Factor groupoid constructions in C*-algebras and iterated function systems Nipissing University Topology Seminar

Mitch Haslehurst

Department of Mathematics & Statistics University of Victoria

October 22, 2021

A C*-algebra, denoted A, is

A C*-algebra, denoted A, is

ullet An algebra over $\mathbb C$,

A C*-algebra, denoted A, is

- ullet An algebra over \mathbb{C} ,
- it has a conjugate linear involution * such that, if a and b are in A,

$$(ab)^*=b^*a^*,$$

A C*-algebra, denoted A, is

- ullet An algebra over \mathbb{C} ,
- it has a conjugate linear involution * such that, if a and b are in A,

$$(ab)^* = b^*a^*,$$

 \bullet has a norm $\|\cdot\|$ in which it is complete and

A C*-algebra, denoted A, is

- ullet An algebra over \mathbb{C} ,
- it has a conjugate linear involution * such that, if a and b are in A,

$$(ab)^*=b^*a^*,$$

- \bullet has a norm $\|\cdot\|$ in which it is complete and
- if a and b are in A, then

A C*-algebra, denoted A, is

- ullet An algebra over $\mathbb C$,
- it has a conjugate linear involution * such that, if a and b are in A,

$$(ab)^* = b^*a^*,$$

- has a norm $\|\cdot\|$ in which it is complete and
- if a and b are in A, then

$$||ab|| \le ||a|| ||b||$$
 and $||a^*a|| = ||a||^2$.



A C*-algebra, denoted A, is

- ullet An algebra over $\mathbb C$,
- it has a conjugate linear involution * such that, if a and b are in A,

$$(ab)^* = b^*a^*,$$

- has a norm $\|\cdot\|$ in which it is complete and
- if a and b are in A, then

$$||ab|| \le ||a|| ||b||$$
 and $||a^*a|| = ||a||^2$.

• If there is a unit 1, then A is called *unital*.



A C*-algebra, denoted A, is

- ullet An algebra over \mathbb{C} ,
- it has a conjugate linear involution * such that, if a and b are in A,

$$(ab)^* = b^*a^*,$$

- has a norm $\|\cdot\|$ in which it is complete and
- if a and b are in A, then

$$||ab|| \le ||a|| ||b||$$
 and $||a^*a|| = ||a||^2$.

- If there is a unit 1, then A is called *unital*.
- If ab = ba for any a and b in A, then A is called *commutative*.



The requirement that

$$||a^*a|| = ||a||^2$$

The requirement that

$$||a^*a|| = ||a||^2$$

The requirement that

$$||a^*a|| = ||a||^2$$

for every a in A is very powerful.

 The analytic structure is completely determined by the algebraic structure.

The requirement that

$$||a^*a|| = ||a||^2$$

- The analytic structure is completely determined by the algebraic structure.
- Every *-homomorphism $\varphi : A \to B$ is automatically continuous.

The requirement that

$$||a^*a|| = ||a||^2$$

- The analytic structure is completely determined by the algebraic structure.
- Every *-homomorphism $\varphi : A \to B$ is automatically continuous.
- ullet If φ is injective, it is automatically isometric.

The requirement that

$$||a^*a|| = ||a||^2$$

- The analytic structure is completely determined by the algebraic structure.
- Every *-homomorphism $\varphi: A \to B$ is automatically continuous.
- ullet If arphi is injective, it is automatically isometric.
- There is at most one norm on a Banach *-algebra which makes it into a C*-algebra.



Example. The complex numbers \mathbb{C} , with its usual addition, multiplication, $z^* = \overline{z}$, and norm |z| (absolute value). It is unital and commutative.

Example. The complex numbers \mathbb{C} , with its usual addition, multiplication, $z^* = \overline{z}$, and norm |z| (absolute value). It is unital and commutative.

Example. If X is a compact Hausdorff space, then

$$C(X) = \{f : X \to \mathbb{C} \mid f \text{ is continuous}\}$$

with $f^*(x) = \overline{f(x)}$ and norm $||f|| = \sup_{x \in X} |f(x)|$ is a unital and commutative C*-algebra.

Example. The complex numbers \mathbb{C} , with its usual addition, multiplication, $z^* = \overline{z}$, and norm |z| (absolute value). It is unital and commutative.

Example. If X is a compact Hausdorff space, then

$$C(X) = \{f : X \to \mathbb{C} \mid f \text{ is continuous}\}$$

with $f^*(x) = \overline{f(x)}$ and norm $||f|| = \sup_{x \in X} |f(x)|$ is a unital and commutative C*-algebra.

Exercise: Why is f necessarily bounded?

Example. The complex numbers \mathbb{C} , with its usual addition, multiplication, $z^* = \overline{z}$, and norm |z| (absolute value). It is unital and commutative.

Example. If X is a compact Hausdorff space, then

$$C(X) = \{f : X \to \mathbb{C} \mid f \text{ is continuous}\}$$

with $f^*(x) = \overline{f(x)}$ and norm $||f|| = \sup_{x \in X} |f(x)|$ is a unital and commutative C*-algebra.

Exercise: Why is f necessarily bounded?

Answer: X is compact, and continuous images of compact sets are compact, so f(X) is bounded in \mathbb{C} .



Example. If X is a locally compact Hausdorff space, then

$$C_0(X) = \{f : X \to \mathbb{C} \mid f \text{ is continuous and vanishes at infinity}\}$$

with the supremum norm is a commutative C^* -algebra. It is unital if and only if X is compact.

Example. If X is a locally compact Hausdorff space, then

$$C_0(X) = \{ f : X \to \mathbb{C} \mid f \text{ is continuous and vanishes at infinity} \}$$

with the supremum norm is a commutative C^* -algebra. It is unital if and only if X is compact.

Think of:

$$C_0(\mathbb{R}) = \{f: \mathbb{R} \to \mathbb{C} \mid f \text{ is continuous and } \lim_{x \to \pm \infty} |f(x)| = 0\}$$

Example. The $n \times n$ matrices $M_n(\mathbb{C})$ form a C*-algebra.

Example. The $n \times n$ matrices $M_n(\mathbb{C})$ form a C*-algebra.

The product is matrix multiplication and the involution is the matrix adjoint (conjugate transpose).

Example. The $n \times n$ matrices $M_n(\mathbb{C})$ form a C*-algebra.

The product is matrix multiplication and the involution is the matrix adjoint (conjugate transpose).

To get a norm, regard each matrix as a linear transformation and

$$||a|| = \sup_{\|\vec{x}\| \le 1} ||a\vec{x}||$$

Example. The $n \times n$ matrices $M_n(\mathbb{C})$ form a C*-algebra.

The product is matrix multiplication and the involution is the matrix adjoint (conjugate transpose).

To get a norm, regard each matrix as a linear transformation and

$$||a|| = \sup_{\|\vec{x}\| \le 1} ||a\vec{x}||$$

 $M_n(\mathbb{C})$ is unital, but never commutative when n > 1.

Example. Let \mathcal{H} be a Hilbert space and let $\mathcal{B}(\mathcal{H})$ denote the bounded linear transformations $a:\mathcal{H}\to\mathcal{H}$. This forms a C*-algebra.

Example. Let \mathcal{H} be a Hilbert space and let $\mathcal{B}(\mathcal{H})$ denote the bounded linear transformations $a:\mathcal{H}\to\mathcal{H}$. This forms a C*-algebra.

The product is composition and the involution is the Hilbert space operator adjoint. The norm is

$$||a|| = \sup_{\|\vec{x}\| \le 1} ||a\vec{x}||$$

Example. Let \mathcal{H} be a Hilbert space and let $\mathcal{B}(\mathcal{H})$ denote the bounded linear transformations $a:\mathcal{H}\to\mathcal{H}$. This forms a C*-algebra.

The product is composition and the involution is the Hilbert space operator adjoint. The norm is

$$||a|| = \sup_{||\vec{x}|| \le 1} ||a\vec{x}||$$

When \mathcal{H} is finite-dimensional, we may identify $\mathcal{B}(\mathcal{H})$ with $M_n(\mathbb{C})$ for some n.

Creating new C*-algebras from old ones:

Creating new C*-algebras from old ones:

If A is a C*-algebra, then so is $M_n(A)$, matrices with entries from A.

Creating new C*-algebras from old ones:

If A is a C*-algebra, then so is $M_n(A)$, matrices with entries from A.

If X is a locally compact Hausdorff space and A is a C^* -algebra, then

$$C_0(X, A) = \{f : X \to A \mid f \text{ is continuous}\}$$

is a C^* -algebra.

Creating new C*-algebras from old ones:

If A is a C*-algebra, then so is $M_n(A)$, matrices with entries from A.

If X is a locally compact Hausdorff space and A is a C^* -algebra, then

$$C_0(X, A) = \{f : X \rightarrow A \mid f \text{ is continuous}\}\$$

is a C^* -algebra.

Exercise: $C_0(X, M_n(\mathbb{C}))$ is canonically isomorphic to $M_n(C_0(X))$. Can you see how?

Theorem (Gelfand-Naimark)

If A is a commutative C*-algebra, then there is a locally compact Hausdorff space X such that $A \cong C_0(X)$.

Theorem (Gelfand-Naimark)

If A is a commutative C*-algebra, then there is a locally compact Hausdorff space X such that $A \cong C_0(X)$.

Theorem (Gelfand-Naimark)

If A is a C*-algebra, then there exists a Hilbert space $\mathcal H$ and an injective *-homomorphism $\varphi:A\to\mathcal B(\mathcal H)$.

Theorem (Gelfand-Naimark)

If A is a commutative C*-algebra, then there is a locally compact Hausdorff space X such that $A \cong C_0(X)$.

Theorem (Gelfand-Naimark)

If A is a C*-algebra, then there exists a Hilbert space \mathcal{H} and an injective *-homomorphism $\varphi : A \to \mathcal{B}(\mathcal{H})$.

So all commutative C*-algebras look like continuous functions

Theorem (Gelfand-Naimark)

If A is a commutative C*-algebra, then there is a locally compact Hausdorff space X such that $A \cong C_0(X)$.

Theorem (Gelfand-Naimark)

If A is a C*-algebra, then there exists a Hilbert space \mathcal{H} and an injective *-homomorphism $\varphi : A \to \mathcal{B}(\mathcal{H})$.

So all commutative C^* -algebras look like continuous functions and all C^* -algebras (commutative or not) look like a *-subalgebra of bounded linear operators.

Gelfand-Naimark dictionary

Properties of X Properties of $C_0(X)$

Properties of X	Properties of $C_0(X)$
open set $U \subseteq X$	ideal $I \subseteq C_0(X)$

Properties of X	Properties of $C_0(X)$
open set $U \subseteq X$	ideal $I \subseteq C_0(X)$
closed set $F = X - U$	quotient $C_0(X)/I$

Properties of X	Properties of $C_0(X)$
open set $U \subseteq X$	ideal $I \subseteq C_0(X)$
closed set $F = X - U$	quotient $C_0(X)/I$
X is compact	$C_0(X)$ is unital

Properties of X	Properties of $C_0(X)$
open set $U \subseteq X$	ideal $I \subseteq C_0(X)$
closed set $F = X - U$	quotient $C_0(X)/I$
X is compact	$C_0(X)$ is unital
X is connected	$C_0(X)$ is projectionless

Properties of X	Properties of $C_0(X)$
open set $U \subseteq X$	ideal $I \subseteq C_0(X)$
closed set $F = X - U$	quotient $C_0(X)/I$
X is compact	$C_0(X)$ is unital
X is connected	$C_0(X)$ is projectionless
X is second-countable	$C_0(X)$ is separable

Properties of X	Properties of $C_0(X)$
open set $U \subseteq X$	ideal $I \subseteq C_0(X)$
closed set $F = X - U$	quotient $C_0(X)/I$
X is compact	$C_0(X)$ is unital
X is connected	$C_0(X)$ is projectionless
X is second-countable	$C_0(X)$ is separable
X and Y homeomorphic	$C_0(X)$ and $C_0(Y)$ *-isomorphic

Gelfand-Naimark dictionary

Properties of X	Properties of $C_0(X)$
open set $U \subseteq X$	ideal $I \subseteq C_0(X)$
closed set $F = X - U$	quotient $C_0(X)/I$
X is compact	$C_0(X)$ is unital
X is connected	$C_0(X)$ is projectionless
X is second-countable	$C_0(X)$ is separable
X and Y homeomorphic	$C_0(X)$ and $C_0(Y)$ *-isomorphic

The pairing $X \leftrightarrow C_0(X)$ is a complete categorical equivalence between locally compact Hausdorff spaces and commutative C^* -algebras.

Gelfand-Naimark dictionary

Properties of X	Properties of $C_0(X)$
open set $U \subseteq X$	ideal $I\subseteq C_0(X)$
closed set $F = X - U$	quotient $C_0(X)/I$
X is compact	$C_0(X)$ is unital
X is connected	$C_0(X)$ is projectionless
X is second-countable	$C_0(X)$ is separable
X and Y homeomorphic	$C_0(X)$ and $C_0(Y)$ *-isomorphic

The pairing $X \leftrightarrow C_0(X)$ is a complete categorical equivalence between locally compact Hausdorff spaces and commutative C^* -algebras.

C*-algebras are often referred to as "noncommutative spaces"



"...Heisenberg postulated that the mathematics describing quantum physics should be the mathematics, not of functions on a space, but of linear operators on a Hilbert space, which, taken as an algebra, behaves, algebraically, much like the algebra of continuous functions on a space, but is not commutative..."

-Heath Emerson, An introduction to C*-algebras and Noncommutative Geometry.

 C^* -algebras have an immense amount of rigid structure, which makes them very difficult to study.

 C^* -algebras have an immense amount of rigid structure, which makes them very difficult to study.

To further understand them, we need some tools. One of the most widely used tools is K-theory.

 C^* -algebras have an immense amount of rigid structure, which makes them very difficult to study.

To further understand them, we need some tools. One of the most widely used tools is K-theory.

We give a few names to important elements in a C^* -algebra.

 C^* -algebras have an immense amount of rigid structure, which makes them very difficult to study.

To further understand them, we need some tools. One of the most widely used tools is K-theory.

We give a few names to important elements in a C*-algebra.

u is called a *unitary* if $u^*u = uu^* = 1$.

 C^* -algebras have an immense amount of rigid structure, which makes them very difficult to study.

To further understand them, we need some tools. One of the most widely used tools is K-theory.

We give a few names to important elements in a C^* -algebra.

u is called a *unitary* if $u^*u = uu^* = 1$.

p is called a *projection* if $p = p^2 = p^*$.

 C^* -algebras have an immense amount of rigid structure, which makes them very difficult to study.

To further understand them, we need some tools. One of the most widely used tools is K-theory.

We give a few names to important elements in a C*-algebra.

u is called a *unitary* if $u^*u = uu^* = 1$.

p is called a *projection* if $p = p^2 = p^*$.

v is called a *partial isometry* if v^*v is a projection.

Let A be a unital C*-algebra. We define two abelian groups called $K_0(A)$ and $K_1(A)$.

Let A be a unital C*-algebra. We define two abelian groups called $K_0(A)$ and $K_1(A)$.

 $K_0(A)$ consists of equivalence classes of projections p in $\bigcup_n M_n(A)$, where $p \sim q$ if $v^*v = p$ and $vv^* = q$ for some v in $\bigcup_n M_n(A)$. Add them by

$$[p] + [q] = [p \oplus q] = \begin{bmatrix} \begin{pmatrix} p & 0 \\ 0 & q \end{pmatrix} \end{bmatrix}.$$

Let A be a unital C*-algebra. We define two abelian groups called $K_0(A)$ and $K_1(A)$.

 $K_0(A)$ consists of equivalence classes of projections p in $\bigcup_n M_n(A)$, where $p \sim q$ if $v^*v = p$ and $vv^* = q$ for some v in $\bigcup_n M_n(A)$. Add them by

$$[p] + [q] = [p \oplus q] = \begin{bmatrix} \begin{pmatrix} p & 0 \\ 0 & q \end{pmatrix} \end{bmatrix}.$$

 $K_1(A)$ consists of equivalence classes of unitaries u in $\bigcup_n M_n(A)$, where $u \sim v$ if there is a continuous path of unitaries connecting them. Add them by [u] + [v] = [uv].

Examples. $K_0(\mathbb{C}) \cong \mathbb{Z}$ (associate a projection in $\bigcup_n M_n(\mathbb{C})$ to its rank). $K_0(M_n(\mathbb{C})) \cong \mathbb{Z}$ for the same reason.

Examples. $K_0(\mathbb{C}) \cong \mathbb{Z}$ (associate a projection in $\bigcup_n M_n(\mathbb{C})$ to its rank). $K_0(M_n(\mathbb{C})) \cong \mathbb{Z}$ for the same reason.

 $K_1(\mathbb{C}) = 0$ because the unitary group of $M_n(\mathbb{C})$ is connected.

Examples. $K_0(\mathbb{C}) \cong \mathbb{Z}$ (associate a projection in $\bigcup_n M_n(\mathbb{C})$ to its rank). $K_0(M_n(\mathbb{C})) \cong \mathbb{Z}$ for the same reason.

 $K_1(\mathbb{C})=0$ because the unitary group of $M_n(\mathbb{C})$ is connected.

 $K_0(C(X)) \cong \mathbb{Z}$ and $K_1(C(X)) = 0$ if X is contractible (K-theory is homotopy invariant).

Examples. $K_0(\mathbb{C}) \cong \mathbb{Z}$ (associate a projection in $\bigcup_n M_n(\mathbb{C})$ to its rank). $K_0(M_n(\mathbb{C})) \cong \mathbb{Z}$ for the same reason.

 $K_1(\mathbb{C})=0$ because the unitary group of $M_n(\mathbb{C})$ is connected.

 $K_0(C(X)) \cong \mathbb{Z}$ and $K_1(C(X)) = 0$ if X is contractible (K-theory is homotopy invariant).

 $K_0(\mathcal{B}(\mathcal{H})) = K_1(\mathcal{B}(\mathcal{H})) = 0$ if \mathcal{H} is infinite dimensional.

Examples. $K_0(\mathbb{C}) \cong \mathbb{Z}$ (associate a projection in $\bigcup_n M_n(\mathbb{C})$ to its rank). $K_0(M_n(\mathbb{C})) \cong \mathbb{Z}$ for the same reason.

 $K_1(\mathbb{C})=0$ because the unitary group of $M_n(\mathbb{C})$ is connected.

 $K_0(C(X)) \cong \mathbb{Z}$ and $K_1(C(X)) = 0$ if X is contractible (K-theory is homotopy invariant).

 $K_0(\mathcal{B}(\mathcal{H})) = K_1(\mathcal{B}(\mathcal{H})) = 0$ if \mathcal{H} is infinite dimensional.

 $K_1(C(S^1))\cong \mathbb{Z}$ where $S^1=\{z\in \mathbb{C}\mid |z|=1\}$ (associate a unitary to its winding number).



If the sequence

$$0 \longrightarrow I \xrightarrow{\iota} A \xrightarrow{\pi} A/I \longrightarrow 0$$

is exact,

If the sequence

$$0 \longrightarrow I \stackrel{\iota}{\longrightarrow} A \stackrel{\pi}{\longrightarrow} A/I \longrightarrow 0$$

is exact, there are group homomorphisms δ_0 and δ_1 such that the sequence

$$K_0(I) \xrightarrow{\iota_*} K_0(A) \xrightarrow{\pi_*} K_0(A/I)$$

$$\downarrow^{\delta_1} \qquad \qquad \downarrow^{\delta_0}$$
 $K_1(A/I) \leftarrow_{\pi_*} K_1(A) \leftarrow_{\iota_*} K_1(I)$

is exact.



There is an immense amount of research being done into what K-theory can tell us about C^* -algebras.

There is an immense amount of research being done into what K-theory can tell us about C^* -algebras.

The Elliott classification program. Suppose A and B are two unital, simple, separable, nuclear, \mathcal{Z} -stable C*-algebras that satisfy the Universal Coefficient Theorem. If A and B have the same K-theory, then they are isomorphic.

There is an immense amount of research being done into what K-theory can tell us about C^* -algebras.

The Elliott classification program. Suppose A and B are two unital, simple, separable, nuclear, \mathcal{Z} -stable C*-algebras that satisfy the Universal Coefficient Theorem. If A and B have the same K-theory, then they are isomorphic.

Given some K-theory data, it is important to have helpful ways of "seeing" the corresponding C^* -algebra.

There is an immense amount of research being done into what K-theory can tell us about C^* -algebras.

The Elliott classification program. Suppose A and B are two unital, simple, separable, nuclear, \mathcal{Z} -stable C*-algebras that satisfy the Universal Coefficient Theorem. If A and B have the same K-theory, then they are isomorphic.

Given some K-theory data, it is important to have helpful ways of "seeing" the corresponding C^* -algebra.

This is where groupoids come in.

A groupoid G is like a group, but not every pair of elements can be multiplied.

A groupoid G is like a group, but not every pair of elements can be multiplied.

Every element x of G has an inverse x^{-1} , but there are many "units". The set of units is denoted $G^{(0)}$ and they are of the form $x^{-1}x$. Define the maps $r(x) = xx^{-1}$ and $s(x) = x^{-1}x$.

A groupoid G is like a group, but not every pair of elements can be multiplied.

Every element x of G has an inverse x^{-1} , but there are many "units". The set of units is denoted $G^{(0)}$ and they are of the form $x^{-1}x$. Define the maps $r(x) = xx^{-1}$ and $s(x) = x^{-1}x$.

Example. Let X be a nonempty set and $R \subseteq X \times X$ an equivalence relation. Then R is a groupoid:

$$(x,y)(y',z) = (x,z)$$
 $(x,y)^{-1} = (y,x)$

only when y = y'.



Given a groupoid with some nice topological properties, we can make a C*-algebra out of it.

Given a groupoid with some nice topological properties, we can make a C*-algebra out of it.

 $C_c(G) = \text{all continuous, compactly supported functions } f: G \to \mathbb{C}.$

$$(f \star g)(x) = \sum_{y \in G^{r(x)}} f(y)g(y^{-1}x) \qquad f^*(x) = \overline{f(x^{-1})}$$

Given a groupoid with some nice topological properties, we can make a C*-algebra out of it.

 $C_c(G)=$ all continuous, compactly supported functions $f:G \to \mathbb{C}$.

$$(f \star g)(x) = \sum_{y \in G^{r(x)}} f(y)g(y^{-1}x) \qquad f^*(x) = \overline{f(x^{-1})}$$

To get a complete norm, represent $C_c(G)$ on a Hilbert space and take the closure to get the *reduced* C^* -algebra of G, called $C^*_r(G)$.

Example. Let $X = \{1, 2, ..., n\}$ and $R = X \times X$.

Example. Let $X = \{1, 2, ..., n\}$ and $R = X \times X$. Then if f and g are in $C_c(R)$, we have

$$(f \star g)(i,k) = \sum_{j=1}^{n} f(i,j)g(j,k) \qquad f^{*}(i,k) = \overline{f(k,i)}$$

Example. Let $X = \{1, 2, ..., n\}$ and $R = X \times X$. Then if f and g are in $C_c(R)$, we have

$$(f \star g)(i,k) = \sum_{j=1}^{n} f(i,j)g(j,k) \qquad f^{*}(i,k) = \overline{f(k,i)}$$

Exercise. Do these formulae look familiar?

Example. Let $X = \{1, 2, ..., n\}$ and $R = X \times X$. Then if f and g are in $C_c(R)$, we have

$$(f \star g)(i,k) = \sum_{j=1}^{n} f(i,j)g(j,k) \qquad f^{*}(i,k) = \overline{f(k,i)}$$

Exercise. Do these formulae look familiar?

Answer. It's matrix multiplication and the conjugate transpose, so $C_c(R) \cong M_n(\mathbb{C})$.

Groupoids¹

If X is a locally compact Hausdorff space and $R = \{(x, x) \mid x \in X\}$, then $C_r^*(R) \cong C_0(X)$.

If X is a locally compact Hausdorff space and $R = \{(x, x) \mid x \in X\}$, then $C_r^*(R) \cong C_0(X)$.

Groupoids can give some fancy C*-algebras. If G is a dynamical system or group action $\Gamma \curvearrowright X$, then $C_r^*(G)$ is the crossed product $C_0(X) \rtimes \Gamma$.

Factor groupoids

G' is a factor groupoid of G if $\pi:G\to G'$ is a surjective groupoid morphism.

Factor groupoids

G' is a factor groupoid of G if $\pi:G\to G'$ is a surjective groupoid morphism.

Obtain an inclusion $C^*_r(G') \subseteq C^*_r(G)$ via $b \mapsto b \circ \pi$ (b in $C_c(G')$)

Factor groupoids

G' is a factor groupoid of G if $\pi:G\to G'$ is a surjective groupoid morphism.

Obtain an inclusion $C^*_r(G') \subseteq C^*_r(G)$ via $b \mapsto b \circ \pi$ (b in $C_c(G')$)

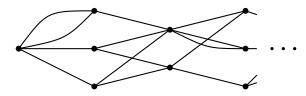
The idea is to arrange that one of $C_r^*(G')$ and $C_r^*(G)$ is familiar, while the other one is new and has some interesting K-theory.

Let (V, E) be a Bratteli diagram.

Let (V, E) be a Bratteli diagram.

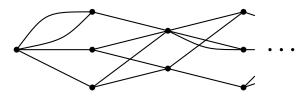


Let (V, E) be a Bratteli diagram.



The *infinite path space* X_E of (V, E) is a totally disconnected compact metric space.

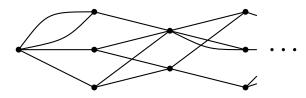
Let (V, E) be a Bratteli diagram.



The *infinite path space* X_E of (V, E) is a totally disconnected compact metric space.

Tail-equivalence $R_E \subseteq X_E \times X_E$ yields that $C_r^*(R_E)$ is an AF-algebra (approximately finite dimensional).

Let (V, E) be a Bratteli diagram.



The *infinite path space* X_E of (V, E) is a totally disconnected compact metric space.

Tail-equivalence $R_E \subseteq X_E \times X_E$ yields that $C_r^*(R_E)$ is an AF-algebra (approximately finite dimensional).

Goal: make a factor groupoid of R_E .

Let (V, E) and (W, F) be two Bratteli diagrams.

Let (V, E) and (W, F) be two Bratteli diagrams.

Two graph embeddings $\xi^0, \xi^1 : (W, F) \to (V, E)$ with $\xi^0|_W = \xi^1|_W$ and $\xi^0(F) \cap \xi^1(F) = \emptyset$.

Let (V, E) and (W, F) be two Bratteli diagrams.

Two graph embeddings $\xi^0, \xi^1: (W, F) \to (V, E)$ with $\xi^0|_W = \xi^1|_W$ and $\xi^0(F) \cap \xi^1(F) = \emptyset$.

Equivalence relation \sim_{ξ} on X_{E} :

$$(x_1, x_2, \dots, x_{n_0-1}, x_{n_0}, \xi^0(z_{n_0+1}), \xi^0(z_{n_0+2}), \dots)$$
 (1)

$$\sim_{\xi} (x_1, x_2, \dots, x_{n_0-1}, x'_{n_0}, \xi^1(z_{n_0+1}), \xi^1(z_{n_0+2}), \dots)$$
 (2)

Denote $X_{\xi} := X_E / \sim_{\xi}$ and $\rho : X_E \to X_{\xi}$ the quotient map.

Denote $X_{\xi}:=X_{E}/\sim_{\xi}$ and $\rho:X_{E}\to X_{\xi}$ the quotient map.

Facts:

- **1** X_{ξ} is a second-countable compact Hausdorff space,
- 2 the covering dimension of X_{ξ} is 1,
- \odot each connected component is either a single point or homeomorphic to S^1 .

Many of the spaces X_{ξ} are fractal-like, sort of like attractors of iterated function systems.

Example 1. We let (V, E) be the Bratteli diagram with one vertex at each level and two edges at each level. Identify X_E with $\{0,1\}^{\omega}$.

(W, F) is a single path, and for f in F, $\xi^{j}(f) = j$ for j = 0, 1.

Example 1. We let (V, E) be the Bratteli diagram with one vertex at each level and two edges at each level. Identify X_E with $\{0,1\}^{\omega}$.

(W, F) is a single path, and for f in F, $\xi^{j}(f) = j$ for j = 0, 1.

$$(x_1, x_2, \ldots, x_n, 1, 0, 0, 0, 0, \ldots)$$
 (3)

$$\sim_{\xi} (x_1, x_2, \dots, x_n, 0, 1, 1, 1, 1, \dots)$$
 (4)

Example 1. We let (V, E) be the Bratteli diagram with one vertex at each level and two edges at each level. Identify X_E with $\{0,1\}^{\omega}$.

(W,F) is a single path, and for f in F, $\xi^j(f)=j$ for j=0,1.

$$(x_1, x_2, \ldots, x_n, 1, 0, 0, 0, 0, \ldots)$$
 (3)

$$\sim_{\xi} (x_1, x_2, \dots, x_n, 0, 1, 1, 1, 1, \dots)$$
 (4)

$$\{0,1\}^{\omega}
ightarrow S^1: (x_n) \mapsto \exp\left(2\pi i \sum_{n=1}^{\infty} x_n 2^{-n}\right)$$

Example 1. We let (V, E) be the Bratteli diagram with one vertex at each level and two edges at each level. Identify X_E with $\{0,1\}^{\omega}$.

(W, F) is a single path, and for f in F, $\xi^{j}(f) = j$ for j = 0, 1.

$$(x_1, x_2, \ldots, x_n, 1, 0, 0, 0, 0, \ldots)$$
 (3)

$$\sim_{\xi} (x_1, x_2, \dots, x_n, 0, 1, 1, 1, 1, \dots)$$
 (4)

$$\{0,1\}^{\omega} \to S^1: (x_n) \mapsto \exp\left(2\pi i \sum_{n=1}^{\infty} x_n 2^{-n}\right)$$

The fibres are precisely the \sim_{ξ} equivalence classes, so X_{ξ} is homeomorphic to S^1 .



Example 2. Let (V, E) have one vertex and three edges at each level. Identify X_E with $\{0, 1, 2\}^{\omega}$.

(W,F) is again a single path, and for f in F, $\xi^0(f)=0$ and $\xi^1(f)=2$.

Example 2. Let (V, E) have one vertex and three edges at each level. Identify X_E with $\{0, 1, 2\}^{\omega}$.

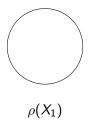
(W,F) is again a single path, and for f in F, $\xi^0(f)=0$ and $\xi^1(f)=2$.

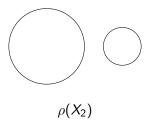
There is a nested sequence $X_1 \subseteq X_2 \subseteq X_3 \subseteq \cdots \subseteq X_E$ such that

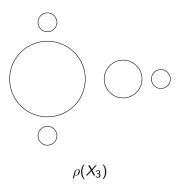
$$X_E = \overline{\bigcup_{n=1}^{\infty} X_n}$$

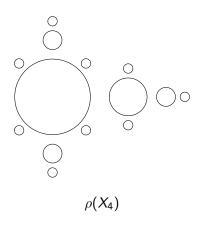
and each $\rho(X_n)$ is a disjoint union of finitely many circles.

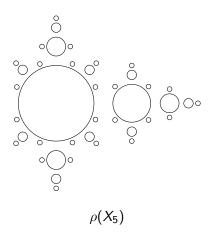


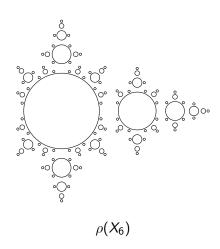












The groupoid R_{ξ}

Let
$$R_{\xi} = \rho \times \rho(R_E)$$
.

With the quotient topology, R_{ξ} is a nice groupoid, and a factor of R_E via $\rho \times \rho : R_E \to R_{\xi}$.

The groupoid R_{ξ}

Let
$$R_{\xi} = \rho \times \rho(R_E)$$
.

With the quotient topology, R_{ξ} is a nice groupoid, and a factor of R_E via $\rho \times \rho : R_E \to R_{\xi}$.

Using some K-theory trickery, we obtain

$$K_0(C_r^*(R_{\xi})) \cong K_0(C_r^*(R_E)) \qquad K_1(C_r^*(R_{\xi})) \cong K_0(C_r^*(R_F))$$

The groupoid R_{ξ}

Let
$$R_{\xi} = \rho \times \rho(R_E)$$
.

With the quotient topology, R_{ξ} is a nice groupoid, and a factor of R_E via $\rho \times \rho : R_E \to R_{\xi}$.

Using some K-theory trickery, we obtain

$$K_0(C_r^*(R_{\xi})) \cong K_0(C_r^*(R_E)) \qquad K_1(C_r^*(R_{\xi})) \cong K_0(C_r^*(R_F))$$

Through the set-up $\xi^0, \xi^1: (W, F) \to (V, E)$, we can prescribe $K_*(C_r^*(R_\xi))$.

This construction was cooked to get the desired K-theory.

This construction was cooked to get the desired K-theory.

Another direction: using work of Deeley, Putnam, Strung, the set-up is $\pi: (\tilde{X}, \tilde{\varphi}) \to (X, \varphi)$, an extension of a Cantor minimal system. $\pi^{-1}(x)$ is either a single point or homeomorphic to the attractor of an iterated function system.

This construction was cooked to get the desired K-theory.

Another direction: using work of Deeley, Putnam, Strung, the set-up is $\pi: (\tilde{X}, \tilde{\varphi}) \to (X, \varphi)$, an extension of a Cantor minimal system. $\pi^{-1}(x)$ is either a single point or homeomorphic to the attractor of an iterated function system.

The K-theory will depend a great deal on the topology of the attractor.

This construction was cooked to get the desired K-theory.

Another direction: using work of Deeley, Putnam, Strung, the set-up is $\pi: (\tilde{X}, \tilde{\varphi}) \to (X, \varphi)$, an extension of a Cantor minimal system. $\pi^{-1}(x)$ is either a single point or homeomorphic to the attractor of an iterated function system.

The K-theory will depend a great deal on the topology of the attractor.

Can K-theory tell us anything about fractals and iterated function systems? Vice versa?

Thank you!