

1 point

1. Which of the following accurately describes the state-action value function $Q(s, a)$?
- ☒ It is the return if you start from state s , take action a (once), then behave optimally after that.
 - ☐ It is the return if you start from state s and repeatedly take action a .
 - ☐ It is the return if you start from state s and behave optimally.
 - ☐ It is the immediate reward if you start from state s and take action a (once).

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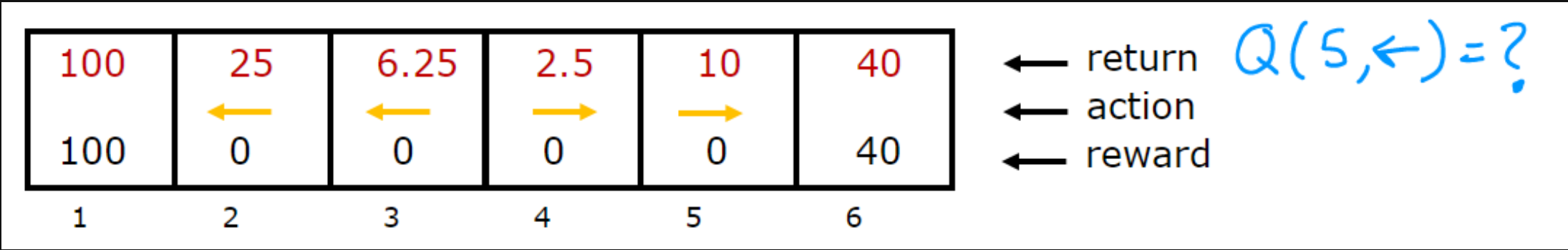
2. You are controlling a robot that has 3 actions: \leftarrow (left), \rightarrow (right) and STOP. From a given state s , you have computed $Q(s, \leftarrow) = -10$, $Q(s, \rightarrow) = -20$, $Q(s, \text{STOP}) = 0$.

What is the optimal action to take in state s ?

- ☒ STOP
- ☐ \leftarrow (left)
- ☐ \rightarrow (right)
- ☐ Impossible to tell

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3. For this problem, $\gamma = 0.25$. The diagram below shows the return and the optimal action from each state. Please compute $Q(5, \leftarrow)$.



- ☒ 0.625
- ☐ 0.391
- ☐ 1.25
- ☐ 2.5