

GauGAN/SPADE

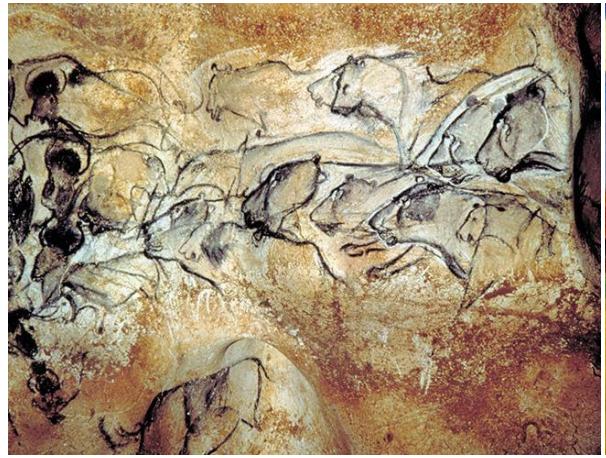
Semantic Image Synthesis with Spatially Adaptive Normalization

Ming-Yu Liu

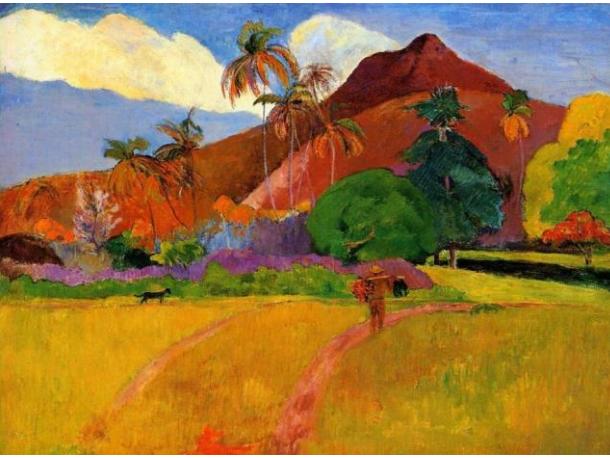
NVIDIA



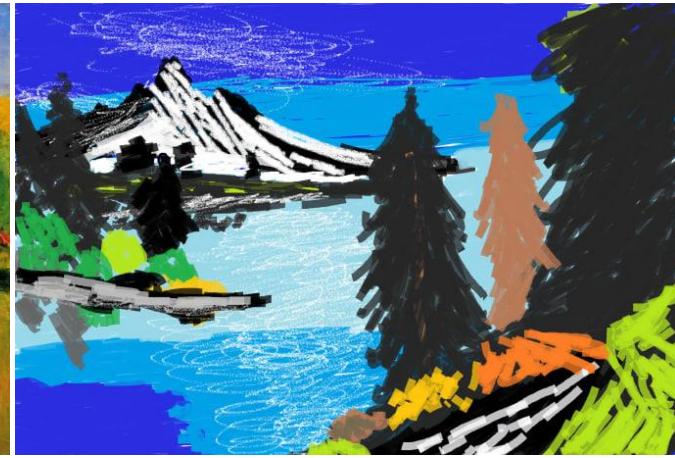
[Image credit: https://www.smithsonianmag.com/history/journey-oldest-cave-paintings-world-180957685/](https://www.smithsonianmag.com/history/journey-oldest-cave-paintings-world-180957685/)



Cave painting



By Gauguin



By fabulouswalrus
using MS Paint



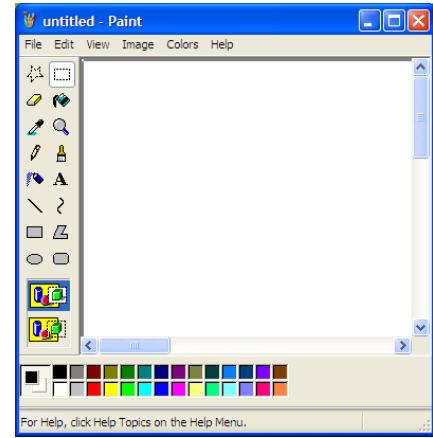
By Pablo Munoz Gomez
using NVIDIA GauGAN



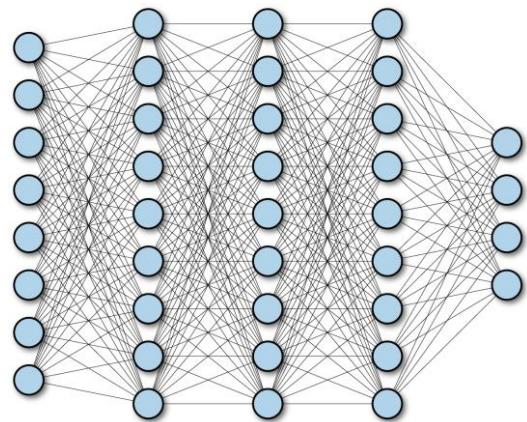
Rock



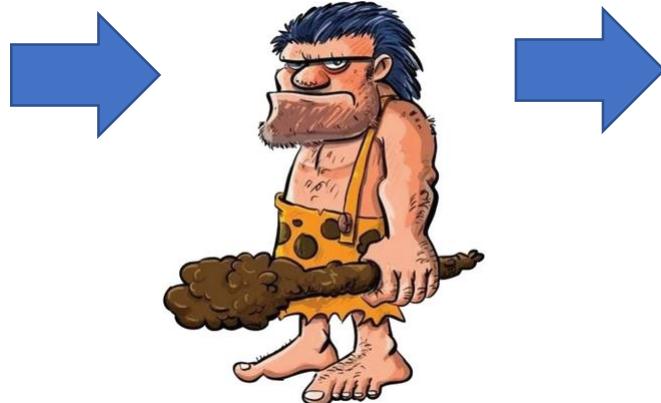
Brush



Digital revolution



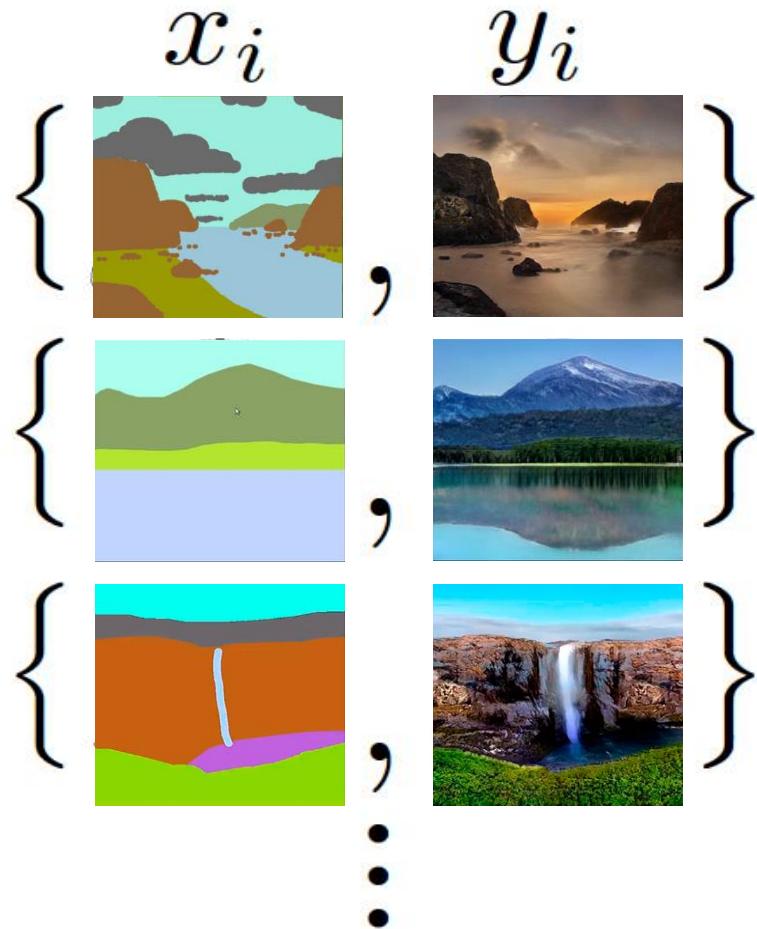
AI revolution



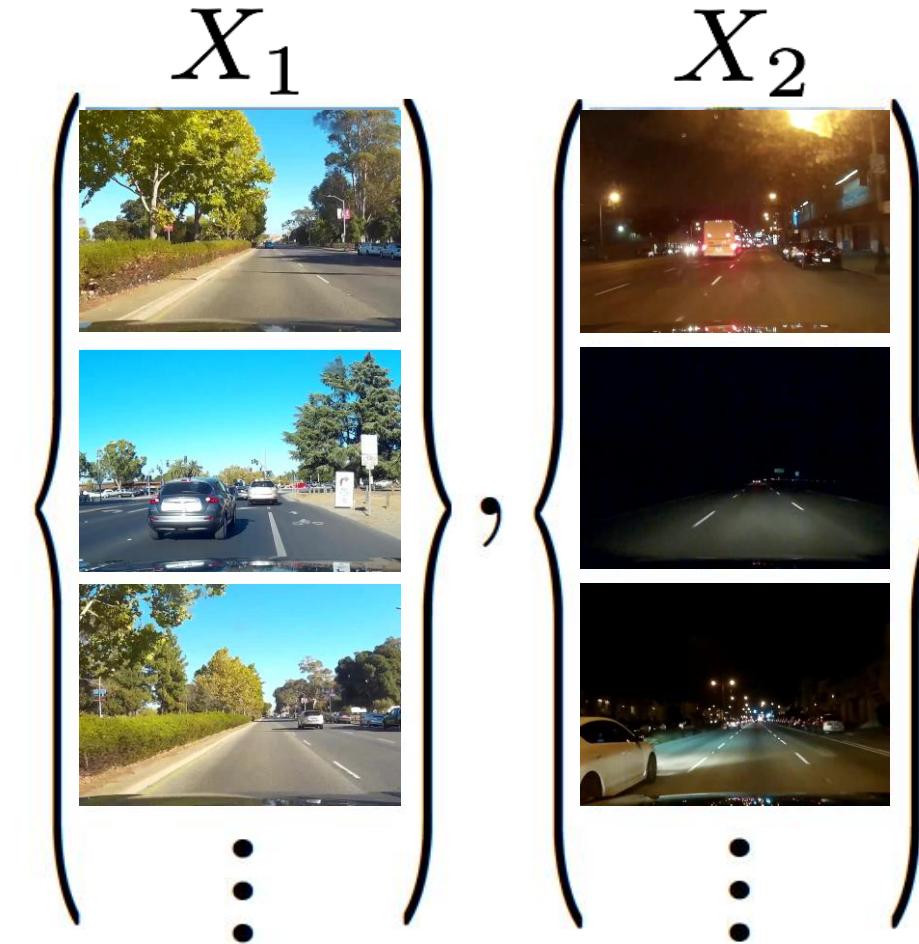
Caveman cartoon image credit: <https://canchamthailand.org/caveman-classic-tees-off-april-6th-reserve-spot-now/>

Supervised vs Unsupervised

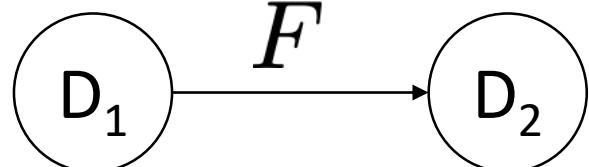
Supervised/Paired/Aligned/Registered



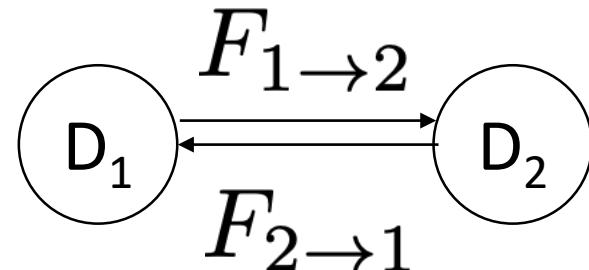
Unsupervised/Unpaired/Unaligned/Unregistered



- Supervised/Paired/Aligned/Registered
 - Image Analogy (Hertzmann et. al. 2001)
 - pix2pix (Isola et. al. 2017)
 - CRN (Chen et. al. 2017)
 - BicycleGAN (Zhu et. al. 2017)
 - pix2pixHD (Wang et. al. 2018)
 - SIMS (Qi et. al. 2018)
 - SPADE (Park et. al. 2019)
 - ...



- Unsupervised/Unpaired/Unaligned/Unregistered
 - CoupledGAN (Liu et. al. 2016)
 - DTN (Taigman et. al. 2017)
 - DiscoGAN (Kim et. al. 2017)
 - CycleGAN (Zhu et. al. 2017)
 - SimGAN (Shrivastava et. al. 2017)
 - DualGAN (Yi et. al. 2017)
 - UNIT (Liu et. al. 2017)
 - MUNIT, 2018 (Huang et. al. 2018)
 - DRIT (Lee et. al. 2018)
 - XGAN (Royer et. al. 2018)
 - GANimorph (Gokaslan et. al. 2018)
 - OST (Benaim et. al. 2018)
 - FUNIT (Liu et. al. 2019)
 - ...



Fill/brush color:



Brush shape:



Brush size: 22



GauGAN Beta

Bush

Cloud

Dirt

Grass

Gravel

Hill

Mountain

Plant

River

Road

Rock

Sand

Sea

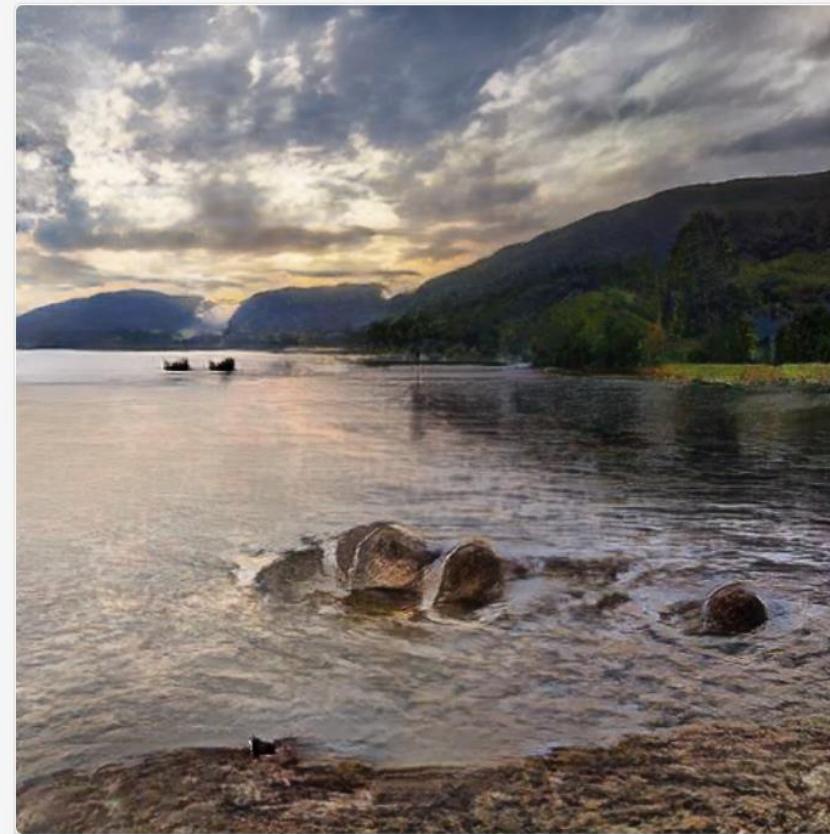
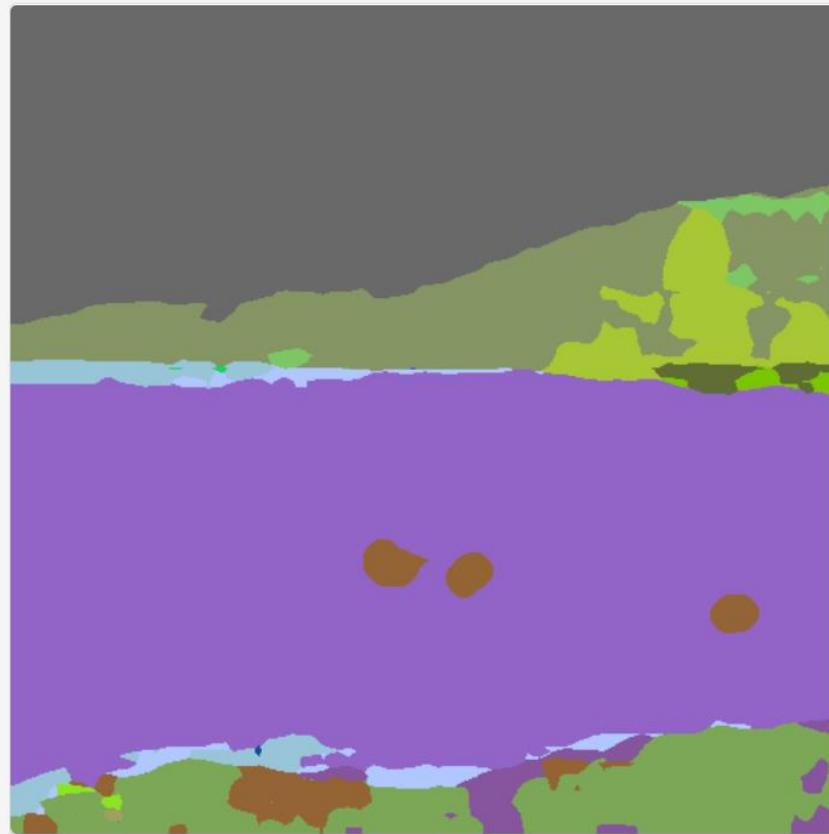
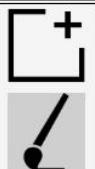
Sky

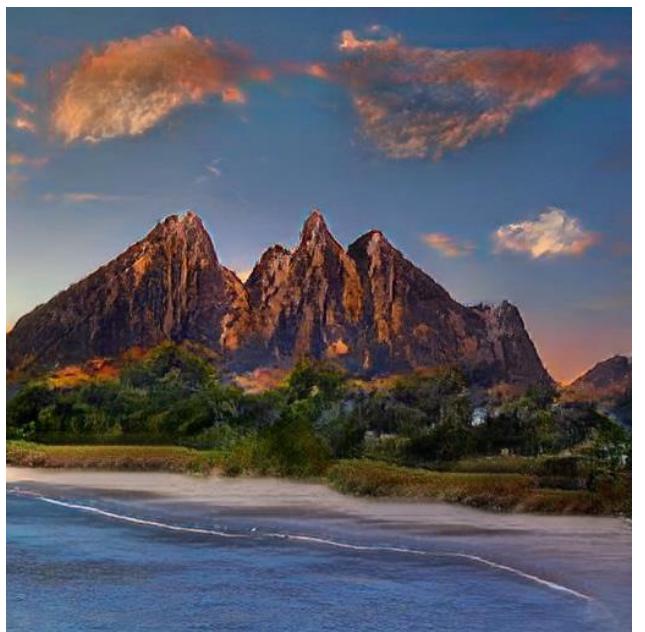
Snow

Stone

Tree

Water





@Soerenpepp



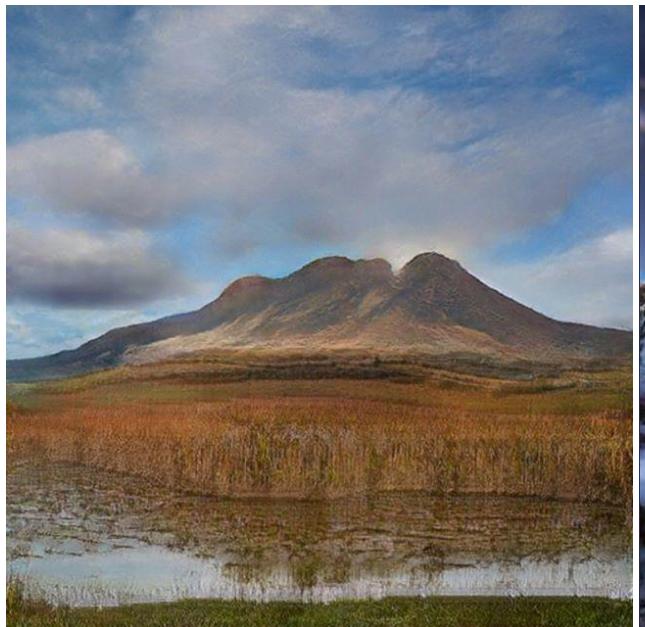
@jonathanfly



@torans_photo123



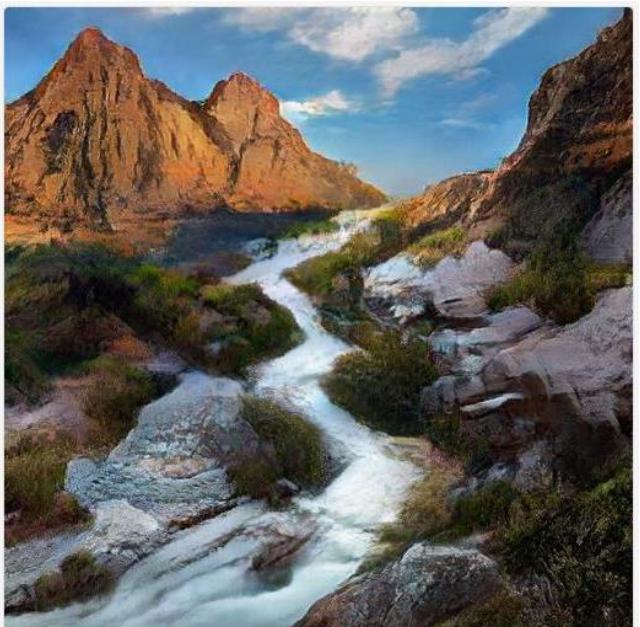
@inning0



@frasSmith



@seahcb



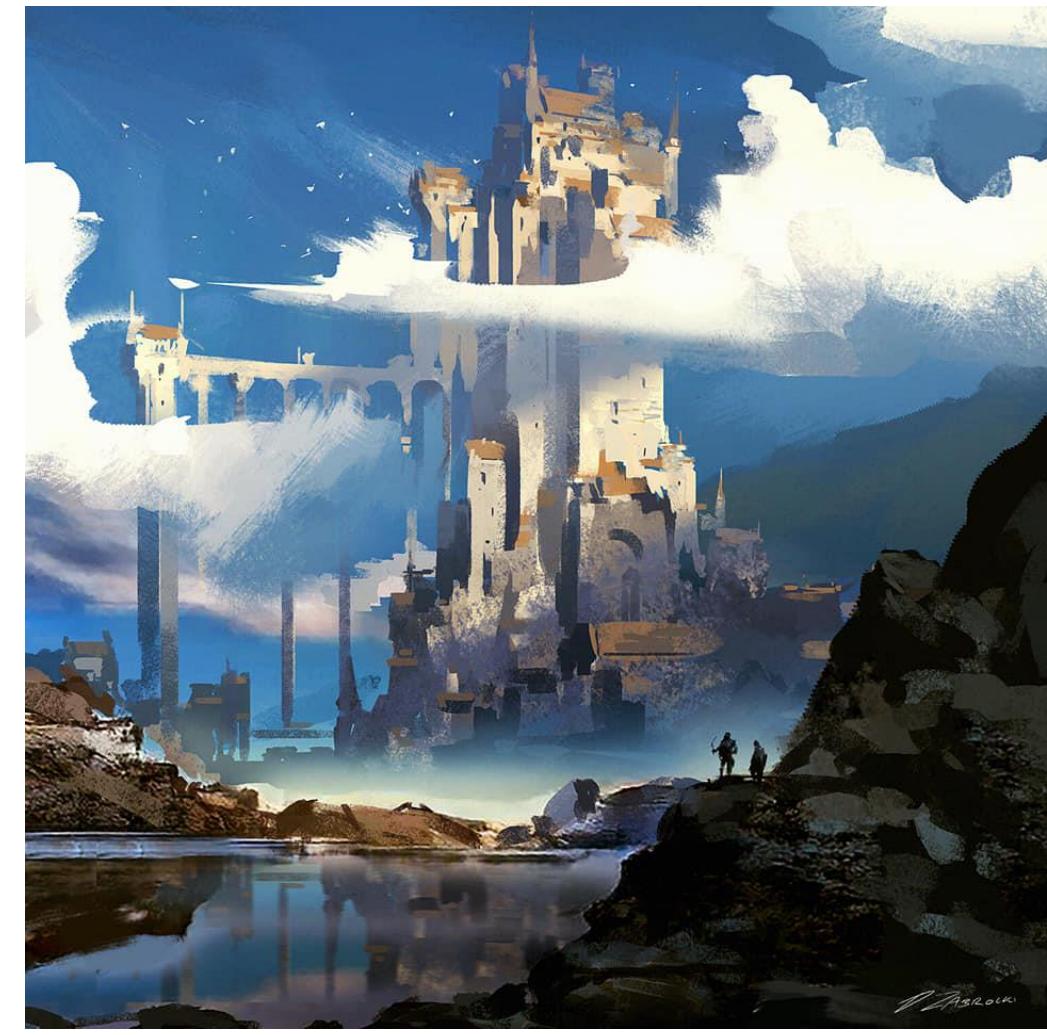
@LipComeralla



Tyler Schatz



@coliewertz



@darekzabrocki



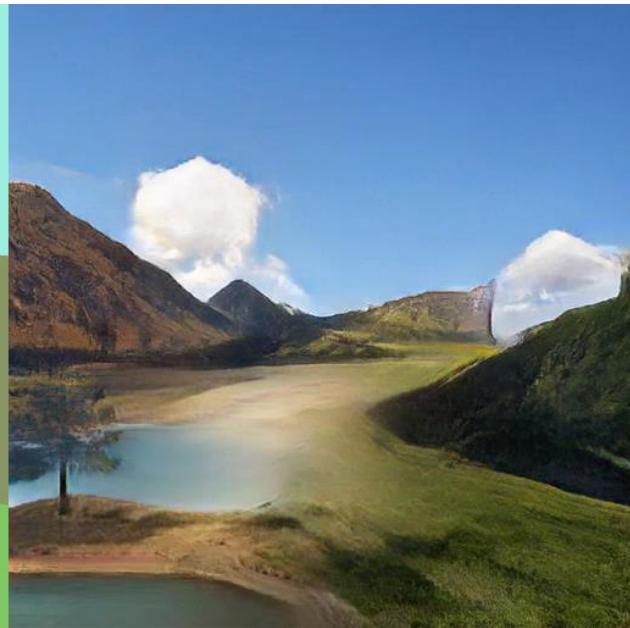
AI generated image



By Jay Axe

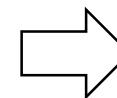
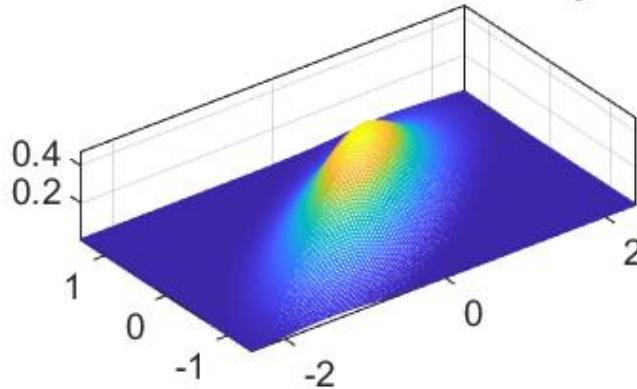
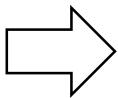
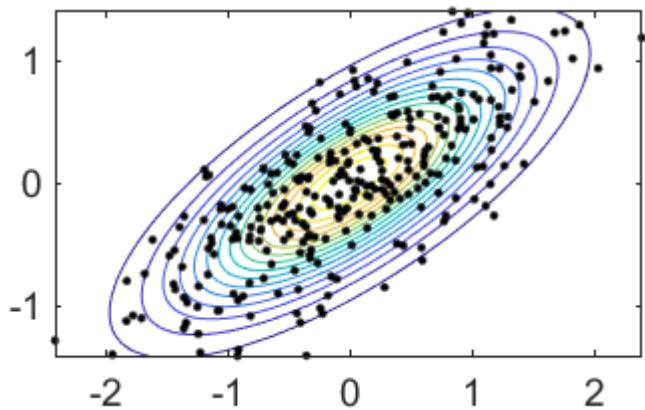


By Neil Bickford



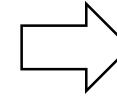
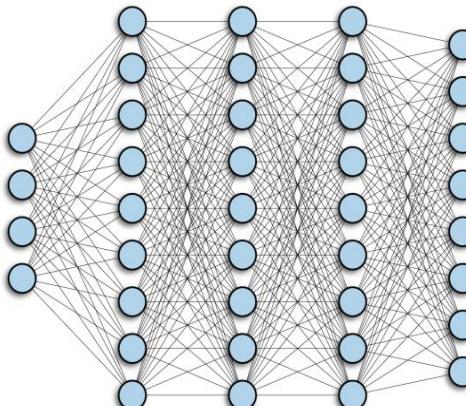
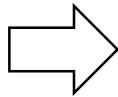
How we achieve it?

Deep Generative Modeling



Generate new 2D Gaussian samples

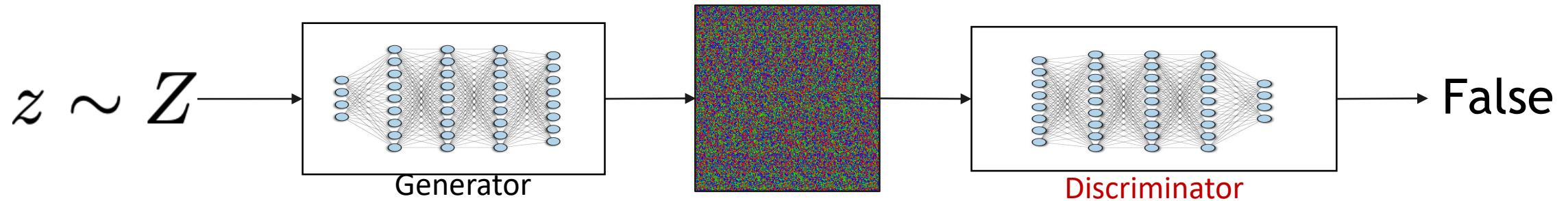
$$f(x|\mu, \Sigma) = \frac{1}{\sqrt{(2\pi)^d \det(\Sigma)}} \exp\left(-\frac{(x-\mu)^T \Sigma^{-1} (x-\mu)}{2}\right)$$



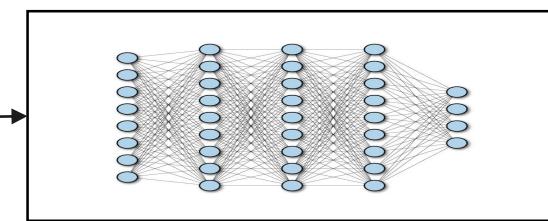
Generate new images

$$f(z) = \frac{1}{2\pi^{\frac{d}{2}}} e^{\frac{-z^2}{2}}$$

Generative Adversarial Networks



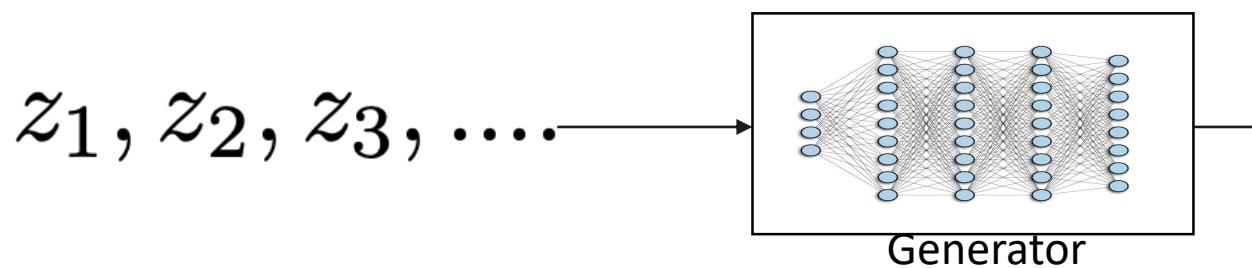
~



Discriminator

True

After training the
model for a while



Conditional Generative Adversarial Networks

modeling

$$p_{X|Y}$$

sampling

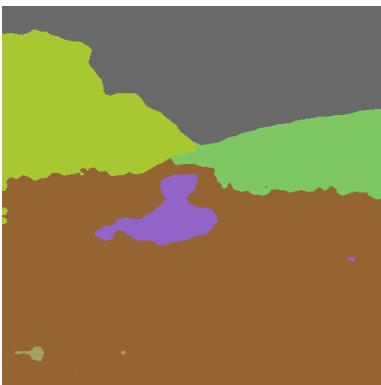
$$z \sim Z, y \sim Y$$

Segmentation Mask–Conditional GANs

$z \sim Z, y_1 \sim Y$



$z \sim Z, y_2 \sim Y$



$z \sim Z, y_3 \sim Y$

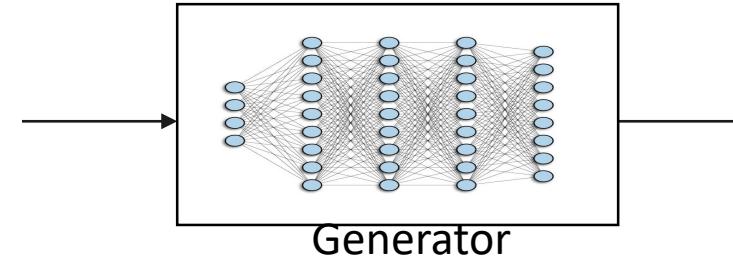
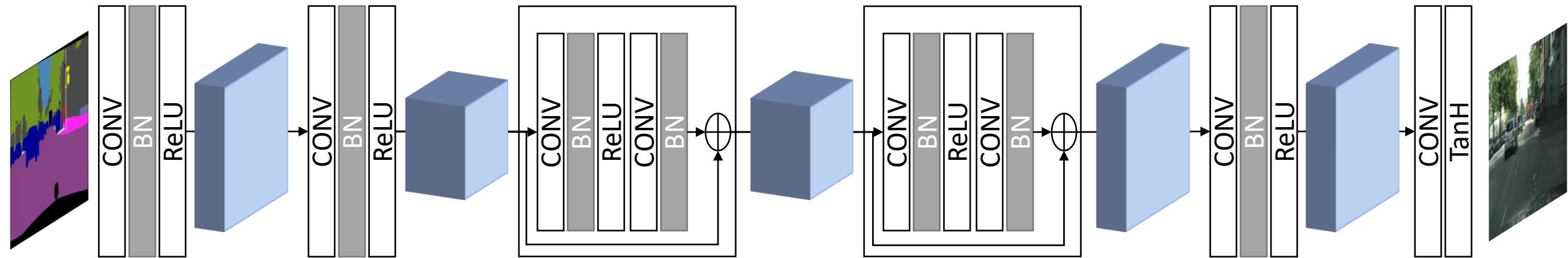


Illustration of pix2pixHD Generator Design



- Previous SOTA method for GAN-based semantic image synthesis
- ResNet-based encoder—decoder architecture
- Work nicely only on highly constrained scenes
- Utilize BatchNorm (BN) or InstanceNorm (IN) in the generator

[pix2pixHD: High-Resolution Image Synthesis and Semantic Manipulation with Conditional GANs](#)

Ting-Chun Wang, Ming-Yu Liu, Jun-Yan Zhu, Andrew Tao, Jan Kautz, Bryan Catanzaro

Conference on Computer Vision and Pattern Recognition (CVPR) Oral 2018, Salt Lake City, Utah

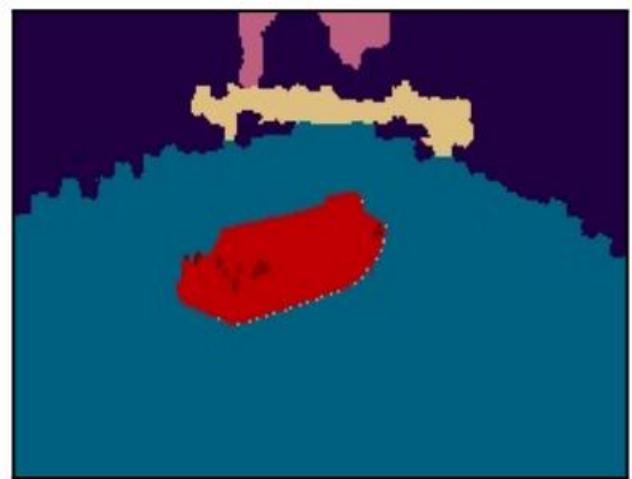
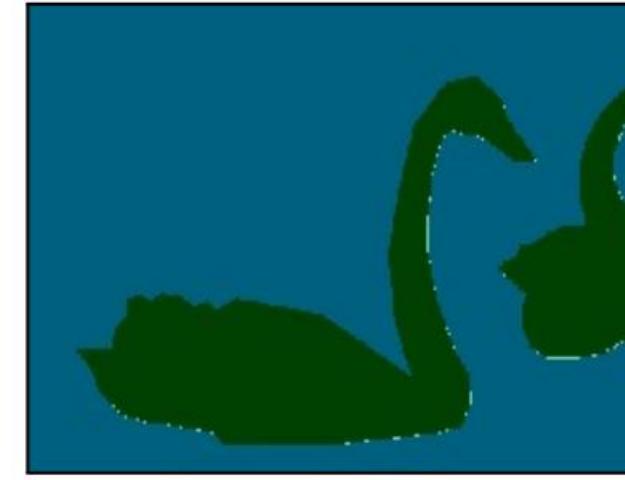
pix2pixHD results

Input labels

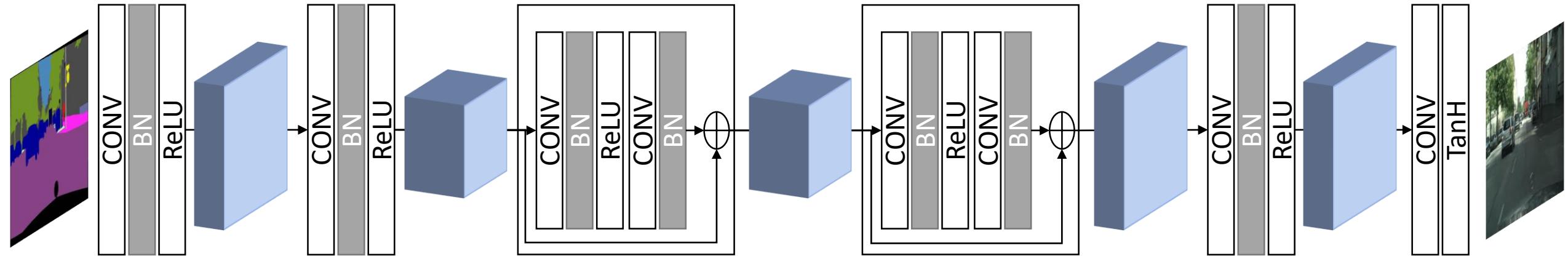


Synthesized image





BN: Batch Normalization



$$\tilde{h}_{n,c,y,x}^{(l)} = \boxed{\gamma_c^{(l)}} \frac{h_{n,c,y,x}^{(l)} - \mu_c^{(l)}}{\sigma_c^{(l)}} + \boxed{\beta_c^{(l)}}$$

$$\mu_c^{(l)} = \frac{1}{NHW} \sum_{n,y,x} h_{n,c,y,x}^{(l)}$$

$$\sigma_c^{(l)} = (\frac{1}{NHW} \sum_{n,y,x} (h_{n,c,y,x}^{(l)})^2) - \mu_c^{(l)2}$$

Batch Normalization: Accelerating Deep Network Training by Reducing Internal Covariate Shift
Sergey Ioffe, Christian Szegedy
International Conference on Machine Learning (ICML) 2015, Lille, France,

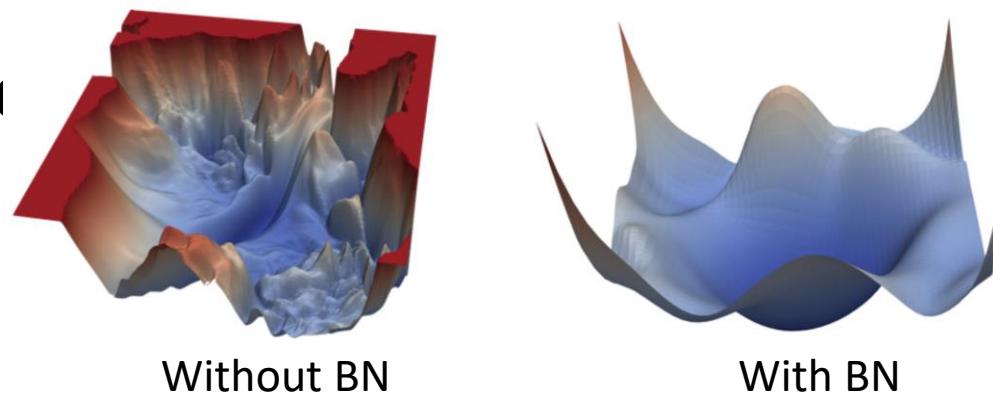
Why Batch Normalization?

- Initial hypothesis: reducing covariance shift in internal activations

Why Batch Normalization?

Loss landscape illustration

- ~~Initial hypothesis: reducing covariance shift in internal activations~~
- New hypothesis #1: leading to smoother optimization landscape
- New hypothesis #2: leading to length-direction decoupling of the weight space -> faster convergence rate

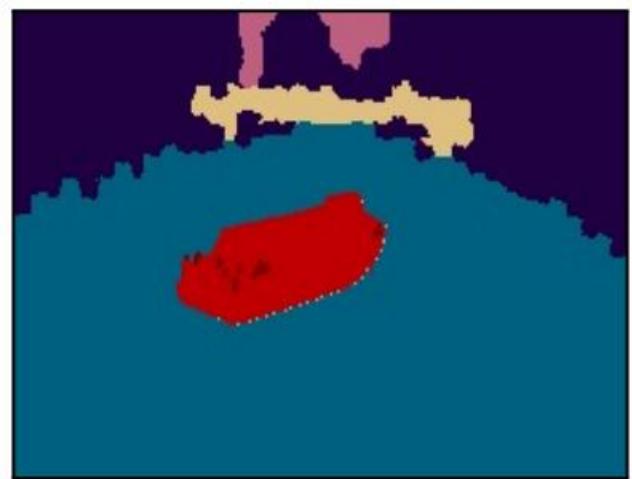
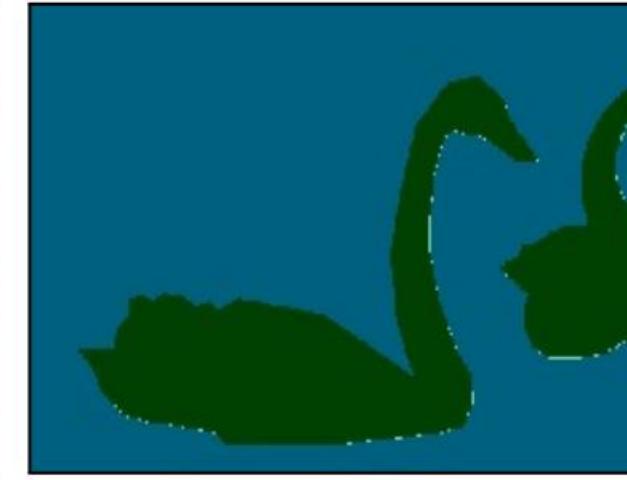


$$\tilde{w} = \frac{\gamma}{\|w\|_s} w$$

length

direction

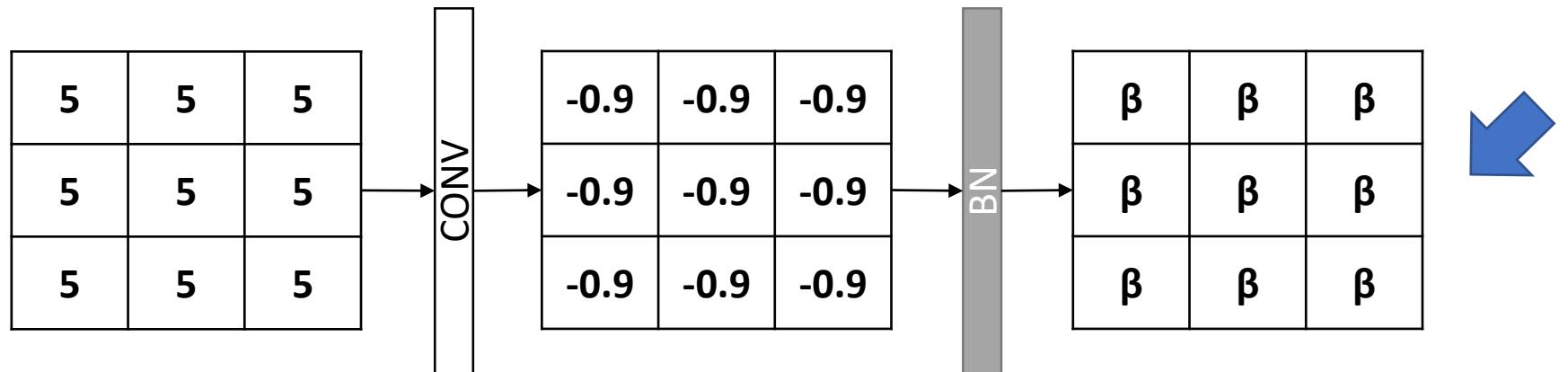
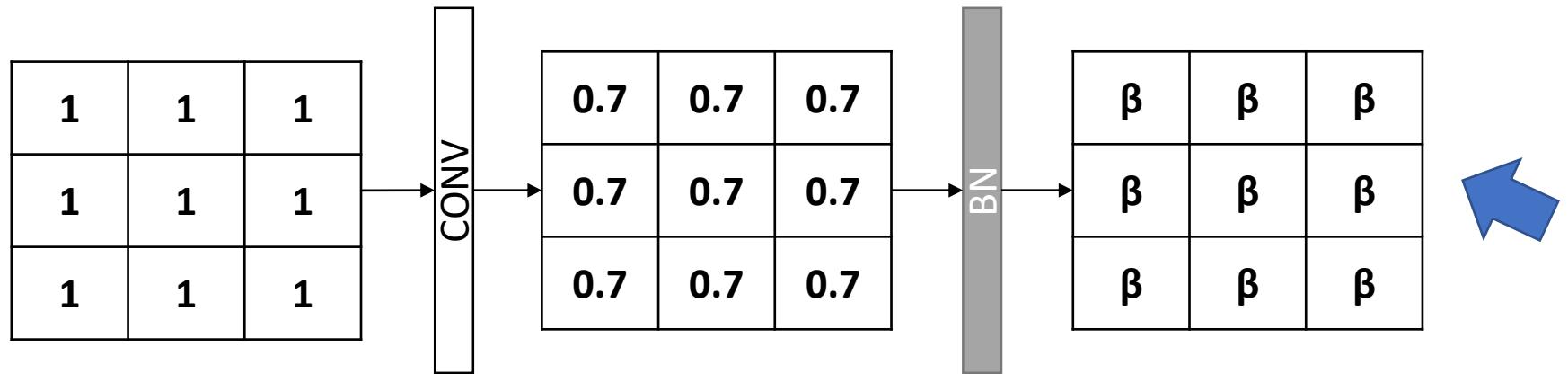
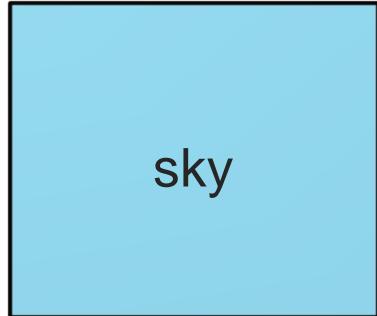
The diagram illustrates the effect of Batch Normalization on the weight vector w . The original vector w is shown as a green rectangle. It is scaled by a factor γ (indicated by a red box) and divided by its L_s norm (indicated by a green box), resulting in the normalized vector \tilde{w} .



Issue with using Batch Normalization for Semantic Image Synthesis

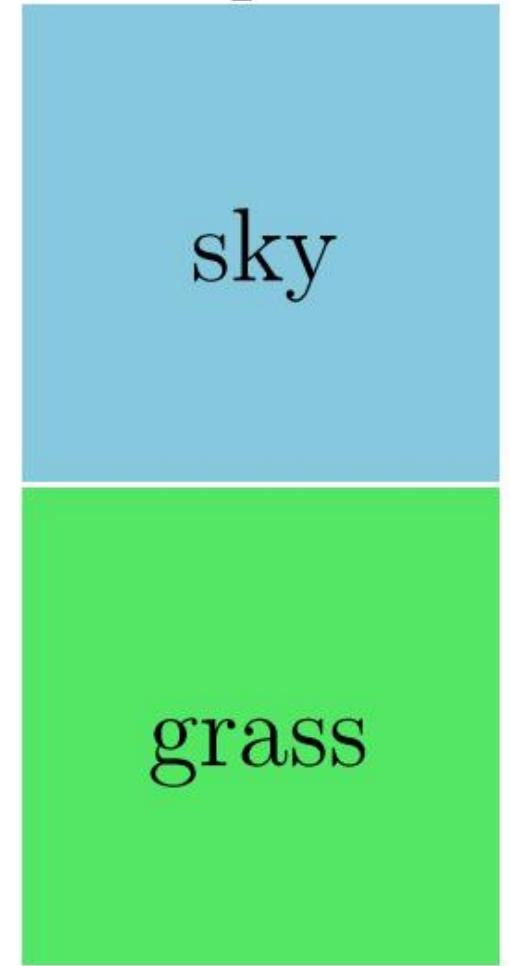
- It tends to wash away semantic input information.

$$\tilde{h}_{n,c,y,x}^{(l)} = \gamma_c^{(l)} \frac{h_{n,c,y,x}^{(l)} - \mu_c^{(l)}}{\sigma_c^{(l)}} + \beta_c^{(l)}$$

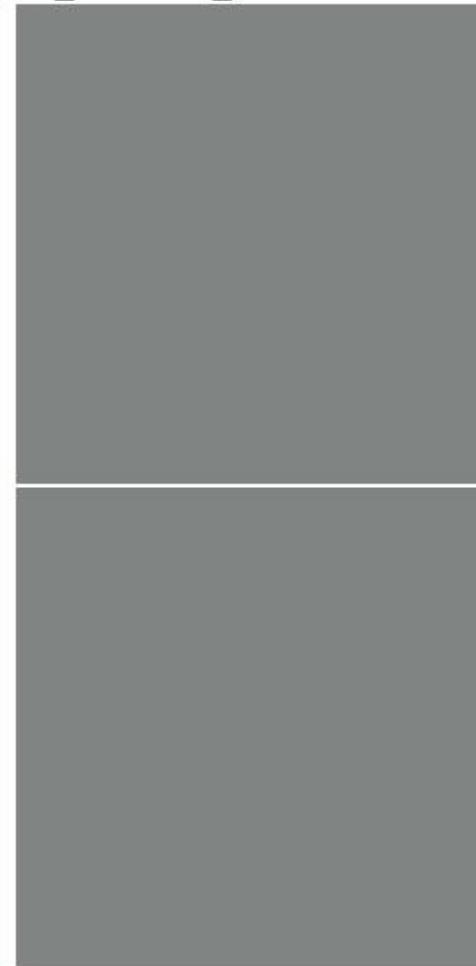


Become identical, all the semantic information is gone.

input



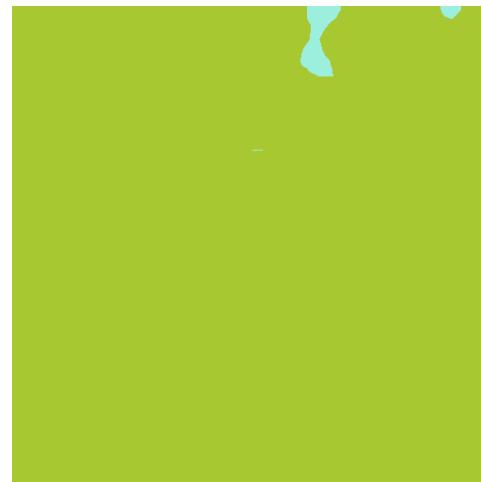
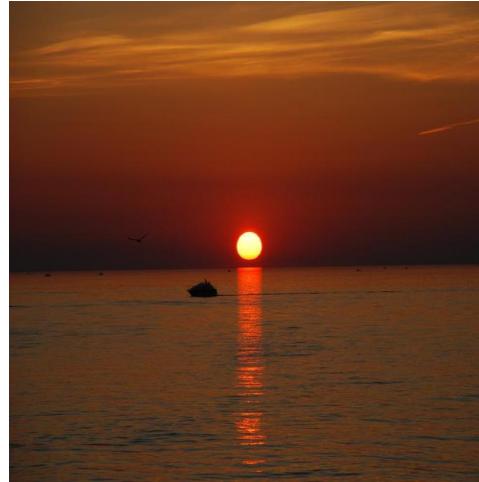
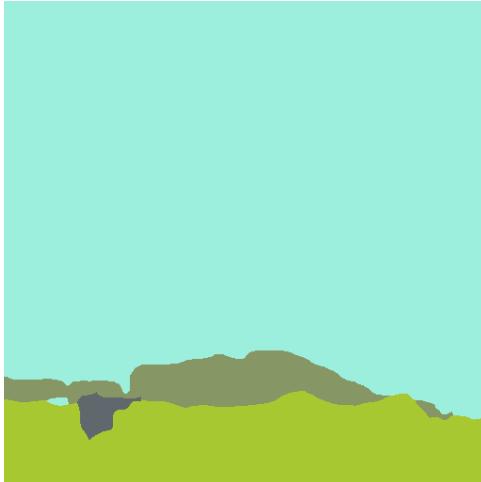
pix2pixHD



SPADE



Segmentation masks often contains large uniform regions



SPADE: SPatially Adaptive DEnormalization

BN

$$\tilde{h}_{n,c,y,x}^{(l)} = \gamma_c^{(l)} \frac{h_{n,c,y,x}^{(l)} - \mu^{(l)}}{\sigma_c^{(l)}} + \beta_c^{(l)}$$

SPADE

$$\tilde{h}_{n,c,y,x}^{(l)} = \boxed{\gamma_{c,y,x}^{(l)}(s)} \frac{h_{n,c,y,x}^{(l)} - \mu^{(l)}}{\sigma_c^{(l)}} + \boxed{\beta_{c,y,x}^{(l)}(s)}$$

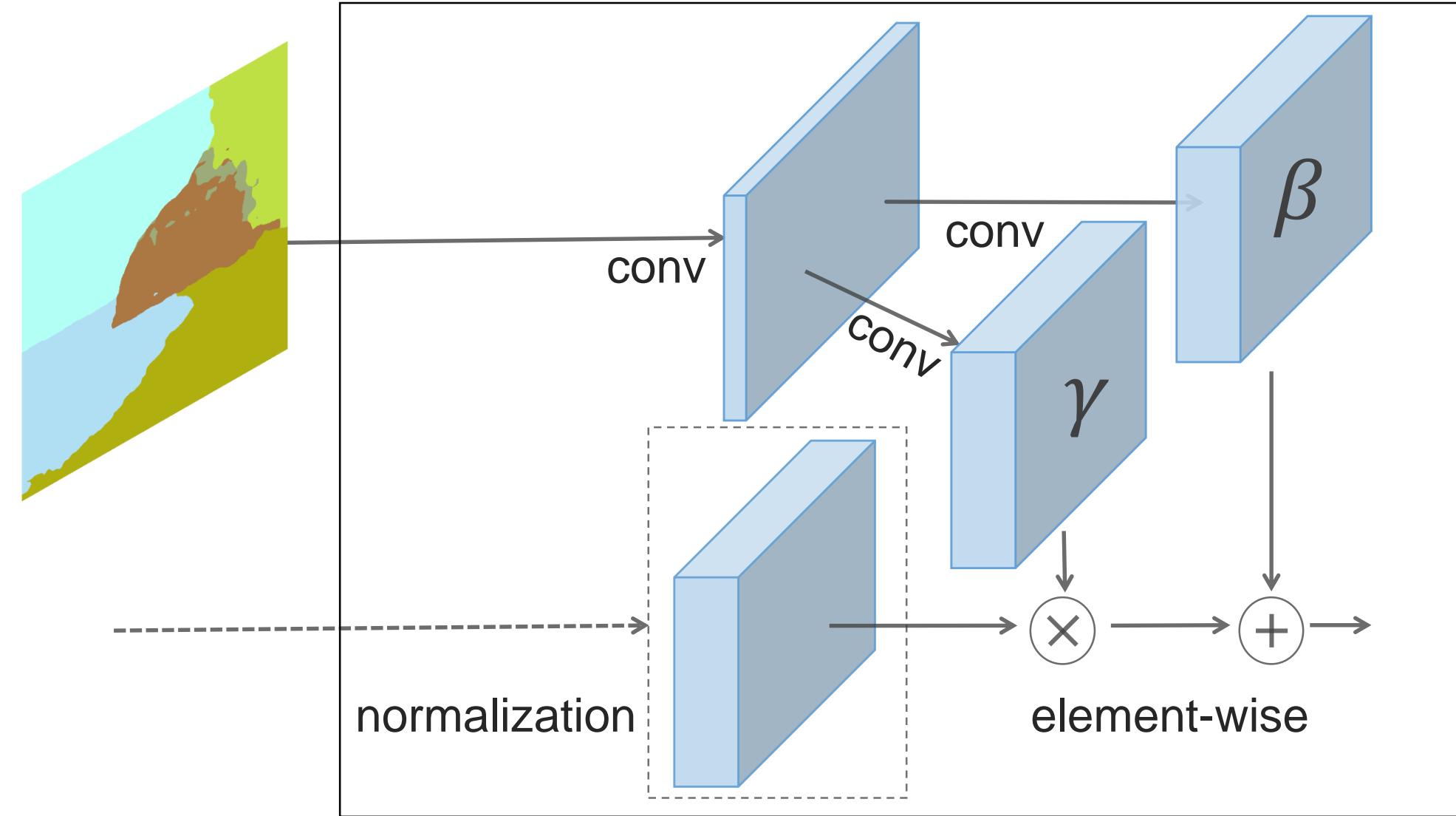
Spatially varying quantity

Depending on the input segmentation mask s

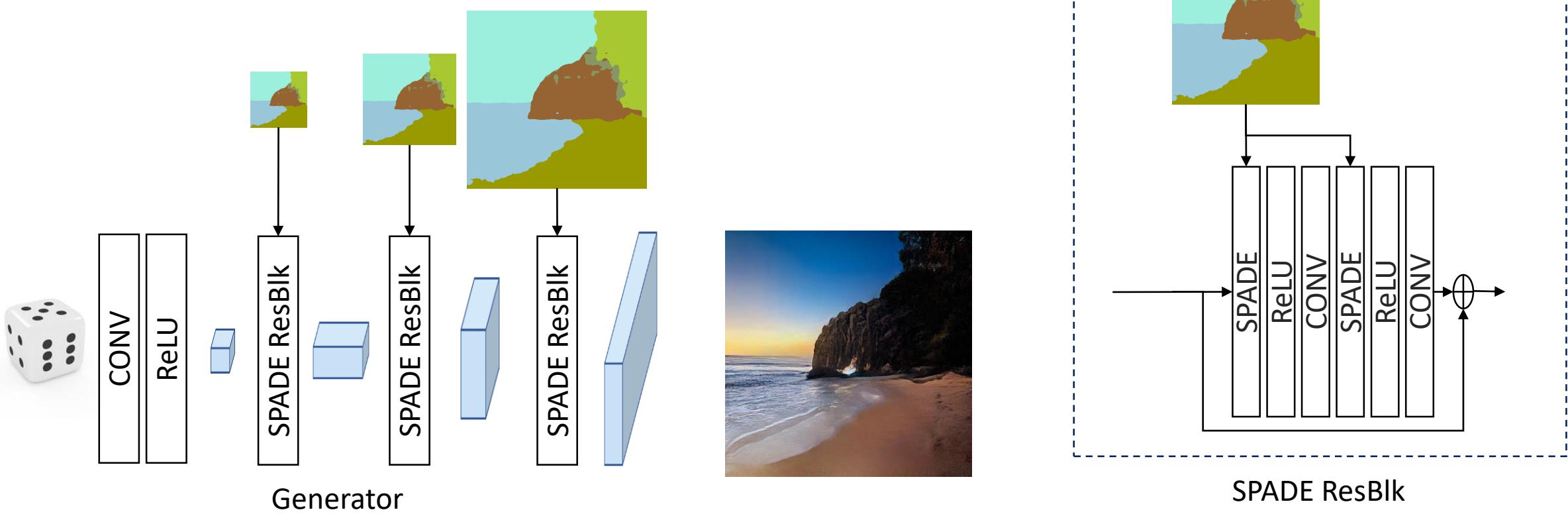
Information removed by normalization can be added back by gamma and beta

SPADE

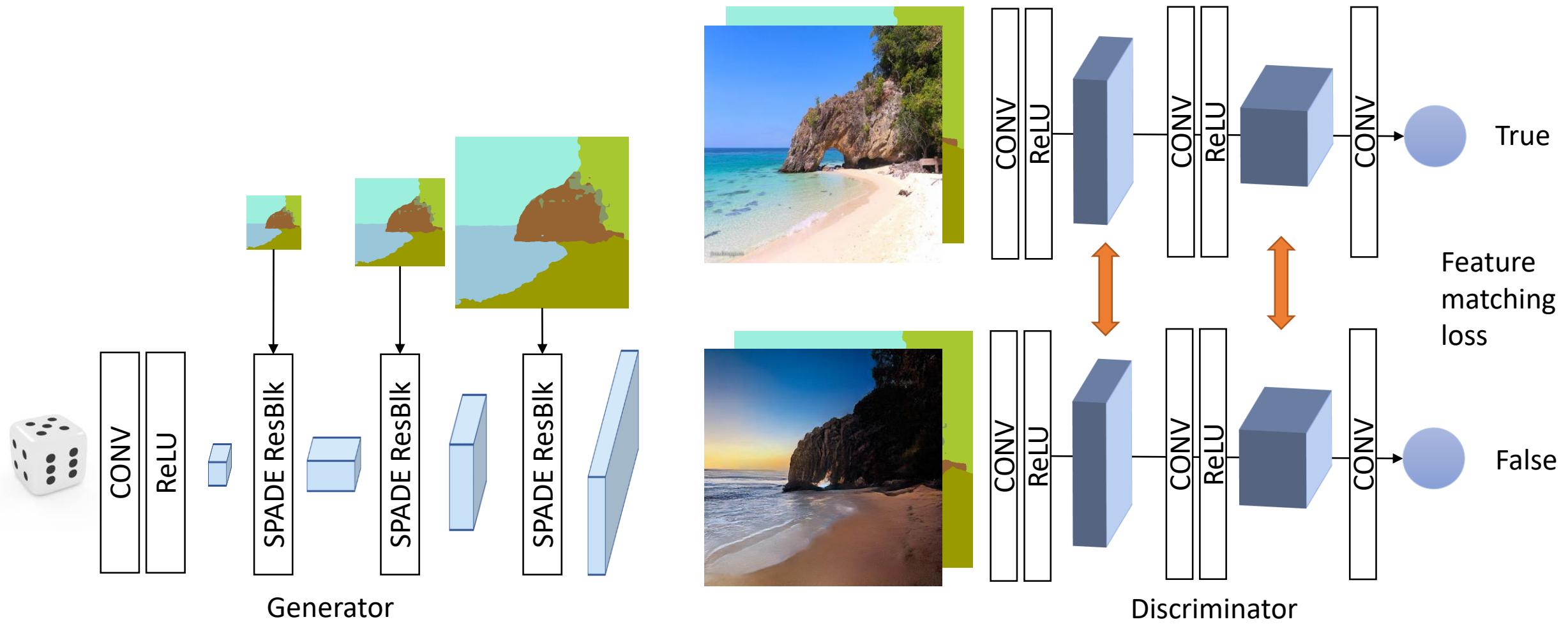
$$\tilde{h}_{n,c,y,x}^{(l)} = \gamma_{c,y,x}^{(l)}(s) \frac{h_{n,c,y,x}^{(l)} - \mu^{(l)}}{\sigma_c^{(l)}} + \beta_{c,y,x}^{(l)}(s)$$



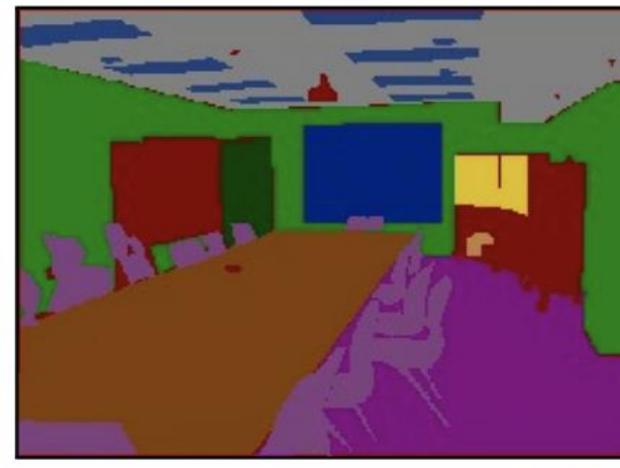
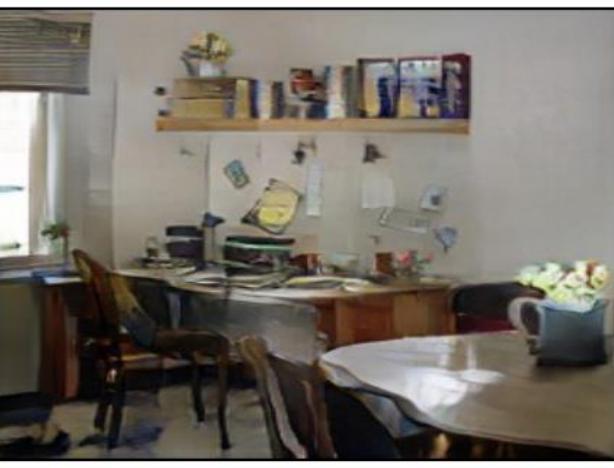
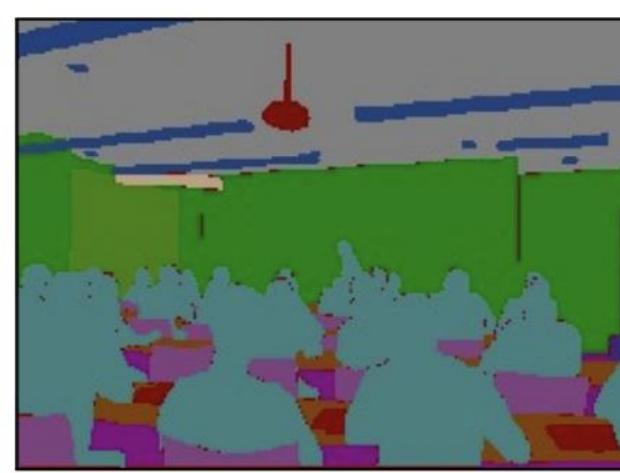
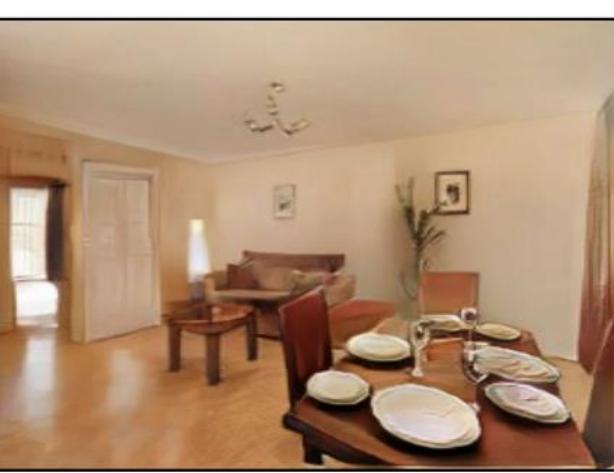
SPADE-based Generator

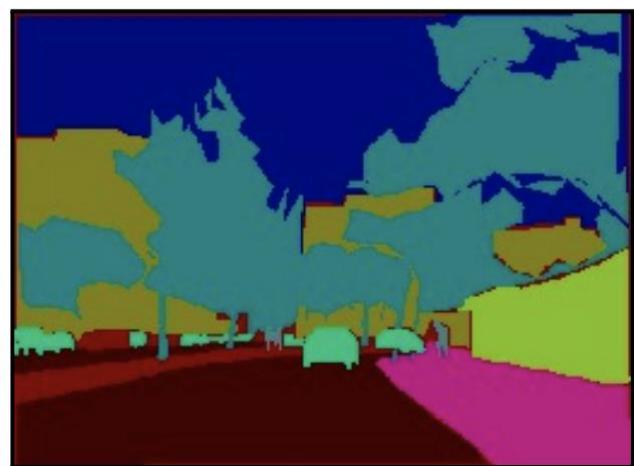
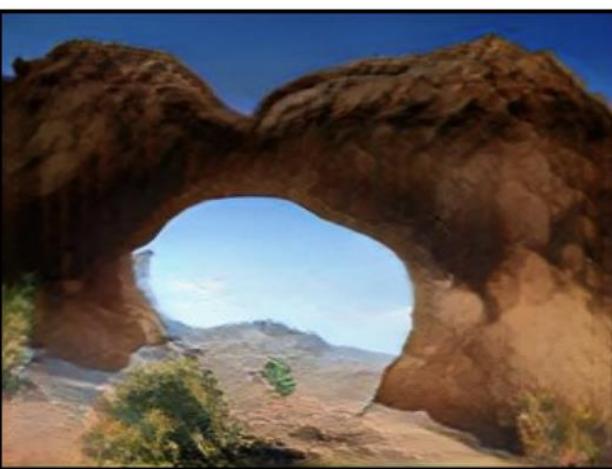


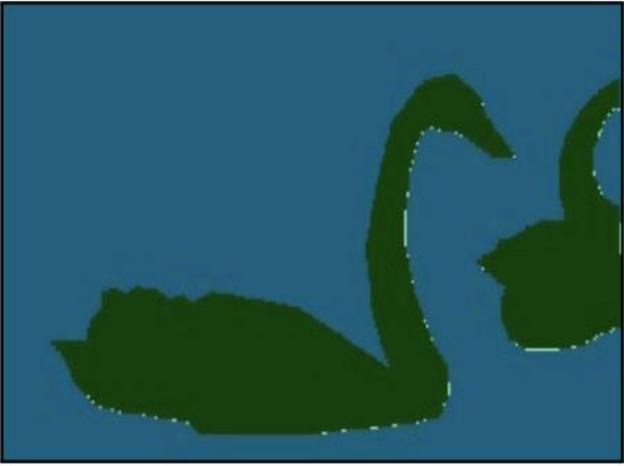
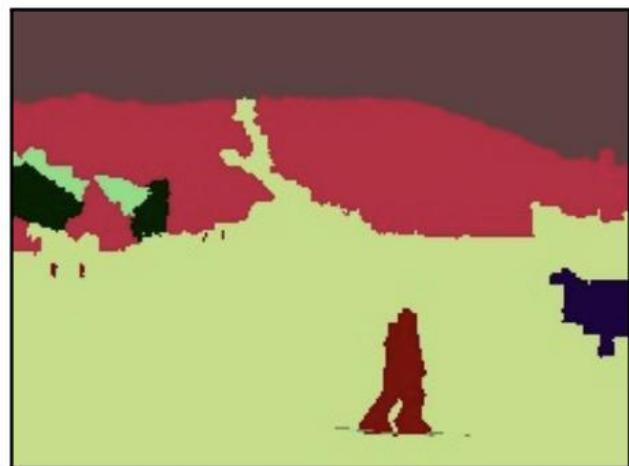
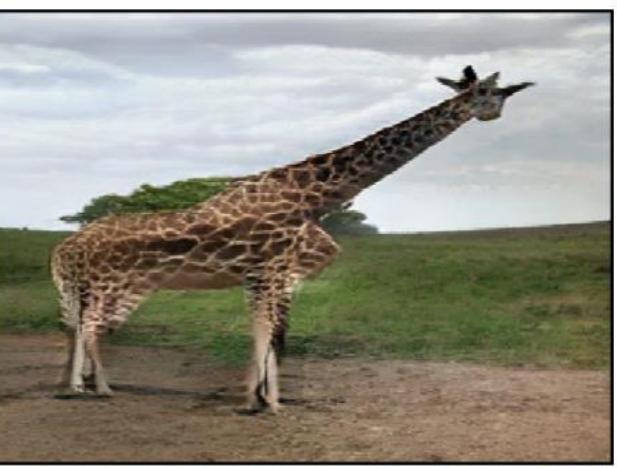
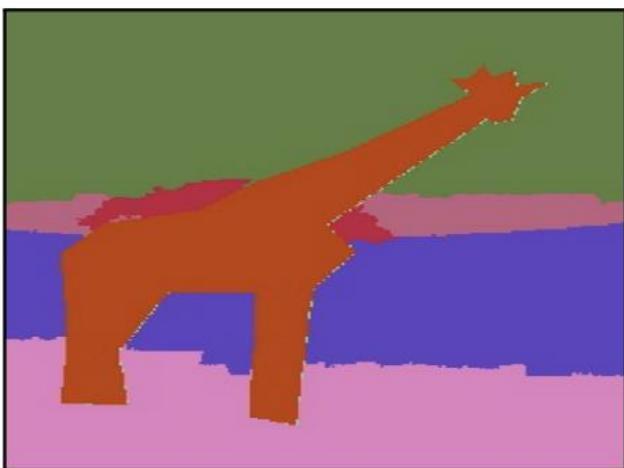
GauGAN Framework



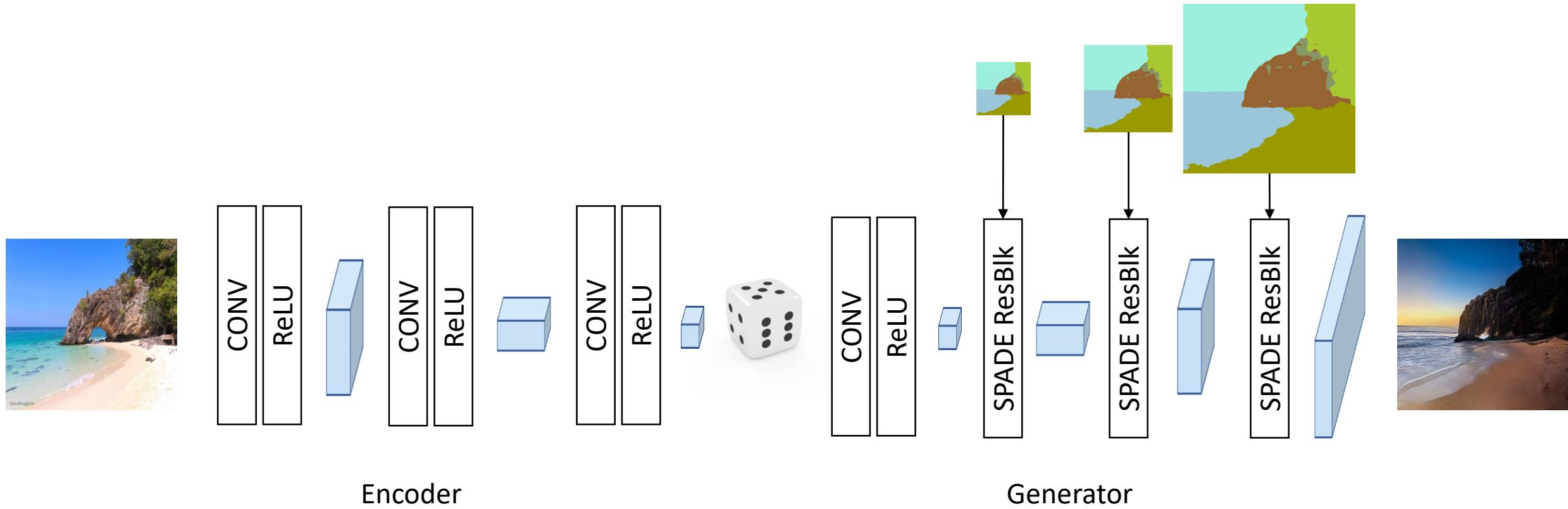
Results



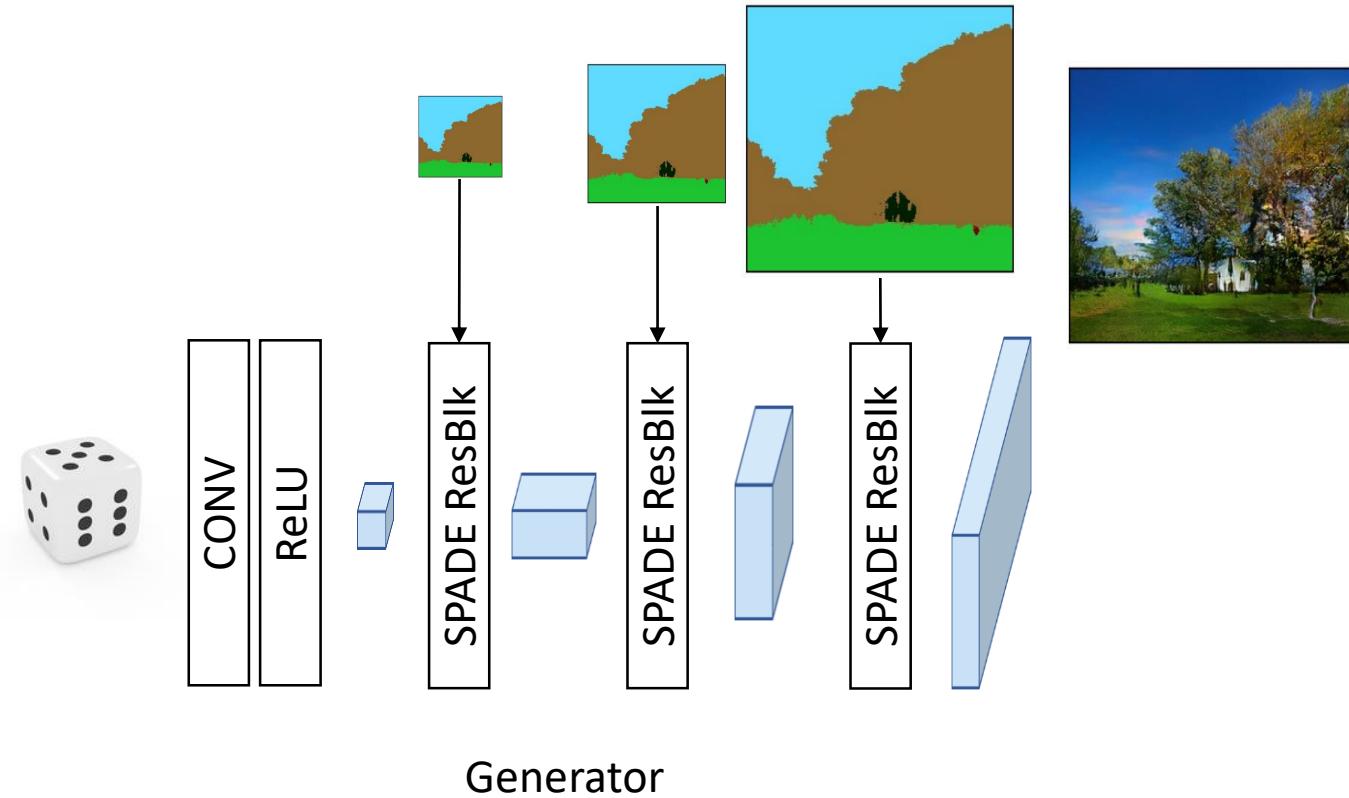




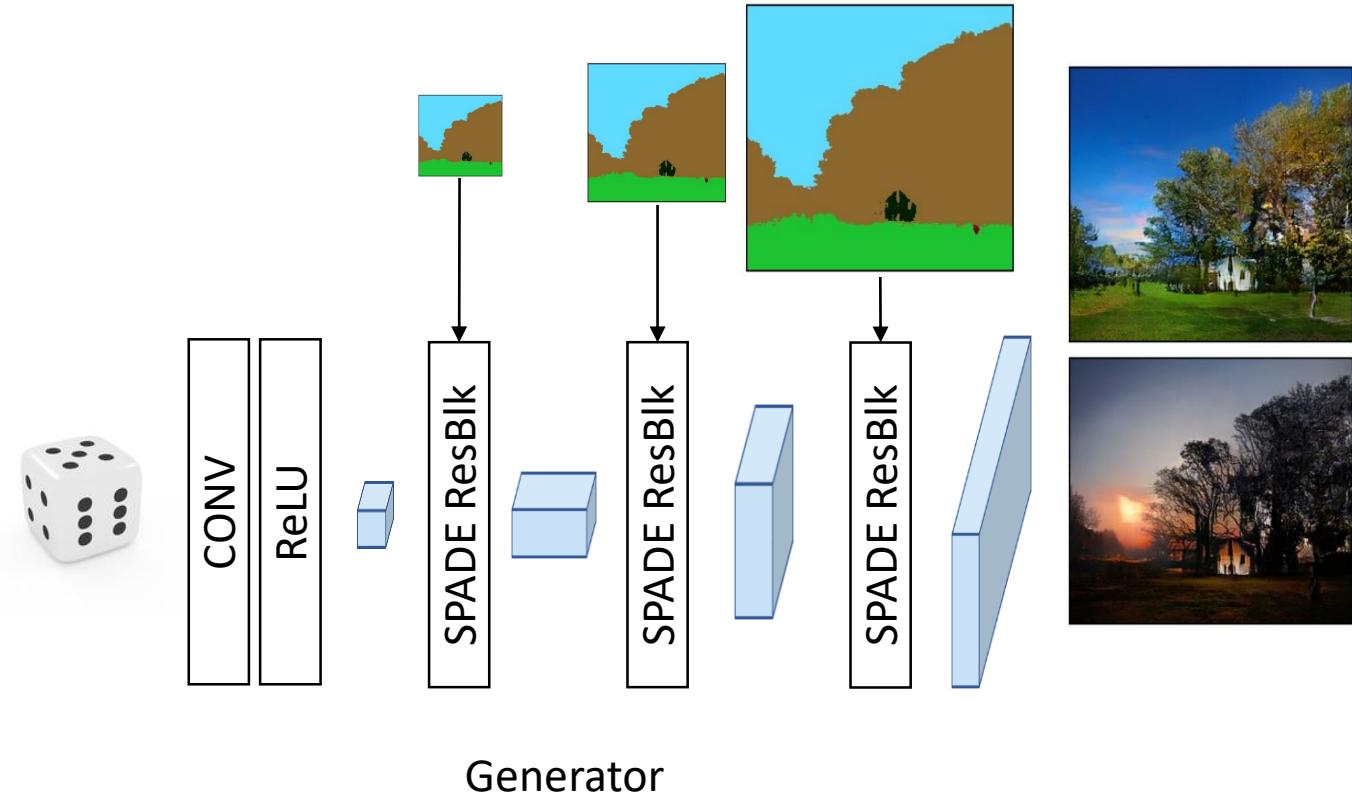
Style Control Learning via a Variational Learning Framework



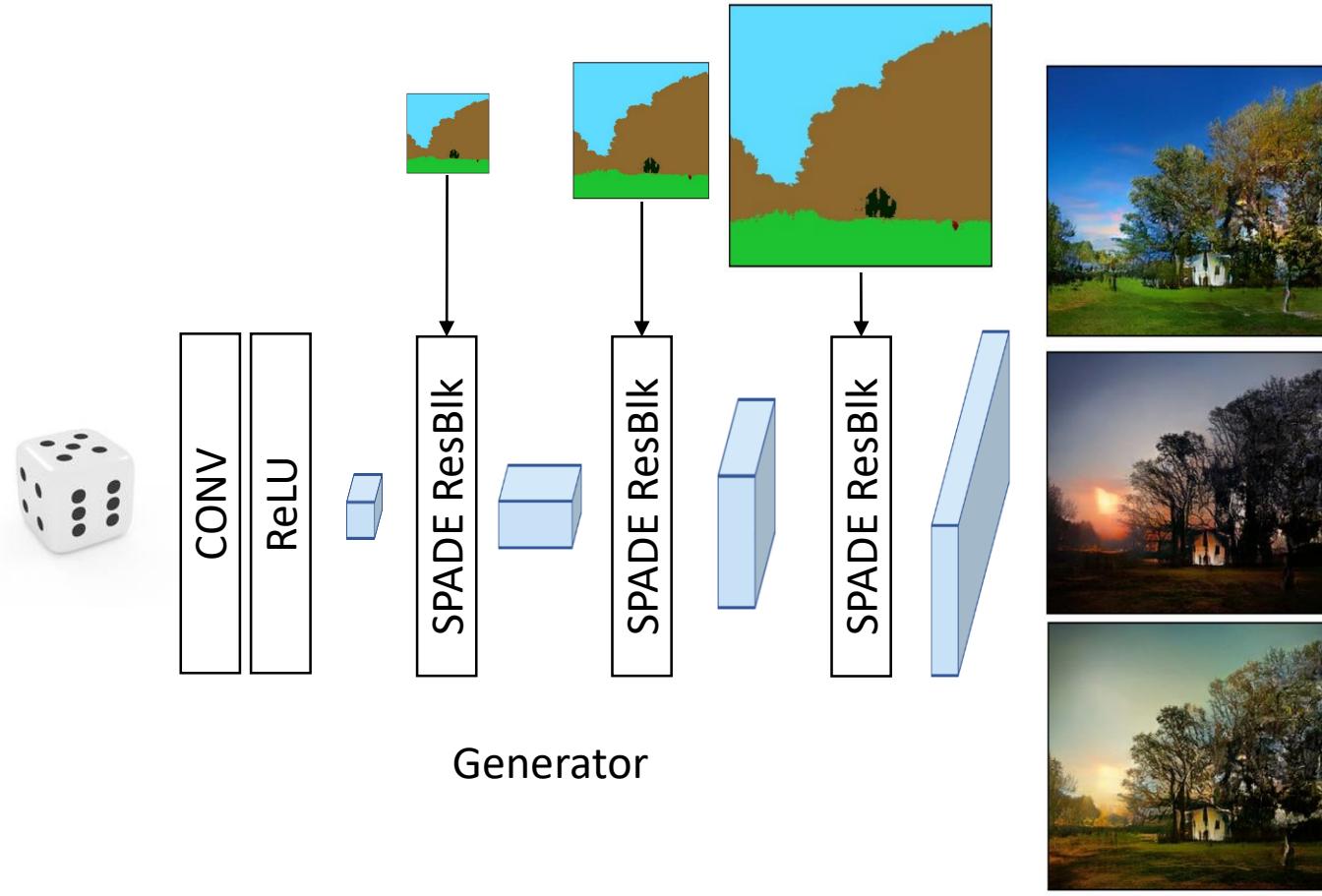
Style Control Learning via a Variational Learning Framework



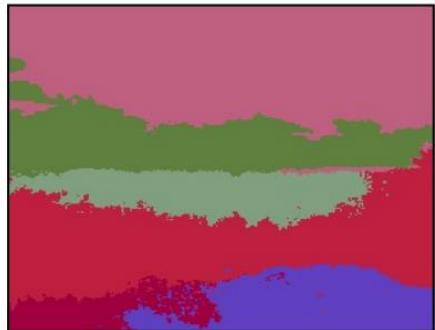
Style Control Learning via a Variational Learning Framework



Style Control Learning via a Variational Learning Framework



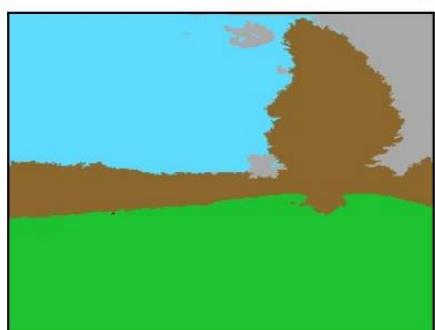
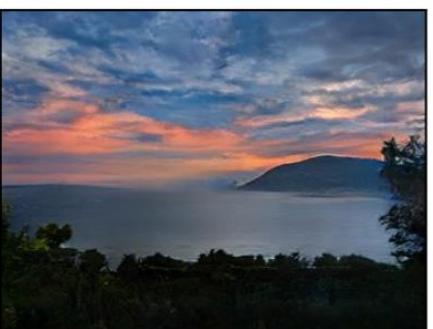
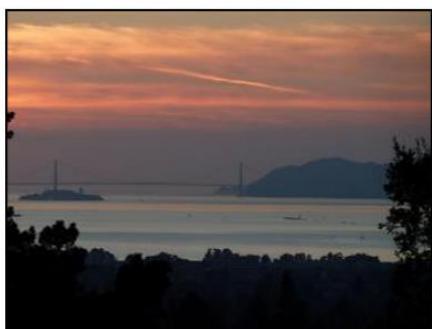
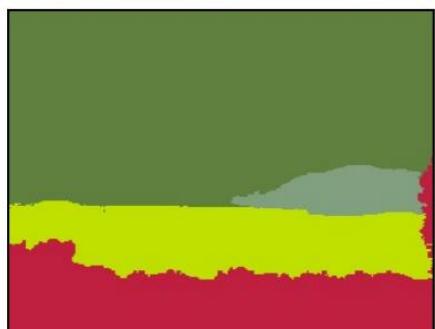
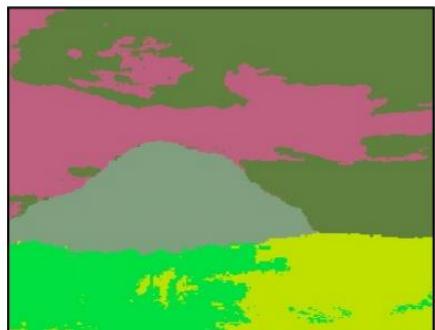
Label



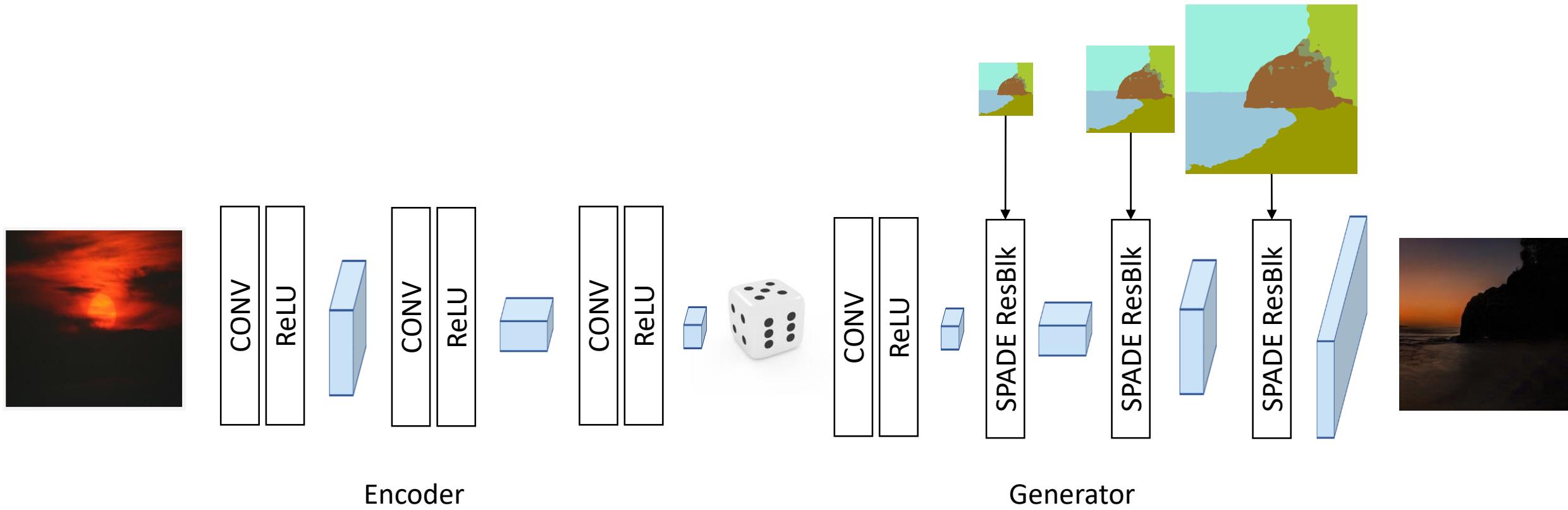
Ground Truth



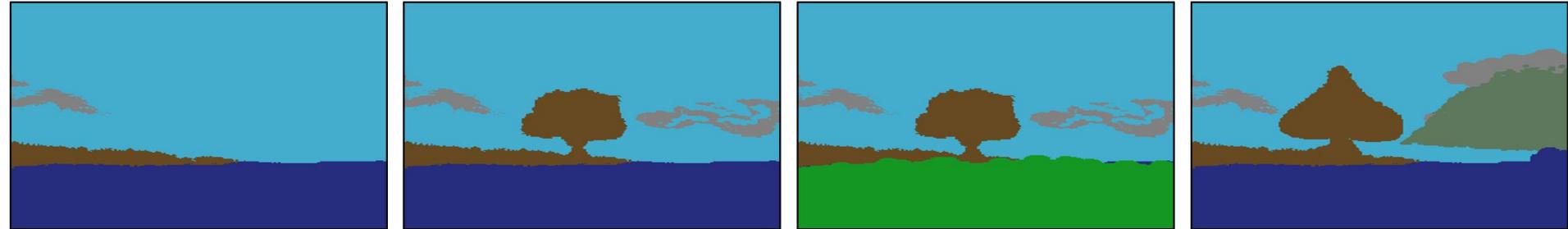
Multi-modal results



In the test time, we can then use different style images to control the global color tone of the output image.



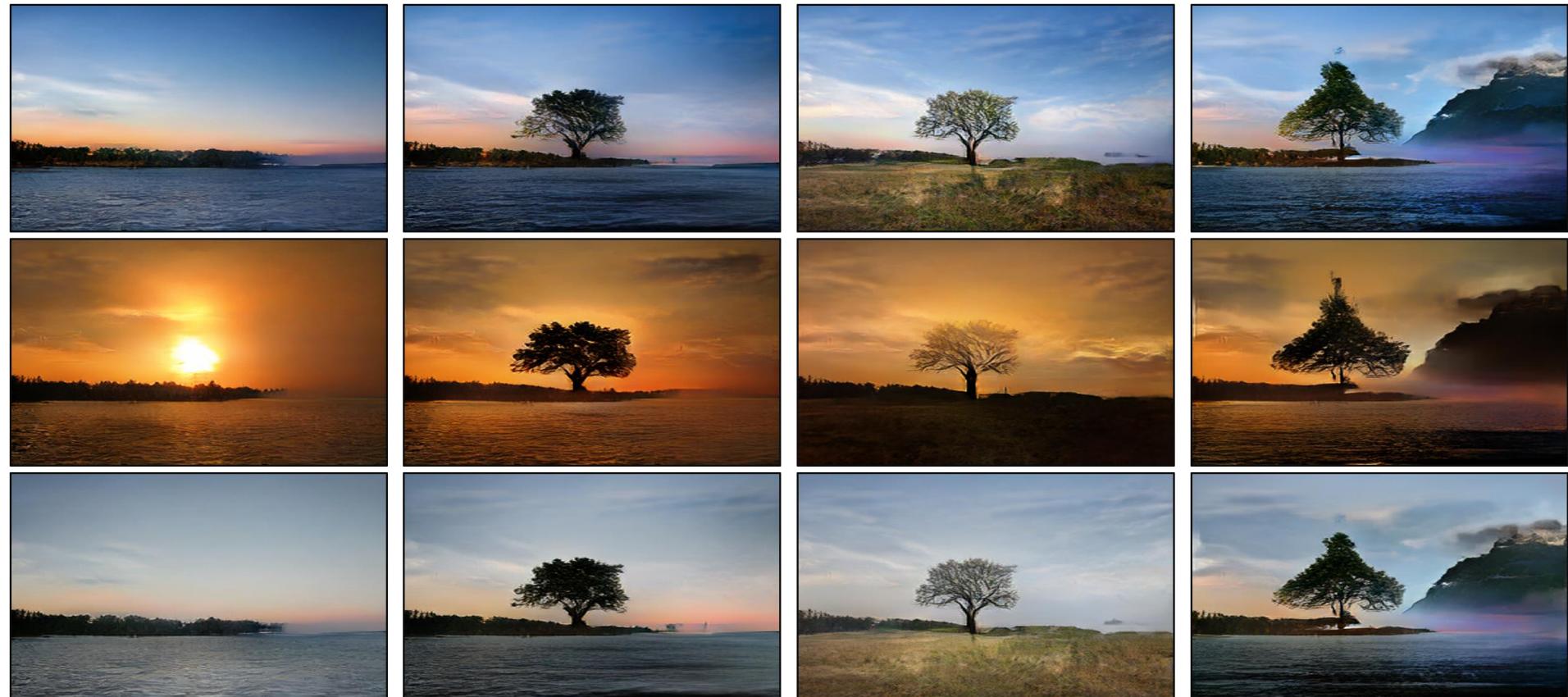
cloud	sky
tree	mountain
sea	grass



Semantic Manipulation Using Segmentation Map



Stylization using Guide Images

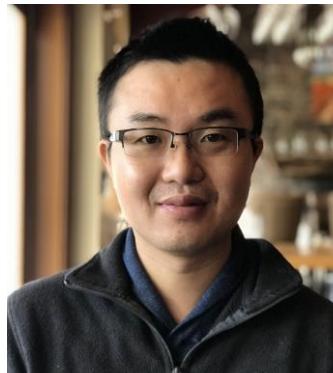


Conclusion

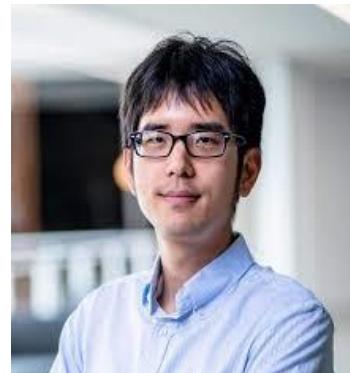
- Segmentation to Image Synthesis Task
- SPADE: Spatially Adaptive Denormalization
- Joint Style and Layout Control
- CVPR2019
- Online demo link: <http://nvidia-research-mingyuliu.com/gaugan>
- SPADE code: <https://github.com/nvlabs/spade/>
- Paper: <https://arxiv.org/abs/1903.07291>



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