



ISFAHAN UNIVERSITY OF TECHNOLOGY
DEPARTMENT OF MATHEMATICAL SCIENCES

Applied Linear Algebra

Assignment #3

Due Date: 11 Khordad 1400

1. Reduce the matrix $A = \begin{bmatrix} 2 & 1 & -5 & -1 & 0 \\ -1 & -1 & 4 & 1 & 2 \\ 0 & -1 & 3 & 2 & 9 \\ -1 & 0 & 1 & 1 & 3 \end{bmatrix}$ to the reduced-echelon-form and find bases for $N(A)$ and $R(A)$ (the null-space and the image of A).
2. Let $A = \begin{bmatrix} 1 & -1 & -4 & 0 & 4 \\ 1 & 1 & 2 & -1 & 1 \\ 0 & 1 & 3 & 0 & -2 \end{bmatrix}$.
 - a) $N(A)$ is a subspace of \mathbb{R}^k . What is k ?
 - b) $R(A)$ is a subspace of \mathbb{R}^p . What is p ?
 - c) Find a nonzero vector $x \in N(A)$ if one exists. otherwise explain why it doesn't.
 - d) Find a nonzero vector $x \in R(A)$ if one exists. otherwise explain why it doesn't.
3. Suppose A is a 5 by 3 matrix and Ax is never zero (except when x is the zero vector).
 - a) What can you say about the columns and rows of A ?
 - b) Show that $A^T Ax$ is also never zero (except when $x = 0$).
4.
 - a) Give an example of two symmetric matrices whose product is not symmetric.
 - b) Now suppose that A and B are symmetric $n \times n$ matrices. Prove that AB is symmetric if and only if A commutes with B , i.e. $AB = BA$.
5. Let $T : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be the linear transformation whose action on the standard basis vectors of \mathbb{R}^3 is

$$\begin{aligned} T(1, 0, 0) &= (1, -\frac{3}{2}, 2) \\ T(0, 1, 0) &= (-3, \frac{9}{2}, -6) \\ T(0, 0, 1) &= (2, -3, 4). \end{aligned}$$

Then what is $T(5, 1, -1)$? The kernel of T is all the vectors $(x, y, z) \in \mathbb{R}^3$ such that $x + ay + bz = 0$. Determine scalars a and b . The range of T is all the vectors $(x, y, z) \in \mathbb{R}^3$ such that $\frac{x}{2} = \frac{y}{c} = \frac{z}{d}$. Determine c and d .

6. Prove that one-to-one linear transformations preserve linear independence. That is: Let $T : V \longrightarrow W$ be one-to-one linear transformation between vector spaces and $\{x_1, x_2, \dots, x_n\}$ be linearly independent, prove that Tx_1, Tx_2, \dots, Tx_n are linearly independent. Give an example that this does not hold for all linear transformation.
7. Consider the linear transformation $T : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ where $T(x, y, z) = (x + 2y - z, -y, x + 7z)$.
 - a) Write the matrix representation of T with respect to the standard basis.
 - b) Consider the basis $\mathcal{B} = \{(1, 0, 0), (1, 1, 0), (1, 1, 1)\}$ for \mathbb{R}^3 and write the matrix representation of T with respect to the basis \mathcal{B} , i.e. $[T]_{\mathcal{B}, \mathcal{B}}$.
8. Suppose that A is an $n \times n$ matrix such that $A^2 = A$. Let $\mathcal{B}_1 = \{u_1, \dots, u_r\}$ be a basis for $R(A)$ and $\mathcal{B}_2 = \{v_1, \dots, v_{n-r}\}$ be a basis for $N(A)$.
 - a) Prove that for each $i \in \{1, \dots, r\}$, $Au_i = u_i$.
 - b) Prove that $\mathcal{B} = \mathcal{B}_1 \cup \mathcal{B}_2$ is a basis for \mathbb{R}^n .
 - c) Prove that $[A]_{\mathcal{B}, \mathcal{B}} = \begin{pmatrix} I_r & O \\ O & O \end{pmatrix}$.