

Heterogeneous Communication API For eHPC (embedded High Performance Computing)

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https://github.com/michaelboth/Takyon

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What is Takyon?

It's a modern message passing communication API focused on eHPC (e.g. edge computing)

- Reliable and unreliable (unicast & multicast) communication
- Most interconnects: e.g. RDMA, sockets
- Any locality: inter-processor, inter-process, inter-thread
- Two-sided (send/recv), and one-sided (read/write)
- Blocking and non-blocking transfers
- Fault tolerant capable (via timeouts, disconnect detection, dynamic path creation)
- Most memory types: e.g. CPU, GPU



Takyon's Intended Audience

Small heterogeneous systems (eHPC, edge computing, SWaP limited environments, etc)







Large homogeneous systems, with highly collective needs are better suited by MPI or libFabric





Why Introduce Another Communication API?

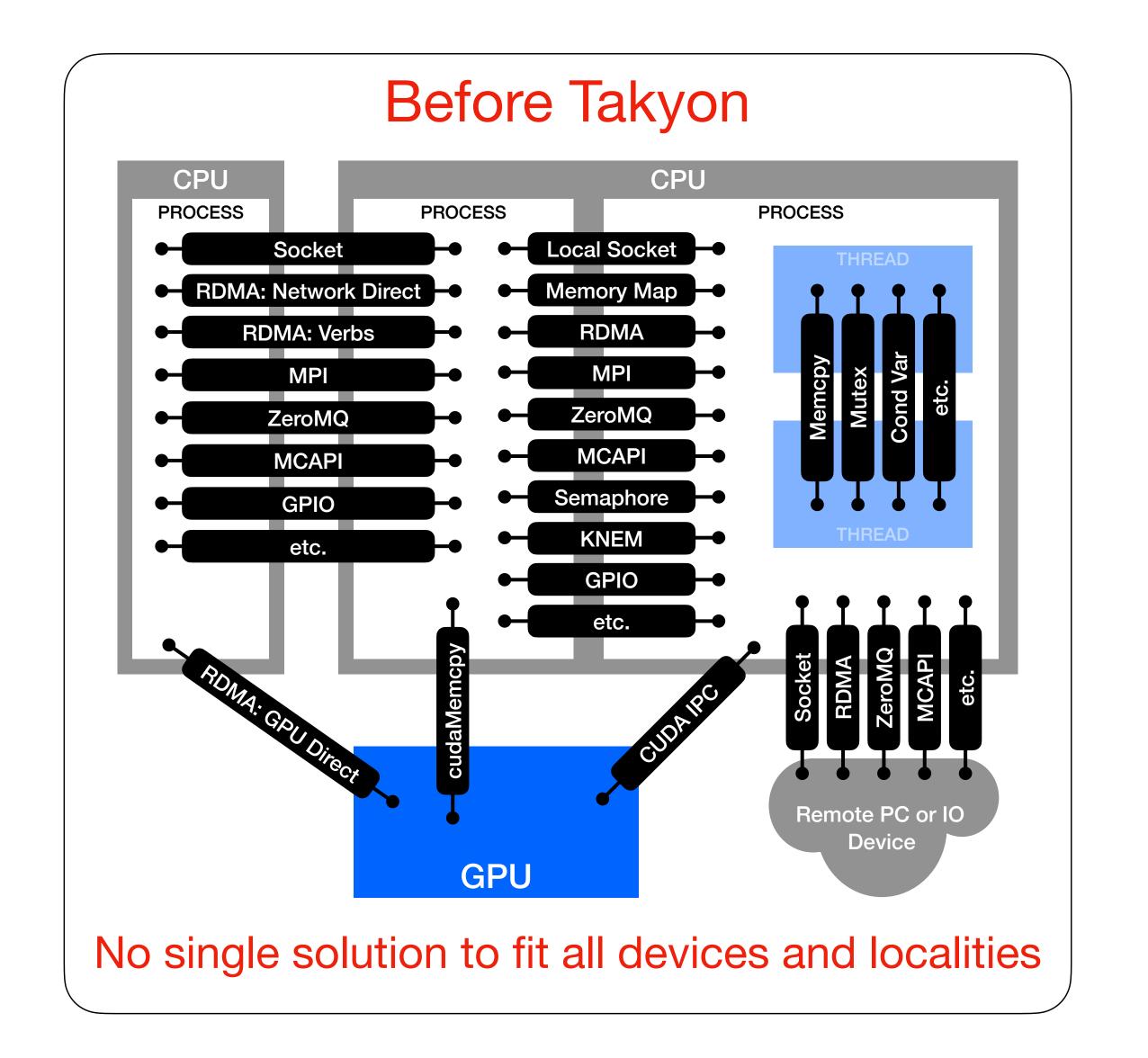
Takyon is an evolution that solves four major communication issues at once:

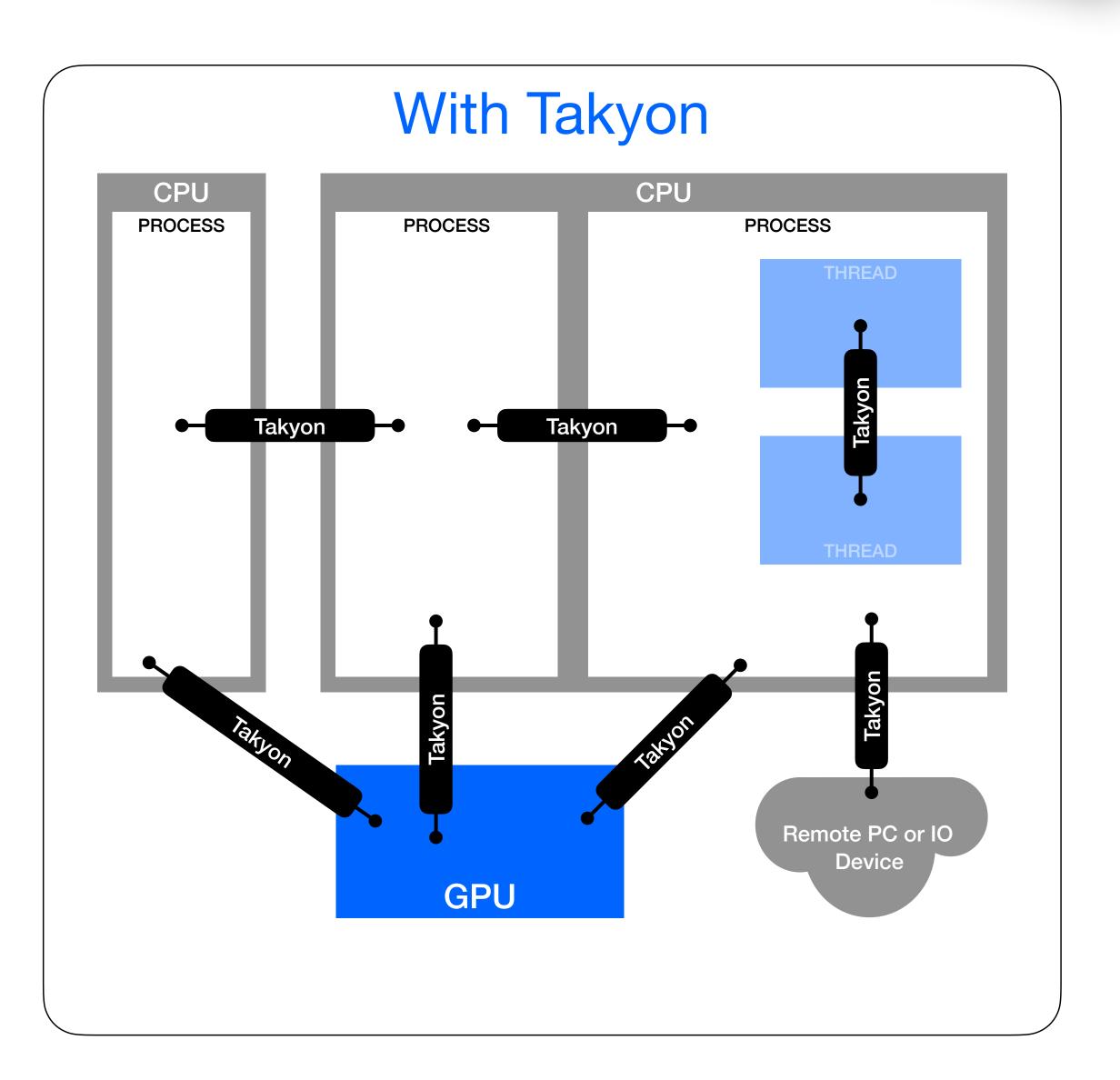
- One API for all device/interconnect variations
- Supports all common communication features
- Simple and intuitive: 8 functions and 8 data structures
- Best possible performance: throughput, latency, and determinism

The next four slides provide details on the above



One API for all Device/Interconnect Variations







Supports all Common Communication Features

| Feature | Sockets and similar: MCAPI, ZeroMQ | RDMA: Verbs and Network Direct | OFA's libFabric | MPI | Takyon |
|--|------------------------------------|--------------------------------------|--------------------|----------|--------|
| Reliable and Unreliable | | | | | |
| Communication to external apps, sensors, and other IO devices | | | ? | | |
| Fault tolerant hooks (timeouts, disconnect detection, path creation) | | | ? | | |
| Deterministic: avoids implicit communication and allocations | | | | | |
| Includes Inter-thread communication | | | | | |
| Non blocking transfers | | | | V | |
| One way read/write/atomcis: no involvement from remote endpoint | | | | V | |
| GPU support | | | | V | |
| Multiple memory blocks per message | | | ? | V | |
| Memory pre-registered before transfer | | | | Partial | |
| Zero copy and one-way (i.e. no implicit round trip) | | | ? | | |
| 32bit piggy back message with main message | | | ? | | |



Simple and Intuitive

| API | Function Count | Typical Drawbacks |
|----------------------------------|-------------------|--|
| Sockets | ~20 | Lots of options, confusing terms |
| RDMA (OFA Verbs, Network Direct) | ~100 | Overwhelming learning curve, experts are rare |
| OFA's libFabrics | ~100 | Overwhelming learning curve, experts are rare |
| MPI | ~300 | Large learning curve for various transfer models, limited to reliable communication, 'mpirun' is not portable and can be difficult to tune |
| Takyon | 8 | Simple API, intuitive terms and concepts |

Takyon eHPC audience is likely focused on something other than communication, such as radar processing, and won't have the time for a high learning curve



Best Possible Performance

Latency, Throughput, and Determinism

- Zero-copy, and one-way (no round trips!)
 - Achieved by:
 - Pre-registering (is time consuming) transport memory when the path is created
 - Pre-post receive requests
 - Creates a holding place for data to arrive later asynchronously in the background
 - This makes sure there is no delay or implicit buffering needed when sending
- Non-Blocking
 - Offload transfers to a DMA to allow for efficient concurrent processing and IO

Not all interconnects support the above, but Takyon's abstraction does not inhibit or degrade the interconnects that do support the above.



Takyon API: 8 Functions

Two-sided functions

One-sided functions

| Function | Description |
|------------------------|---|
| takyonCreate() | Create one endpoint of a communication path |
| takyonDestroy() | Destroy the endpoint |
| takyonSend() | Start sending a message If the communication does not support non-blocking then this will block |
| takyonIsSent() | Check if send is complete, up to a specified timeout period. |
| takyonPostRecvs() | If supported, pre-post a list of recv requests before the sender starts sending Provides memory buckets for receiving messages asynchronously |
| takyonIsRecved() | Check if a message has arrived, up to a specified timeout period. |
| takyonOneSided() | Start a one sided message transfer (read, write, atomics) |
| takyonIsOneSidedDone() | Check if one-sided transfer is complete, up to a specified timeout period. |

Not all interconnects support the above; e.g. sockets don't support one-sided or posting receives



Takyon Provider: Defines the Interconnect

All providers are defined in a text string passed to takyonCreate()

| Locality | Examples |
|-----------------|--|
| Inter-Thread | "InterThread -pathID= <non_negative_integer>"</non_negative_integer> |
| Inter-Process | "InterProcess -pathID= <non_negative_integer>" "SocketTcp -local -pathID=<non_negative_integer>"</non_negative_integer></non_negative_integer> |
| | "SocketTcp -client -remoteIP= <ip_addr> -port=<number>" "SocketTcp -server -localIP=<ip_addr> Any -port=<number> [-reuse]"</number></ip_addr></number></ip_addr> |
| | "SocketUdpSend -multicast -localIP= <ip_addr> -groupIP=<multicast_ip> -port=<number> [-noLoopback] [-TTL=<time_to_live>]"</time_to_live></number></multicast_ip></ip_addr> |
| Inter-Processor | "RdmaRC -client -remoteIP= <ip_addr> -port=<number> -rdmaDevice=<name> -rdmaPort=<number>" "RdmaRC -server -localIP=<ip_addr> Any -port=<number> [-reuse] -rdmaDevice=<name> -rdmaPort=<number>"</number></name></number></ip_addr></number></name></number></ip_addr> |
| | "RdmaUC -client -remoteIP= <ip_addr> -port=<number> -rdmaDevice=<name> -rdmaPort=<number>" "RdmaUC -server -locaIIP=<ip_addr> Any -port=<number> [-reuse] -rdmaDevice=<name> -rdmaPort=<number>"</number></name></number></ip_addr></number></name></number></ip_addr> |
| | "RdmaUDMulticastSend -localIP= <ip_addr> -groupIP=<multicast_ip>" "RdmaUDMulticastRecv -localIP=<ip_addr> -groupIP=<multicast_ip>"</multicast_ip></ip_addr></multicast_ip></ip_addr> |

No limit to the Takyon Provider possibilities: GPIO, sensors, FPGAs, etc.



Transport Memory

Takyon does NOT allocate transport memory (this is intentional)

Transport memory may need to be shared between communication paths (Takyon or 3rd party) and other processing APIs and IO devices

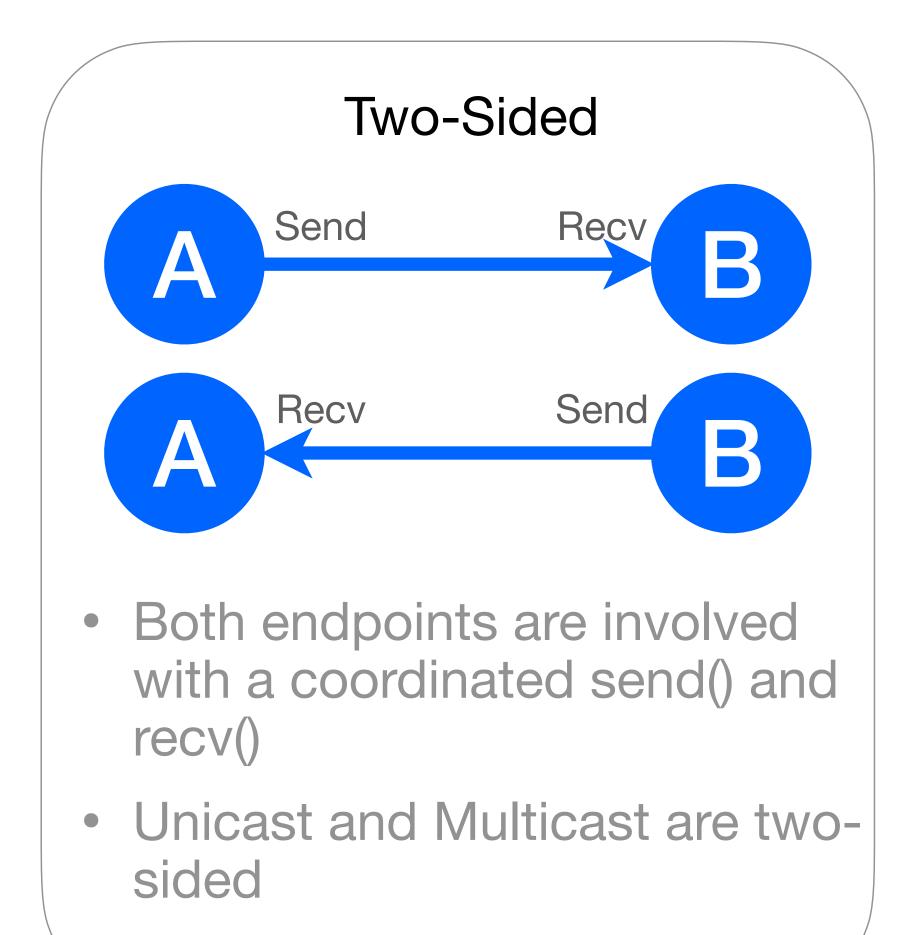
Therefore it is logical to have the application organize all transport memory

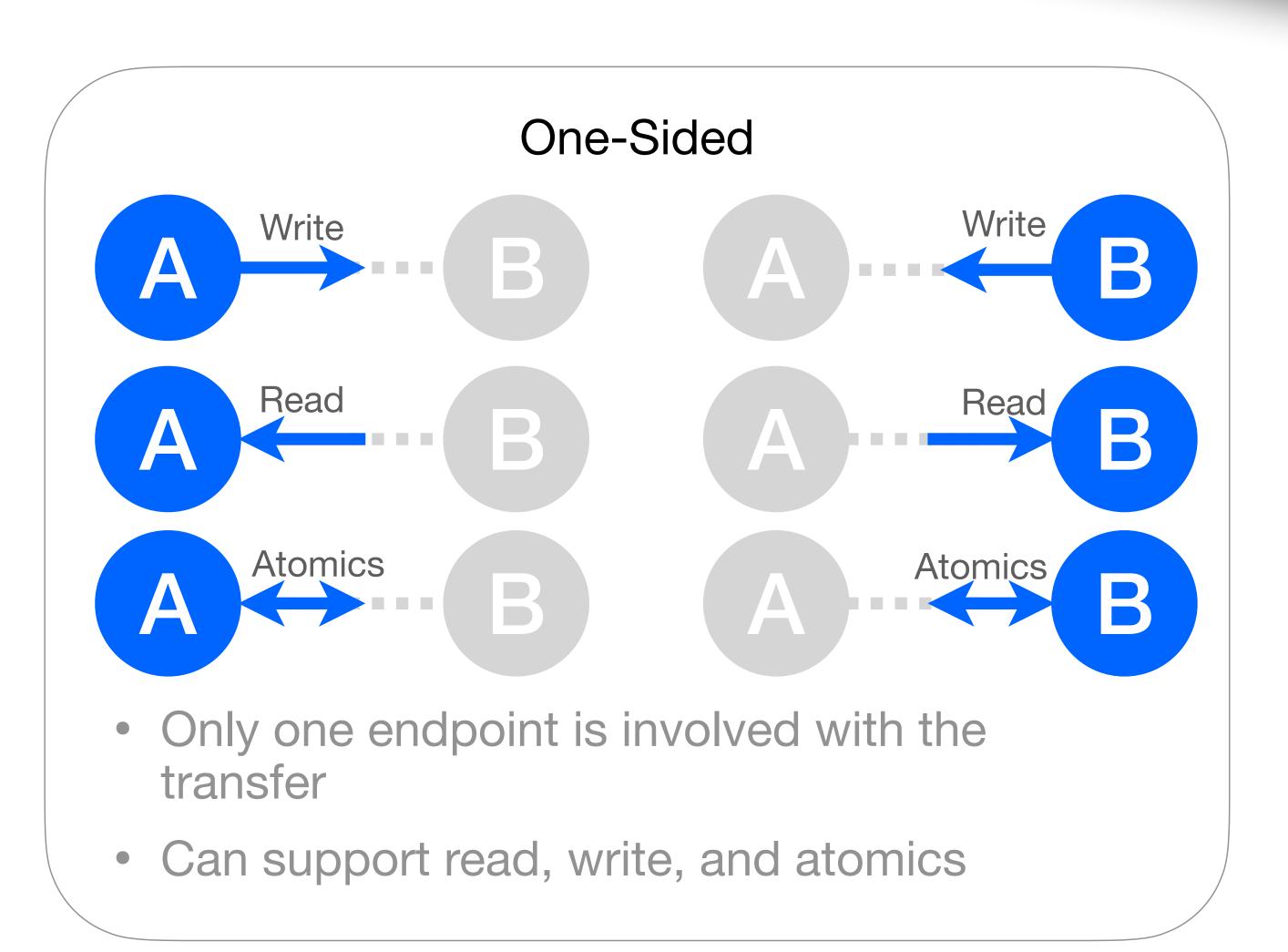
- CPU (local or memory map)
- GPU (CUDA)
- Sensor/FPGA/etc. memory

And then provide pointers to the TakyonBuffer structure and other 3rd party APIs



Two-Sided versus One-Sided Transfers

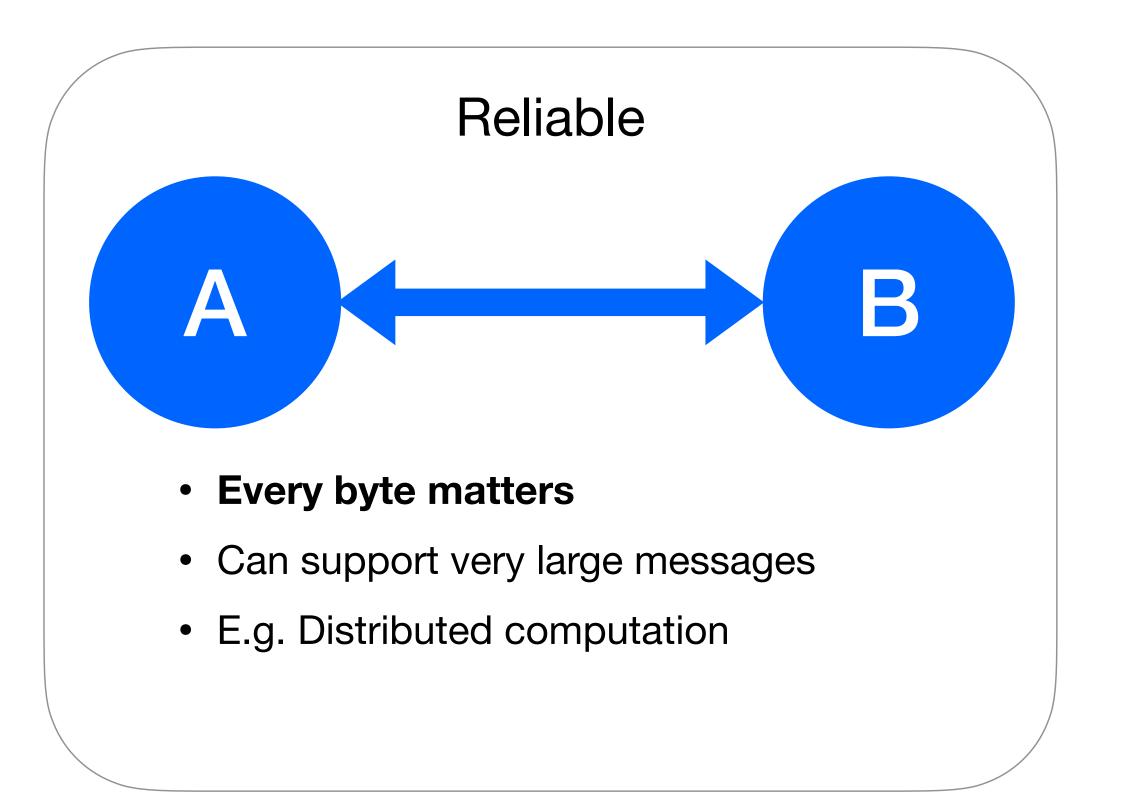


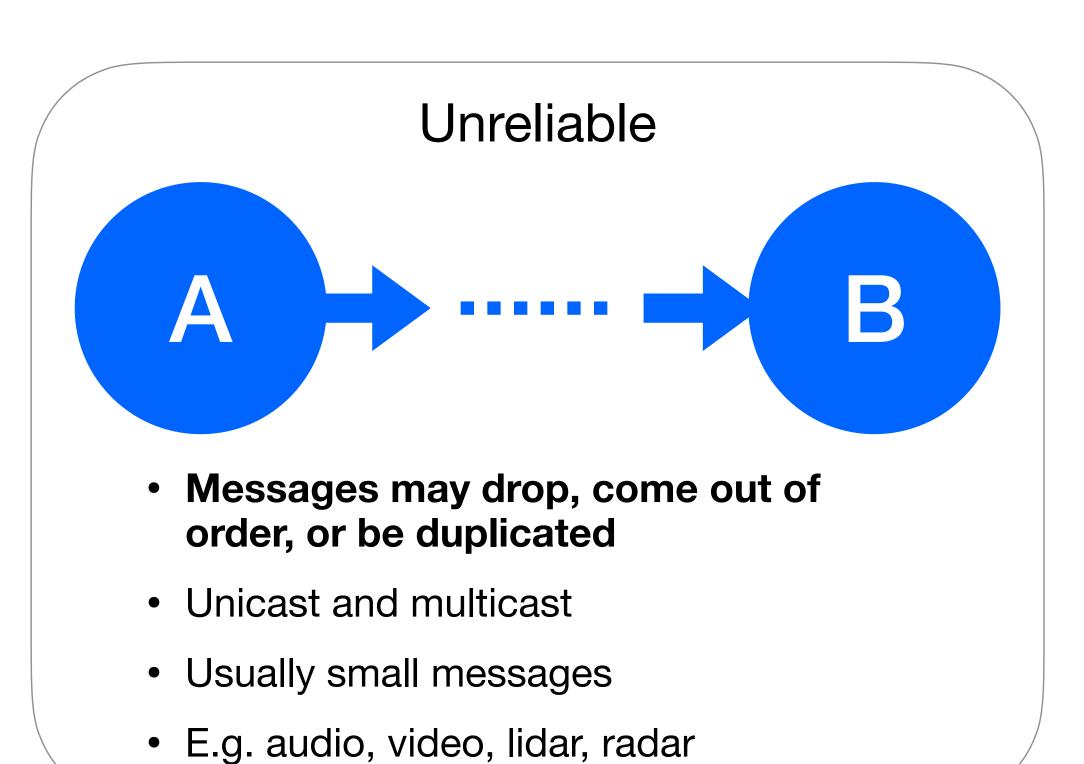


Some Takyon Providers only allow one or the other



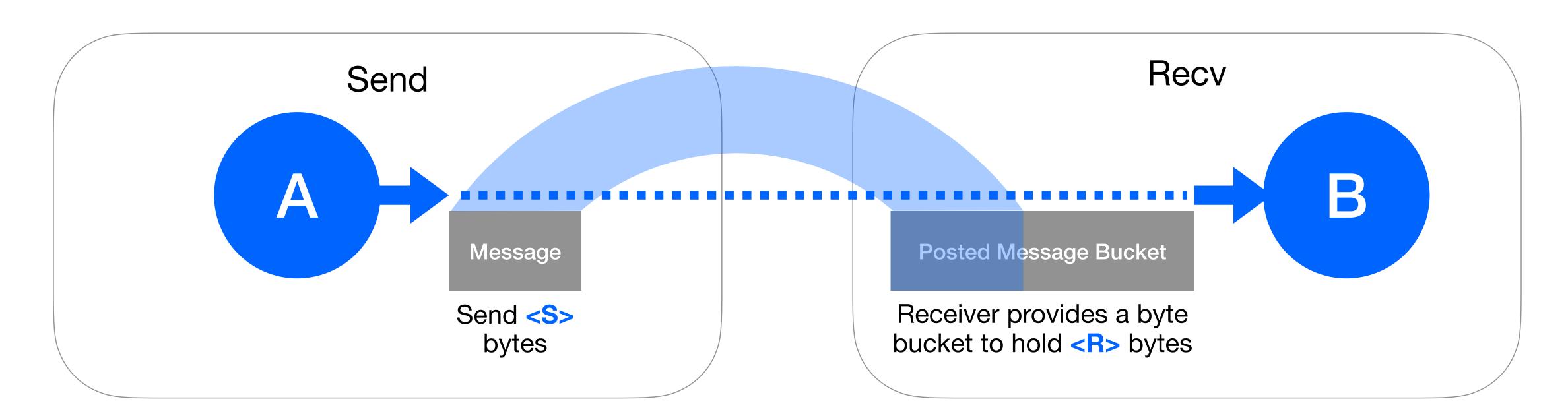
Takyon Supports Reliable and Unreliable Transfers







Two-Sided (Send/Recv) Semantics: Message Size



I.e. sent messages can be smaller than what takyon's recv request provided as a byte bucket



Two-Sided (Send/Recv) Semantics: Message Order

Rule 1: The order of arriving messages is based on one of:

- If the Provider is 'reliable' then the messages will arrive in the same order as sent
- If the Provider is 'unreliable' then the messages may:
 - Arrive in a different order than sent
 - Be dropped and lost forever
 - Be a duplicate of a previously arrived message

Rule 2: The arrived message is put into the recv buffer based on:

- If takyonPostRecvs() IS supported: the order of received messages is defined by the order of posting recv requests
- If takyonPostRecvs() NOT supported: the order of received messages is defined by the order of calling takyonIsRecved()



Blocking versus Non-Blocking Transfers

Interconnects that can support non-blocking usually have a DMA engine

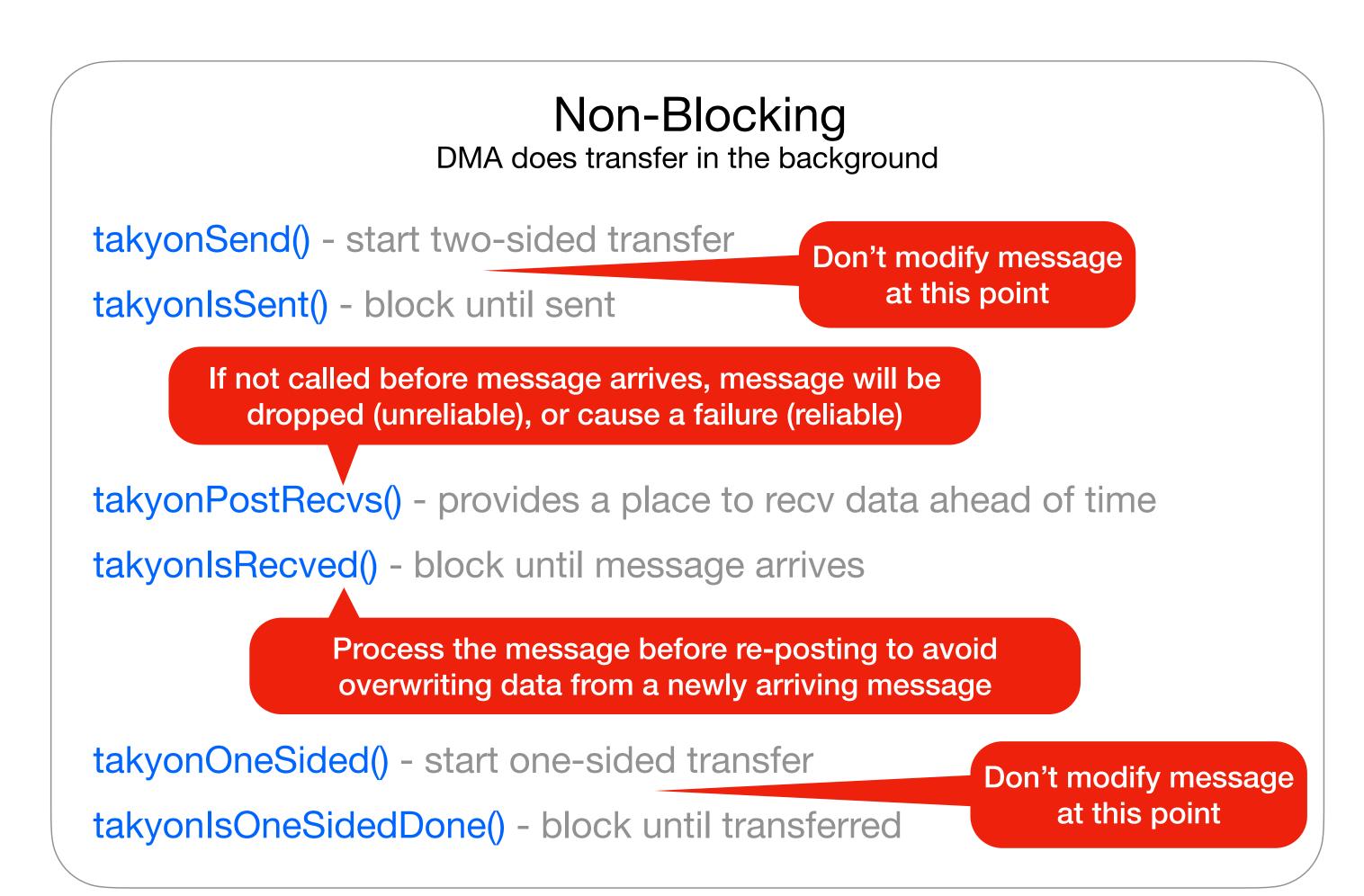
Blocking

CPU does transfer

takyonSend() - Send message and block until message is sent. Memory buffer can be updated when this call is complete.

takyonlsRecved() - Wait for a message to arrive. Memory buffer won't be overwritten until reused by subsequent call this this function.

takyonOneSided() - Transfer message and block until complete. Memory buffer can be updated when this call is complete.





Non-Blocking Notifications and Fences

Send and one-sided completion notifications

• The application can decided if a completion notification should be used or not:

 Since transfers are processed in order, can used a subsequent transfer to see of if previous un-signaled transfer completed. Improves latency and throughput.

Fences

• Forces preceding non-blocking transfers (send, read, write, atomics), where notification is turned off, to complete before the new transfer starts

```
TakyonSendRequest.submit_fence = true;
TakyonOneSidedRequest.submit_fence = true;
```

 This is typically only needed if a preceding 'read' or 'atomic' operation is invoked (changes local memory) just before sending the results of the preceding operations

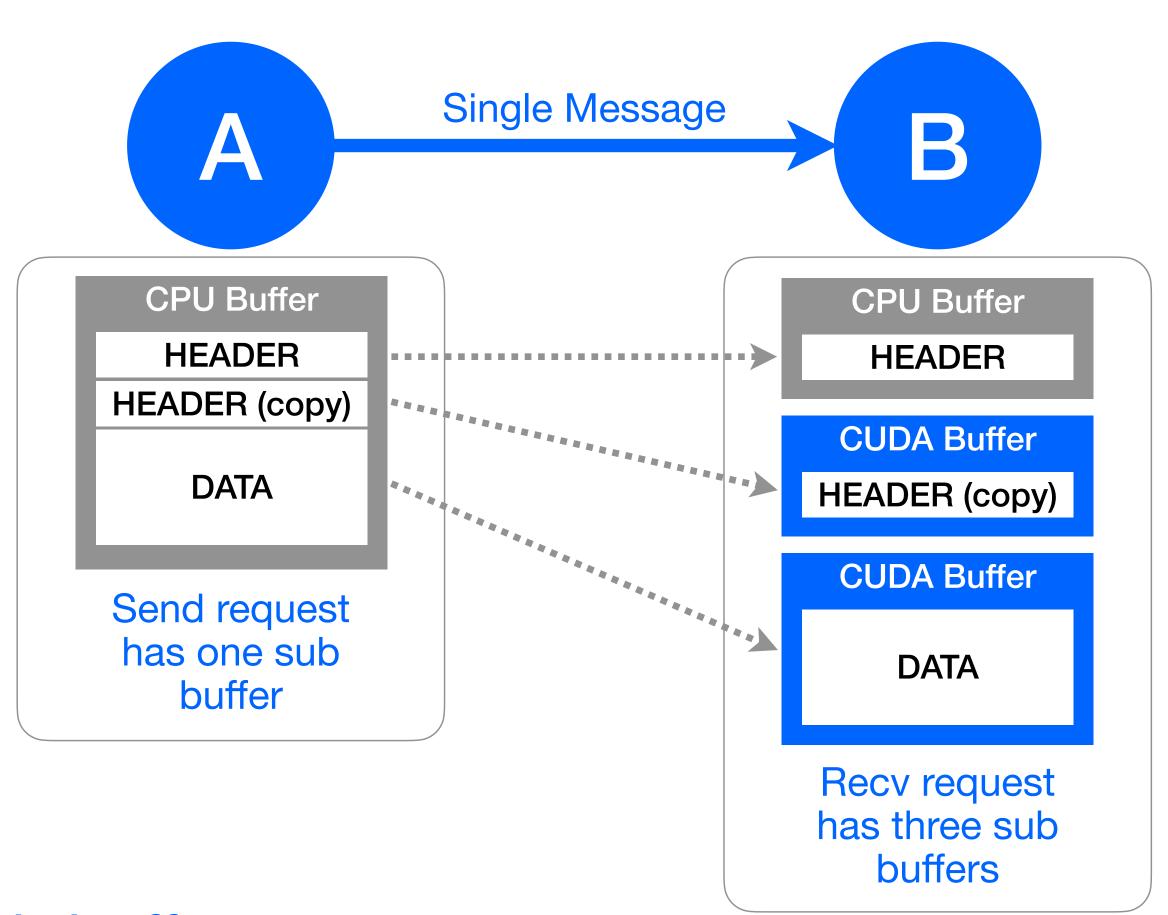


Single Message, Multiple Sub Buffers

Multiple sub buffers may allow for highly organized and optimized processing

Hypothetical Example:

 It's common for GPUs to do heavy processing and CPU does light book keeping, but both need to know the attributes of the data



Some providers only allow one sub buffer per message



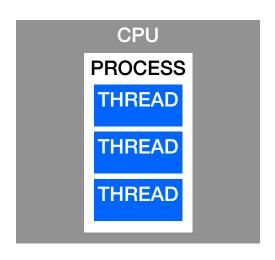
Fault Tolerant Communication

- Detecting degraded communication
 - Disconnect detected (e.g. network is down); i.e. Takyon function return false
 - Timeout (the transfer is not occurring in a reasonable amount of time)
- Handle a degraded communication path
 - Used dynamic path destruction/creation, without effecting other existing paths
 - Some other application defined alternative
- Notes about being fault tolerant
 - Communication API should provided the hooks for fault tolerance
 - Only the app can know what to do when communication degrades
 - Communication paths should be independent (Want to avoid "One light goes out they all go out")

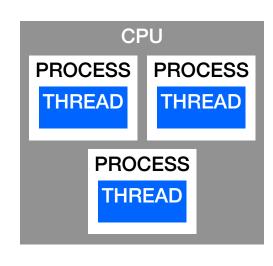
Takyon is not fault tolerant (by design), but does provide fault tolerant hooks



Accelerate Development by Locality Staging



- 1. Start with one process and multiple threads
 - While dataflow is being developed, only need to run a single executable
 - Easier to debug crashes or validate memory leaks/overwrites (e.g. valgrind)

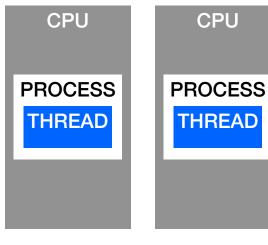


CPU

THREAD

- Move to multiple processes on one CPU
 - Simple way to validate the migration of dataflow, without jumping to multiprocessors





- 3. Move to multiple processors
 - Migration should be simple
 - Can now test for deployment performance

All Takyon examples support this



Looking to the Future

Posible Enhancements

- Strided Transfers
 - Currently avoiding this since common interconnects don't support this
- Publish/Subscribe
 - A potential replacement for the overly complex DDS
 - Could have simplified participants, publishers, subscribers, and QoS
 - Make messages opaque and private (removes need for DDS's intermediate language)
- Collectives: barrier, scatter, gather, all-to-all, reduce, etc.
 - Already done as a separate API with Takyon 1.x, and may be converted to Takyon 2.x
 - Create a complimenting GUI to build and maintain the collective groups visually

CHALLENGE: Is Takyon missing a key feature?



Ultimate Goal: Open Standard





The creation of Takyon inspired a Khronos exploratory group that hinted that the industry is in need of an eHPC Heterogeneous Communication API

It's difficult to find experts who can contribute. Join the next stage of the Khronos Exploratory Group to help determine industry interest

https://www.khronos.org/exploratory/heterogeneous-communication/