

Pedestrian tracking

VUT FIT POVa

Task Inspiration

- Marauder's Map from Harry Potter
 - Magic parchment that reveals the current location of anyone on Hogwarts grounds



http://harrypotter.wikia.com/wiki/Marauder%27s Map

Task definition

- 1. Multiple people walking in a scene
- 2. Multiple stationary cameras
 - ✓ Initial calibration
- 3. Individual path tracking

Front camera

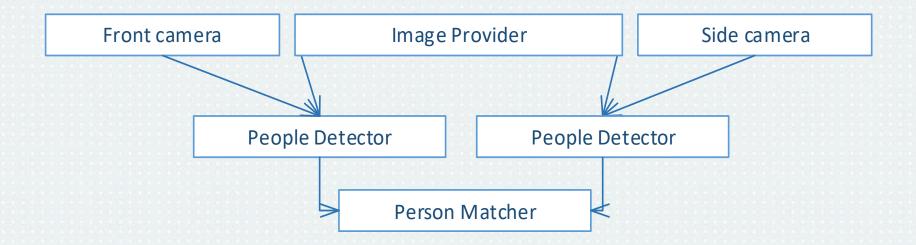
Side camera

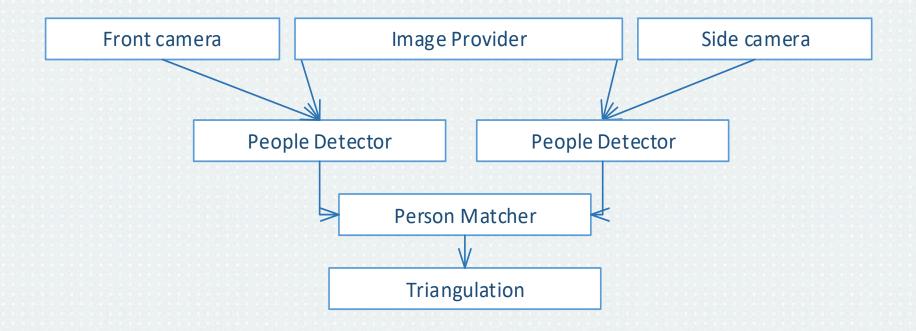
Front camera

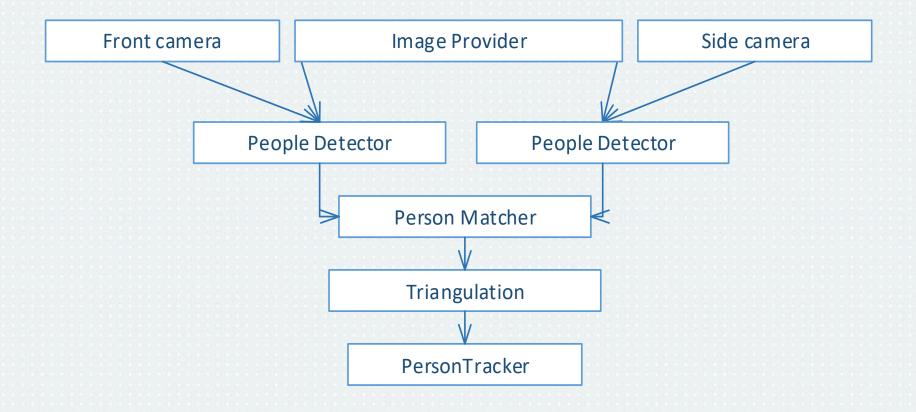
Image Provider

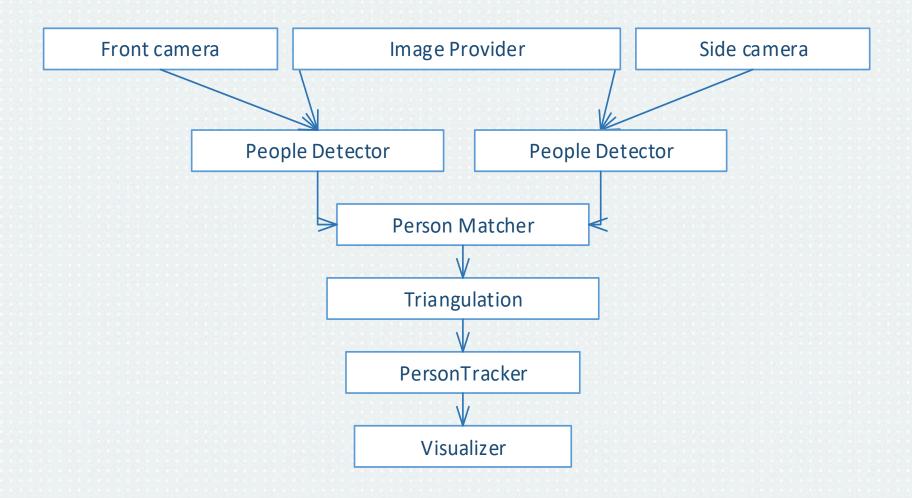
Side camera





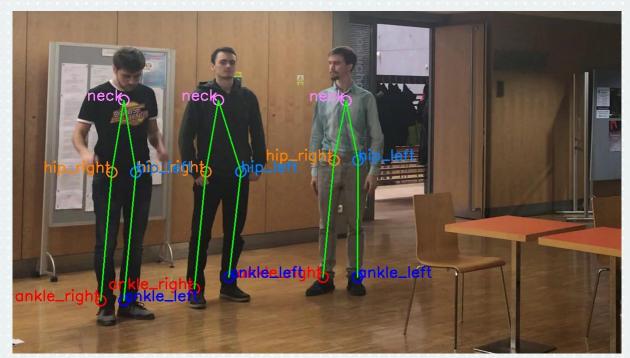






Human Detection in 2D

- OpenPose deep neural network
- Pretrained model with COCO dataset



Multi-person key point detection

Person View Matching

Similar torso histograms → same person



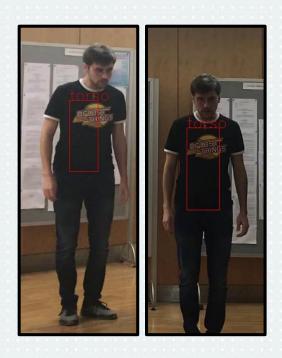
Side person views



Front person views

Person View Matching

Similar torso histograms → same person



PersonTimeFrame A



PersonTimeFrame B



PersonTimeFrame C

Triangulation

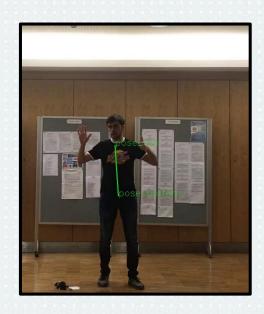
Average person's torso → distance from camera







$$y = 3 \text{ m}$$



$$y = 6 \text{ m}$$

Triangulation

Average person's torso → distance from camera







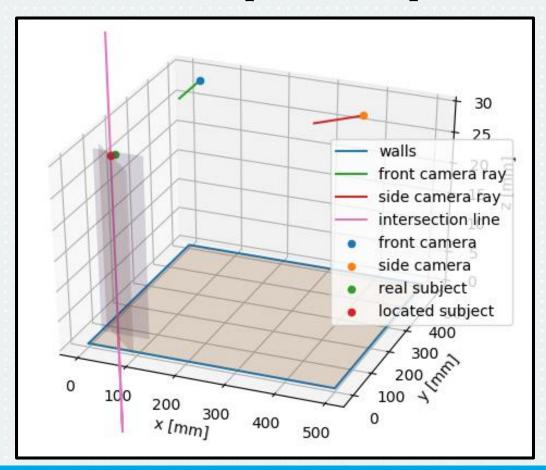
y = 3 m



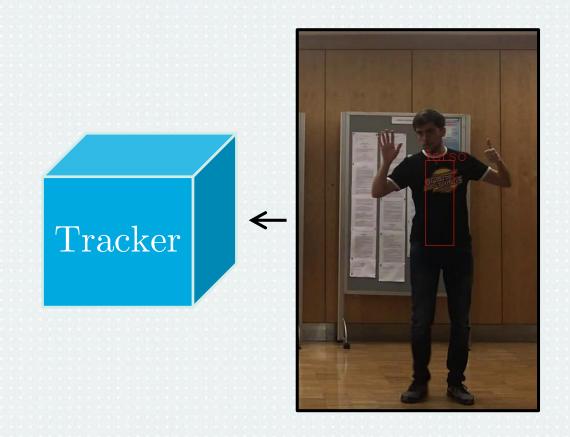
y = 6 m

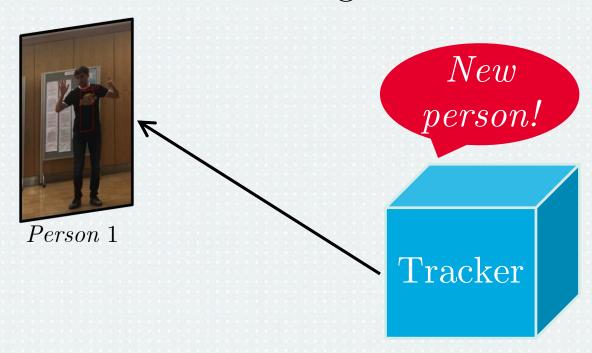
Triangulation

Intersection of distance planes \rightarrow person's position



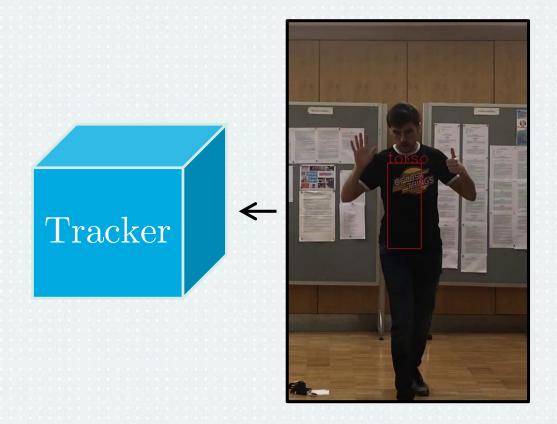


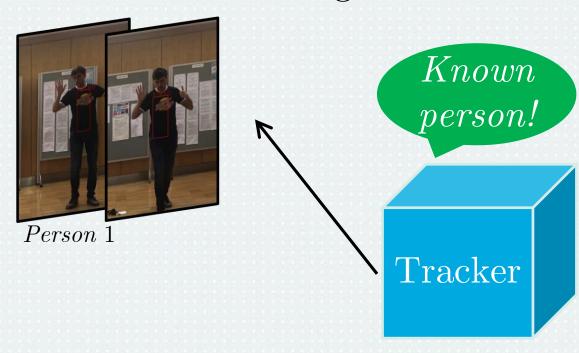






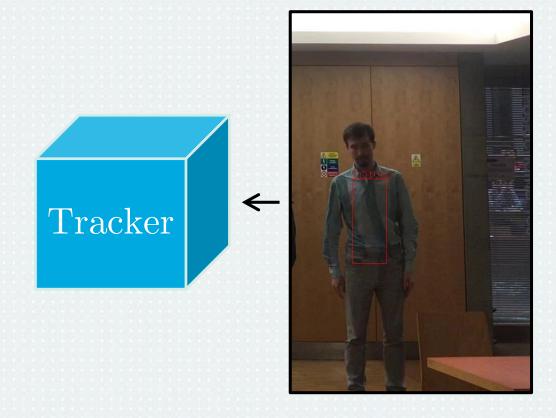
Person 1

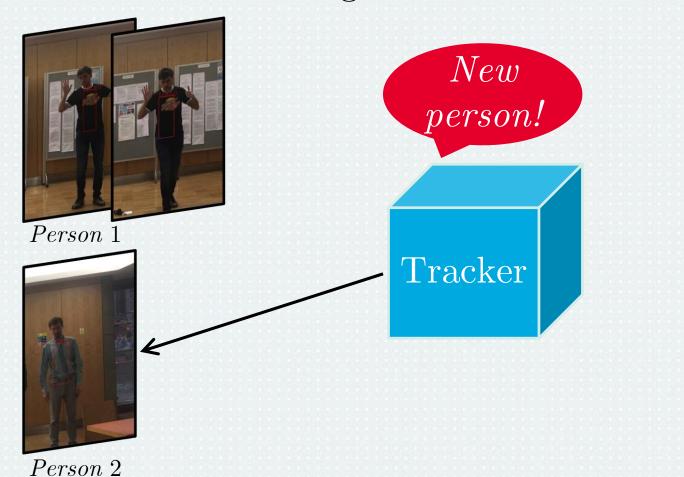






Person 1



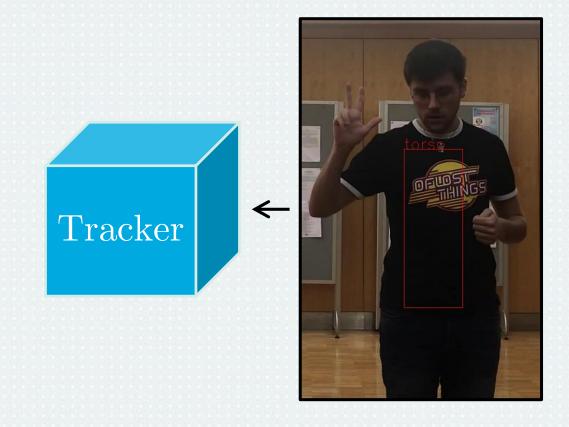


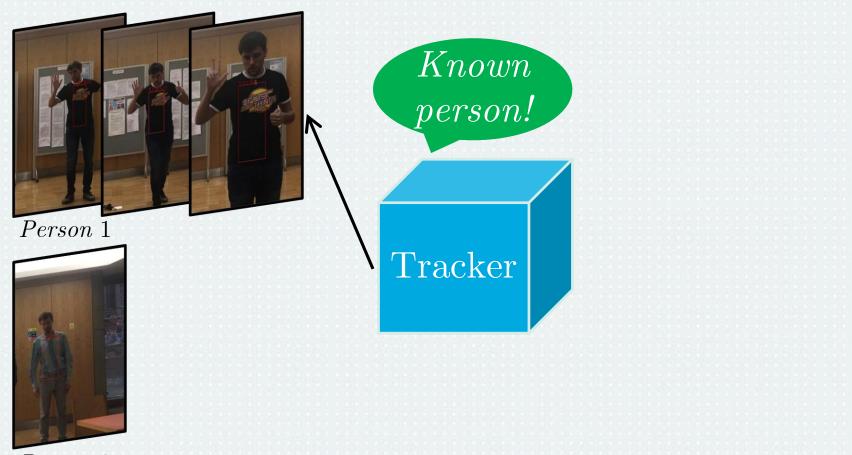


Person 1



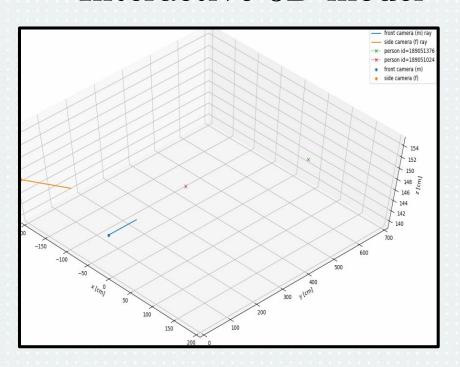
Person 2

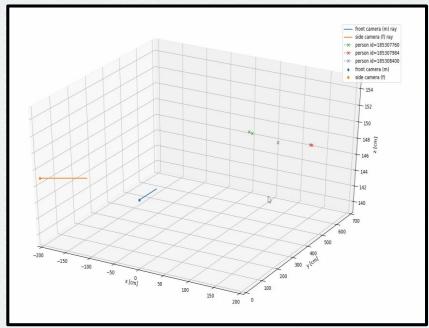




Visualisation

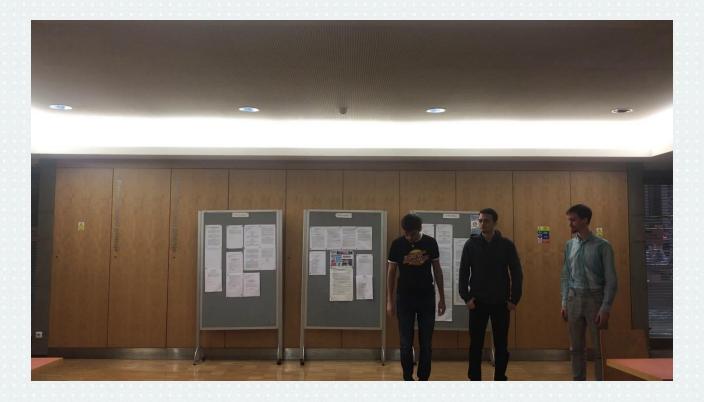
- Paths of all tracked people, positions of cameras
- Interactive 3D model





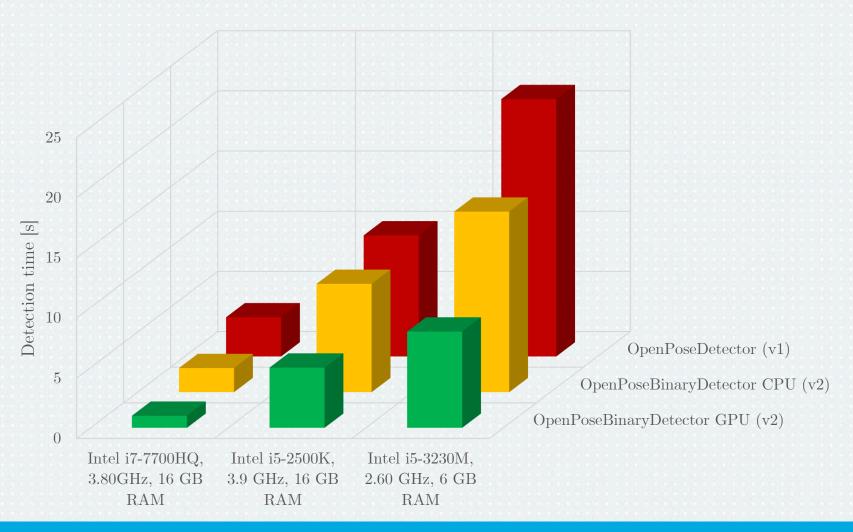
Testing Data

- Own images and videos
- COCO dataset for OpenPose



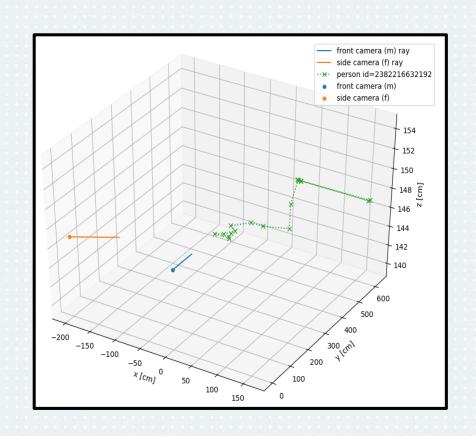
Evaluation

Human Detection Time

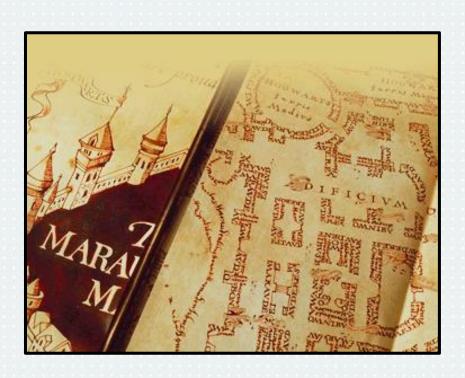


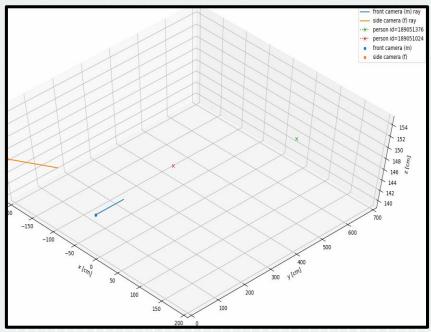
Evaluation

- Matching
- Triangulation
 worst case less than 35 cm
 error in 600 cm space.
- Tracking
 Similarity threshold



Pedestrian tracking





Thank you for your attention.