Big Data GAM methods

Matteo Fasiolo (University of Bristol, UK)

matteo.fasiolo@bristol.ac.uk

Material available at:

https://github.com/mfasiolo/workshop_WARSAW19

Example: a Gaussian GAM for expected load is

$$\mathbb{E}(\mathsf{Load}_i) \ = \ \sum_{j=1}^7 \beta_j w^j_{d(i)} \quad \cdot \mathsf{Day\text{-}of\text{-}week factor} \\ + \ \beta_8 \mathsf{Load}_{i-48} \quad \cdot \mathsf{Lagged load} \\ + \ f_1(t_i) \quad \cdot \mathsf{Long\text{-}term trend} \\ + \ f_2(T_i) \quad \cdot \mathsf{Temperature} \\ + \ f_3(T_i^s) \quad \cdot \mathsf{Smoothed temperature} \\ + \ f_4(\mathsf{toy}_i), \quad \cdot \mathsf{Time\text{-}of\text{-}year}$$

where
$$T_i^s = \alpha T_i + (1 - \alpha) T_{i-1}^s$$
, with $\alpha = 0.05$.

It is standard practice to model the 48 30min slots separately. So we need to fit 48 models.

Example: a more ambitious model is

$$\begin{split} \mathbb{E}(\mathsf{Load}_i) &= \sum_{j=1}^7 \beta_j w_{d(i)}^j \quad \cdot \; \mathsf{Day\text{-of-week factor}} \\ &+ f(\mathsf{tod}_i) \mathsf{Load}_{i-48} \quad \cdot \; \mathsf{Lagged load} \\ &+ \mathsf{te}_1(t_i, \mathsf{tod}_i) \quad \quad \cdot \; \mathsf{Long\text{-term trend}} \\ &+ \mathsf{te}_2(T_i, \mathsf{tod}_i) \quad \quad \cdot \; \mathsf{Temperature} \\ &+ \mathsf{te}_3(T_i^s, \mathsf{tod}_i) \quad \quad \cdot \; \mathsf{Smoothed temperature} \\ &+ \mathsf{te}_4(\mathsf{toy}_i, \mathsf{tod}_i), \quad \cdot \; \mathsf{Time\text{-of-year}} \end{split}$$

where

- tod is time of day 1, . . . , 48
- te's are 2D tensor product smooths
- $f(tod_i)Load_{i-48}$ is varying coefficient effect

Why is this useful? Some answers:

- ullet statistical efficiency o share information across time-of-day
- ease of use and interpretation

Do we need Big Data methods? Notice that:

- n is 48 times bigger than a 30min model
- tensor product can have large number of basis functions

$$\mathsf{te}(\mathsf{T},\mathsf{tod}) = \sum_{j=1}^J \sum_{k=1}^K \beta_{ij} b_j(\mathsf{T}) b_k(\mathsf{tod}) = \sum_{j=1}^J \sum_{k=1}^K \beta_{ij} \tilde{b}_{jk}(\mathsf{T},\mathsf{tod})$$

so tensor effect has $J \times K$ coefficients.

Recall that $\mathbb{E}(\mathsf{load}|\mathbf{x}_i) = g^{-1}(\mathbf{X}_i^\mathsf{T}\boldsymbol{\beta})$, where \mathbf{X}_i^T row of

$$\mathbf{X} = \begin{bmatrix} 1 & \mathbb{1}(\mathsf{dow}_1 = \mathsf{Mon}) & \cdots & b_{11}(\mathsf{T}_1, \mathsf{tod}_1) & \cdots & b_{JK}(\mathsf{T}_1, \mathsf{tod}_1) & \cdots \\ 1 & \mathbb{1}(\mathsf{dow}_2 = \mathsf{Mon}) & \cdots & b_{11}(\mathsf{T}_2, \mathsf{tod}_2) & \cdots & b_{JK}(\mathsf{T}_2, \mathsf{tod}_2) & \cdots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 1 & \mathbb{1}(\mathsf{dow}_n = \mathsf{Mon}) & \cdots & b_{11}(\mathsf{T}_n, \mathsf{tod}_n) & \cdots & b_{JK}(\mathsf{T}_n, \mathsf{tod}_n) & \cdots \end{bmatrix}$$

with *n* rows and

$$d=p+J\times K+\cdots,$$

columns.

Bottom line: X can get very big, which causes problems:

- storing X takes too much memory
- computing with X (e.g. X^TX or QR(X)) takes time

bam() implements memory-saving methods of Wood et al. (2015):

• do not create **X** but only sub-blocks:

$$\mathbf{X} = \left[\begin{array}{ccc} \mathbf{X}_{11} & \mathbf{X}_{12} \\ \mathbf{X}_{21} & \mathbf{X}_{22} \\ \vdots & \vdots \\ \mathbf{X}_{B1} & \mathbf{X}_{B2} \end{array} \right]$$

do not store them either, but build them when needed

ullet any computation involving old X is based on the blocks

Block-oriented methods can be used also to perform fast model updates:

Faster computation and memory savings using Wood et al. (2017).

Simple observation is that many variables are discrete in nature:

- time of day (tod) $\in \{1, \ldots, 48\}$
- time of year (toy) $\in \{1, \ldots, 365\}$
- temperature (T) $\in \{..., -0.1, 0, 0.1, 0.2, ...\}$

There is room for data compression, example:

- ullet we have 10 year of data and 48 imes 365 obs per year
- effect of toy is

$$s(\mathsf{toy}) = \sum_{i=1}^p \beta_i b_i(\mathsf{toy}).$$

so model matrix part **X** of toy is $(10 * 48 * 365) \times p$

- compressed model matrix $\bar{\mathbf{X}}$ is $365 \times p$
- saving factor $\#elem(\mathbf{X})/\#elem(\bar{\mathbf{X}}) = 10 * 48$

Discretization can be applied to variables that are not "naturally" discrete.

Sampling variability is $O(n^{-\frac{1}{2}})$, so discretizing in $m = O(n^{\frac{1}{2}})$ bins is ok.

Wood et al. (2017) use discretization to fit UK black smoke pollution data from 2000 stations, with $n=10^8$ and $p=10^4$.

With latest mgcv version, the model

$$\begin{split} \log(\mathsf{bs}_i) &= f_1(\mathsf{y}_i) + f_2(\mathsf{doy}_i) + f_3(\mathsf{dow}_i) + f_4(\mathsf{y}_i, \mathsf{doy}_i) + f_5(\mathsf{y}_i, \mathsf{dow}_i) \\ &+ f_6(\mathsf{doy}_i, \mathsf{dow}_i) + f_7(\mathsf{n}_i, \mathsf{e}_i) + f_8(\mathsf{n}_i, \mathsf{e}_i, \mathsf{y}_i) + f_9(\mathsf{n}_i, \mathsf{e}_i, \mathsf{doy}_i) \\ &+ f_{10}(\mathsf{n}_i, \mathsf{e}_i, \mathsf{dow}_i) + f_{11}(\mathsf{h}_i) + f_{12}(\mathsf{T}_i^0, \mathsf{T}_i^1) + f_{13}(\bar{\mathsf{T}}_1, \bar{\mathsf{T}}_2) \\ &+ f_{14}(\mathsf{r}_i) + \alpha_{k(i)} + b_{\mathrm{id}(i)} + e_i \end{split}$$

can be fitted in 5min on 8 cores (Li and Wood, 2019).

References I

- Li, Z. and S. N. Wood (2019). Faster model matrix crossproducts for large generalized linear models with discretized covariates. *Statistics and Computing*, 1–7.
- Wood, S. N., Y. Goude, and S. Shaw (2015). Generalized additive models for large data sets. *Journal of the Royal Statistical Society: Series C (Applied Statistics)* 64(1), 139–155.
- Wood, S. N., Z. Li, G. Shaddick, and N. H. Augustin (2017). Generalized additive models for gigadata: modeling the uk black smoke network daily data. *Journal of the American Statistical Association* 112(519), 1199–1210.