For background see: Rate-limiting entry/exits, not withdrawals

The validator sets of B_L

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We can calculate the safety of a block taking into account the passage of time as follows. Suppose that the last finalized
block you saw was at time T_0
, the current time is T {now}
, and you receive a finalized block from slot T L
(call the older block B 0
and the new one B L
). ("from slot T
" means "supposed to have been published at time T
") How many validators would need to be slashed for the network to have accepted some block B_R
conflicting with B_L
as final?
If the validator set is static, with N
validators, then the answer is obvious: \frac{N}{3}
. But what if the validator set can change, and specifically if N
validators are part of the validator set of a block at slot T
then the validator set at slot T+1
can incur a maximum of a(N)
activations and e(N)
exits?
We know the number of activations and exits between the validator set of B 0
and that of B_L
exactly; call this a_L
and e_L
. We can also compute an upper bound on the number of activations and exits between B_0
and a hypothetical block B_R
that appears now
; we can call this a_R
and e R
. If the activation and exit rates are constant, then a_R \le k_1 * (T_{\text{now}} - T_0)
and e R \le k 2 * (T {now} - T 0)
. If the rates are proportional to validator set size, then A_R = |V(B_0)| * (e^{-t} - T_0)| * (e^{-
and e_R = |V(B_0)| * (e^{\frac{T_{\text{now}} - T_0}{k_2}} - 1)
. If the formula is more complex, the calculation will be more complicated.
Now, we can calculate the intersection of quorums of B_L
and B_R
. Here is a Venn diagram to illustrate what is going on:
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and B R
are V_1
and V 2
. The validator subsets that participated in finalizing each block ("quorums") are Q 1
and Q 2
, with |Q_i| \ge \frac{2}{3} * |V_i|
. The intersection Q 1 \cap Q 2
gets slashed.
The size of the set complement V_2 - V_1
is a_R + e_L
, and V_1 - V_2
is a_L + e_R
. Let I = V 1 \cap V 2
("intersection"). In the worst case, members of these complements are all
members of Q 1
or Q 2
, so |Q_1 \le I| \le |V_1| * \frac{2}{3} - a_L - e_R
and Q 2 \cap I \ge |V 2| * \frac{2}{3} - e L - a R
. We also know I
equals |V_2| - a_R - e_L
or |V_1| - a_L - e_R
. To do a sneaky mathematical trick, we'll use the affine-combined form (|V_2| - a_R - e_L) * \frac{2}{3} + (|V_1| - a_L - e_R)
* \frac{1}{3}
We can compute the intersection that gets slashed via |Q_1 \cap I| + |Q_2 \cap I| - |I|
or:
|V_1| * \frac{2}{3} - a_L - e_R + |V_2| * \frac{2}{3} - e_L - a_R - |V_2| * \frac{2}{3} + a_R * \frac{2}{3} + e_L * \frac{2}{3} - e_L - a_R - |V_2| * \frac{2}{3} + a_R * \frac{2}{3} + e_L * \frac{2}{3} - e_L + a_R + a_R + \frac{2}{3} - e_L + a_R + a_
|V_1| * \frac{1}{3} + a_L * \frac{1}{3} + e_R * \frac{1}{3}
This simplifies to:
V_1| \times \frac{1}{3} - a_L \cdot \frac{2}{3} - e_R \cdot \frac{2}{3} - e_L \cdot \frac{1}{3} - a_R \cdot \frac{1}{3} - a_R \cdot \frac{1}{3}
If our goal is to take into account latency until validators get slashed, then we would need to add another parameter \delta
and compute the "escapees" on each chain via k 1 * \delta
, |V(B)| * (e^{\frac{\delta}{k 1}} - 1)
or otherwise the appropriate formula to count exits, and subtract the escapees from the intersection to determine how many
validators must have been slashed on each chain.
Implementation
Whenever a validator receives a new block, they know the previous finalized block that they saw, B_0
, as well as the new block B L
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and the upper bound on time T_{now}

, so they can simply use the formulas above to compute the actual safety level of the block.	