Thesis notes

1st June

The Echo Chamber Problem

Goal: given an interaction graph G, find $U \subseteq V$ maximing

$$\xi(U) = \sum_{C \in \hat{C}} \sum_{T[U] \in S_C(U)} (|T^+[U]| - |T^-[U]|) \tag{1}$$

where $|T^{-}[U]|$ and $|T^{+}[U]|$ denotes the number of negative and positive edges induced in the subgraph, respectively.

The set of users maximing the expression is denoted as \hat{U} and the corresponding score is $\xi(G)$

The rounding algorithm

Algorithm 1: Rounding algorithm

```
\hat{G} \leftarrow \mathsf{empty} \; \mathsf{graph} \; ;
 \hat{V} \leftarrow \text{vertices of } \hat{G}:
S=0
\begin{array}{ll} \text{foreach} & e^k_{ij} \in \tilde{E} \text{ do} \\ & | & \hat{V} \leftarrow \hat{V} \bigcup \{v_i\} \text{ if } v_i \not \in \hat{V} \text{ ;} \end{array}
         \hat{V} \leftarrow \hat{V} \cup \{v_i\} \text{ if } v_i \notin \hat{V} ;
         S \leftarrow \xi(\hat{V});
         foreach component C in \hat{G} do
            S \leftarrow \xi(C);
         end
end
return highest S;
```

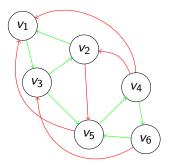


Figure: The original graph

If many edges get the same value in the result of the relaxation, they are selected randomly

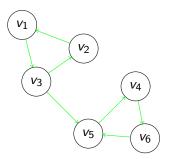


Figure: Only positive edges are reported, getting all value 0.666

When the edge e_{35} is added then the 2 communities cannot be reconstructed.

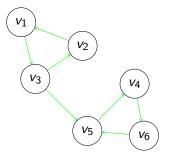
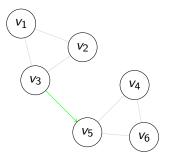


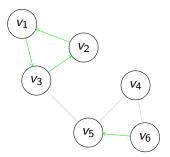
Figure: Only positive edges are reported, getting all value 0.666

Let us suppose it is added in the first iteration. Then we have a situation as follows



We won't be able to find a whole community during the remaining iterations and the result may even be $U = \{v_3, v_5\}$.

A "luckier" iteration would be the following



Effects on the results

Since the addition of positive cross-community edges degradates the result, we can generally improve the chances of finding better fits on the community

- ▶ Reducing the number of positive cross-community edges
- increasing the number of positive edges inside a community
- icreasing the number of threads in order to be less sensitive to single edges

A model for the Echo Chamber Problem

Each node has a group assignment and there are probabilities of positive and negative edges ω_{rs}^+ and ω_{rs}^+ , respectively.

- 1. Generate the *follow* graph G by using a SBM with parameters $\{\phi_{rs}\}$.
- 2. Each node can be active with probability β_a
- 3. Any active node activates his inactive neighbours in G with probability β_n
- 4. active nodes interact according to the categorical $(\omega_{rs}^+,\omega_{rs}^-,1-\omega_{rs}^+-\omega_{rs}^-)$ otherwise (at least one of the 2 nodes is inactive) with categorical $(\theta\omega_{rs}^+,\theta\omega_{rs}^-,1-\theta(\omega_{rs}^++\omega_{rs}^-))$, $\theta\leq 1$

A parametrized model (1)

Parameter choice:

$$\phi_{rs} = \begin{cases} 1 & \text{if } r = s \\ 0 & \text{otherwise} \end{cases} \tag{2}$$

Users follow other all and only users in the same community.

 $\beta_a = 1$, $\beta_n = 1$: all users interact on each post.

$$\omega_{rs}^{+} = \begin{cases} 1 - x & \text{if } r = s \\ \frac{x}{4} & \text{otherwise} \end{cases} \quad \omega_{rs}^{-} = \begin{cases} x & \text{if } r = s \\ \frac{1 - x}{4} & \text{otherwise} \end{cases}$$
(3)

This means that the probability of having an edge between two nodes in different communities is 1/4.

Clustering results

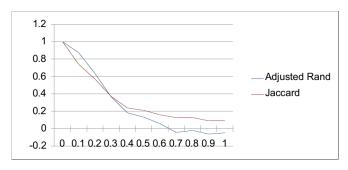


Figure: Approximation algorithm scores

Results obtained with 8 nodes per community and 12 threads.

More observations

The results clearly depends on factors like:

- the number of threads (the higher the number of threads the more the algorithm is robust to noise),
- ▶ the number of nodes (the higher the number of nodes the more the algorithm is robust to noise).