

# **UPGRADE TO 3D PRINTABLE JET ENGINE - TURBOFAN DRIVER WITH MAGNETIC COVER**

**V2**

**NOV 2022**

**Electronics Assembly Instructions**

By Adam B. Johnson

# TABLE OF CONTENTS

Things you'll need

Cables to make

Header and jumper soldering

Voltage checks

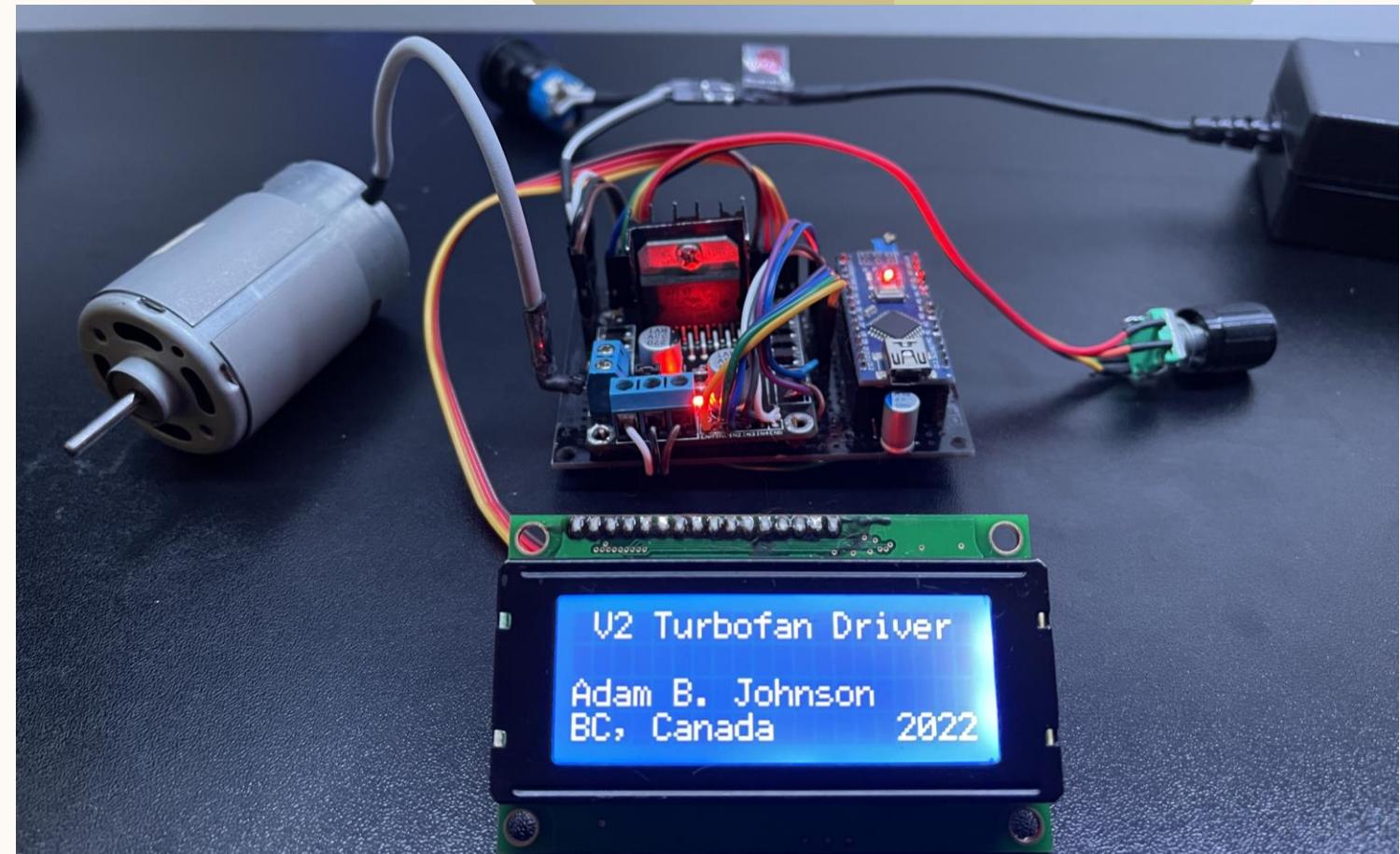
Analog voltage check

Arduino programming and  
screen contrast

First time startup and speed reset

12V motor test

Signal conditioning - extra



# THINGS YOU'LL NEED



## Required Equipment

Multimeter with voltage and continuity settings

Soldering iron with solder and flux

Isopropyl alcohol

Small brush

Mini-USB cable for Arduino programming

Wire strippers 16-22AWG

Side cutters

Fine pointed knife

clear tape

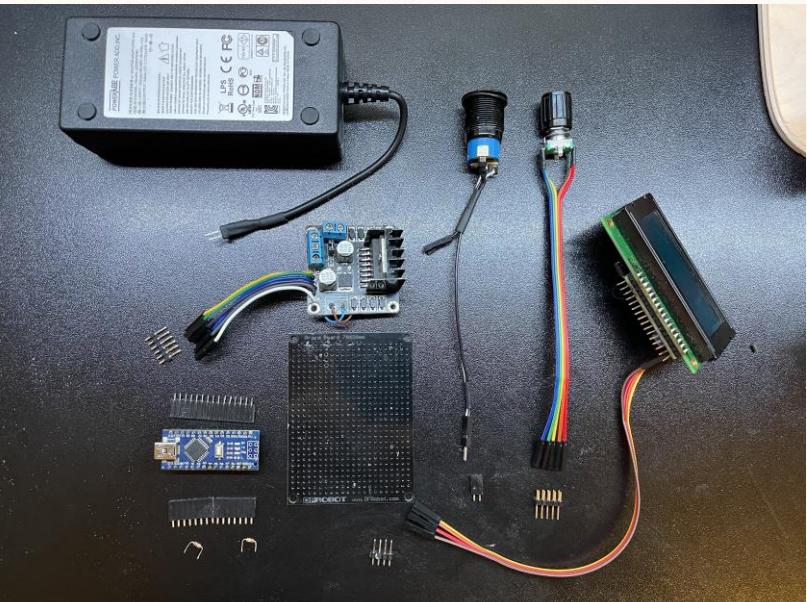
red sharpie

GitHub repository: <https://github.com/nairck/TurbofanDriver>

Control Schematic V2:

<https://github.com/nairck/TurbofanDriver/blob/main/Control%20Schematic%20-%20V2.pdf>

Arduino Code: [https://github.com/nairck/TurbofanDriver/tree/main/Control\\_Sketch\\_V2](https://github.com/nairck/TurbofanDriver/tree/main/Control_Sketch_V2)



## Off-the-shelf Hardware for Turbofan Driver

1x Arduino Nano - [https://www.amazon.ca/Arduno-ELEGOO-ATmega328P-Compatible-Without/dp/B071NMD14Y/ref=sxts\\_sxwds-bia-wc-rsf-lq2a1\\_0](https://www.amazon.ca/Arduno-ELEGOO-ATmega328P-Compatible-Without/dp/B071NMD14Y/ref=sxts_sxwds-bia-wc-rsf-lq2a1_0)

1x L298N Motor Driver - [https://www.amazon.ca/Neuftech-H-Bridge-Stepper-Controller-Raspberry/dp/B01KBTNHS6/ref=sr\\_1\\_3](https://www.amazon.ca/Neuftech-H-Bridge-Stepper-Controller-Raspberry/dp/B01KBTNHS6/ref=sr_1_3)

1x RS-555SH 12V Brushed DC Motor - <https://www.parts-express.com/Mabuchi-Type-Motor-RS-555SH-12V-DC-Motor-9-15V-57mm-x-36mm-125-566?quantity=1>

1x 20x4 2004D rev. C LCD Screen with I2C module - <https://www.buydisplay.com/small-size-arduino-code-lcd-20x4-i2c-character-display-wide-view-angle>

1x EC11 Rotary Encoder with Button - [https://www.amazon.ca/Cylewet-Encoder-Digital-Potentiometer-Arduino/dp/B07DM2YMT4/ref=dp\\_prsubs\\_1](https://www.amazon.ca/Cylewet-Encoder-Digital-Potentiometer-Arduino/dp/B07DM2YMT4/ref=dp_prsubs_1)

1x 120VAC 19mm Latching Power Button - [https://www.amazon.ca/gp/product/B017KP67FY/ref=ppx\\_yo\\_dt\\_b\\_search\\_asin\\_title](https://www.amazon.ca/gp/product/B017KP67FY/ref=ppx_yo_dt_b_search_asin_title)

1x 58mm x 78mm Proto Board - [https://www.robotshop.com/ca/en/prototyping-board.html?glcid=CjOKCQjAmL-ABhDFARisAKywVadrBUsqdr9uNxGyM8eJ5VqHiz2U\\_HtVTzj7YqXQUhuB1ejnLW4MaAnh7EALw\\_wcb](https://www.robotshop.com/ca/en/prototyping-board.html?glcid=CjOKCQjAmL-ABhDFARisAKywVadrBUsqdr9uNxGyM8eJ5VqHiz2U_HtVTzj7YqXQUhuB1ejnLW4MaAnh7EALw_wcb)

22AWG male and female jumper wire – multiple colours. - [https://www.amazon.ca/gp/product/B01M1IEUAF/ref=ppx\\_yo\\_dt\\_b\\_search\\_asin\\_image](https://www.amazon.ca/gp/product/B01M1IEUAF/ref=ppx_yo_dt_b_search_asin_image)

Breadboard Jumper Cable Wire Kit Jumper Protoboard - [https://www.amazon.ca/140pcs-Solderless-Breadboard-Jumper-Shield/dp/B07D32FDMZ/ref=sr\\_1\\_4\\_sspx](https://www.amazon.ca/140pcs-Solderless-Breadboard-Jumper-Shield/dp/B07D32FDMZ/ref=sr_1_4_sspx)

1x 10k potentiometer - [https://www.amazon.ca/Uxcell-a14052600ux0954-Trimmer-Potentiometer-3296W-103/dp/B00SWIJZMM2/ref=sr\\_1\\_32](https://www.amazon.ca/Uxcell-a14052600ux0954-Trimmer-Potentiometer-3296W-103/dp/B00SWIJZMM2/ref=sr_1_32)

1x 10k resistor – could use a second 10k pot (as pack comes with multiple, or single 10k resistor)

2x 15, 1x 3, 1x 2      socket female header (2.54mm pitch).

1x 6, 1x 5, 1x 4, 1x 2      male header pins (2.54mm pitch).

[https://www.amazon.ca/DAOKI-2-54mm-Female-Connector-Arduino/dp/B019WOPOHI/ref=sr\\_1\\_2\\_sspx](https://www.amazon.ca/DAOKI-2-54mm-Female-Connector-Arduino/dp/B019WOPOHI/ref=sr_1_2_sspx)

Variably sized heat shrink - [https://www.amazon.ca/730pcs-Shrink-Electrical-Storage-Portable/dp/B09XXG45Q7/ref=sr\\_1\\_1\\_sspx](https://www.amazon.ca/730pcs-Shrink-Electrical-Storage-Portable/dp/B09XXG45Q7/ref=sr_1_1_sspx)

1x 120/240VAC to 12VDC Transformer, 4A (wall plug included but detachable) - [https://www.amazon.ca/COOLM-Transformer-Doorbell-100-240V-5-5x2-5mm/dp/B07D5BX22W/ref=sr\\_1\\_2\\_sspx](https://www.amazon.ca/COOLM-Transformer-Doorbell-100-240V-5-5x2-5mm/dp/B07D5BX22W/ref=sr_1_2_sspx)

4x 0.25in Square Neodymium Magnet (only the shape is important) - <https://www.sparkfun.com/products/8643>

35x M3x0.5, 6mm Long Pan Head Screws – I replaced most M2.5's with M3's. - [https://www.amazon.ca/Glarks-230Pcs-Stainless-Button-Assortment/dp/B01J7NM9JA/ref=sr\\_1\\_2\\_sspx](https://www.amazon.ca/Glarks-230Pcs-Stainless-Button-Assortment/dp/B01J7NM9JA/ref=sr_1_2_sspx)

1x M5x0.8, 10-15mm Long Socket Cap Screw (hopefully you can source 1x this instead of buying a whole kit) - [https://www.amazon.ca/Glarks-150Pcs-Stainless-Button-Assortment/dp/B01J9865L6/ref=sr\\_1\\_8](https://www.amazon.ca/Glarks-150Pcs-Stainless-Button-Assortment/dp/B01J9865L6/ref=sr_1_8)

Optional – 4.7μF electrolytic capacitor (see extra slide at the end). - [https://www.amazon.ca/Electrolytic-Capacitors-Appliances-Communication-Electronic/dp/B086VLGRR2/ref=sr\\_1\\_7](https://www.amazon.ca/Electrolytic-Capacitors-Appliances-Communication-Electronic/dp/B086VLGRR2/ref=sr_1_7)

# CABLES TO MAKE



DC motor



Power supply



Power button

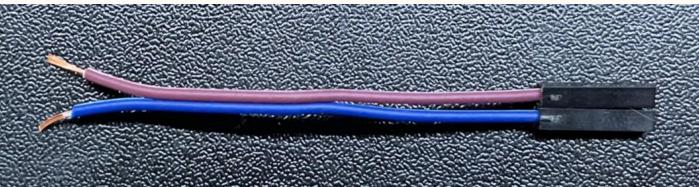


Encoder/button



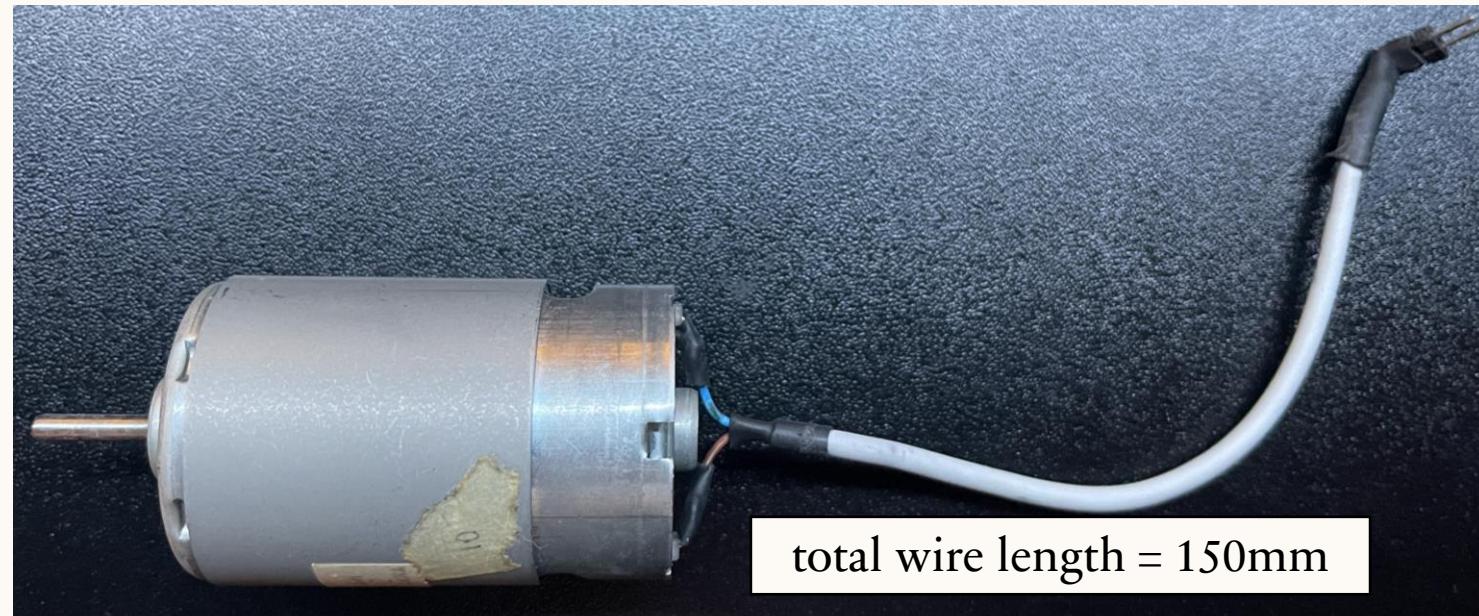
LCD – 4x female - female header  
(150mm unmodified)

Motor driver cables



# CABLES TO MAKE – DC MOTOR

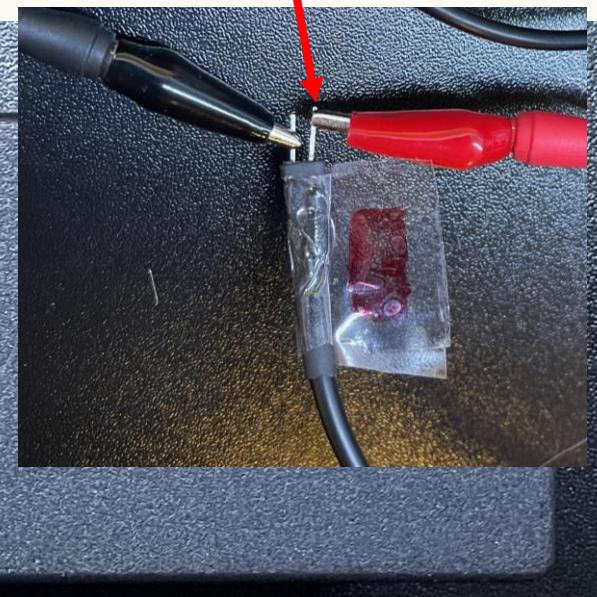
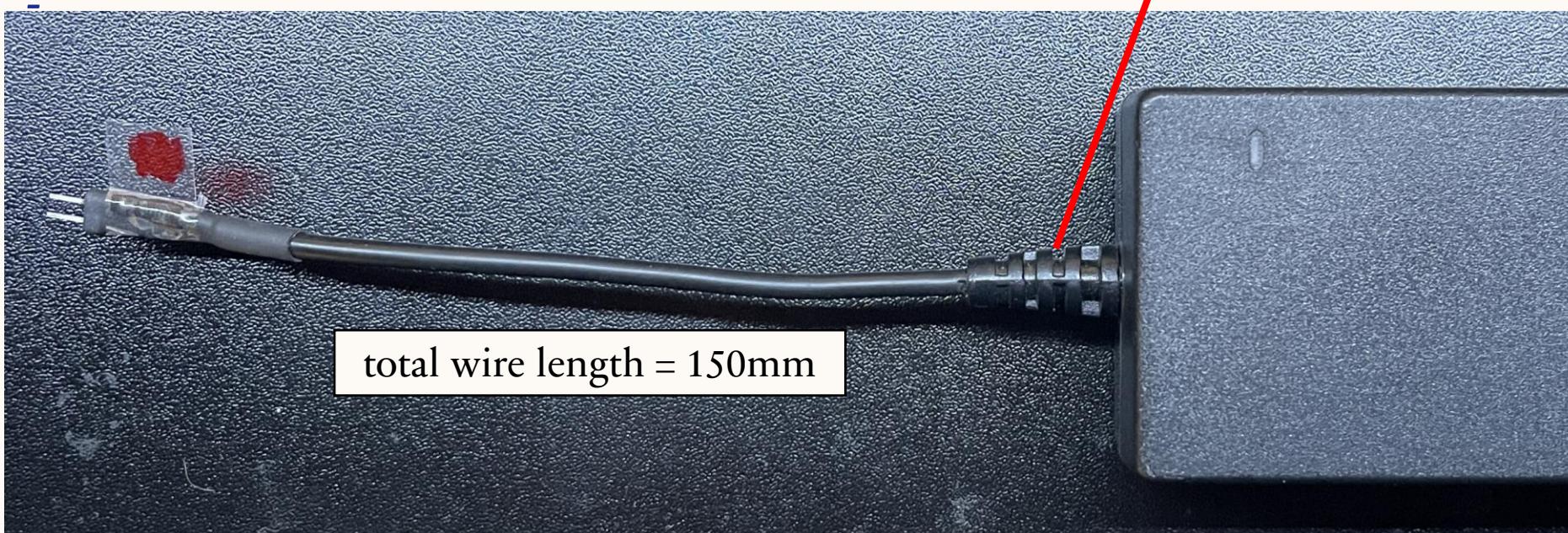
- Heat shrink all connections and keep tight to motor
- Be consistent with coloring (positive terminal with red dot = BLUE wire)
- Mark positive side on cable end with tape/sharpie
- Bend pins to one side to make final installation easier and maintain the same driving polarity



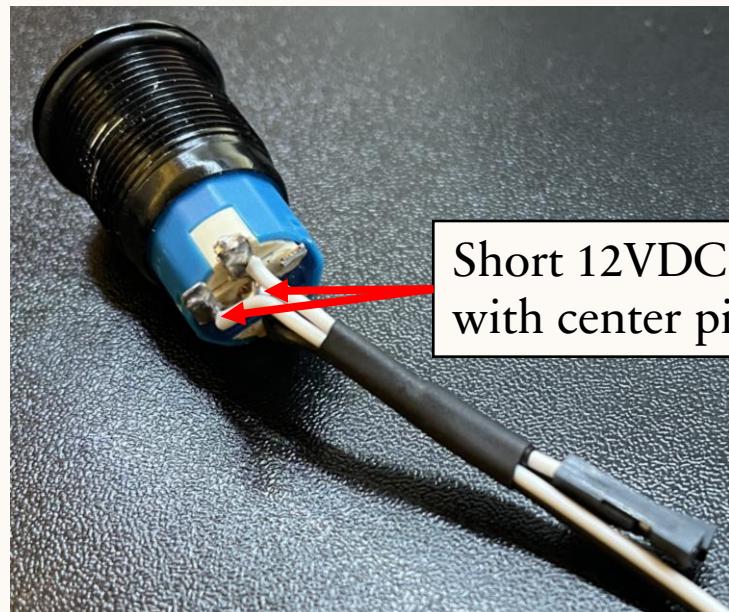
total wire length = 150mm

# CABLES TO MAKE – POWER SUPPLY

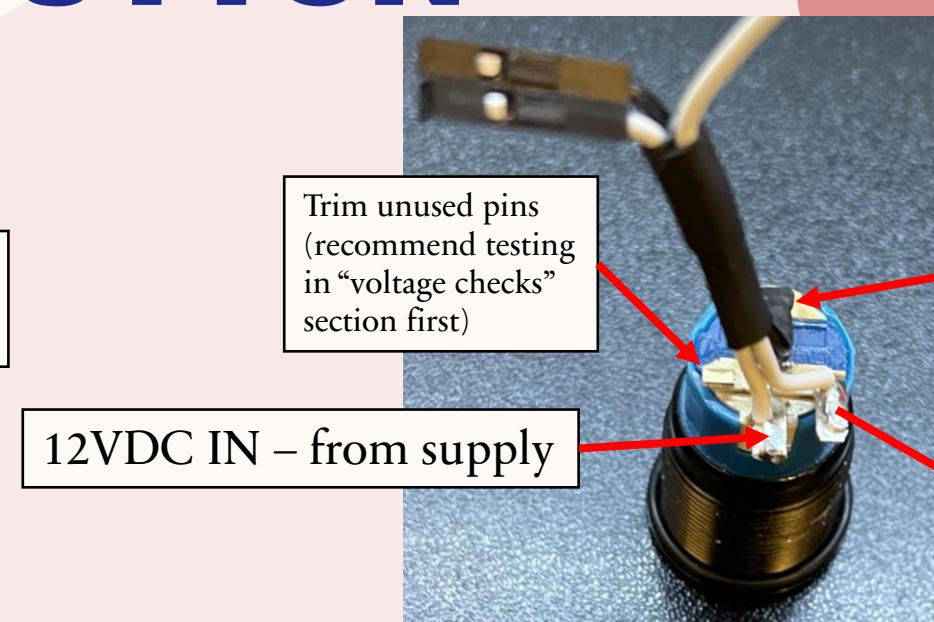
- 2x male header soldered onto transformer output (12V) line
- Carefully trim off strain relief
- verify +12VDC with multimeter and mark +12VDC side with tape and red sharpie



# CABLES TO MAKE – POWER BUTTON



Short 12VDC IN  
with center pin



Trim unused pins  
(recommend testing  
in “voltage checks”  
section first)

12VDC IN – from supply

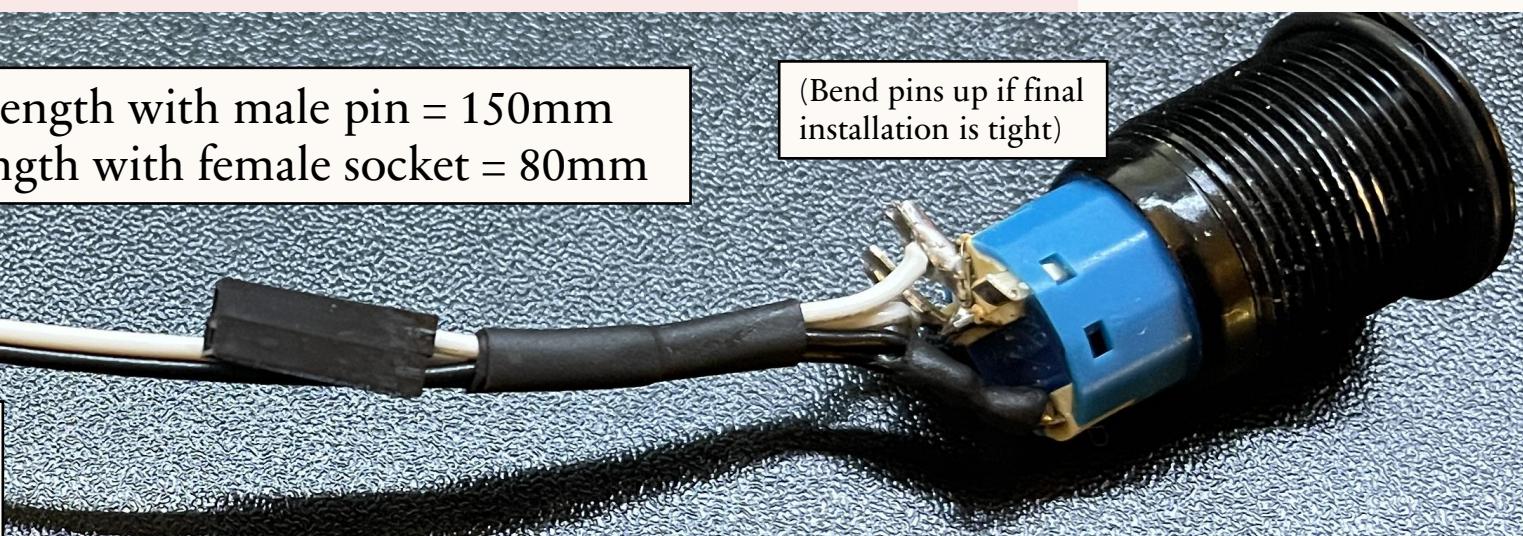
Black “GND” wires together

12VDC OUT – to motor controller

(Bend pins up if final  
installation is tight)

total length with male pin = 150mm  
total length with female socket = 80mm

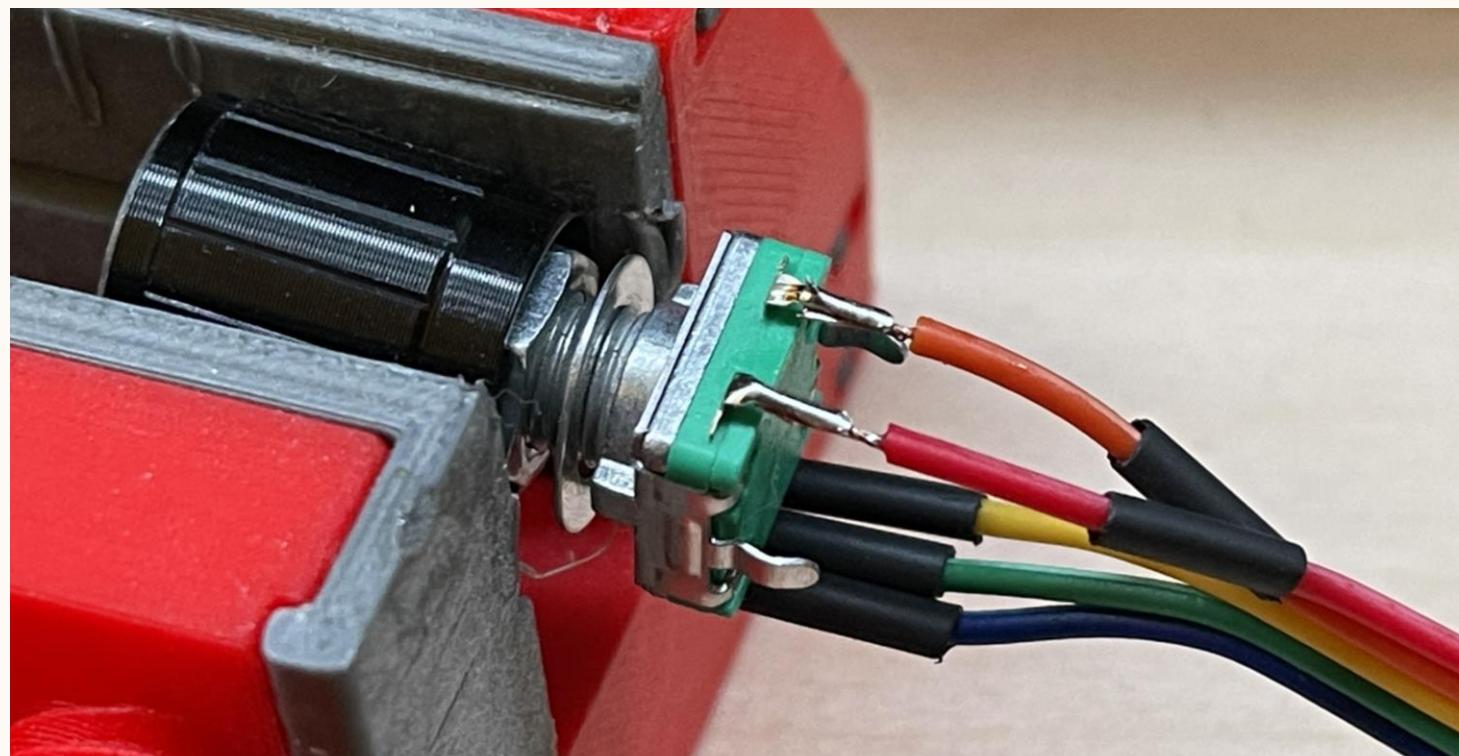
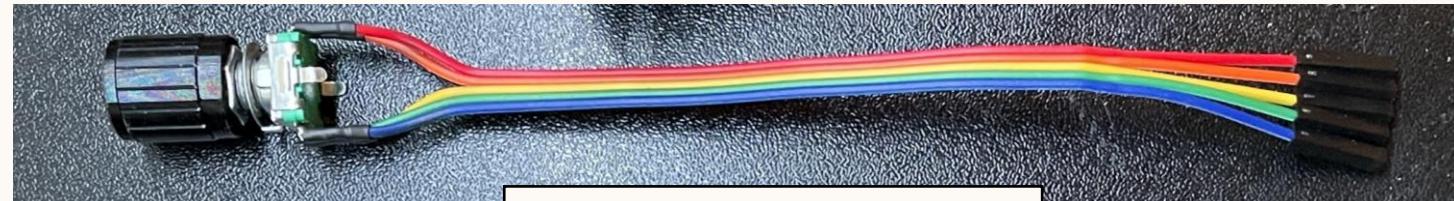
use white and black colours consistently  
(white is 12V and black is GND)



# CABLES TO MAKE – ENCODER/BUTTON

- 1 – BLUE – CH\_B Encoder – D2
- 2 – GREEN – GND
- 3 – YELLOW – CH\_A Encoder – D3
- 4 – ORANGE – Button – D4
- 5 – RED – GND

- Place 10mm of heat shrink over each pin



# CABLES TO MAKE - MOTOR DRIVER

1 – PURPLE – OUT4 / OUT1

2 – BLUE – OUT3 / OUT2

1 – YELLOW – ENA

2 – GREEN – IN1

3 – BLUE – IN2

4 – PURPLE – IN3

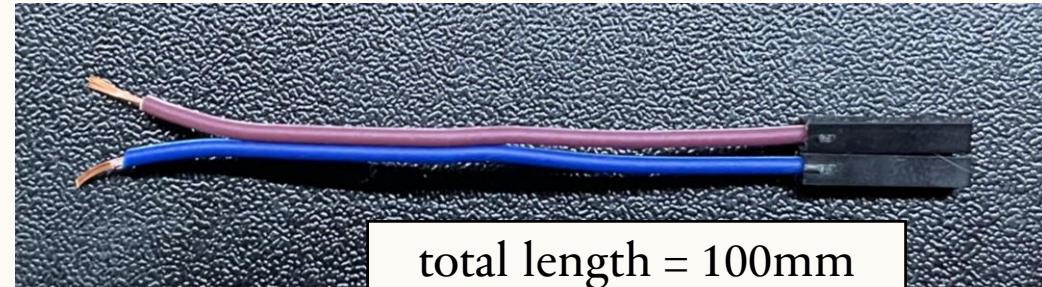
5 – GREY – IN4

6 – WHITE – ENB

1 – BROWN – +5VDC

2 – BLACK – GND

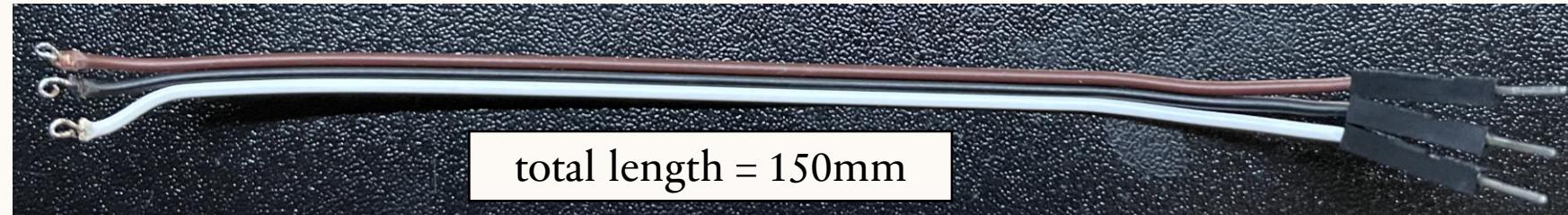
3 – WHITE – +12VDC



total length = 100mm



total length = 100mm

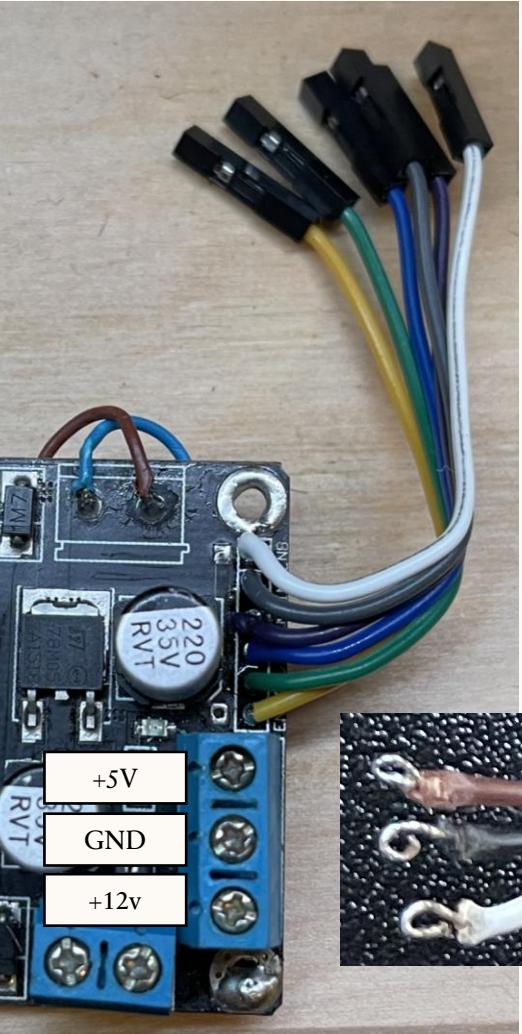
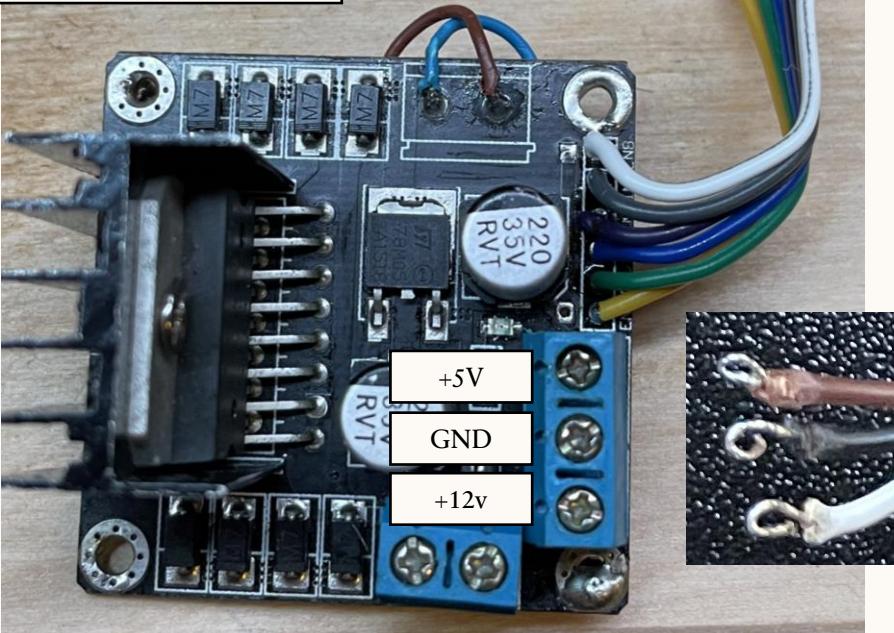


total length = 150mm

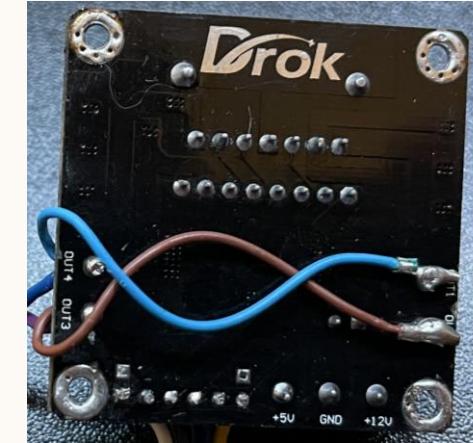
# CABLES TO MAKE MOTOR DRIVER

- 1 - YELLOW - ENA
- 2 - GREEN - IN1
- 3 - BLUE - IN2
- 4 - PURPLE - IN3
- 5 - GREY - IN4
- 6 - WHITE - ENB

You can solder to pins but jumpers are too tall. I removed pins and soldered to board holes



Solder OUT4 to OUT1, and OUT3 to OUT2 on bottom of board. Can jump to screw terminals but hard to reach once installed if cable slips out



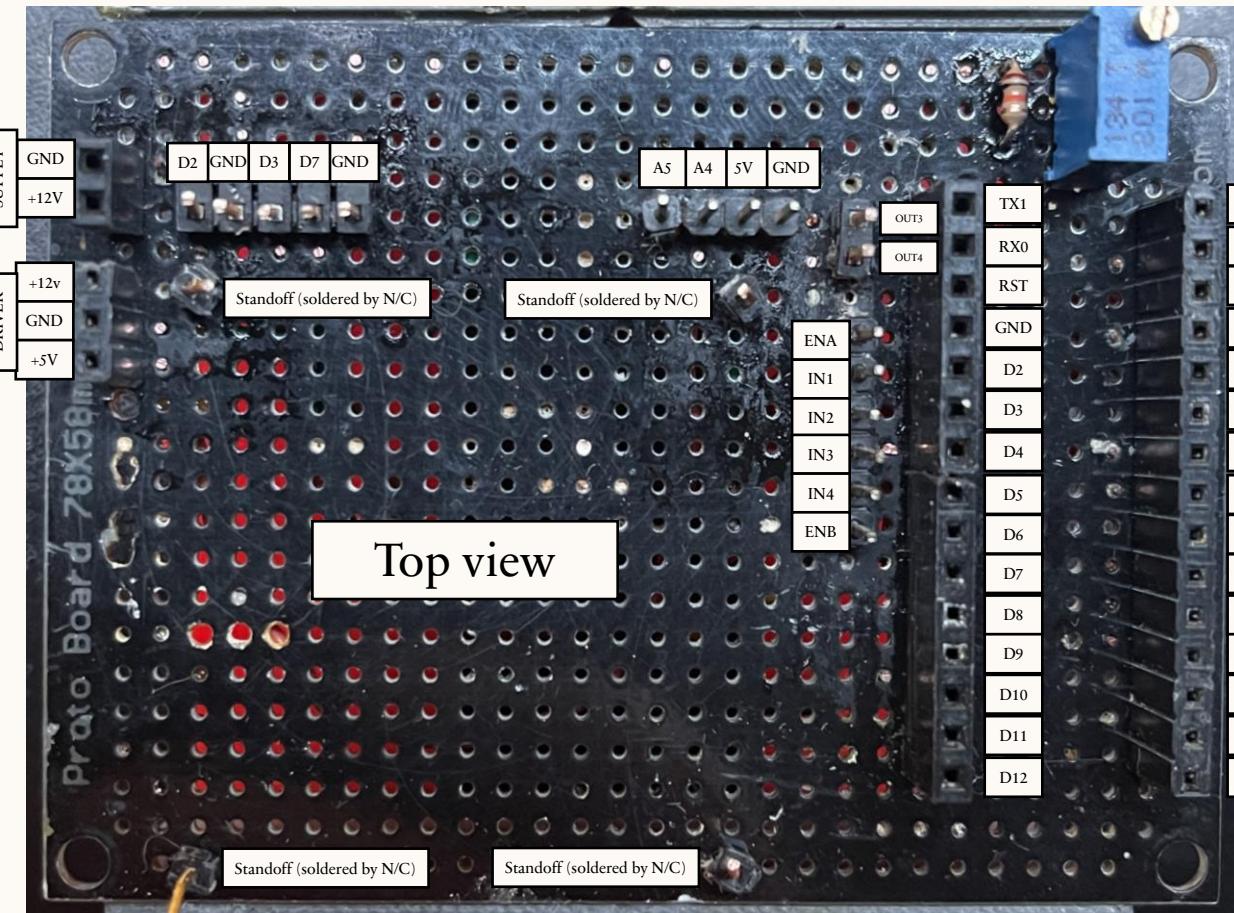
- 1 - BROWN - +5VDC
- 2 - BLACK - GND
- 3 - WHITE - +12VDC

- 1 - PURPLE - OUT4 / OUT1
- 2 - BLUE - OUT3 / OUT2

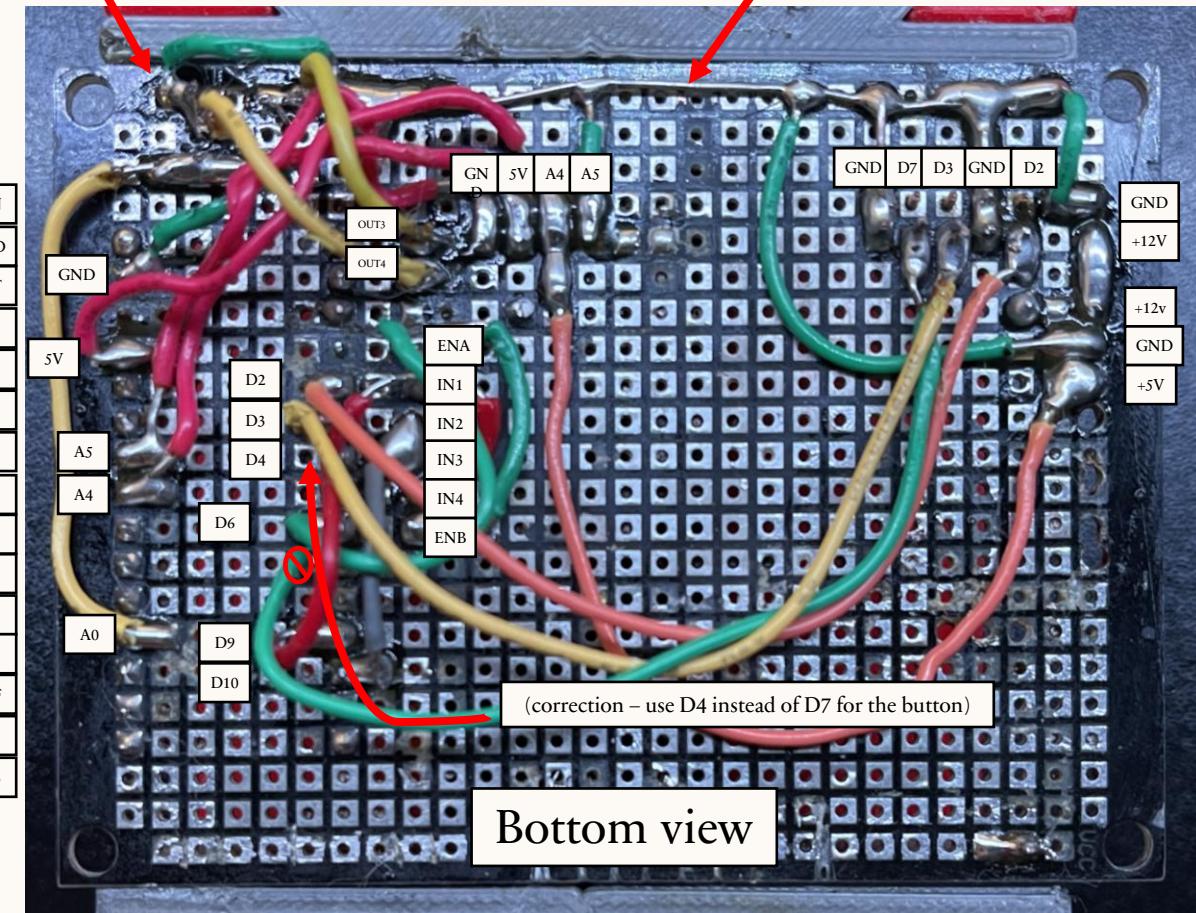
Can solder to board or use screw terminal (I removed mine for another project). Careful not to work joints after

# HEADER AND JUMPER SOLDERING

- Verify position/orientation on board before soldering
  - Refer to Control Schematic V2 from Thingiverse
- Clean all joints with alcohol and brush
- Trim leads coming out of the top after cleanup
- Verify connections with continuity test (for help - Fluke)

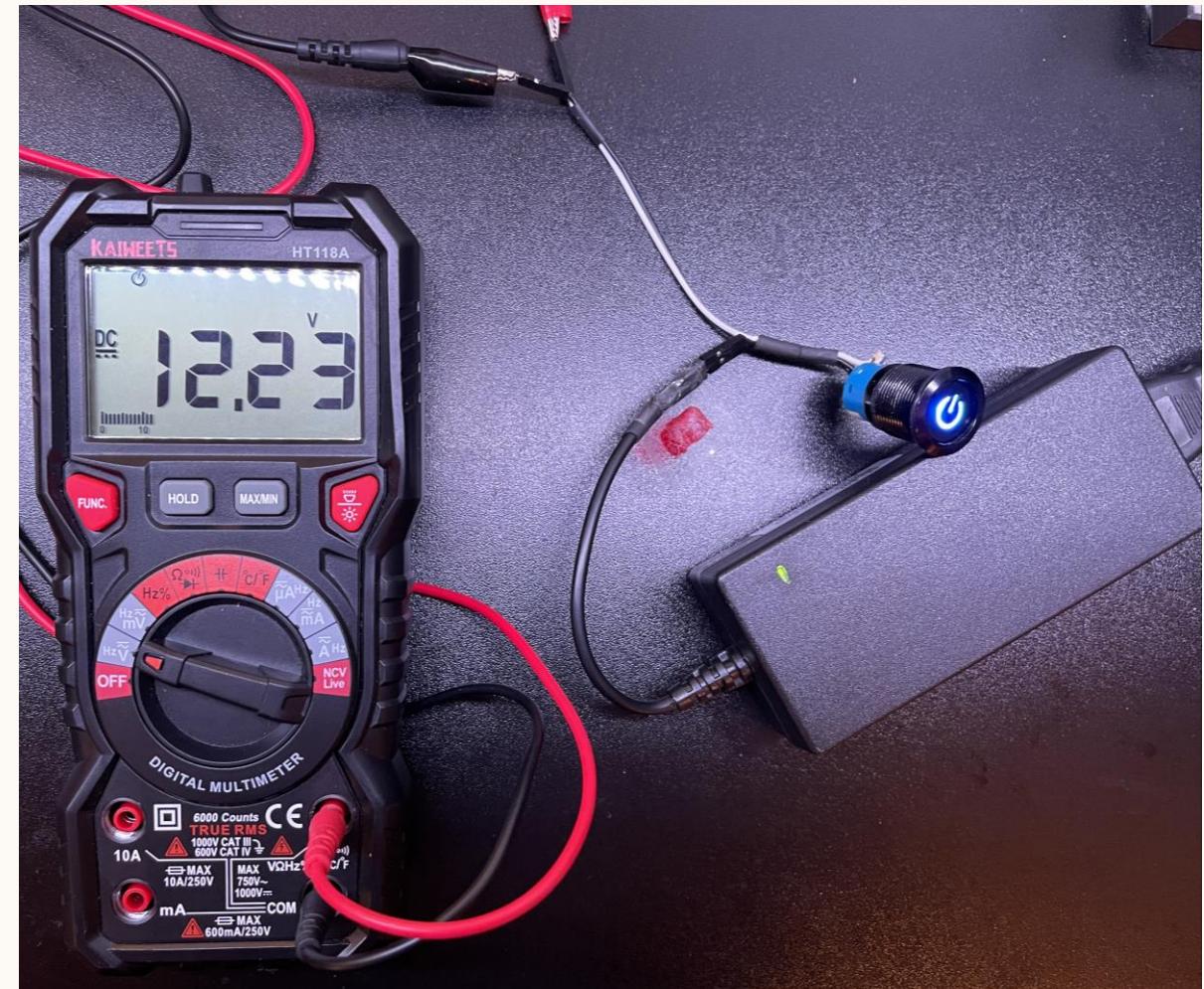
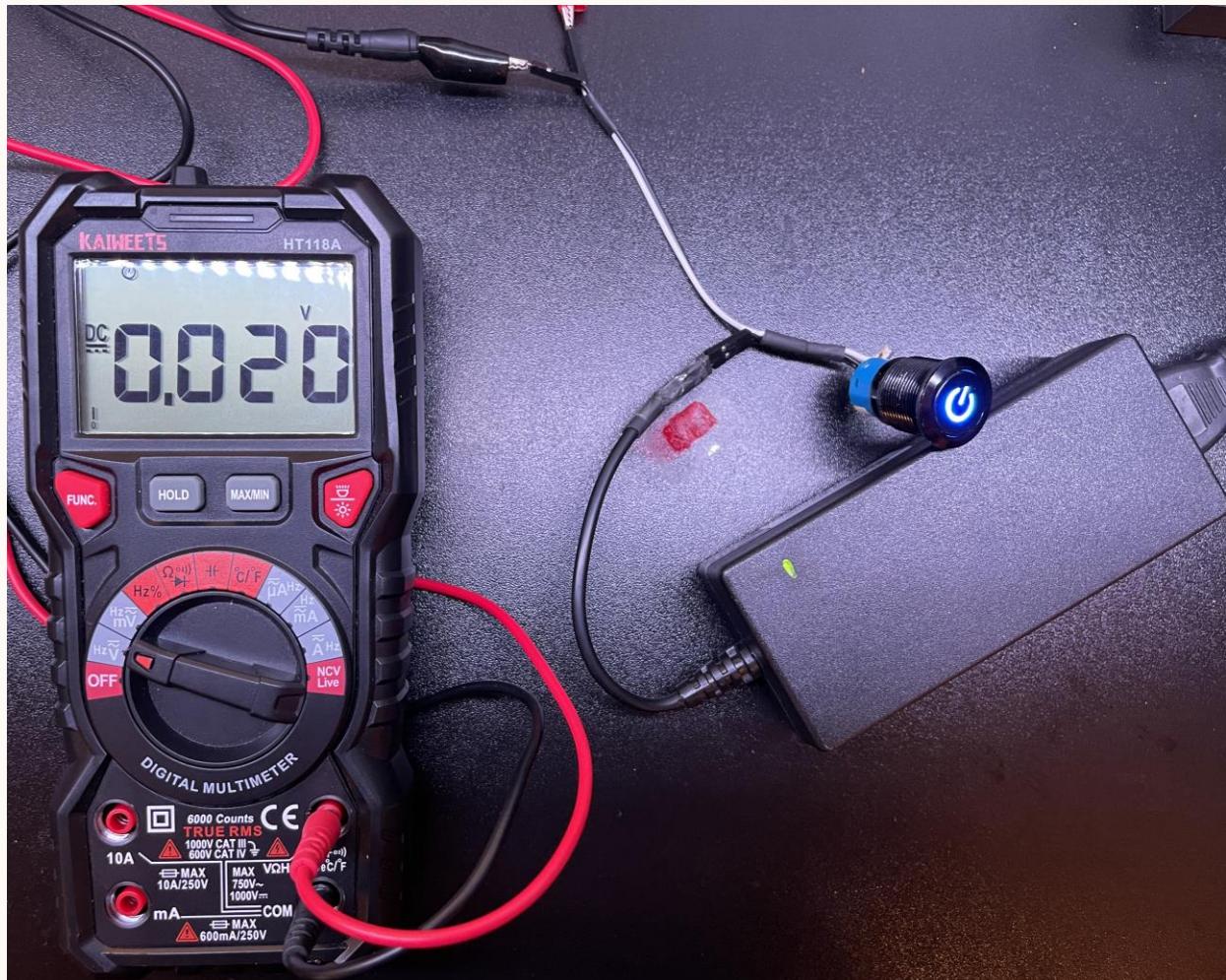


use knife to cut between traces on outer rails.  
**Sometimes the outer rows are all connected**



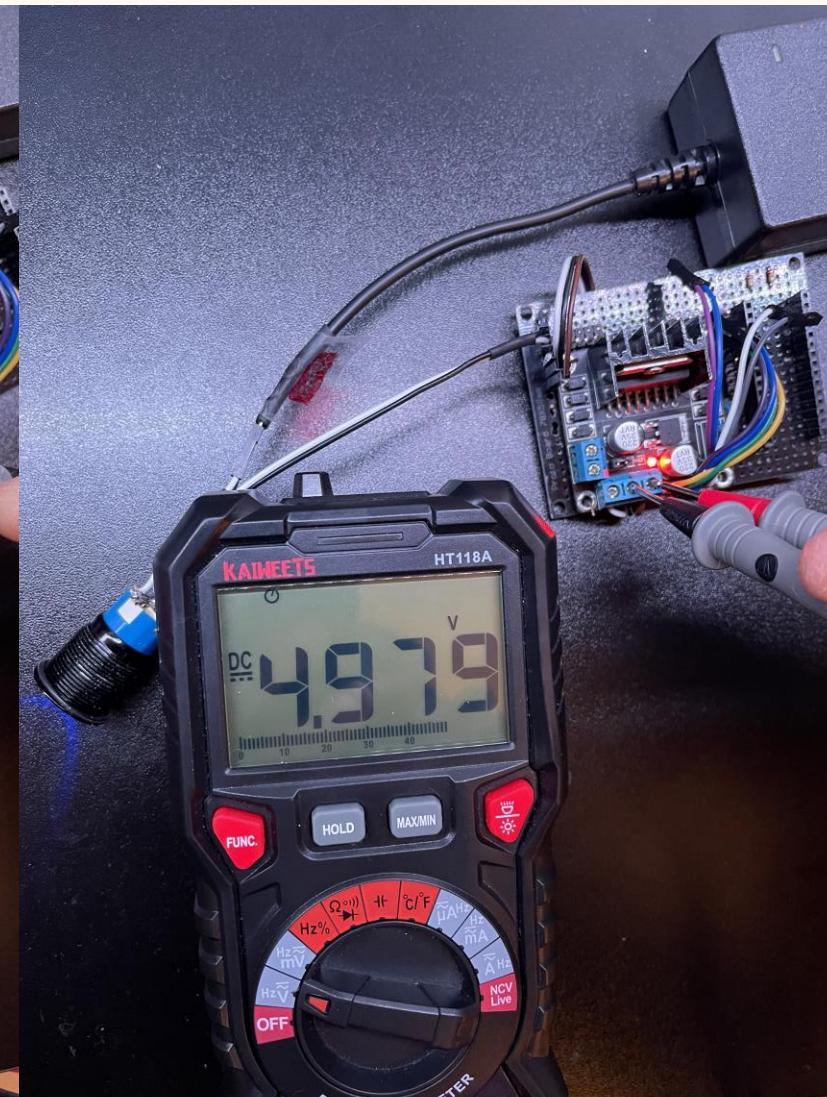
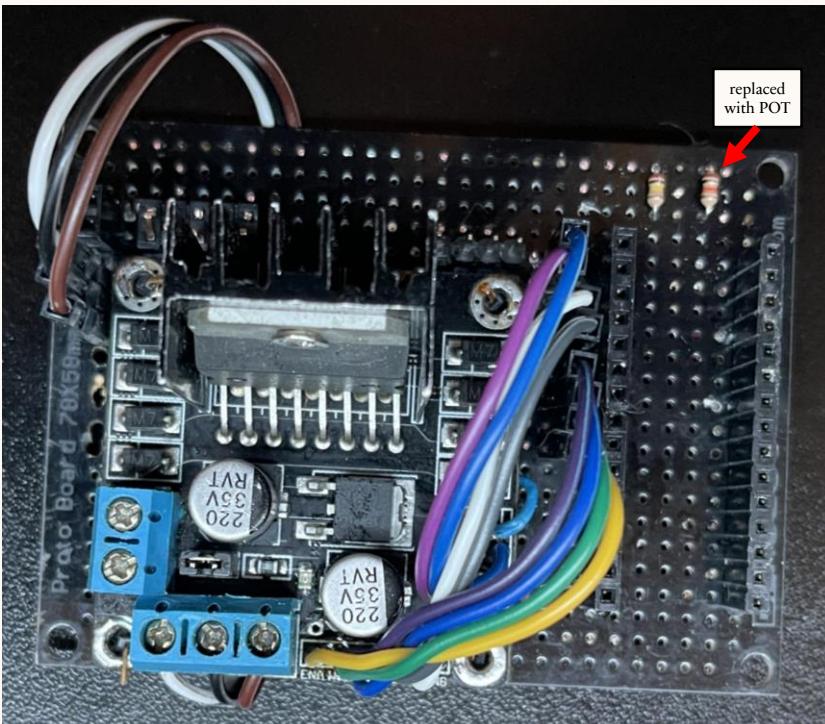
# VOLTAGE CHECK - POWER BUTTON

- Plug in power button (white wire to +12VDC).
  - with button unpressed (circuit open), button should illuminate but voltage should be ~0VDC
  - with button depressed (circuit closed), button should stay illuminated and voltage should go to ~12VDC



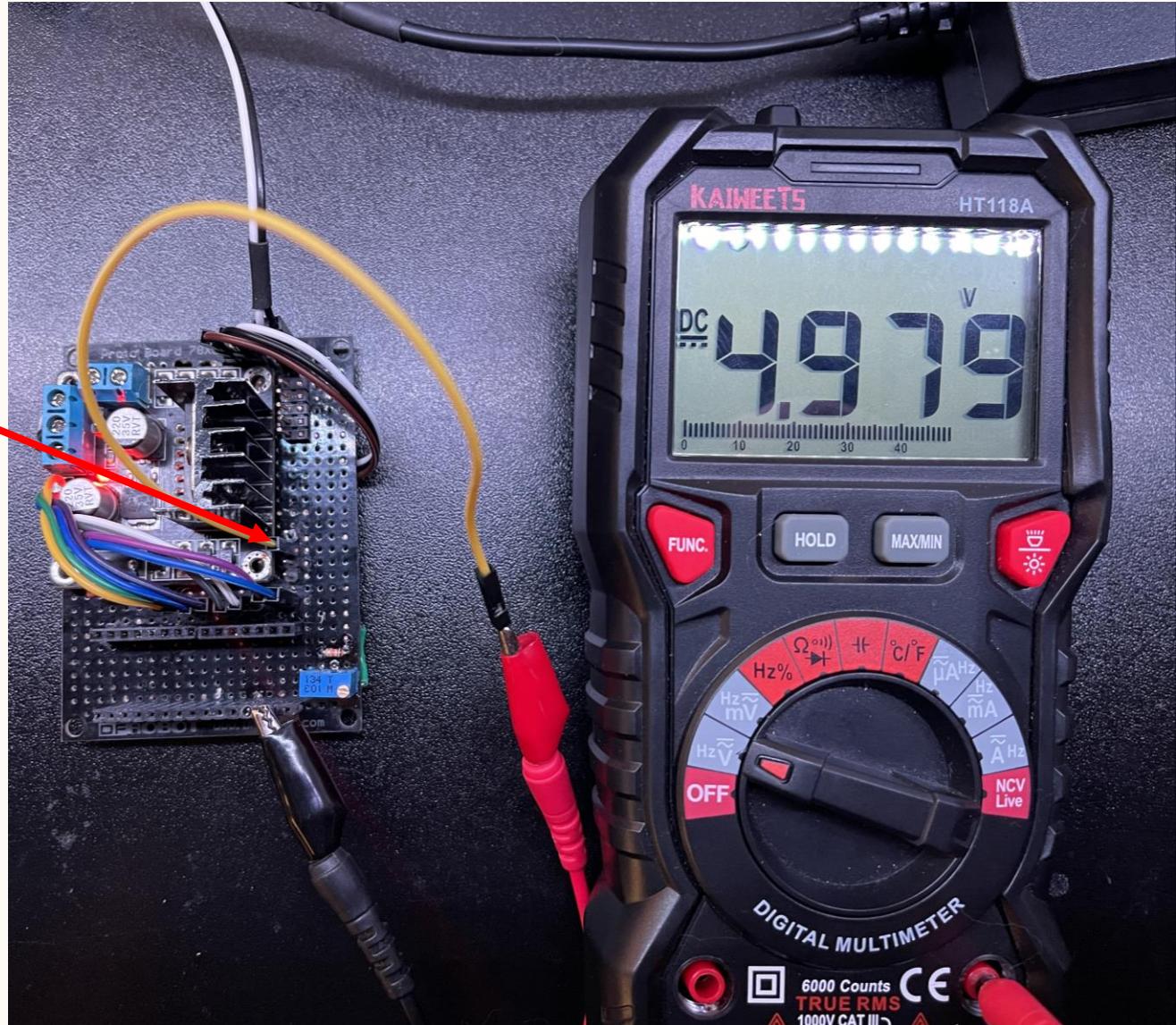
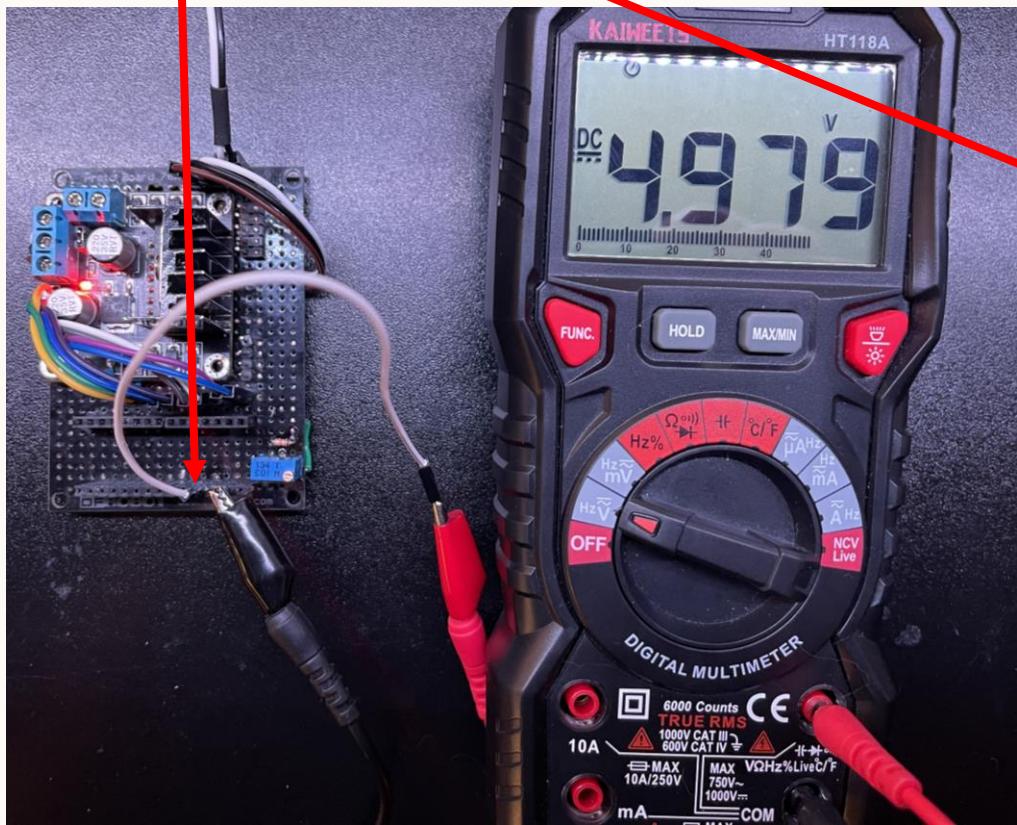
# VOLTAGE CHECK - MOTOR DRIVER

- Mount motor driver to protoboard assembly (bend mounting pins so it is easy to remove later if needed)
- With motor driver power cable plugged in, and power button ON, LEDs on motor driver should illuminate
  - check +12VDC and +5VDC
  - using power button should de-energize entire board



# VOLTAGE CHECK - 5V SUPPLIES

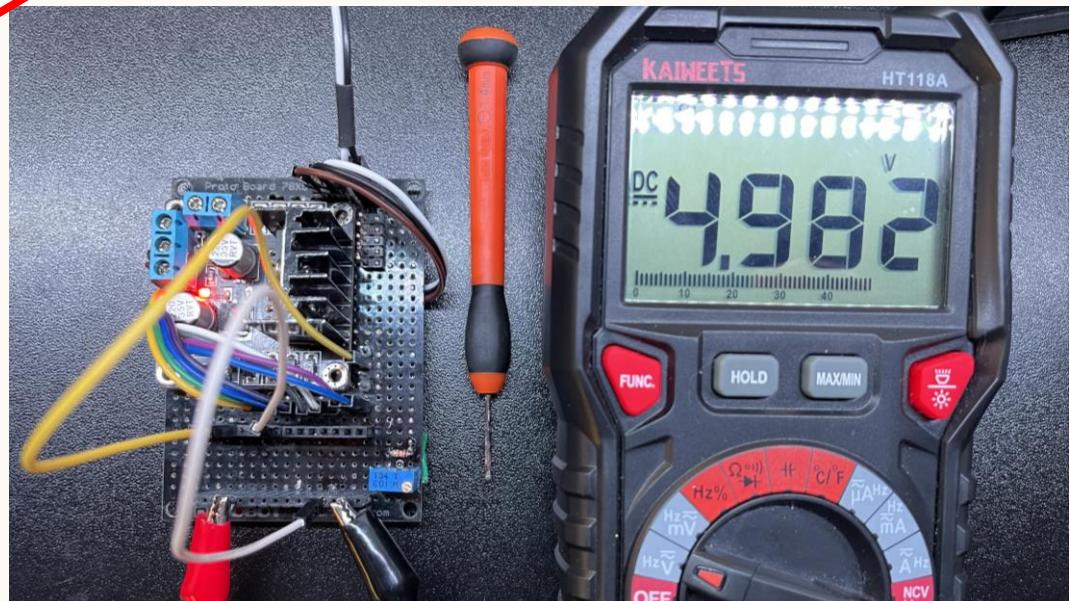
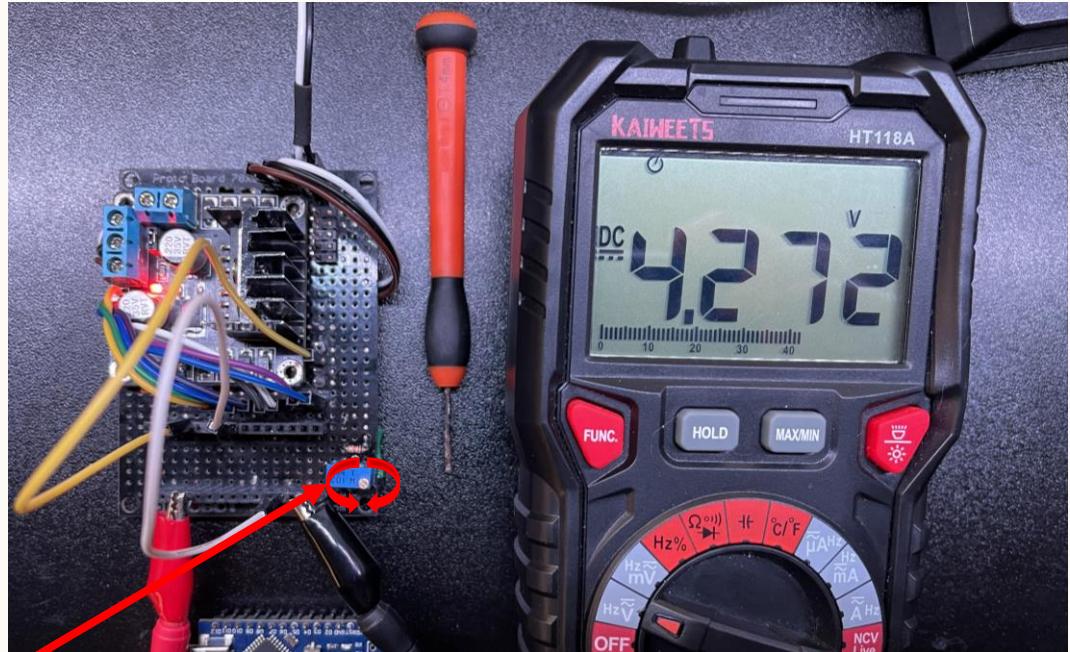
- Using jumpers, measure power pins with respect to the GND:
  - the 5V Arduino pin
  - the 5V LCD pin



- Each should be approximately 5V

# VOLTAGE CHECK - ANALOG INPUT

- Motor speed is measured by measuring the voltage across the motor terminals.
  - A high voltage indicates a high speed (without considering current)
  - The Arduino pins **ARE ONLY 5V TOLERANT**, this is why we have two resistors to split the voltage
  - Adjusting the potentiometer will bring the voltage measured across A0 and GND to a safer level
- Using jumpers, power:
  - the D9 pin with 5V from the LCD header
  - the D6 pin with 5V from the Arduino 5V socket
- Adjust the potentiometer with a screwdriver until A0 pin reads at least  $\leq 5\text{VDC}$ , but try to match what you measured previously for Vs ( $\sim 4.979\text{V}$  for me)
  - If you can only get between 5 and 12V, your resistors need to be switched with each other. If they aren't swapped, the Arduino will be damaged
  - If you can't get a reading, recheck your soldering work with a continuity check and verify there are no shorts or ground loops.



# ARDUINO PROGRAMMING

- Download Arduino IDE (I use version 1.8.16) [here](#)
  - Any version should be fine, like the shown 1.8.19 version
  - \*\*Arduino forum and website are a great repository for help
- Go to GitHub directory and download sketch folder:
  - [https://github.com/nairck/TurbofanDriver/tree/main/Control\\_Sketch\\_V2](https://github.com/nairck/TurbofanDriver/tree/main/Control_Sketch_V2)
- Open Control\_Sketch.ino in the Arduino IDE
  - File > Open > 'Control\_Sketch.ino'
- You don't need to understand the code, but you should:
  - make sure you have the three libraries
    - Encoder.h
    - LiquidCrystal\_I2C.h
    - EEPROM.h
  - Download libraries through the IDE (if needed)
    - Tools > Manage Libraries > \*Search for these titles\*
  - Check and change the I2C address for the screen
    - File > Examples > Wire > i2c\_scanner
    - Will need to wire the Arduino and screen together
      - Use LCD female jumper cable and plug directly into Arduino pins
      - Program Arduino with i2c\_scanner sketch (follow tutorial)

Legacy IDE (1.8.X)

 Arduino IDE 1.8.19

The open-source Arduino Software (IDE) makes it easy to write code and upload it to the board. This software can be used with any Arduino board.

Refer to the [Getting Started](#) page for installation instructions.

SOURCE CODE

Active development of the Arduino software is [hosted by GitHub](#). See the instructions for [building the code](#). Latest release source code archives are available [here](#). The archives are PGP-signed so they can be verified using [this gpg key](#).

Control\_Sketch | Arduino 1.8.16

File Edit Sketch Tools Help

Control\_Sketch §

/\* TurboFan Driver

This program uses an L298N motor driver with a 12VDC motor.  
The 20x4 LCD displays motor speed, turbofan speed, and motor voltage.  
An encoder is used to control the motor speed.  
ON THE FIRST STARTUP: Press the button to set speed back to zero.  
Hold the button for 2 seconds to set the Maximum Fan RPM  
Hold the button for 5 seconds to reset the Maximum Fan RPM to uncapped.  
Maximum RPM set is remembered inside the program even after power down.

Visit <https://www.thingiverse.com/thing:4743929> for the project directory

Written and designed by Adam B Johnson  
in British Columbia, Canada  
V1 - 15 January 2021  
V2 - 19 November 2022

\*/

```
#define gearRatio 2.27          //fixed gear ratio

#include <Encoder.h>           //Might need to download this library. Tools > Manage Libraries > Search for 'Encoder'
#include <LiquidCrystal_I2C.h>   //Might also need to download this one in the same way.
#include <EEPROM.h>            //This should have been included when you installed Arduino IDE. No download needed

//##### Adjust these values if needed #####
#define chB 2                   //***pin B of the rotary encoder (channel B)
#define chA 3                   //***pin A of the rotary encoder (channel A)
#define pushButton 4             //***Button pin
#define motorPwm 6                //***PWM pin to motor controller
#define motorDir1 9               //***motor direction forward pin to driver
#define motorDir2 10              //***motor direction reverse pin to driver
#define voltageMeasurePin A0     //***Analog pin for motor voltage measurement
#define arduinoVoltage 4.98       //***Actual measured 5 volt pin from the arduino

float motorRPMperVolt = (4025 / 12);    //***DC motor max RPM (4025) divided by max voltage (12VDC. Measure both parameters and adjust
LiquidCrystal_I2C lcd(0x3F, 20, 4);      //***Adjust screen address if needed. Use File > Examples > Wire > i2c_scanner to acquire address and change 0x3F as needed.

//##### End of adjustable parameters #####

```

• (I have heard the replacement screen has a different address. This is normal for devices to have different addresses)

DOWNLOAD OPTIONS

Windows Win 7 and newer  
Windows ZIP file

Windows app Win 8.1 or 10 [Get it!](#)

Linux 32 bits  
Linux 64 bits

Linux ARM 32 bits  
Linux ARM 64 bits

Mac OS X 10.10 or newer

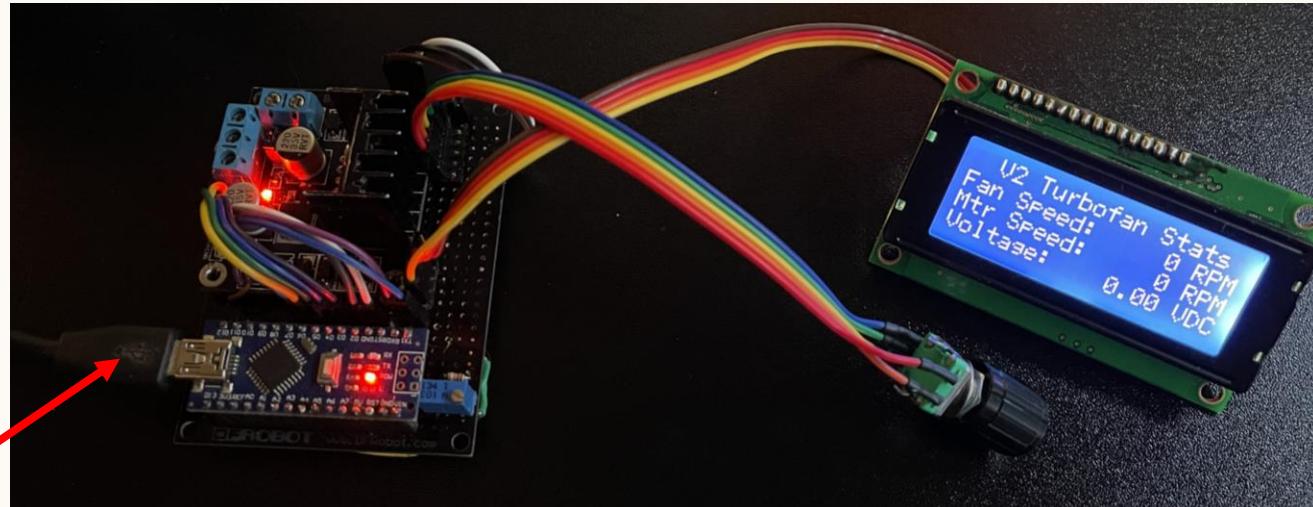
Release Notes

Checksums (sha512)

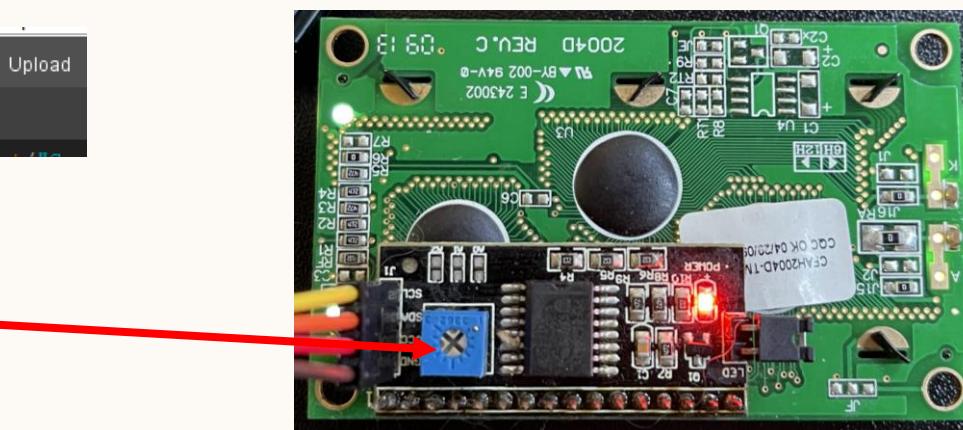
# ARDUINO PROGRAMMING AND SCREEN CONTRAST

- Select the correct board to program
  - Tools > Board: “\_\_” > Arduino AVR Boards > Arduino Nano
- Select the correct programming port
  - Tools > Port > COMX
    - Arduino must be plugged in with USB – see [here](#) for help

- Once you are happy with your connections, plug in all the devices and connectors **except the 12V supply or power switch.**

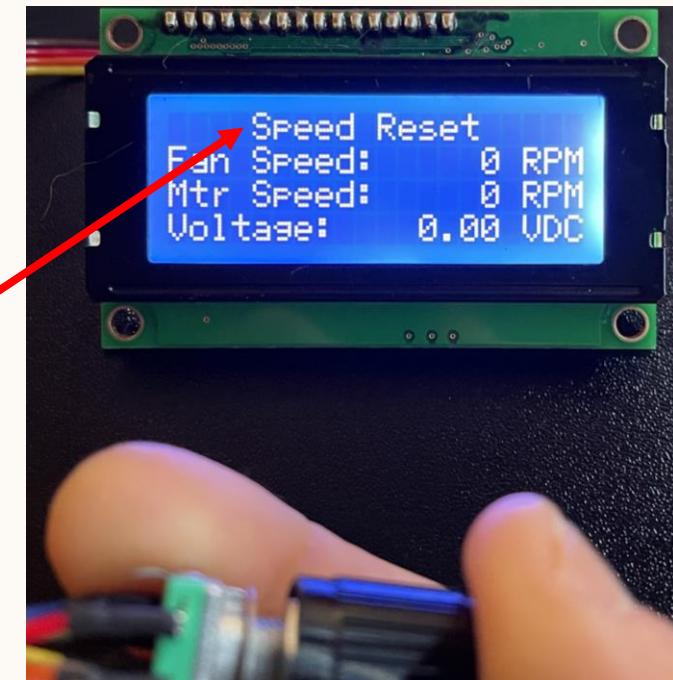


- Program the Arduino over USB
  - If it worked, you should see a startup screen for a few seconds, then the status screen!
- If the screen contrast is too low, you can adjust it on the I2C module potentiometer, located on the back of the LCD assembly
  - When we plug in the 12 VDC, it will likely need to adjust it again



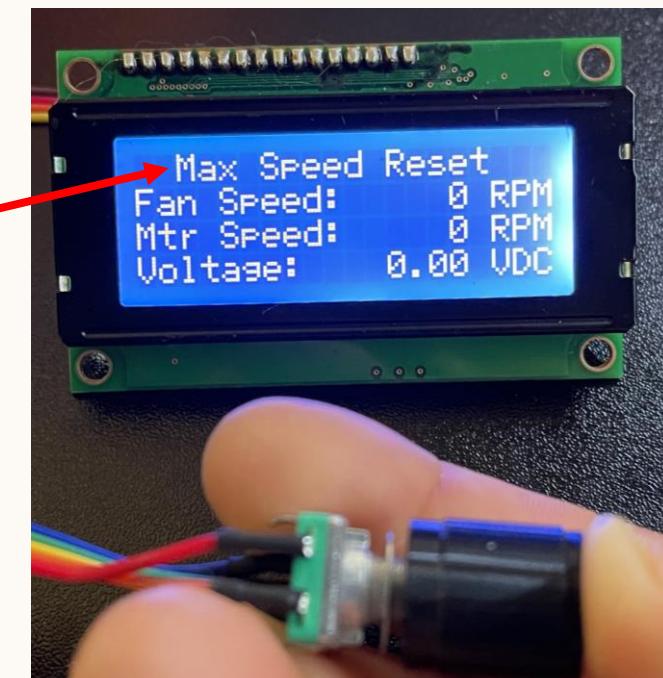
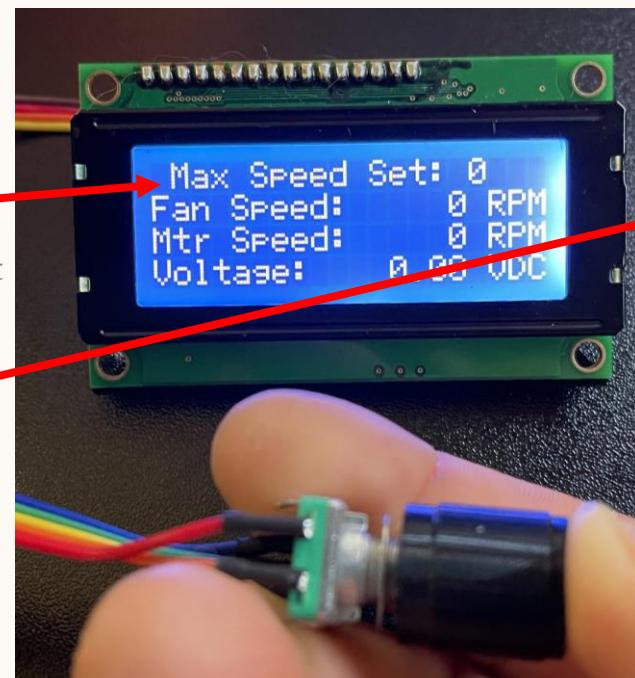
# FIRST TIME STARTUP AND SPEED RESET

- \*\* The code now detects a first-time startup, so this procedure isn't required, but is recommended just incase a zeroed EEPROM system isn't detected\*\*\*



\*\*With the system still only powered by USB\*\*

- Press the button for less than 0.5 seconds
  - This will zero the driving voltage, stopping the fan instantly
- Hold the encoder button for 2 seconds
  - This will set the maximum speed of the system so you can limit your system if you so choose
- Hold the encoder button for 5 seconds
  - This will reset the maximum speed



\*\*\*The motor driver will do nothing if the maximum speed is set to zero\*\*\*

# 12V CIRCUIT TEST

- If everything has gone well so far, we can test the system with the 12VDC supply

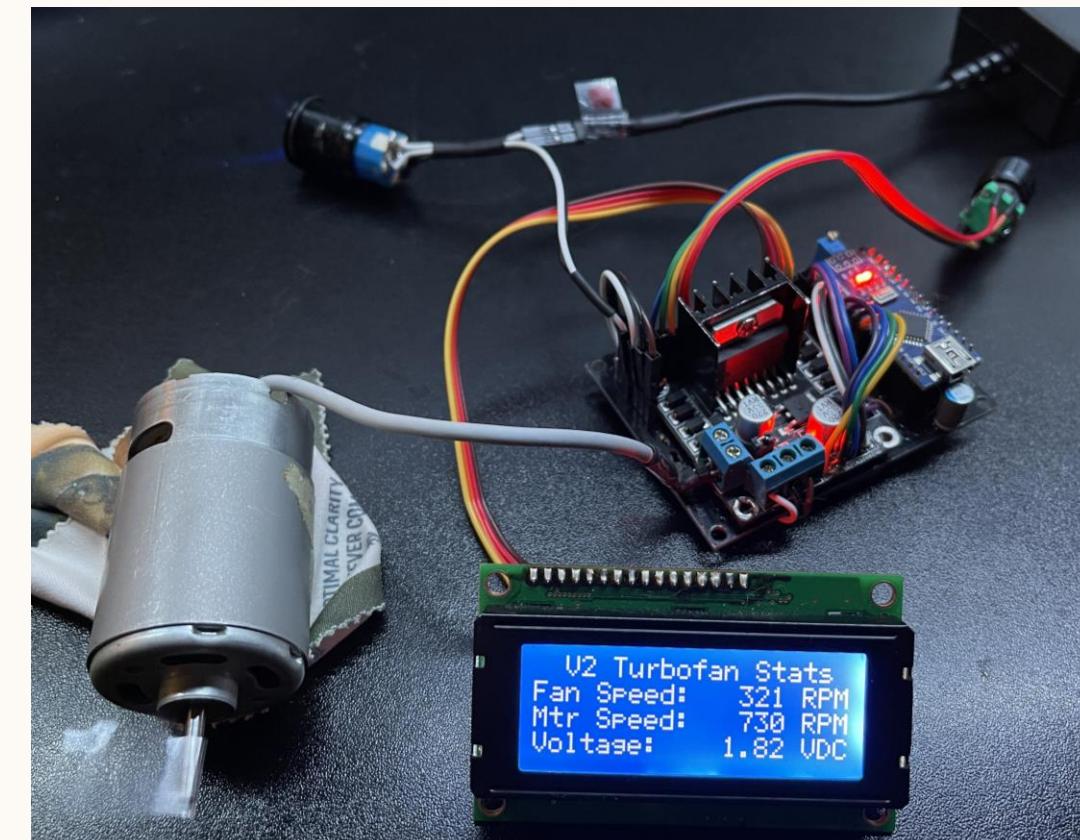
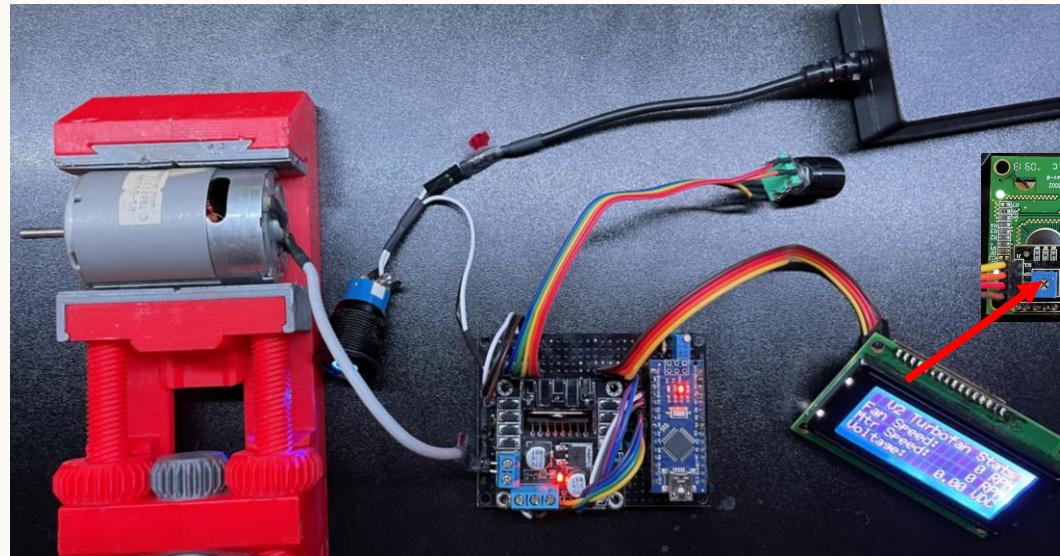
- Unplug the USB for programming
- Plug in the motor to the motor driver screw terminal
  - Secure it (without squishing) in a clamp or vice
- Plug in the 12VDC power supply and power button
- Adjust LCD contrast on back of LCD

- Slowly adjust encoder button and make the motor spin

- Hold it in hand so you get a feel for the adjustability
- Don't let motor rip away from electronics and pull on any wires
- If the system works as expected, resting on a cloth can be good enough

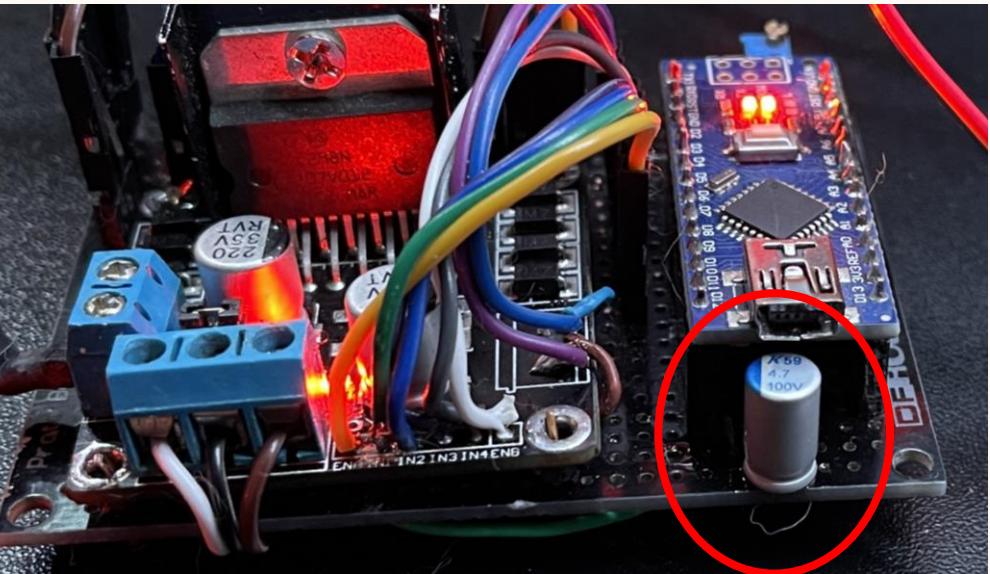
Great work, you're done!!! Everything is ready to install into the electronics bay.

One extra step (next slide) can help voltage reading noise if you have a capacitor kicking around.

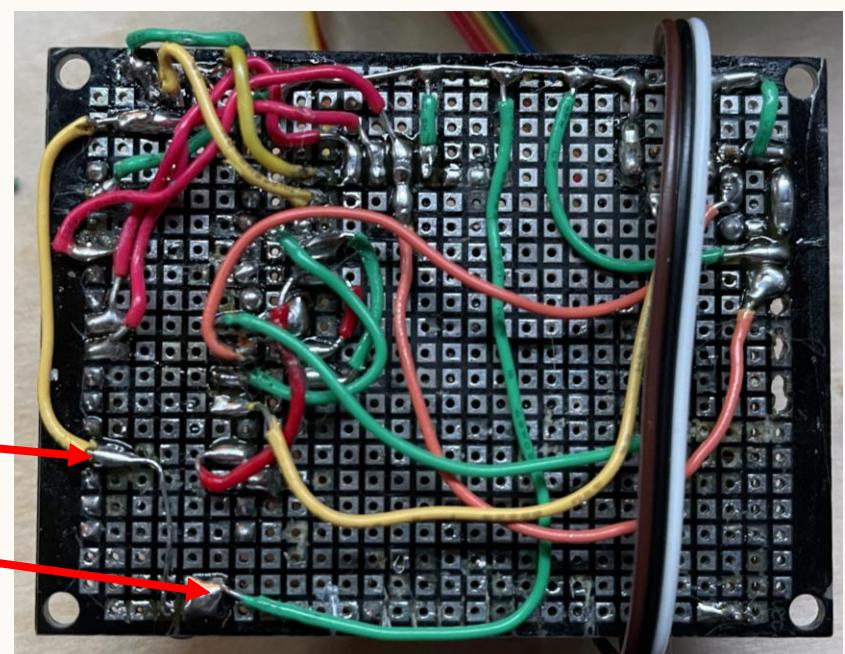


# SIGNAL CONDITIONING - EXTRA

- To filter out AC noise on the motor voltage reading, a  $4.7\mu\text{F}/100\text{V}$  electrolytic capacitor was used (which I had laying around)
  - Anything between  $0.1\mu\text{F}$  and  $100\mu\text{F}$  will be helpful
  - Other capacitor would also be okay (like non-polarized ceramic)
  - Make sure voltage rating is at least 10V
  - Make sure to get the polarity correct (if applicable)



- Solder to the breadboard near/under the USB port
  - Positive terminal connected to A0 (voltage read pin)
  - Negative terminal connected to GND
  - (make sure capacitor is connected physically close to the A0 pin)



# **THANK YOU, AND GREAT WORK!**

Continue the build with the YouTube assembly videos on my channel!

<https://www.youtube.com/channel/UCdyHOoZkerU78A9CjtsDdRQ>

Follow the project directory on Thingiverse for the most recent updates:

<https://www.thingiverse.com/thing:4743929>