Microprocessor Systems and Interfacing

Lab Report

Lab04

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Class	Microprocessor Systems and Interfacing CPE342 (**BCE-6B**)
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Pre-Lab Tasks

Task-1

Read the theory section of this lab thoroughly.

Task-2

Write an assembly language program that is able to display the numbers '0' to '9' on an LCD as connected in figure 5.2. *[hint: look up ASCII table]*

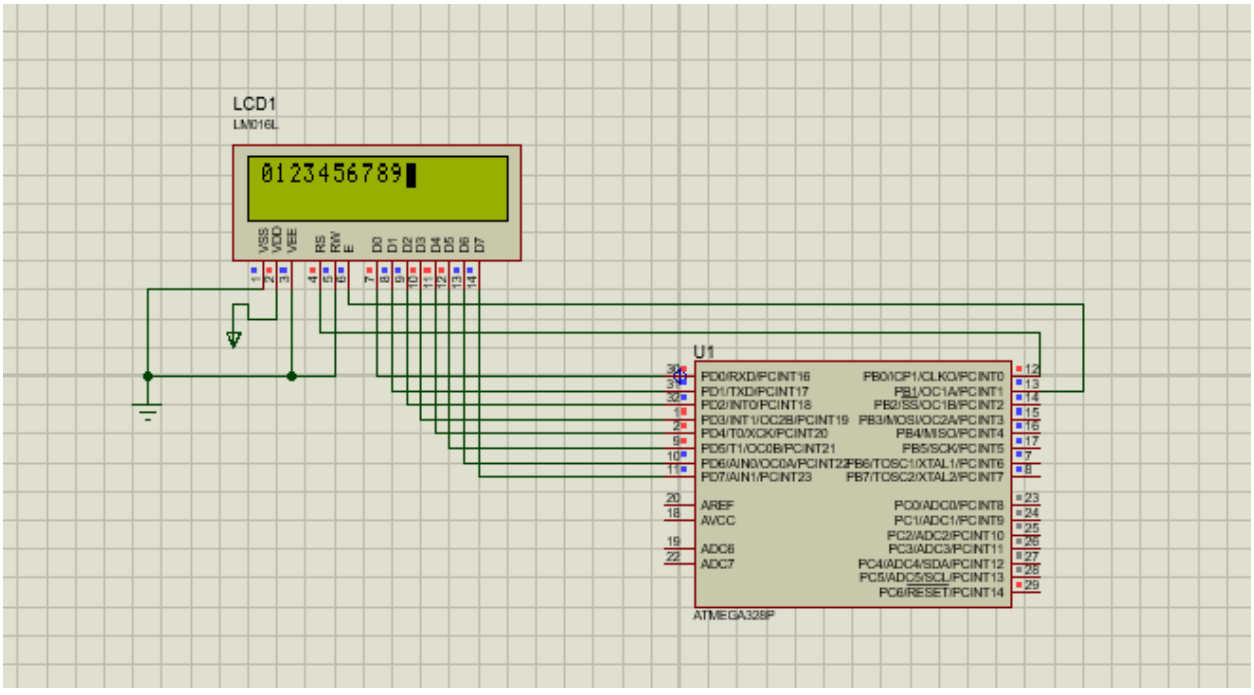
Code

```
.equ RS = 0
.equ En = 1

.org 0x0000

       rjmp start

.org 0x0034

start:
       ldi R16, 0xFF ; Set PortB to output
    out DDRB, R16
       out DDRD, R16 ; Set PortD to output

       rcall LCD_Init       ; Initiallize the LCD

       rcall DisplayNums    ; Display Numbers 0-9 on the LCD

forever:
       nop
rjmp forever  ; Do nothing in a never ending loop


delay_1ms:    ; This function will generate a delay of approximately 1 ms on an 8-MHz
Atmega328p
       push R16
       push R17
       ldi R17, 8
       L1:
       ldi R16, 250
    L11:
              nop
              dec R16
              brne L11

              dec R17
              brne L1
       pop R17
       pop R16
```

```
ret

delay_50ms:
	push R16
	ldi R16, 50
	L2:
	rcall delay_1ms
	dec R16
	brne L2
	pop R16
ret

LCD_Send_Command:    ; This function assumes that command byte is in R18.

	cbi PORTB, RS ; Clear RS for command
	out PORTD, R18       ; Output the command byte on PORTD
	rcall LCD_Pulse_En   ; Send a 1 ms pulse on En (PB1)
ret


LCD_Send_Data:       ; This function assumes that data byte is in R18.

	sbi PORTB, RS ; Set RS for data
	out PORTD, R18       ; Output the data byte on PORTD
	rcall LCD_Pulse_En   ; Send a 1 ms pulse on En (PB1)
ret

LCD_Pulse_En:
	sbi PORTB, En ; Set En high
	rcall delay_1ms      ; wait for 1ms
	cbi PORTB, En
ret


LCD_Init:
	rcall delay_50ms     ; wait for more than 40ms

	ldi R18, 0x30 ; send command 0x30
	rcall LCD_Send_Command

	rcall delay_1ms      ; delay of more than 4.1 ms
	rcall delay_1ms
	rcall delay_1ms
	rcall delay_1ms

	ldi R18, 0x30 ; send command 0x30
	rcall LCD_Send_Command

	rcall delay_1ms      ; wait more than 100 us

	ldi R18, 0x38 ; send command 0x38 (2 lines, 5x7 size)
	rcall LCD_Send_Command


	ldi R18, 0x0E ; send command 0x08 (Display off)
	rcall LCD_Send_Command
```

```
        ldi R18, 0x01 ; send command 0x01 (Clear display)
        rcall LCD_Send_Command


        ldi R18, 0x0F ; send command 0x0F (Entry mode set)
        rcall LCD_Send_Command

ret

DisplayNums:

        push R18      ; save R18 to the stack
        push R17      ; save R17 to the stack

        ldi R18, '0'          ; R18 holds ASCII value for 0
        ldi R17, ('9'+1)      ; Loop has to run till digit 9 has been displayed

        L3:
                rcall LCD_Send_data
                inc R18
                cp R18, R17
                BRNE L3

        pop R17               ; restore R17
        pop R18               ; restore R18
ret
```

Simulation



Task-3

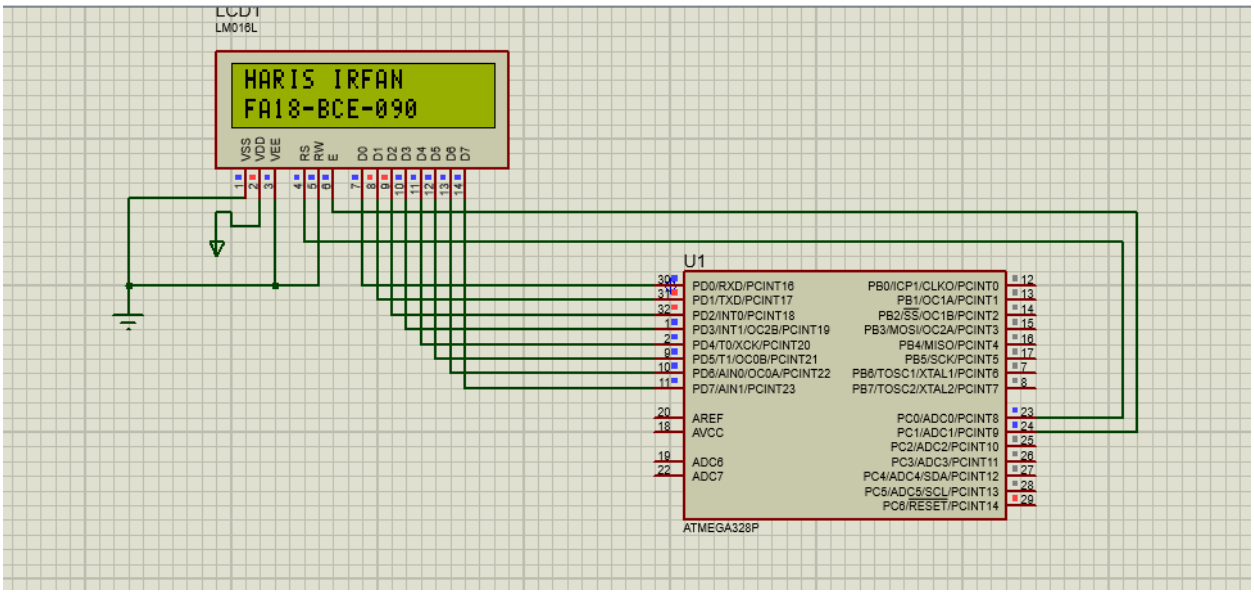
Consider the basic wiring shown between an ATmega328P chip and an LCD in figure 5.2. Write and execute a C-program on Proteus that is able print your name on the first row of the LCD and your roll-number on the second row of the LCD

Code:

```
#include <avr/io.h>
#define F_CPU 1000000
#include <util/delay.h>
#define RS PC0
#define EN PC1

void lcd_comm (char);
void lcd_data(char);
void lcd_init (void);


int main(void)
{
	char name[16]={'H','A','R','I','S', 'I','R', 'F', 'A', 'N',' ',' ',' ',' ',' ',' '
'};
	char rnum[16]={'F','A','1','8','-','B','C','E','-','0','9','0',' ',' ',' ',' '}
	;
	while(1)
	{

		DDRD = 0xFF;
		DDRC = 0x03;
		lcd_comm(0x38);  //2 lines
		lcd_comm(0x0C);  //cursor off
		//lcd_comm(0x01);   clear screen
		lcd_comm(0xD80);   //force to first line

		for(int i=0; i<16;i++)
		{
			_delay_ms(500);

			lcd_data(name[i]);
			lcd_comm(0x06);
			if(i==4)
			lcd_comm(20);

					//increametn cur
		}
		lcd_comm(192);
		for(int j=0; j<16;j++)
		{
			_delay_ms(50);

			lcd_data(rnum[j]);
			lcd_comm(0x06);

			//increametn cur
		}
		return 0;
```

```
        }
}

void lcd_comm(char x){
        PORTD = x;
        PORTC &= ~(1<<RS);
        PORTC |= (1<<EN);
        _delay_ms(5);
        PORTC &= ~(1<<EN);
}

void lcd_data(char x){
        PORTD = x;
        PORTC |= (1<<RS);
        PORTC |= (1<<EN);
        _delay_ms(50);
        PORTC &= ~(1<<EN);
}
```

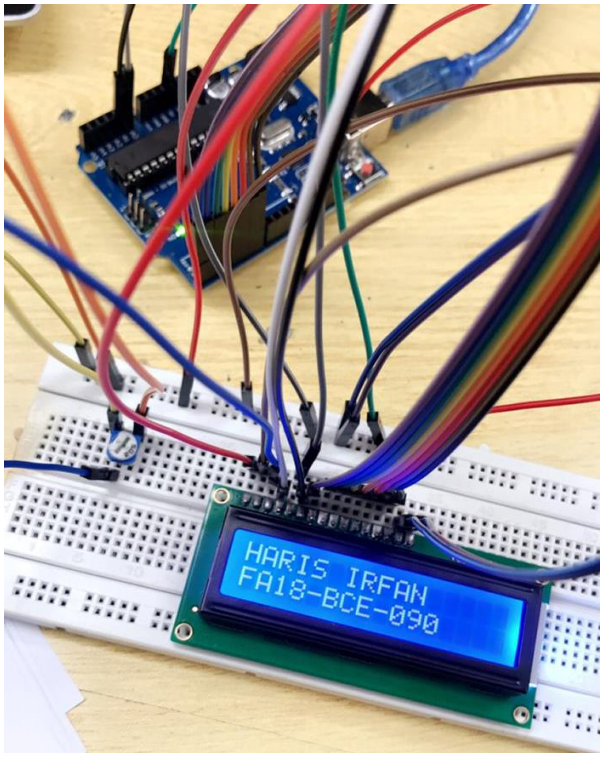
Simulation:



In Lab Tasks

Task 1:

Wire your Arduino Uno / Nano / ATmega328P to an LCD on your breadboard and execute the program performed in Task-2 from 'Pre-Lab' Tasks



Task 2:

Consider your controller connected to an 8×dipswitch, a push-button and an LCD. Program your controller in a way that whenever the push-button is pressed, the input from the dipswitch should be pushed on to the LCD as an ASCII character. Execute your code on Proteus.

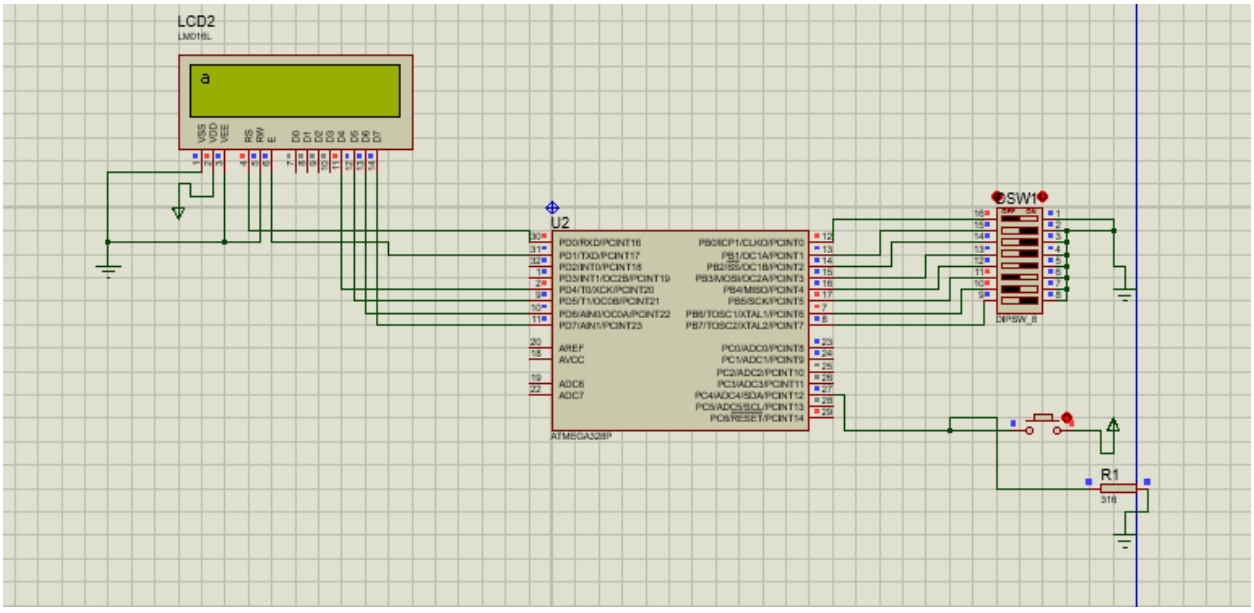
Code:

```
#define F_CPU 8000000UL                                    /* Define CPU Frequency e.g. here
its 8MHz */
#include <avr/io.h>                                        /* Include AVR std. library file
*/
#include <util/delay.h>                                    /* Include inbuilt defined Delay
header file */

#define LCD_Dir  DDRD                                      /* Define LCD data port direction
*/
#define LCD_Port PORTD                                     /* Define LCD data port */
#define RS PD0                                                  /* Define Register Select
(data reg./command reg.) signal pin */
#define EN PD1                                                  /* Define Enable signal pin
*/
void LCD_Init (void);
void LCD_String (char *str);
void LCD_Command( unsigned char cmnd );
void LCD_data( unsigned char data );

int main()
{

	LCD_Init();                                                 /* Initialization of LCD*/
	DDRC = 0x03;
	DDRB = 0x00;
	PORTB = 0xff;

unsigned char a = 0b00000000;



	if ((PINC & (1<<PC4)) == 0)
	{

		a |= (PINB & 0xff);
	}

	while(1)
	{
		if((PINC & (1<<PC4)) != 0)
		{
			LCD_data(a);
			_delay_ms(10000);
		}
```

```
        }

}



void LCD_Command( unsigned char cmnd )
{
        LCD_Port &= 0x0F ;
        LCD_Port |= (cmnd & 0xF0); /* sending upper nibble */
        LCD_Port &= ~ (1<<RS);                          /* RS=0, command reg. */
        LCD_Port |= (1<<EN);                    /* Enable pulse */
        _delay_us(1);
        LCD_Port &= ~ (1<<EN);

        _delay_us(200);

        LCD_Port &= 0x0F;
        LCD_Port |= (cmnd << 4);  /* sending lower nibble */
        LCD_Port |= (1<<EN);
        _delay_us(1);
        LCD_Port &= ~ (1<<EN);
        _delay_ms(2);
}


void LCD_data( unsigned char data )
{
        LCD_Port = (LCD_Port & 0x0F) | (data & 0xF0); /* sending upper nibble */
        LCD_Port |= (1<<RS);                    /* RS=1, data reg. */
        LCD_Port|= (1<<EN);
        _delay_us(1);
        LCD_Port &= ~ (1<<EN);

        _delay_us(200);

        LCD_Port = (LCD_Port & 0x0F) | (data << 4); /* sending lower nibble */
        LCD_Port |= (1<<EN);
        _delay_us(1);
        LCD_Port &= ~ (1<<EN);
        _delay_ms(2);
}

void LCD_Init (void)                            /* LCD Initialize function */
{
        LCD_Dir = 0xFF;                                         /* Make LCD command port
direction as o/p */
        _delay_ms(20);                                          /* LCD Power ON delay
always >15ms */

        LCD_Command(0x33);
        LCD_Command(0x32);                      /* send for 4 bit initialization of LCD
*/
        LCD_Command(0x28);              /* Use 2 line and initialize 5*7 matrix in (4-
bit mode)*/
        LCD_Command(0x0c);              /* Display on cursor off*/
        LCD_Command(0x06);              /* Increment cursor (shift cursor to right)*/
        LCD_Command(0x01);              /* Clear display screen*/
```

```
        _delay_ms(2);
        LCD_Command (0x80);                                  /* Cursor 1st row 0th position */
}


void LCD_String (char *str)                          /* Send string to LCD function */
{
        int i;
        for(i=0;str[i]!=0;i++)                               /* Send each char of string till
the NULL */
        {
                LCD_data (str[i]);
        }
}
```

Simulation



Post Lab Tasks

Task 1:

Implement the in-lab task for the 4-pin communication mode on Proteus. Additionally, add a 5×dip-switch array at an input. Use the dip switch to pass 8-bit ASCII code, one nibble at a time, to be displayed on the LCD. Toggle the 5th switch to indicate that one nibble is ready to load.

Simulation