GPU Programmierung mit CUDA

Matthias Endler





Apple II, 1977



Videx Videoterm, 1981

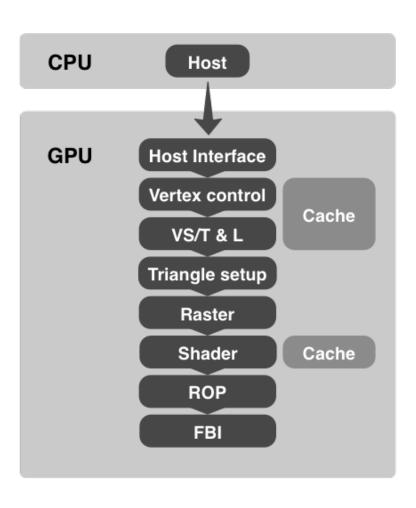


Videx Videoterm, 1981

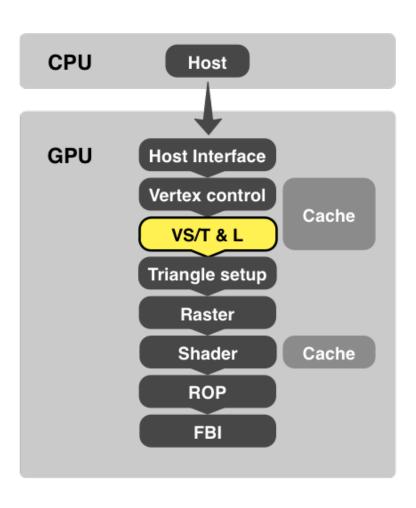


VisionTek Geforce 256, 1999

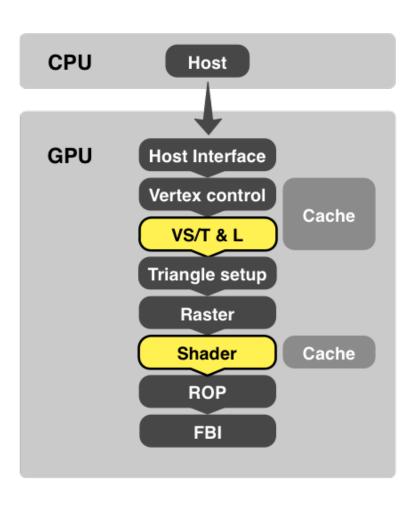
Fixed-function pipeline



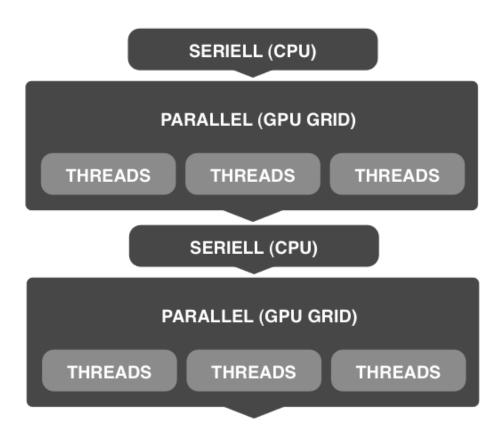
Fixed-function pipeline



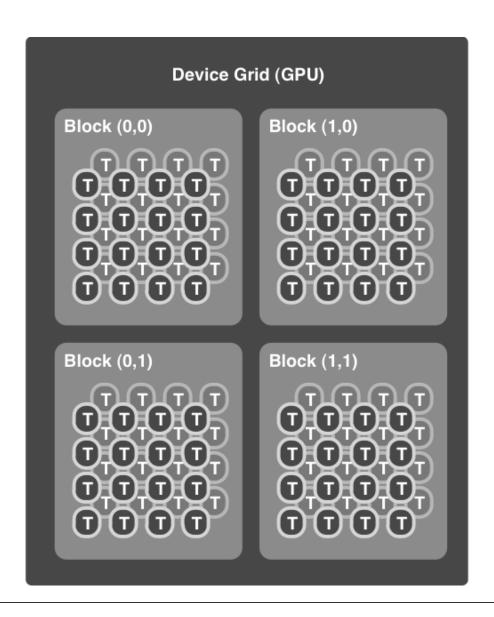
Fixed-function pipeline



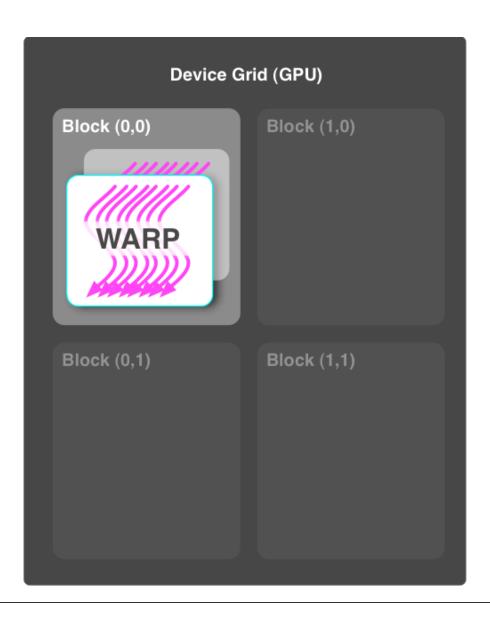
Ein CUDA Programm



CUDA Device Architektur



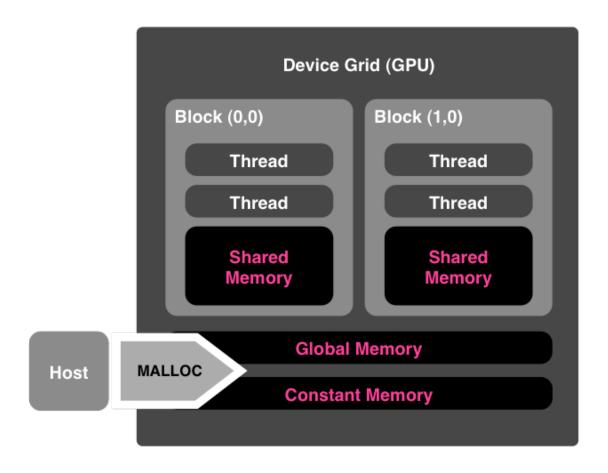
CUDA Device Architektur



CUDA Spracherweiterungen

Signatur	Aufruf durch	Ausführung auf	Anmerkungen
host	Host (CPU)	Host (CPU)	Standard
global	Host (CPU)	Device (GPU)	
device	Device (GPU)	Device (GPU)	

CUDA Memory Model



CUDA Memory Model (2) Speicherallokierung

Signatur	Speicherort	Sichtbarkeit
device	Global Memory	Programmlaufzeit
constant	Constant Memory	Programmlaufzeit
shared	Shared Memory	Laufzeit des Blocks

Beispiel: Matrixprodukt

$$\underbrace{\begin{pmatrix} m_{11} & \cdots & m_{1n} \\ \vdots & \ddots & \vdots \\ m_{n1} & \cdots & m_{nn} \end{pmatrix}}_{M} \cdot \underbrace{\begin{pmatrix} n_{11} & \cdots & n_{1n} \\ \vdots & \ddots & \vdots \\ n_{n1} & \cdots & n_{nn} \end{pmatrix}}_{N} = \underbrace{\begin{pmatrix} p_{11} & \cdots & p_{1n} \\ \vdots & \ddots & \vdots \\ p_{n1} & \cdots & p_{nn} \end{pmatrix}}_{P}$$

Beispiel: Matrixprodukt

$$\underbrace{\begin{pmatrix} m_{11} & \cdots & m_{1n} \\ \vdots & \ddots & \vdots \\ m_{n1} & \cdots & m_{nn} \end{pmatrix}}_{M} \cdot \underbrace{\begin{pmatrix} n_{11} & \cdots & n_{1n} \\ \vdots & \ddots & \vdots \\ n_{n1} & \cdots & n_{nn} \end{pmatrix}}_{N} = \underbrace{\begin{pmatrix} p_{11} & \cdots & p_{1n} \\ \vdots & \ddots & \vdots \\ p_{n1} & \cdots & p_{nn} \end{pmatrix}}_{P}$$

Implementierung auf CPU

```
void mult_matrix(float *M, float *N, float *P)
{
  int i, j, k;
  for (i = 0; i < DIM; ++i) {
    for (j = 0; j < DIM; ++j) {
      float sum = 0;
      for (k = 0; k < DIM; ++k) {
        float a = M[i*DIM + k];
        float b = N[k*DIM + j];
        sum += a * b;
    }
    P[i*DIM + j] = sum;
    }
}</pre>
```

```
void mult_matrix(float *M, float *N, float *P)
{

   /*
    * TODO:
    * - Allocate device memory
    * - Copy matrices to device
    * - Perform calculation
    * - Copy result and free matrices
    */
```

```
void mult_matrix(float *M, float *N, float *P)
{
    /* Allocate device memory */
    float *Md, *Nd, *Pd;
    size_t size = DIM*DIM * sizeof(float);
    cudaMalloc((void**) &Md, size);
    cudaMalloc((void**) &Nd, size);
    cudaMalloc((void**) &Pd, size);

    /* Copy matrices to device */
    /* Perform calculation */
    /* Copy result from device to host and free matrices */
}
```

```
void mult matrix(float *M, float *N, float *P)
  /* Allocate device memory... */
  /* Copy matrices to device */
  cudaMemcpy (Md, M, size, cudaMemcpyHostToDevice);
  cudaMemcpy(Nd, N, size, cudaMemcpyHostToDevice);
  /* Perform calculation */
  /* Copy result from device to host and free matrices */
```

```
void mult matrix(float *M, float *N, float *P)
  /* Allocate device memory... */
  /* Copy matrices to device... */
  /* Perform calculation */
  dim3 dimBlock(DIM, DIM);
  dim3 dimGrid(1,1);
  device mult matrix << < dim Grid, dim Block >>> (Md, Nd, Pd);
  /* Copy result from device to host and free matrices */
```

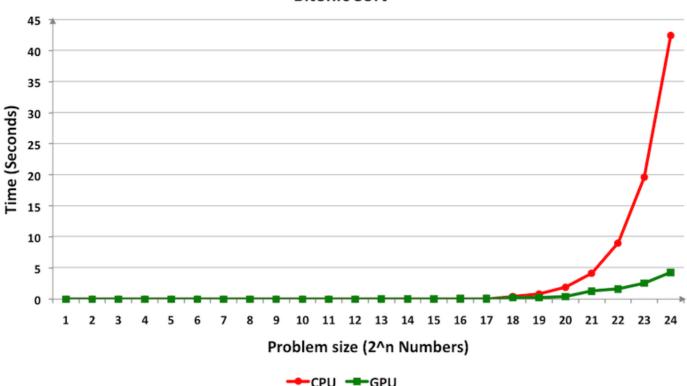
```
global void device mult matrix(
float *Md, float *Nd, float *Pd)
/* Thread ID */
int tx = threadIdx.x;
int ty = threadIdx.y;
/* Compute one value per thread */
float v = 0;
int k;
for (k = 0; k < DIM; ++k) {
  float Md value = Md[ty * DIM + k];
  float Nd value = Nd[k * DIM + tx];
  v += Md value * Nd value;
/* Write to result matrix on device */
Pd[ty * DIM + tx] = v;
```

```
void mult matrix(float *M, float *N, float *P)
  /* Allocate device memory... */
  /* Copy matrices to device... */
  /* Perform calculation... */
  /* Copy result from device to host */
  cudaMemcpy(P, Pd, size, cudaMemcpyDeviceToHost);
  /*free matrices */
  cudaFree (Md);
  cudaFree(Nd);
  cudaFree(Pd);
```

CUDA Spracherweiterungen (2) syncthreads();

Benchmark Bitonic Sort





←CPU **←**GPU