I wanted to try out making a programming language vaguely corresponding to the double category **Rel**.

You have a calculus of "values" corresponding to one edge of **Rel** and a sort of relational calculus of "predicates" corresponding to the other edge. Satisfies judgements stating a value satisfies a predicate ought to correspond to squares.

The language of "predicates" is based off the Simply Typed Lambda Calculus (in category theory terms is closed/has exponential objects) and the language of "values" has product types (in category theory terms is Cartesian.)

This is the core framework. I've been thinking about further extensions but I want to see how far I can get characterizing **Rel** with as few language features as possible. Later on I give a few possible extensions.

## **Core Calculus**

Types  $t := \top \mid t \times t$ 

**Sorts** s := t? | t!

**Values**  $v := x \mid \mathbf{tt} \mid \mathbf{fst}(v) \mid \mathbf{snd}(v) \mid (v, v)$ 

**Predicates**  $p := x \mid p p \mid \mu(x:t?).p$ 

**Environment**  $\Gamma ::= \cdot \Gamma, \mid x : s$ 

**Substitutions**  $\sigma := \cdot \mid \sigma, v \models x$ 

I need a better name for the abstraction for predicates. It's a little like the  $\mu$  abstraction from the  $\bar{\lambda}\mu\tilde{\mu}$  calculus but different.

Typing judgments.

$$\begin{array}{l} \overline{\Gamma \vdash \mathbf{tt} \colon \top !} \\ \overline{\Gamma \vdash v \colon t_0 \times t_1 !} \\ \overline{\Gamma \vdash v \colon t_0 \times t_1 !} \\ \overline{\Gamma \vdash \mathbf{fst}(v) \colon t_0 !} \\ \overline{\Gamma \vdash v \colon t_0 \times t_1 !} \\ \overline{\Gamma \vdash \mathbf{snd}(v) \colon t_1 !} \\ \overline{\Gamma \vdash v_0 \colon t_0 !} \quad \overline{\Gamma \vdash v_1 \colon t_1 !} \\ \overline{\Gamma \vdash (v_0, v_1) \colon t_0 \times t_1 !} \\ \overline{\Gamma \vdash p_0 \colon t_0 \times t_1 ?} \quad \overline{\Gamma \vdash p_1 \colon t_0 ?} \\ \overline{\Gamma \vdash p_0 p_1 \colon t_1 ?} \\ \overline{\Gamma \vdash \mu x \colon t_0 ? \vdash p \colon t_1 ?} \\ \overline{\Gamma \vdash \mu x \colon t_0 ? p \colon t_0 \times t_1 ?} \end{array}$$

When a value satisfies a predicate (I need a better symbol here.)

$$\begin{aligned} &\frac{v_0 \models p \quad [\sigma]}{\mathbf{fst}(v_0, v_1) \models p \quad [\sigma]} \\ &\frac{v_1 \models p \quad [\sigma]}{\mathbf{snd}(v_0, v_1) \models p \quad [\sigma]} \\ &\frac{v \models [x \colon = p_1]p_0 \quad [\sigma]}{v \models (\mu(x \colon t?).p_0) p_1 \quad [\sigma]} \\ &\frac{v_1 \models p \quad [\sigma, v_0 \models x]}{(v_0, v_1) \models \mu(x \colon t?).p \quad [\sigma]} \end{aligned}$$

## 1 Examples

Pattern matching on equality

$$(v,v) \models \mu(x:t?).x$$

Transposition

$$\mu(p: t \times t \times \top)(x: t)(y: t).pyx$$

## **Disjoint Unions**

I am fairly confident in a simple extension to disjoint unions of sets which are sum types in the value calculus and product types in the predicate calculus.

Types 
$$t := \ldots \mid \bot \mid t + t$$

Typing judgments.

Values 
$$v := \ldots \mid \langle x : = t, v \rangle$$

 $\frac{\Gamma \vdash t_0 \colon * \quad \Gamma, \ x \colon * \vdash v \colon t_1!}{\Gamma \vdash \langle x \colon = t_0, v \rangle \colon \Sigma(x \colon *).t_0!}$ 

 $\frac{\Gamma \vdash p \colon \Sigma(x \colon *).t_1? \quad \Gamma \vdash t_0 \colon *}{\Gamma \vdash p_0 t_0 \colon [x \colon = t_0]t_1?}$ 

 $\frac{\Gamma, x \colon * \vdash p \colon t?}{\Gamma \vdash \mathbf{M}(x \colon *).p \colon \Sigma(x \colon *).t?}$ 

**Predicates** 
$$p := ... | pt | \mathbf{M}(x : *).p$$

**Substitutions** 
$$\sigma ::= \ldots \mid \sigma, t \models x$$

 $\overline{\Gamma \vdash \mathbf{inr}(t_0, v) \colon t_0 + t_1!}$ Not really good at the typing judgements for de- $\frac{\Gamma \vdash v_0 \colon t_0 + t_1 ! \ \Gamma, \ x_0 \colon t_0 ! \vdash v_1 \colon t_2 ! \ \Gamma, \ x_1 \colon t_1 ! \vdash v_2 \colon t_2 !}{\Gamma \vdash \mathbf{match} \ v_0} \underbrace{\begin{cases} v_1 & \leftarrow \mathbf{inl}(x_0) \\ v_2 & \leftarrow \mathbf{inr}(x_1) \end{cases}}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ t_2 !}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *} \underbrace{\vdots \ T \vdash t_0 \colon *}_{\Gamma \vdash t_0 \colon *}$ 

$$\Gamma \vdash \mathbf{match} \ v_0 \begin{cases} v_1 & \leftarrow \mathbf{inl}(x_0) \\ v_2 & \leftarrow \mathbf{inr}(x_1) \end{cases} : t_2!$$

$$\begin{array}{l} \overline{\Gamma \vdash \mathbf{false} \colon \bot?} \\ \underline{\Gamma \vdash p \colon t_0 + t_1?} \\ \overline{\Gamma \vdash \mathbf{left}(p) \colon t_0?} \\ \underline{\Gamma \vdash p \colon t_0 + t_1?} \\ \overline{\Gamma \vdash \mathbf{right}(p) \colon t_1?} \\ \underline{\Gamma \vdash p_0 \colon t_0? \quad \Gamma \vdash p_1 \colon t_1?} \\ \underline{\Gamma \vdash [p_0; p_1] \colon t_0 + t_1?} \end{array}$$

 $\Gamma \vdash v \colon t_0!$ 

 $\Gamma \vdash \mathbf{inl}(t_1, v) \colon t_0 + t_1!$ 

I can't figure out satisfaction at all.

Satisfies

$$\frac{[x_0 := v_0]v_1 \models p \quad [\sigma]}{\mathbf{match\ inl}(t, v_0) \begin{cases} v_1 & \leftarrow \mathbf{inl}(x_0) \\ v_2 & \leftarrow \mathbf{inr}(x_1) \end{cases} \models p \ [\sigma]}{[x_1 := v_0]v_2 \models p \quad [\sigma]}$$
$$\mathbf{match\ inr}(t, v_0) \begin{cases} v_1 & \leftarrow \mathbf{inl}(x_0) \\ v_2 & \leftarrow \mathbf{inr}(x_1) \end{cases} \models p \ [\sigma]$$

$$\begin{aligned} & \mathbf{match\ inr}(t,v_0) \ \ \begin{cases} v_1 & \leftarrow \mathbf{inr}(x) \\ v_2 & \leftarrow \mathbf{inr}(x) \end{cases} \\ & \frac{v \models p_0 \ [\sigma]}{v \models \mathbf{left}([p_0;p_1]) \ \ [\sigma]} \\ & \frac{v \models p_1 \ [\sigma]}{v \models \mathbf{right}([p_0;p_1]) \ \ [\sigma]} \\ & \frac{v \models p_0 \ [\sigma]}{\mathbf{inl}(t,v) \models [p_0;p_1] \ \ [\sigma]} \\ & v \models p_1 \ [\sigma] \end{aligned}$$

$$v \models (\mathbf{M}(x: *).p) t \quad [\sigma]$$

$$v \models p \ [\sigma, t \models x]$$

$$\langle x := t, v \rangle \models \mathbf{M}(x: *).p \quad [\sigma]$$

## **Dependent Sums**

 $\overline{\mathbf{inr}(t,v) \models [p_0; p_1] \quad [\sigma]}$ 

If product of sets becomes an exponential in the predicate calculus then dependent sums ought to become like  $\Pi$  types. So the predicate calculus effectively becomes like System-F.

Some things become awkward to interpret here

I also really can't figure out unpacking. messy if you don't want full dependent types.

Types 
$$t ::= \ldots \mid x \mid \Sigma(x \colon *).t$$

**Sorts** 
$$s := ... | *$$