

Frontmesh

Reference Manual

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Chapter 1

Class Index

1.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

Collection< Item >	5
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Chapter 2

File Index

2.1 File List

Here is a list of all documented files with brief descriptions:

frontmesh.cc	Implementation of the propagating front routines	11
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Chapter 3

Class Documentation

3.1 Collection< Item > Class Template Reference

```
#include <frontmesh.h>
```

Public Member Functions

- int **number** ()
- void **add** (Item *item)
- void **push** (Item *item)
- void **insert** (Item *item)
- void **append** (Item *item)
- void **remove** ()
- void **erase** ()
- void **remove** (Item *item)
- void **erase** (Item *item)
- void **goFirst** ()
- void **goLast** ()
- void **goNext** ()
- void **goPrev** ()
- bool **isFirst** ()
- bool **isLast** ()
- void **goTag** ()
- void **setTag** ()
- void **untag** ()
- bool **isTagged** ()
- void **removeTagged** ()
- void **tagFirst** ()
- void **tagNext** ()
- void **tagPrev** ()
- bool **tagIsFirst** ()
- bool **tagIsCurrent** ()
- Item * **getItem** ()
- void **replaceltem** (Item *newitem)
- Item * **getTaggedItem** ()
- void **clean** ()
- void **wipe** ()
- void **show** (string name)

3.1.1 Detailed Description

```
template<class Item>
class Collection< Item >
```

[Collection](#) class implements linked list operations on other data strutures.

The documentation for this class was generated from the following file:

- [frontmesh.h](#)

3.2 Node Struct Reference

```
#include <frontmesh.h>
```

Public Member Functions

- **Node** ([Point](#) *Q)
- **Node** ([Point](#) *Q, [Segment](#) *A, [Segment](#) *B)
- REAL **coordinate** (int i)
- REAL * **coordinates** ()
- REAL **distance** (REAL y[])
- REAL **distance** ([Node](#) *node)
- REAL **distance** ([Node](#) *node, REAL dist[])
- void **addSegs** ([Segment](#) *A, [Segment](#) *B)
- void **add** ([Segment](#) *seg)
- int **numNeibs** ()
- void **replace** ([Segment](#) *oldseg, [Segment](#) *newseg)
- bool **isNeib** ([Node](#) *node)
- void **show** (string name)
- void **setSegs** ([Segment](#) *s0, [Segment](#) *s1)
- [Collection](#)< [Segment](#) > * **getSegs** ()
- [Segment](#) * **getSeg** ([Node](#) *node)
- [Segment](#) * **getOtherSeg** ([Segment](#) *seg)
- void **remove** ([Segment](#) *seg)

Public Attributes

- int **index**
- [Collection](#)< [Segment](#) > **segs**
- [Point](#) * **P** = NULL

3.2.1 Detailed Description

[Node](#) contains a point and a list of segments which are connected to it

The documentation for this struct was generated from the following file:

- [frontmesh.h](#)

3.3 Point Struct Reference

```
#include <frontmesh.h>
```

Public Member Functions

- **Point** ([Vector](#) &newX, [Vector](#) &newF)
- **Point** (int ind, REAL *newX, REAL *newF)
- void **set** ([Vector](#) &newX, [Vector](#) &newF)
- void **setRange** (REAL r)
- REAL **bond** ([Point](#) *Q)
- void **show** (string name)

Public Attributes

- REAL **range** = 0.0
- int **i** = 0
- [Vector](#) **X**
- [Vector](#) **F**

3.3.1 Detailed Description

[Point](#) data strucure combines position vector with the surface normal vector.

The documentation for this struct was generated from the following file:

- [frontmesh.h](#)

3.4 Segment Class Reference

```
#include <frontmesh.h>
```

Public Member Functions

- **Segment** ([Node](#) *n0, [Node](#) *n1, [Node](#) *n2)
- void **setTriangle** ([Triangle](#) *tri, int vert)
- [Triangle](#) * **getTriangle** ()
- void **setEndNodes** ([Node](#) *n0, [Node](#) *n1)
- [Vector](#) * **getNorm** ()
- void **setNode** (int i, [Node](#) *n)
- [Node](#) * **getNode** (int i)
- [Node](#) ** **getNodes** ()
- [Node](#) * **getOtherNode** ([Node](#) *n)
- [Node](#) * **getApex** ()
- void **setApex** ([Node](#) *nd)
- REAL **length** ()
- void **show** (string name)
- void **setNorm** ()
- [Point](#) * **getVertex** ()

3.4.1 Detailed Description

[Segment](#) consists of two nodes and a vector in the direction perpendicular to the line connecting the nodes. The direction points inside the already generated mesh and is used to avoid points already in the mesh when selecting a new point for a surface triangle.

The documentation for this class was generated from the following file:

- [frontmesh.h](#)

3.5 Triangle Class Reference

```
#include <frontmesh.h>
```

Public Member Functions

- **Triangle** ([Point](#) *A, [Point](#) *B, [Point](#) *C)
- void **setVert** (int i, [Point](#) *P)
- [Point](#) * **getVert** (int i)
- bool **replaceVert** ([Point](#) *P, [Point](#) *Q)
- bool **has** ([Point](#) *point)
- REAL **perimeter** ()
- REAL **area** ()
- void **show** (string name)

3.5.1 Detailed Description

[Triangle](#) holds pointers to three points which form its vertices

The documentation for this class was generated from the following file:

- [frontmesh.h](#)

3.6 Vector Class Reference

```
#include <frontmesh.h>
```

Public Member Functions

- **Vector** (REAL x, REAL y, REAL z)
- **Vector** (REAL X[])
- **Vector** ([Vector](#) *X)
- **Vector** ([Vector](#) &X)
- REAL * **vec** ()
- void **set** (int i, REAL x)
- void **set** (REAL *X)
- REAL **get** (int i)
- void **set** ([Vector](#) *X)
- void **set** ([Vector](#) &X)
- void **add** ([Vector](#) &X)
- void **add** ([Vector](#) *X)
- void **sub** ([Vector](#) *X)
- void **sub** ([Vector](#) &X)
- void **sub** ([Vector](#) &X, [Vector](#) &Y)
- void **sub** ([Vector](#) &X, [Vector](#) *Y)
- void **sub** ([Vector](#) *X, [Vector](#) *Y)
- void **mid** ([Vector](#) &A, [Vector](#) &B)
- void **mid** ([Vector](#) *A, [Vector](#) *B)
- void **mul** (REAL c)
- void **rot** (REAL angle, [Vector](#) &axis)
- REAL **len** ()
- void **one** ()
- void **cross** ([Vector](#) *A, [Vector](#) *B)
- void **show** (string name)

3.6.1 Detailed Description

[Vector](#) class. Implements vector operations.

The documentation for this class was generated from the following file:

- [frontmesh.h](#)

Chapter 4

File Documentation

4.1 frontmesh.cc File Reference

Implementation of the propagating front routines.

```
#include <cstdlib>
#include <unistd.h>
#include <string.h>
#include <math.h>
#include <iostream>
#include <fstream>
#include "frontmesh.h"
```

Functions

- void **doc** ()
- void **usage** (char *prog)
- int **main** (int argc, char *argv[])
- bool **isIntersecting** (Point *A, Point *B, Segment *seg0, Segment *seg, Node *node, int level)
- REAL **maxBond** (Point *P, Collection< Point > &points, Segment *seg, Point *&Q)
- REAL **maxBond** (Point *P, Collection< Node > &nodes, Segment *seg, Point *&Q)
- void **moveNode** (Node *node, Collection< Node > &setA, Collection< Node > &setB)
- int **frontmesh** (int nPoints, REAL *Coords, REAL *Snorms, int *Indices, int *&Faces)

Variables

- bool **verbose** = false
- bool **silent** = false

4.1.1 Detailed Description

Implementation of the propagating front routines.

Author: Andrei Smirnov andrei.v.smirnov@gmail.com

4.1.2 Function Documentation

4.1.2.1 frontmesh()

```
int frontmesh (
    int nPoints,
    REAL * Coords,
    REAL * Snorms,
    int * Indices,
    int *& Faces )
```

Generates Mesh Using Propagating Front Method.

4.1.2.2 isIntersecting()

```
bool isIntersecting (
    Point * A,
    Point * B,
    Segment * seg0,
    Segment * seg,
    Node * node,
    int level )
```

Checks if a segment connecting points A and B intersects other segments in the front.

4.1.2.3 main()

```
int main (
    int argc,
    char * argv[ ] )
```

Main routine performing IO and calling the mesher.

4.1.2.4 maxBond() [1/2]

```
REAL maxBond (
    Point * P,
    Collection< Point > & points,
    Segment * seg,
    Point *& Q )
```

Finds point with maximum bonding to a given point

4.1.2.5 maxBond() [2/2]

```
REAL maxBond (
    Point * P,
    Collection< Node > & nodes,
    Segment * seg,
    Point *& Q )
```

Finds a front node with maximum bonding to a given point.

4.1.2.6 moveNode()

```
void moveNode (
    Node * node,
    Collection< Node > & setA,
    Collection< Node > & setB )
```

Moves node from one collection to another.

4.2 frontmesh.h File Reference

Header file with definitions of basic data structures.

Classes

- class [Vector](#)
- struct [Point](#)
- class [Collection< Item >](#)
- class [Segment](#)
- struct [Node](#)
- class [Triangle](#)

Macros

- `#define INT int`
- `#define REAL double`
- `#define BIG 1.e30`
- `#define SMALL 1.e-30`
- `#define DIM 3`
- `#define NV 3`
- `#define MIN_ASPECT_RATIO 0.005`
- `#define ZIP_PROXIMITY 0.2`
- `#define RANGE 2.5`

Functions

- REAL **dist** ([Vector](#) &A, [Vector](#) &B)
- REAL **dist** ([Vector](#) *A, [Vector](#) *B)
- REAL **dot** ([Vector](#) &A, [Vector](#) &B)
- REAL **dot** ([Vector](#) &A, [Vector](#) *B)
- REAL **dot** ([Vector](#) *A, [Vector](#) *B)
- void **add** ([Vector](#) &A, [Vector](#) &B, [Vector](#) &C)
- void **mid** ([Vector](#) &A, [Vector](#) &B, [Vector](#) &C)
- void **sub** ([Vector](#) &A, [Vector](#) &B, [Vector](#) &C)
- void **mul** (REAL c, [Vector](#) &A)
- void **cross** ([Vector](#) &A, [Vector](#) &B, [Vector](#) &C)
- bool **clockwise** ([Vector](#) *A, [Vector](#) *B, [Vector](#) *C, [Vector](#) *D)
- bool **intersecting** ([Vector](#) *A, [Vector](#) *B, [Vector](#) *C, [Vector](#) *D, [Vector](#) *E)
- REAL **perimeter** ([Point](#) *A, [Point](#) *B, [Point](#) *C)
- REAL **area** ([Point](#) *A, [Point](#) *B, [Point](#) *C)

Variables

- bool **silent**
- bool **verbose**

4.2.1 Detailed Description

Header file with definitions of basic data structures.

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