognormal simulations. Table 3 describes the best-fitting and marginalized mean estimates of f_{NL} from fitting the power spectrum of the DESI LRG targets before and after cleaning with the non-linear approach given various combinations for the imaging systematic maps. Figure 11 shows the marginalized probability distribution for f_{NL} in the top panel, and the 68% and 95% probability contours for the linear bias parameter and f_{NL} in the bottom panel, from our sample before and after applying various corrections for imaging systematics. Overall, we find the maximum likelihood estimates to be consistent among the various cleaning methods. We obtain $36.08(25.03) < f_{NL} < 61.44(75.64)$ with $\chi^2 = 34.6$ for nonlinear three maps over 34 degrees of freedom. Accounted for overcorrection, we obtain $36.88(24.87) < f_{NL} < 63.31(77.78)$ with $\chi^2 = 35.2$ with the additional stellar density map in the non-linear four maps. With or without nStar, the confidence intervals are consistent with each other and more than 3σ off from zero PNG. Cleaning the sample with non-linear nine maps weakens our constraints to $13.10(-15.96) < f_{NL} < 69.14(91.84)$ with $\chi^2 = 39.5$. For comparison, we obtain $98.14(83.51) < f_{NL} < 132.89(151.59)$ at 68%(95%) confidence with $\chi^2 = 44.4$ for the *no weight* approach.

Table 3. The calibrated best-fitting, marginalized mean, and marginalized 68% (95%) confidence estimates for f_{NL} from fitting the power spectrum of the DESI LRG targets before and after correcting for imaging systematic effects.

	$f_{ m NL}$					
Footprint	Method	Best fit	Mean	68% CL	95% CL	χ^2/dof
DESI	No Weight	113.18	115.49	98.14 < f _{NL} < 132.89	83.51 < f _{NL} < 151.59	44.4/34
DESI	Nonlinear Three Maps	47.38	48.81	$36.08 < f_{\rm NL} < 61.44$	$25.03 < f_{\rm NL} < 75.64$	34.6/34
DESI	Nonlinear Four Maps	48.92	50.10	$36.88 < f_{NL} < 63.31$	$24.87 < f_{\rm NL} < 77.78$	35.2/34
DESI	Nonlinear Nine Maps	49.69	41.91	$13.10 < f_{\rm NL} < 69.14$	$-15.96 < f_{NL} < 91.84$	39.5/34

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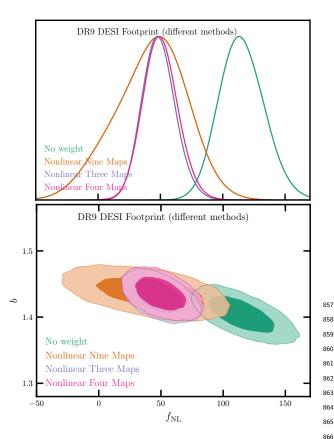


Figure 11. The calibrated constrains from the DESI LRG targets. *Top*: probability distribution for $f_{\rm NL}$ marginalized over the shotnoise and bias. *Bottom*: 68% and 95% probability distribution contours for the bias and $f_{\rm NL}$ from the DESI LRG targets before and after applying non-linear cleaning methods. The lognormal mocks are used to calibrate these distributions for over correction.

4.1.2 Uncalibrated constraints: robustness tests

Alex: I may have missed this—but do you ever quote the marginalized fnl constraints without mitigation bias (corresponding to Fig. 876 12)? I think they should probably be in a table and commented on 877 in the text. 878

Figure 12 shows the probability distributions of $f_{\rm NL}$ for various treatments before accounting for the over-correction effect. The method with the largest flexibility and more number of imaging systematic maps is more likely to regress out the clustering signal and return biased $f_{\rm NL}$ constraints. As expected, non-linear maps yields a smaller maximum likelihood estimate of $f_{\rm NL}$. Our non-linear three maps returns a best-fitting estimate of $f_{\rm NL} = 26$ with the 68%(95%) confidence of $19(9) < f_{\rm NL} < 41(53)$ and $\chi^2 = 34.6$. With the stellar density map included, non-linear four maps yields a smaller best-fitting estimates of $f_{\rm NL} = 17$ with the

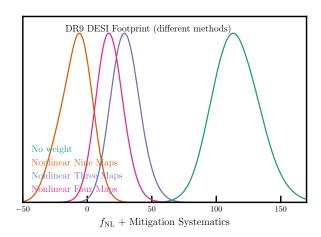


Figure 12. Same as Figure 11 but without accouting for over correction.

error of $7(-2) < f_{\rm NL} < 27(38)$. The non-linear nine maps gives an asymetric posterior with the marginalized mean $f_{\rm NL} = -9$, best estimate $f_{\rm NL} = -6$ with the error of $-21(-34) < f_{\rm NL} < 2.4(12)$.

Now we proceed to perform some robustness tests and assess how sensitive the $f_{\rm NL}$ constraints are to the assumptions made in the analysis or the quality cuts applied to the data. For each case, we retrain the cleaning methods and derive new sets of imaging weights. Accordingly, for the cases where a new survey mask is applied to the data, we re-calculate the covariance matrices using the new survey mask to account for the changes in the survey window and integral constraint effects. Calibrating the mitigation biases for all of these experiments is beyond the scope of this work and redundant, as we are only interested in the relative shift in the $f_{\rm NL}$ constraints after changing the assumptions. Therefore, the absolute scaling of the $f_{\rm NL}$ constraints presented here are biased because of the over correction effect. Table 4 summarizes the uncalibrated $f_{\rm NL}$ constraints from the DESI LRG targets. Our tests are as follows:

- **Linear methods**: We find consistent constraints from *linear eight maps* and *linear three maps*, $26(16) < f_{NL} < 49(62)$ vs $26(16) < f_{NL} < 50(63)$ at 68%(95%) confidence, which suggests that not all of the eight imaging systematic maps are needed to completely mitigate systematic effects. ADD how this compares to nonlinear constraints.
- Imaging regions: We compare how our constraints from fitting the power spectrum of the whole DESI footprint compares to that from the power spectrum of each imaging region individually, namely BASS+MzLS, DECaLS North, and DECaLS South. Figure 13 shows the 68% and 95% probability contours on $f_{\rm NL}$ and b from each individual region, compared with that from DESI. The cleaning method here is *non-linear three maps*, and the covariance matrices are estimated from the $f_{\rm NL}=0$ mocks. Overall, we find that the constraints from all imaging surveys are consis-

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Table 4. The uncalibrated best-fitting and marginalized mean estimates for f_{NL} from fitting the power spectrum of the DESI LRG targets before and after correcting for systematics. The estimates are not calibrated for over correction, and thus are subject to mitigation systematics. The number of degrees of freedom is 34 (37 data points - 3 parameters). The lowest mode is $\ell = 2$ and the covariance matrix is from the $f_{NL} = 0$ clean mocks (no mitigation) except for the case with '+cov' in which the covariance matrix is from the $f_{\rm NL}$ = 76.9 clean mocks (no mitigation).

		$f_{\rm NL}$ + Mitigation Systematics				
Footprint	Method	Best fit	Mean	68% CL	95% CL	χ^2
DESI	No Weight	113.18	115.49	98.14 < f _{NL} < 132.89	83.51 < f _{NL} < 151.59	44.4
DESI	Linear Eight Maps	36.05	37.72	$26.13 < f_{\rm NL} < 49.21$	$16.31 < f_{\rm NL} < 62.31$	41.1
DESI	Linear Two Maps	49.58	51.30	$38.21 < f_{\rm NL} < 64.33$	$27.41 < f_{\rm NL} < 78.91$	38.8
DESI	Linear Three Maps	36.63	38.11	$26.32 < f_{\rm NL} < 49.86$	$16.36 < f_{\rm NL} < 63.12$	39.6
DESI	Nonlinear Three Maps	28.58	29.79	$18.91 < f_{\rm NL} < 40.59$	$9.47 < f_{\rm NL} < 52.73$	34.6
DESI (imag. cut)	Nonlinear Three Maps	29.16	30.57	$19.05 < f_{\rm NL} < 42.18$	$9.01 < f_{\rm NL} < 54.81$	35.8
DESI (comp. cut)	Nonlinear Three Maps	28.07	29.48	$18.38 < f_{\rm NL} < 40.50$	$8.81 < f_{\rm NL} < 53.10$	34.5
DESI	Nonlinear Four Maps	16.63	17.52	$7.51 < f_{\rm NL} < 27.53$	$-1.59 < f_{\rm NL} < 38.49$	35.2
DESI	Nonlinear Nine Maps	-5.87	-9.19	$-21.45 < f_{\rm NL} < 2.40$	$-33.81 < f_{\rm NL} < 12.06$	39.5
DESI	Nonlinear Three Maps+ f_{NL} = 76.92 Cov	31.62	33.11	$20.94 < f_{\rm NL} < 45.24$	$10.56 < f_{\rm NL} < 59.16$	33.5
BASS+MzLS	Nonlinear Three Maps	15.43	19.01	$-1.17 < f_{\rm NL} < 39.43$	$-19.19 < f_{\rm NL} < 63.56$	35.6
BASS+MzLS	Nonlinear Four Maps	13.12	15.39	$-4.59 < f_{\rm NL} < 35.56$	$-24.88 < f_{\rm NL} < 59.31$	34.7
BASS+MzLS	Nonlinear Nine Maps	-3.73	-6.34	$-27.11 < f_{\rm NL} < 13.75$	$-47.44 < f_{\rm NL} < 33.94$	36.8
BASS+MzLS (imag. cut)	Nonlinear Three Maps	25.03	29.12	$6.16 < f_{\rm NL} < 52.44$	$-14.22 < f_{\rm NL} < 80.54$	36.2
BASS+MzLS (comp. cut)	Nonlinear Three Maps	16.99	20.90	$0.26 < f_{\rm NL} < 41.76$	$-18.30 < f_{\rm NL} < 67.12$	35.8
DECaLS North	Nonlinear Three Maps	41.02	44.89	$23.33 < f_{\rm NL} < 66.78$	$4.96 < f_{\rm NL} < 93.02$	41.1
DECaLS North	Nonlinear Four Maps	31.45	34.78	$14.14 < f_{\rm NL} < 55.79$	$-5.81 < f_{\rm NL} < 80.80$	41.2
DECaLS North	Nonlinear Five Maps	55.46	60.44	$36.78 < f_{\rm NL} < 84.05$	$17.86 < f_{\rm NL} < 112.81$	38.4
DECaLS North	Nonlinear Nine Maps	0.81	-5.68	$-29.73 < f_{\rm NL} < 16.71$	$-53.15 < f_{\rm NL} < 36.19$	45.1
DECaLS North (no DEC cut)	Nonlinear Three Maps	41.05	44.82	$23.58 < f_{\rm NL} < 66.08$	$6.40 < f_{\rm NL} < 91.42$	40.7
DECaLS North (imag. cut)	Nonlinear Three Maps	43.27	48.39	$24.60 < f_{\rm NL} < 72.50$	$4.71 < f_{\rm NL} < 101.42$	35.1
DECaLS North (comp. cut)	Nonlinear Three Maps	40.55	44.63	$22.41 < f_{\rm NL} < 67.11$	$3.95 < f_{\rm NL} < 94.06$	41.4
DECaLS South	Nonlinear Three Maps	31.24	33.21	$14.89 < f_{\rm NL} < 52.40$	$-5.11 < f_{\rm NL} < 74.35$	30.2
DECaLS South	Nonlinear Four Maps	14.34	6.28	$-21.19 < f_{\rm NL} < 30.01$	$-53.63 < f_{\rm NL} < 49.51$	31.9
DECaLS South	Nonlinear Five Maps	33.79	37.50	$17.71 < f_{\rm NL} < 57.42$	$-0.31 < f_{\rm NL} < 80.94$	30.8
DECaLS South	Nonlinear Nine Maps	-36.76	-32.01	$-49.38 < f_{\rm NL} < -13.61$	$-65.26 < f_{\rm NL} < 7.52$	31.5
DECaLS South (no DEC cut)	Nonlinear Three Maps	43.79	46.79	$30.16 < f_{\rm NL} < 63.41$	$16.38 < f_{\rm NL} < 82.72$	23.8
DECaLS South (imag. cut)	Nonlinear Three Maps	26.47	23.36	$3.18 < f_{\rm NL} < 47.84$	$-57.69 < f_{\rm NL} < 71.39$	30.0
DECaLS South (comp. cut)	Nonlinear Three Maps	29.62	31.76	$13.00 < f_{\rm NL} < 51.58$	$-9.78 < f_{\rm NL} < 74.28$	29.7

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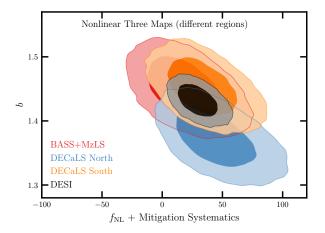


Figure 13. The uncalibrated 2D constraints from the DESI LRG targets for each imaging survey compared with that for the whole DESI footprint. The dark and light shades represent the 68% and 95% confidence intervals, respectively. Edmond: maybe comment why the bias is lower in Decalsnorth? Have you a physical explanation?

tent with each other and DESI within 68% confidence. Ignoring the 916 over-correction effect, both BASS+MzLS and DECaLS South yield 917 constraints consistent with $f_{\rm NL}=0$ within 95%, but DECaLS North 918 deviates from zero PNG at more than 2σ . This motivates follow-up 919 studies with the spectroscopic sample of LRGs in DECaLS North. 920

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Edmond: maybe comment why the bias is lower in Decals-north? Have you a physical explanation? Ashley: The statement about DE-CaLS north being the region with the most significantly non-zero fNL was a little confusing. I would re-write to something like: "Ignoring the over-correction effect, we find that the results from the DECaLS North region to be the only one that finds PNG nonzero at greater than 95%.'

- Stellar density template (nStar): Adding the stellar density template (non-linear four maps) does not change the constraints from BASS+MzLS much, but it shifts the f_{NL} distributions to lower values in DECaLS North and DECaLS South by 0.5σ and σ , respectively, reconciling all constraints with $f_{\rm NL} = 0$. We note that differences are more significant when all nine maps are used as input. This is somewhat expected as cleaning the data with more imaging systematic maps is more prone to the over-correction issue. We find that the shifts in f_{NL} from adding *nStar* are reveresed after accounting for the over correction effect. Comparing the $f_{\rm NL}$ constraints from non-linear four maps and non-linear three maps in Table 3 to those in 4, we can argue that the f_{NL} shifts after adding nStar are probably caused by the over-correction issue from the chance correlations between the stellar density map and large-scale structure. Ashley: When not accounting for mitigation bias, adding the stellar density map appears to result in significant changes, but these changes go away when we account for the mitigation bias and we find all methods recover the same maximum likelihood estimate for fNL to within XX
- Pixel completeness (comp. cut): We discard pixels with frac-

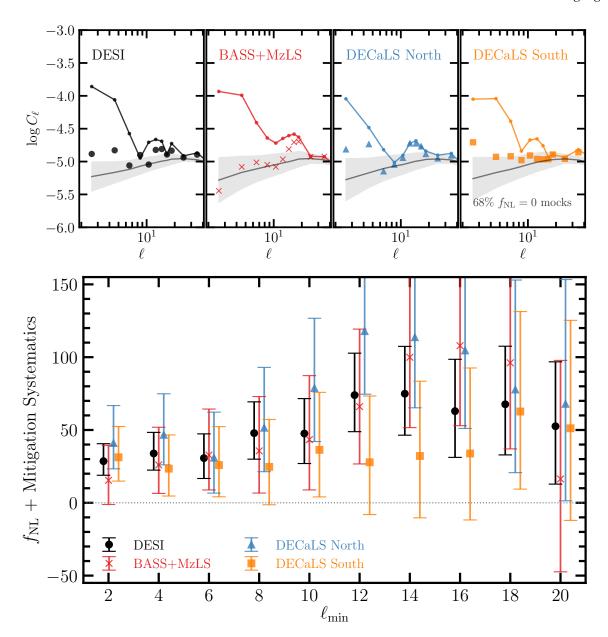


Figure 14. Top: The measured power spectrum of the DESI LRG targets before (solid curves) and after non-linear three maps (scatter points) for the DESI, BASS+MzLS, DECaLS North, and DECaLS South regions. Bottom: The uncalibrated f_{NL} constraints vs the lowest ℓ mode used for fitting f_{NL} . The points represent marginalized mean estimates of f_{NL} and error bars represent 68% confidence estimated from the $f_{NL} = 0$ mocks. The scaling of f_{NL} is not calibrated to account for over correction caused by mitigation.

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tional completeness less than half to assess the effect of partially 934 complete pixels on f_{NL} . This cut removes 0.6% of the survey area, and no changes in the f_{NL} constraints are observed.

937 • Imaging quality (imag. cut): Pixels with poor photometry are 938 removed from our sample by applying the following cuts on imaging; E[B-V] < 0.1, nStar < 3000, $depth_g > 23.2$, $depth_r > 22.6$, $depth_z > 22.5$, $psfsize_g < 2.5$, $psfsize_r < 2.5$, and $psfsize_z < 2$. Although these cuts remove 8% of the survey mask, there is a 939 940 negligible impact on the best-fitting $f_{\rm NL}$ from fitting the DESI 942 power spectrum. However, when each region is fit individually, the 943 BASS+MzLS constraint shift toward higher values of $f_{
m NL}$ by ap- $_{
m 944}$ proximately $\Delta f_{\rm NL} \sim 10$, whereas the constraints from DECaLS 945 North and DECaLS South do not change significantly.

- Covariance matrix (cov): We fit the power spectrum of our sample cleaned with non-linear three maps correction, but use the covariance matrix constructed from the $f_{\rm NL}$ = 76.92 mocks. With the alternative covariance, a 12% increase in the $\sigma f_{\rm NL}$ is observed. We also find that the best-fitting and marginalized mean estimates of f_{NL} increase by 10 – 11%. Overall, we find that the differences are not significant in comparison to the statistical precision.
- External maps (CALIBZ+HI): The neural network five maps correction includes the additional maps for HI and CALIBZ. With this correction, the best-fitting $f_{\rm NL}$ increases from 41.02 to 55.46 for DECaLS North and from 31.24 to 33.79 for DECaLS South, which might suggest that adding HI and CALIBZ increases the input noise,

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and thus negatively impacts the performance of the neural network 1007 model. This test is not performed on BASS+MzLS due to a lack of 1008 coverage from the CALIBZ map. 1009

- Declination mask (no DEC cut): The fiducial mask removes 1010 the disconnected islands in DECaLS North and regions with DEC 1011 <-30 in DECaLS South, where there is a high likelihood of callibration issues as different standard stars are used for photometric 1013 calibrations. We analyze our sample without these cuts, and find that 1014 the best-fitting and marginalized $f_{\rm NL}$ mean estimates from DECaLS 1015 South shift significantly to higher values of $f_{\rm NL}$ by $\Delta f_{\rm NL}\sim10$, 1016 which supports the issue of photometric systematics in the DECaLS 1017 South region below DEC = -30. On the other hand, the constraints 1018 from DECaLS North do not change significantly, indicating the is- 1019 lands do not induce significant contaminations. [Did you try cutting 1020 out more of DECaLS North, such as everything below the equator?] 1021
- Scale dependence (varying ℓ_{\min}): We raise the value of the 1022 lowest harmonic mode ℓ_{\min} used for the likelihood evaluation dur- 1023 ing MCMC. This is equivalent to decreasing the highest scale of 1024 measurement in the power spectrum. By doing so, we anticipate a 1025 reduction in the impact of imaging systematics on $f_{\rm NL}$ inference 1026 as lower ℓ modes are more likely to be contaminated. Figure 14 1027 illustrates the power spectra before and after the correction with 1028 non-linear three maps in the top panel. The bottom panel shows 1029 the marginalized mean and 68% error on $f_{\rm NL}$ with non-linear three 1030 maps for the DESI, BASS+MzLS, DECaLS North, and DECaLS 1031 South regions. ALEX: We find that the mean estimates of f_{NL} 1032 slightly shifts to higher values on scales $12 < \ell < 18$ in DECaLS 1033 North and BASS+MzLS when higher ℓ_{\min} is used. This is the opposite behavior from what one would expect if there were just a giant 1035 systematics induced spike at low ℓ . So it shows that the issue here is 1036 more subtle than what one would have initially suspected. Edmond: 1037 Fig10 / 13: do you have an explanation why there is this remaining 1038 bump at l=10-12? is a correction artefact? you should mention it 1039 in the text and comment the effect since it increase the value of fnl 1040 when you chose higher l_min .

4.2 Summary

In summary, we find that the non-linear methods outperform the linear methods in removing the excess clustering signal on large scales. Adding the stellar density map results in significant changes, however when accounted for the mitigation bias, all methods recover the same maximum likelihood estimate. With calibration on the lognormal mocks, the neural network three maps and four maps approaches show $f_{\rm NL}$ detection at more than 2σ confidence. The most flexible neural network method with nine maps returns a greater associated uncertainty which is consistent with $f_{\rm NL}=0$.

We also run various tests with cuts on the DR9 sample or $_{1051}$ changing the configuration or details of the analysis. Overall, we $_{1052}$ find consistent results across sub imaging surveys within DESI. $_{1053}$ However, our results show that a declination cut at DEC = $_{-30}$ $_{1054}$ is necessary for DECaLS South to avoid potential calibration is- $_{1055}$ sues. Our analysis does not show a statistical demand for including $_{1056}$ external templates for HI and CALIBZ, using a different covari- $_{1057}$ ance matrix, or imposing additional cuts on the DR9 sample based $_{1058}$ on imaging and pixel completeness. We also obtain robust results $_{1059}$ regardless of the largest scale used for constraining $f_{\rm NL}$.

Ashley: I think we need some kind of discussion section for 1061 the results. We should also compare the results to those from other 1062 galaxy/QSO samples and Planck. If we don't have enough for a 1063 whole section, the Conclusions could just become Discussion and 1064 Conclusion. I would start the section something like: "We have 1065

measured the PNG parameter fNL using the angular clustering of an LRG sample selected from DESI imaging data. In our fiducial analysis, we have found nonzero PNG at XX% confidence, with a maximum likelihood value of fNL=XX. We have applied a series of robustness tests on the impact of how we estimate the selection function of our LRG sample, including: the methods (), the set of maps used (), and data quality cuts on the accepted regions. We find no change in the analysis that shifts the maximum likelihood value of fNL to a significantly lower value. The only manner in which the significance of nonzero PNG decreases is due to the uncertainty on the measurement increasing when we employ more maps to the selection function estimation and by doing so remove large-scale clustering information (the effect of which on fNL recovery we have calibrated with mocks).

We compare our fiducial results to recent CMB and QSO measurements. Assess agreement. If we are in reasonable agreement with QSO measurement, what is combined constraint Either we have measured an fNL signal that is inconsistent with CMB measurements or there is a hidden source of systematic contamination in our data. Discuss generic effect of calibration. Ask Rongpu if we can include the Gaia calibration test map, which shows patterns that look related to the Gaia scanning strategy, rather that Legacy Survey? (If not, we can just say something like "internal DESI tests of the photometric calibration are unable to uncover DESI-specific issues, e.g., when comparing to Gaia data") Then, something like "The most significant trends that we find are with the E(B-V) map. The source of such a trend would be a mis-calibration of the E(B-V) map itself or the coefficients applied to obtain Galactic extinction corrected photometry. Such issues are generically likely to be proportional in amplitude to the estimated E(B-V), but may not strictly follow the estimated E(B-V). In order to explain the fNL signal we measure, such an effect would need to be approximately twice that of the trend we find with E(B-V). There are ongoing efforts within DESI to obtain improved Galactic extinction information, which will help discover if this is indeed the cause. (Anything to say about Mudur et al. map? I think we need to write something. Perhaps for now just something like "a first look at the Mudur et al E(B-V) maps did not suggest including them would change our results" and then during CWR you could add Mudur-SFD as a map to test against?)"

5 CONCLUSIONS

We have presented constraints on the local primordial non-Gaussianity parameter $f_{\rm NL}$ from the angular power spectrum of LRGs from the DESI imaging DR9. We infer the redshift distribution of LRGs from early spectroscopy during DESI Survey Validation (Figure 1). Our LRG sample includes more than 14 million targets covering around 18,000 square degrees in the redshift range of 0.2 < z < 1.35. Our analysis utilizes the scale-dependent bias effect that primarily comes from large scales; thus, it is very sensitive to systematic errors caused by photometric calibration issues, survey depth variations, and Milky Way foregrounds (Figure 2).

We use the FFTLog algorithm to model the angular clustering on large scales or multipoles as low as $\ell=2$ (Figure 4). We simulate lognormal density fields with DESI-like LRG angular and redshift distributions to validate the pipeline, estimate covariance matrices, and characterize remaining systematic errors. Our mock test reveals that the distribution of power spectra on large scales is asymmetric (Figure 5). We demonstrate our likelihood inference benefits from fitting the log transformation of the power spectrum.

Multivariate linear and neural network-based regression mod-

els are applied to regress out spurious fluctuations in the LRG density field against various maps for the extinction, survey depth, astronomical seeing, neutral hydrogen column density, and stellar density. Feature selection uses the Pearson correlation and the Spearman correlation coefficients to reduce the likelihood of overcorrection, i.e., removing the clustering signal (Figure 3). The LRG density map is cross-correlated against the imaging systematic maps (Figure 6), and the mean LRG density is calculated for different regions with similar imaging to look for systematic trends in the mean density (Figure 7). Using the mean density and cross-power spectrum diagnostics, we quantify the remaining systematics against lognormal simulations (Figure 8). We identify the extinction, zband depth, and r-band seeing as the primary sources of systematic error. Our simulation-based tests reveal that the DESI LRG targets cleaned with linear three maps suffers from significant remaining systematic error primarily due to depth variations. We observe that the non-linear mitigation approach reduces the excess clustering signal more effectively.

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We apply our cleaning methods to the lognormal mocks with and without PNG, with and without systematic effects, to calibrate the level of mitigation biases introduced in our constraints (Table 2 and Figure 9). With three maps, we obtain best-fitting estimates which are inconsistent with zero at more than 95% confidence. Adding local stellar density to the list of maps used for cleaning the LRG sample does not influence the constraints. However, using the combination of all imaging systematic maps and stellar density yields an asymmetric likelihood distribution with larger uncertainty and consistent with $f_{NL} = 0$ at 95% confidence (Table 3). This is interesting as the same covariance matrix is used for all; but we find that the *non-linear nine maps* approach introduces a larger bias by having a larger multiplicative parameter, m_1 , Table 2. Overall, our non-linear cleaning methods return consistent best-fitting estimates of $f_{\rm NL} \sim 47-50$ (Figure 11). We run multiple robustness tests but find no significant changes other than that there is spurious correlation against stellar density in the NGC and potential calibration issues in the SGC below DEC< -30 (Table 4). Our constraints are consistent with each other when each imaging region is fit separately and/or the lowest mode used is increased (Figure 13 and Figure 14). Assuming Planck's measurement of f_{NL} is accurate a priori, our results indicate some unknown systematic effects. Santi: Potentially, this could also indicate a more complicated type of PNG (scale dependent, beyond quadratic fnl, non-local...) I would also discuss possible implications from assuming a different cosmology. Our results also suggest follow-up investigations of stellar contamination and depth-related variations in the spectroscopic sample of DESI LRGs. Hui: cite LRG redshift success rate, stellar contamination rate. Noting possible improvements when we have all spectra data available. On the other hand, calibrating simulations for the over correction effect might not be feasible for DESI spectroscopy. So, a simulation-based forward-model approach for estimating the imaging weights can become helpful to reduce the dimensionality of the imaging parameter space. We leave the idea of combining the forward-modeling and backward-modeling cleaning approaches to future work.

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DATA AVAILABILITY

The DR9 catalogues from the DESI Legacy Imaging Surveys are publicly available at https://www.legacysurvey.org/dr9/. The software used for cleaning the imaging data is available at https://github.com/mehdirezaie/sysnetdev. The lognormal mock catalogs can be made available upon reasonable request.

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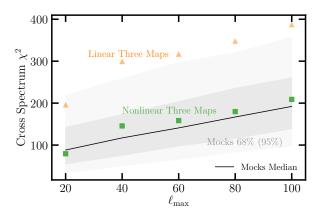


Figure A1. The cross power spectrum χ^2 between the LRG density and imaging systematic maps as a function of the highest mode $\ell_{\rm max}$ when the sample is cleaned with the linear (triangles) and non-linear (squares) three maps. The lowest mode is fixed at $\ell_{\rm min}=2$. The solid curve and dark (light) shade represent the median value and 68% (95%) confidence regions, estimated from the $f_{\rm NL}=0$ mocks.

APPENDIX A: SCALE DEPENDENT SYSTEMATICS

We investigate the dependence of statistical significance for the cross power spectrum χ^2 between the DESI LRG targets and imaging maps. We extend the highest harmonic mode from $\ell=20$ to 100, which corresponds to density fluctuations on scales below 2 degrees. As shown in Figure A1, the solid line represents the median of the cross power spectrum χ^2 measured from the $f_{\rm NL}=0$ mocks as a function of highest mode, $\ell_{\rm max}$ increases from 20 to 100. The red circles and blue crosses show the chi2 values for our sample cleaned respectively with the linear and neural network approaches, both with *three maps*. This test supports that our cross spectrum χ^2 values are stable.

APPENDIX B: LOGNORMAL MOCKS

Corner plots of the PNG parameter $f_{\rm NL}$ and bias coefficient are shown in Fig. B1 for fitting the mean power spectrum of mocks, with and without $f_{\rm NL}$. The best-fitting estimates, marginalized mean, 1σ and 2σ confidence intervals are summarized in Tab. B1. Fig B1 (right) shows confidence contours for different combinations of target variable (e.g., either power spectrum or its log transform) and covariance matrix. First we attempt to understand the impact of covariance on confidence intervals. We fit the mean power spectrum of $f_{\rm NL}$ = 76.9 mocks or its log transformation using covariance matrices constructed from the same set of mocks or from the $f_{\rm NL} = 0$ mocks. When covariance is consistent with mean, the difference between fitting power spectrum and log of it is only 2%. If a wrong covariance is used for the log power, the effect is only 7%. However, when mean power spectrum of the $f_{\rm NL}$ = 76.9 mocks is fit using the covariance matrix estimated from the $f_{\rm NL} = 0$ mocks, the constraints improve by a factor of 5, simply due to a false higher signal to noise ratio. Therefore, we argue that fitting logarithm of power spectrum would remove the need for having f_{NL} -dependent covariance matrices and make the constraints less sensitive to covariance construction. Fig. B1 shows the confidence contours for $f_{\rm NL}$ = 0 mocks when fit is done to the log of mean spectra of $f_{\rm NL} = 0$ mocks for the different regions. We find that the underlying true $f_{\rm NL}$ value is recovered within 2σ confidence. Add a paragraph for the constraining power vs fsky.

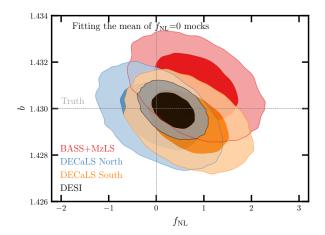


Figure B1. 68% and 95% confidence contours from the mean power spectrum of the $f_{\rm NL}=0$ mocks for the DESI footprint and sub-imaging surveys. The truth values are represented by vertical and horizontal lines.

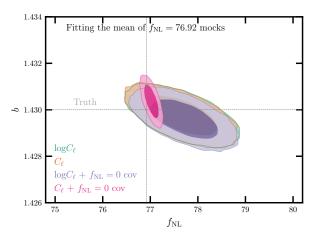


Figure B2. 68% and 95% confidence contours of fitting the mean power spectrum or its log transformation from the $f_{\rm NL}=76.92$ mocks for the DESI footprint. Using the log C_ℓ fitting yield constraints that are insensitive to the covariance used. The truth values are represented by vertical and horizontal lines.

Fig B3 shows the best-fitting estimates for b vs $f_{\rm NL}$ for $f_{\rm NL}=0$ and = 76.92 mocks in the left and right, respectively. Truth values are represented via the dotted lines. The points are color-coded with the minimum χ^2 from fit for each realization. The histograms of best-fitting $f_{\rm NL}$ estimates are plotted in the background.

Table B1. best-fitting and marginalized mean estimates for f_{NL} from fitting the mean power spectrum of the mocks. Degree of freedom is 34 (37 data points - 3 parameters).

					$f_{ m NL}$		
Mock / f_{NL}	Footprint	Observable	Best fit	Mean	68% CL	95% CL	χ^2
Clean 76.92	DESI	$\log C_{\ell}$	77.67	77.67	$77.17 < f_{\rm NL} < 78.16$	$76.71 < f_{\rm NL} < 78.64$	38.8
Clean 76.92	DESI	C_ℓ	77.67	77.65	$77.17 < f_{\rm NL} < 78.14$	$76.70 < f_{\rm NL} < 78.60$	39.0
Clean 76.92	DESI	$\log C_{\ell} + f_{\rm NL} = 0 \text{cov}$	77.70	77.71	$77.25 < f_{\rm NL} < 78.17$	$76.81 < f_{\rm NL} < 78.63$	39.9
Clean 76.92	DESI	$C_{\ell} + f_{\rm NL} = 0 {\rm cov}$	77.03	77.02	$76.93 < f_{\rm NL} < 77.12$	$76.83 < f_{\rm NL} < 77.22$	207.6
Clean 0	DESI	$\log C_{\ell}$	0.36	0.36	$0.06 < f_{\rm NL} < 0.65$	$-0.23 < f_{\rm NL} < 0.94$	35.7
Clean 0	BASS+MzLS	$\log C_\ell$	0.83	0.82	$0.25 < f_{\rm NL} < 1.40$	$-0.31 < f_{\rm NL} < 1.96$	39.4
Clean 0	DECaLS North	$\log C_\ell$	0.07	0.06	$-0.47 < f_{\rm NL} < 0.60$	$-1.00 < f_{\rm NL} < 1.12$	26.7
Clean 0	DECaLS South	$\log C_\ell$	0.67	0.67	$0.13 < f_{\rm NL} < 1.22$	$-0.40 < f_{\rm NL} < 1.75$	34.3

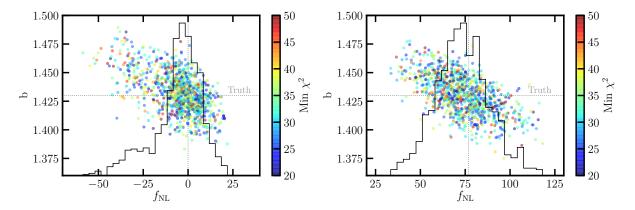


Figure B3. best-fitting estimates from fitting 1000 lognormal mocks with $f_{NL} = 0$ (left) and 76.92 (right) in the DESI footprint. The truth values are represented by vertical and horizontal lines. The truth values are represented by vertical and horizontal lines. up and down figures?

Table B2. best-fitting and marginalized estimates for f_{NL} from fitting the mean power spectrum of the mocks before and after corrections using the non-linear approach with various combinations of the imaging systematic maps. The estimates are not accounted for over correction, and therefore are subject to mitigation systematics.

		$f_{\rm NL}$ + Mitigation Systematics				
Mock / $f_{\rm NL}$	Method	Best fit	Mean	68% CL	95% CL	χ^2
Clean 0	No Weight	0.36	0.36	$0.06 < f_{\rm NL} < 0.65$	$-0.23 < f_{\rm NL} < 0.94$	35.7
Clean 0	Three Maps	-11.64	-11.65	$-12.00 < f_{\rm NL} < -11.30$	$-12.34 < f_{\rm NL} < -10.97$	86.8
Clean 0	Four Maps	-20.14	-20.13	$-20.44 < f_{\rm NL} < -19.82$	$-20.74 < f_{\rm NL} < -19.52$	472.8
Clean 0	Nine Maps	-26.91	-26.92	$-27.16 < f_{\rm NL} < -26.68$	$-27.39 < f_{\rm NL} < -26.46$	5481.0
Contaminated 0	Three Maps	-12.12	-12.13	$-12.48 < f_{\rm NL} < -11.78$	$-12.83 < f_{\rm NL} < -11.44$	94.0
Contaminated 0	Four Maps	-20.97	-20.98	$-21.28 < f_{\rm NL} < -20.67$	$-21.58 < f_{\rm NL} < -20.37$	556.3
Contaminated 0	Nine Maps	-28.13	-28.13	$-28.36 < f_{\rm NL} < -27.90$	$-28.59 < f_{\rm NL} < -27.67$	6760.5
Clean 76.92	No Weight	77.67	77.67	$77.17 < f_{\rm NL} < 78.16$	$76.71 < f_{\rm NL} < 78.64$	38.8
Clean 76.92	Three Maps	54.57	54.57	$54.14 < f_{\rm NL} < 55.01$	$53.72 < f_{\rm NL} < 55.45$	603.5
Clean 76.92	Four Maps	38.38	38.38	$37.99 < f_{\rm NL} < 38.78$	$37.60 < f_{\rm NL} < 39.16$	537.0
Clean 76.92	Nine Maps	6.04	6.04	$5.72 < f_{\rm NL} < 6.36$	$5.41 < f_{\rm NL} < 6.67$	694.0
Contaminated 76.92	Three Maps	54.01	54.00	$53.57 < f_{\rm NL} < 54.44$	$53.15 < f_{\rm NL} < 54.86$	588.0
Contaminated 76.92	Four Maps	37.48	37.49	$37.09 < f_{\rm NL} < 37.88$	$36.70 < f_{\rm NL} < 38.27$	510.7
Contaminated 76.92	Nine Maps	4.59	4.58	$4.26 < f_{\rm NL} < 4.90$	$3.95 < f_{\rm NL} < 5.22$	649.7

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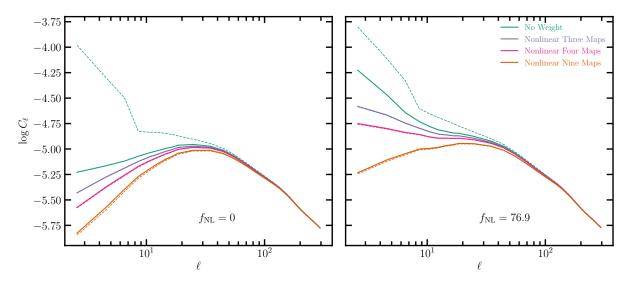


Figure B4. The mean power spectrum of the $f_{\rm NL}=0$ and 76.9 mocks with (dashed) and without (solid) imaging systematics before ('No Weight') and after applying the non-linear cleaning method with three, four, and nine maps.

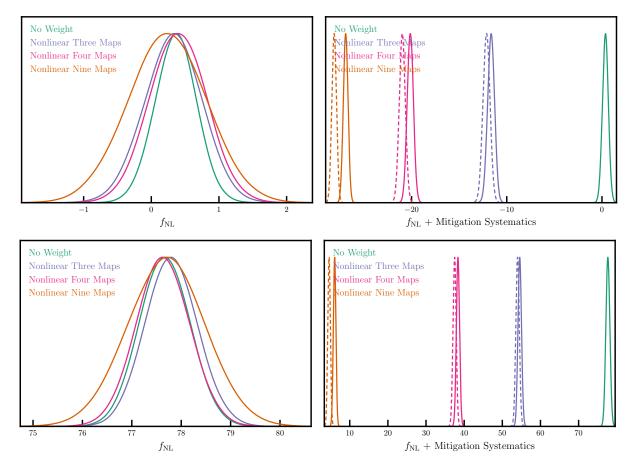


Figure B5. Probability distributions of f_{NL} from the mean power spectrum of the $f_{NL} = 0$ (top) and $f_{NL} = 76.9$ (bottom) mocks before and after mitigation with the non-linear methods using three, four, and nine maps. Left: The posteriors are adjusted to account for the over correction effect. Right: The posteriors are subject to the over correction effect, and thus the scaling of f_{NL} values is biased due to mitigation.

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