

# 1 Features

- 7-bit address space allows up to 128 different slave addresses
- Multi-master arbitration support
- Up to 400kHz data transfer speed
- Noise suppression circuitry rejects spikes on bus lines
- Fully programmable slave address with general call support
- Compatible with Phillips I2C

## 2 2-wire Serial Interface

- Suited for typical microcontroller applications
- Allows upto 128 different device.
- All devices connected must have individual address and method to resolved bus contention

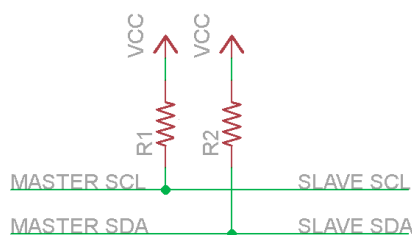
### 2.1 I<sup>2</sup>C Pins

- Output driver consist of slew-rate limiter to confirm the TWI specification.
- Input stage consist of spike suppression unit to remove spikes shorter than 50ns.
- Internal pull-up can also be used.
- *SDA* - Serial Data - the actual serial data transfer pinFormat
- *SCL* - Serial Clock - driven by device in Master Mode

### 2.2 Terminology

Term	Descripton
Master	Device that initiates and terminates transacting and also Generates <i>SCL</i> Clock.
Slave	Device addressed by a master.
Transmitter	Device placing data on the bus.
Receiver	Device reading data on the bus.

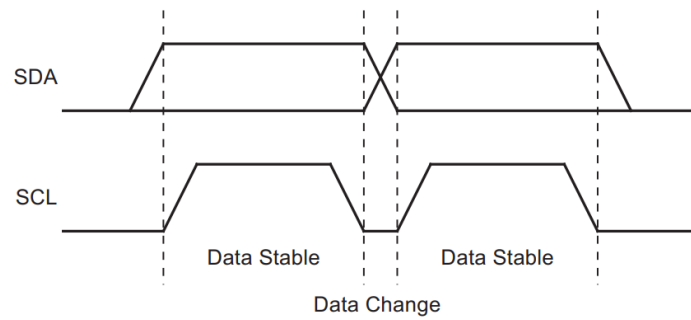
### 2.3 Electrical Interconnection



- both lines are connected to positive supply voltage through pull-up resistor
- bus driver are open-drain or open-collector
- no. of device also depends on the bus capacitance limit of 400pF

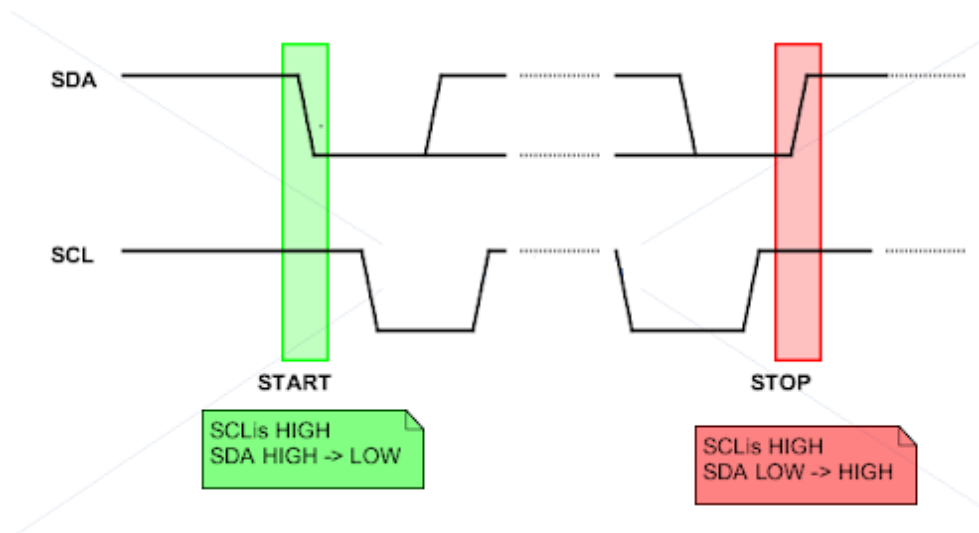
### 3 Data Transfer and Frame Format

#### 3.1 Transferring Bits



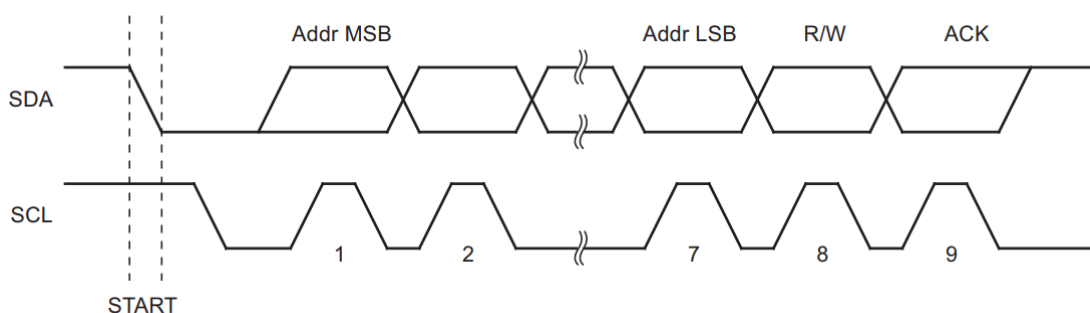
- Each data bit transferred is done by a pulse on clock line.
- Level of data line must be stable when the clock line is high.

#### 3.2 START and STOP Conditions



- Both **START** and **STOP** conditions are done by changing **SDA** line when **SCL** is kept high.
- Master initiates transmission by issuing a **START** condition.
- Master terminates transmission by issuing a **STOP** condition.
- Between **START** and **STOP**, bus is busy and no other master should try to control bus.
- The same master however can issue **REPEATED START**(same as **START**) to initiate a new transfer.

#### 3.3 Address Packet format

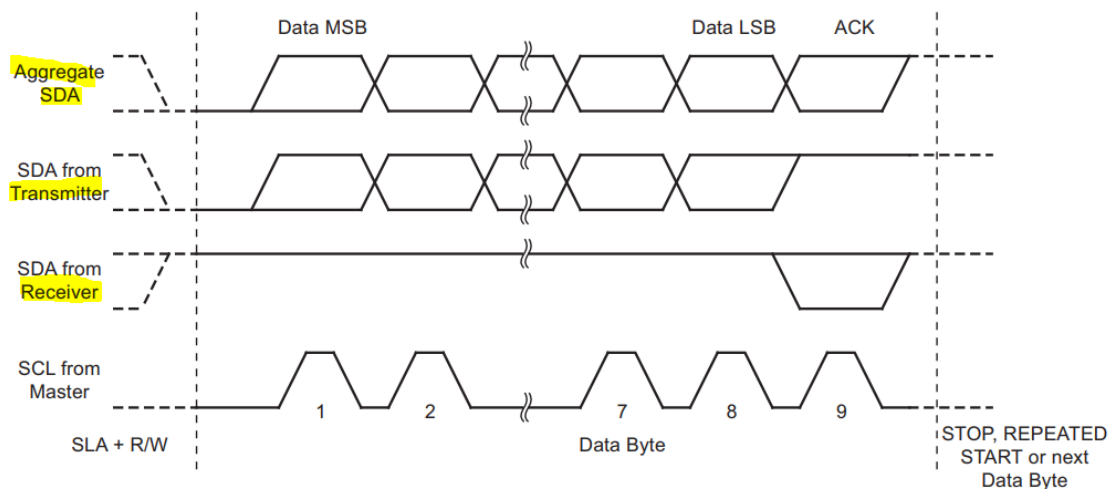


- Addresses packets(**SLA**) are 9-bit long.

- 7 address bits with MSB transmitted first
- one READ(1)/WRITE(0) control bit indicating the transmitter or receiver mode respectively
- one acknowledge bit by the Slave
- Would take 8 clock cycles by the master to send 7 address bits and one READ/WRITE control bit. SLA+R or SLA+W.
- On the 9th clock cycle, Master will leave out the control of *SDA* line (making it high due to pull-up resistor) but clocks out the 9th clock on the *SCL* line.
- On the 9th clock cycle, Slave recognizes that it is being addressed by pulling *SDA* line low making the ACK.
- If the Slave couldn't for some reason respond, the *SDA* line remains high in the 9th clock cycle making the NACK.

### 3.4 Data Packet format

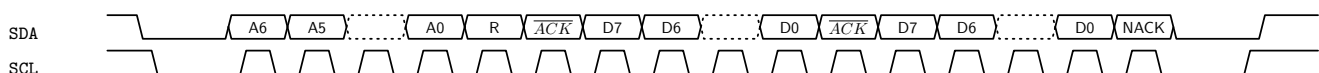
- Data packets are 9-bit long.
  - one data byte - 8 bits with MSB first.
  - one acknowledge bit by the master or slave depending on the mode.
- The transmitter (either the master or slave) sends 8-bit data in 8 clock cycles.



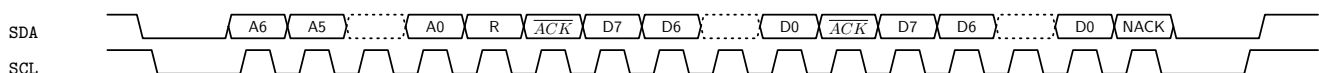
- On the 9th clock cycle, the transmitter will leave out the control of *SDA* line (making it high due to pull-up resistor).
- During the 9th clock cycle, the receiver pulls down the *SDA* line low to acknowledge the reception. – ACK is signaled by receiver.
- If the receiver doesn't pull down the *SDA* line for some reason, then the *SDA* line remains high. – NACK is signaled by receiver.
- When the receiver received the last byte or can't receive more byte, it should inform the transmitter by sending a NACK.

### 3.5 Overall Operation

#### Write Operation

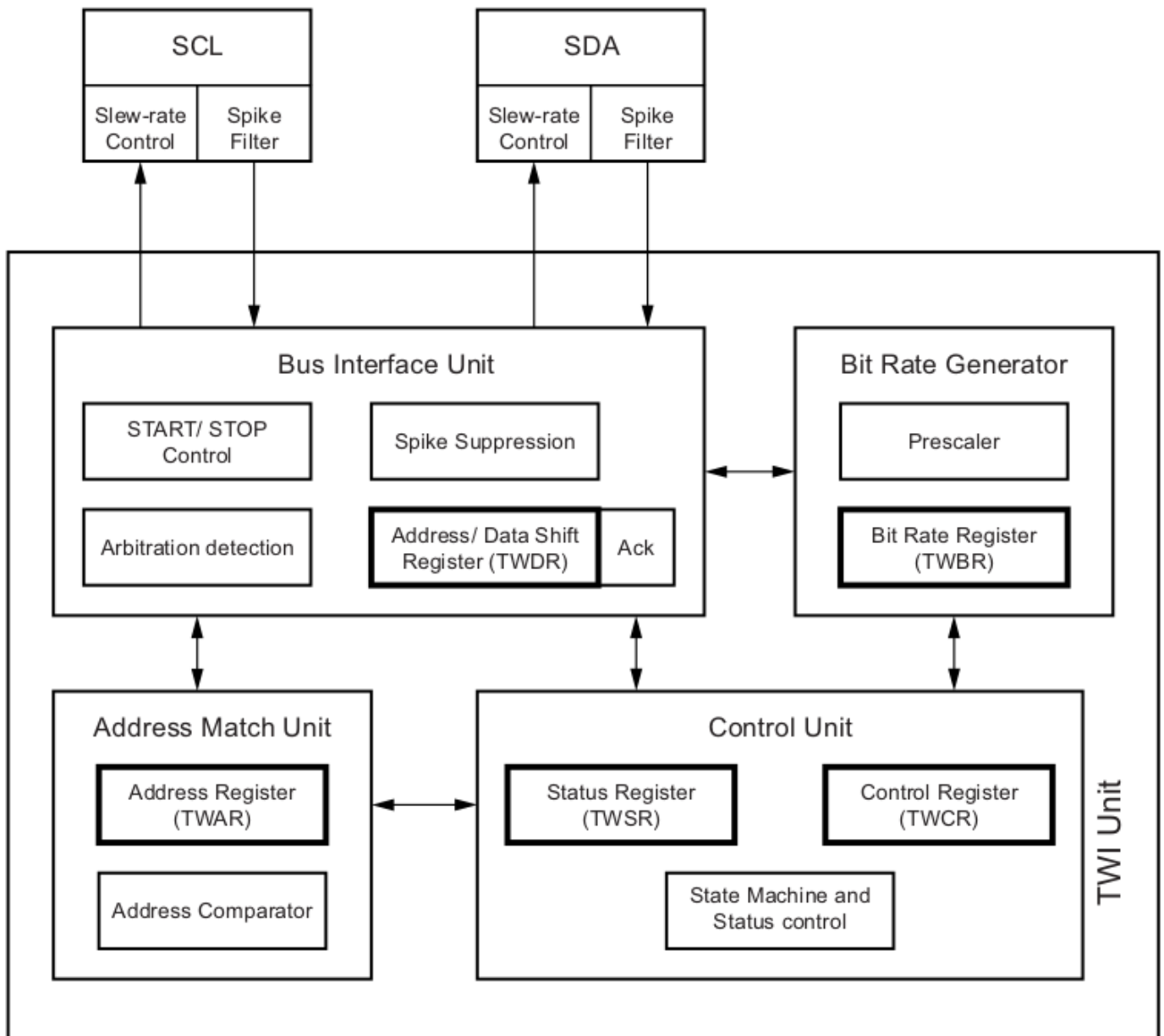


#### Read Operation



## 4 TWI Module

### 4.1 Block Diagram



### 4.2 Bit Rate Generation Unit

- controls **SCL** line when in Master mode
- **TWBR** (TWI Bit Rate Generator) and Prescaler Bits in TWI status register **TWSR** control **SCL**
- The **SCL** frequency can be

$$SCLfrequency = \frac{CPUClockFrequency}{16+2*TWBR*PrescalarValue}$$

**Note:** Slave's clock frequency must be atleast 16 times higher than SCL frequency.

### 4.3 Bus Interface Unit

- contains Data and adress Shift register - **TWDR** register - address or data transmitted or received
- **START/STOP** Controller - Generates and detects **START**, **STOP** and **REPEATED START**
- Register Containing the **(N)ACK** to be transmitted or received
- Arbitration detection hardware.

## 4.4 Address Match Unit

- Received address bytes matches the seven-bit address in **TWAR** (TWI Address register).
- address match results in informing the control unit

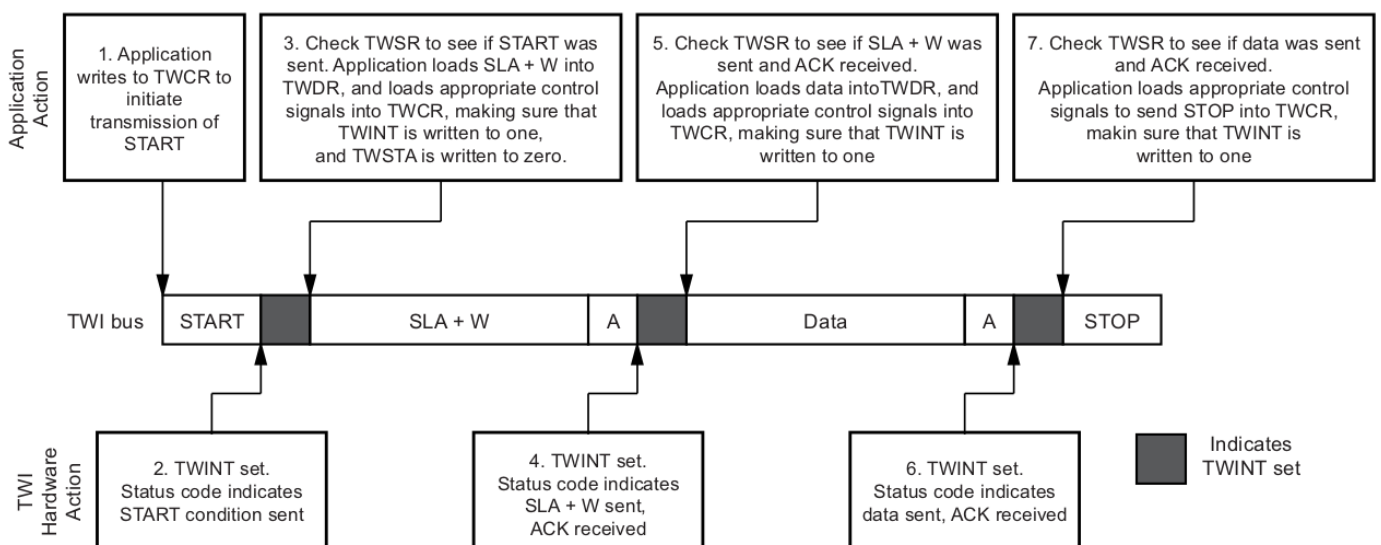
## 4.5 Control Unit

- Monitors TWI bus and generates responses based on TWI control register (**TWCR**).
- When an event requires attention:
  - **TWINT** (TWI Interrupt flag) is set
  - **TWSR** (TWI Status Register) is updated with status code identifying the event.
  - when the **TWINT** is set, the **SCL** line is held low.
- **TWINT** flag is set if
  - TWI has transmitted a **START/REPEATED START** condition
  - TWI has transmitted **SLA+R/W**
  - TWI has transmitted an address byte
  - TWI has lost arbitration
  - TWI has been addressed by own slave address or general call
  - TWI has received a data byte
  - **STOP** or **REPEATED START** has been received
  - bus error occurred due to illegal **START** or **STOP**

## 5 TWI Usage

- TWI is interrupt based and so **TWIE** bit in **TWCR** register should be enabled; If the **TWIE** is disabled, then the **TWINT** flag must be polled.
- When the **TWINT** flag is asserted, TWI has finished operation and awaits for application response and **TWSR** register describes the current status of TWI bus.
- Then, application should respond by manipulating the **TWCR** and **TWDR** register.

### 5.1 An Example - Master transmits single data byte to slave



1. Transmission is started by writing specific value into **TWCR** register to transmit the **START** condition. The **TWINT** flag is cleared by writing Logic HIGH which initiates the transmission of **START** condition.
2. When the **START** condition has been transmitted, the TWINT flag in TWCR is set, and **TWSR** is updated with a status code indicating that the **START** condition has successfully been sent.

3. The application should now respond by examining the **TWSR** register value. If status code is as expected, the application loads **SLA+W** into **TWDR** and a specific value is written into **TWCR** register to transmit the **SLA+W** present in **TWDR**. The **TWINT** flag is cleared by writing logic HIGH which initiates the transmission of address packet.
4. When the address packet has been transmitted, the **TWINT** flag in **TWCR** is set, and **TWSR** is updated with a status code indicating that the address packet has successfully been sent. The status code will also reflect whether a slave acknowledged the packet or not.
5. The application should now respond by examining the **TWSR** register value and **ACK** bit is as expected. If status code is as expected, the application loads Data packet into **TWDR** and a specific value is written into **TWCR** register to transmit the Data packet present in **TWDR**. The **TWINT** flag is cleared by writing logic HIGH which initiates the transmission of data packet.
6. When the data packet has been transmitted, the **TWINT** flag in **TWCR** is set, and **TWSR** is updated with a status code indicating that the data packet has successfully been sent. The status code will also reflect whether a slave acknowledged the packet or not.
7. The application should now respond by examining the **TWSR** register value and **ACK** bit is as expected. If status code is as expected, the application loads a specific value is written into **TWCR** register to transmit the **STOP** Condition. The **TWINT** flag is cleared by writing logic HIGH which initiates the transmission of STOP condition.

## 6 Transmission Modes

There are four major Modes

- (i) Master Transmitter (MT)
- (ii) Master Receiver (MR)
- (iii) Slave Transmitter (ST)
- (iv) Slave Receiver (SR)

Status Code	Meaning
S	<b>START</b> Condition
Rs	<b>REPEATED START</b> Condition
R	Read bit (high level on <b>SDA</b> )
W	Write bit (low level on <b>SDA</b> )
A	Acknowledge bit (low level on <b>SDA</b> )
$\bar{A}$	Not Acknowledge bit (high level on <b>SDA</b> )
DATA	8-bit data
P	<b>STOP</b> Condition
SLA	Slave Address

### 6.1 Master Transmitter Mode (MT)

- Many number of data bytes are transmitted to Slave receiver.
- For Master, **START** Condition is transmitted
- **START** condition is sent by:
  - **TWEN** bit is set to enable TWI.
  - **TWSTA** bit is set to transmit **START** condition.
  - **TWINT** flag is written 1 to clear to send start bit.
  - After Transmitting **START** condition, **TWINT** flag is set by hardware and status code in **TWSR** register should be **0x08** - indicating successful transmission of **START** condition.
- To enter into Master Transmitter Mode and transmit the address:
  - Write **SLA+W** into **TWDR** register.
  - **TWINT** flag is written 1 to clear to transmit Address and read/write status.

- After transmitting SLA+W, an acknowledgment bit will be received, the TWINT flag is set by hardware and status code in TWSR register will be 0x18 (indicating SLA+W has been transmitted and ACK has been received ), 0x20 (indicating SLA+W has been transmitted and NACK has been received ), 0x38 (Arbitration lose in sending SLA+W).
- Data packet is transmitted by:
  - Write DATA packet into TWDR register.
  - TWINT flag is written 1 to clear to transmit Address and read/write status.
  - After transmitting DATA packet, an acknowledgment bit will be received, the TWINT flag is set by hardware and status code in TWSR register will be 0x28 (indicating DATA packet has been transmitted and ACK has been received ), 0x30 (indicating DATA packet has been transmitted and NACK has been received )
  - To send further data, the above process is repeated by sending REPEATED START.
  - To stop the transmission, the STOP condition is sent.
- STOP condition is sent by:
  - TWSTO bit is set to transmit STOP condition.
  - TWINT flag is written 1 to clear to send stop bit.
- REPEATED START condition is sent by:
  - TWSTA bit is set to transmit REPEATED START condition.
  - TWINT flag is written 1 to clear to send repeated start bit.
  - After Transmitting REPEATED START condition, TWINT flag is set by hardware and status code in TWSR register should be 0x10 - indicating successful transmission of REPEATED START condition.

## 6.2 Master Receiver Mode (MR)

- Many number of data bytes can be received from Slave transmitter.
- For Master, START Condition is transmitted
- START condition is sent by:
  - TWEN bit is set to enable TWI.
  - TWSTA bit is set to transmit START condition.
  - TWINT flag is written 1 to clear to send start bit.
  - After Transmitting START condition, TWINT flag is set by hardware and status code in TWSR register should be 0x08 - indicating successful transmission of START condition.
- To enter into Master Receiver Mode and transmit the address:
  - Write SLA+R into TWDR register.
  - TWINT flag is written 1 to clear to transmit Address and read/write status.
  - After transmitting SLA+R, an acknowledgment bit will be received, the TWINT flag is set by hardware and status code in TWSR register will be 0x40 (indicating SLA+R has been transmitted and ACK has been received ), 0x48 (indicating SLA+R has been transmitted and NACK has been received ), 0x38 (Arbitration lose in sending SLA+R).
- Data packet is received by:
  - Reading the DATA packet from TWDR register if TWINT flag is logic HIGH.
  - TWINT flag is written 1 to clear.
  - After receiving DATA packet, an acknowledgment bit will be returned, the TWINT flag is set by hardware and status code in TWSR register will be 0x58 (indicating DATA packet has been received and ACK has been returned ), 0x50 (indicating DATA packet has been received and NACK has been returned )
  - To receive further data, the above process is repeated by sending REPEATED START.
  - To stop the reception, the STOP condition is sent.
- STOP condition is sent by:

- **TWSTO** bit is set to transmit **STOP** condition.
- **TWINT** flag is written 1 to clear to send stop bit.
- **REPEATED START** condition is sent by:
  - **TWSTA** bit is set to transmit **REPEATED START** condition.
  - **TWINT** flag is written 1 to clear to send repeated start bit.
  - After Transmitting **REPEATED START** condition, **TWINT** flag is set by hardware and status code in **TWSR** register should be **0x10** - indicating successful transmission of **REPEATED START** condition.

### 6.3 Slave Receiver Mode (SR)

- Many number of data bytes are received from Master transmitter.
- To initiate the Slave Mode:
  - **TWA[5:0]** bits from **TWAR** register format is loaded with our slave address.
  - **TWSTA** and **TWSTO** are set to 0
  - **TWEN** bit is set to enable the TWI.
- TWI waits until it is addressed by its own slave address followed by data direction bit.
- After receiving own Slave address and Write bit, the **TWINT** flag is set and valid status code is available in **TWSR** register.
- If the status code is **0x60** (Own **SLA+W** has been received and **ACK** has been returned)
- Now, data can be read by wiring Logic HIGH on **TWINT** flag to clear and read from **TWDR** register.
- **TWEA** bit is set to acknowledge and receive further data or **TWEA** bit is cleared and last byte is received.
- Now, **TWINT** flag is set and status code is available in **TWSR**.
- If status code is **0x80** (Previously addressed with own **SLA+W** and data has been received and **ACK** has been returned) - to receive further data.
- If status code is **0x88** (Previously addressed with own **SLA+W** and data has been received and **NACK** has been returned) - last data is received.
- If status code is **0xA0** - A **STOP** condition is received. has been received

### 6.4 Slave Transmitter Mode (ST)

- Many number of data bytes are transmitted to Master receive.
- To initiate the Slave Mode:
  - **TWA[5:0]** bits from **TWAR** register format is loaded with our slave address.
  - **TWSTA** and **TWSTO** are set to 0
  - **TWEN** bit is set to enable the TWI.
- TWI waits until it is addressed by its own slave address followed by data direction bit.
- After receiving own Slave address and Read bit, the **TWINT** flag is set and valid status code is available in **TWSR** register.
- If the status code is **0xA8** (Own **SLA+R** has been received and **ACK** has been returned)
- Now, data to be sent is set on the **TWDR** register.
- **TWINT** flag is written 1 to clear to transmit the data.
- Now, **TWINT** flag is set and status code is available in **TWSR**.
- If status code is **0xB8** -(Data byte in **TWDR** has been transmitted and **ACK** has been received) - can send further data.
- If status code is **0xC8** -(Data byte in **TWDR** has been transmitted and **NACK** has been received) - last byte send and don't send further.



## 7 Register Description

### TWBR – TWI Bit Rate Register

7	6	5	4	3	2	1	0
TWBR[7:0]							

The bit rate is found by,

$$SCLfrequency = \frac{CPUClockFrequency}{16+2*TWBR*PrescalarValue}$$

### TWCR – TWI Control Register

7	6	5	4	3	2	1	0
TWINT	TWEA	TWSTA	TWSTO	TWWC	TWEN	-	TWIE

- **TWINT** - TWI Interrupt Flag - Set by hardware when TWI has finished its current job and expects application software response. This Flag should be cleared by software by writing logic HIGH to start the operation of TWI.
- **TWEA** - TWI Enable Acknowledge Bit - Controls the generation of acknowledge pulse.
- **TWSTA** - TWI **START** condition - to generate **START** or **REPEATED START**.
- **TWSTO** - TWI **STOP** condition - to Generate **STOP** condition.
- **TWEN** - TWI Enable Bit - To enable and active TWI interface - takes control over **SDA** and **SCL** pins, enables slew-rate limiter and spike filter.
- **TWIE** - TWI Interrupt Enable - to enable interrupt when TWI flag is high.

### TWSR – TWI Status Register

7	6	5	4	3	2	1	0
TWS[7:3]					-	TWPS1	TWPS2

- **TWS[7:3]** - TWI Status - reflects the status of TWI logic and 2-wire status bus.

<b>TWPS[1:0] - TWI Bit rate Prescaler</b>	<b>Prescaler Value</b>
00	1
01	4
10	16
11	64

### TWDR – TWI Data Register

7	6	5	4	3	2	1	0
TWD[7:0]							

### TWAR – TWI (Slave) Address Register

7	6	5	4	3	2	1	0
TWA[6:0]							TWGCE

- **TWA[6:0]** - TWI Slave address Register - contain seven bit slave address.
- **TWGCE** - TWI General Call Recognition Bit - enables the recognition of general call.

## 8 Configuring the I2c

### 8.1 Master Transmitter and Receiver

The code can be seen below:

```
uint8_t status = 0;
void I2C_Master_Init()
{
    // Initiaize the I2C clock frequency to 100kHz
    // let the prescalr be 1
    // f_i2c = F_CPU / (16 + (2*xTWBR*Prescaler)) = 32
    // setting the TWBR register.
    TWBR = 32;

    // writing 1 to prscalre
    // setting the TWPS bits in TWSR to 00
    TWSR &= ~(1<<TWPS0);
    TWSR &= ~(1<<TWPS1);
}
uint8_t I2C_Master_Status()
{
    // Status value are available from TWSR[7:3]
    return TWSR & 0XF8;
}
uint8_t I2C_Master_START()
{
    // Enabling the TWI interface
    TWCR |= (1<<TWEN);
    // sending START condition
    TWCR |= (1<<TWSTA);
    // Do the transaction
    TWCR |= (1<<TWINT);
    // Checking if START condition is sent correctly
    while((TWCR & (1<<TWINT )) == 0x00);
    status = I2C_Master_Status();
    // checking status if START condition is sent correctly
    if(status == 0x08)
    {
        // no error occured
        return 0;
    }
    else
    {
        // error occured
        return 0;
    }
}
uint8_t I2C_Master_STOP()
{
    // Removing Start condition on bit
    TWCR &= ~(1<<TWSTA);
    // sending STOP condition
    TWCR |= (1<<TWSTO);

    // Do the transaction
    TWCR |= (1<<TWINT);

    // disaabling stop and interface

    TWCR &= ~(1<<TWSTO);
    TWCR &= ~(1<<TWEN);
}
```

```

        return 0;
    }
}
uint8_t I2C_Master_Mode(uint8_t slave_address, uint8_t transmitter0_receiver1)
{
    // Entering MASTER mode
    // Writing SLA+W into TWDR for transmitter and SLA+R for receiver
    // slave address must be MSB first
    // slave address is left shifted by 1 in order to accompany the R/W bit
    TWDR = (slave_address<<1) | transmitter0_receiver1;
    // Do the transaction
    TWCR |= (1<<TWINT);
    while((TWCR & (1<<TWINT)) == 0x00);
    status = I2C_Master_Status();
    // For transmitter the status would have to be 0x18 and for receiver 0x40
    uint8_t status_val_checker = (transmitter0_receiver1==0) ? 0x18 : 0x40;
    if(status == status_val_checker)
    {
        // no error occurred
        return 0;
    }
    else
    {
        // error occurred
        return 0;
    }
}
uint8_t I2C_Master_DataTransmitByte(uint8_t data_)
{
    // Data packet is transmitted
    // Writing data into TWDR
    TWDR = data_;
    // Do the transaction
    TWCR |= (1<<TWINT);
    while((TWCR & (1<<TWINT)) == 0x00);
    status = I2C_Master_Status();
    if(status == 0x28)
    {
        // ACK received and still data can be sent
        return 0;
    }
    else if(status == 0x30)
    {
        // NACK received and this is the last data so stop
        return 1;
    }
    else
    {
        // error occurred
        return 2;
    }
}
}
void I2C_Master_DataTransmitString(uint8_t *cdata)
{
    while(*cdata != '\0')
    {
        status = I2C_Master_DataTransmitByte(*cdata++);
        if(status == 0)
        {
            // ACK received and still data can be sent
            // continue
        }
        else if(status == 1)
        {

```

```

        // NACK received and this is the last data so stop
        return;
    }
    else
    {
        // error occurred
        return;
    }
}

uint8_t I2C_Master_DataReceiveByte()
{
    uint8_t value_ = 0;

    // Data packet is recieved
    TWCR |= (1<<TWINT);
    // Do the transaction
    while((TWCR & (1<<TWINT )) == 0x00)
    {
        value_ = TWDR;
    }

    status = I2C_Master_Status();
    if(status == 0x58)
    {
        // no error occurred
        return value_;
    }
    else
    {
        // error occurred
        return 1;
    }
}

void I2C_Master_DataReceiveString(uint8_t *recData,uint8_t NUMBYTE)
{
    uint8_t i=0;
    recData[NUMBYTE] = '\0';
    while(i < NUMBYTE)
    {
        // Enabling the Acknowledgment bit for replying positive ACK
        TWCR |= (1<<TWEA);
        if(i==(NUMBYTE-1))
        {
            // disbale the Acknowledgment bit for replying Negatice ACK for last byte
            TWCR &= ~(1<<TWEA);
        }
        status = I2C_Master_DataReceiveByte();
        if(status==0xFF)
            return;
        else
            recData[i] = status;
        i++;
    }
}

```

## 8.2 Slave Transmitter and Receiver

The code can be seen below:

```
uint8_t status = 0;
void I2C_SlaveInit(uint8_t my_address)
{
    // slave address and last LSB 0 is for general call
    TWAR = (my_address<<1) & 0xFE;
    // Enabling the TWI interface.
    TWCR |= (1<<TWEN);
    // Disabling Start and Stop conditon bits
    TWCR &= ~(1<<TWSTA);
    TWCR &= ~(1<<TWSTO);
}
uint8_t I2C_Status()
{
    // Status value are available from TWSR[7:3]
    return TWSR & 0XF8;
}

uint8_t I2C_SlaveMode( uint8_t transmitter0_receiver1)
{
    // Acknowldege the address
    TWCR |= (1<<TWEA);
    // Watiting for the Master to call this slave
    while((TWCR & (1<<TWINT )) == 0x00);
    status = I2C_Status();
    // For transmitter the staus would have to be 0xA8 and for receiver 0x60
    uint8_t status_val_checker = (transmitter0_receiver1==0) ? 0xA8 : 0x60;
    if(status == status_val_checker)
    {
        // Master called this slave
        return 0;
    }
    else
    {
        // error occured
        return 1;
    }
}

uint8_t I2C_Slave_DataTransmitByte(uint8_t data_)
{
    // Data packet is transmitted
    // Writing data intor TWDR
    TWDR = data_;
    // Do the transaction
    TWCR |= (1<<TWINT);
    while((TWCR & (1<<TWINT )) == 0x00);

    status = I2C_Status();
    if(status == 0xB8)
    {
        // ACK received and still data can be sent
        return 0;
    }
    else if(status == 0xC8)
    {
        // NACK received and this is the last data so stop
        return 1;
    }
    else
    {

```

```

        // error occurred
        return 2;
    }
}

void I2C_Slave_DataTransmitString(char *cdata)
{
    uint8_t i = 0;
    while(cdata[i] != '\0')
    {
        status = I2C_Slave_DataTransmitByte(cdata[i]) ;
        i++;
        if(status == 0)
        {
            // ACK received and still data can be sent
            // continue
        }
        else if(status == 1)
        {
            // NACK received and this is the last data so stop
            return;
        }
        else
        {
            // error occurred
            return;
        }
    }
}

uint8_t I2C_Slave_DataReceiveByte()
{
    uint8_t value_ = 0;

    // Data packet is recieved
    TWCR |= (1<<TWINT);
    // Do the transaction
    while((TWCR & (1<<TWINT )) == 0x00)
    {
        value_ = TWDR;
    }

    status = I2C_Status();
    if(status == 0x80)
    {
        // Data is sent and ACK has been returned
        return value_;
    }
    else if(status == 0x88)
    {
        // Data is sent and NACK has been returned for last byte
        return value_;
    }
    else
    {
        // error occurred
        return 0xFF;
    }
}

void I2C_Slave_DataReceiveString(uint8_t *recData,uint8_t NUMBYTE)
{
    uint8_t i=0;
    recData[NUMBYTE] = '\0';
    while(NUMBYTE > 0)

```

```

{
    NUMBYTE = NUMBYTE - 1;
    // Enabling the Acknowledgment bit for replying positive ACK
    TWCR |= (1<<TWEA);
    if(NUMBYTE==0)
    {
        // disable the Acknowledgment bit for replying Negative ACK for last byte
        TWCR &= ~(1<<TWEA);
    }
    status = I2C_Slave_DataReceiveByte();
    if(status==0xFF)
        return;
    else
        recData[i] = status;
    i++;
}
}

```