Classification

Ekhine Irurozki







Classification

- Supervised learning: n features, a categorical class variable Y
- A classifier is a ML algorithm for classification. Training, learning,...
- Approaches:
 - Separation of the instances of each class in the feature space
 - Learning the distribution of the data

1 X ₂		X _{n-1}	Xn	Υ
6		5	9	1
1		5	6	0
6		5	5	0
89		23	85	1
435	5	3	1	1
1		77	321	0
8		6	8	1
77		3	132	0
9		1	8	0
8		4	8	?
	6 1 6 89 435 	6 6 89 435 1 1 9	6 5 1 5 6 5 89 23 435 3 1 77 8 6 77 3 9 1	6 5 9 1 5 6 6 5 5 89 23 85 435 3 1 1 77 321 8 6 8 77 3 132 9 1 8



OvO - OvA

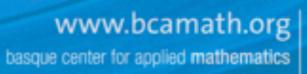
- Some classification algorithms can only distinguish between two classes, how can we use them in multi class problems?
 - One vs One strategy: train k(k-1)/2 binary classifiers. At prediction stage we will assign a new observation to the class that wins in more classifiers
 - One vs All (or One vs Rest) strategy: one classifier per class. The outcome must be numerical, representing the confidence on it



Outline

- K Nearest Neighbour, KNN
- Decision trees, bagging, random forests, boosting
- Logistic regression
- Discriminant analysis: LDA, QDA, GaussianNB
- Support Vector Machines, SVM





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KNN 3-Class classification (k = 3) 4.5 It is a lazy algorithm which does 4.0 not learn any model and makes 3.5 computations in classification 3.0 2.5 time 2.0 1.5 Given a dataset D a new 1.0 instance for prediction X sepal length (cm)

- Let D' be the k closest instances to X on D
- Assign X to the most popular class on D'



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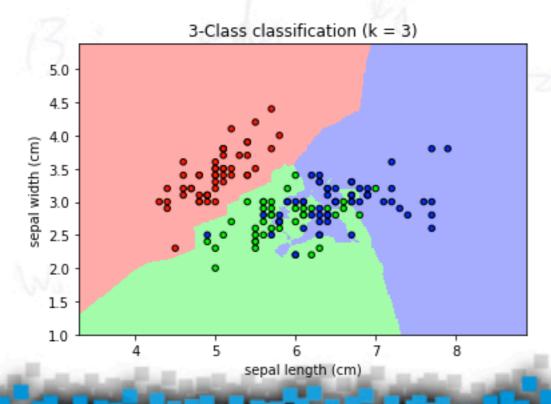
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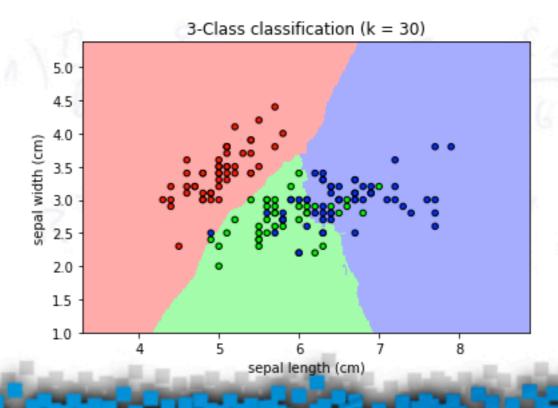
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• What happens as we change k? The decision boundaries get smoother and we control overfitting

How do we choose k?



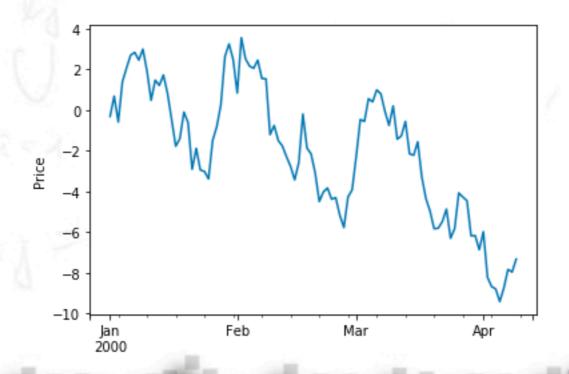




- If we can define similarity measures for the features we can use the KNN
- Time series, a series of data points indexed sequentially



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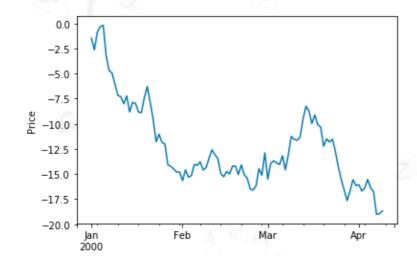


Instance Class





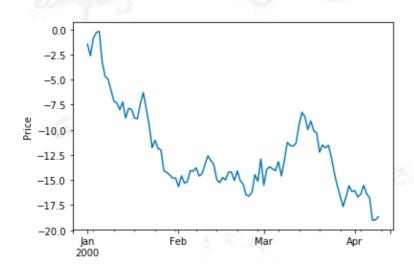
Class







Class

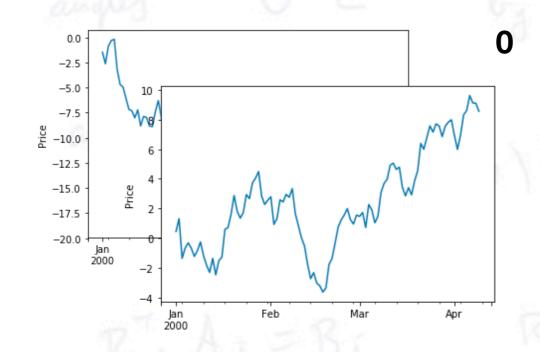


0

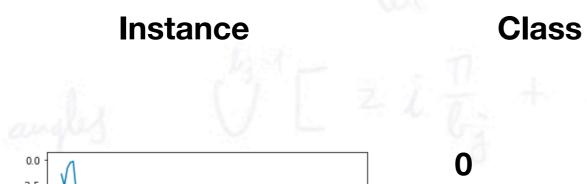


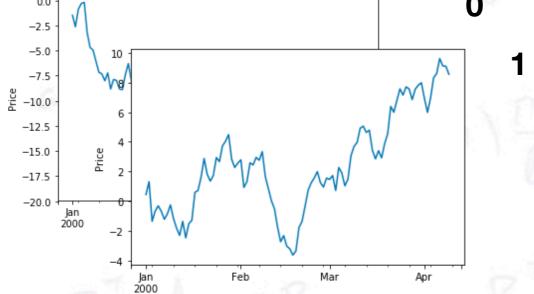


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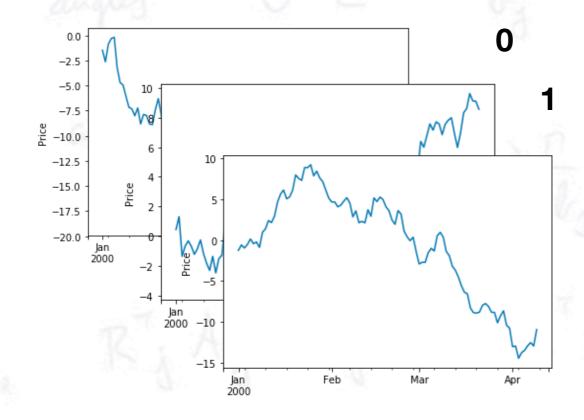




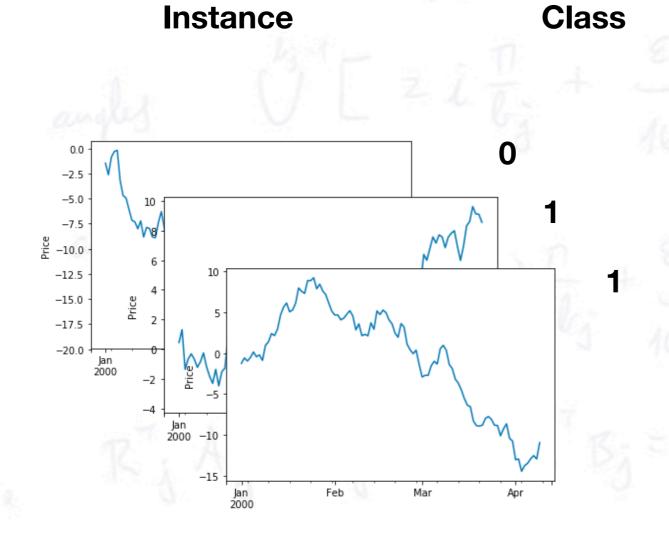




Class



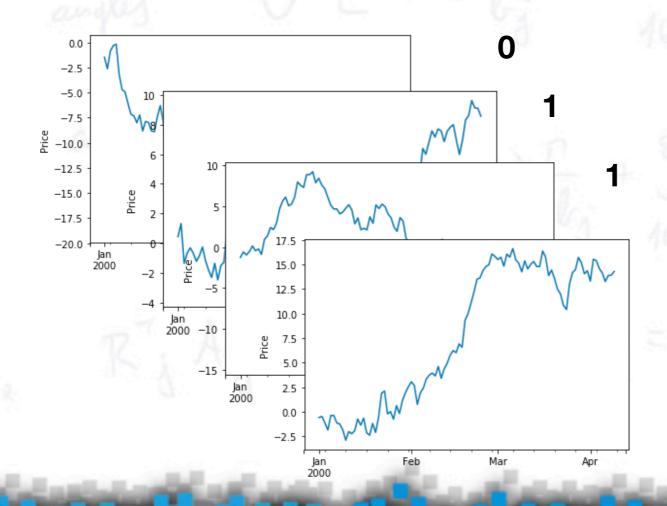




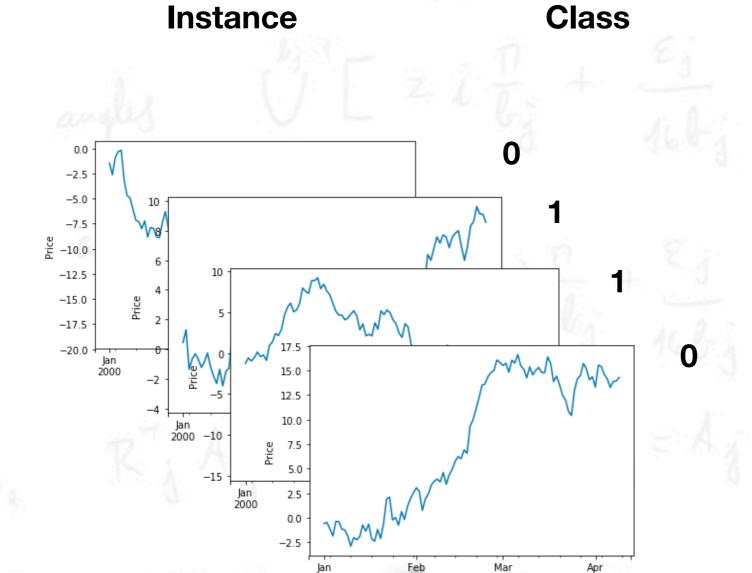




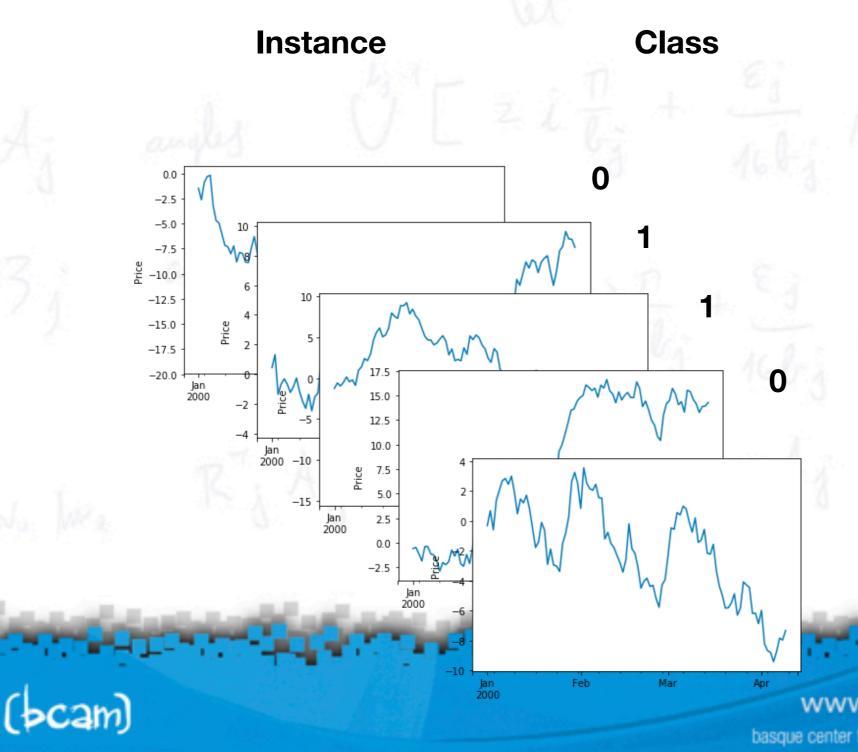
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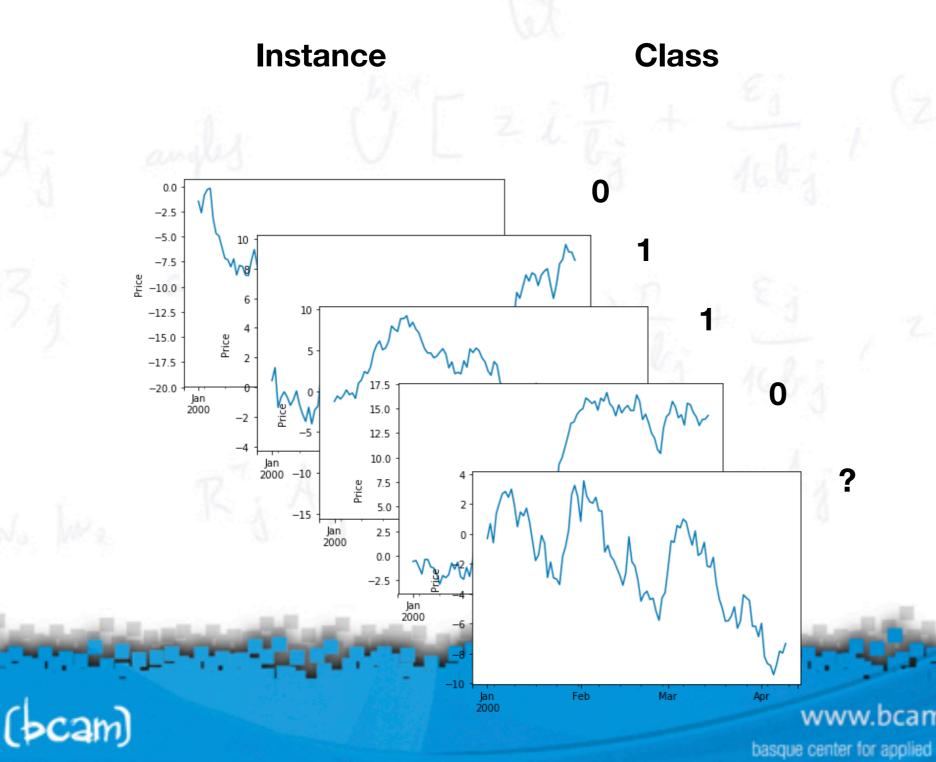




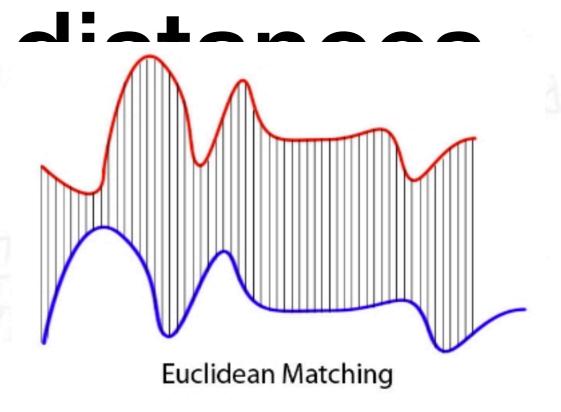


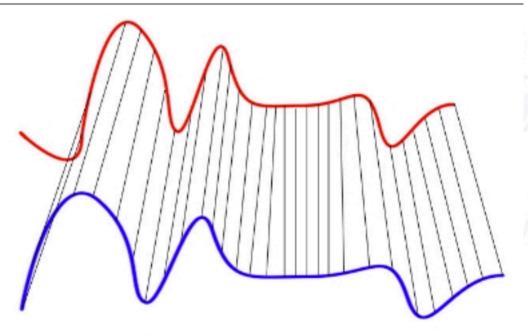






KNN - TS

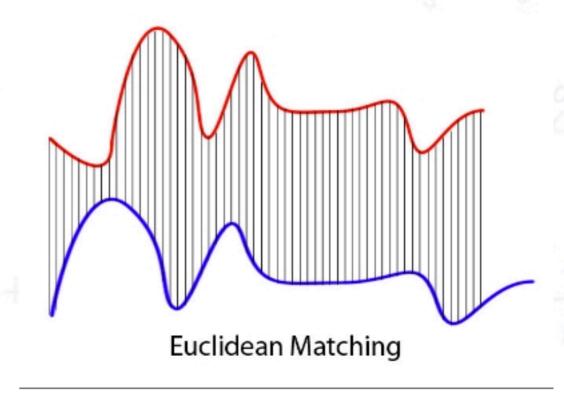


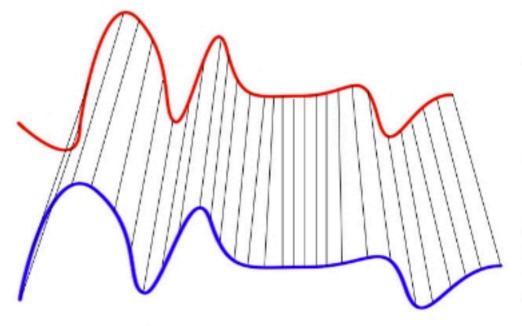


Dynamic Time Warping Matching

KNN for time series

Dynamic time warping, DTW, a distance for time series





Dynamic Time Warping Matching



- Easy to understand and implement
- Computationally efficient in general
- Defining similarities
- The first thing that you should try when approaching a ML problem
- The curse of dimensionality: Nearest neighbours tend to be far away in high dimensions

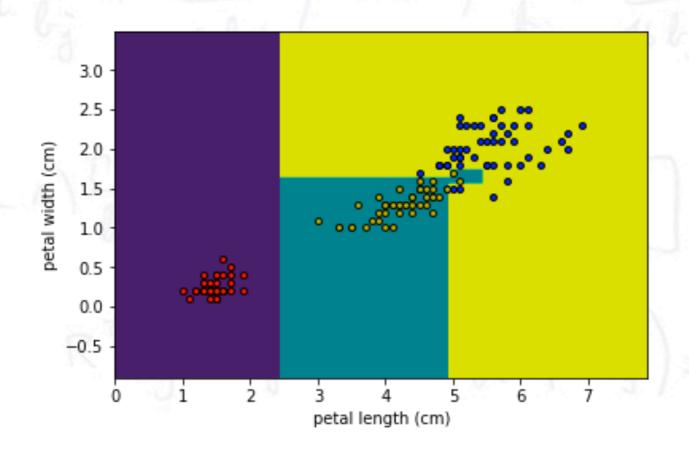


Outline

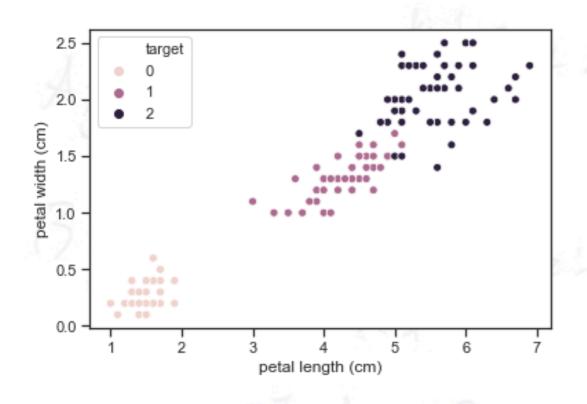
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- Divide the feature space into high dimensional rectangles
- Find the boxes that minimise the classification error
- Infeasible!

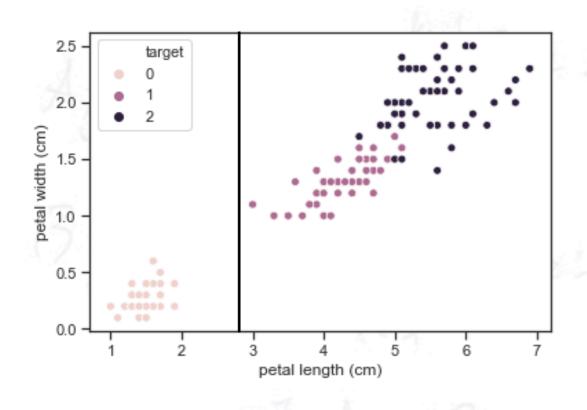






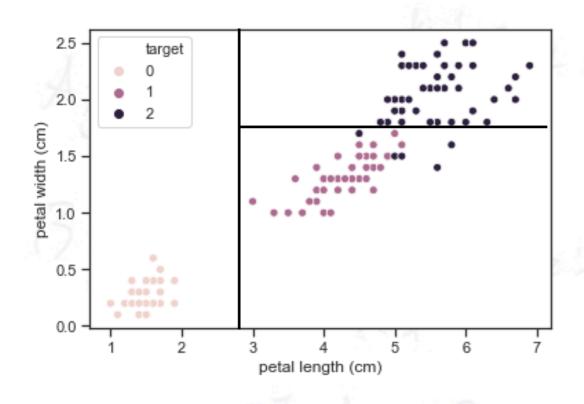
- Recursive binary splitting: iteratively partition the feature space.
- Error measured as

$$G = \sum_{k=1}^{K} \hat{p}_{mk} (1 - \hat{p}_{mk}) \text{ where } \hat{p}_{mk}$$



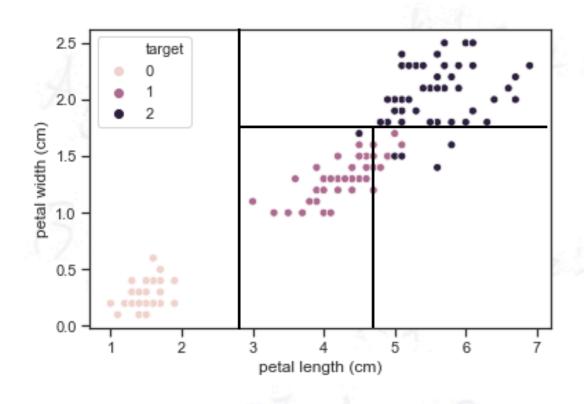
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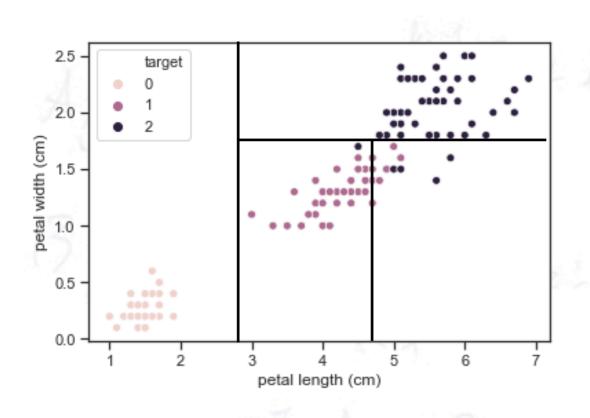
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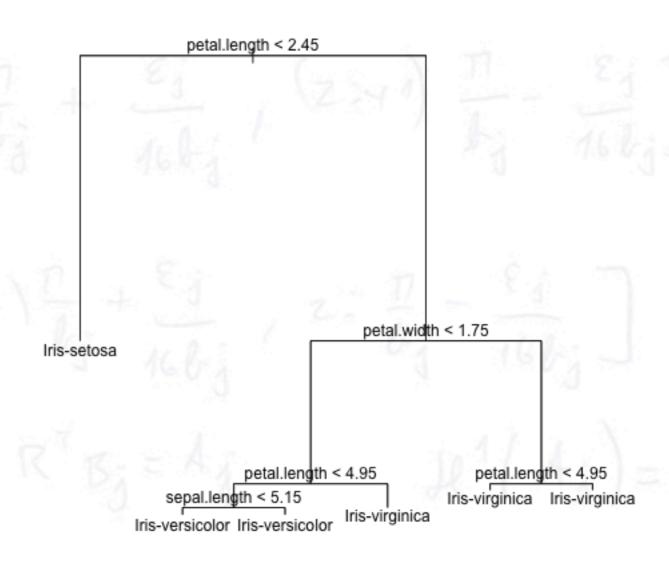
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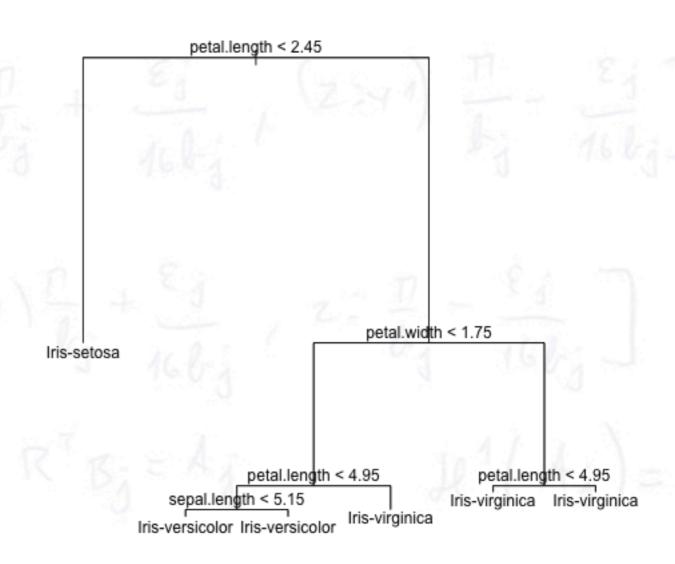
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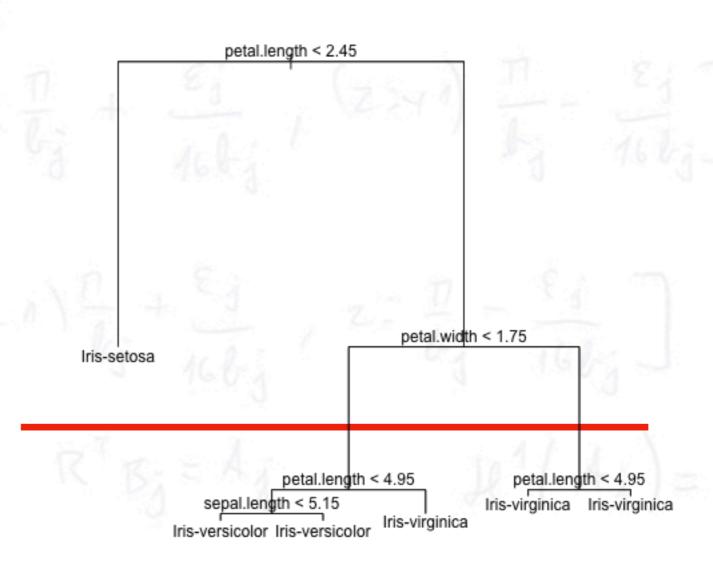


- Deep trees lead to high variance and overfitting
- When do we stop growing the tree?
 - iterate until each region contains no more than k samples
 - prune the tree, regularization





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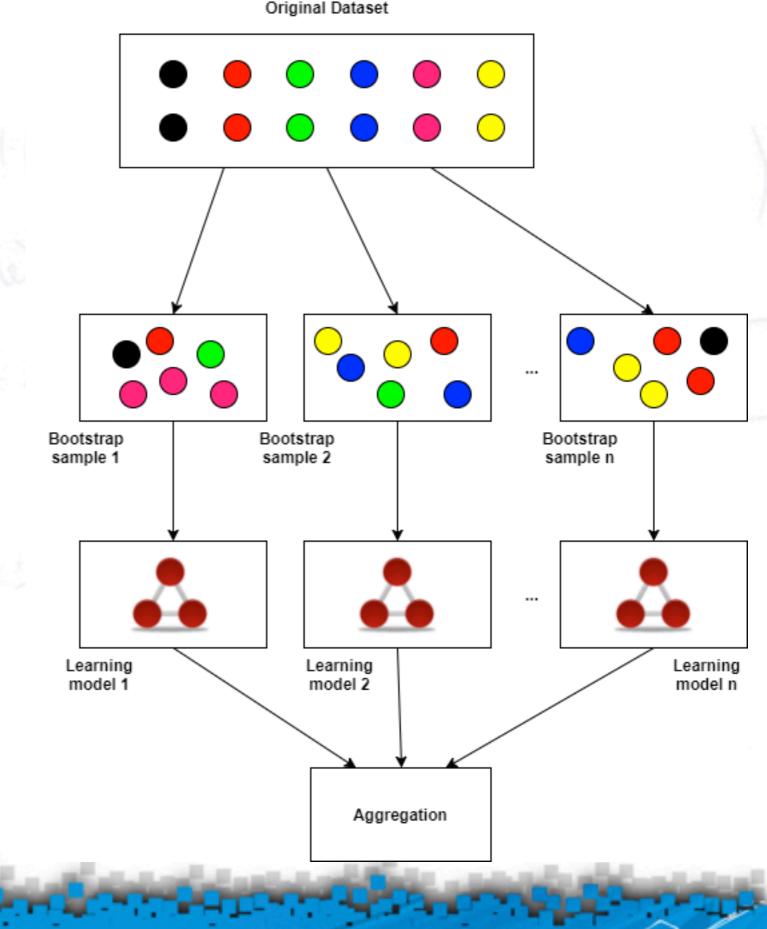


- Simple and interpretable. It is easy to understand by an expert
- Not competitive with modern algorithms
- High variance
- Can be a building block for other techniques



Bagging

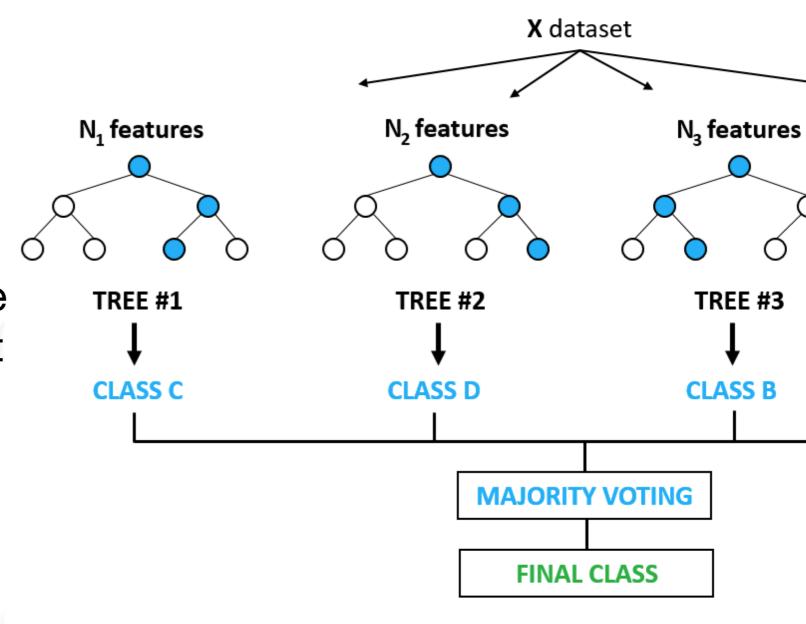
- Bootstrap sample
- Grow a full tree
- Aggregate all results
- The mean decrease of Gini index by split for a given feature gives the variable importance





Random forests

- Bootstrap sample
- Select a subset of the features for each split
- Aggregate the results





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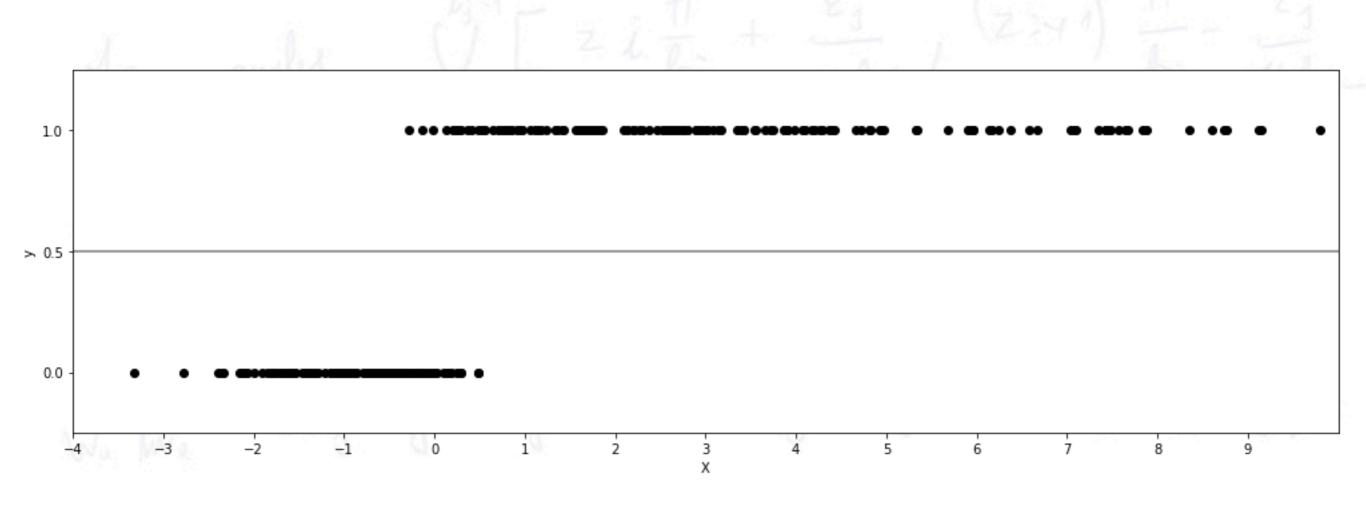


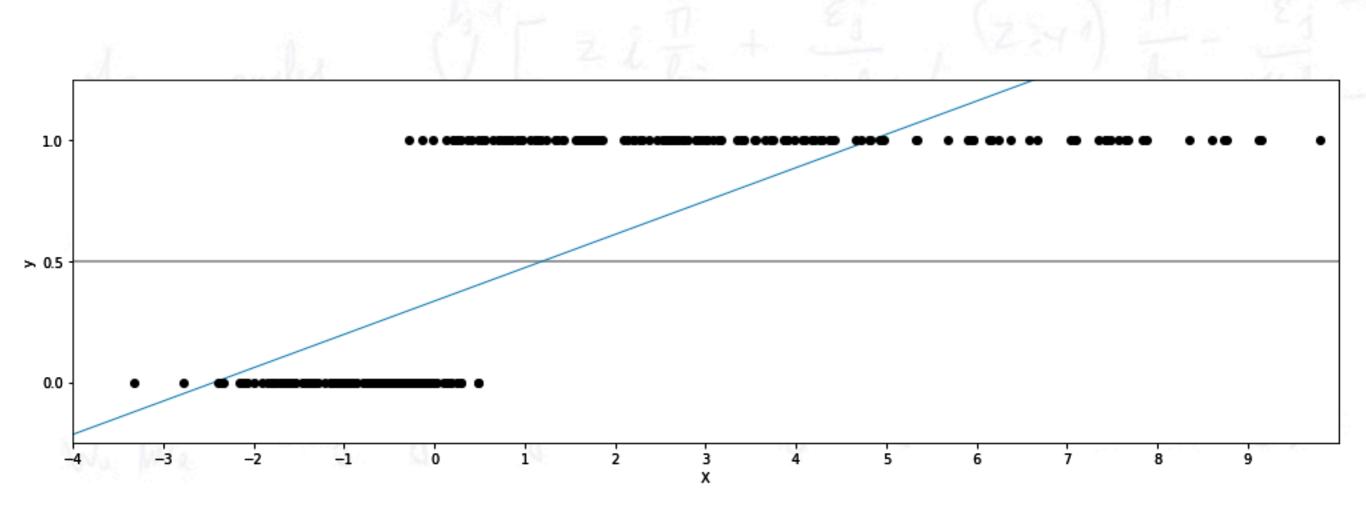
- Binary class variable, Y
- Example in finance: X is the balance of a client and Y client's default
- Different approach from previous chapter: model the relation between X, the balance, and the probability of default of this client $p(X) = Pr(Y = 1 \mid X)$



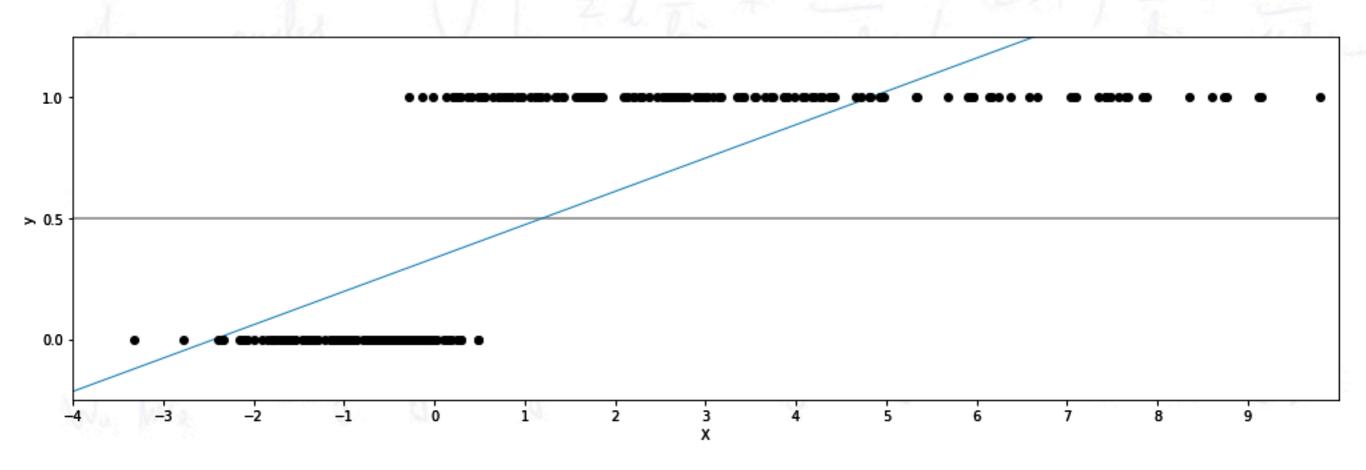
- First approach is to use linear regression: $Y = \beta_0 + \beta_1 X$
 - LR is a very powerful solution in many context
 - Easy to fit
 - Interpretable







• Change the domain from $(-\infty, \infty)$ to [0,1]





One approach is to use the logistic function

$$p(X) = \frac{exp(\beta_0 + \beta_1 X)}{1 + exp(\beta_0 + \beta_1 X)}$$

• This is equivalen to $log \frac{p(X)}{1 - p(X)} = \beta_0 + \beta_1 X$

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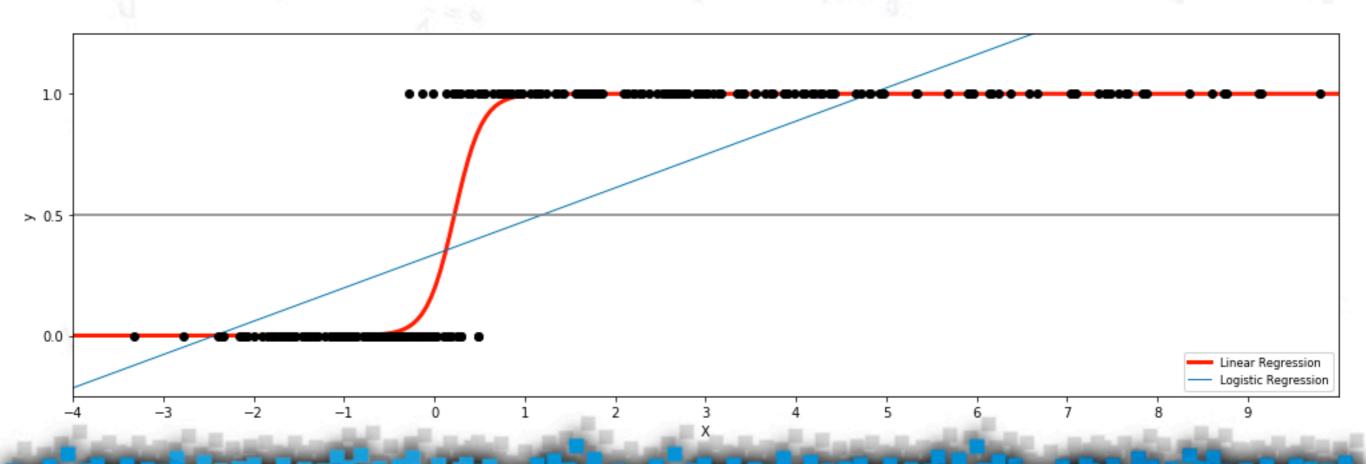
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The logit is linear in X

• This is equivalen to $log \frac{p(X)}{1 - p(X)} \neq \beta_0 + \beta_1 X$

- Making predictions is easy
- Maximum likelihood estimation of the coefficients efficient



- When the classes are well separated it can be unstable: if there is a feature that separates clases perfectly the coefficients go up to infinity
- If the sample is small discriminant analysis is more accurate



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$$\bullet \ \ P(Y=k)$$

- P(X = x | Y = y): assume that they follow the Gaussian distribution with the same variance in each class (Linear Discriminant Analysis)
- P(Y = k | X = x)

X	Y
3	1
5	0
4	0
7	1
3	1
	•••
8	0
9	1
4	0
8	?

• Model the distribution of X and use the Bayes theorem to obtain P(Y|X):

$$P(Y = k \mid X = x) = \frac{P(X = x \mid Y = y)P(Y = k)}{P(X = x)} = \frac{\pi_k f_k(x)}{\sum_{i \le k} \pi_i f_i(x)}$$

- Assign x to the class with maximum P(Y|X)
- We do not need the denominator
- Particularly accurate when the classes are normal



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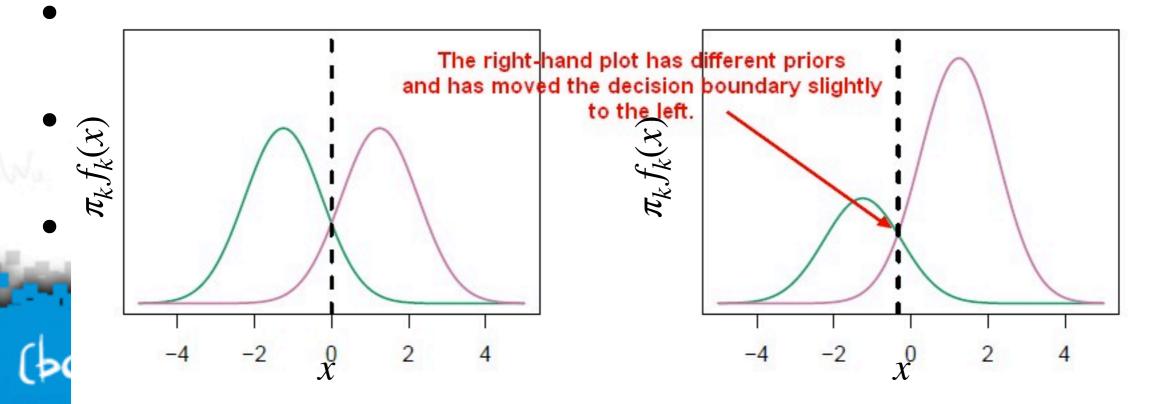


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$$\pi_1 = .5, \quad \pi_2 = .5$$

$$\pi_1 = .3$$
, $\pi_2 = .7$



Linear Discriminant analysis

 If we assume that f is Gaussian, the Bayes classifier assign an observation to the class with maximum discriminant funciton value

$$\delta_k(x) = x \frac{\mu_k}{\sigma^2} - \frac{\mu_k^2}{2\sigma^2} + \log(p_k)$$

- Linear function of x
- Learning from data implies estimating the means and the variances



Quadratic discriminant analysis

•
$$P(Y = k \mid X = x) = \frac{P(X = x \mid Y = y)P(Y = k)}{P(X = x)} = \frac{\pi_k f_k(x)}{\sum_{i \le k} \pi_i f_i(x)}$$

- assume that the density follows a Gaussian distribution with different variance in each class
- Discriminant function $\delta_k(x)$ is quadratic on x



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Naive Bayes

In each class the density factors into a product of

densities,
$$f_k(x) = \prod_{j=1}^{p} f_{jk}x(j)$$

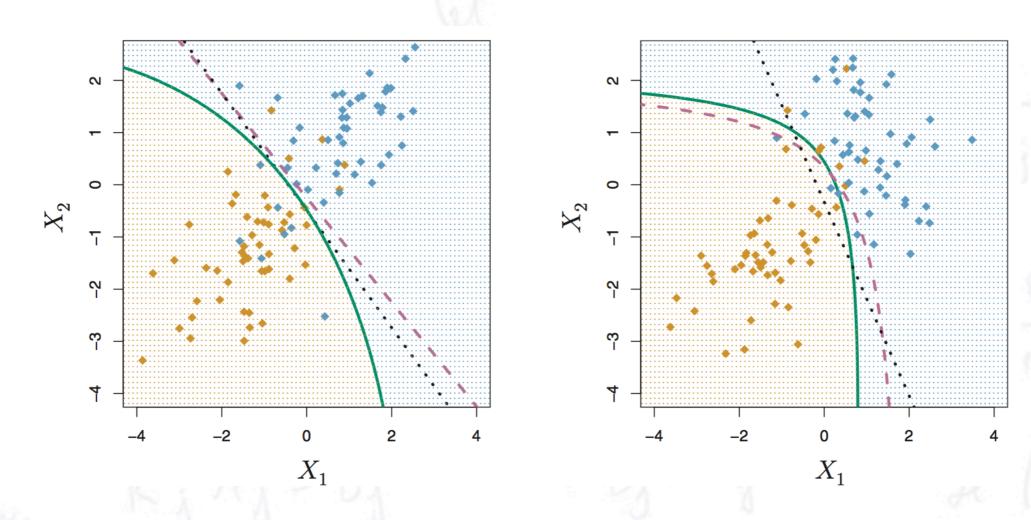
 The assumptions are strong (conditionally independence in each of the classes) but for classification we are interested in finding the class for which the probability

$$P(Y = k | X = x) = \frac{P(X = x | Y = y)P(Y = k)}{P(X = x)}$$
 is

maximized



LDA QDA



Bayes, LDA and QDA decision boundaries



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Separating hyperplanes

- Find decision boundaries that separate the data in different classes
- Two dimensional feature space in the example



- A flat affine subspace of dimension n-1
- In a two dimensional space, a hyperplane is a line
- It has the form

$$\beta_0 + X_1 \beta_1 + X_2 \beta_2 + \ldots + X_n \beta_n = 0$$

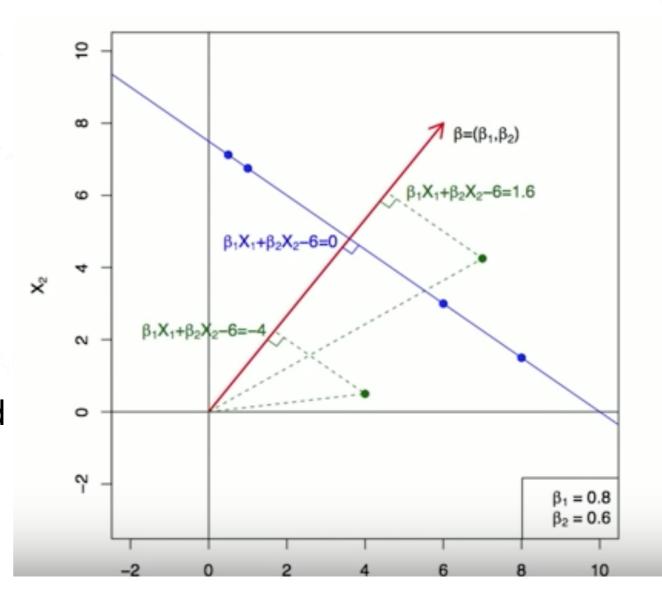
• The vector $(\beta_1, \beta_2, ..., \beta_n)$ is called a normal vector and goes from the origin in a direction orthogonal to the surface of the hyperplane



- Hyperplane, $\beta_0, \beta_1, \beta_2$
- Normal, β_1, β_2

•
$$\beta_1^2 + \beta_2^2 = 1$$

- Projections onto the normal and the distance to the hyperplane
- Can be positive, zero or negative



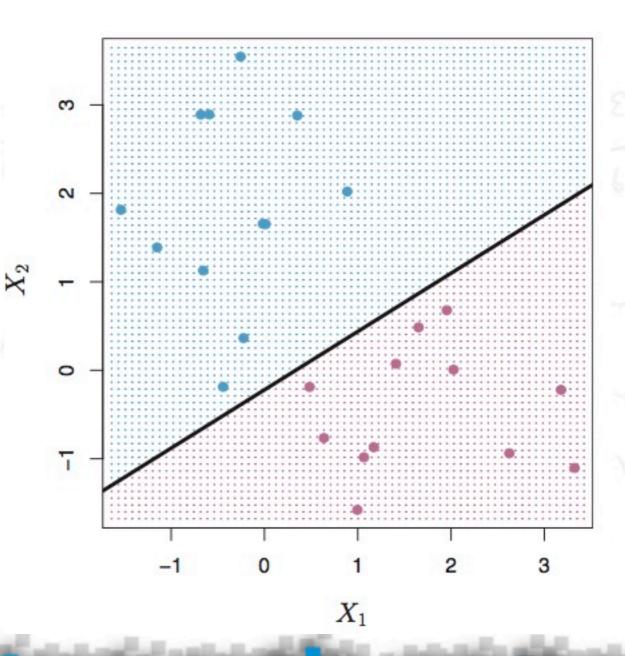
For every blue point i

$$\beta_0 + \sum_j X_{ij} \beta_{ij} > 0$$

For every purple point i

$$\beta_0 + \sum_j X_{ij} \beta_{ij} < 0$$

- Predictions are very easy
- Data has to be normalised



- Assume that the class value of instance i is $y_i = \{-1, +1\}$
- Then for every separating hyperplane it holds that for every sample i

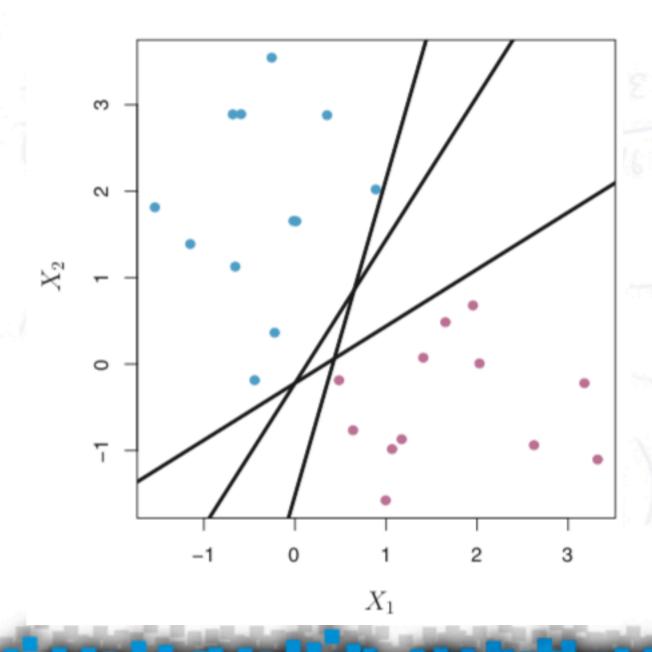
$$y_i * (\beta_0 + \sum_j X_{ij} \beta_{ij}) > 0$$

This is the key to the learning algorithm



Max margin classifier

- Which separating Hyperplane do we choose?
- In order to reduce the variance we will prefer the hyperplane that is farther from the observations





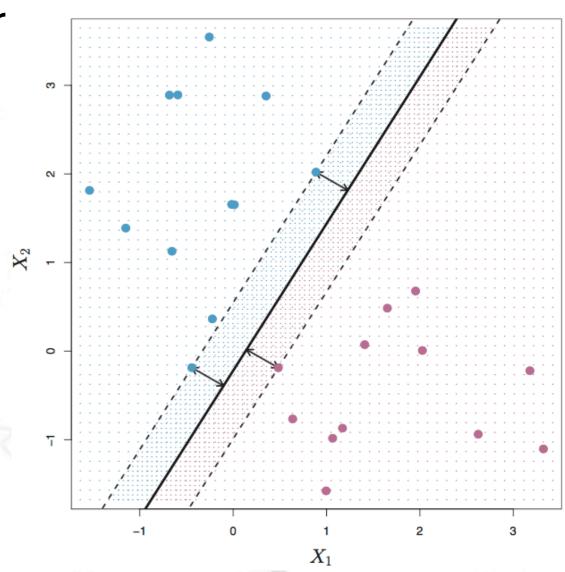
Max margin classifier

 The maximal margin classifier can be estimated as an optimisation problem

$$\arg\max_{\beta_0,\beta_1,...,\beta_n} M$$

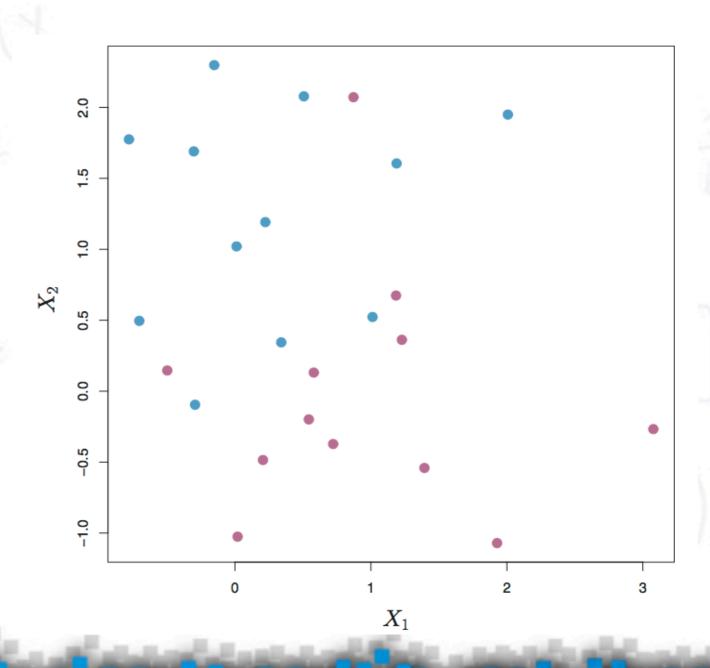
subject to
$$\sum_{j=1}^{n} \beta_j^2 = 1$$
,

$$y_i * (\beta_0 + \sum_j X_{ij} \beta_{ij}) \ge M$$



The non-separable case

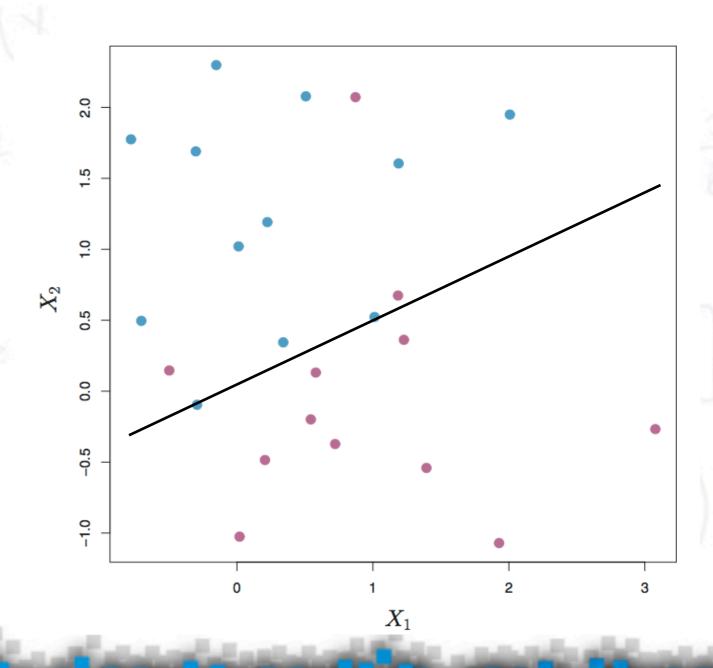
 In most cases the data is not separable. In this case we can try to look for the hyperplane that almost separates the classes, the support vector classifier





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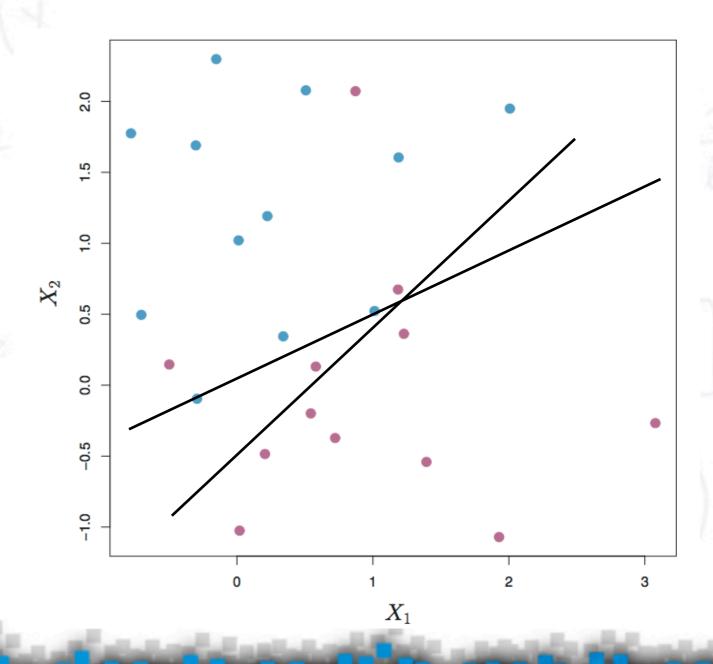
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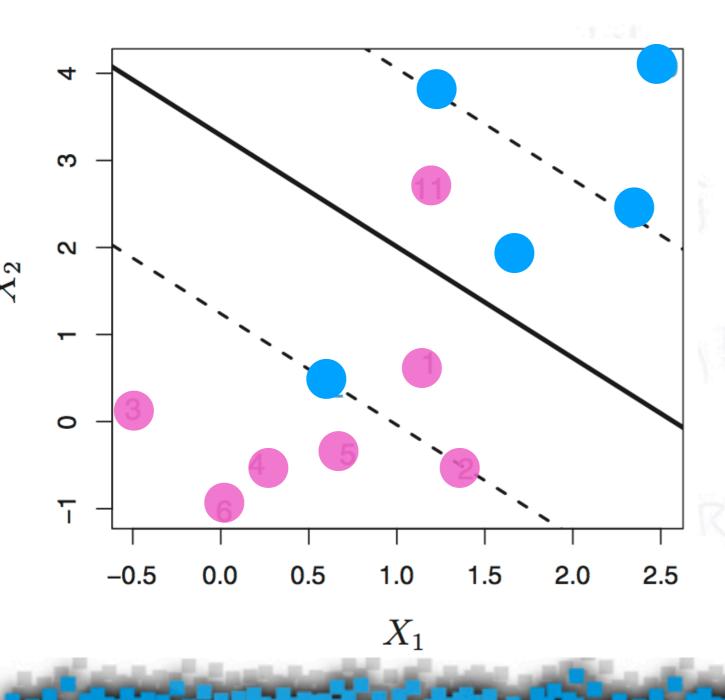


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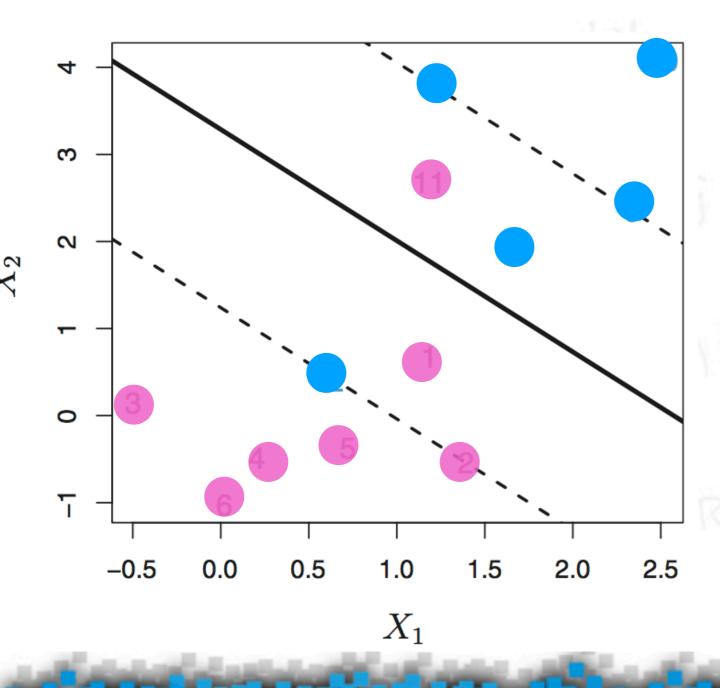
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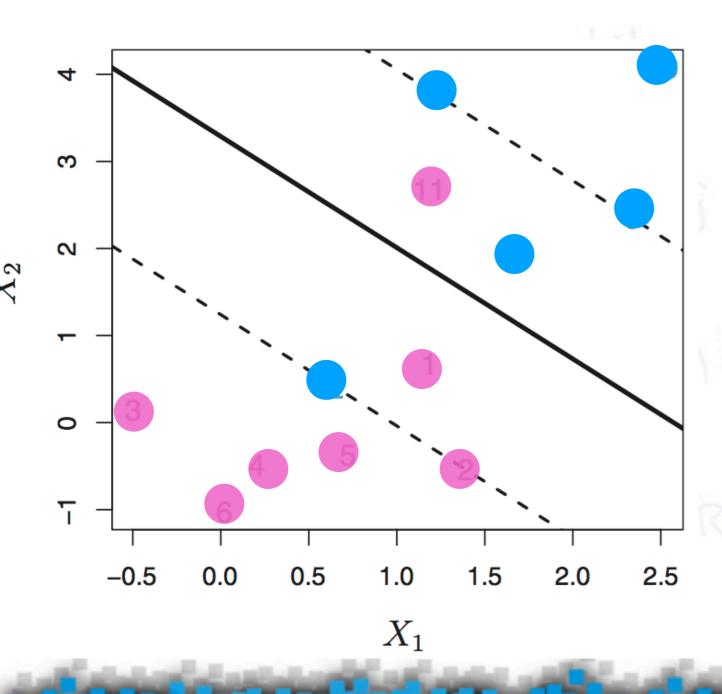




$$\arg\max_{\beta_0,\beta_1,\dots,\beta_n} M_{i},\dots,\epsilon_n$$
subject to
$$\sum_{j=1}^n \beta_j^2 = 1,$$

$$y_i * (\beta_0 + \sum_j X_{ij}\beta_{ij}) \ge M(1 - \epsilon_i),$$

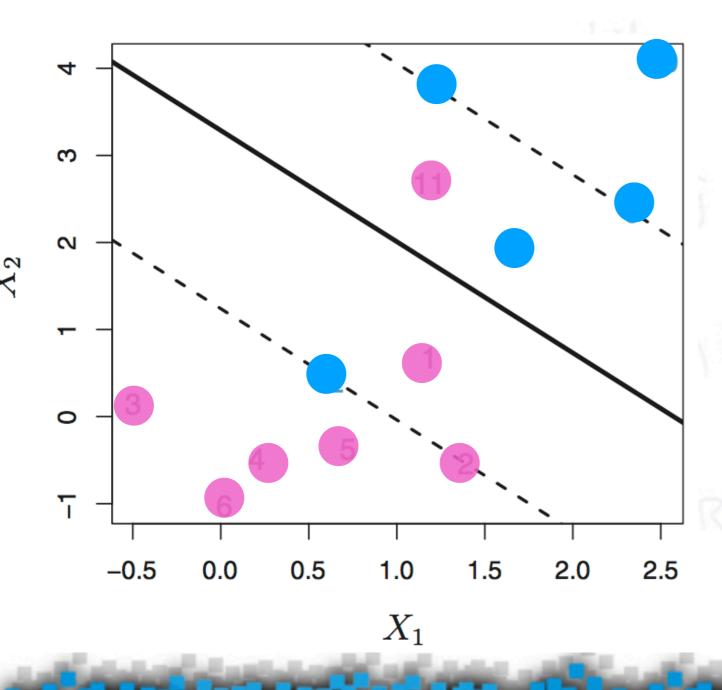
$$\epsilon_i \ge 0, \sum_i \epsilon_i \le C$$



$$\arg\max_{\beta_0,\beta_1,\dots,\beta_n,\epsilon_1,\dots,\epsilon_n} M$$
subject to
$$\sum_{j=1}^n \beta_j^2 = 1,$$

$$y_i * (\beta_0 + \sum_j X_{ij}\beta_{ij}) \ge M(1 + \epsilon_i)$$

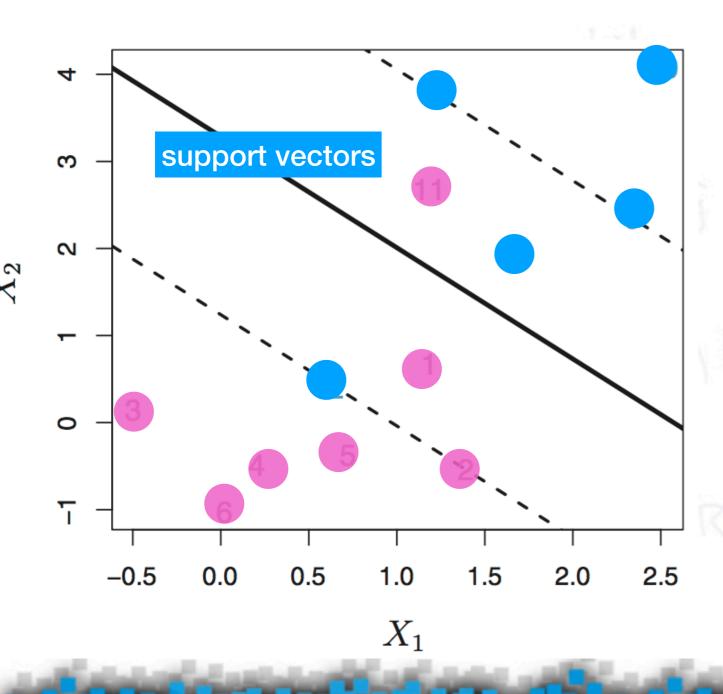
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$$\arg\max_{\beta_0,\beta_1,...,\beta_n} M_{i},...,\epsilon_n$$
 subject to
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 control overfitting



$$\arg\max_{\beta_0,\beta_1,...,\beta_n} M_{i},...,\epsilon_n$$
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 control overfitting

SVC non linearities

 We can address non-linearities by enlarging the feature space as follows

$$X_1^2, X_1^3, X_1X_2, X_1X_2^2, \dots$$

Then we can fit

$$\beta_0 + X_1^2 \beta_1 + X_1^3 \beta_2 + X_1 X_2 \beta_3 + X_1 X_2^2 \beta_0 \dots$$



SVM

• The SVC classifies a test instance to the size of the hyperplane it lies on. When K is the inner product it can also be expresses as

$$f(x) = \beta_0 + \sum \alpha_i K(x, x_i)$$

- To estimate it we just need the pairwise distance among observations. It happens that α_i is going to be non-zero just for the support vectors
- The support vector machine is an extension of the support vector classifier using kernels.



SVM kernels

Kernels quantify the similarities between two observations

$$K(x_i, x_k) = \sum_{j} x_{ij} x_{kj}$$

Polynomial

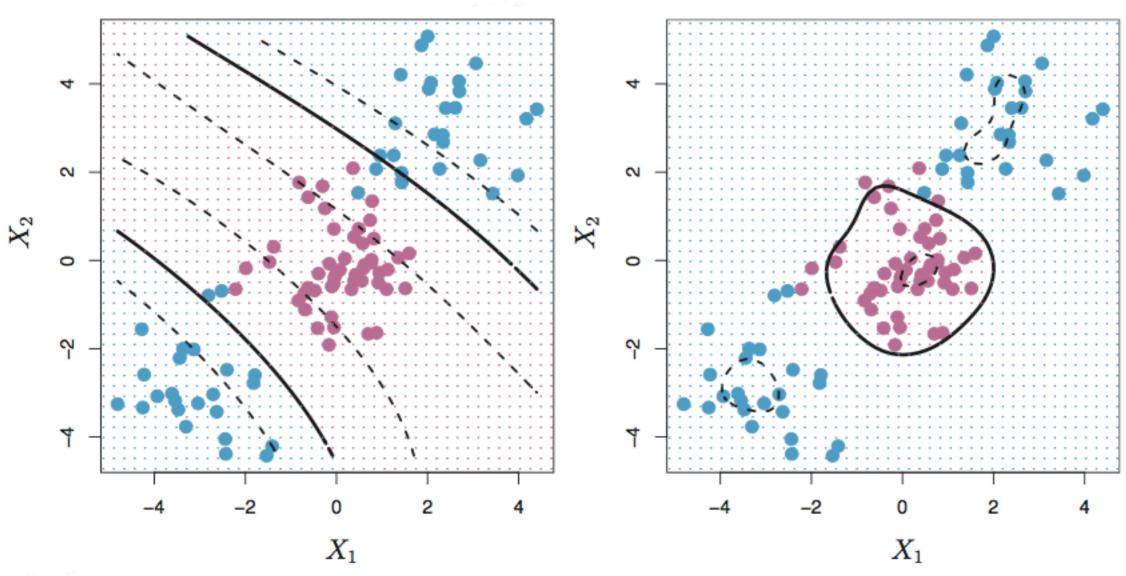
$$K(x_i, x_k) = (1 + \sum_{j} x_{ij} x_{kj})^d$$

Radial Kernel

$$K(x_i, x_k) = exp(-\lambda + \sum_{j} (x_{ij} x_{kj})^2)$$



SVM kernels



• Polynomial kernel of degree 3

Radial kernel

