

Using Multiple Instance Learning for Explainable Flare Prediction

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Outline

Using Multiple Instance Learning for Explainable Solar Flare Prediction

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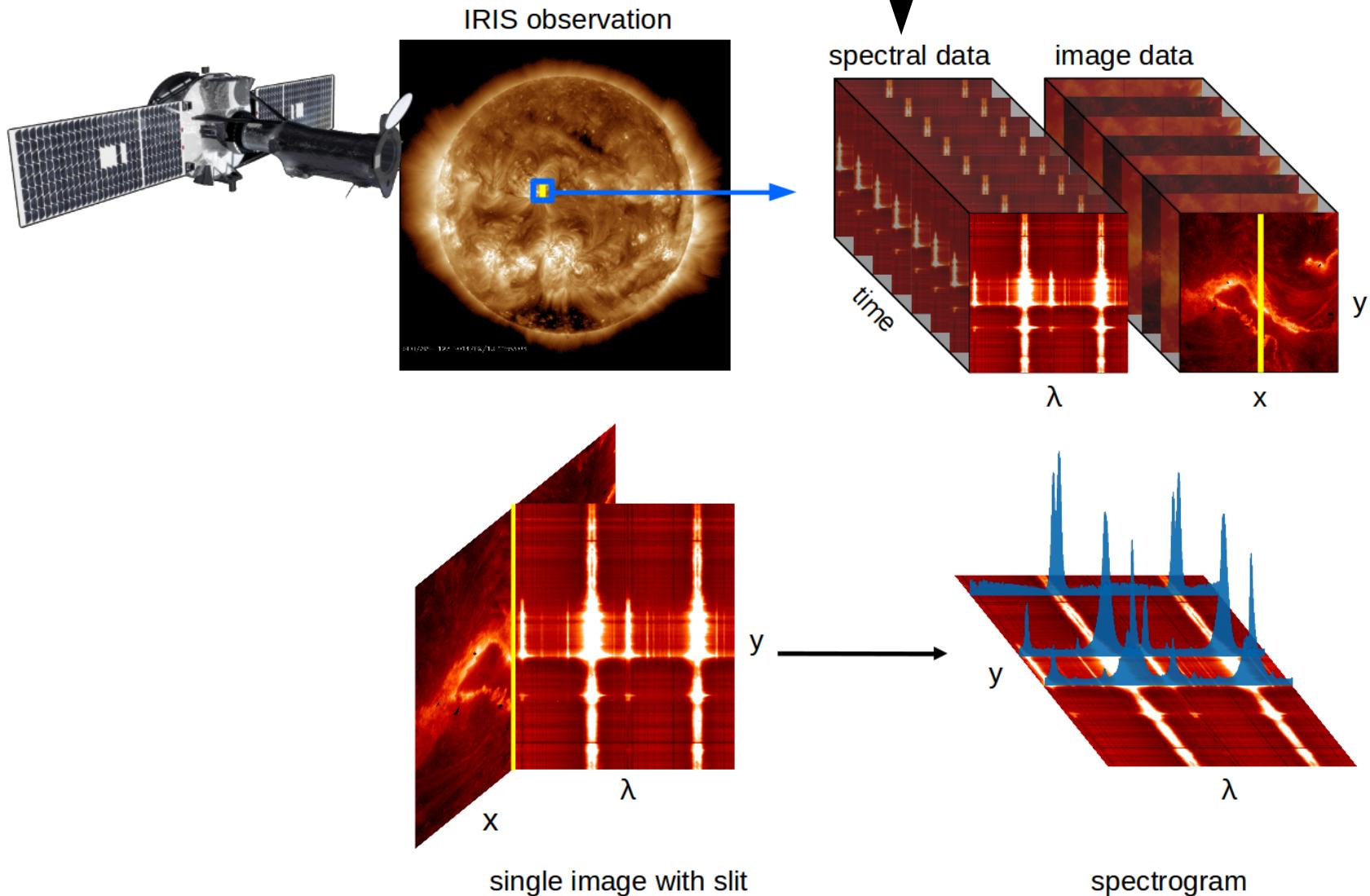
Main message:

When labels are only available on a higher hierarchical level,
use Multiple Instance Learning! (also works for images)

Use case:

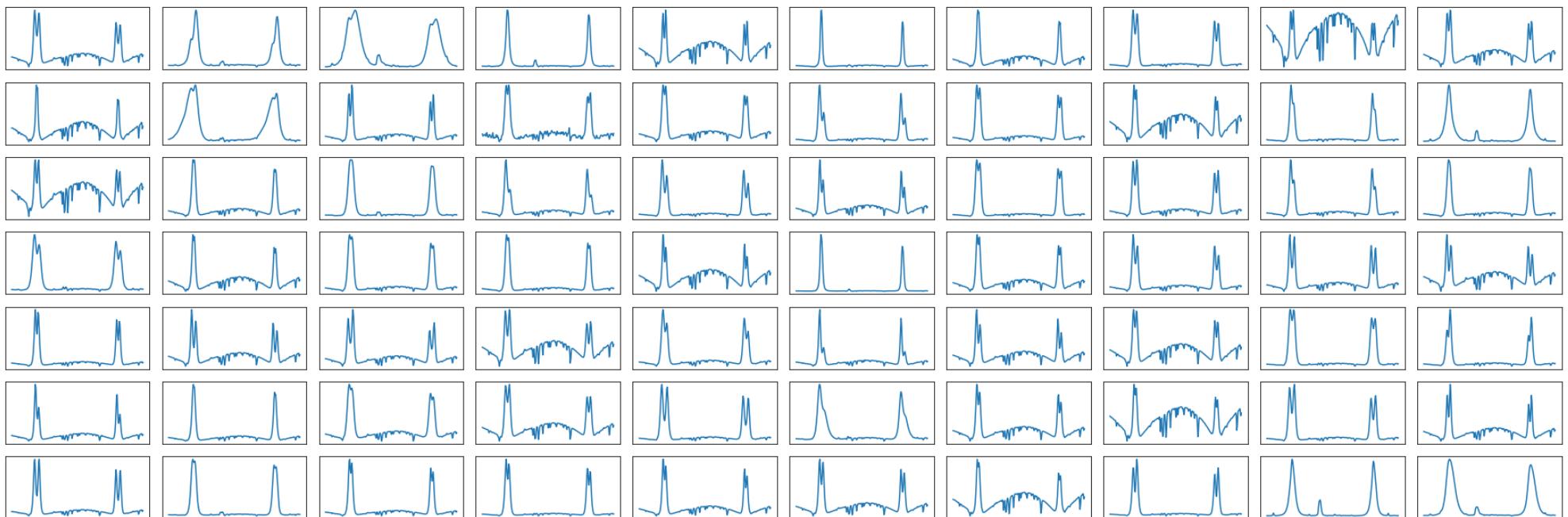
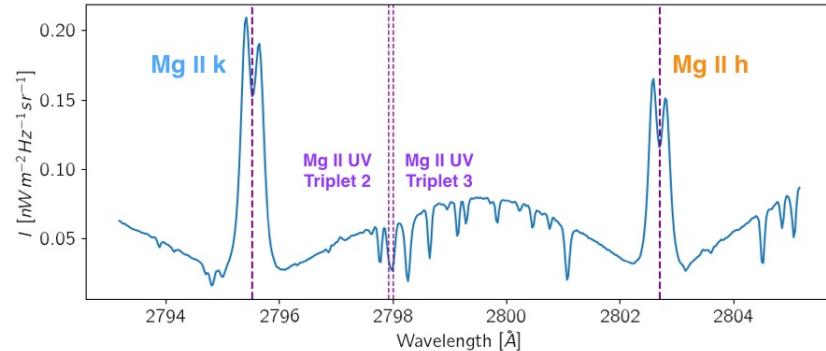
Explainable flare prediction with IRIS spectral data

IRIS data



Mg II h&k spectral profiles

source: Lockheed Martin



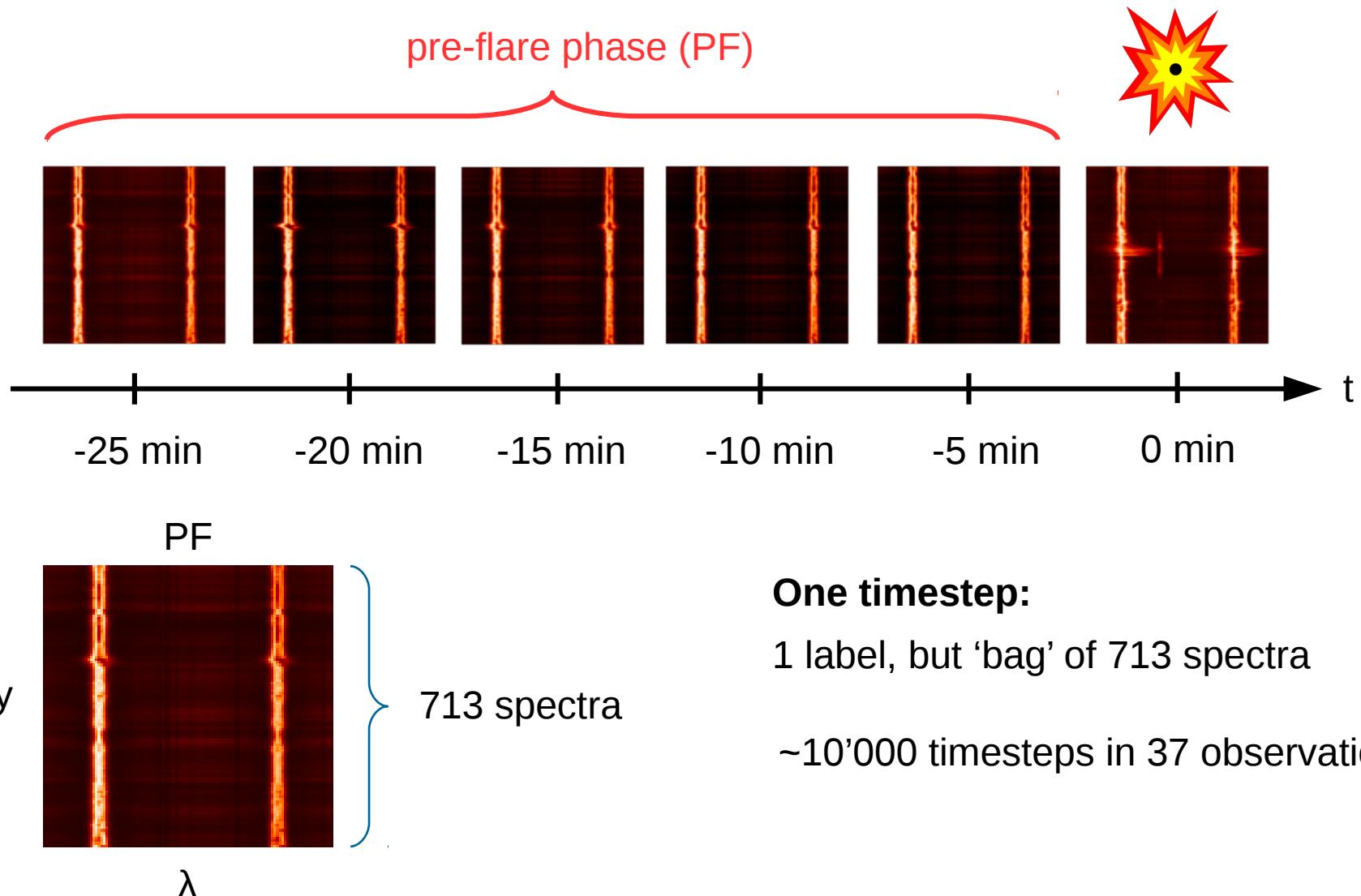
Research Problem

- ▶ **Which types of Mg II h&k spectra appear shortly before a flare?**
- ▶ **How well can they be used to predict flares?**

Dataset:

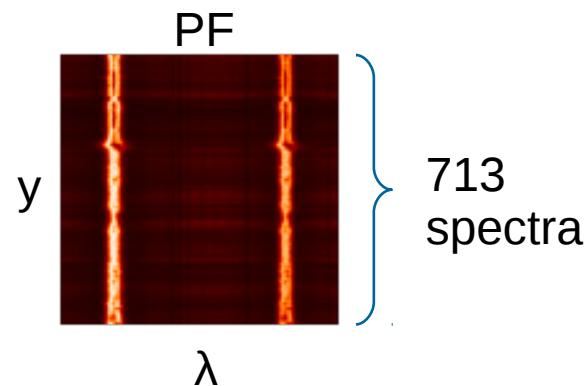
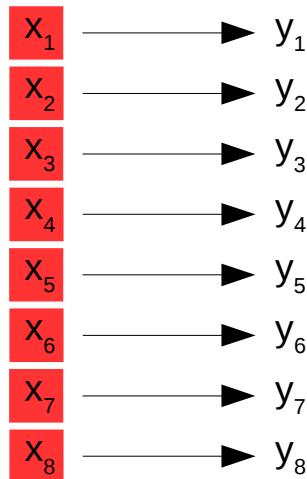
- 37 carefully selected IRIS observation windows
 - 18 non-flaring active regions (AR)
 - 13 M and 6 X-class pre-flare active regions (PF)
- Each of 25 minutes length
- Each with tens to hundreds of timesteps and a few hundred y-pixels
- Balanced classes (not an operational scenario)
- Spectra interpolated to 240 bins, stored as vectors
- Spectra normalized to range [0, 1]

Flare prediction with IRIS

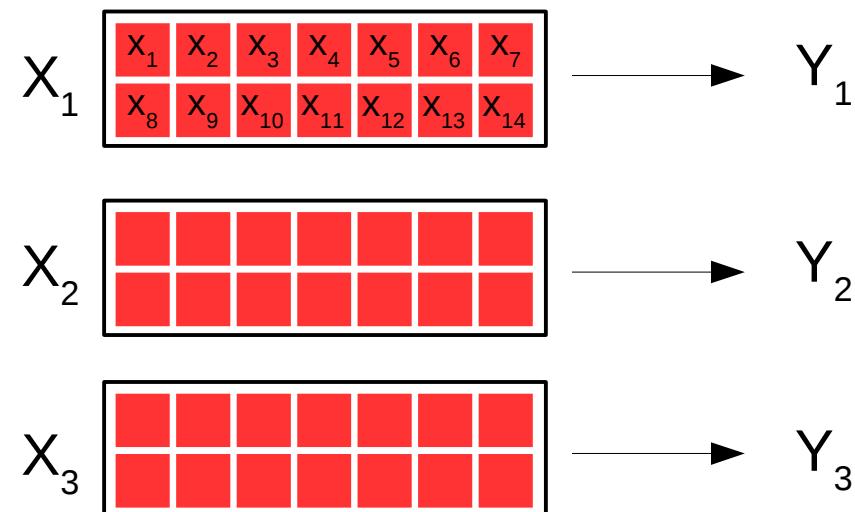


Multiple Instance Learning

Supervised Learning:

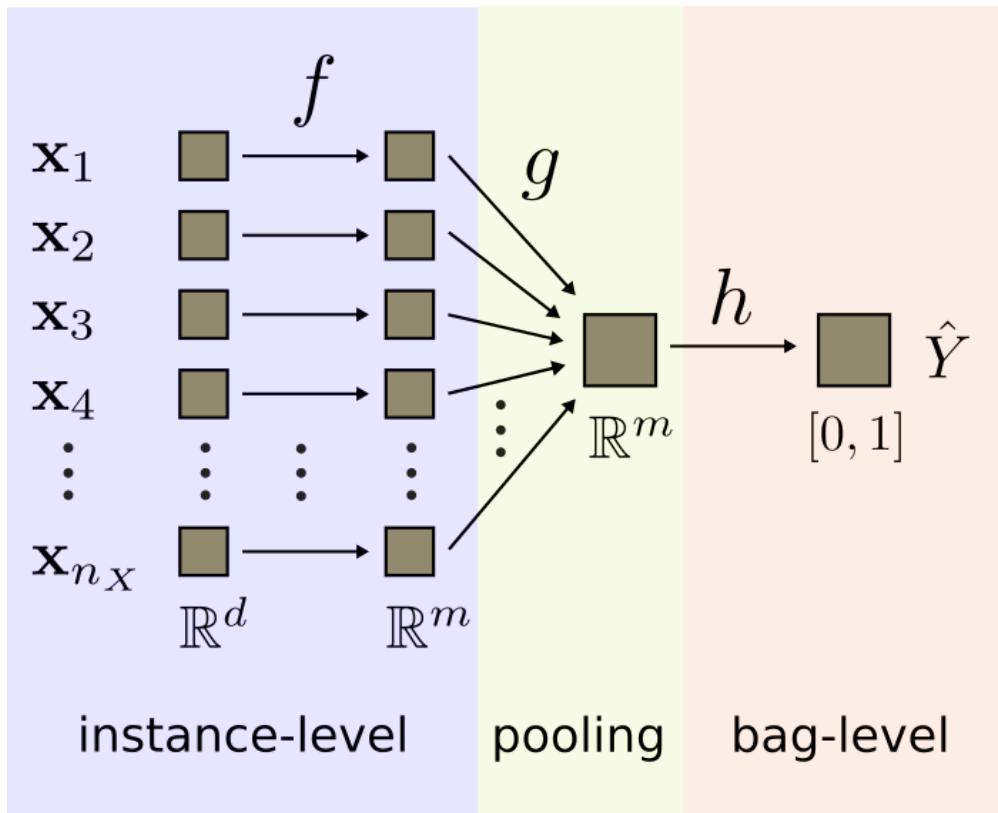


Multiple Instance Learning (MIL):



$$\begin{aligned} X &= \{\mathbf{x}_k\}_{k=1,\dots,n_X} \in \mathbb{R}^d \\ Y &\in \{0, 1\} \end{aligned}$$

Multiple Instance Learning



C. Huwyler, M. Melchior, 2021

$$X = \{\mathbf{x}_k\}_{k=1,\dots,n_X} \in \mathbb{R}^{d \times n_X}$$
$$Y \in \{0, 1\}$$

$$\hat{Y} = S(X)$$

$$S = h \circ g \circ f$$

Neural networks:

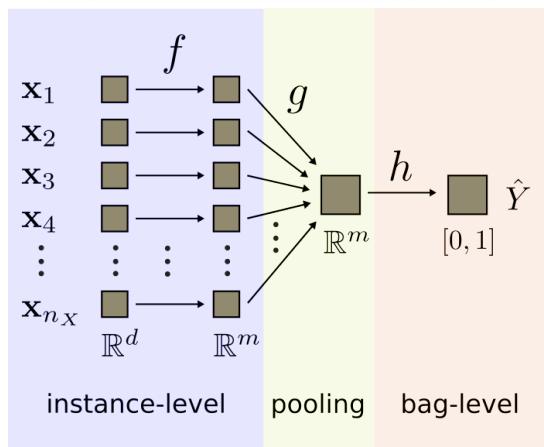
$$f = f_\theta \quad (\text{'mapper'})$$

$$g = g_\varphi \quad (\text{'pooling'})$$

$$h = h_\psi \quad (\text{'classifier'})$$

Instance-based MIL

$$S = h \circ g \circ f$$



Use f to assign a probability to every instance:

$$p_k = f_\theta(\mathbf{x}_k) \in [0, 1]$$

Log-Mean-Exp to interpolate between minimum and maximum pooling:

hyperparameter

$$g(p_k) = \frac{1}{r} \log \left(\frac{1}{n_X} \sum_k e^{rp_k} \right) \in [0, 1]$$

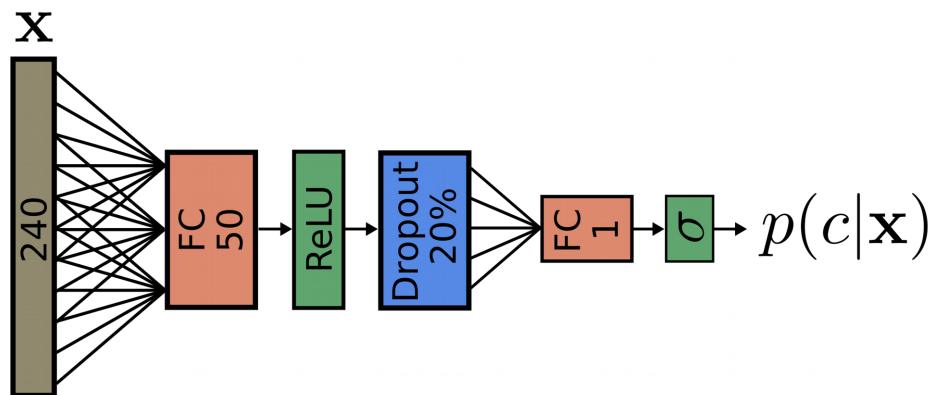
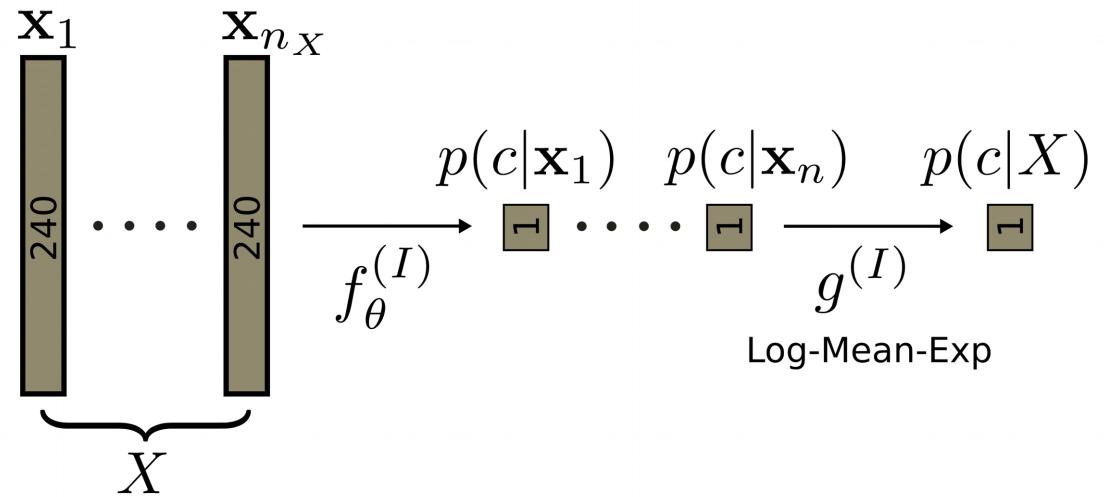
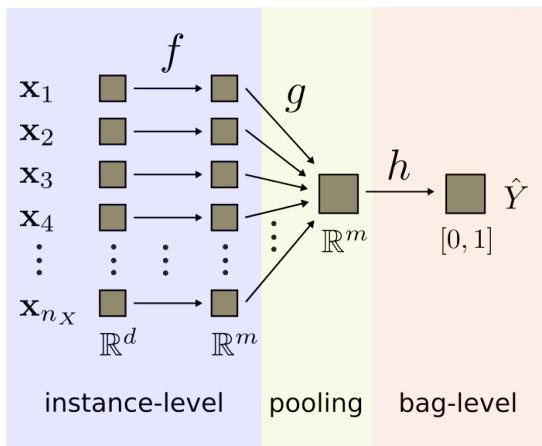
$$\lim_{r \rightarrow 0} g(p_k) = \frac{1}{n_X} \sum_k p_k$$

$$\lim_{r \rightarrow \infty} g(p_k) = \max_k p_k$$

The pooling g already returns a probability, the function **h can be set to the identity.**

Instance-based MIL

$$S = h \circ g \circ f$$

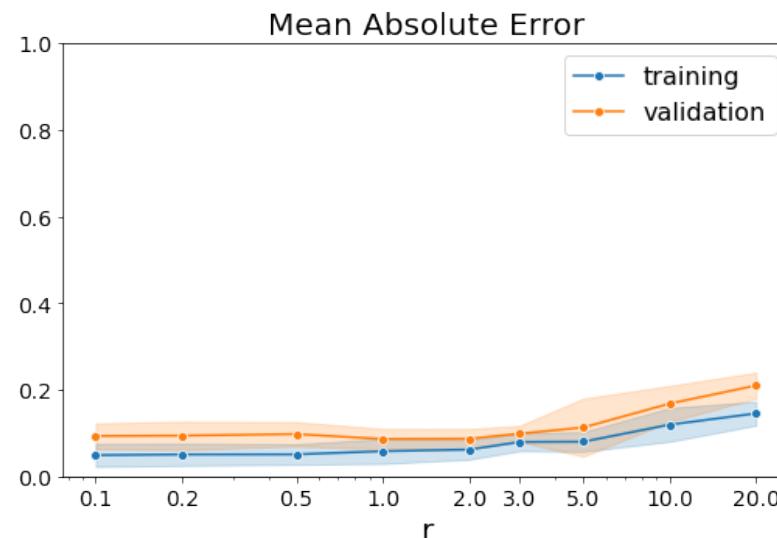
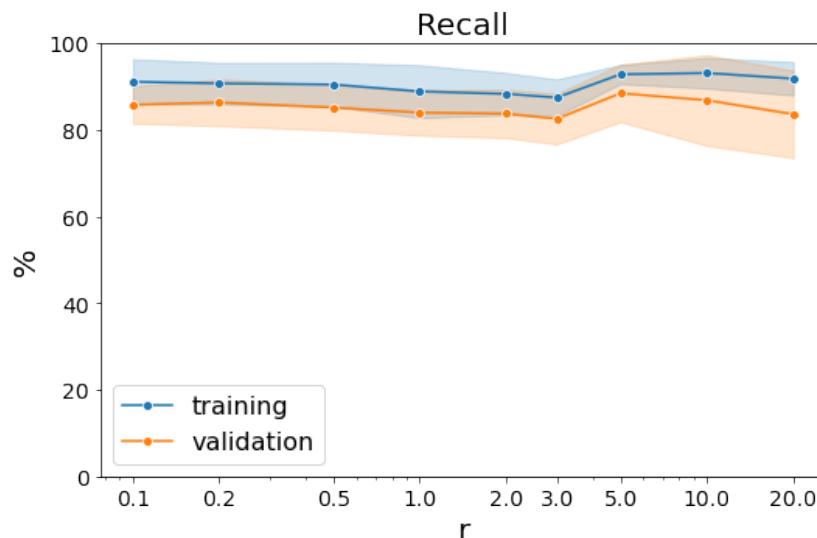
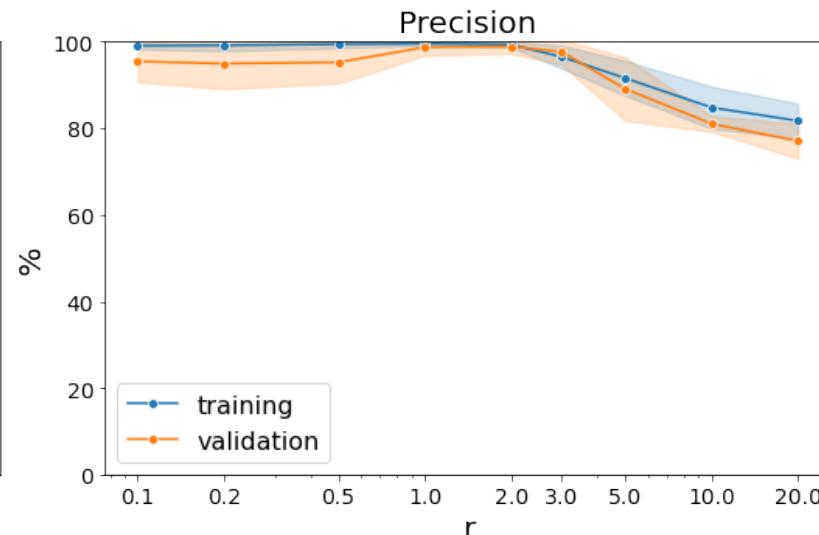
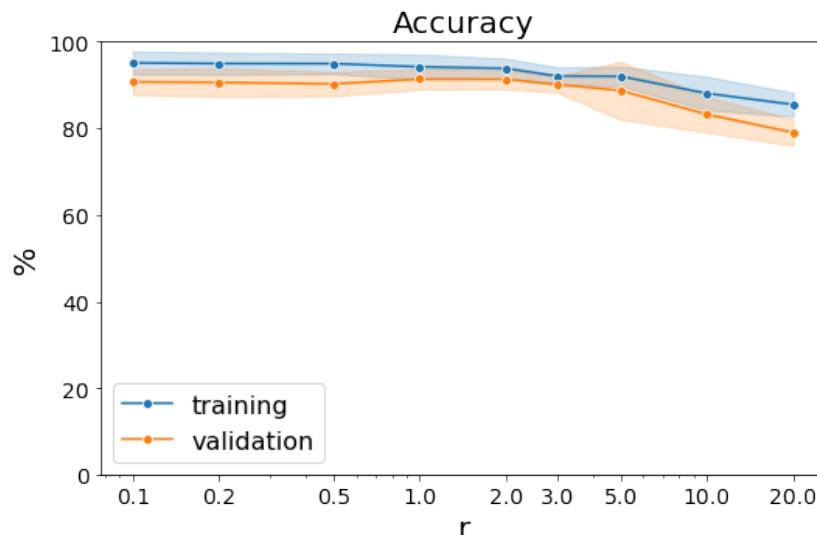


Training:

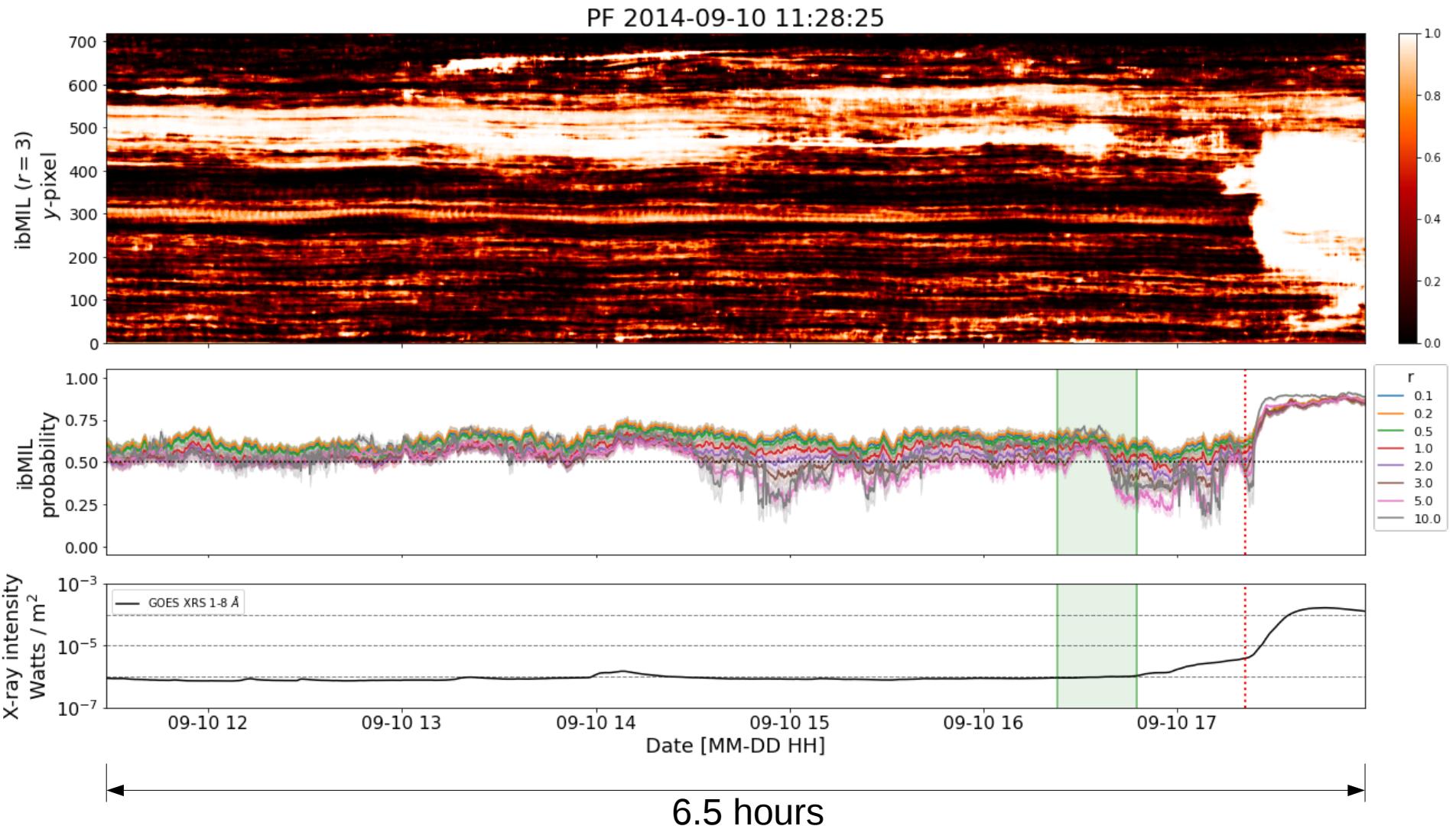
- Dataset with 10'000 labeled bags of spectra
- MAE loss
- Early stopping

$$f_\theta^{(I)}:$$

Bag-Level: Prediction Results

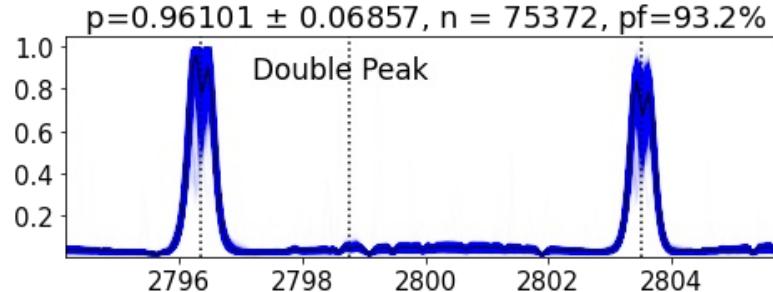
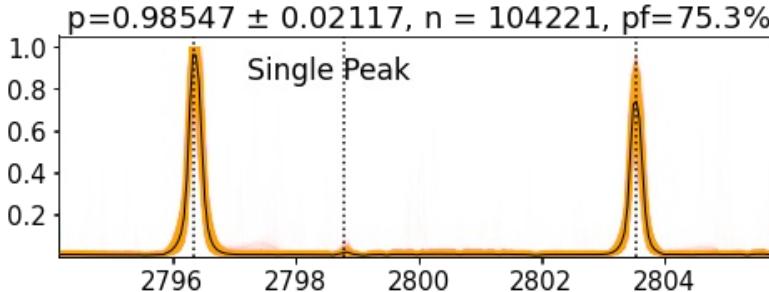
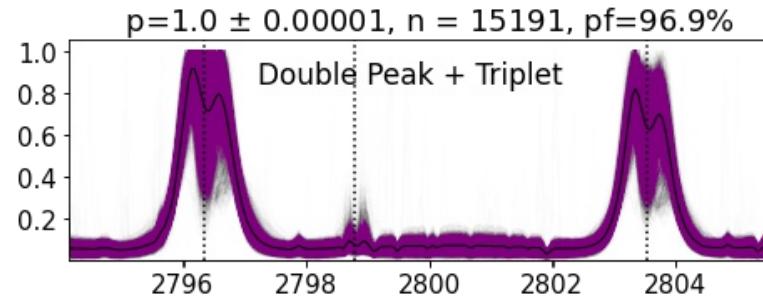
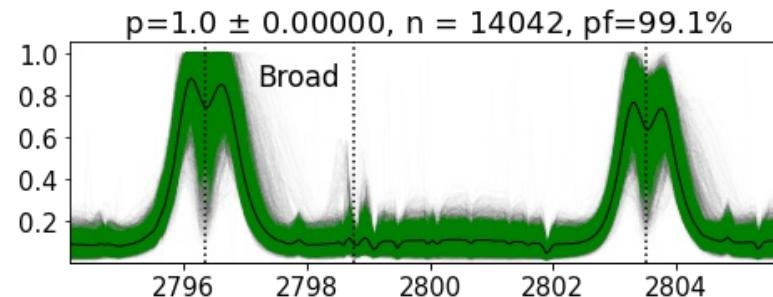
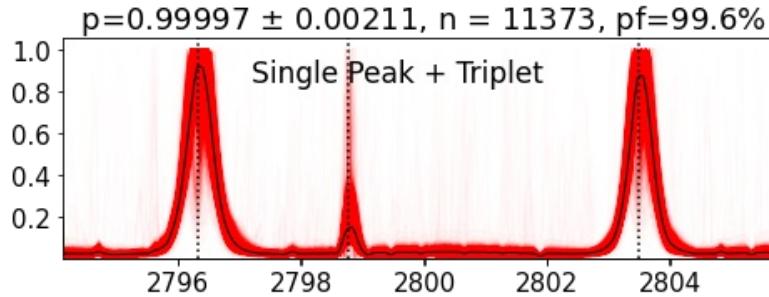


Instance-Level: Saliency Maps



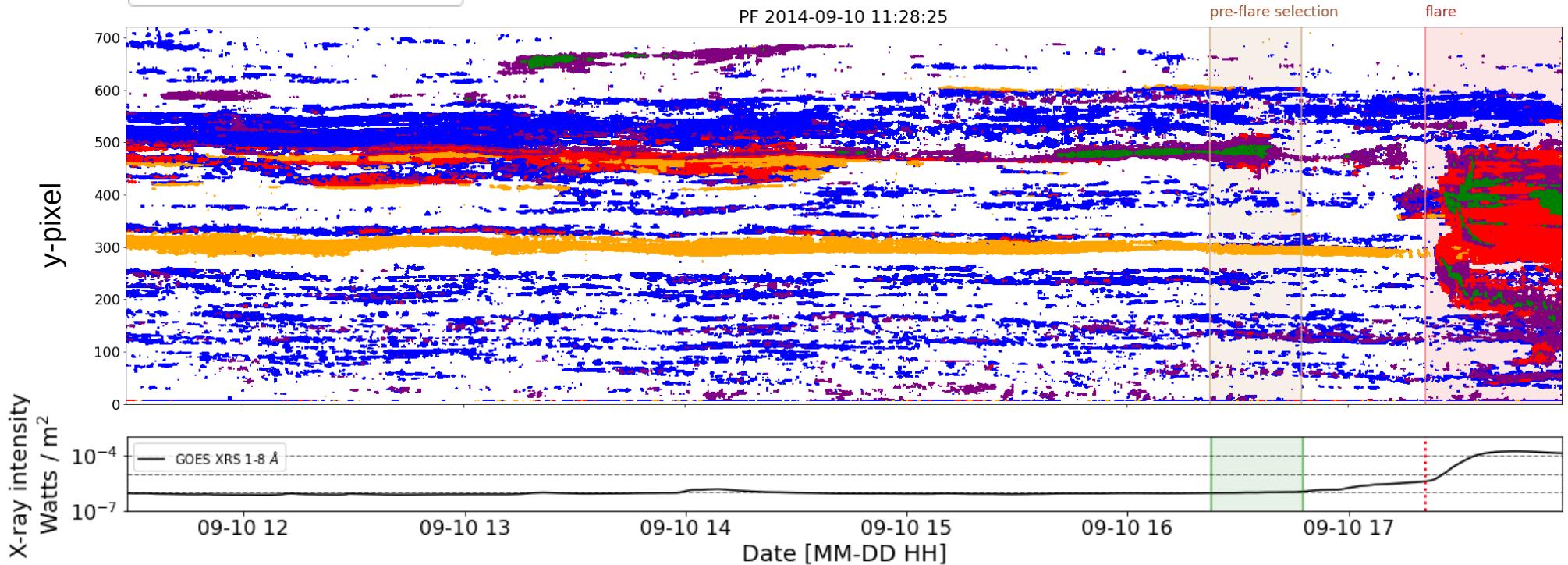
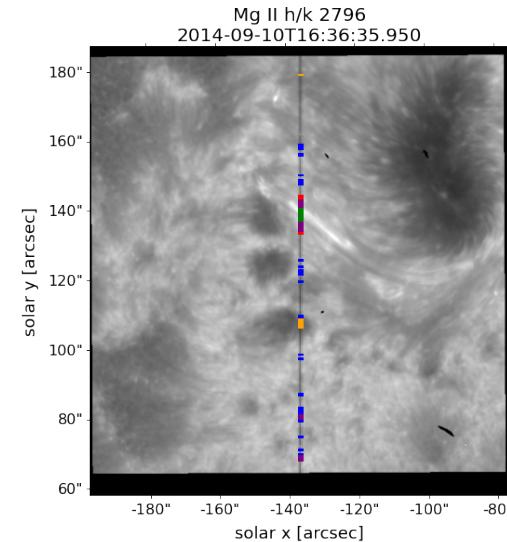
Instance-Level: Characteristic Pre-Flare Spectra

k-means clustering with k=128 – 5 particular types of spectra for high average probabilities:

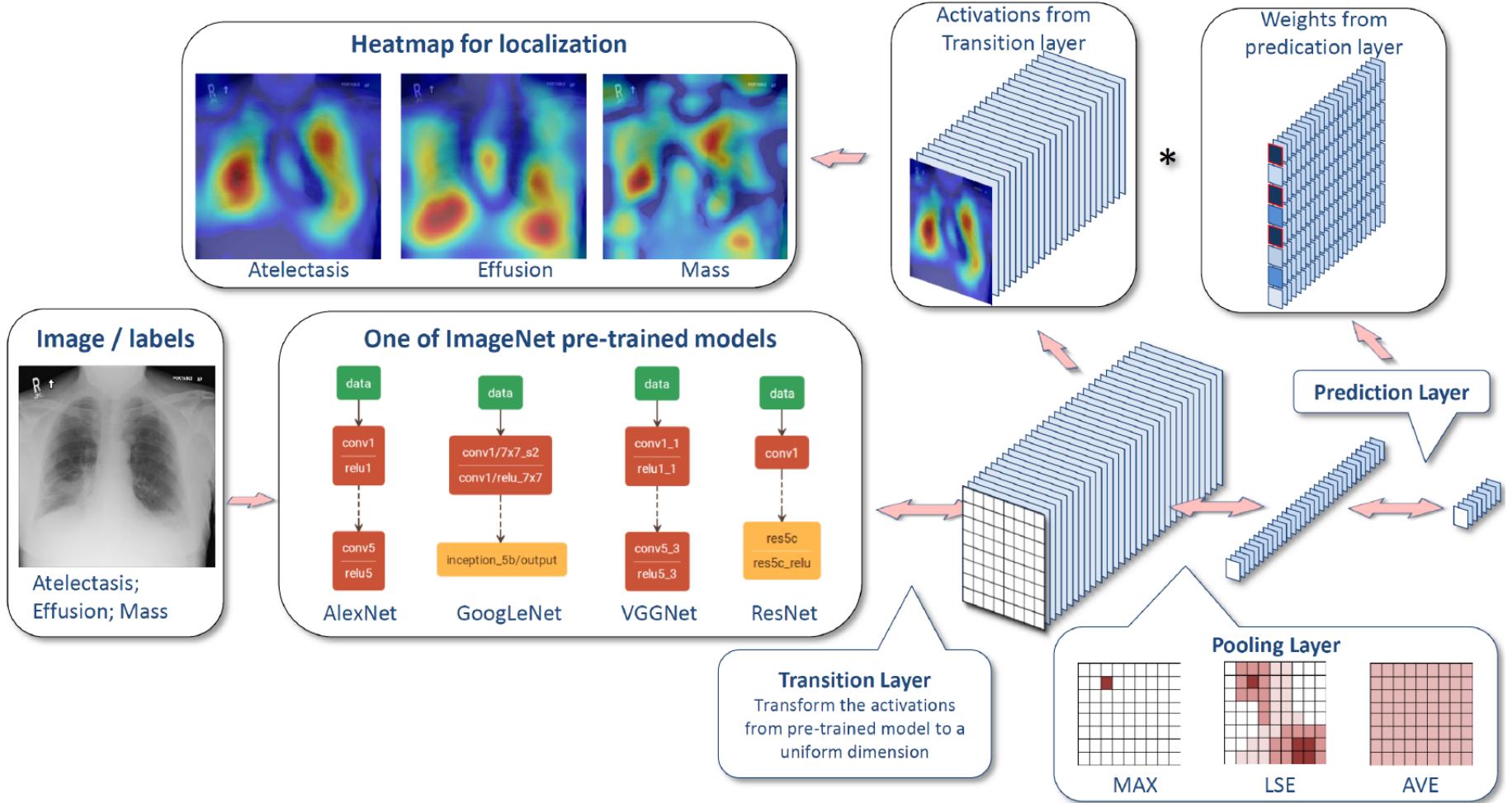


Visualizing Groups

- Double Peak
- Double Peak + Triplet
- Broad
- Single Peak + Triplet
- Single Peak



Multiple Instance Learning on Images



X. Wang et al, 2017

ChestX-ray8: Hospital-scale Chest X-ray Database and Benchmarks on Weakly-Supervised Classification and Localization of Common Thorax Diseases

Conclusion

- Use MIL when labels are not available at level of individual instances, but higher up.
- Use MIL when your problem can be divided into instances and you desire explainability of bag-level predictions.
- MIL also works for image segmentation tasks – to be used on image data, such as AIA / HMI!