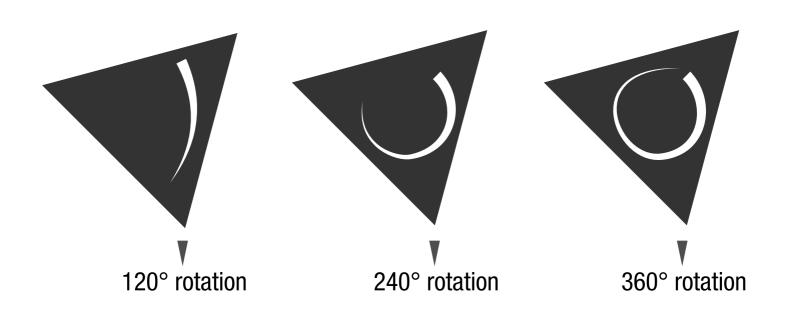
## Symmetry in Dynamical System Networks

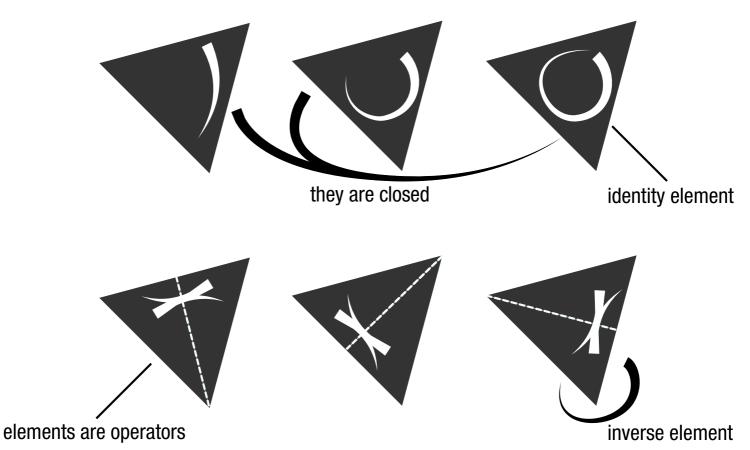
Mehmet Ali Anıl

## Symmetry is immunity to a possible change

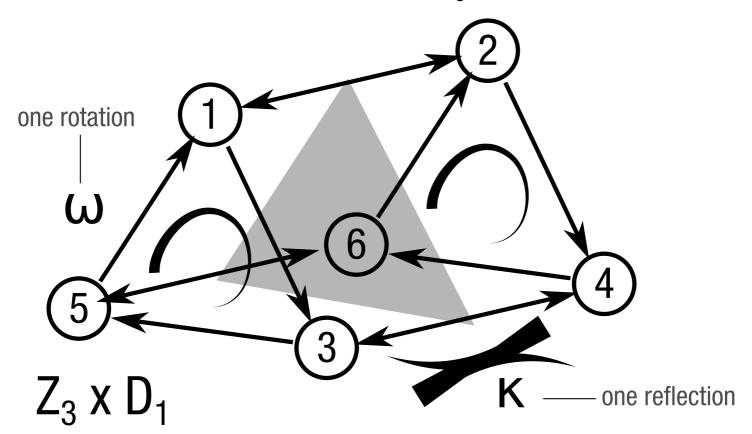


Cyclic **~**Z<sub>3</sub>

### Symmetry operations form a group



## Networks can have symmetries



$$G = \{e, \omega, \omega^2, \kappa, \kappa\omega, \kappa\omega^2\}$$

Homorphism is a structure preserving mapping with a twist

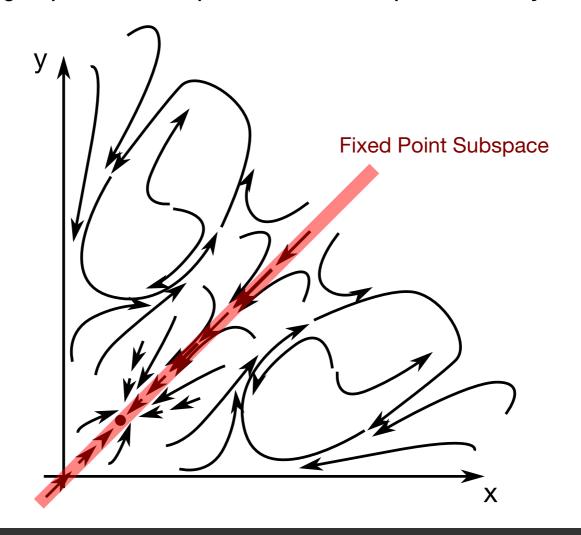
$$G = \{ \underbrace{e , \omega , \omega^{2}}_{q}, \underbrace{\kappa , \kappa \omega , \kappa \omega^{2}}_{q} \}$$

$$G' = \{ \underbrace{e' , k'}_{lm(\phi)}, \dots \}$$

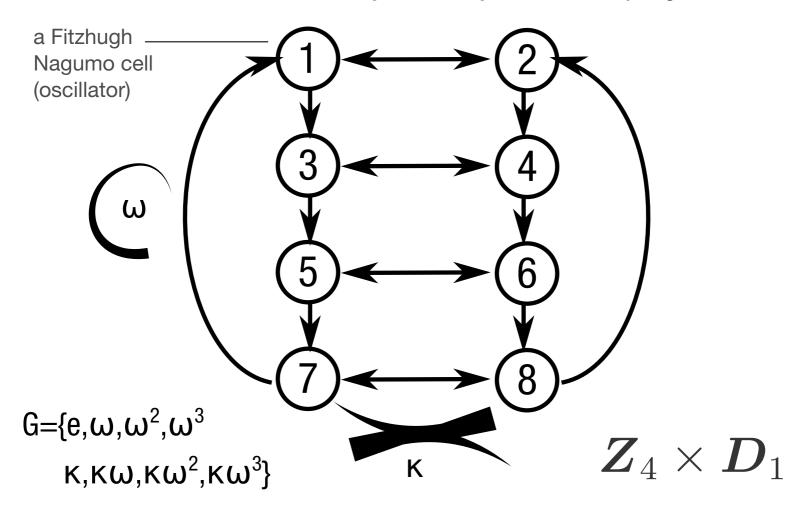
 $\gamma$  is a symmetry of a Dynamical System if it preserves all solutions to  $\dot{x}(t) = f(x)$ 

$$\dot{x}(t)=f(x)$$
 
$$\gamma\frac{\partial}{\partial t}x(t)=\frac{\partial}{\partial t}\gamma x(t)=f(\gamma x)$$
 equivariance condition

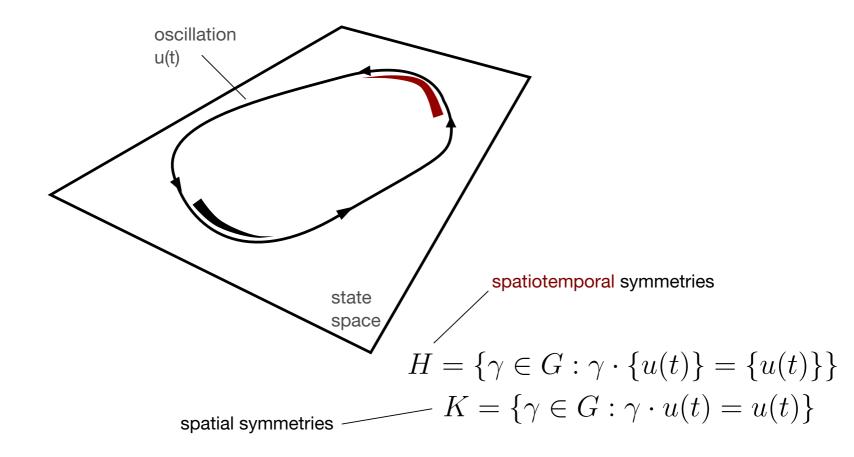
A symmetry group fixes a subspace of the state space of the system



#### A neural network may have a symmetric coupling

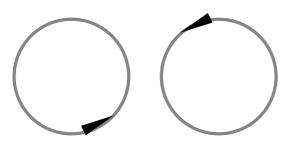


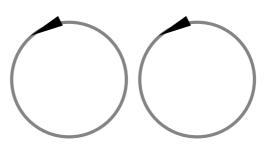
### A symmetric network of oscillators will have two kinds of symmetries



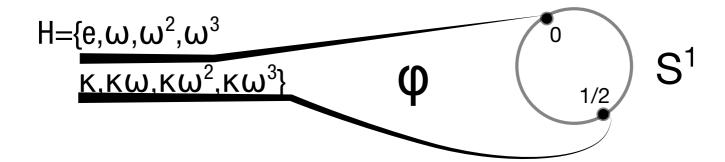
# A phase difference between symetrically coupled oscillators arise from a homomorphism

$$H = \{\gamma \in G : \gamma \cdot \{u(t)\} = \{u(t)\}\}$$





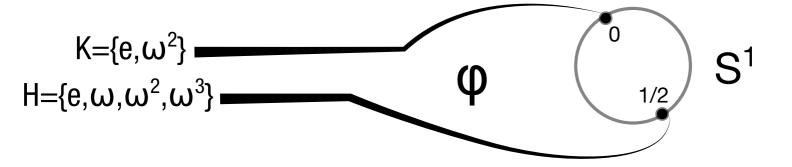
$$K = \{ \gamma \in G : \gamma \cdot u(t) = u(t) \}$$



#### **First Isomorphism Theorem**

The image of  $\varphi$ , Im( $\varphi$ ) is isomorphic to the closed quotient group H/K.

$$\begin{split} & \text{H=}\{\text{e},\omega,\omega^2,\omega^3\} \\ & \text{K=}\{\text{e},\omega^2\} \\ & \text{H / K=}\{\text{e}.\{\text{e},\omega^2\},\omega.\{\text{e},\omega^2\},\omega^2.\{\text{e},\omega^2\},\omega^3\{\text{e},\omega^2\}\} \\ & \text{H / K=}\{\{\text{e},\omega^2\},\{\omega,\omega^3\},\{\omega^2,\text{e}\},\{\omega^3,\omega\}\} \\ & = \!\! \{\{\text{e},\omega2\},\!\{\omega,\omega3\}\} \cong \mathbf{Z}_2 \end{split}$$



## Numerical simulations also confirm the presence of such solutions $H=\{e,\omega,\omega^2,\omega^3\}$ $K=\{e,\omega^2\}$

