

MMCESIM DOCUMENTATION & TUTORIALS

TASK-ORIENTED MMWAVE CHANNEL ESTIMATION SIMULATION

Version 0.2.1

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The latest edition of this document (MMCESIM DOCUMENTATION & TUTORIALS) can be freely accessed online at https://pub.mmcesim.org/mmCEsim-doc.pdf or mmces.im/pdf for short.

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mmCEsim Website: https://mmcesim.org

Source of This Document: https://github.com/mmcesim/mmcesim-doc

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Preface

TIP

mmCEsim documentation & tutorials are under development!

As a researcher in wireless communications and signal processing, I have always had a passion for programming. Since my first year at university when I started using C++ to accomplish amazing tasks, I have been convinced of the importance of software in research.

Despite this, many researchers underestimate the significance of software in implementation, simulation, and verification of algorithms. Scientific software and programming languages, along with libraries, have been the driving force behind advances in science. Therefore, I am proud to present mmCEsim, an open-source software that is not only easy to use but also free for all.

The idea for mmCEsim originated from the tedious process of writing C++ code for implementing compressed channel estimation for reconfigurable intelligent surface (RIS)-assisted multiple-input multiple-output (MIMO) systems. I was driven by a desire to get rid of these repetitive tasks and eliminate the need to spend so much time setting up simulations. Inspired by NYUSIM, I decided to create my own simulation software.

To make it even easier to use, I designed a programming language called ALG, with simple syntax for describing algorithms. This language can be converted into other languages, such as C++ and Matlab, for simulation. To use mmCEsim, simply configure your system settings, decide on your channel estimation algorithm, and extend the sounding and estimation process with ALG.

At present, mmCEsim supports channel estimation based on compressed sensing in mmWave and is expected to be more general in the future. It is still under active development and evolving.

I would like to thank my professor, seniors, and fellow students for their help and inspiration. I would also like to express my gratitude to Jinwen Xu for designing the elegant LaTeX template, beaulivre, which has made this document possible.

WUQIONG ZHAO Nanjing, China May 2023



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I

PRELIMINARY

Make preparations before we start.



Preview 1

Before diving into documentation details, let's first have a preview of mmCEsim. Maybe you are not sure whether your research or study need this powerful tool, then read this chapter to have a glimpse of mmCEsim.

1.1 Introduction

The application is dedicated to simulate millimeter wave (mmWave) channel estimation:

mmCEsim = mmWave + Channel Estimation + simulation,

where reconfigurable intelligent surface (RIS), also known as intelligent reflecting surface (IRS) [1] is supported for multiple input multiple output (MIMO) systems.



Figure 1.1: mmCEsim banner.

We offer a task-oriented simulation software for researchers to focus on algorithms only without being bothered by coding.

1.2 Features

Here is a list of basic features of mmCEsim:

- Task-oriented mmWave channel estimation formulation;
- Customizable system model;
- Extendable algorithms with our designed ALG language;
- Multiple RISs support;
- Automatic report generation (in plain text and LATEX PDF);
- Well-written documentation with examples and tutorials.

1.3 Algorithm Background

The task-oriented channel estimation for (RIS-assisted) mmWave MIMO systems is implemented with compressed sensing (CS), which exploits the sparsity of mmWave channels.

1.4 Software Implementation

Based on the algorithm background, we implement this software with command line interface (CLI), graphic user interface (GUI), web application and a VS Code extension. The workflow of mmCEsim is depicted in Fig. 1.2.

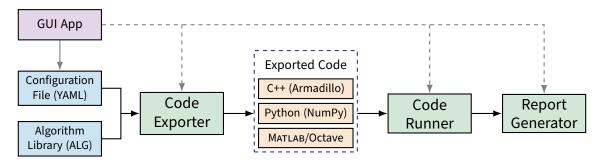


Figure 1.2: mmCEsim workflow.

Installation 2

2.1 Download Binary

You can download the built binary of mmCEsim from GitHub releases. The built CLI binaries include support for Linux (x86), macOS (x64 and arm) and Windows (x86).

They all statically link to libraries, so theoretically no dependency is needed.

Note

Since GitHub Actions currently only provide x86_64 machines, the binary for macOS with arm architecture is built manually on my MacBook Air with an M1 chip.

2.2 Build from Source

Since mmCEsim is built with CMake, so you can easily build the source on Unix-based systems. For Windows, I think there are similar ways.

On a Unix-based system, you can simply use the following code to build and install mmCEsim.

```
git clone https://github.com/mmcesim/mmcesim.git --recurse-submodules
cd mmcesim
mkdir build
cmake . build
td build
make
sudo make install
```



The option --recurse-submodules is required because some dependencies of mmCEsim are managed by Git submodules.

You need to have a C++ compiler that supports C++17 standard, and have installed the Boost library (statically) of minimum version 1.70.0 on your system. You can install them easily on Unix-based systems with your favourite package manager. For Windows users, please follow the official instruction of Boost.

```
# Debian, Ubuntu
sudo apt install libboost-dev
# Arch
sudo pacman -Ss boost
# macOS
sudo port install boost # with MacPorts
brew install boost # with HomeBrew
```

If you want to build the GUI app as well, you need to install Qt6.

Some options can be configured when calling cmake.

- CMAKE_BUILD_TYPE: Build type (default as Release)
- CMAKE_INSTALL_PREFIX: Installation prefix (default as system path)
- MMCESIM_BUILD_ASTYLE: Build astyle code ormatter (default as ON)
- MMCESIM_BUILD_LOG: Build mmCEsim log tool (default as ON)
- MMCESIM_BUILD_MAINTAIN: Build mmCEsim maintenance tool (default as ON)
- MMCESIM_BUILD_GUI: Build mmCEsim GUI App with Qt (default as OFF)
- MMCESIM_APPLE_COPY_SH: Copy additional shell script for macOS (default as OFF).
- MMCESIM_TESTS: Run mmCEsim tests (default as ON).

For example, you may use cmake . build -D CMAKE_INSTALL_PREFIX=usr/mmcesim to install mmCEsim to the directory usr/mmcesim.

2.3 Troubleshooting

2.3.1 macOS Safety Warning

You may view a safety warning after downloading the binary from GitHub Releases. The trust_mmcesim.sh is a script to remove that warning. (Give the script proper permission before running in its directory). Technically, it does xattr -r -d com.apple.quarantine

binary>.

Cannot find your problems here?

- If you have a bug to report, a suggestion for developers, or an issue relating to the software itself, feel free to open an issue on GitHub;
- If you have a general question to ask, you can join the discussions on GitHub;
- Or you can directly send emails to contact@mmcesim.org.

II

DOCUMENTATION

Every syntax and option in details.



3.1 CLI Options

3.1.1 Help Yourself

With mmcesim -h, you can view all supported commands and options.

```
1 mmCEsim 0.2.1 (C) 2022-2023 Wuqiong Zhao
2 Millimeter Wave Channel Estimation Simulation
5 Usage: mmcesim <command> <input> [options]
7 Commands:
   sim [ simulate ]
                          run simulation
   dbg [ debug ]
                          debug simulation settings
  exp [ export ]
10
                          export code
   cfg [ config ]
                          configure mmCEsim options
   (Leave empty)
                          generic use
14 Allowed options:
16 Generic options:
   -v [ --version ]
                          print version string
   -h [ --help ]
                          produce help message
18
    --gui
                          open the GUI app
19
20
21 Configuration:
22
   -o [ --output ] arg
                          output file name
   -s [ --style ] arg
                          style options (C++ only, with astyle)
23
   -l [ --lang ] arg
                          export language or simulation backend
24
   --value arg
                          value for configuration option
25
26
   -f [ --force ]
                          force writing mode
   -V [ --verbose ]
                          print additional information
27
    --no-error-compile
                          do not raise error if simulation compiling fails
   --no-term-color
                          disable colorful terminal contents
```

3.1.2 Command

The allowed commands are explained in the following.

3.1.2.1 exp

Command exp exports the .sim configuration and corresponding .alg algorithms to a selected language. Currently, only export to C++ with Armadillo is supported.

3.1.2.2 sim

Command sim simulates the exported code with the selected backend. Currently, only C++ with Armadillo is supported.

So far, only C++ compiler g++ (default) and clang++ are supported which can be configured with option cfg cpp. You may also need to configure additional C++ flags with cfg cppflags if by default the compiler cannot find armadillo library.

3.1.2.3 dbg

Debug the simulation. This is different from sim in that the generated C++ code is compiled with -g3 instead of -03. Therefore, debug information is retained.

3.1.2.4 cfg

Configure settings.

- Use mmcesim cfg <name> to show the value of <name>.
- Use mmcesim cfg <name> --value=<name> to set the value of <name> as <value>.

```
EXAMPLE 3.1 (Configure C++)
1 mmcesim cfg cpp --value="clang++"
2 mmcesim cfg cppflags --value="-I/opt/local/include -L/opt/local/lib"
 Source: https://github.com/mmcesim/mmcesim/blob/master/scripts/mac_config_cppflags_tvj.sh.
```

3.1.3 Options

3.1.3.1 -v (--version)

Print the version string of mmCEsim.

3.1.3.2 -h (--help)

See §3.1.1.

3.1.3.3 --gui

Open the GUI application.

3.1.3.4 -o (--output)

Set the output file name. No extension name is required, and is added automatically according to your backend settings. .cpp for C++, .py for Python, .ipynb for Jupyter, and .m for Matlab or GNU Octave.

```
3.1.3.5 -s (--style)
```

Set C++ AStyle (code formatting) options.

3.1.3.6 -l (--lang)

Set the export language or simulation backend.

3.1.3.7 --value

The value for configuration options.

3.1.3.8 -f (--force)

Enable the force writing mode. This will overwrite existent output files.

3.1.3.9 -V (--verbose)

Print additional information.

3.1.3.10 --no-error-compile

Do not raise error if compiling fails. This is useful in sim and dbg.

3.1.3.11 --no-term-color

Disable colorful terminal contents.

mmCEsim also supports the NO COLOR standard: Command-line software which adds ANSI color to its output by default should check for a NO_COLOR environment variable that, when present and not an empty string (regardless of its value), prevents the addition of ANSI color.

When you have a non-empty NO_COLOR environmental variable, the color output is disabled, and you no longer need the --no-term-color option.

3.2 Configuration

Configuration is written in a text file with extension .sim (actually, can be any file extension) in YAML syntax. [Required] keys need to be filled in, unless provided with a Default value. [Optional] keys can be specified. [Conditional] keys can be either required or optional, depending on other settings.

3.2.1 version Default: 0.2.1 [Required]

This field takes a string value representing the targeted mmCEsim version. For compatibility convenience, this string can be used by the compiler to decide the behavior. The current default value is the same as the compiler version (0.2.1).

3.2.2 meta [Optional]

This is a map that provides metadata which can be used in the report. The used fields now include title, description, author.

This field is a map that contains physical system settings.

3.2.3.1 physics/frequency Default: narrow [Required]

The frequency bandwidth is specified in this field, which can have value narrow for narrowband (default) or wide for wideband.

3.2.3.2 physics/off_grid Default: true [Required]

This is actually about the model. With the geometric channel model with grid, there can be off-grid (or power leakage) problems. Recently, there are also super resolution formulations to solve the problem. But we still adopt the grid representation for its popularity and simplicity. By setting off_grid to false, the off grid effect is discarded, i.e. all angles fall on the grid. The default value is true.

3.2.3.3 physics/carriers [Conditional]

For a wideband system, you may specify the number of carriers used in OFDM. Its corresponding macro in CALC is `CARRIERS_NUM`.

3.2.4 nodes [Required]

A sequence (array) of nodes in the channel network. Transmitter (Tx), Receiver (Rx), Reconfigurable Intelligent Surface (RIS) are all considered node (channels are the connecting edges to these nodes). For each of its elements, you need to specify the following fields.

3.2.4.1 nodes/id [Required]
The id is used in channels so that we know the direction of channel.
3.2.4.2 nodes/role Default: RIS [Required]
3.2.4.3 nodes/num Default: 1 [Required]
3.2.4.4 nodes/size [Required]
3.2.4.5 nodes/beam [Required]
3.2.4.6 nodes/grid Default: same [Required]
3.2.4.7 nodes/beamforming [Required]
For a node with role transmitter (Tx) or receiver (Rx), it is the active beamforming as precoding and combing, respectively. For a RIS node, it is the passive reflection tensor.
► nodes/beamforming/variable [Required] For Tx or Rx, this sets the variable name of the beamforming matrix (for narrowband) or tensor (for wideband). For RIS, this is the variable name of the reflection tensor.
▶ nodes/beamforming/scheme
▶ nodes/beamforming/formula [Conditional] Custom beamforming formula.
3.2.5 macro [Optional]
3.2.6 channels [Required]
3.2.6.1 channels/id [Required]
3.2.6.2 channels/from [Required]
3.2.6.3 channels/to [Required]
3.2.6.4 channels/sparsity [Required]
3.2.6.5 channels/gains Default: normal [Required]
3.2.7 sounding [Required]
3.2.7.1 sounding/variables [Required]
Channel variable names are defined here, including
• received: received signal
noise: received noise
• channel: cascaded channel
3.2.8 preamble
This is the code part before main simulation (including sounding, estimation and report generation).
TIP ————————————————————————————————————
This part is specified using the ALG language.
3.2.9 estimation Default: auto [Required]
This part is specified using the ALG language.

3.2.10 conclusion
This part is specified using the ALG language.
3.2.11 appendix
This is the code part after all jobs are done. This part is specified using the ALG language.
3.2.12 simulation [Required]
3.2.12.1 simulation/backend Default: cpp [Required]
3.2.12.2 simulation/jobs [Required]
Simulation jobs. Each job is independent of one another.
► simulation/jobs/name
► simulation/jobs/test_num Default: 50 [Required] Number of Monte-Carlo simulations.
► simulation/jobs/SNR [Required] Signal-to-noise ratio (SNR).
▶ simulation/jobs/SNR_mode
► simulation/jobs/pilot [Required] The number of pilot overheads.
▶ simulation/jobs/algorithms
3.2.12.3 simulation/report
3.3 Algorithm
Algorithm are defined in ALG language, please refer to §6 for details.
3.4 Tools
3.4.1 Compose
Compose .sim configuration file from command line options.
NOTE -
This is still under development

3.4.2 Log

View or copy mmCEsim log file with mmcesim-log.

3.4.2.1 Log File

The log file is at $<install_prefix>$ /bin/mmcesim.log. It stores information about the configuration and many internal processing details. This is especially useful for diagnosis.

Here is an example of the header part of a log file:

```
1 [INFO] * Time
                   : 2023-05-06 10:40:17 (UTC +0800)
2 [INFO] * Version : 0.2.1
3 [INFO] * System : MacOs-ARM
4 [INFO] * Compiler : clang v13.0.0
5 [INFO] * CLI Args : mmcesim "-h"
```

3.4.2.2 Usage

The available command line options are listed as follows:

- -v (--version): produce help message;
- -h (--help): print version string;
- -p (--print): print mmCEsim log on terminal;
- -c (--copy): copy mmCEsim log to clipboard;
- -f (--file): show mmCEsim log file location.

If no option is provided, it will use the -p option to print the log. You can use several options together, such as -cp to print and copy.

```
TIP
 Use can use grep to filter the log, for example use
1 mmcesim-log | grep "\[ERROR\]"
 to get all error messages.
```

3.4.3 Maintain

You can view the latest stable version available with mmcesim-maintain -1. This internally invokes curl https://mmcesim.org/VERSION, so you need to have curl installed.

GUI Application 4

The GUI application is written with Qt, and is currently undergoing a major update.



Web Application 5

The web app address is https://app.mmcesim.org. The example web app page is shown in Fig. 5.1.

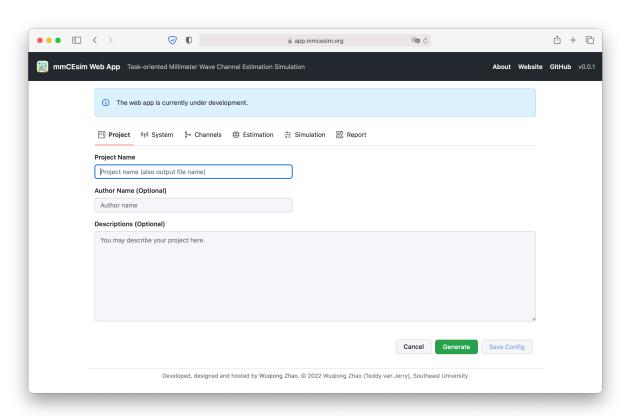


Figure 5.1: Web app interface.

Note

Since this app is hosted on my server, so it can be a little slow.



ALG Language 6

6.1 Data Type

6.1.1 Why Need Data Type

Languages Python and Matlab/Octave are weakly typed which can be convenient for writing the code. However, that is problematic for implementation. The efficiency is not satisfactory compared to C++, and sometimes you may encounter ambiguous error information in Matlab. Therefore, for the sake of efficiency and generality, ALG language is designed to be **strongly typed**.

6.1.2 Structure

The type specification is very simple, because ALG language concentrates on matrices. Basically, the structure of ALG language is

prefix + dimension + suffix.

For example, f2c means a matrix (dimension is 2) with data type as float and property as a constant.

6.1.3 Specifiers

6.1.3.1 Prefix

Basic Type Prefix Basic type just names the element type. They are shown in Table 6.1.

Table 6.1: ALG variable basic type prefix.

Prefix	Type	C++ Type	Python Type	Matlab/Octave Type
С	Complex	cx_double	complex	complex
f	Float	double	double	double
i	Integer	int	int	int64
u	Unsigned Integer	uword	uint	uint64
b	Boolean	bool	bool	logical
s	String	std::string	str	string
h	Character	char	char	char

Table 6.2: ALG variable alias prefix.

Alias Prefix	Туре	Equivalent Two-character Type
v	(Column) Vector	c1
r	Row Vector	c2
m	Matrix	c2
t	Tensor	c3
d	Double	fO

Alias Prefix Alias prefixes not only set the element type, but also the dimension. They are the one character alias for a two-character type. A list of alias prefixes is shown in Table 6.2.

v, r, m and t are all for complex types. For a non-complex type, you need to use the normal twocharacter way.

Row vector (r) is actually regarded as a matrix for simplicity, so its dimension is still 2. Only column vector (v) is the real vector. But there can be differences in terms of INIT, so it should not be confused with m.

6.1.3.2 Dimension

Dimensions range from 0 to 3. Details are shown in Table 6.3.

Table 6.3: ALG variable dimension.

Dimension	Type	C++ Type
0	Scalar	_
1	Vector	Col
2	Matrix	Mat
3	Tensor	Cube

Dimension for a scalar can not be omitted.

Please note that matrices are stored in **column major** order, which is the default order in C++ (Armadillo) and Matlab/Octave. In Python (NumPy), it is equivalent to the option order='F'.

You should always remember the column major order, especially if you use are accustomed to Python. The order will make a big difference to matrix reshape and vectorization.

6.1.3.3 Suffix

All suffixes of ALG variables are shown in Table 6.4.

Table 6.4: ALG variable suffix.

Suffix	Meaning	C++	Python	MATLAB/Octave
С	Constant	const	(None)	persistent
r	Reference	reference	(None)	(None)

TIP

Two suffixes cannot be used together and there is also no need to do so. The use of r is mainly in function, allowing a parameter to be changed inside the function body.

6.2 Function

6.2.1 Syntax Basics

The initiative of proposing a new programming language for algorithm implementation is based on the multi-backend design of mmCEsim. The language is specially designed so that it can be exported to C++ (with Armadillo), Python (with NumPy) and MATLAB/Octave easily.

Every line of ALG language calls a function. Let's first have a look at its basic structure before we cover its details.

```
1 ret1::type1 ret2 = FUNC param1 param2::type2 key1=value1 key2=value2::type3 # com.
```

It may look like an assembly language at the first glance, due to all parameters are separated by space. But it is actually much more convenient. Here are some basic rules:

- All tokens are separated by space.
- Function names are in all upper cases, like CALC, WHILE.
- Indentation does not matter. Blocks are ended with END.
- The function line is mainly composed of three parts: return values, function name, parameters, in the left to right direction.
- Some functions may not have return values, and you may also omit the return values. If there are return values, there is a = between return values and function names.
- Function name is the first word on the right of = (if there are return values) or the first word of line (if there is no return value).
- Like Python, parameters can be passed in by two ways:
 - 1) value in position: Like param1 and param2 in the above example. Parameters in different positions correspond to different usages in the function. This is the only way in C++.
 - 2) key and value: Parameters can also be specified using key and its corresponding value. value1 and value2 are passed in using this method. It should be noted that there should be no space around the = between key and value.

There are some special cases that parameters are viewed as a whole, for example COMMENT and CALC.

- If a parameter contains space or special characters, you need to use the double quotes like "param with space" and escape special characters as in C++ and Python.
- You may optionally specify the type of return value and parameters with :: after the value. For example, in the above example dtype1, dtype2 and dtype3 are type specifications for ret1, param2 and value2, respectively. For more information about data type, please refer to data type of ALG language.
- Like Python, the backslash (\) at the end of the line can be used for continuing the function on next line.
- Comments start with the hash (#) like Python.
- There should be no space around the = between key and value for parameters. For example, key=val is valid while key = val is forbidden.

Special rules may be applied for different functions. Please refer to the specific documentation for each function.

6.2.2 BRANCH

Declare start of the scope of job algorithms.

Explanations

This is useful in estimation. Contents between BRANCH and MERGE will be repeated for different algorithms. So you need to place compressed sensing estimation ESTIMATE and RECOVER inside.

Example

Example of OFDM OMP.

6.2.3 BREAK

Break from a block (for FOR, FOREVER, LOOP, WHILE).

Explanations

The same as break in C++, Python and MATLAB/Octave. This function takes no parameter.

Example with FOREVER.

6.2.4 CALC

Make arithmetic calculations.

Explanations

There are two kinds of CALC usage: inline and standalone:

- inline: The contents to be calculated are placed in a set of dollar signs, like LATEX syntax: \$some operations \hookrightarrow to be calculated\$.
- Standalone: This is like a normal function, with function name as CALC. You may also omit the function name CALC since it is the default function name if nothing is specified. Therefore, result = CALC your → expression is equivalent to result = your expression.

For more information about the CALC syntax, please refer to §6.3.

For safety, you should not use anything other than ANSI characters in CALC functions. Otherwise, there can be undefined behaviour.

If you want the calculation result to be a new variable, you may use function NEW.

Example

```
EXAMPLE 6.1 (Example of CALC)
1 a = CALC b + 2 # explicit CALC function
2 a = \sin(b) @ c # implicit CALC function
3 a = b^H + c^{-1} \# conjugate transpose and inverse
4 c = b_{2}, 3 # get element of a matrix
5 c = abs\{b_{:, 3}\} + pow(b_{:, 2}) # use : in subscript & use {} for function
6 \exp 2(a + c \cdot * d) ./ e^T - f_{\{:,3,1:index\}} # element-wise operator and
  → subscript : range
 Equivalent C++ Code
1 a = b + 2;
2 a = arma::sin(b) * c;
a = b.t() + c.i();
```

```
4 c = b(2, 3);
5 c = arma::abs(b(arma::span::all, 3)) + arma::pow(b, 2);
6 arma::exp2(a + c % d) / e.st() - f(arma::span::all, 3, arma::span(1, index));
```

6.2.5 CALL

Call a custom function defined by FUNCTION.

6.2.6 COMMENT

Place a line of comment in the exported code.

All contents after the function keyword COMMENT are considered as comments.

Example

```
EXAMPLE 6.2 (Example of COMMENT)
1 COMMENT Hi, this is a comment!
 Equivalent C++ Code
1 // Hi, this is a comment!
 Equivalent Python Code
1 # Hi, this is a comment!
 Equivalent Matlab/Octave Code
1 % Hi, this is a comment!
```

6.2.7 CPP

Write standard C++ contents.

Explanations

All contents after the CPP keywords are copied to exported codes. For backend other than C++, this function is ignored.

Example

```
EXAMPLE 6.3 (Example of CPP)
1 CPP std::cout << "Standard C++ Language!" << std::endl;
 Equivalent C++ Code
1 std::cout << "Standard C++ Language!" << std::endl;
 For Python, Matlab/Octave, nothing will happen with the CPP function.
```

6.2.8 ELIF

ELIF is a shorthand for combining ELSE and IF statements into a continuous sequence.

Explanations

The parameter is the same as IF.

Example

Example with IF.

6.2.9 ELSE

Used in IF blocks.

Explanations

This function implements as else in C++, Python and Matlab/Octave. There is no parameter for the ELSE function.

Example

Example with IF.

6.2.10 END

End of a block for ELSE, ELIF, FUNCTION, FOREVER, IF, LOOP, WHILE.

Explanations

In C++, this functions as }, in Python it is the indentation goes back for one block. In MATLAB/Octave, it is the end specification.

Example

Example with FOR, FOREVER, IF, LOOP, WHILE.

6.2.11 ESTIMATE

CALL standard ALG functions or your custom algorithms to estimate the sparse channel with compressed sensing (CS).

6.2.12 FOR

Start a for loop.

Explanations

The parameters are similar to C++, as listed in Table 6.5.

Table 6.5: ALG FOR function parameters.

Position	Parameter Key	Descriptions
1	init	Initialization before entering the loop.
2	cond	Condition to continue into the loop.
3	oper	Operation after each iteration.

If there is = or other special characters inside your parameter or there exists space, do remember to place them inside double quotes (").

Example

```
EXAMPLE 6.4 (Example of FOR)
1 FOR "i::u0 = INIT 0" "i != 10" "i=i+2" # a for loop taking three parameters
  COMMENT "Do something here in the for loop."
3 END
 Equivalent C++ Code
1 for (uword i = 0; i != 10; i = i + 2) {
     // Do something here in the for loop.
3 }
```

6.2.13 FOREVER

Repeat in the block until BREAK.

Example

```
EXAMPLE 6.5 (Example of FOREVER)
1 FOREVER # takes no param
  BREAK # Wow, nothing is done when I just break here [Lol]
3 END
 Equivalent C++ Code
1 while (1) {
     break;
3 }
```

6.2.14 FUNCTION

Start a function definition.

Explanations

The function requires an END to mark the end of the function.

6.2.15 IF

Conditional statement.

Explanations

This works the same as if in C++, Python, MATLAB/Octave. All contents after the IF keyword are part of the condition. If you insist using the key value style, the key is cond.

Example

```
EXAMPLE 6.6 (Example of IF)
1 IF \accu(\pow(\abs(A), 2)) > 0.1 * threshold
  IF b < 0
2
3
     b = 0
  ELIF b > 100
    b = 100
5
  ELSE
```

```
7
      b = -b
   END
8
9 ELSE
   IF cond="c == d" # use key value style if you insist
10
    A = A * 0.1
11
13 END
  Equivalent C++ Code
1 if (arma::accu(arma::pow(arma::abs(A), 2)) > 0.1 * threshold) {
      if (b < 0) {
3
          b = 0;
      } else if (b > 100) {
4
          b = 100;
5
      } else {
6
          b = -b;
7
8
9 } else {
     if (c == d) {
          A = A * 0.1;
11
12
13 }
```

6.2.16 INIT

Initialize a variable.

Explanations

This function can initialize a **scalar**, a **vector**, a **matrix** and a **tensor**. The initialization target can be specified in two ways:

- return value type specification: You can specify the type of the variable to be initialized by ::;
- parameters: Parameter dtype is used for element type, and dim1, dim2, dim3 are used for dimension specification.

Please be **consistent**! The current implementation of the function is fragile and can be fooled by any inconsistent actions. While we are trying to enhance the error detection, you are advised to use the correct dimension.

However, there are also a few exceptions for user's convenience. Though row vector (r) is regarded as a matrix, you can still specify its dimension with only one parameter on dim1. For a scalar initialization, the value can directly follow =.

The parameters are listed in Table 6.6. For initialization of a row vector (\mathbf{r}) , you may just use one dimension. For initialization of a scalar (dimension as 0), you can specify the value directly after =, but if you want to use fill and scale, you must specify the parameter key.

TIP

Since the development of ALG concentrates on matrix operations, the initialization also performs in a matrix-oriented way. Please refer to data type of ALG language if you are not sure how to use the data type.

Table 6.6: ALG INIT function parameters.

Position	Parameter Key	Descriptions
1	dim1	Size of the first dimension (for vector).
2	dim2	Size of the second dimension (for vector and matrix).
3	dim3	Size of the third dimension (for vector, matrix and tensor).
4	fill	Element filling mode. randn for standard normal distribution $\mathcal{N}(0,1)$, randu for standard uniform distribution $\mathcal{U}(0,1)$, zeros for filling as 0, ones for filling as 1. Default is zeros.
5	scale	Scale of the value. This works like multiplying a value after the initialization by fill.
6	dtype	Element data type. This is the one character prefix like c, i. The default value is complex (c).

Example

```
EXAMPLE 6.7 (Example of INIT)
1 a = INIT 4 3 fill=ones scale=4 dtype=c # a matrix
2 b::r = INIT 10 scale="-1+i" # row vector (viewed as a matrix)
3 pi::f0c = INIT 3.1415926 # a const float
4 random_number = INIT fill=randn scale=-2
 Equivalent C++ Code
1 cx_mat a = (4) * arma::ones<cx_mat>(4, 3);
2 cx_mat b = (-1 + i) * arma::zeros < cx_mat > (1, 10);
3 const double pi = 3.1415926;
4 std::complex <double > random_number = (-2) * arma::randn < std::complex <double
  → >>();
```

6.2.17 LOG

Write to log file.

Example

```
EXAMPLE 6.8 (Example of INIT)
1 LOG [INFO] A user-defined message.
 Log file: mmcesim.log
1 [INFO] $ LOG [INFO] A user-defined message.
2 [INFO] * FUNCTION: LOG
3 [INFO] * PARAMS:
4 [INFO] > {}={[INFO]}::{}
5 [INFO] > {}={A}::{}
6 [INFO] > {}={user-defined}::{}
          > {}={message.}::{}
7 [INFO]
8 [INFO] A user-defined LOG message.
```

6.2.18 LOOP

Loop with iteration counter.

- 6.3 Calculation (CALC)
- 6.4 Macro
- 6.5 ALG Library



TUTORIALS

Step-by-step guide on using mmCEsim.



Millimeter Wave Channel Estimation

7

Millimeter wave channel estimation for multiple-input multiple-output (MIMO) systems techniques are discussed in [2].

A novel channel estimation algorithm *orthogonal matching pursuit list-sparse Bayesian learning* (OMPL-SBL) is proposed in [3], which also reviews the compressed channel estimation scheme for RIS-aided MIMO systems. The structure of angular domain sparsity is also discussed.



CLI Application Tutorials



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VS Code Extension Tutorials 11

11.1 Installation

The extension mmCEsim is published at the VS Code Marketplace, and you can view it at https://marketplace.visualstudio.com/items?itemName=mmcesim.mmcesim.

11.2 Features

Currently, there is syntax highlight support for .sim and .alg, and the YAML schema is also provided for the .sim configuration.





APPENDIX

Additional information about mmCEsim.



Additional Resources A

A.1 Publications

A brief introduction of mmCEsim is given in the poster at the 2022 National Postdoc Seminar in Nanjing, which I attend as the only undergraduate student, and got the Honorable Mention award.

This document is also published online at https://pub.mmcesim.org/mmCEsim-doc.pdf.

A.2 Websites

A.2.1 For Users

If you are the user of mmCEsim and wants to know more, you may find the following websites in Table A.1 useful.

Table A.1: Websites for users.

Website	URL
Homepage	https://mmcesim.org
Web Application	https://app.mmcesim.org
Blog	https://blog.mmcesim.org
Publications	https://pub.mmcesim.org
VS Code Extension	https://marketplace.visualstudio.com/items?itemName=mmcesim.mmcesim

A.2.2 For Developers

If you are a developer and maybe want to contribute to the mmCEsim project, you can find additional websites in Table A.2.

Table A.2: Websites for developers.

Website	URL
GitHub Organization	https://github.com/mmcesim
C++ Dev Documentation	https://dev.mmcesim.org
CLI App Wiki	https://github.com/mmcesim/mmcesim/wiki

A.3 Author

Wuqiong Zhao (Student Member, IEEE) is an undergraduate student pursuing the Bachelor's Degree in communications engineering, working at Lab of Efficient Architectures for Digital-communication and Signal-processing (LEADS) and National Mobile Communications Research Laboratory, Southeast University. He is the honors student of Chien-Shiung Wu College and earned the National Scholarship and Cyrus Tang Scholarship in 2021. From 2020 to 2021, he also served as the Special Student Assistant to President of Southeast University. He was also nominated as the most influential undergraduate student of Southeast University in 2022. His research interest includes channel estimation, Bayesian algorithms, and the intelligent reflecting surface (IRS) in wireless communication of 5G and 6G. He is also the reviewer of IEEE TCAS II and ISCAS 2023.

Change History B

B.1 HEAD
New Features
• ALG library enhancement (#49, PR#51):
 Add OMPL [3] algorithm to the library.
- ALG dependency check.
 Enhanced log and TeX report (PR #55).
 Update Doxygen website configurations (including more graphs).
Bug Fixes
 Rename configuration file to mmcesim.cfg (#50, PR #53).
• Fix C++ (Armadillo) runtime error when simulating with -02 or -03 on macOS by patching arma::randperm (#52, PR #54).
B.2 v0.2.1
New Features
• Colorful terminal (#22).
mmcesim-maintain tool support (#25).
 Log system support with cleaner terminal output (#32, PR #36).
mmcesim-log tool support (#37, PR#39, PR#47).
• Support NO_COLOR standard (#42, PR #48).
• Syntax highlight for ALG language on mmcesim.org with a custom lexer (mmcesim.org#1).
Bug Fixes
• Fix the Docker entrypoint command.
• Fix total lines badge display in README (#40, PR #41).

• Fix Ubuntu 20 release error (#46).

• Short domain mmces.im has been registered alongside mmcesim.org (#43).

News

New Features Active beam pattern design support (#18). • Report generation of RIS-assisted systems (#3). **Bug Fixes** • Fix inconsistency of LATEX report destination directory. News • The research paper entitled 'OMPL-SBL Algorithm for Intelligent Reflecting Surface-Aided mmWave Channel Estimation' has been accepted by IEEE Transactions on Vehicular Technology (Jan. 14, 2023). **New Features** Multi RIS assisted systems support (#3); • RIS pattern design support (#17). **Bug Fixes** • Fix cmake install configurations. News Automated release process with a better CI workflow (#20). v0.1.0 **New Features** Basic mmWave MIMO systems channel estimation support; Design of ALG language; Export of code with Armadillo library; • Auto simulation (#5). B.6 v0.0.1 2022/07/27 Though the app has not been fully developed, the task-oriented concept has already been established.

B.3 v0.2.0

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- [3] W. Zhao, Y. You, L. Zhang, et al., "OMPL-SBL algorithm for intelligent reflecting surface-aided mmWave channel estimation", *IEEE Trans. Veh. Technol.*, 2023, to be published.



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