

With Fast Fourier transforms it's possible to convert a set of evaluations of a polynomial over a prime field at a set of specific points,  $P(1)$

,  $P(r)$

,  $P(r^2)$

...  $P(r^{2^k-1})$

(where  $r^{2^k} = 1$

) into the polynomial's coefficients in  $n \cdot \log(n)$

time. This is used extensively and is key to the efficiency of [STARKs](#) and most other general-purpose ZKP schemes. Polynomial interpolation (and its inverse, multi-point evaluation) is also

used extensively in erasure coding, which is useful for [data recovery](#) and in blockchains for [data availability checking](#).

Unfortunately, the FFT interpolation algorithm works only if you have all

evaluations at  $P(r^i)$

for  $0 \leq i \leq 2^k - 1$

. However, it turns out that you can make a somewhat more complex algorithm to also achieve polylog complexity for interpolating a polynomial (ie. the operation needed to recover the original data from an erasure code) in those cases where some of these evaluations are missing. Here's how you do it.

## Erasure code recovery in $O(n \cdot \log^2(n))$

time

Let  $d[0] \dots d[2^k - 1]$

be your data, substituting all unknown points with 0. Let  $Z_{\{r, S\}}$

be the minimal polynomial that evaluates to 0 at all points  $r^k$

for  $k \in S$

. Let  $E(x)$

(think  $E$  = error) be the polynomial that evaluates to your data with erasures (ie.  $E(r^i) = d[i]$

), and let  $P(x)$

be the polynomial that evaluates to original data. Let  $I$

be the set of indices representing the missing points.

First of all, note that  $D * Z_{\{r, I\}} = E * Z_{\{r, I\}}$

. This is because  $D$

and  $E$

agree on all points outside of  $I$

, and  $Z_{\{r, I\}}$

forces the evaluation on points inside

$I$

to zero. Hence, by computing  $d[i] * Z_{\{r, I\}}(r^i) = (E * Z_{\{r, I\}})(r^i)$

, and interpolating  $E * Z_{\{r, I\}}$

, we get  $D * Z_{\{r, I\}}$

.

Now, how do we extract  $D$

? Just evaluating pointwise and dividing won't work, as we already know that at least for some points (in fact, the points we're trying to recover!)  $(D * Z_{\{r,l\}})(x) = Z_{\{r,l\}}(x) = 0$

, and we won't know what to put in place of  $0 / 0$

. Instead, we do a trick: we generate a random  $k$

, and compute  $Q1(x) = (D * Z_{\{r,l\}})(k * x)$

(this can be done by multiplying the  $i$ th coefficient by  $k^{-i}$ )

). We also compute  $Q2(x) = Z_{\{l\}}(k * x)$

in the same way. Now, we compute  $Q3 = Q1 / Q2$

(note:  $Q3(x) = D(k * x)$

), and then from there we multiply the  $i$ th coefficient by  $k^i$

to get back  $D(x)$

, and evaluate  $D(x)$

to get the missing points.

Altogether, outside of the calculation of  $Z_{\{r,l\}}$

this requires six FFTs: one to calculate the evaluations of  $Z_{\{r,l\}}$

, one to interpolate  $E * Z_{\{r,l\}}$

, two to evaluate  $Q1$

and  $Q2$

, one to interpolate  $Q3$

, and one to evaluate  $D$

. The bulk of the complexity, unfortunately, is in a seemingly comparatively easy task: calculating the  $Z_{\{r,l\}}$  polynomial.

## Calculating $Z$ in $O(n \log^2(n))$

time

The one remaining hard part is: how do we generate  $Z_{\{r,S\}}$

in  $n \text{polylog}(n)$  time? Here, we use a recursive algorithm modeled on the FFT itself. For a sufficiently small  $S$

, we can compute  $(x - r^{\{s_0\}}) * (x - r^{\{s_1\}}) \dots$

explicitly. For anything larger, we do the following. Split up  $S$

into two sets:

$$S_{\text{even}} = \{\frac{x}{2} \text{ for } x \in S \text{ if } S \bmod 2 = 0\}$$

$$S_{\text{odd}} = \{\frac{x-1}{2} \text{ for } x \in S \text{ if } S \bmod 2 = 1\}$$

Now, recursively compute  $L = Z_{\{r^2, S_{\text{even}}\}}$

and  $R = Z_{\{r^2, S_{\text{odd}}\}}$

. Note that  $L$

evaluates to zero at all points  $(r^2)^{\{\frac{s}{2}\}} = r^s$

for any even  $s \in S$

, and  $R$

evaluates to zero at all points  $(r^2)^{\{\frac{s-1}{2}\}} = r^{s-1}$

for any odd  $s \in S$

. We compute  $R'(x) = R(x * r)$

using the method we already described above. We then use FFT multiplication (use two FFTs to evaluate both at 1,  $r$ ,  $r^2 \dots r^{-1}$ )

, multiply the evaluations at each point, and interpolate back the result) to compute  $L * R'$

, which evaluates to zero at all the desired points.

In one special case (where  $S$

is the entire

set of possible indices), FFT multiplication fails and returns zero; we watch for this special case and in that case return the known correct polynomial,  $P(x) = x^{2^k} - 1$

.

Here's the code that implements this (tests [here](#)):

[github.com](#)

[ethereum/research/blob/master/mimc\\_stark/recovery.py](#)

```
from fft import fft, mul_polys
```

## Calculates modular inverses [1/values[0], 1/values[1] ...]

```
def multi_inv(values, modulus):
    partials = [1]
    for i in range(len(values)):
        partials.append(partial[-1] * values[i] % modulus)
    inv = pow(partial[-1], modulus - 2, modulus)
    outputs = [0] * len(values)
    for i in range(len(values), 0, -1):
        outputs[i-1] = partials[i-1] * inv % modulus
    inv = inv * values[i-1] % modulus
    return outputs
```

## Generates $q(x) = \text{poly}(k * x)$

```
def p_of_kx(poly, modulus, k):
    o = []
    power_of_k = 1
    for x in poly:
        o.append(x * power_of_k % modulus)
```

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Questions:

- Can this be easily translated into binary fields?
- The above algorithm calculates  $Z_{\{r,S\}}$

in time  $O(n * \log^2(n))$

. Is there a  $O(n * \log(n))$

time way to do it?

- If not, are there ways to achieve constant factor reductions by cutting down the number of FFTs per recursive step from 3 to 2 or even 1?
- Does this actually work correctly in 100% of cases?
- It's very possible that all of this was already invented by some guy in the 1980s, and more efficiently. Was it?