

Zain Merchant

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Experience

NASA Langley Research Center

Hampton, VA

Computer Engineer — Flight Software Systems Branch

January 2020 — Current

- Support the design, development, and testing of embedded software for satellites and scientific instruments.
- Lead the development of a high fidelity simulator for the Navigation Doppler Lidar instrument. The simulator aided in the creation and verification of ground software, and was shipped to external partners for use in hardware-in-the-loop testing. Received the agency's *Superior Accomplishment Award* for the project based on feedback from users.
- Implemented flight software modules for interfacing with various peripherals (cryocooler, lidar, Iridium modem, sensors, etc.) over protocols such as SPI, I2C, UART, Ethernet, TCP/IP, and SpaceWire on ARM and RISC-V architectures.
- Created tools in Python / C++ for ground system control, test procedure automation, and data visualization.

Pathways Intern — Flight Software Systems Branch

May 2019 — July 2019

- Created a memory access driver in C / FreeRTOS, allowing for thread-safe memory allocation, wear leveling, etc.
- Developed command and telemetry GUIs for debugging and interfacing with instrument subsystems using PyQt.

Pathways Intern — Flight Software Systems Branch

September 2018 — December 2018

- Developed an equatorial mount subsystem in C / FreeRTOS and integrated it within existing flight software.
- Created Ruby scripts to automate test procedures and verify the functionality of multiple instrument subsystems.

The University of California, San Diego

La Jolla, CA

Undergraduate Researcher (REU) — Engineers for Exploration

June 2018 — August 2018

- Used C++ High Level Synthesis (HLS) to write FPGA overlays for I2C sensor data acquisition, PID motor control, and PWM signal generation for a Xilinx PYNQ (Zynq) development board.
- Developed similar functionality using a MicroBlaze to compare resource utilization, performance, and complexity against HLS design. Used Jupyter Notebooks for debugging and functional demonstrations.

NASA Johnson Space Center

Houston, TX

Intern — Integrated Guidance, Navigation, and Control Analysis Branch

August 2017 — December 2017

- Analyzed ascent abort procedures and assisted in creating models to characterize propellant slosh within the SpaceX Crew Dragon landing and orbit tanks using the Trick Simulation Environment.
- Created a 3D animation tool in Python to calculate and render propellant slosh for various tank geometries.

Massachusetts Institute of Technology

Cambridge, MA

Undergraduate Researcher (REU) — Haystack Observatory

June 2017 — August 2017

- Designed and implemented the foundations of an autonomous avionics system in FreeRTOS and Linux.
- Wrote software in C and C++ for a UART Iridium modem interface, autonomous system health monitoring, process management, GPIO sensor data collection, and power reduction optimizations.

Education

The University of Texas at Dallas

Bachelor of Science, Computer Science

December 2019

Languages: C, C++, Python, MATLAB, SQL

Software & Tools: RTOS, Linux, Xilinx Vivado, Flask, Docker, Git, Make, Bash

Awards: 1st place Fall 2019 Senior Design Capstone Project, 1st place at HackNAU 2017, 1st place at Richardson Community Hack Week 2016 (incl. a \$25,000 grant for continued project development)

Publications

B. Cain, **Z. Merchant**, I. Avendano, D. Richmond and R. Kastner, "PynqCopter - An Open-source FPGA Overlay for UAVs," in *2018 IEEE International Conference on Big Data (Big Data)*, Dec. 2018, pp. 2491-2498. [Online].

Available: <https://ieeexplore.ieee.org/document/8622102>