

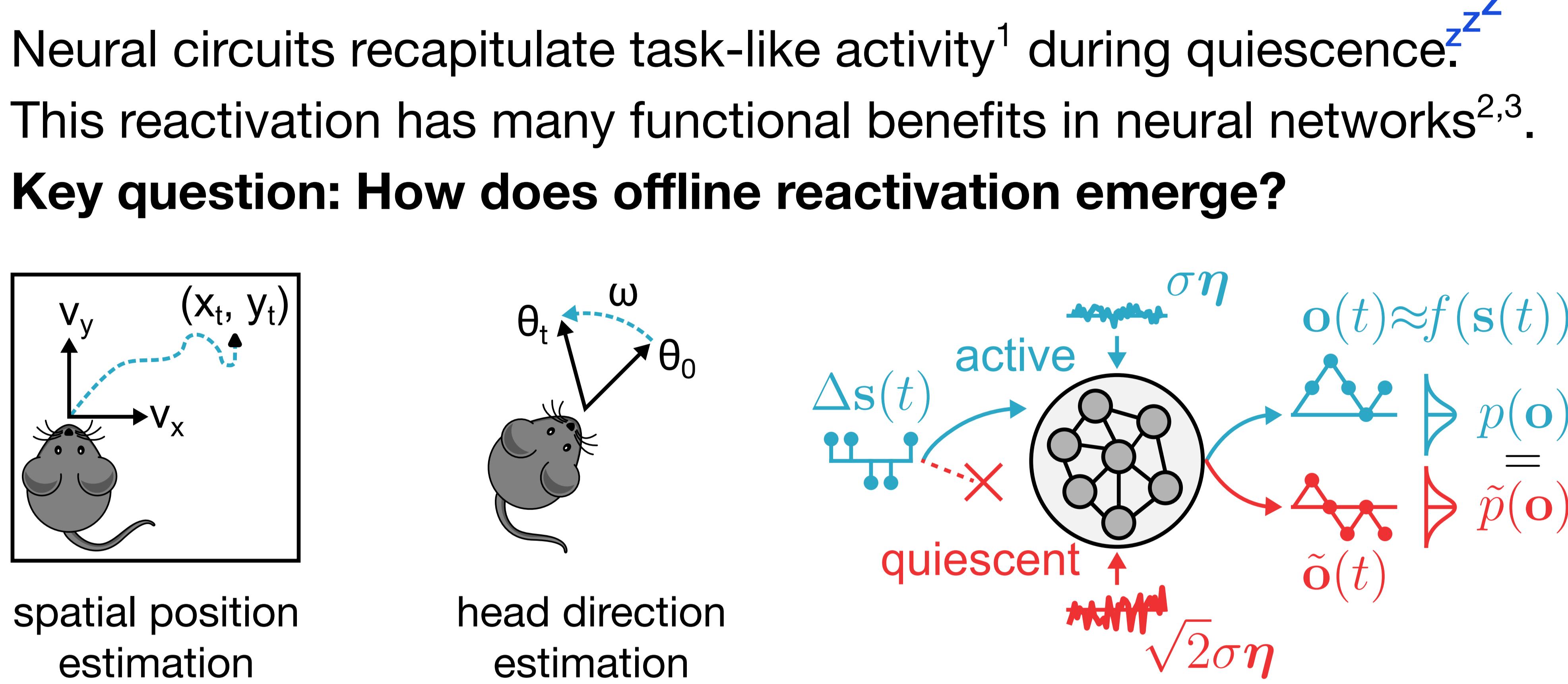
# Sufficient conditions for offline reactivation in recurrent neural networks

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## Introduction



We show that diffusive reactivation can emerge as a consequence of optimally encoding environmental variables in the presence of noise!

## Greedily Optimal Dynamics

**Conditions** – the recurrent neural network must:

1. Implement a **continuous-time dynamical system**.
2. Perform **noisy path integration** using change-based inputs.
3. Estimate state variables **near-optimally**.

$$\begin{aligned} \mathcal{L}(t + \Delta t) &= \mathbb{E}_\eta \left\| f(s(t + \Delta t)) - D(r(t) + \Delta r_1(t) + \Delta r_2(t) + \sigma \eta(t)) \right\|_2 \\ &\approx \mathbb{E}_\eta \left\| \frac{df(s(t))}{ds(t)} \Delta s(t) - D \Delta r_2(t) + f(s(t)) - D(r(t) + \Delta r_1(t) + \sigma \eta(t)) \right\|_2 \\ \mathcal{L}_{\text{upper}} &= \left\| \frac{df(s(t))}{ds(t)} \Delta s(t) - D \Delta r_2(t) \right\|_2 + \|D\|_2 \sqrt{\mathbb{E}_\eta \|\Delta r_1(t) + \sigma \eta(t)\|^2} \end{aligned}$$

The greedily optimal neural dynamics during the active phase are:

$$\Delta r^*(t) = \left[ \underbrace{D^\dagger \frac{df(s(t))}{ds(t)} \frac{ds(t)}{dt}}_{\text{state estimation}} + \underbrace{\sigma^2 \frac{d}{dr(t)} \log p(r(t))}_{\text{denoising}} \right] \Delta t + \sigma \eta(t)$$

## Emergent Offline Reactivation

The dynamics in the absence of inputs, i.e. during quiescence, are:

$$[\Delta \tilde{r}(t)] = \left[ \sigma^2 \frac{d}{dr(t)} \log p(r(t)) \right] \Delta t + \sqrt{2} \sigma \eta(t)$$

This is exactly **Langevin sampling** of  $p(r)$ !

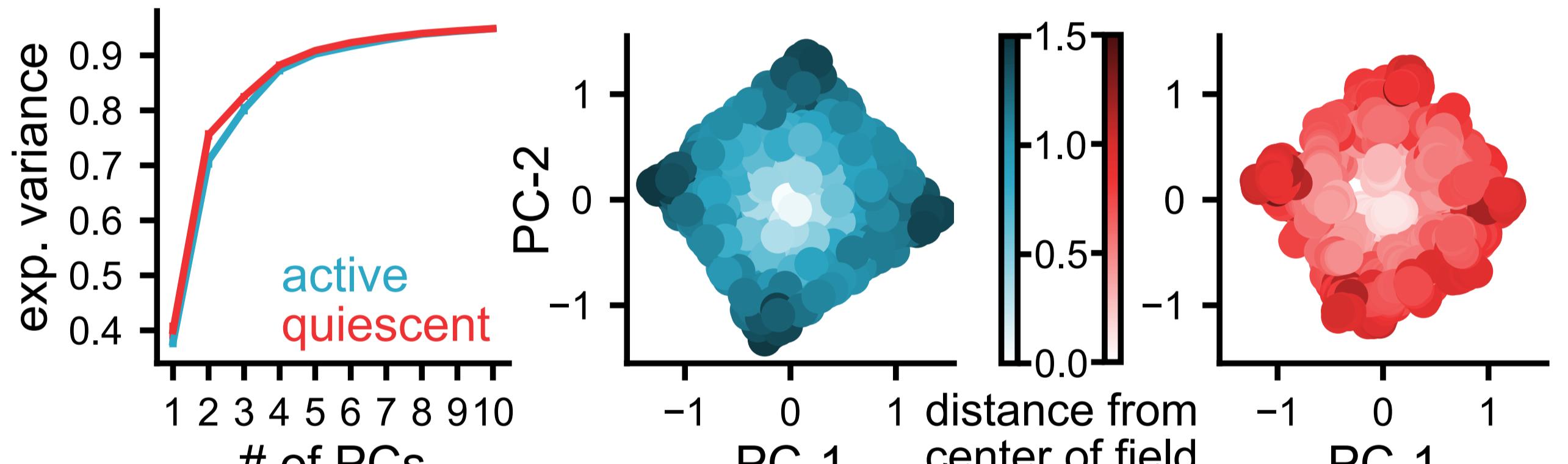
Doubled noise variance is not necessary for reactivation to emerge.

Diffusion along attractor manifold<sup>4</sup> → statistically faithful reactivation

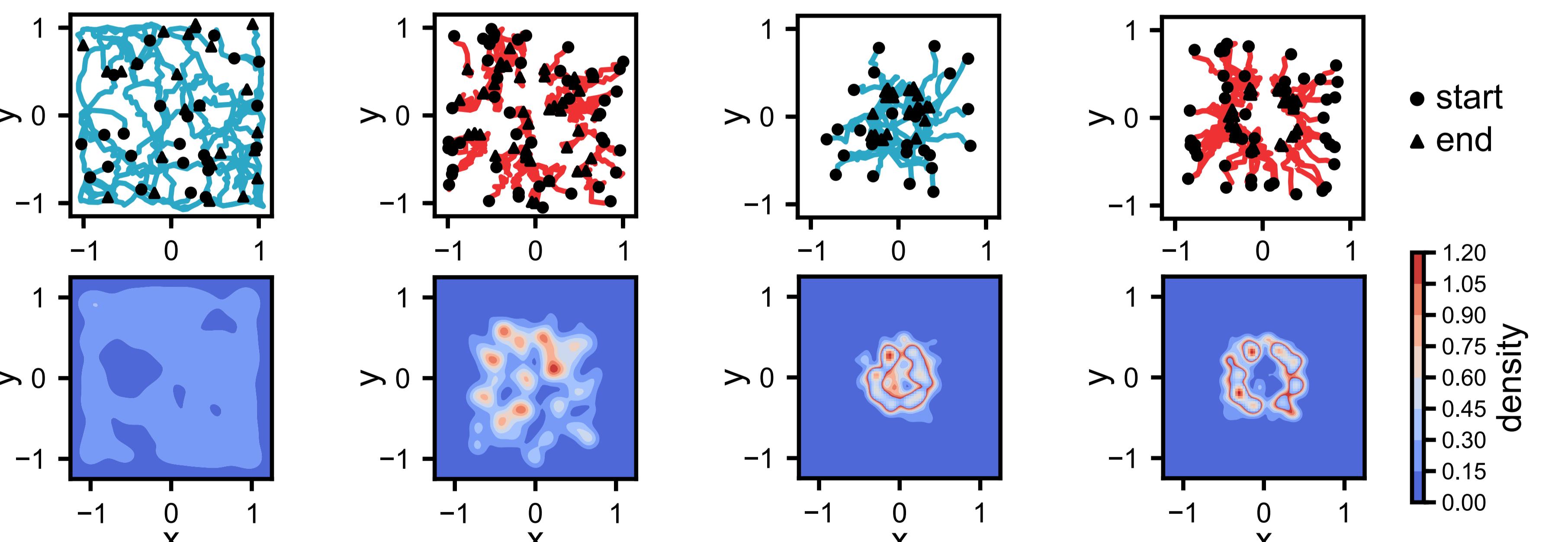
$$p(r) = \tilde{p}_{t \rightarrow \infty}(r) \Rightarrow p(o) = \tilde{p}_{t \rightarrow \infty}(o)$$

## Reactivation in Spatial Position Estimation

The neural activity manifold is low-D for both the active and quiescent phases.

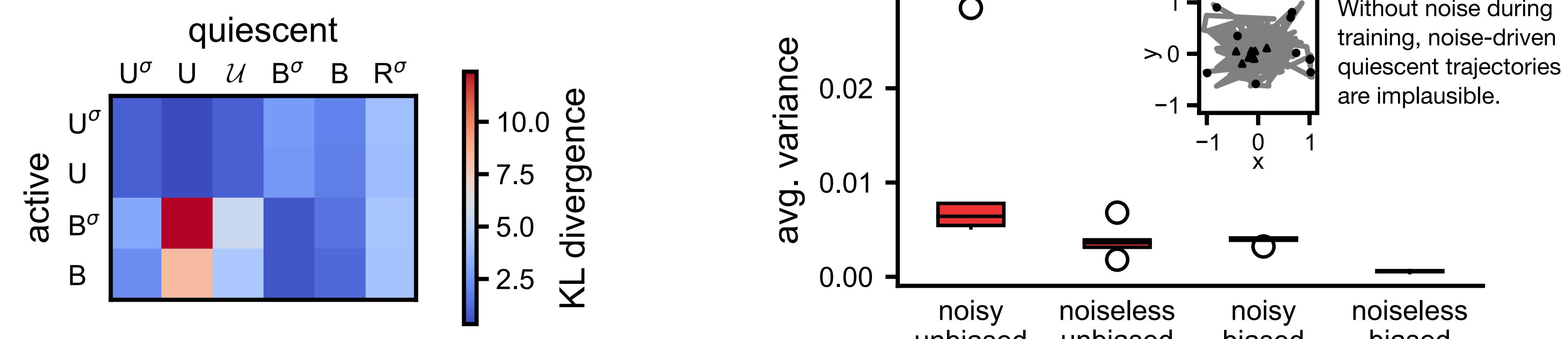


Decoded output trajectories from both phases tile space similarly.



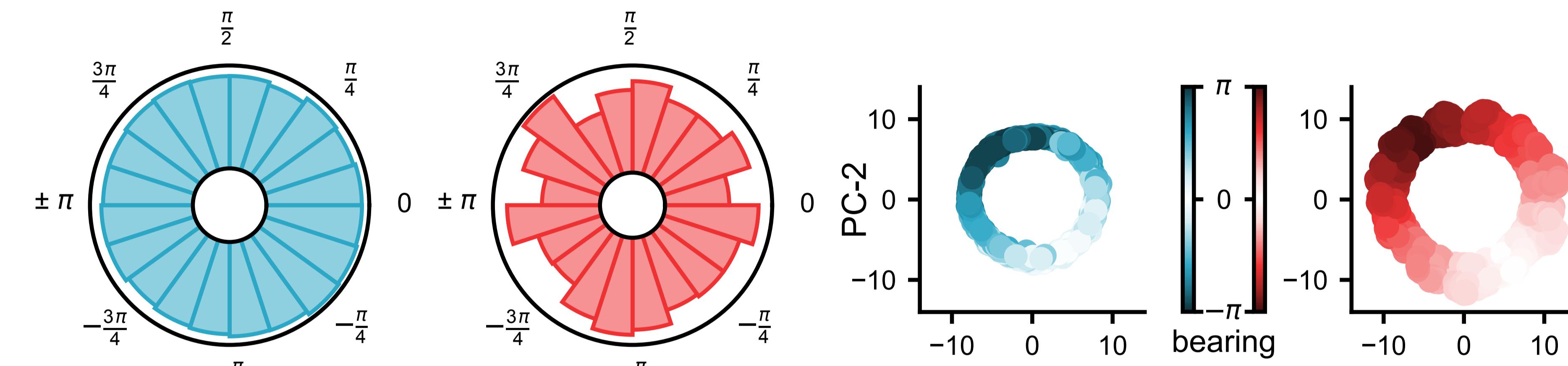
Quiescent distributions resemble corresponding active distributions.

Quiescent trajectories fail to explore in the absence of noise.

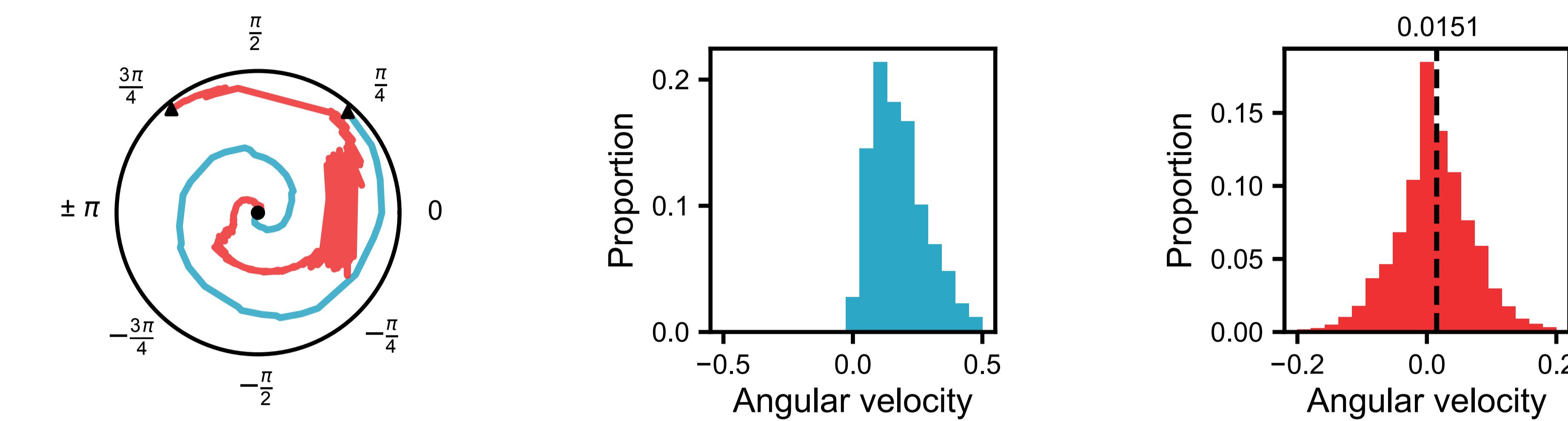


## Reactivation in Head Direction Estimation

Distributions are similar across both phases in this task as well.



By biasing motion to be counter-clockwise, we observe that the transition structure is partially recapitulated during quiescence.



## Conclusions and Future Work

**Reactivaton could be a natural consequence of learning in the presence of noise.**

Our results could be extended to explain reactivation in brain regions dedicated to higher-order cognition & decision making<sup>5</sup>.

Future work could study the transition dynamics<sup>6</sup> of reactivations & their functional utility, e.g. in memory consolidation<sup>7</sup>.

## References

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