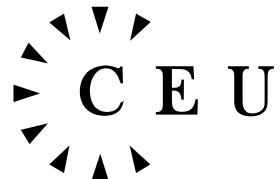


Multilayer network analysis of sustainable, multimodal urban transport networks



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RESEARCHER DECLARATION

I Luis Guillermo Natera Orozco certify that I am the author of the work Multimodality and sustainability in urban networks. I certify that this is solely my own original work, other than where I have clearly indicated, in this declaration and in the thesis, the contributions of others. The thesis contains no materials accepted for any other degrees in any other institutions. The copyright of this work rests with its author. Quotation from it is permitted, provided that full acknowledgement is made. This work may not be reproduced without my prior written consent.

Statement of inclusion of joint work

I confirm that Chapter 2 is based on a paper which was written in collaboration with Laura Alessandretti, Michael Szell and Federico Battiston. Dr. Battiston and I concived the idea of doing a review about the application of multiplex networks to the study of urban mobility systems. All authors contributed to the writing of the paper. Dr. Battiston endorses this statement with his signature below.

I confirm that Chapter 3 is based on a paper which was written in collaboration with Federico Battiston, Gerardo Iñiguez, and Michael Szell. I, with Dr. Battiston and Dr. Szell concived the idea of the overlap census. I collected the data and carried out the analyses. All authors developed the methods used, contributed to the writing of the paper on which the chapter is based and gave final approval for publication. Dr. Szell endorses this statement with his signature below.

I confirm that Chapter 4 is based on a paper which was written in collaboration with Federico Battiston, Gerardo Iñiguez, and Michael Szell. I, with Dr. Battiston and Dr. Szell concived the research. I collected, processed and cleaned data, and carried out the computational analysis. All authors designed the algorithms, analysed the data and results, and helped draft the manuscript. Dr. Szell endorses this statement with his signature below.

I confirm that Chapter 5 is based on a paper which was written in collaboration with Dávid Deritei, Anna Vancsó, and Orsolya Vásárhelyi. I with Dr. Deritei and Dr. Vásárhelyi concived the research and methodology, all authors collected, processed and cleaned data, and carried out the computational analysis. Together with Dr. Deritei and Dr. Vásárhelyi we analyzed the results. All author helped draft the manuscript and gave final approvement for its publication. Dr. Vásárhelyi endorses this statement with her signature below.

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June, 2021

ABSTRACT

With more than half of the world's population living in cities, it is fundamentally important to understand how the complex system of urban mobility infrastructure, from sidewalks and bicycle paths to streets and rails, shapes and modifies human mobility. In this thesis, we use network science to study cities and their mobility infrastructures. We treat these infrastructures as layers of a multiplex network, such as sidewalks, bicycle paths, subway systems and streets, and develop and apply network science based tools to study these layers both individually and jointly. First, we survey the existing literature of cities as multiplex networks, from infrastructure and dynamics to existing measures, data and analysis tools. Second, we propose a new method to extract the multimodal profile from a city's multiplex transport network. We show how this method can be applied to identify multimodal similarities between cities. Third, we focus on the bicycle layer of the multimodal network, investigate its structure, and find that it consists of hundreds of disconnected patches. To connect these patches, we develop and apply data-driven, algorithmic network growth strategies, showing that small but focused investments allow to significantly increase the connectedness and directness of urban bicycle networks. In the fourth chapter, we present a data-driven, network-based method to quantify the livability of a city, computing pedestrian accessibility to amenities and services, taking into consideration safety and environmental variables. Finally, we discuss the main contributions of this thesis and outline possible applications and open questions for the future. We anticipate that this work contributes directly to the understanding of urban systems providing new insights and tools for the evaluation of sustainable urban mobility infrastructures. Understanding, improving, and evaluating urban mobility infrastructures are major steps for improving urban life and to plan ahead of climate change, thus a well-defined set of tools and metrics will be relevant to move forward.

hablo de la ciudad, pastora de siglos, madre que nos engendra y nos devora, nos inventa y nos olvida.

Octavio Paz, *Hablo de la ciudad*
(1986)

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To be written

CONTENTS

Contents	i
1 Introduction: Cities and networks	1
1.1 Cities and network science	2
1.2 Aim and structure of the thesis	5
2 Related Work: Multimodal transportation and mobility in urban networks	7
2.1 Multilayer networks: A framework for multimodality	8
2.2 Multimodal infrastructures	10
2.2.1 Modeling urban infrastructure	11
2.2.2 Characterizing multimodal infrastructure	14
2.3 Multimodal mobility	19
2.3.1 Modeling urban mobility	20
2.3.2 Characterizing multi-modal mobility.	22
2.4 Open data & Tools	27
2.4.1 Data	27
2.4.2 Tools	29
2.5 Conclusions	31
3 Extracting the multimodal fingerprint of transportation networks	33
3.1 Evolution of urban networks	34
3.2 Data: Building the multiplex urban network	34
3.3 Overlap census: A local measure of multimodal integration	36
3.4 Identifying clusters of cities with the Overlap Census	37
4 Data-driven strategies for optimal bicycle network growth	41
4.1 Bicycles in urban networks	42
4.2 Data: Bicycle infrastructure networks	43
4.3 Defining bicycle network growth strategies and quality metrics	44
4.3.1 Algorithmic approach	45

4.3.2	Evaluating the algorithms	47
4.4	Growing bicycle networks shows stark improvements with small investments	50
4.5	Different cities have different optimal investment strategies . . .	54
4.6	Discussion	57
5	Life quality as walkability	59
5.1	Walking the city	60
5.2	Data: Pedestrian network, points of interest, and city attributes .	61
5.2.1	Pedestrian network	61
5.2.2	Points of interest	61
5.2.3	City attributes	62
5.3	Quantifying life quality	62
5.3.1	Services index	64
5.3.2	Safety index	66
5.3.3	Environmental index	67
5.4	Results	68
5.4.1	Evaluation	69
5.5	Discussion	71
6	Conclusion and open questions	73
7	Appendices	97
7.1	Data-driven strategies for optimal bicycle network growth	97
7.1.1	Data	97
7.1.2	Bicycle network improvement	97
7.1.3	Bicycle network and 30 km/h streets	98
7.2	Life quality as walkability	98
7.2.1	Secondary data sources	98
7.2.2	Categorization	100
List of Tables		107
List of Figures		110

CHAPTER 1

INTRODUCTION: CITIES AND NETWORKS

Cities have the capability of providing something for everybody, only because, and only when, they are created by everybody.

Jane Jacobs, *The Death and Life of Great American Cities* (1961, p. 238)

As an architect my first approach to study cities was from the buildings' perspective, understanding how, by building, we delimit and shape spaces that model experiences in the city [1]. These buildings are fundamental to define public spaces, mobility infrastructures, and even services that enable us to inhabit the *ville* [2]. The way we shape the city has an influence on how we inhabit it. Thus, understanding its infrastructures is fundamental to understanding and planning better cities for an increasingly complex future. Especially, when tackling urban mobility challenges, the way we plan, build and use mobility infrastructures is fundamentally entangled with the livability of our cities.

When thinking about urban infrastructures, my first approach was to use drawings and blueprints. These tools are useful to understand, and plan urban mobility. They provide a way to move from the physical structure of cities to a more concrete way to represent them. These maps and blueprints are a useful tool to abstract the reality and make it more manageable. Of course, one must be cautious when building such maps: at the end they are a representation of

the territory, not the territory itself [3]. Maps and blueprints provided me with an overview of cities and tools to move between scales.

As I studied cities, I became interested in getting to understand the relation between different transportation modes, and how cities and their mobility infrastructures could be studied using large scale data systematically. This curiosity led me to the complex systems field, and the use of network science to study cities.

In this thesis I present the work of four years of research in the intersection of cities and complex networks. From this point onward I speak in plural, as even though I am the one presenting it, my research has been done in collaboration with co-authors.

1.1 Cities and network science

As a complex system, a city offers a fertile study ground from multiple perspectives. Urban studies have engaged in analyzing different aspects of urban life, from sociological perspectives to more technical ones such as engineering. Due to this diversity and overlapping approaches, the “science of cities” is inherently interdisciplinary.

In cities, interdisciplinarity goes beyond the application of tools and methods borrowed from one discipline to study a different object. Indeed, when we think and engage in the analysis of urban phenomena, we encounter a multitude of approaches without a single dominant one. When studying cities one can start taking apart its pieces and analyze them separately. For instance, buildings, roads, and functions can all be studied without taking into consideration the rest of the pieces. However, following this approach misses the interactions between the pieces.

Cities are more than the sum of their parts. It is in the interactions between their different pieces and components where one can find the richness of cities and the spark of urban life [4]. In a mostly urbanized world, capturing these relations is fundamental to not only understand the cities, but to plan better and more human ones. As cities evolve through time they grow and change, as defined by Manuel Castells, contemporary cities are a “space of flows” [5].

To capture these changes and flows, the complex system framework can be used. Indeed, this approach has enabled new urban research opportunities, such as the characterization of urban areas as fractals [6] to investigate the cities’ spatial organization, and their growing processes and evolution [7]. However, to be able to capture the relations and interactions between places one can study cities as a system. To do so, we can use networks.

Over the last decades, networks have emerged as a versatile tool to un-

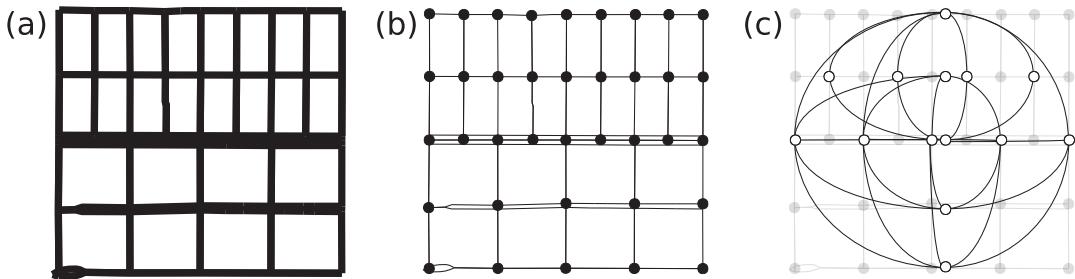


Figure 1.1. (a) Schematic street plan representation. (b) Primal representation of a street network, intersections are represented as nodes, and streets as edges. (c) Space syntax representation of a city. Continues streets mapped as nodes, and edges between intersecting streets.

derstand, map and visualize the interconnected architecture of a wide range of complex systems, from social systems to biology [8, 9, 10, 11], and in particular spatially embedded ones [12]. When modelling a city as a network, there are two approaches. First, intersections can be mapped as nodes, and the streets (or any other mobility infrastructure) as edges [13]. Following this approach it is possible to replicate the city's structure as a planar network [14] (see Figure 1.1 (a-b)). On the other hand, it is possible to model a city as a network following space syntax theory [15] in which the streets are mapped as nodes depending on their continuity, and intersections are edges (see Figure 1.1 (c)). Although the space syntax theory is useful to map relations between spaces/streets, it fails to capture the morphological properties of cities [16]. Along this thesis we will work with the primal representation of urban networks, considering intersections as nodes, and streets, sidewalks, or bike paths as edges connecting the nodes. As this network representation allow us to capture the urban structure and provide us with a framework to analyze it and compare multiple layers systematically.

Cities as networks have been extensively studied in the field of Network Science, first from a single-layer perspective, while more recently with a multi-layer perspective, with special attention to transportation networks [17, 12, 18], focusing on topological properties [19, 20, 21, 22, 12, 23, 24, 25], centrality metrics [26, 14, 27], and growth processes [7, 28]. Other topics include the impact of the street networks on pedestrian volume [29], accessibility and vitality of cities [30, 31], resilience of transportation networks [32, 33]. These recent approaches can be seen as the beginning of emerging fields such as the Science of Cities or Urban Data Science, which exploit new large-scale urban datasets with quantitative tools from physics, geoinformatics, and data/network sci-

ence [34, 35].

When using networks to represent transportation systems [17], nodes can represent the stations of the system, and links the direct connections between such stations. However, in real world scenarios, the transportation systems are composed of multiple transportation options, such as subways, buses, tramways, and dedicated pedestrian and cyclist infrastructure. To be able to integrate these systems and represent the multimodal transportation options of a city, the system can be conveniently described by *multiplex* or *multilayer* networks [36, 37, 38, 39].

Having interconnected urban transportation infrastructure enables multimodal mobility. Multimodal mobility is the idea of the combination of modes in one trip. Naturally this happens in all cities - for example, a trip with a bus includes walking to and from a bus station. On the other hand, multimodal mobility can also be intentionally designed, such as bicycle-trains [40] or share mobility solutions to the last mile problem [41]. A multimodal transportation system offers the benefit of combining multiple transport modes and their advantages while avoiding their weaknesses, by connecting different modes through interfaces (e.g. stations) that facilitate transfers between the distinct services [42]. Along this thesis we build our methodologies on top of multilayer networks to be able to capture and evaluate urban mobility infrastructures.

The study of urban mobility combined with network science has not only been beneficial when dealing with infrastructures, as it has also been used to analyze human mobility dynamics [43]. The availability of data sets such as large-scale mobile phone data, have been used as proxies to understand mobility patterns in cities [44], finding predictable human mobility motifs related to socio-economic activities in cities. Understanding the interplay between infrastructure and dynamics is fundamental to tackle further multimodal planning challenges. Challenges such as the need of processing large amounts of information when choosing convenient travel routes in multimodal systems [45], and the synchronization between different agencies and transportation modes [46].

The primary aim of this thesis is to provide an original contribution to the study of multimodal transportation networks in urban areas. For that, we build on the tools and methods of network science to analyze the underlying complexity of urban mobility infrastructure.

Along the thesis we build on current research to give original contribution to open research problems such as the characterization of multimodal transport infrastructure, and the use of large scale open data sets to identify similarities between cities based on their multimodal transportation options. Identifying universal patterns in urban development help plan systematic ways to build better cities. In that sense, it is important to address the open research problem

of planning and identifying strategies to improve sustainable mobility options in cities. We give an original contribution to the field by designing algorithms to systematically connect different patches of urban bicycle infrastructure. In a similar sense, we propose to leverage network science tools to create a framework that incorporates both: the urban physical structure, and practical knowledge from stakeholders, to measure liveability conditions. These works contribute directly to the understanding of urban systems, while at the same time provides new tools for scientists, planners and public policy evaluations.

1.2 Aim and structure of the thesis

In this thesis we begin focusing on the multimodal infrastructure network, first by providing a review of previous works related to multimodal transportation networks, and then giving an original contribution to the analysis of this specific type of system. In the following chapters, we focus on specific layers: first, by analyzing and giving an original contribution for the connectivity of bicycle infrastructure networks, and second, we propose and use a methodology to measure the urban quality of life as urban walkability taking the pedestrian infrastructure layer as the base for our calculations.

This thesis has six chapters. In Chapter 2: We provide a review of previous works on multimodal transportation and mobility research from a complex systems' perspective. First we focus on the infrastructure and measures to quantify it, then on the mobility dynamics on top of these infrastructures, and finally we offer a review of available datasets and tools to analyze this specific type of networks.

In Chapter 3 we make an original contribution to the field by proposing a method to extract the multimodal profile from a city's multiplex transport network. In this chapter, we apply our methods to fifteen cities, finding clusters of cities with similar multimodal infrastructure.

In Chapter 4 we focus our attention on the bicycle layer of the multimodal network and propose algorithmic approaches to improve its connectivity. We find that focalized investment has the potential to rapidly improve the connectedness and directness of the bicycle infrastructure.

In Chapter 5 we present a methodology to measure the quality of life in a city based on the pedestrian accessibility to amenities and services. We apply the methodology to Budapest and show how it can be used to capture inequalities in neighborhoods.

Finally, in chapter 6: We review the main contributions from this thesis, and outline future streams of work and open questions.

CHAPTER 2

RELATED WORK: MULTIMODAL TRANSPORTATION AND MOBILITY IN URBAN NETWORKS

In this chapter we provide a comprehensive overview of complex systems approaches to multimodal transportation and mobility in urban networks. We cover multiple approaches that had been used to model cities using the multiplex framework, measures to quantify centralities and changes in the given networks and layers. After reviewing the mobility infrastructure and measures, we move our focus to the mobility dynamics on top of those layers, covering the study of urban mobility dynamics in public transport systems and at individual level. Finally, we conclude the chapter with an overview of the available data and computational tools for the study of urban mobility networks¹.

¹A stand alone of this chapter is currently being prepared as a paper, to be submitted to Transportation Reviews. No preprint is yet available.

In this chapter, we survey the literature on urban multimodal mobility, and on urban transportation infrastructure as multilayer networks. Here, we focus on the primal approach to networks [13], where streets and mobility infrastructure constitute the network links, and intersections (bus stops, subway stations, etc.) constitute the nodes of the network.

The remainder of this chapter is arranged as follows. Section 2.1 introduces the mathematical concept of multilayer networks and related theoretical research underlying network science approaches to the topic. In Section 2.2 we discuss research on urban transport infrastructures, including their theoretical modelling (see Subsection 2.2) as multilayer networks and their empirical characterization (see Subsection 2.2.2). In Section 2.3 we focus on mobility, flows and navigation across these multimodal systems, and implications for transportation choices. In Section 2.4 we cover the relevant open datasets and the main software tools which can be used to analyse multimodal transportation systems. We conclude with an outlook and a summary of open questions for the research community in Section 2.5.

2.1 Multilayer networks: A framework for multimodality

Over the last decades, networks have emerged as a versatile tool to understand, map and visualize the interconnected architecture of a wide range of complex systems [8, 9, 10, 11], in particular spatially-embedded ones [12, 47]. Formally, a network – or graph – $\mathcal{G} = (\mathcal{N}, \mathcal{L})$ consists of a set of nodes \mathcal{N} , and a second set \mathcal{L} of edges, describing connections among unordered pairs of elements of the first set. This information can be conveniently stored into an adjacency matrix $A = a_{ij}$, where $i = 1, \dots, N$ are the nodes, and $a_{ij} = 1$ if there is a link between nodes i and j , $a_{ij} = 0$ if there is no link between i and j . In transportation systems [17], nodes can represent the stations of a network, and links direct connections between them. The adjacency matrix can also include weights $W = w_{ij}$, where w_{ij} are positive real numbers, for instance describing how strongly connected two nodes are. For spatial systems, weights are often taken as the reciprocal of the distance between two nodes, or the time it takes to travel from one to another, i.e. $w_{ij} = 1/d_{ij}$ or $w_{ij} = 1/t_{ij}$.

More recently, network scientists have put effort into characterizing the structure of systems which are formed by different interconnected networks. Such interconnected structures are natural for transportation systems but also for social and biological networks. An example of these interconnections are the largest transportation hubs in worldwide cities, where stations are routinely

served by bus, underground and railway infrastructures.

Indeed, most urban transportation systems systemically rely on the interplay between different means of transportation. These systems can be conveniently described by *multiplex* or *multilayer* networks. Here we introduce the *vectorial* formalism for multilayer networks [38, 39], widely used in most papers on multimodal transportation. An alternative description can be provided by a more mathematically involved *tensorial* framework [36, 37].

In multilayer networks, links of different types, describing for instance a different mean of transportation, are embedded into different *layers*. Each layer α , $\alpha = 1, \dots, M$, is described by an adjacency matrix $W^{[\alpha]} = \{w_{ij}^{[\alpha]}\}$. In a multimodal urban transportation network with three mobility infrastructure layers, $\alpha = 1$ can represent the bus network, $\alpha = 2$ the underground network, and $\alpha = 3$ the urban railway network, for example. The full transportation system \mathcal{M} can be described as $\mathcal{W} = \{W^{[1]}, \dots, W^{[M]}\}$. Nodes $i = 1, \dots, N$ are labeled in the same order in all networks.

In the case of transportation networks, simply identifying nodes of different networks as the same station might not provide the most complete description of the multimodal network. Take for instance the largest stations in mega-cities, like King's Cross - St. Pancras in London, Grand Central Station in New York or Hongqiao transportation hub in Shanghai. All of these are identified by a unique location (node index) i across the different transportation layers. Yet, switching from one mean of transportation to another within the same station might require a non-negligible fraction of time and effort, given the complexity and size of the overall infrastructure.

For this reason, it is often relevant to complement the description of the *intra-layer* connections present in the system, with *inter-layer* links associated to the cost, spatial distance or time required to switch layers. Inter-layer links between layers α and β at a node i can be encoded through the inter-layer matrix $C_i = \{c_i^{[\alpha\beta]}\}$, and all such inter-layer connections can be stored in the vector $C = C_1, \dots, C_N$. In this case, the full multiplex structure of the system is described by taking into account both intra-layer and inter-layer connectivity, hence $\mathcal{M} = (W, C)$. Inter-layer links may be neglected for many measures focusing on diversity [39], as well as correlations [48] across the layers of the systems, relevant to assess the different roles and geographical spanning of the different mean of transportation of a multilayer network.

Multilayer networks are a natural framework for multimodal transport networks. Indeed, one of the pioneering works introducing the framework and concept of “layered complex networks” [49] explicitly focuses on the case of transportation systems, where a first layer encodes the physical infrastructure of the system, and the second one describes the flows on such infrastructure.

Other early works on the topic also dealt with interconnected systems at the worldwide level, focusing on different modes of transport such as the multiplex airline networks [50].

Noticeably, multimodal infrastructures seem to possess exclusive characteristics different from other multilayer networks. For instance, when tools to assess the redundancy of the different layers are considered, transportation networks are often found to be irreducible [51]. Differently from many biological systems, where layers often duplicate information to guarantee the interconnected system a high level of robustness, the layers of a multiplex transportation systems are purposefully engineered to be different, in order to maximise efficiency [52]. As a byproduct of this feature, multimodal systems are also often highly fragile [53], and sensitive to disruptions or failures of a single infrastructure [54] (For a more detailed view on the topic see the early reviews [38, 37] and textbook [55] covering the field). Aleta et al. [56] provides a more recent eye-bird view of the field. A thorough review of the measures and models used to analyse such systems can be found in Battiston et al. [57], whereas de Domenico et al. [58] gave a theoretical overview of spreading and diffusive processes on such systems. In the following sections of this chapter, we focus on findings of more direct relevance to the research community working with multimodal transportation and urban mobility. The division of related research across these two themes is not meant to be rigid, but rather serves as an indication of the core topic treated in the different works.

2.2 Multimodal infrastructures

As cities grow and add different transportation modes, understanding the transportation infrastructure and its interconnected nature is crucial to capturing patterns of urban mobility. Since the 1950s, fields ranging from Architecture to Urbanism and Transport Planning have grown a large body of literature studying the structure of cities and their transport systems. With the growth of the Complex Systems and Network Science fields, new models have been developed to study the complexity behind urban systems, and specifically mobility infrastructure.

Multimodal urban infrastructures can be represented as multilayer networks, in which each layer α represents a mobility infrastructure (e.g. subway, light railway, bus service, pedestrian or bicycle infrastructure), the set of nodes \mathcal{N} are locations (e.g. bus stops, intersections, subway stations), and the set of edges \mathcal{L} in layer α are the infrastructure links between nodes in the same layer (e.g. subway lines, bus routes, bicycle lanes, see also Section 2.1). Modeling infrastructures is of great importance for understanding how urban systems

work, and for the design of new sustainable mobility options.

In the following we describe recent findings related to how transportation layers are coupled and grow. First, we review the main complex systems models of urban transportation. Then, we describe empirical findings related to the transport infrastructures.

2.2.1 Modeling urban infrastructure

One of the first contributions to the modeling of multimodal urban infrastructures was provided by de Cea et al. [59] who pointed out that most of the models from the transport community [60, 61, ?] used to plan and simulate the effects of new transportation options and failed to consider congestion associated with transit modes. This shortcoming is particularly relevant when the models are used for infrastructure development and predict transportation equilibria in future years.

The model proposed by de Cea et al. [59] takes the road network as the base layer. There, links have an average operating cost that takes into account different mobility options (e.g. cars, taxi, etc.). For every public transportation mode a new layer is defined, with their unique nodes and links. For these layers, the cost function of the public transportation links depends on the combined effect of travel, waiting, and transfer time. The model considers the existence of combined trips (e.g. car/metro, bus/metro, etc) and looks for an equilibrium condition under the assumption that every user chooses her route to minimize their average operation cost (Wardrop's first principle). This means that at equilibrium, only non-congested routes have a minimum cost, while those without flow represent a more costly option. Travel time might be affected by the interplay of different transportation means. For instance, vehicle flow over the road network may induce longer travel times in the bus network. Similarly, a passenger might decide not to take the subway if it is too crowded. [59] show that their model is able to find the equilibrium in the trips between origin and destination in a toy model, and can be successfully applied to real-world scenarios. For instance, a rich version of this model (which consisted of 13 user classes, 11 transport modes, and 450 zones) successfully informed the planning of the new metro line 5 in Santiago (Chile).

A similar philosophy was deployed by Li et al. [62] who considered a transportation infrastructure of cars, combined walk-metro paths, and park-and-ride. Differently from the previous work in which the model take into consideration the availability of routes, here parking availability and time spent by car commuters while looking for parking, which can be considerable [63], is considered explicitly. The focus here is on the interplay and impact of park-and-ride (P&R) schemes to encourage users to switch from car travel to subway

and public transportation options when traveling to the cities' central area. The model proposed by Li et al. [62] considers the effects of traffic conditions on travel demand, and incorporates elastic demand into the model to capture commuters' responses to traffic congestion and availability of parking supply. The responses of a user include the decision to switch to another transportation option, or to not make the trip at all. For the public transportation layer, the model also takes in consideration discomfort that may result from crowded subways. Through numerical simulations, Li et al. [62] found that it is possible to reach an equilibrium control which prevents the emergence of traffic jams in the city center by implementing a suitable P&R scheme, which looks at the combined effect of cost at the P&R sites, parking availability in the city center, as well as metro fares and frequency.

While in the above works the interplay of different transportation modes was introduced, they were not yet modeled as a multilayer network. One of the first applications of this new modeling framework was presented by Morris et al. [64] who developed a toy model to couple different transport modes, according to the following rules. First, N nodes are placed at random within the unit circle, mimicking a spatial configuration typical of many cities, and are connected by a Delaunay triangulation. Second, to simulate another transport mode, a second layer is generated by drawing a subset of the previously generated nodes and a second Delaunay triangulation. Finally, the two layers are coupled with interlayer links when a node is present in both layers. Using this toy model and a simulated Origin-Destination matrix, Morris et al. [64] investigated how fragile the network is to changes in supply and demand. They found that increasing travel speed in one layer tends to concentrate trips in the fastest layer, and also produces congestion in the nodes where is possible to change transport mode.

Similar results have been reported for coupled random networks [65], as well as scale-free networks [66] where a similar modelling approach is used to mimic a real-world transport scenario [67]. In their work, Du et al. [67] used a two-layer traffic model, where one layer provides higher transport speed than the other, and applied a Particle Swarm Optimisation algorithm to optimize the transport system capacity and reduce congestion both in synthetic and real-world multimodal networks. A more detailed coverage of the findings can be found when discussing betweenness centrality and interdependence in Section 2.2.2.

Gil [68] proposed to use open data from Open Street Map to model the multimodal infrastructure network of a given city as a combination of three layers. The first layer is the street network, where the nodes are intersections and links are streets. This layer, accounting for private transportation, was again the ref-

erence layer with respect to the other transportation modes in the system, i.e. all other layers have to be connected to and interact with it. The second layer is the public transport layer that represents the stations as nodes. It links the stations whenever there is a public transport service between two stations. This layer is coupled to the street layer by the stations and their closest street intersection. Gil [68] also include land use in their model to measure urban accessibility. This framework was applied to the analysis of the Randstad city-region in the Netherlands. The model was tested under different parameters and layer combinations, measuring reachability of the different city areas through closeness and betweenness centralities. Comparison with ground truth data showed that betweenness centrality in the public transportation layer can be a good indicator of passenger flows.

Aleta et al. [69] exploited one step further the richness of multilayer networks for transportation systems, highlighting two possible frameworks. In the first framework, each bus or metro line on its own could be considered an independent layer. This approach is useful to have a realistic model of human mobility which takes into consideration transfer times and synchronization between single trips. Yet, it does not allow to evaluate the importance of an entire transportation mode. This issue is resolved in the second framework. Here all the lines of the same mode are combined into a so-called *superlayer*, which is fundamental to study the interdependence and resilience of the whole system.

Using the previously described frameworks, Aleta et al. [69] investigated the public transport systems of nine European cities. Following the first framework, the authors focused on some structural features of the emerging system such as the overlapping degree (sum of the node's degree in all layers [39]). They found that public transport infrastructures have some universal properties, and that the maximum overlapping degree is similar in all the systems, even if the number of layers is different. This depends on the fact that networks are embedded in a physical space, hence imposing some bounds on the maximum number of links of each node structural constraints. Following the second framework, Aleta et al. [69] investigated in detail the superlayers and found that – surprisingly – the nodes with the highest overlapping degree are not necessarily the ones with the highest superlayer activity [48]. Indeed, some transportation modes (and in particular the bus layer) have a tendency for hubs which might be disconnected to the other transportation modes, leading to high overlapping degree but low multilayer activity. The prevalence of such hubs is relevant when considering the robustness of the whole system. As the study highlights, it is often easier to move a bus stop to a street nearby, even if it is a local hub where multiple lines stop, than solving a disruption in a subway station. Aleta et al. [69] also assess the importance of the superlayers based on

the number of shortest paths that make use of the superlayer, a measure that we characterize later in Section 2.2.2.

It is important to note that cities and their transportation systems are not static in time. This means new transport modes may be introduced or extended, such as when new bus/subway stops are added. Recently, to plan for Open Streets during the COVID-19 pandemic, Rhoads et al. [70] proposed an investigation of the relation between streets and sidewalks. First, the authors used percolation theory to examine whether the sidewalk infrastructure in cities can withstand the tight pandemic social distancing. They then proposed an algorithm that takes into consideration both the sidewalk and street layers while improving the sidewalk connectivity. Despite spatial constraints, Rhoads et al. [70] showed that it is possible to widen the sidewalks and improve the pedestrian connectivity with a minimum loss in the road network.

More in general, some works have focused on the growth and evolution of multilayer networks [71, 72, 73], generalising preferential attachment mechanisms in different ways [74]. However, these works do not take into account spatial constraints, and are not well suited to describing the evolution of spatial networks. For this reason, there is ample potential for future work to develop growth models for multimodal infrastructures, for instance considering densification and exploration, as previously done for street networks [28]. An alternative view can be obtained by investigating the optimal growth and design of the multiplex structure of the different layers, as was done for the multilayer airline network composed by routes of different airline companies [75].

The models discussed in this section have shown how the multilayer networks framework has been used to investigate the structure, function and vulnerabilities of a complex transportation system. In the next section we cover some measures to quantify the multiplexity of these structures and their interconnections.

2.2.2 Characterizing multimodal infrastructure

The empirical study of urban transportation infrastructure has revealed some structural properties of specific transport networks [12]. However, the question remains how to quantify the effectiveness of their interconnections? In this section, we describe a number of measures that have been used to capture the multiplexity of multimodal infrastructures, such as the importance of different nodes, the system's resilience, and the similarity between layers.

Paths At a more global scale, multimodality is often associated with the ability of an agent to navigate the system by using the available transportation modes.

For this reason, the navigation of an agent in a transportation network can be measured through the available types of paths.

A first possibility is to consider the quickest path, neglecting transfer and waiting times between transportation modes. This path is computed using the fastest speed associated to the edges, assuming a perfect synchronization between the different transportation modes. This is analogous to finding the shortest path between i and j in an aggregated weighted-single layer network, where the weight describing the time to travel between two nodes is the minimum among those offered by the different transportation options.

Yet, this approach often falls short in capturing real patterns of mobility. Indeed, transportation networks also have a temporal dimension that has to be taken into consideration. In order to find a path that allows for a change between two or more different transportation options we must find a time-respecting path [76], defined as the shortest path between nodes i and j that considers the departures and arrivals constraints given by timetables. Such timetables are often shared by transport agencies using General Transit Feeds Specification (GTFS) Feeds². Furthermore, for multimodal transportation networks, the walking transfer time between modes has to be taken into account when computing time-respecting paths.

Besides time constraints, in order to find a viable path between i and j , the logic of the proposed sequence of modes has to be assessed [77, 78]. For instance, in some cases, a path composed by subway-bus-subway-car-subway might solve the shortest path, but the presence of private transportation (car) as an intermediate option makes it an “illogical path” and thus an unlikely choice for a user. The validity of transportation sequences can in general be formalized in terms of cost associated to change of transportation mode.

Finding viable paths is one of the most important problems in urban transportation, as it has the potential to help users finding the most efficient paths in the city. Lozano et al. [78] have proposed an efficient algorithm to find such paths when the agent establishes her limitations on the number of modal transfers.

The contribution of the different layers of a multiplex networks to shortest paths might be very unequal [69]. For instance, the rail systems (trams, subway) contribute to most of the shortest paths in a city, connecting distant points at a greater velocity and in straighter routes than bus or other transport modes. However, such layers have only few stations. Slower and more local transport modes often serve a complementary role, offering a deeper coverage of the city.

²For an overview of possible data sources see Section 2.4)

Spatial outreach The availability of different transportation modes, such as subways or tramways affects how easily it is to reach certain locations in the city. A way to measure this effect is to quantify the associated *spatial outreach* [79]. The spatial outreach can be computed as the average distance from node i to all other nodes in the same layer α that are reachable within a given travel cost τ . Mathematically it is defined as follows:

$$L_\tau(i) = \frac{1}{N(\tau)} \sum_{j|\tau_m(i,j) < \tau} d_e(i, j), \quad (2.1)$$

where $d_e(i, j)$ is the distance between nodes i and j , and $N(\tau)$ is the number of nodes reachable on the multilayer network within a travel cost τ .

Strano et al. [79] modified the average speed (traversal time of a link) in the layers of multiplex systems to measure their effects on the corresponding travel outreach. Strano et al. [79] found that when the metro speed increases compared to the street layer speed, a clear area of high-outreach nodes emerges in the city center and around the nodes that have connections to the high-speed layer. In other words, as the velocity in layer β increases, the nodes that are closer to the interchange nodes in layer α improve their accessibility, implying that a person can efficiently travel from this area to faraway places. This concept of travel outreach is similar to that of isochrones which quantify the accessible area from a given point within a certain time threshold, e.g.: What is the area that a user can reach traveling x minutes, in any direction, from a given point? Biazzo et al. [31] used this approach to measure accessibility in different urban areas computing the isochrones as a combination of public transit and pedestrian infrastructure. With this method, scores were obtained that capture how well a city is served by the public transit and how accessible a specific area is to the rest of the city.

Betweenness centrality and interdependence The relevance of the nodes in a network is characterized by centrality scores. Additional to single layer networks, in multiplex networks the overall centrality of a location or station also depends on the interplay of the different transportation options.

The simplest way to define the centrality of a node is to measure its degree, or the number of locations directly connected to it. Such a measure, however, is not so relevant for systems embedded in space due to spatial constraints. For example, the number of possible connections of a given node (intersection) in the street layer is highly constrained by the physical space, as a single intersection can only have a limited number of intersecting streets/sidewalks. For this reason, other centralities than degree are typically used to assess the relevance of a location. One of such measures is the betweenness centrality [80], measur-

ing the number of shortest paths passing via a given node. This measure is also called “load” and can be seen as the simplest proxy for traffic flow in the system as it assumes uniform demand between each pair of nodes. In the absence of explicit mobility data, betweenness centrality can be used as a proxy to assess the areas at risk to become overcrowded and to identify potential bottlenecks in the system.

In multiplex networks, shortest paths from one node to another can pass through links in two or more layers. This effect can be quantified by measuring the interdependence of a given node i as:

$$\lambda_i = \frac{1}{N-1} \sum_{j \neq i} \frac{\psi_{ij}}{\sigma_{ij}}, \quad (2.2)$$

where ψ_{ij} is the number of shortest paths between i and j that use edges in two or more layers, and σ_{ij} is the total number of shortest paths between i and j [64, 39, 79]. Node interdependence takes values in $[0, 1]$, with values close to 1 associated to a high coupling of the layers, while values close to 0 mean that most of the paths from that node to other nodes go through just one layer. By taking the average over all nodes $\lambda = 1/N \sum_i \lambda_i$ it is possible to obtain a single score for the whole system.

This interdependence measure can be modified to obtain a score for a specific layer [69]. Then the layer interdependence for layer α is defined as:

$$\lambda^\alpha = \frac{\sum_i \sum_{i \neq j} \psi_{ij}^\alpha}{\sum_i \sum_{i \neq j} \psi_{ij}}, \quad (2.3)$$

where ψ_{ij}^α describes the number of shortest paths between nodes i and j using two or more layers and such that at least one of them corresponds to layer α .

When applying this measure to multimodal transport networks, Aleta et al. [69] found that the metro and tram layers play an important role in concentrating shortest paths. For Madrid, Aleta et al. [69] found that more than 40% of the trips have at least one link in the metro layer, even if the metro layer has only 241 nodes while the bus layer has 4590 nodes.

As cities grow and new lines and transport modes are added into the mobility system, new interconnections between layers appear, changing the betweenness of the different nodes. Ding et al. [81] studied how centralities evolved when the rail network of Kuala Lumpur grew from a tree-like structure to a more complex one. Their findings suggest that, as the network grows, the average shortest path in the multilayer network can decrease dramatically, especially as new nodes are able to serve as interchange between layers, thus enabling new shortest paths along the system.

The results from Ding et al. [81] are in line with the previous findings by Strano et al. [79], on how the subway layer affect the distribution of nodes centrality in London and New York. Strano et al. [79] show that the introduction of new interconnected layers affects the congestion of the street layer. In fact, the presence of the subway layer allows to move traffic from internal routes and bridges to the terminal points of the subway system which might be used as interchange locations for suburban flows into the city center. Theoretical work by Solé-Ribalta et al. [82] confirms that one of the main drivers affecting traffic dynamics and congestion in multimodal transport networks is the interchange from the least to the most efficient layers.

Resilience Evaluating the robustness of a transport system under failures is an important task with practical implications in urban planning. Notably, multimodality affects significantly the resilience of transportation system [54].

In a single layer network, the disruption of an infrastructure, i.e. the removal of a link, can make a station or a part of the city disconnected. For example, for a transit station in a single layer network: If the links connecting the station with the rest of the system are removed, the station is inaccessible. However, if such a station is part of a multimodal transportation network, it could still be accessed through other layers. To measure the impact of multimodality on resilience, de Domenico et al. [54] used random walks (see Sec.2.3.1) to mimic trips among locations and investigated the coverage time in the London's transportation system under different scenarios. De Domenico et al. showed that the interconnected nature of the different transport modes dramatically enhances the overall system resilience to failure compared with the single layers. A similar approach was followed by Baggag et al. [32], where the coverage time of random walks was used to measure the robustness of the multimodal transportation networks of Paris, London, New York, and Chicago. To mimic realistic trips, Baggag et al. introduced several constraints on the complexity of the trips, for instance limiting the maximum number of transport mode changes. More recently [33] used the multiplex framework to model Singapore's public transportation infrastructure and test its resilience against floods in the city in different scenarios, finding that the system is extremely resilient as it faces the first significant disruption only after the removal of 50% of its edges.

Overlap census Urban transportation networks present different degrees of multimodality and integration. The overlap census proposed by Natera et al. [83] proposed a method to observe, quantify and compare those differences. In Chapter 3 we cover this original contribution in detail.

The overlap census was not the first measure to compare similarities be-

tween multiplex networks and layers. Indeed, similar approaches were developed for multiplex networks more in general. For a detailed view see Nicosia et al. [48] who proposed measures capturing nontrivial correlations in multiplex networks and models to reproduce those correlations. More recently, Brodka et al. [84] also presented an overview of different metrics to compute similarities between layers in multiplex networks.

2.3 Multimodal mobility

Understanding urban travel is paramount for a range of real-world applications, including planning transportation [85] and designing urban spaces. Starting from the 1950s, a large body of literature in the fields of Geography and Transportation has studied how people move and use transportation technology.

As the transport infrastructure becomes increasingly multimodal, modelling how individuals make travel decisions in complex interconnected networks is critical. In recent years, the scientific understanding of human mobility has dramatically improved, also due to the widespread diffusion of mobile-phone devices and other positioning technologies, which allowed to gather large-scale geo-localized datasets of human movements and develop increasingly realistic behavioural models. Concurrently, these recent developments had benefited by the dramatic growth of the fields of Complex Systems and Network Science, which brought together ideal tools to study interconnected systems³. This new data-driven modeling framework for multimodal mobility was pioneered by Kurant et al. [86], who extracted data from public transportation timetables to characterize the mobility structure and traffic flow of a transportation network. Despite recent advancements, our understanding of multimodal mobility in urban systems remains limited, also due to the difficulties related to collecting comprehensive data across multiple transportation modalities.

In this section we review the scientific literature on multimodal mobility. While our focus will be on multimodality, we will inevitably touch upon some concepts related more broadly to modelling of urban travel. In Section 2.3.1, we briefly summarize existing models, focusing on latest advances driven by the Complex Systems literature. In Section 2.3.2, we review measures and empirical findings, with a focus on recent studies based on passively collected data sources.

³For a comprehensive review of the recent literature stream of Human Mobility see [43]

2.3.1 Modeling urban mobility

Modeling travel in a multimodal system involves understanding how individuals make decisions in a constantly changing complex environment. The most common family of models for travel demand in the Geography and Transportation literature are the *four-step models* proposing that each trip results from four decisions [87]: 1) whether to make a trip or not, 2) where to go, 3) which mode to use, 4) and which path to take. For simplicity, these steps have been largely considered as independent, sequential choices, and correspond to four modelling steps: trip generation, trip distribution, mode choice, and route assignment⁴.

In recent years, the field of Complex Systems has modeled travel behavior on multiplex networks using different approaches that we briefly review in this section. Complex Systems research has proposed novel individual [88, 89, 90] and collective [91, 92] models that capture well the first two aspects of travel behaviour: trip generation and trip distribution. In this review, we will focus largely on the last two of the four modelling steps, mode choice and route assignment, because they are the most relevant in the framework of multimodality. It is important to remark that, also due to the lack of empirical data on the mechanisms driving human navigation, many models rely on simplistic assumptions, for example that individuals are rational, homogeneous, or have unlimited knowledge. Research based on novel data sources will be key to developing mobility models on multilayer networks that include realistic elements such as limited knowledge and cognitive limitations.

Random walks. The random walk is one of the most fundamental dynamic processes [93] that has been widely studied in the Complex Systems literature as a prototypical model for numerous phenomena occurring upon networks, including human mobility. Importantly, in contrast to widely used models that assume individuals with global knowledge of the system thus choosing shortest routes [94], random walks assume that agents are only aware of the local connectivity at each node. A random walk on a graph is defined by a walker that, located on a given node i at time t , hops to a random nearest neighbor node j at time $t + 1$. In the case of multilayer networks, the walk between nodes and layers can be described with four transition rules accounting for all possibilities [54]: (i) $P_{ii}^{\alpha\alpha}$, the probability for staying in the same node i and layer α ; (ii) $P_{ij}^{\alpha\alpha}$ the probability of moving from node i to j in the same layer α ; (iii) $P_{ii}^{\alpha\beta}$ the probability of staying in the same node i while changing to layer β ; (iv) $P_{ij}^{\alpha\beta}$ the probability of moving from node i to j and from layer α to β , in the same time

⁴See the review of McNally [87] for a comprehensive overview about this modeling approach

step. These probabilities depend on the strength of the links between nodes and layers, e.g. the frequency of vehicles and the cost associated to switching layers.

Despite their simple formulation, random walks provide fundamental insights to many types of diffusion processes on networks and allow to measure a network's dynamical functionality. For example, random walk processes were used to measure the navigability of multiplex networks [54]. To this end, one can measure the coverage of the multiplex network $\rho(t)$, defined as the average fraction of distinct nodes visited by a random walker in a time shorter than t (assuming that walks started from any other node in the network), and describing the efficiency of a random walk in the network exploration:

$$\rho(t) = 1 - \frac{1}{N^2} \sum_{i,j=1}^N \delta_{i,j}(0) \exp[-\mathbf{P}_j(0) \mathbb{P} \mathbf{E}_i^\dagger], \quad (2.4)$$

where $\mathbf{P}_j(0)$ is the supravector of probabilities at time $t = 0$, the matrix \mathbb{P} accounts for the probability to reach each node through any path of length $1, 2, \dots$, or $t + 1$, and \mathbf{E}_i^\dagger is a supra-canonical vector allowing to compact the notation. De Domenico et al. [54], showed that the ability to explore a multilayer network is influenced by different factors, including the topological structure of each layer and the strength of interlayer connections and the exploration strategy. Further, they showed that the multilayer system is more resilient to random failures than its individual layers separately because interconnected networks introduce additional paths from apparently isolated parts of single layers, and thus enhance the resilience to random failures.

Random walks have further been used to assign a measure of importance to each node in each layer, by measuring the asymptotic probability of finding a random walker at a particular node-layer as time goes to infinity, the so-called *occupation centrality* [93]. Solé-Ribalta et al. [93] provided analytical expressions for the occupation centrality in the case of multilayer networks.

Travel time minimization approaches. At the other end of the spectrum, where agents are assumed to have global (or nearly global) knowledge of the system, Complex Systems research has developed models where agents aim at minimizing their individual travel times in congested [95, 96, 97, 82] or uncongested [98, 67] networks. A similar approach, rooted in Wardrop's first principle [94], is widespread in transportation planning [87].

Bassolas et al. [96] developed an agent-based models describing mobility of individuals through a multilayer transportation system with limited capacity. The routing protocol used by individuals for planning is adaptive with local information. In the absence of congestion, individuals follow the temporal optimal path of the static multilayer network calculated by the Dijkstra algorithm.

If there are line changes, Bassolas et al. [96] estimate besides the change walking penalty an additional waiting time of half the new line period (the real waiting time will be given by the vehicles' location in the line when the individual arrives at the stop). An individual's route is only recalculated when a congested node, whose queue is larger than the vehicle's capacity, is reached. The work investigates analytically (for simple networks) and via numeric simulations the robustness of the network to exceptional events which give rise to congestion, such as demonstration concerts or sport events. The study revealed that the delay suffered by travellers as a function of the number of individuals participating in a large-scale event obeys scaling relations. The exponents describing these relations can be directly connected to the number and line types crossing close to the event location. The study suggested a viable way to identify the weakest and strongest locations in cities for organizing massive events.

Similarly, Manfreid et al. [97] introduced a limit to the nodes capacity of storing and processing the agents. This limitation triggers temporary faults in the system affecting the routing of agents that look for uncongested paths.

Importantly, the assumption that individuals have global knowledge of the system and minimize travel time contrast recent findings in spatial cognition, showing that human spatial knowledge and navigation ability is limited [45, 99]. For example, a recent study on pedestrian navigation made clear that path choices seem to be affected by the orientation of street segments along the route [99]. Recent modelling approaches for single-layer networks [100] incorporate these ideas in routing models where agents are characterized by bounded knowledge and limited rationality. Further research will be necessary to develop realistic multilayer routing models accounting for the limits of spatial cognition.

2.3.2 Characterizing multi-modal mobility.

Traditionally, multimodal mobility models are calibrated using data from travel surveys: *Revealed Preference* surveys retrieve actual travel information from the respondents, while *Stated Preference* surveys expose the travelers to various hypothetical scenarios and record their choices [101]. Studies based on survey data have provided insights into how multimodal travelers value aspects such as the different travel time components (in-vehicle time, walk time, access time, wait time...) [102], service quality [103], travel costs [101], and heterogeneities across socio-demographic groups [104]. Due to the high costs associated with data collection and inherent biases in self-reported data, these studies suffer from serious limitations, including small sample sizes, data inaccuracy and incompleteness [105, 106]. Covering empirical results from travel surveys is outside the scope of this review, and we refer the reader to Arentze et al. [101] for a

comprehensive introduction to the topic.

In recent years, the empirical research on Human Mobility has taken new directions. A growing body of literature has focused on quantitative descriptions of human movements from large, automatically collected data sources, such as mobile phone records, travel cards and GPS traces [43]. In this section, we give an overview of recent empirical findings on multimodal mobility in the field of Complex Systems which focused on two important aspects: 1) the dynamics of public transport systems, whose study was driven by the availability of public transport data such as schedules and positions of stop and stations, and 2) individual multimodal behaviour driven by the availability of data collected using ‘smart travel cards’ and GPS data.

The existing empirical research on multimodal travel based on passively collected data-sources is far from being comprehensive. Most studies have focused on public transit, such that the interplay between public and forms of private transportation such as walking, driving and cycling has been poorly characterized. Further, several studies are based on public transport schedules instead of real-time data, thus neglect important effects deriving from congestion. The increasing availability of high-resolution GPS trajectories collected by individual mobile phones and sensors installed on private and public transport vehicles [43] will be key to filling these gaps in the literature.

Public transport systems dynamics.

Over the last decade, the availability of detailed public transport schedules shared by public transport companies (see also Section 2.4) has allowed to better estimate travel times and characterize transport systems.

Efficiency To satisfy the demand of large number of individuals while reducing energy and costs, multilayer transport systems must achieve high efficiency. One aspect concerns the *synchronization* between the network layers, because the more layers are synchronized, the less users have to wait for vehicles. The synchronization inefficiency $\delta(i, j)$ [76, 46] for nodes i and j can be measured as the ratio of the time-respecting travel time $\tau_t(i, j)$, which accounts for walking and waiting times and the fact that the speed of vehicles varies during the day, and the minimal travel time $\tau_m(i, j)$, assuming that vehicles travel at their maximum speed and that transfers are instantaneous:

$$\delta(i, j) = \frac{\tau_t(i, j)}{\tau_m(i, j)} - 1 \quad (2.5)$$

Using the synchronization inefficiency, Gallotti et al. [76] showed that, on average in the UK, 23% of travel time is lost in connections for trips with more

than one mode. Interestingly, across several urban transport system in the UK, the synchronization efficiency $\delta(i, j)$ obeys the same scaling relation with the path length $\ell(i, j)$:

$$\delta(i, j) \approx \delta_{min} + \frac{\delta_{max} - \delta_{min}}{\ell(i, j)^v}, \quad (2.6)$$

with $v \approx 0.5$ and where δ_{max} and δ_{min} are the maximum and minimum values of $\delta(i, j)$ for a given urban transport system.

Further, Gallotti et al. [76] have shown that the average synchronization inefficiency $\bar{\delta}$ for a given urban system follows:

$$\delta \sim \Omega^{-\mu}, \quad (2.7)$$

where Ω is the total number of stop-events per hour (e.g. the number of times a vehicle stops), and $\mu = 0.3 \pm 0.1$.

Other studies focused on the efficiency in terms of ability to satisfy users demand. Alessandretti et al. [107], introduced a method based on non-negative matrix factorization to compare the network of commuting flows and the public transport network. This methodology, applied to various public transport systems in France, showed that, while in Paris the transportation system meets the overall demands, it does not do so in smaller cities where people prefer to use a car despite having access to fast public transportation. Sui et al. [108] proposed three topological metrics to quantify the interaction between public transport network and passenger flow and applied it to study differences between the cities of Chengdu and Qingdao in China. Hollecsek et al. [109] used data mining approaches to compare the use of public and private transportation and identify the existence of weak transportation connections.

Congestion. Congestion can dramatically alter travel time estimates for routes that use popular network links in an urban system, but adding network layers in a multilayer transport system can help reduce global congestion [110]. Given a network with edges e and flows j_e , one can quantify the total time lost in congestion as

$$T_c(\mathbf{j}) = \sum_{e \in \mathcal{L}} j_e(t_e^* - t_e(j_e)), \quad (2.8)$$

where \mathbf{j} is the vector of flows whose e th element is the flow along edge e , t_e^* is the free flow time on edge e (in the absence of congestion), and $t_e(j_e)$ is the congested travel time in the presence of flow j_e . This measure can be used to analyze the impact of changes in flow along a route. The quantity

$$\Delta_p = -\nabla T_c(\mathbf{j}) \cdot \mathbf{e}_p \quad (2.9)$$

where p is a path and \mathbf{e}_p is the vector whose e th component is 1 iff $e \in p$, quantifies the impact of removing a single unit of flow from p on the global congestion function T_c . Chodrow et al. [110] quantified how the creation of a planned metro network in Riyadh would affect congestion, by quantifying the change Δ_p as a function of the speed ratio between the street and metro systems:

$$\beta = v_c/v_m \quad (2.10)$$

Using this approach, Chodrow et al. showed that, as the subway speed increases global congestion is reduced, but it increases locally close to key metro stations.

Navigability As cities and their transportation systems become increasingly complex and multimodal, it is important to quantify our difficulty navigating in them. It has been shown that multilayer transport system are characterized by limited navigability, implying that finding one's way is cognitively challenging [45]. To quantify the difficulty of navigating between two nodes s and t in a network, one can compute the total information value of knowing any of the shortest paths to reach t from s :

$$S(s \rightarrow t) = -\log_2 \sum_{\{p(s,t)\}} P[p(s,t)] \quad (2.11)$$

where $p(s,t)$ is the set of shortest paths between s and t (note that there can be more than one with the same length) and $P[p(s,t)]$ is the probability to follow path $p(s,t)$, making the right choice at each intersection along the path [111]:

$$P[p(s,t)] = \frac{1}{k_s} \prod_{j \in p(s,t)} \frac{1}{k_j - 1}, \quad (2.12)$$

Gallotti et al. [45] quantified the amount of information an individual needs to travel along the shortest path between any given pair of metro stations, in the single-layer metro networks for 15 large cities. They found that this information has an upper bound of the order of 8 bits, corresponding to approximately 250 connections between different routes. Further, studying several among the largest multilayer transport networks (metro/buses/light rail), Gallotti et al. [45] showed that the amount of information necessary to know to travel between any two points exceeds the identified cognitive limit of 8 bits in 80% the cases, suggesting multilayer networks are too complex for individuals to navigate easily.

Individual multi-modal behaviour.

In recent years, data collected via smart travel cards has dramatically improved our ability to characterise multimodal behaviour in urban transport systems, overcoming some of the limitations related to collecting and analyzing survey data [105, 106]. Smart-card automated fare collection systems allow passengers to make journeys involving different transport modes using magnetic cards and automatic gate machines. As these systems identify and store the location and time when individuals board and, in some cases, exit public transport, they collect accurate descriptions of individual travel [112]. Concurrently, advancements were made possible by the development of methodologies allowing to identify typical travel patterns [113].

Route choices. Smart-card data has allowed to quantify how individuals navigate multilayer networks. One of the key findings is that individuals do not choose optimal paths (those with shortest travel time), especially when the system is congested. Focusing on the bus and subway trips of 2.4 million passengers in Shenzhen (China), Zheng et al. [114] studied the coupling (see eq. 2.2) between the bus and subway layers. In contrast to previous studies [79], Zheng et al. [114] characterized the coupling λ using passenger behaviour rather than structural properties of the multilayer network. Under their definition, the *coupling* between layers is the fraction of multimodal trips actually undertaken by passengers, rather than the fraction of multimodal shortest paths (see eq. 2.2). Zheng et al. found that this ‘behavioural’ coupling correlates weakly with the empirical speed ratio measured between the two layers over time, implying that passengers choose unimodal trips even when multimodal trips may be preferred because one of the two layers is congested. This finding highlights that the speed ratio of different network layers, which was regarded as a key factor in determining coupling strength [79, 110], may have a negligible effect on travelers’ route selections, possibly because passengers do not have a full view of the status of traffic. Instead, Zheng et al. [114] showed that the coupling between layers is generated by long-distance trips originating from nodes served by a single transport layer.

Power-law distribution of displacements The availability of large-scale data sources has revealed that individual mobility patterns display universal properties. One key finding is that the distribution $P(\Delta r)$ describing the probability of travelling a given distance Δr is characterized by a power-law tail $P(\Delta r) \sim \Delta r^{-\beta}$, with $1 \leq \beta \leq 2$ [44, 43]. This finding is consistent across a range

of studies that used different data sources⁵. It was recently shown that these observed scaling properties result from the aggregation of movements within and across characteristic spatial scales, corresponding to the sizes of buildings, neighbourhoods, cities and regions [90]. Further, the emergence of scaling properties was associated to the use of multimodal transportation: Zhao et al. [116] used GPS data to show that mobility using a single mode can be approximated by a lognormal distribution, but the mixture of the distributions associated with each modality generates a power-law; Gallotti et al. [117] found that a simple model where individual trajectories are subject to changes in velocity generates a distribution of displacements with a power-law tail. In fact, individuals using multimodal infrastructure are subject to drastic changes in velocity. Varga et al. [118] showed that the travel speed v increases with travel distance according to the power-law functional form $v \sim r^\alpha$, where $\alpha \approx 0.5$. This dependence is due to the hierarchical structure of transportation systems and the fact that waiting-times (parking, take-off, landing, etc) decrease as a function of trip distance.

2.4 Open data & Tools

Together with other fields, urban and transportation science are becoming more open, increasingly relying on datasets and computational tools freely available to the scientific community. In this section we highlight some of these openly available datasets and computational resource developed for the analysis of multimodal transport networks.

2.4.1 Data

During the last years new datasets have been made publicly available either from the public sector or from crowd-sourced data, allowing to go beyond simulations and synthetic data to understand how urban dynamics and mobility unfold, providing a better picture of the world.

In the last years, the study of transportation networks has benefited from the development of OpenStreetMap [119], an open-source collaborative project focused on collecting and sharing world-wide high-quality spatial data [120, 121, 122, 43]. Data extracted from OpenStreetMap allows to build and analyse several transportation networks, of which the most common are street networks [25, 123]. Data from OpenStreetMap is further useful to obtain information about infrastructures, such as subways and railways. All such data

⁵see Ref. [115] for an extensive review

can be combined to build multimodal transport networks. Gil. [124] obtained multimodal data from OpenStreetMap and built a multiplex network for the Randstad region of the Netherlands linking the layers through the intersections between transport modes. More recently, Natera [125] followed the same approach to analyse the multiplex transport of fifteen cities in different development stages, including London, Los Angeles, and Mexico City.

As the transportation network of a city also encodes a temporal dimension, it is important to take into account the frequency of buses, tramways, and subways when modeling transportation and mobility. To capture these dynamics, Gallotti et al. [126] constructed and shared the temporal network of public transport in Great Britain. This is a large dataset, where links, associated to flows from one location to another, only exist at specific times. Link information has to be properly combined to compute travel time from origin and destination, highlighting the importance of synchronization of the different transportation models. An interesting feature of this dataset is that it not only contains the public transport layers of several cities, but also connections among them, for instance through coaches, planes, and ferries operating at the national level.

In general, the use of timetables and transit feeds has been enabling researchers to capture with increasing accuracy the dynamics of public transportation systems. A large collection of GTFS feeds in multiple locations has been collected and made freely available as a webpage [127]. These datasets include stops, routes and timetables of public transport in multiple cities and providers from 667 locations around the world. As shown by Aleta et al. [69], these data can be used to analyze the public transportation as a multiplex network, considering each bus line and/or transport provider as one layer. Using the data from GTFS feeds, Kujala et al. [128] built and published a collection of 25 urban public transport networks covering cities from North America, Europe, and Oceania. This dataset is peculiar as it also includes the pedestrian layer of the cities, and public transport is further differentiated across the different public transport modes.

More recently, Tenkanen et al. [129] published an accurate multimodal dataset for the Helsinki region in Finland. This dataset includes multiple transport modes, such as walking, cycling and public transportation options. To calculate the travel times Tenkanen et al. [129] use a door-to-door principle. This means that travel time and distance are calculated considering every step of a journey, including walking legs and transfers between vehicles. An important feature of this dataset is the inclusion of travel time matrices for three distinct years, 2013, 2015 and 2018. This is a rare occasion to compare how travel times changed over the years, allowing a characterization of the evolution of human mobility.

Concerning mobility, the Geolife dataset [130] consists of GPS trajectories collected by Microsoft Research Asia for 178 users in a period of over four years (from April 2007 to October 2011). 69 users labeled their trajectories with the corresponding transportation mode, such as driving, taking a bus, riding a bicycle and walking. As such, the GeoLife data has allowed to investigate mobility behaviours using different transport modes [116].

The data described above are freely available, and represent an opportunity for further data-driven investigations of multimodal transportation networks.

2.4.2 Tools

Over the years computational tools have become more and more important for studying urban systems, and in particular transportation networks⁶.

Multiple tools allow to work with graphs. A few examples of freely available softwares and tools are: *Networkx* [132], *igraph* [133], and *graph-tool* [134]. These tools are freely available and constantly updated over time relying on contributions from an engaged community. Although these tools serve a general purpose, they can also be used for the study of transportation networks.

Multiple tools were developed to obtain data on transportation and multimodal infrastructures. One of the best known is *OSMnx* [135], a Python package that downloads street networks from OpenStreetMap into Python objects. *OSMnx* can further be used to download other transportation networks, and build its multimodal transport networks.

Another reliable Python library to read data from OpenStreetMap and extract transportation networks is *Pyrosm* [136]. Differently from *OSMnx*, *Pyrosm* reads the data directly from OpenStreetMap's Protocol Buffer Format files (*.osm.pbf), while *OSMnx* downloads the data from the Overpass API [137]. For this reason *Pyrosm* is a particularly good alternative when working with large urban areas, states, and even countries, while *OSMnx* typically offers a more precise way to collect data from specific points in a city.

To work with public transportation data Google developed *transitfeed* [138], a Python library to parse, validate and build GTFS files. This tool is particularly useful to those interested in the manipulation of the raw data. However, to convert the data into a network, some additional steps are needed. An alternative to read the GTFS feeds and directly extract its transportation network is *Pearmtree* [139], a Python library allowing to convert GTFS feed schedules into the corresponding directed network graph.

Movingpandas, developed by Graser [140] is a Python package that provides trajectory data structures and functions for the analysis and visualisa-

⁶For an overview of the available tools in geographic analysis in transport planning see [131]

tion of mobility data. In a similar sense, and also developed in Python, *scikit-mobility* [141] is a library that implements a framework for analyzing statistical patterns and modeling mobility, including functions for estimating movement between zones using spatial interaction models, and tools to asses privacy risks related to the analysis of mobility datasets.

The aforementioned tools were not built specifically with the purpose to work with multiplex networks. To cover this need, specific libraries have been developed. A first example is *muxViz* by de Domenico et al. [142], a stand-alone front-end tool which allows the computation of several multilayer measures, from centrality to community detection. *MuxViz* is also an advanced visualization tool, providing an effective way to display edge-colored multigraph or multislice networks.

Several software options are available in Python, often built on top of NetworkX. A library originally designed for the study of multilayer networks, which can be easily adapted to multimodal networks, is *MAMMUL* by Nicosia et al. [143]. This library contains a collection of algorithms to analyze and model multilayer networks. The functions included in the collection cover a wide range of applications from structural properties, such as node, edge, and layer basic properties, to the analysis of dynamics on multilayer networks, such as random walks.

Another example is *multiNetX* [144]. This library extends Networkx allowing the creation of undirected weighted and unweighted multilayer networks from Networkx objects. Once the multilayer networks are built, the library focuses on the spectral properties of the corresponding adjacency or Laplacian matrices. This tool also provides nice visualization tools improving from Networkx, allowing the user to better visualize multilayer dynamics through coloring the nodes and links over time.

A more recently developed Python library, not relying on Networkx, is *Pynet* [145]. The package handles general multilayer networks, including multiplex networks with temporal variables. For this reason, it is possible to use it for the analysis of multimodal urban transport networks that incorporate transit schedules. This library also includes multiple network analysis methods, transformations, and models to analyze and visualize multilayer networks. Another alternative is the *multinet* library [146], available both in Python and R. This package provides tools to work with multilayer networks, including community detection and visualizations. When visually working with multilayer networks it is important to account for principles of visualization and cognitive overload [147]. Another option in R is *multiplex* developed by Rivero et al. [148]. This library offers multiple functions to work with matricial representations and visualization of multilayer networks.

Finally, tools such as *mapbox* [149], *carto* [150], *kepler.gl* [151], and *studio unfolded* [152], built on top of OpenStreetMap [119], allow to create and share geospatial interactive web visualizations. While these tools have not been designed to work specifically with networks, it is possible to leverage their geospatial visualization capabilities to create appealing visualization of urban systems.

All the aforementioned tools are available freely online, with an open source code open to edits, collaborations and improvements. Most tools for multilayer network analysis currently serve a general purpose and have not been designed to support features for multimodal transportation networks in particular. Given the growing interest in this topic, we anticipate future open source libraries built specifically for multimodal urban data.

2.5 Conclusions

In this review we discussed the state-of-the art in the field of multimodal mobility and multilayer transport networks from a complexity science perspective, focusing on urban environments. On one hand we covered the science of the *dynamics* of mobility: How do people move? Which forms of transportation do they use? How do they find their paths or switch between modes? On the other hand these dynamics take place on an underlying (*infra*)structure which can be well modeled by multilayer networks. In this context, a number of mathematical metrics have been developed in network science recently which allow the rigorous study of the topic. Parallel to the methodological developments we have witnessed a spur of new computational tools – many of them open source – and datasets which considerably facilitate and boost further research on the topic. Despite an explosion in geospatial data collection, it is still relatively difficult to access spatio-temporally fine-grained – and appropriately anonymized [153] – mobility data openly. Such high-quality data are in danger of being siloed in by commercial stakeholders, obstructing transparent research on the topic. We must therefore push for the implementation of better systems by governments, academia, and industry to recognize and promote efforts for making data sets and tools openly available by and for researchers [154, 131].

The increasing availability of mobility data, concurrently with the continuous growth and developments of urban transport infrastructures are raising new research challenges. A first critical issue relates to the modelling of shared mobility services, such as shared bicycles and vehicles [41]. Multimodal frameworks that integrate shared services with traditional public and private transport infrastructures are becoming necessary to ensure real-time and user-centered solutions for planning, forecasting and managing services, while in-

creasing safety, reducing congestion and emissions. A second important area focuses on investigating at scale the decision-making processes underlying individual transport mode choice and routing behaviour leveraging the increasingly available high-resolution individual traces. We anticipate that this new understanding will be key to describe how microscopic decision-making processes contribute to the emergence of collective mobility flows in multimodal systems.

Despite the currently exploding research on multimodal mobility, there exists a wide frontier of topics to tackle and new approaches to explore. Important advances on multimodal mobility and transportation have been shown to be interdisciplinary, and have clearly benefitted from the large variety of scientific fields and practices. Indeed, synergies between disciplines such as urban planning, geoinformatics, computer science, or physics have increased in the last few years, giving rise to new interdisciplinary approaches such as a Science of Cities or Urban Data Science. We envision that research on multimodal mobility and transportation will maintain a highly interdisciplinary character in the future. For example, the study of human mobility has recently benefited from novel scientific advances from other fields such as deep learning. Luca et al. [155] offers a comprehensive overview of the topic and its applications to human mobility, surveying data sources, public datasets, and deep learning models, and we anticipate the possibility that this area will soon make an impact in unveiling new features of multimodal mobility and transportation.

Finally, understanding multimodal mobility and its underlying infrastructure is of paramount importance for developing sustainable urban transport, as it relies on the central role of public transport modes. Indeed, studying multimodal mobility is one piece in the puzzle towards reversing the global societal threat of climate change which is caused to a considerable extent by car-centric transport monocultures. For this reason, we hope that our review can serve as a starting point to develop a more modern, sustainable and integrated idea of mobility worldwide.

CHAPTER 3

EXTRACTING THE MULTIMODAL FINGERPRINT OF TRANSPORTATION NETWORKS

Urban mobility increasingly relies on multimodality, combining the use of bicycle paths, streets, and rail networks. These different modes of transportation are well described by multiplex networks. Here we propose the overlap census method which extracts a multimodal profile from a city's multiplex transportation network. We apply this method to 15 cities, identify clusters of cities with similar profiles, and link this feature to the level of sustainable mobility of each cluster. Our work highlights the importance of evaluating all the transportation systems of a city together to adequately identify and compare its potential for sustainable, multimodal mobility¹.

¹A stand alone of this chapter has been published in Transport findings [83].

3.1 Evolution of urban networks

In the previous chapter, we survey the literature on the topic of multimodal transportation networks. In this chapter, we provide an original contribution to the topic by suggesting a method to extract the multimodal profile from a given city's multiplex transport network.

The infrastructure of different modes of transportation can be described as a mathematical object, the multiplex transport network [64, 28, 156, 39, 76, 54, 79, 69, 157]. A city's multiplex transport network contains the layer of streets and other co-evolving network layers, such as the bicycle or the rail networks, which together constitute the multimodal transportation backbone of a city. Due to the car-centric development of most cities [4], streets form the most developed layers [158, 159] and define or strongly limit other layers: For example, sidewalks are by definition footpaths along the side of a street and make up a substantial part of a city's pedestrian space [158]. Similarly, most bicycle paths are part of a street or are built along the side. Yet, the different layers of a multimodal network typically serve as diverse channels to permeate a city. Here we consider the transport networks of 15 world cities and develop an urban fingerprinting technique based on multiplex network theory to characterize the various ways in which transport layers can be interconnected, identifying the potential for multimodal transport. Using clustering algorithms on the resulting urban fingerprints, we find distinct classes of cities, reflecting their transport priorities.

3.2 Data: Building the multiplex urban network

We acquired urban transportation networks from multiple cities around the world, defined by their administrative boundaries, using OSMnx [135] a Python library to download and construct networks from OpenStreetMap (OSM). OSMnx simplifies the OpenStreetMap's raw data to retain only nodes at the intersections and dead ends of streets, and the spatial geometry of the edges, generating a length-weighted nonplanar directed graph [14]. These data sets are of high quality [120, 121] in terms of correspondence with municipal open data [160] and completeness [43]. The various analyzed urban areas and their properties are reported in Table 3.1. Figure 3.1 shows the different network layers for Manhattan, one of our analyzed cities.

Code to replicate our results is available as Jupyter Notebooks (<https://github.com/naturaluis/Multimodal-Fingerprint>) and data can be downloaded from Harvard Dataverse [125].

To characterize the city as a multiplex network [38, 37, 57] we follow the approach presented in section 2, in which the system has M layers and N nodes

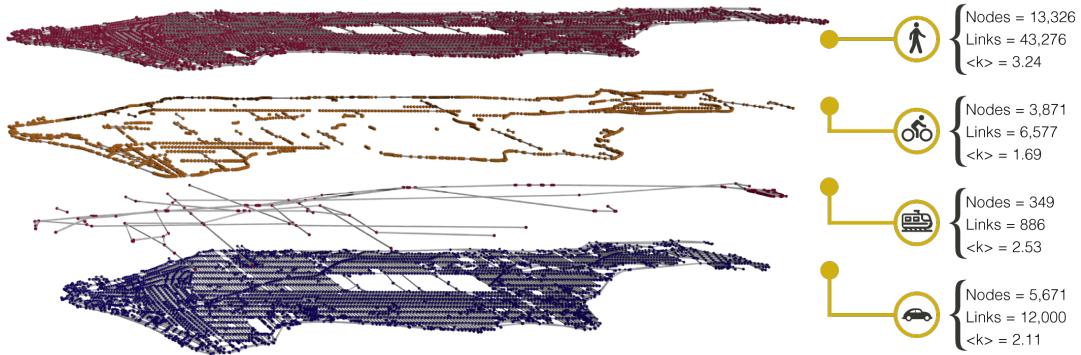


Figure 3.1. (Map plot left) Multiplex network representation of Manhattan with the four analyzed layers of transport infrastructure (pedestrian paths, bicycle paths, rail lines, and streets), with data from OpenStreetMap. (Right) Network information for each layer, number of nodes, links and average degree $\langle k \rangle$.

	Pedestrian			Bicycle			Rail			Street			Population
	Nodes	Links	$\langle k \rangle$	Nodes	Links	$\langle k \rangle$	Nodes	Links	$\langle k \rangle$	Nodes	Links	$\langle k \rangle$	
Amsterdam	23,321	33,665	2.89	34,529	35,619	2.06	1,096	1,655	3.02	15,125	21,722	2.87	872,680
Barcelona	20,203	30,267	3.00	7,553	7,647	2.02	249	249	2.00	10,393	15,809	3.04	1,600,000
Beihai	2,026	2,978	2.94	0	0	0.00	59	62	2.10	2,192	3,209	2.93	1,539,300
Bogota	81,814	121,038	2.96	9,760	9,651	1.98	166	165	1.99	62,017	91,197	2.94	7,412,566
Budapest	73,172	106,167	2.90	10,494	10,318	1.97	1,588	1,964	2.47	37,012	52,361	2.83	1,752,286
Copenhagen	30,746	41,916	2.73	13,980	13,988	2.00	276	369	2.67	15,822	20,451	2.59	2,557,737
Detroit	47,828	78,391	3.28	3,663	3,626	1.98	20	21	2.10	28,462	45,979	3.23	672,662
Jakarta	140,042	191,268	2.73	248	231	1.86	58	54	1.86	138,388	188,637	2.73	10,075,310
LA	89,543	128,757	2.88	14,577	14,428	1.98	173	221	2.55	71,091	101,692	2.86	3,792,621
London	270,659	351,824	2.60	62,398	60,043	1.92	2,988	3,535	2.37	179,782	219,917	2.45	8,908,081
Manhattan	13,326	21,447	3.22	3,871	3,777	1.95	349	436	2.50	5,671	9,379	3.31	1,628,701
Mexico	108,033	158,425	2.93	5,218	5,278	2.02	370	364	1.97	95,375	140,684	2.95	8,918,653
Phoenix	111,363	157,075	2.82	35,631	35,979	2.02	105	138	2.63	73,688	102,139	2.77	1,445,632
Portland	50,878	72,958	2.87	24,252	24,325	2.01	230	340	2.96	35,025	49,062	2.80	583,776
Singapore	82,808	110,612	2.67	12,981	12,947	1.99	683	740	2.17	50,403	66,779	2.65	5,638,700

Table 3.1. Measures for the administrative area of analyzed cities. The number of nodes, links and average degree ($\langle k \rangle$) for each layer in all cities of our dataset are highly diverse due to the varying developmental levels and focus of transport. The range of population in the analyzed cities goes from half million people to ten million people living in Jakarta, this allows to have a range of different sizes and cover different developmental stages.

that can be active in one or more layers in the system. Layers follow a primal approach [13] where nodes represent intersections (that may be present in one or more layers), and links represent streets (denoted by s), bicycle paths and designated bicycle infrastructure (b), subways, trams and rail infrastructure (r), or pedestrian infrastructure (p). Construction of these intersection nodes follows the topological simplification rules of OSMnx [135]. This recent approach

has been useful to demonstrate how cities grow [28, 156], how efficient [76] and dense they are, and to capture the tendency of travel routes to gravitate towards city centers [157]. Each layer $\alpha = 1, \dots, M$ is described by adjacency matrix $A^{[\alpha]} = a_{ij}^{[\alpha]}$ where $a_{ij}^{[\alpha]} = 1$ if there is a link between nodes i and j in layer α and 0 otherwise. The multiplex urban system is then specified as a vector of adjacency matrices $A = (A^{[1]}, \dots, A^{[M]})$.

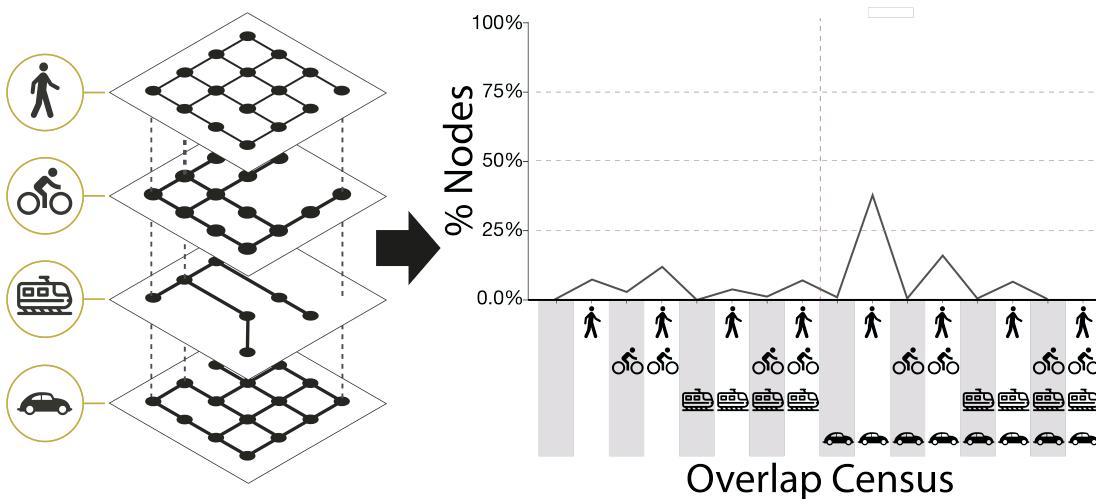


Figure 3.2. Schematic of multiplex layers in a city (left) and its transformation to the overlap census (right). In the overlap census, the vertical red line gives a visual separation of the left from the right half where nodes become active in the street layer. High spikes in the right half indicate car-centricity.

3.3 Overlap census: A local measure of multimodal integration

Whereas one of the simplest features of single layer networks is the degree distribution, in multiplex networks a node can have different degrees in each layer, which inform us about the multimodal potential of a city through the different roles that its intersections play. If a city has nodes that are mainly active in one layer but not in others, there is no potential for multimodality. On the contrary, in a multimodal city we expect to find many transport hubs that connect different layers, such as train stations with bicycle and street access, i.e. nodes that are active in different multiplex configurations. Note that even in a multimodal “optimal” city there will be a high heterogeneity of node activities due to the

different speeds and nature of transport modes, implying, for example, a much lower density of nodes necessary for a train network than for a bicycle network. Still, if we had a way to see and compare all combinations of node activities in the system, we could learn how much focus a city puts on connecting different modes. We can define such a fingerprint using the multiplex network formalism.

In a multimodal city, we expect to find many transport hubs that connect different layers, such as train stations with bicycle and street access, i.e. nodes that are active in different multiplex configurations. Here we propose a method to assess all such combinations of node activities in the system, helping us to learn how well-connected different modes are. For each city, we build a profile based on the combinations of node activities, and refer to it as *overlap census* (Figure 3.2). The overlap census captures the percentage of nodes that are active in different multiplex configurations and provides an “urban fingerprint” of its multimodality [69]. To define the overlap census formally, given a multiplex transport network with M layers the overlap census is a vector of $(2^M) - 1$ components, which accounts for the fractions of nodes that can be reached through at least one layer.

In Fig. 3.2 we show a schematic of how the overlap census is built: taking the multiplex network, and calculating the percentage of nodes that overlap in different configurations. The multiplex approach addresses the multimodality of a city: it not only counts how many nodes or links there are in each layer, but it shows how they are combined, revealing the possible multimodal mobility combinations in the city. Understanding the possibilities for interchange between mobility layers provides us with a better understanding of urban systems, showing us the complexity and interplay between layers.

3.4 Identifying clusters of cities with the Overlap Census

Due to the expected heterogeneity of node activities in different layers, the overlap census of a specific city is also expected to be heterogeneous and hard to assess on its own. Therefore, a good way to assess a city’s overlap census is by comparing it with the overlap census of other cities. We find similarities between cities via a k-means algorithm fed with fifteen vectors (one per city), where each vector contains the percentages of nodes active in each possible configuration. The algorithm separates the 15 analyzed cities into six different clusters [Fig. 3.3].

On the left half of the overlap census, we show the configurations in which

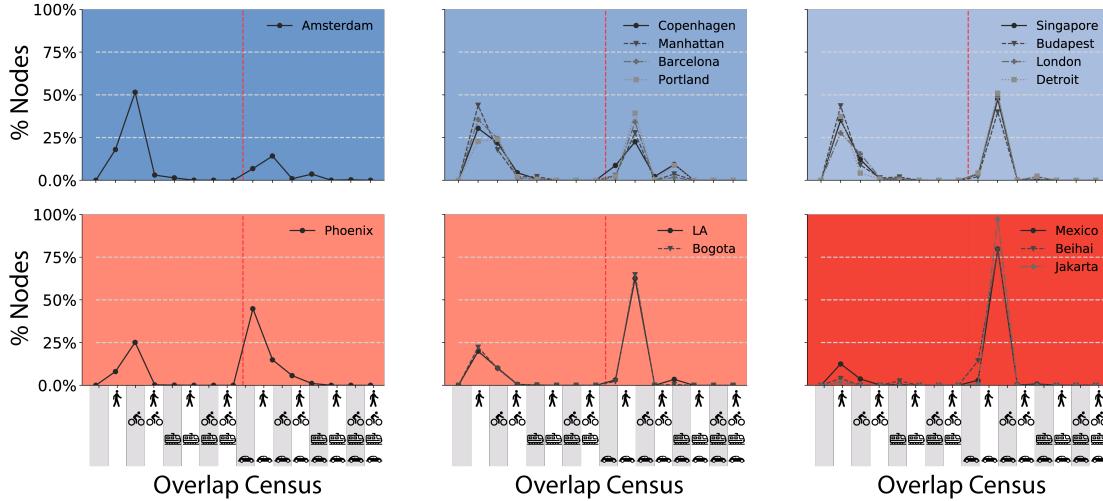


Figure 3.3. Clusters of cities based on similarity of their overlap census. We find six different clusters using a k-means algorithm (coloured areas), which explain more than 90% of the variance.

nodes are not active in the street layer, while the right half contains car-related configurations [Fig. 3.3]. These clusters of cities are useful to explain similarities in infrastructure planning in different transport development paths [161, 24], with clusters of car-centric urbanization (like Mexico, Beihai, and Jakarta) opposed to clusters that show a more multimodal focus in their mobility infrastructure (like Copenhagen, Manhattan, Barcelona, and Portland). In the extreme cluster that contains only Amsterdam, close to 50% of nodes are active in the bicycle layer, whereas in the Mexico-Beihai-Jakarta cluster more than 50% of nodes are active in the street-pedestrian configuration. The concentration of nodes in just one configuration informs not only about the mobility character of the city, i.e. Amsterdam being a bicycle-friendly city, but unveils the importance of explicitly considering overlooked layers and their interconnections. For example, Singapore, Budapest, London, and Detroit have two main peaks indicating that most of their nodes are either active in the street-pedestrian or only in the pedestrian configuration. This is not the case in Los Angeles and Bogotá, where the majority of nodes are active in the car-pedestrian combination, i.e. the pedestrians have to share most of the city with cars. Our multimodal fingerprint unravels how different transport modes are interlaced, helping to identify which layer (or set of layers) could be improved to promote multimodal, sustainable mobility.

To summarize, we propose the new “overlap census” method based on multiplex network theory allowing to rigorously identify and compare the multi-

modal potential of cities.

CHAPTER 4

DATA-DRIVEN STRATEGIES FOR OPTIMAL BICYCLE NETWORK GROWTH

Urban transportation networks, from sidewalks and bicycle paths to streets and rails, provide the backbone for movement and socioeconomic life in cities. To make urban transport sustainable, cities are increasingly investing to develop their bicycle networks. However, it is yet unclear how to extend them comprehensively and effectively given a limited budget. Here we investigate the structure of bicycle networks in cities around the world, and find that they consist of hundreds of disconnected patches, even in cycling-friendly cities like Copenhagen. To connect these patches, we develop and apply data-driven, algorithmic network growth strategies, showing that small but focused investments allow to significantly increase the connectedness and directness of urban bicycle networks. We introduce two greedy algorithms to add the most critical missing links in the bicycle network focusing on connectedness, and show that they outmatch both a random approach and a baseline minimum investment strategy. Our computational approach outlines novel pathways from car-centric towards sustainable cities by taking advantage of urban data available on a city-wide scale. It is a first step towards a quantitative consolidation of bicycle infrastructure development that can become valuable for urban planners and stakeholders.¹

¹A stand alone version of this chapter has been published in Royal Society Open Science [162].

4.1 Bicycles in urban networks

In the first two chapters we investigated the interconnected network of urban transportation systems. Here, we shift our attention to the bicycle layer. We do this for two reasons: First, to cover the aspect of sustainable urban mobility; second, due to the lack of research on how to extend bicycle infrastructure comprehensively.

Most modern cities have followed a car-centric development in the 20th century [4] and are today allocating a privileged amount of urban space to automobile traffic [158, 159]. From a network perspective, this space can be described as the street layer of a larger mathematical object, the multiplex transport network [64, 79, 69]. A city's multiplex transport network, as previously shown in Chapter 3, contains other network layers that have co-evolved with the street layer, such as the bicycle layer or the rail network layer, Fig. 4.1. Due to the car-centric development of most cities, street layers are the most developed layers and define or strongly limit other layers: For example, sidewalks are by definition footpaths along the side of a street and make up a substantial part of a city's pedestrian space [158]; similarly most bicycle paths are part of a street or are built along the side.

From an urban sustainability perspective, this situation is suboptimal because the unsustainable mode of automobile transportation dominates sustainable modes like cycling. Consequently, urban planning movements in a number of pioneering cities are increasingly experimenting with drastic policies, such as applying congestion charges (London) [163] and repurposing or removing car parking (Amsterdam, Oslo) [164, 165, 166]. These efforts agree in one common goal, together with the literature on cycling safety [167, 168, 169, 170] and with cost-benefit analysis [171]: Protected bicycle lanes need to be extended considerably to create complete bicycle networks that provide a safe infrastructure for cycling citizens. Although scattered efforts in this direction have shown preliminary success, a quantitative framework for developing and assessing systematic strategies is missing [172].

In this chapter we analyze the bicycle infrastructure network from the previously analyzed cities in Chapter 3 (we did not include Beihai, as it was the only city without bicycle infrastructure). These cities are from leading bicycle-culture countries like the Netherlands, to car-centric countries like Great Britain, the USA, or Colombia. We first uncover network fragmentation within the bicycle dedicated infrastructure. Then, to improve a city's vital dedicated bicycle infrastructure [173, 174, 175, 176], we develop algorithms for connecting disconnected graphs based on concrete quality metrics from bicycle network planning [177] and apply them to the empirical bicycle networks via network growth

simulations. We find that localized investment into targeted missing links can rapidly consolidate fragmented bicycle networks, allowing to significantly increase their connectedness and directness, with potentially crucial implications for sustainable transport policy planning.

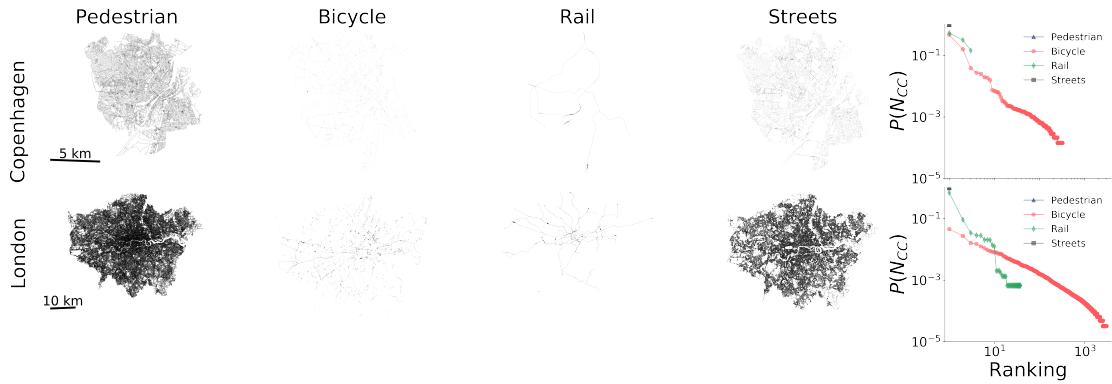


Figure 4.1. (Map plots, left) Networks representing various layers of transport infrastructure (pedestrian paths, bicycle paths, rail lines, and streets) for Copenhagen and London, with data from OpenStreetMap. **(Right)** Connected component size distribution $P(N_{cc})$ as a function of the ranking of the component for all considered network layers and cities. All layers are well connected except the bicycle layer: Copenhagen has 321 bicycle network components despite being known as a bicycle-friendly city, while London's bicycle layer is much more fragmented, featuring over 3000 disconnected components. Copenhagen's largest connected bicycle component (leftmost data point) spans 50% of the network, but London's only less than 5%.

4.2 Data: Bicycle infrastructure networks

We acquired street and bicycle infrastructure networks from multiple cities around the world using OSMnx [135], the same library we described in details in the previous chapter (see Chapter 3.2). OSMnx simplifies the OpenStreetMap's raw data to retain only nodes at the intersections and dead ends of streets, or any other mobility infrastructure. In this case we downloaded the pedestrian, bicycle, rail and street infrastructure. The resulting networks retain the spatial geometry of the edges, generating a length-weighted nonplanar directed graph [14]. As we have shown, the data from OpenStreetMap are of high quality [120, 121, 160] and completeness: More than 80% of the world is covered by OSM [43]. In particular, OSM's bicycle layer has better coverage than proprietary alternatives like Google Maps [178]. We collect data from a diverse set of cities to capture different development states of bicycle infrastructure networks;

from consolidated networks like Amsterdam and Copenhagen, less developed ones like Manhattan and Mexico City, to rapidly developing cities like Jakarta and Singapore. The various analyzed urban areas and their properties (number of nodes N , number of connected components CC , and population) are reported in Table 4.1. Code to replicate our results is available as Jupyter Notebooks (<https://github.com/naturaluis/bicycle-network-growth>) and data can be downloaded from Harvard Dataverse [125].

	walk			bike			rail			drive			Population
	N	CC	$\ell(km)$	N	CC	$\ell(km)$	N	CC	$\ell(km)$	N	CC	$\ell(km)$	
Amsterdam	23,321.0	1.0	2,075.67	34,529.0	355.0	972.08	1,096.0	8.0	288.72	15,125.0	1.0	2,010.49	872,680
Barcelona	20,203.0	1.0	2,122.6	7,553.0	122.0	229.19	263.0	29.0	105.98	10,393.0	1.0	1,551.44	1,600,000
Bogota	81,814.0	1.0	8,686.51	9,760.0	171.0	367.33	166.0	12.0	62,017.0	1.0	7,383.69	7,412,566	
Budapest	73,172.0	1.0	7,746.12	10,494.0	257.0	336.13	1,588.0	20.0	522.06	37,012.0	1.0	5,332.97	1,752,286
Copenhagen	30,746.0	1.0	2,286.66	13,980.0	321.0	417.01	276.0	3.0	123.56	15,822.0	1.0	1,547.3	2,557,737
Detroit	47,828.0	1.0	6,769.46	3,663.0	53.0	141.06	20.0	3.0	11.54	28,462.0	1.0	5,624.49	672,662
Jakarta	140,042.0	1.0	13,947.96	248.0	19.0	8.44	60.0	8.0	81.24	138,388.0	1.0	14,194.2	10,075,310
LA	89,543.0	1.0	14,329.92	14,577.0	230.0	653.16	173.0	9.0	90.82	71,091.0	1.0	13,324.46	3,792,621
London	270,659.0	1.0	23,846.62	62,398.0	3,023.0	1,281.71	2,988.0	38.0	1,045.39	179,782.0	1.0	18,154.52	8,908,081
Manhattan	13,326.0	1.0	1,320.78	3,871.0	105.0	111.42	349.0	5.0	197.51	5,671.0	1.0	1,022.13	1,628,701
Mexico	108,033.0	1.0	14,547.18	5,218.0	52.0	332.37	371.0	18.0	253.48	95,375.0	1.0	13,732.39	8,918,653
Phoenix	111,363.0	1.0	14,314.0	35,631.0	141.0	1,221.18	105.0	4.0	71.64	73,688.0	1.0	11,841.49	1,445,632
Portland	50,878.0	1.0	5,324.78	24,252.0	198.0	596.36	230.0	2.0	132.36	35,025.0	1.0	4,583.47	583,776
Singapore	82,808.0	1.0	8,633.13	12,981.0	104.0	339.39	683.0	14.0	428.66	50,403.0	1.0	6,635.37	5,638,700

Table 4.1. Measures for the administrative area of analyzed cities. The number of connected components (CC) and nodes (N) for each layer in all cities of our dataset are highly diverse due to the varying developmental levels and focus of transport.

We characterize each city street and bicycle infrastructure as a primal network, [13] in which nodes are intersections, while links represent bicycle paths, and designated bicycle infrastructure. This recent approach has been useful to demonstrate how cities grow [28, 156], how efficient [76] and dense they are, and to capture the tendency of travel routes to gravitate towards city centers [157]. This network is described by an adjacency matrix $A = \{a_{ij}^{[\alpha]}\}$ where $a_{ij} = 1$ if there is a link between nodes i and j and 0 otherwise.

4.3 Defining bicycle network growth strategies and quality metrics

Across all cities considered, we find that almost all network layers are made up of one giant component, except for the bicycle layer which is always fragmented into many disconnected components (see Table 4.1). This discovery is remarkable given that the fragmentation occurs also in bicycle-friendly cities like Copenhagen (Fig. 4.1), showing that cycling infrastructure can be suboptimal even in the leading cycling cities on the planet. To quantify such an un-

derdevelopment in the sustainable mobility infrastructure of cycling, we focus on the single layer of bicycle networks and on two well-established metrics in bicycle infrastructure quality assessment [179, 180, 181, 177, 182]: *connectedness* and *directness*. Connectedness indicates “the ease with which people can travel across the transportation system” [177], and it is related to answering the question “can I go where I want to, safely?”. Directness addresses the question “how far out of their way do users have to travel to find a facility they can or want to use?”, and can be measured by how easy it is to go from one point to another in a city using bicycle infrastructure versus other mobility options, like car travel.

As our main approach, we choose to measure connectedness and directness over the designated bicycle infrastructure only, without considering travel on streets. Although it is possible to cycle on streets, growing evidence from bicycle infrastructure and safety research is unveiling serious safety issues for cycling when mixed with vehicular traffic [167, 168, 169]. However, we also tested our algorithms on a combination of bicycle infrastructure plus streets for which the maximum speed is 30 km/h, following common best-practice reasoning that low speed limits can make streets safe for cycling [183]. The results of these additional simulations are available in the Supplementary Information; they do not differ significantly from the case of designated bicycle infrastructure presented below, as the developed algorithms follow the same rules to connect the multiple components in both cases of segregated bicycle infrastructure only and of included bikeable streets.

To quantify connectedness, we first measure the number of disconnected components of each city’s bicycle network. It is no surprise that car-centric cities have a highly fragmented bicycle infrastructure: for example, London has more than 3,000 disconnected bicycle infrastructure segments. However, even bicycle-friendly cities like Copenhagen have over 300 disconnected bicycle path components – see the connected component size distribution $P(N_{cc})$ in Fig. 4.1. This infrastructure fragmentation in the bicycle layer poses a challenge for a city’s multimodal mobility options [83] and for the safety of its cycling citizens [184, 185].

4.3.1 Algorithmic approach

There are various approaches in developing automated strategies for bicycle infrastructure planning. Hyodo et al. [186] have proposed a bicycle route choice model to plan bicycle lanes taking into account facility characteristics. Other studies have used input data from bicycle share systems [187] or origin destination matrices [188] to plan bicycle lanes. More recently, taxi trips have been used to identify susceptible clusters for bicycle infrastructure [189]. Here we attempt an alternative approach: Since hundreds of bicycle network components

already exist in most cities, we aim at consolidating the existing infrastructure by making strategic connections between components rather than starting from scratch.

Algorithm 1 Largest-to-Second. The algorithm takes the bicycle network G and a list of its weakly connected components wcc , then it iterates over the weakly connected components, sorts them by their size (number of nodes inside each component), locates the closest pairs of nodes between the first and the second components. The process is repeated until all the components have been connected.

```

1: procedure L2S
2:    $G \leftarrow$  bicycle network graph
3:    $wcc \leftarrow$  components of network  $G$ 
4:   for  $i$  in  $\text{length}(wcc)-1$  do
5:     sort  $wcc$  by components size
6:      $cc \leftarrow$  two biggest components from  $wcc$ 
7:      $i\_j \leftarrow$  the closest nodes between  $cc_0$  and  $cc_1$ 
8:     connect  $cc_0$  and  $cc_1$  in  $i\_j$ 

```

Algorithm 2 Largest-to-Closest. The algorithm takes the bicycle network G and a list of its weakly connected components wcc , then it iterates over the weakly connected components, sorts them by their size (number of nodes inside each component), locates the largest connected component and the closest of the remaining components, the components are connected. The process is repeated until all the components have been connected.

```

1: procedure L2C
2:    $G \leftarrow$  bicycle network graph
3:    $wcc \leftarrow$  components of network  $G$ 
4:   for  $i$  in  $\text{length}(wcc)-1$  do
5:     sort  $wcc$  by components size
6:      $cc_0 \leftarrow$  the biggest component from  $wcc$ 
7:      $cc_n \leftarrow$  closest component to  $cc_0$ 
8:      $i\_j \leftarrow$  the closest nodes between  $cc_0$  and  $cc_n$ 
9:     connect  $cc_0$  and  $cc_n$  in  $i\_j$ 

```

Our approach takes into account the currently available bicycle infrastructure and uses an algorithmic process to improve the network by finding the most important missing links step by step. This way we focus on optimizing the connectedness metric, growing the bicycle infrastructure by making it more

connected, merging parts into fewer and fewer components. We develop two iterative greedy algorithms that we check against a random and a minimum investment approach. The first algorithm, *Largest-to-Second* (L2S), identifies in each step the largest connected component in the bicycle infrastructure network and connects it to the second largest (see algorithm 1 for details). The second algorithm, *Largest-to-Closest* (L2C), also identifies the largest connected component, but connects it to the closest of the remaining bicycle infrastructure components (see algorithm 2 for details). In both algorithms, components are connected through a direct link between their two closest nodes. We use this technique as an approximation to the underlying street-shortest path – since the most relevant shortest 100 connections typically range from 14 to 500 meters, roughly the length of two blocks, this approximation is reasonable. The algorithms repeat this process until there are no more disconnected components in the network.

To have a random baseline, we compare our algorithms with a *Random-to-Closest* (R2C) component approach. In each step of this baseline approach, one component is picked at random and connected with the closest remaining one (see algorithm 3 for details). This baseline allows us to model a scenario where infrastructure is developed following a systematic but random linking approach – in urban development this corresponds to uncoordinated local planning that randomly connects close pieces of bicycle infrastructure. We also implement a second baseline, the extreme case of *Closest-Components* (CC), which prioritizes connecting the closest two components disregarding their size (see algorithm 4 for details). This CC approach is equivalent to an “invest as little as possible” development strategy – it builds up a minimum-spanning-tree-like structure following a modified Kruskal’s algorithm [190]. All four algorithms connect components optimizing a well-defined criterion, finding the critical missing links in the network, and adding one new link per iteration. See Fig. 4.2 for a schematic of the four algorithms.

We apply the algorithms to the bicycle infrastructure inside the political demarcation of the cities, however it is possible to extend the methods and include bicycle highways and cross-city trails, since they use as input a set of spatial network components to connect. We opt to not include cross-city links, since they are a special case only available in a few regions and where adequate intra-urban bicycle infrastructure has already been established [191, 192].

4.3.2 Evaluating the algorithms

To test how much cities improve their bicycle layers using these four algorithms, we define two metrics on the bicycle layer that operationalize the notion of con-

Algorithm 3 Random-to-Closest. The algorithm takes the bicycle network G and a list of its weakly connected components wcc , then it iterates over the weakly connected components, randomly picks a component and connects it to the closest of the remaining components. The process is repeated until all the components have been connected.

```

1: procedure R2C
2:    $G \leftarrow$  bicycle network graph
3:    $wcc \leftarrow$  components of network  $G$ 
4:   for  $i$  in  $\text{length}(wcc)-1$  do
5:      $cc_{ran} \leftarrow$  random component from  $wcc$ 
6:      $cc_n \leftarrow$  closest component to  $cc_{ran}$ 
7:      $i\_j \leftarrow$  the closest nodes between  $cc_{ran}$  and  $cc_n$ 
8:     connect  $cc_{ran}$  and  $cc_n$  in  $i\_j$ 
```

Algorithm 4 Closest-Components. The algorithm takes the bicycle network G and a list of its weakly connected components wcc , then it iterates over the weakly connected components, calculate the distance between available components and connect the two closest ones. The process is repeated until all the components have been connected.

```

1: procedure CC
2:    $G \leftarrow$  bicycle network graph
3:    $wcc \leftarrow$  components of network  $G$ 
4:   for  $i$  in  $\text{length}(wcc)-1$  do
5:      $\Delta_{min} \leftarrow$  closest components in  $wcc$ 
6:      $cc_0 \leftarrow$  first component for  $\Delta_{min}$ 
7:      $cc_1 \leftarrow$  second component for  $\Delta_{min}$ 
8:      $i\_j \leftarrow$  the closest nodes between  $cc_0$  and  $cc_1$ 
9:     connect  $cc_0$  and  $cc_1$  in  $i\_j$ 
```

nectedness: i) $n_{LCC} = \frac{N_{LCC}}{N}$, the fraction of nodes from the bicycle infrastructure inside the largest connected component (N_{LCC}) compared to the total number of nodes from the same type of infrastructure (N), and ii) $\ell_{LCC} = \frac{L_{LCC}}{L}$, the fraction of link kilometers inside the bicycle infrastructure largest connected component (L_{LCC}) compared to the total number of link kilometers in the bicycle network (L). Both metrics take values between 0 and 1, where 1 means that there is only one connected component. An intermediate value, for example 0.2, means that the largest connected component contains 20% of all bicycle intersections or path kilometers. Executing our algorithms step by step these metrics can only grow, approaching 1 when the process is complete and they terminate. What

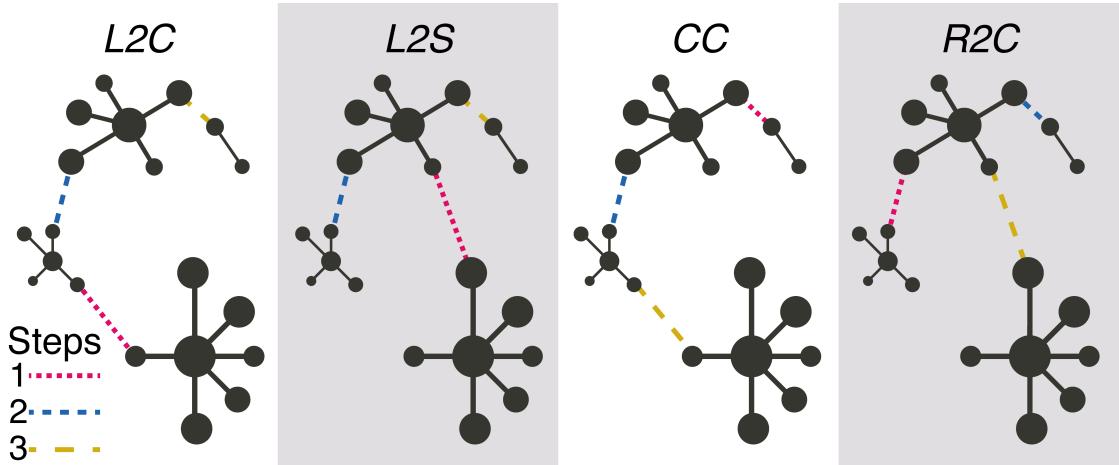


Figure 4.2. Schematic representation of algorithms to improve bicycle network infrastructure: Largest-to-Closest (L2C) finds the largest component and connects it with the closest one; Largest-to-Second (L2S) connects the largest component with the second largest; Closest-Connected (CC) connects the two closest components; and Random-to-Closest (R2C) picks a random component and connects it to the closest.

distinguishes the algorithms is *how fast* these values grow.

We quantify directness through the metric: iii) bicycle-car directness Δ , which answers the question “how direct are the average routes of bicycles compared to cars?” via the ratio between average distance by car and average distance by bicycle. For example, if the shortest car-route from west to east Manhattan is 4 km and the shortest route on the bicycle network between these two points is 5 km, the bicycle-car directness is $4/5 = 0.8$. Note that if the bicycle network is a subset of the street network, then Δ cannot be larger than 1. Formally we write $\Delta = \frac{\langle \delta_{ij}^b \rangle_{ij}}{\langle \delta_{ij}^s \rangle_{ij}}$, where $\langle \delta_{ij}^s \rangle_{ij}$ is the average car-route distance, and $\langle \delta_{ij}^b \rangle_{ij}$ is the average length of the shortest bike-route between i and j . In each iteration of any of our algorithms, we implement this measure by randomly selecting one thousand pairs of origin-destinations nodes and then averaging the corresponding street/bicycle distance. To avoid undefined values due to disconnected components in the bicycle layer, we add the following condition: If a node from the pair i and j is in a different component, we assign the value $\delta_{ij}^b = 0$. This condition also ensures consistency of growing directness values while the algorithm merges more and more nodes into the same component.

Finally, in order to measure the cumulative efficiency of our algorithms, we define the metric: iv) G_{LCC} as the relative gain of bicycle path kilometers in the largest connected component. For example, $G_{LCC} = 1.5$ means that the algo-

rithm has increased the largest connected component's original size by 150%. Formally, $G_{LCC} = \frac{L_{LCC} - L_{LCC_0}}{L_{LCC_0}}$, where L_{LCC_0} is the sum of kilometers in the largest connected component before the algorithm runs. As with all other metrics, G_{LCC} is monotonically increasing with the growth algorithm, and reaches $\frac{1 - \ell_{LCC_0}}{\ell_{LCC_0}}$ at the end of the dynamics.

4.4 Growing bicycle networks shows stark improvements with small investments

We demonstrate in Fig. 4.3 the power of the various growth strategies by showing the initial state of the bicycle layer for the case of Budapest and its state after 85 iterations of the *Largest-to-Closest* algorithm: At this point the network has almost quadrupled the size of its largest connected component (from 82 km to 313 km), with a negligible investment of just less than 5 km (corresponding to 1.4% of the previously existing bicycle infrastructure) in new connecting bicycle paths. In terms of connectedness, it goes from 15% to 56% connected. This rapid increase shows that the city can easily improve its bicycle infrastructure with small investments. For some extreme cases, like Bogota, with the same 5 km investment (an increase of 1.3% to the previously existing infrastructure) the bicycle-car directness increases from 6% to almost 48% and connectedness from 34% to 89%. Similar encouraging results hold for other cities (See Section 7.1.2).

The fraction of nodes inside the largest connected component increases rapidly with newly added links for all considered algorithms except *Random-to-Closest*, Fig. 4.3(a). The *Largest-to-Closest* algorithm performs better than the others, even more than *Closest-Components* which prioritizes minimum investments in the network. Since we are considering bicycle infrastructure, a better practical measure than the number of intersections is the number of kilometers that can be cycled using only designated paths. Figure 4.3(b) shows how this measure improves in a similarly explosive way: with an investment of only 20 km (5.9% of the existing infrastructure), the largest connected component will contain 80% of the original bicycle infrastructure. Results for the kilometer gain G_{LCC} are shown in Fig. 4.3(c). Three of the four algorithms rapidly gain new kilometers, but as the invested new kilometers grow, each algorithm follows a different gain rate. Also, for this metric, *Largest-to-Closest* is the algorithm with the best performance.

We also measure the bicycle-car directness ratio, Fig. 4.3(d). The bicycle-car directness Δ improves as the algorithms consolidate the network. These

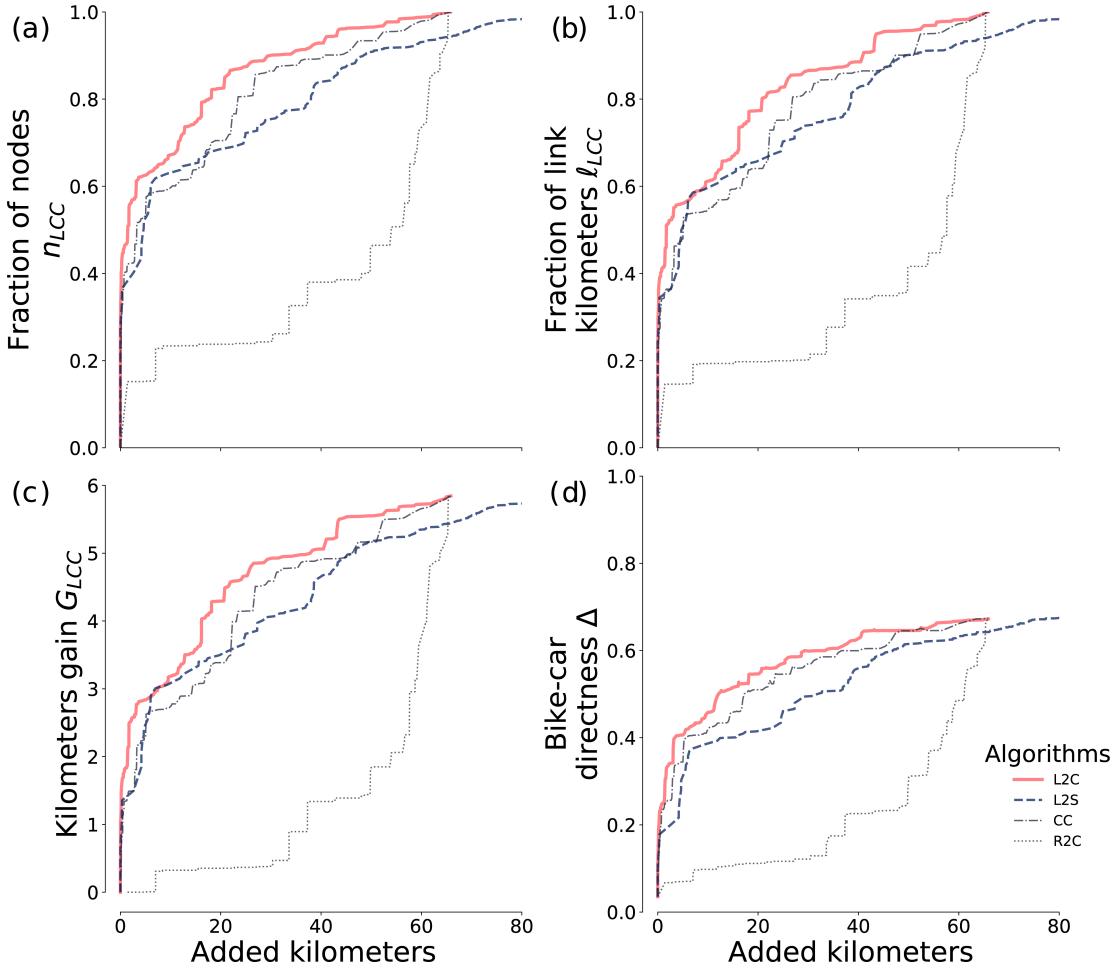


Figure 4.3. (a) Normalized increase in nodes inside the largest connected component (n_{LCC}). (b) Normalized increase in kilometers inside the largest connected component (ℓ_{LCC}). (c) Kilometers gain (G_{LCC}). (d) Bicycle-car directness (Δ). Measures in (b-e) are plotted as a function of the sum of added links in kilometers, for the case of Budapest (for all cities see Fig. 7.1)

improvements are, however, indirectly driven by the improvement of connectedness, which boosts the accessibility of bicycles to different areas of the city. The flattening of the curves at a value considerably smaller than 1 (around 0.65) shows that cars will always outperform bicycles in terms of directness, having on average at least 33% shorter paths in the city. This suboptimal flattening is a natural consequence of the algorithms optimizing for connectedness only, not adding “redundant” connections. Nevertheless, the measure shows that, similar to connectedness, with a relatively negligible investment of bicycle path kilometers into the system, the bicycle network’s directness improves

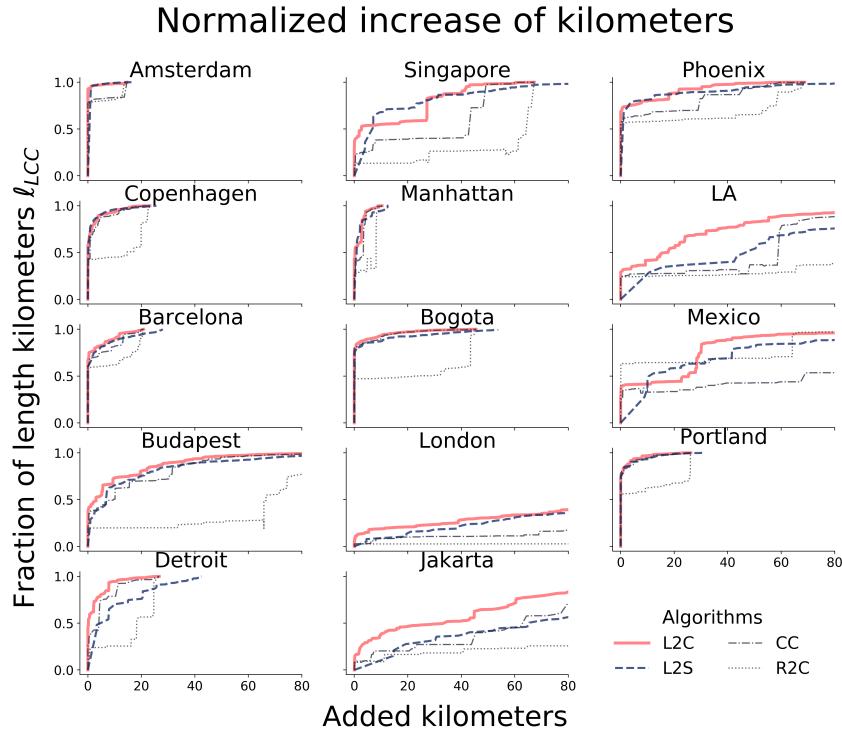


Figure 4.4. Normalized increase in kilometers inside the largest connected component (ℓ_{LCC}).

drastically, even in the greediest case where the shortest possible missing link is added in every iteration. This result holds for all analyzed cities (see SI). The large differences between the baseline *Random-to-Closest* and our two algorithms (*Largest-to-Second* and *Largest-to-Closest*) show the importance of following an approach that consolidates and grows the largest connected component. Similar results are obtained for all the cities when taking into account the combination of bicycle infrastructure and safely bikeable streets ($\leq 30 \text{ km/h}$), in Figure 4.4 we show the increase in bikeable kilometers when taking into consideration bikeable streets and designated bicycle infrastructure combination for all the analyzed cities (see Section 7.1.3 for the rest of the measures).

5 km investment

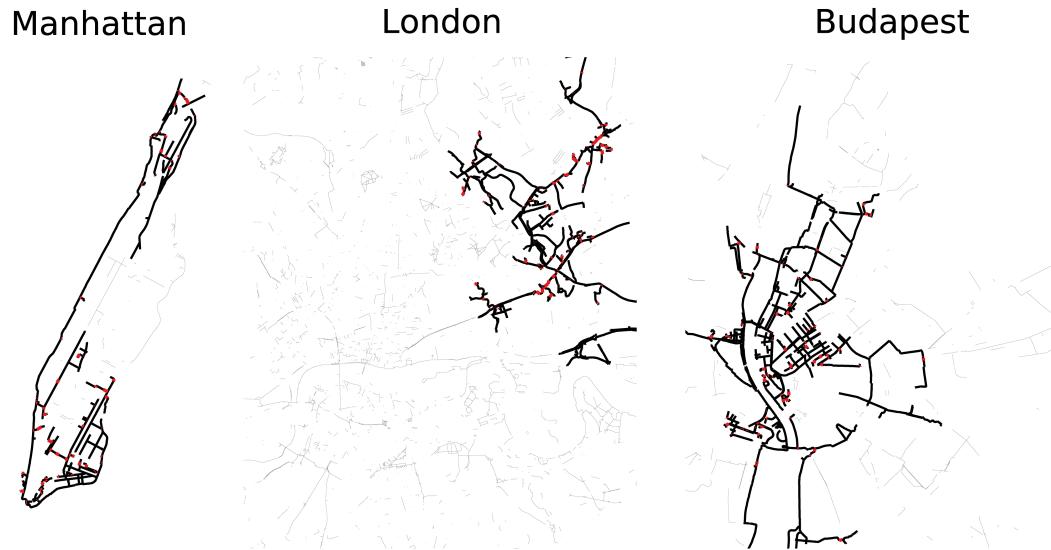
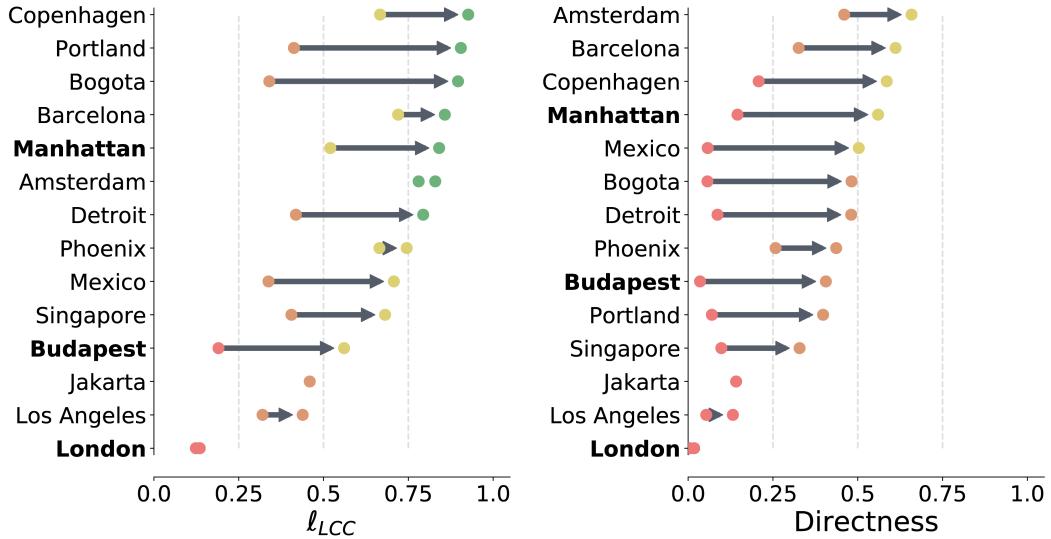


Figure 4.5. Cities improvement and ranking using the Largest-to-Closest algorithm. We report the improvement and ranking on the fraction of total kilometers of bicycle infrastructure in the largest connected component (ℓ_{LCC}) and in the bicycle-car directness (Δ). Dotted lines show thresholds of 25%, 50%, and 75%. Plots (a-b) show investment strategies of 5 km and 35 km, respectively, the Manhattan, London, and Budapest plots show the suggested new links (red) after adding 5 km and 35 km, the newly created largest connected component (black), and the remaining separated components (grey).

4.5 Different cities have different optimal investment strategies

Differences arise in the state of the bicycle layer and its improvement after applying a growth algorithm. To see this effect, we rank how cities improve using the *Largest-to-Closest* algorithm in two different investment scenarios: investing either i) 5 km, or ii) 35 km. Figure 4.5 shows how cities improve when investing 5 km of bicycle infrastructure. We see that some cities get above 75% of their existing infrastructure connected, meaning that their bicycle layer only needs a small extension. On the other hand, cities like London, Los Angeles, and Jakarta need a larger investment to improve. Concerning bicycle-car directness, cities reach lower values due to the focus of the algorithms on completeness. In the worst performing cities like Los Angeles, a covered length close to 50% can be reached easily, while the bicycle-car directness ratio stays below 20%, showing that it is much harder to gain an acceptable bicycle infrastructure in cities where cars are overprioritized. The 35 km investment strategy shows that most cities can get at least 75% of their bicycle infrastructure connected, Fig. 4.6. The worst performing outlier is London, due to its bicycle layer containing more than 3000 connected components scattered around 1600 km² (see Table 4.1). In terms of bicycle-car directness London also performs badly, while Amsterdam is the best performing one.

The four proposed metrics capture the impact of newly created connections on the various components of the bicycle network. By linking previously disconnected neighborhoods with a sustainable mode of transport, our approach focuses on consolidating bicycle infrastructure networks, thus making cities more cohesive and green. It does not, however, focus on growing the bicycle network into large areas of the city not currently served. To test to which extent such connectedness-based algorithms bring an indirect benefit for coverage, we measured the proportion of the city that is covered and reachable by bicycle with an epsilon of 500 meters around the bicycle infrastructure of the largest connected component, and calculated the percentage of nodes in the street layer that are covered by the bikeable area. The results of this measurement show a wide range of effects: Cities with an already high coverage above 80% (Amsterdam, Copenhagen) reach near instantly 100%, cities with an intermediate coverage (Manhattan, Bogota, Budapest) follow a more linear progression per added kilometer, while underdeveloped or sprawling cities (LA, London, Jakarta) show negligible growth (Fig. 4.7).

While our present goal (consolidation of the bike network) is intended to show the potential of our approach, an extension towards the exploration of new city areas will increase further the real-world applicability of our re-

35 km investment

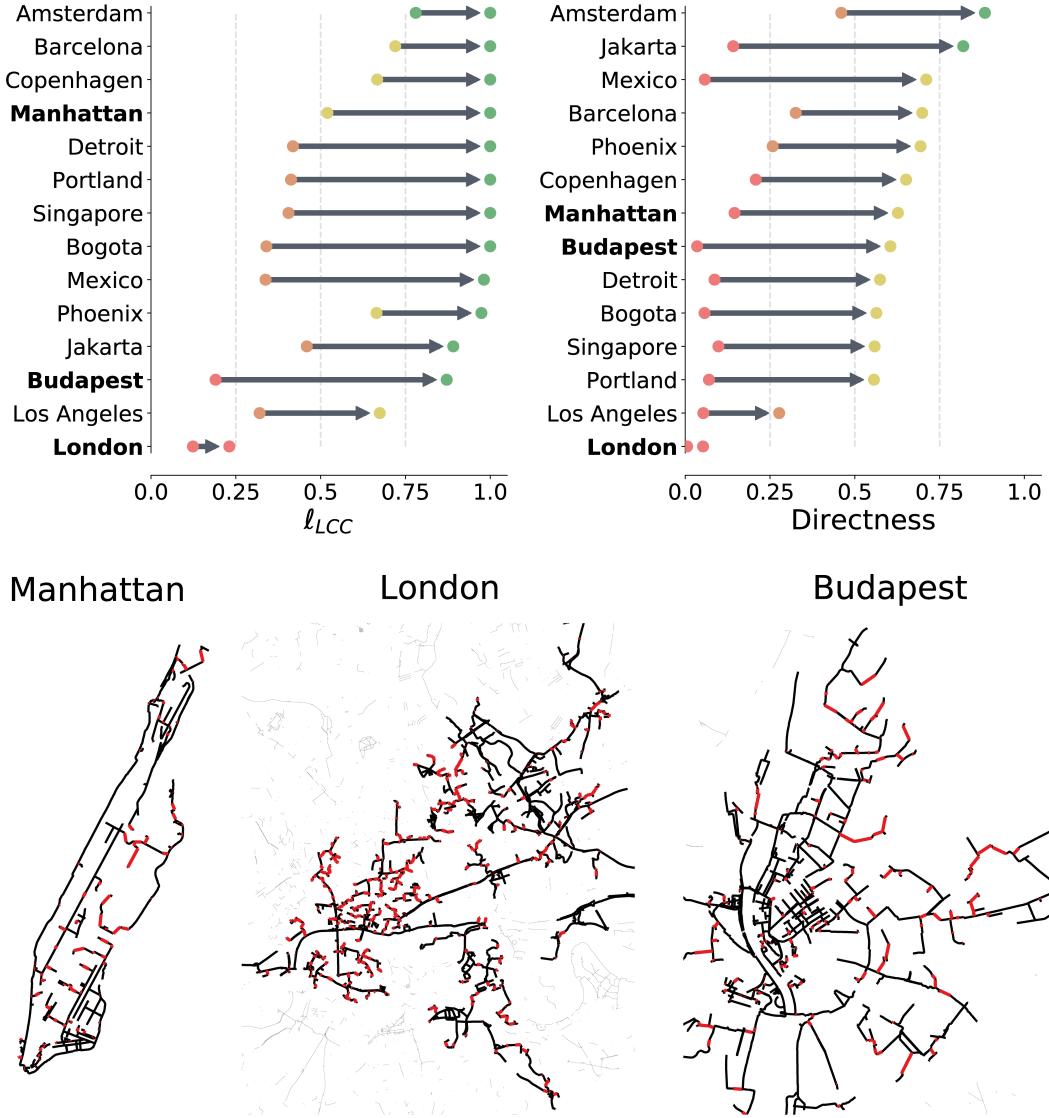


Figure 4.6. Cities improvement and ranking using the Largest-to-Closest algorithm. We report the improvement and ranking on the fraction of total kilometers of bicycle infrastructure in the largest connected component (ℓ_{LCC}) and in the bicycle-car directness (Δ). Dotted lines show thresholds of 25%, 50%, and 75%. Plots (a-b) show investment strategies of 5 km and 35 km, respectively, the Manhattan, London, and Budapest plots show the suggested new links (red) after adding 5 km and 35 km, the newly created largest connected component (black), and the remaining separated components (grey).

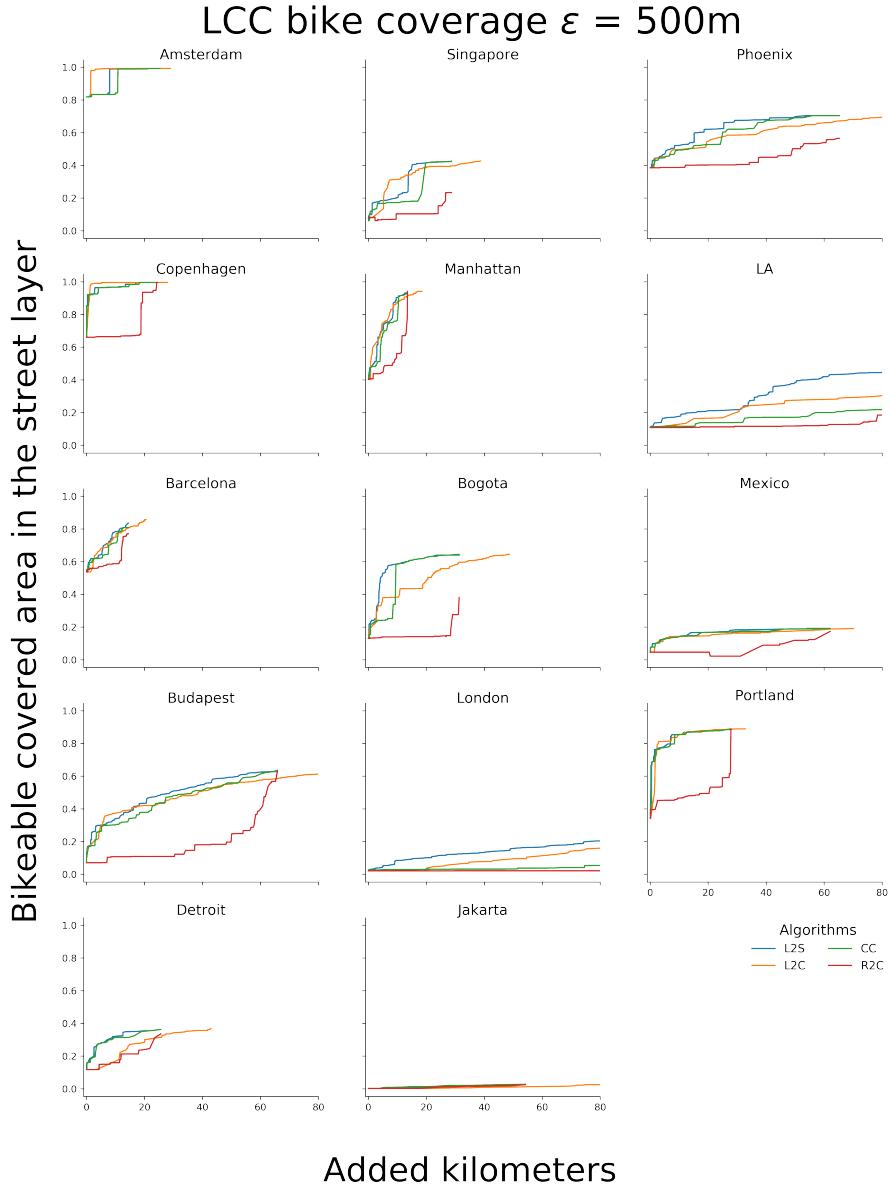


Figure 4.7. Area of influence (coverage) for the bicycle infrastructure in the street layer.

sults. We consider this extension an interesting line of future research in the challenge of developing optimal data-driven strategies of transport network growth, potentially informed by theoretical frameworks such as optimal percolation [193, 194]. Besides, the use of other network metrics, such as network efficiency [52], might unveil new dimensions characterizing the impact of the proposed algorithms on the development of the bicycle infrastructure.

4.6 Discussion

Our starting point showed that a common characteristic of cities is the fragmentation of their bicycle networks. We have proposed the use of data-driven algorithms to consolidate bicycle network components into connected networks to improve efficiently sustainable transport. We have shown that connecting the bicycle infrastructure in an algorithmic way rapidly improves the connectedness and directness of the bicycle layer. These algorithms, when compared with two baselines, highlight the usefulness of growing the bicycle network on a city-wide scale (considering all areas of the city) rather than randomly adding local bicycle infrastructure. Improving the connectivity of bicycle lanes and paths improves not only the network itself, but also promotes the use of bicycles as means of transportation in a city, improving the health of its inhabitants [195].

Improving bicycle infrastructure one link at the time (by identifying suitable components to connect) is only the first step towards a systematic framework for realistic bicycle network growth strategies. Our current approach is not the last word in this development, since it does not yet explicitly optimize for directness and does not account for transport flow. Further, our proposed approach helps implement a more connected transport network which can improve the possibilities for multimodal transport. This could be starting point for implementing truly multimodal strategies, such as integration with public transportation, or bicycle parkings in transportation hubs [177].

In our algorithms, each new link works as a bridge between components, potentially having large betweenness centrality. Such high-betweenness segments could become overused and create bottlenecks in practice. To improve this situation, it would be necessary to create links in the network that act as redundant paths. In doing so, directness and coverage would also be improved, along with the network's robustness to interruptions. This is an interesting and possibly demanding task that we leave for future research, as the new links would have to be created in a coherent manner balancing trade-offs between network structure and mobility dynamics. We anticipate that complementing OpenStreetMap data with additional information on the use of traffic flow and movement data, like trips from bike share systems or origin-destination matrices, possibly from alternative sources such as municipalities and transportation agencies, might further improve the algorithms by better detecting underserved and optimal areas in the city where new links should be created. Despite these various possibilities for qualitative updates to the studied growth strategies, our first models have demonstrated the capability to generate substantial improvements with minimal effort.

The use of data-driven algorithms to identify crucially missing links in bi-

cycle infrastructure has the potential to improve the mobility infrastructure of cities efficiently and economically. This approach is not only useful for planning city structure, but could also be used together with simulating mobility flows and to provide insights on how the system will behave after new measures are implemented. Ultimately, planning cultures and processes will also have to be accounted for [196]. We anticipate that a future stream of work should include longitudinal studies [197] in multiple cities, along with algorithmic simulations to first model and simulate possible changes to the transport network, and then to test those models with ground truth data, to compare the evolution of infrastructure and mobility dynamics between cities with different transport priorities.

CHAPTER 5

LIFE QUALITY AS WALKABILITY

Life quality in cities is deeply related to the mobility options, and how easily one can access different services and attractions. The pedestrian infrastructure network provides the backbone for social life in cities. While there are many approaches to quantify life quality, most do not take specifically into account the walkability of the city, and rather offer a city-wide measure. Here we develop a data-driven, network-based method to quantify the liveability of a city. We introduce a life quality index (LQI) based on pedestrian accessibility to amenities and services, safety and environmental variables. Our computational approach outlines novel ways to measure life quality in a more granular scale, that can become valuable for urban planners, city officials and stakeholders. We apply data-driven methods to Budapest, but as having an emphasis on the online and easily available quantitative data, the methods can be generalized and applied to any city.¹

¹A stand alone version of this chapter has been published in Complex Networks and Their Applications VIII [198].

5.1 Walking the city

In this chapter, we shift our attention from the bicycle, to the pedestrian layer. We focus on measuring the livability of a city using its pedestrian infrastructure to compute how easy it is to access different types of amenities that serve multiple purposes, such as cultural, educational and access to day-to-day goods.

As mentioned in the previous chapters, the evolution that most cities followed during the 20th century promoted a car-centric vision [4, 158, 159], neglecting the presence of other mobility options. From a liveability perspective, this situation is suboptimal because the automobile infrastructure dominates and defines the walkable area, increasing car traffic, air pollution and deteriorating walkable conditions.

The concept of walkability is an important factor to consider in connection with liveability. Liveability refers to an environment from an individual perspective [199] which includes “a vibrant, attractive and secure environment for people to live, work and play and encompasses good governance, a competitive economy, high quality of living and environment sustainability” [200]. Thus, in a liveable city, there must be an emphasis not only on sustainable transportation and built environment to reduce the harm on nature [201, 202] but also encouraging citizens to walk for supporting their physical and mental well-being [203]. However, improving walkability is more complex than we would think. Walking should be an available, safe and well-connected mode of transportation, but as Speck put it well, it should be interesting and comfortable as well, to have a feeling of the streets as ‘outdoor living rooms’ [204].

The pedestrian infrastructure that sustains walkability in a city can be described as a network [13]. This approach has been useful to identify street patterns [21, 24] and its evolution [28, 156], measure the morphology of cities [205], and how the streets’ connectivity impacts on pedestrian volume [206].

The various approaches to create a walkability index or so-called walk score consider mainly the following components: safety and security [207, 208]; convenience, attractiveness and public policy [209, 204], connectedness [210], but also reckon with the land use mix and residential density of the certain area[211]. Another approximation rather accents the importance of its effect on air pollution, health problems, travel costs and even on the sense of community[212]. Thus measuring walkability not only captures the propensity to walk in a city but also includes the components a liveable city must have and support, under the umbrella of sustainability.

There are good examples of how sustainable city development initiatives tackle growing inequalities with data-driven approaches. Long Island used city data to analyze which amenities are needed to increase the quality of life in a

newly built environment [213], other cities are investing in smart technologies to develop public transport, connecting spatially discriminated areas [214, 215].

Since the number of components which should be taken into consideration in creating a walkability index is high, the types of data are also mixed and thus difficult to integrate. While the information on connectedness, security, residential density, etc. is quantitative and in general easily available, gaining opinion about attractiveness, convenience, or even about the feeling of security is more complicated. Here we propose to use a data-driven approach as a proxy to quantify life quality, making it reproducible and easily expanded to include different data sources. We apply our methods to Budapest, but as having an emphasis on the online and easily available quantitative data, the methods can be generalized and applied to any city.

5.2 Data: Pedestrian network, points of interest, and city attributes

5.2.1 Pedestrian network

We work with three different data sources: networks, points of interest and city attributes. To acquire the pedestrian network and points of interest, we used OSMnx [135], the same tool we used in the previous chapters (see Chapter 2.4). As we have shown, the data from open street maps is of high quality [120, 121, 160], and completeness [43]. The obtained network contains all the sidewalks and pedestrian designated infrastructure, it is conceptualized as undirected, nonplanar and primal network [13]. This network is described as a weighted graph, with its adjacency matrix $W = w_{ij}$ where the weight w_{ij} contains the length between i and j if connected, and 0 otherwise. We also encoded in the links the traversal time Tt_{ij} between nodes i and j calculated as $Tt_{ij} = \frac{\ell_{ij}}{ps}$ where ps is the pedestrian speed as a constant rate of $5km/h$.

5.2.2 Points of interest

The majority of points of interest were downloaded from OpenStreetMap, from different classification keys (amenity, tourism, shop, office, leisure) using OSMnx [135]. We filtered the points of interest using the districts' demarcation [216], to get only the data within Budapest boundaries, having, as a result, more than 39,000 data points. We complement the data sets with secondary data sources as specialized directories of doctors and childcare facilities (see Section 7.2.1).

We categorize the points of interest in six main categories: I) Family friendliness (Access to education and daycare, and family support services), II) Access to health care and sport facilities, III) Art and culture (e.g. museums, exhibitions), IV) Nightlife (e.g. bars, restaurants), V) Environment (air quality and access to green areas), and VI) Public Safety. The points of interest and secondary data sources are available at https://github.com/naturaluis/Budapest_LQI

5.2.3 City attributes

The district-level data (population and crimes) were obtained from the Hungarian Police's public database. The crime statistics are reported as the number of crimes committed in public places in 2018 [217]. Population data is coming from the 2016 micro-census conducted by the Hungarian Statistical Bureau [218]. We took into account the air pollution, this data set coming from National Air Pollution Measurement Network [219], containing the geolocation of the air quality stations and different measures (annual median concentration of carbon monoxide, nitrogen dioxide, and PM10 dust).

Accuracy of the Life Quality Index (LQI) model highly depends on how comprehensive the distribution of listed services. We use OSM as our key data source, but to achieve a more comprehensive and country-specific database we collect publicly available data from various Hungarian websites for each category.

To project the city attributes to the network we assigned properties to its nodes. Matching them with their corresponding districts, then assign attributes to the nodes based on the district level data (population and crimes, see section 5.3.2). For the pollution data, we calculated the corresponding Voronoi cells for the air quality stations, and matched the nodes with them. Finally, we divided the pollution by the number of nodes in each corresponding cell and assigned the value to the nodes (See section 5.3.3).

5.3 Quantifying life quality

The life quality of a person is largely subjective and hard to quantify. However, it is both intuitive and has been scientifically shown that the environment and personal well-being strongly correlate [220]. Thus using environmental factors as proxies, life quality and livability becomes quantifiable [221].

The main environmental factors we consider in our model are: the availability of services and amenities, the quality of the infrastructure, environmental factors and safety. The goal of our model is to quantitatively characterize the

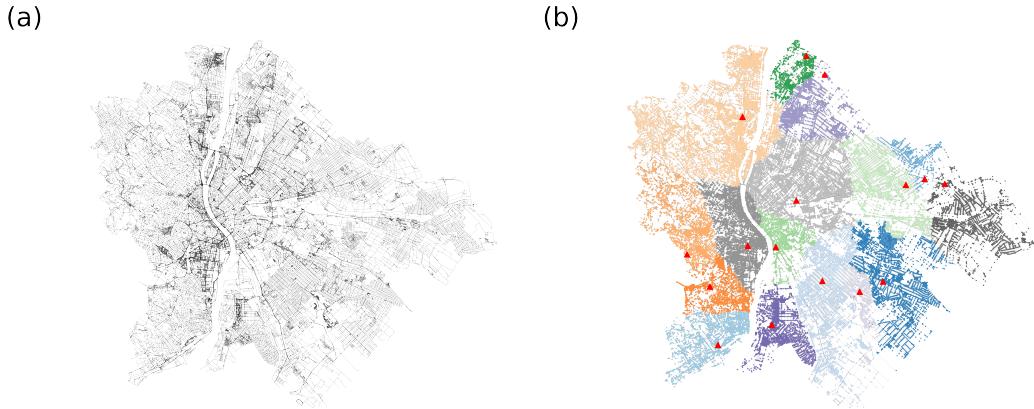


Figure 5.1. (a) Network representing Budapest pedestrian structure. The network was built following a primal approach, where the edges are sidewalks and pedestrian infrastructure, and nodes are intersections. (b) The graph-Voronoi tessellation of the Budapest network, generated using a subset of 15 parks as seeds. The color of the nodes represents the cell they belong to and the highlighted red dots are the seeds of each cell. The distance measure between two points is defined as the weighted shortest path on the graph, the weights being the average time required to cross a given edge.

immediate environment of residents in the space of factors that affect life quality.

The fundamental framework of our model and our calculations is the network representation of Budapest's pedestrian infrastructure. The nodes of the network represent intersections, while links are sidewalks and pedestrian infrastructure. The output of our model is an index, that characterizes every node of the Budapest network, giving a high-resolution quality-landscape of the city. The index is ultimately a number aggregated from multiple sub-categories, and its main value is highlighting inequalities and relative deficiencies within the city.

The final value of the index is a weighted sum, characterizing every node (intersection) in the network:

$$Q_i = w^{services} \tilde{Q}_i^{services} + w^{safety} \tilde{Q}_i^{safety} + w^{environment} \tilde{Q}_i^{environment} \quad (5.1)$$

In the equation i represents an individual node in the network. The “tilde” above the Q terms means that the values of the different category indices are normalized within the category. The weights w assigned to every term are arbitrary and are highly context-dependent. All terms of the equation are discussed in the following sections.

The weights of the different Q indices in the final aggregation highly depend on the context and the nature of the problem. For this study we followed a participatory design process [222, 223, 224], actively involving stakeholders to define them. This process let us incorporate practical knowledge of the importance of the services, safety and the environment in a city.

The weights of the sub-indices from equation (5.1) are of the following values:

- $w^{\text{services}} = 0.7;$
- $w^{\text{safety}} = 0.1;$
- $w^{\text{environment}} = 0.2$

5.3.1 Services index

The number quantifying each node in terms of how well it is connected with amenities and services is a weighted sum of sub-categories as well.

$$Q_i^{\text{services}} = \sum_c w^c Q_i^c \quad (5.2)$$

where, c denotes categories (family, culture, health, sport, and nightlife), and w^c the importance of category c .

As when building the aggregated index, we also followed a participatory process to account for the importance of different category-services in the city. The weights used in equation (5.2) are as follows:

- $w^{\text{family}} = 0.3;$
- $w^{\text{health}} = 0.3;$
- $w^{\text{culture}} = 0.15;$
- $w^{\text{sport}} = 0.15;$
- $w^{\text{night life}} = 0.1$

Some categories, like family, have further subcategories. Even though we have also had data and made a separate analysis on tourism, its effects on life quality of the residents are ambiguous, so we decided to omit it from the index.

What sets categories apart is that they incorporate different sets of amenities, with a few overlaps. The details of the categorization of amenities are included in the Appendix.

For every service/amenity class we have a given set of points of interest (POI) along with where the amenities of that class are available, with exact geolocation. We assign every POI of a given amenity class (e.g. supermarket, pharmacy, school, etc.) to the nearest node on the infrastructure network. Each set of POIs organically generates a spatial partitioning of the city with one partition per POI. The partition of a POI is the set of all the nodes from which that particular POI can be reached faster than any other POI of the same class.

Mathematically these partitions are called graph-Voronoi cells [225, 226], where every node of a cell is assigned to its closest seed (POI). Distance, in this case, is not euclidean or geometric distance, but the distance on the network, where we use the weighted shortest path between two nodes as the distance measure. The weight of links is a temporal parameter encoding the average time required to cross the represented street from one end to the other, thus the weight is a simple product of average speed and length of the street. This is in principle very similar to the way navigation systems find routes between points. For an example of a graph-Voronoi partitioning see Figure 5.1 (b).

To assess how well-connected a node is to amenities we consider the following factors:

- How important is an amenity - weight (w_a)
- How long does it take to reach the amenity - time to reach (t_{ia})
- Relatively how many nodes (or people) does the amenity share with - exclusivity (P_a)

From the three factors, the latter two are calculated using the city infrastructure network. The index for an amenity class, from the perspective of node i , is proportional with its importance (weight) and it is inversely proportional with the time to reach the closest POI from i and with the degree of exclusivity.

$$q_i^a = \frac{w_a}{(P_a + 1)(t_{ia} + 1)} \quad (5.3)$$

There can be certain singular cases when a Voronoi cell is empty ($P_a = 0$, i.e. no residents in the area) or the node i in question is right at the POI ($t_{ia} = 0$). To avoid anomalies in the index we added 1 to both parameters.

The index of one category is proportional to the sum of its amenity-indices (calculated in (5.3)). To treat this number on the right scale (in practice we can get very large and very small numbers) we take the natural logarithm of the sum across amenities.

$$Q_i^c = \log\left(\sum_a q_i^a\right) : \quad (5.4)$$

As we have mentioned earlier, the final services index is the weighted sum of the indices of the sub-categories.

$$Q_i^{services} = \sum_c w^c Q_i^c$$

Finally, we normalize the values of $Q^{services}$, so its values are comparable to the other values of the final Q equation (5.1):

$$\tilde{Q}_i^{services} = \frac{Q_i^{services} + |min(Q^{services})|}{max(Q^{services}) + |min(Q^{services})|} \quad (5.5)$$

Even if there are potentially other ways to build a life quality index, this is a synthetic way of doing it that can be used as a tool for policymakers to evaluate the urban conditions and how they relate to the quality of life in a given city. In particular, this approach has been used in Budapest to evaluate the current urban conditions and to plan future developments. More recently, a variation of this approach was used to evaluate the impact of new cyclist infrastructure during the beginning of the COVID-19 pandemic in Budapest. The variation took into consideration the existing pedestrian and bicycle infrastructure. We built a network combining both infrastructures and measure the accessibility with the proposed method to establish baseline. Then, we incorporated the pop-up temporary bicycle infrastructure into the previously built network and evaluate how the accessibility changed. A set of preliminary results were presented to the Budapest municipal government. The use of this kind of metrics provides local governments with an opportunity to plan and evaluate the feasibility of public policies and mobility investments.

5.3.2 Safety index

The safety index is calculated across districts based on the number of crimes committed per one hundred thousand residents. Since the highest resolution data available to us was on the district level, every node i in the same district will have the same safety index value. The crime index:

$$Q_i^{crime} = \frac{N_{district}^{crime}}{n_i^{district}}$$

Where $N_{district}^{crime}$ is the number of crimes committed in a district in a year, and $n_i^{district}$ is the number of nodes in the district. The safety index is one minus the normalized crime index.

$$\tilde{Q}_i^{safety} = 1 - \frac{Q_i^{crime}}{max(Q^{crime})} \quad (5.6)$$

5.3.3 Environmental index

The environmental index is made up of two components: air pollution ratio and ratio of natural areas.

Air pollution ratio

We use the data provided by Budapest's air pollution measuring stations for the year 2018. For this study, we used the yearly median value of three polluters: carbon monoxide, nitrogen dioxide, and PM10 dust-pollution. As an approximation, we project the geometric Voronoi cells of the measuring stations onto the city map and each node will receive the pollution metrics of the geometrically closest station. We divide these values with the yearly upper health limit for the given polluter to assess to what degree do these values approximate the health limit. Thus the air pollution index of one node is formalized as follows:

$$C_i = \frac{c_i^{CO}}{c_{limit}^{CO}} + \frac{c_i^{NO_2}}{c_{limit}^{NO_2}} + \frac{c_i^{Pm10}}{c_{limit}^{Pm10}}$$

Where $c_{limit}^{CO} = 3000g/m^3$, $c_{limit}^{NO_2} = 40g/m^3$, $c_{limit}^{Pm10} = 40g/m^3$ are the yearly upper limits based on data from the Hungarian Air Quality Network [219].

Ratio of natural areas

For this index, we have data on the neighborhood level, which is a more granular level of administrative partitioning the city than the districts are. In this case, we project the same index onto every node in the same neighborhood. We consider as natural areas forests, parks and water surfaces (ponds, rivers, etc). The index:

$$T_i = \frac{R_{water}^{nh(i)} + R_{forest}^{nh(i)} + R_{park}^{nh(i)}}{\max(T)}$$

Where $R_x^{nh(i)}$ is the relative surface area of natural area x within the neighborhood that i belongs to ($nh(i)$). In other words, the surface area of a natural area is divided by the number of nodes in the neighborhood and the surface area of the neighborhood. Thus $R_x^{nh(i)} = \frac{T(x)}{T(nh(i))n_{nh}}$, where $T(x)$ is the surface area of x natural area, $T(nh)$ is the surface area of nh neighborhood and n_{nh} is the number of nodes in neighborhood nh . The final environmental index:

$$Q_i^{environment} = \frac{1 + T_i}{1 + C_i},$$

That after a normalization is:

$$\tilde{Q}_i^{environment} = \frac{Q_i^{environment}}{\max(Q^{environment})}$$

5.4 Results

We quantify life quality in terms of each category (family support, education healthcare, sport, culture, nightlife, environment), and an overall measurement which contains all 6 categories and crime rate normalized by the population for the city of Budapest. Our method allows us to measure life quality for each intersection of the city, which helps to capture within neighborhood inequalities too. Analysis on the category level is beneficial for targeted policy interventions for better service allocation.

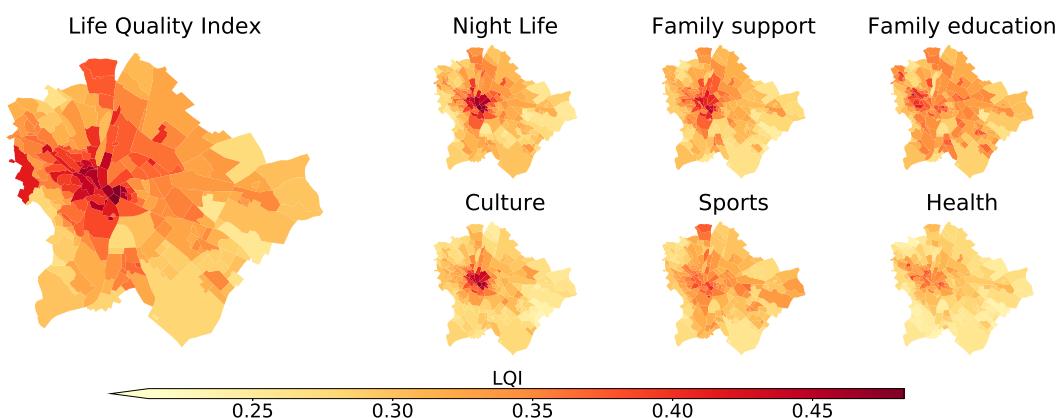


Figure 5.2. Budapest neighborhoods, average life quality by categories and aggregated life quality index.

Figure 5.2 shows our overall life quality index (LQI) and by categories. Heatmaps reveal important features of Budapest. Similarly to most European cities life quality is much better in the inner districts [227, 228], especially in the case of Night Life and Culture.

Budapest is divided by the Danube river into two main parts: Buda and Pest. The river does not only serve as a geographical border but due to historical reasons, it also divides the citizens by social status. Hilly Buda, on the West side of the river, used to be the capital of the country, with the residence of the former Hungarian king. On the other side, the mainly flat Pest used to be the agricultural supporter of the aristocrats in Buda [229]. Even though the city

has changed dramatically since the Monarchy, the division of Buda and Pest persists, and our life quality index captures it well. However certain services are legally guaranteed to be evenly distributed in the city, such as education and healthcare, for precise modeling one should take into account private care too, which highlights inequalities. So, the traditional division of Buda and Pest is even visible in categories where there should not be that much of a difference (Education, Family Support, Healthcare).

Results also highlight that category LQI-s are highly correlated, less liveable neighborhoods are constant regardless of the amenity category, and well-performing neighborhoods do not change either. It is caused by two main factors: the lack of amenities and the relatively high walking distances in the suburbs.

The compact city concept focuses on building more sustainable and livable cities while designing practical neighborhoods where citizens can maintain everyday life without a car [230]. Since, the walkability of a neighborhood highly correlates with its liveability [231] and the suburbs in Budapest do not show any compact city design features, both long distances and the lack of amenities effects suburban habitats lives negatively.

5.4.1 Evaluation

Multiple methods have been developed to evaluate the accuracy of quality of life metrics: Scholars used expert validation with geographic visualization [232, 233], correlations with socioeconomic characteristics [234] and surveying citizens' perceptions of the conditions of life [235].

Our evaluation is based on the micro-economical *hedonic approach* of estimating the values of public goods. In a capitalist market, real estate prices reflect the recognition of a neighborhood's characteristics: Prices are formed based on demand, more desirable places are more expensive, due to the underlying assumption of providing a higher quality of life. [228] Estimating neighborhoods life-quality with real estate prices has a long tradition in urban literature [236, 237, 238], therefore we adopt this method to evaluate our model.

We collected the average m^2/EUR price for all 23 districts of Budapest in January 2019 [239] and correlated each LQI category averaged by district with it. Figure 5.3 shows that our overall LQI correlates the most ($R=0.91$) with the real-estate prices. Most of its components have a positive correlation with real-estate prices, except the environment which is calculated based on air pollution and green surface proximity. The life quality (LQI) in Budapest is much higher in densely populated downtown districts, which are lack of green surface and suffers from high air pollution due to heavy traffic.

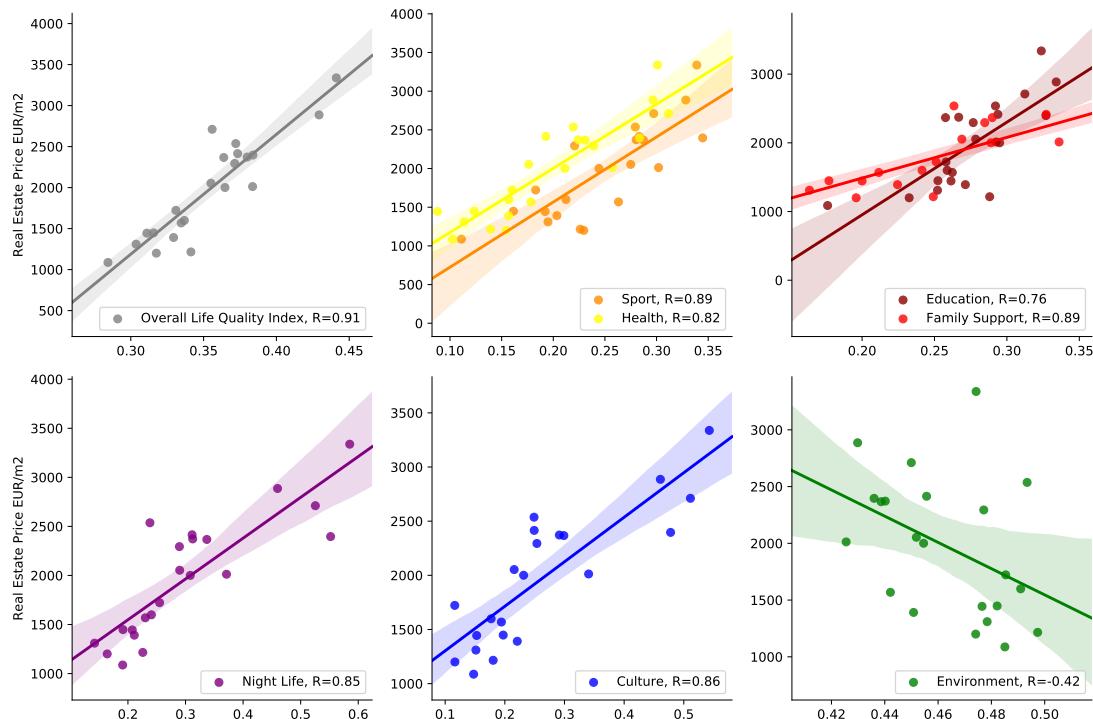


Figure 5.3. Districts of Budapest Life Quality Index (LQI) and its components correlated with real estate prices (m^2/EUR)

Summary Locals of Budapest, like in most European cities, traditionally values downtown areas. The relative closeness to CBD, good access to public transport, and vital city life kept it as a desirable area for living [240]. However, in recent years, the city is facing new challenges: due to gentrification [241] and over-tourism (eg.:Airbnb) real estate prices are sky-rocketing in downtown areas. In contrast with the early 2000-s when (upper) middle-class moved to the suburbs, nowadays, lower-income families and young professionals are leaving the downtown behind in hope for more affordable living.

As our findings show, Budapest is quite centralized and the quality of life highly correlates with real estate prices, which possibly lead to even more inequalities in the future. This spatial discrimination with longer traveling time, less fulfilling environment, and potential segregation reduces the chances of upward mobility and the quality of life of individuals [242].

5.5 Discussion

We have proposed a methodology to quantify life quality as a function of walkability on urban networks. We have used open data to capture inequalities between neighborhoods and districts in the city. We have shown that the real estate market reflects the life quality that our methods found.

A data-driven approach for quantifying life quality at such a granular level like our proposed method can help decision-makers to tackle social and environmental challenges better. Designing compact, liveable neighborhoods, considering also the upcoming environmental crisis is the number one priority of many cities worldwide.

The use of open data sources and algorithmic approaches adds up towards a systematic framework for understanding urban liveability. Our current approach is not the last word in this development since it does not yet account for multiple other variables, such as the quality of services and infrastructure, and other qualitative variables. To capture the more specific indicator of liveability in different cities it would be necessary to work with more granular and city-dependant data.

We anticipate a future stream of research focused on the use of worldwide open data sets to quantify urban liveability, including longitudinal studies in multiple cities, along with algorithmic modeling, simulations, and machine learning approaches, to first quantify the liveability, propose changes and test them with the ground truth data.

CHAPTER 6

CONCLUSION AND OPEN QUESTIONS

Conclusion for chapters and thesis [Luis: Personal reflection of interdisciplinary approaches (social sciences benefit from quantitative methods, but it is important to acknowledge interdisciplinary as a two-way street, recognize the importance of social sciences, and the long tradition of urban studies. Not because we have a hammer, should we treat everything as if it were a nail)]

Future Work

What is next.

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CHAPTER 7

APPENDICES

7.1 Data-driven strategies for optimal bicycle network growth

7.1.1 Data

Figure 7.1 shows the connected component size distribution $P(N_{cc})$ for all considered layers and cities.

7.1.2 Bicycle network improvement

Here we show the improvement of the bicycle network after the implementation of the algorithms. We measure the improvement with four different metrics. Two of them implement the notion of connectedness: i) Fraction of nodes inside the largest connected component compared to the total number of nodes in the bicycle layer, and ii) the fraction of link kilometers inside the largest connected component. In Figure 7.2 and 7.3 we show these two measures for fourteen different cities. We also quantify iii) bicycle-to-car directness to answer the question “how direct are the average routes of bicycles compared to cars?”. Finally, in order to measure the cumulative efficiency of our algorithms, we define the metric: iv) G_{LCC} as the relative gain of bicycle path kilometers in the largest connected component. In Figures 7.5 and 7.6 we report these two measures for all algorithms and cities considered.

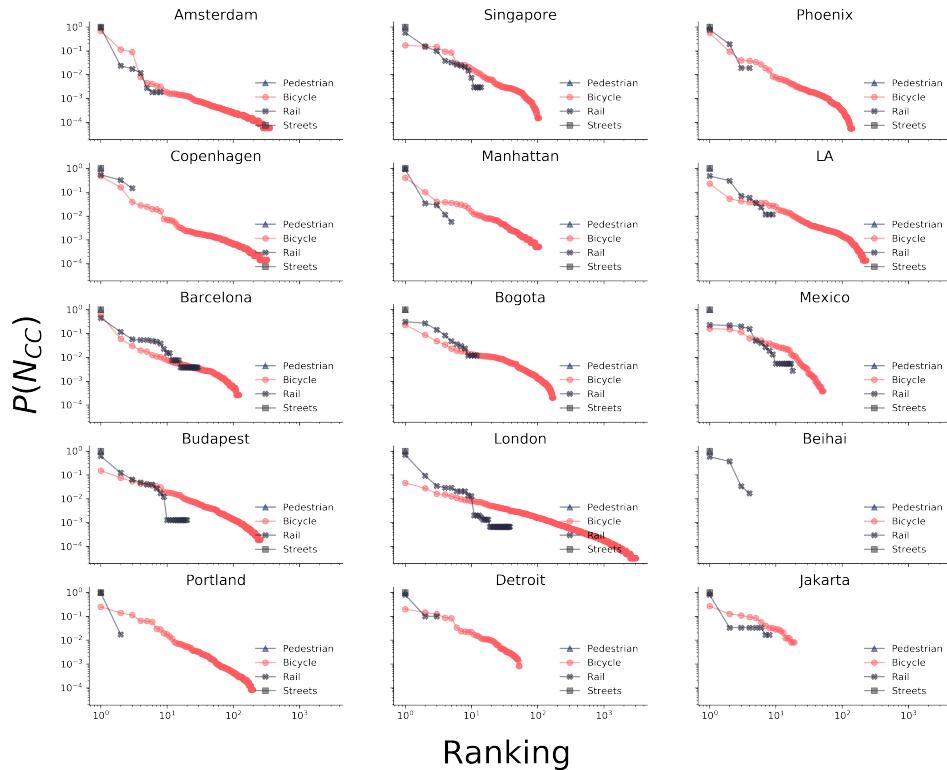


Figure 7.1. The connected component size distribution [$P(N_{cc})$] for all cities and layers is well connected except in the bicycle layer. London has the most fragmented bicycle infrastructure layer, with more than 3000 components

7.1.3 Bicycle network and 30 km/h streets

We applied the algorithms to the bicycle infrastructure and all the bike friendly streets, those with a speed limit of 30 km/h or less (see Figures 7.7, 4.4, 7.8, and 7.9).

7.2 Life quality as walkability

7.2.1 Secondary data sources

- Sport associations in Budapest [243]

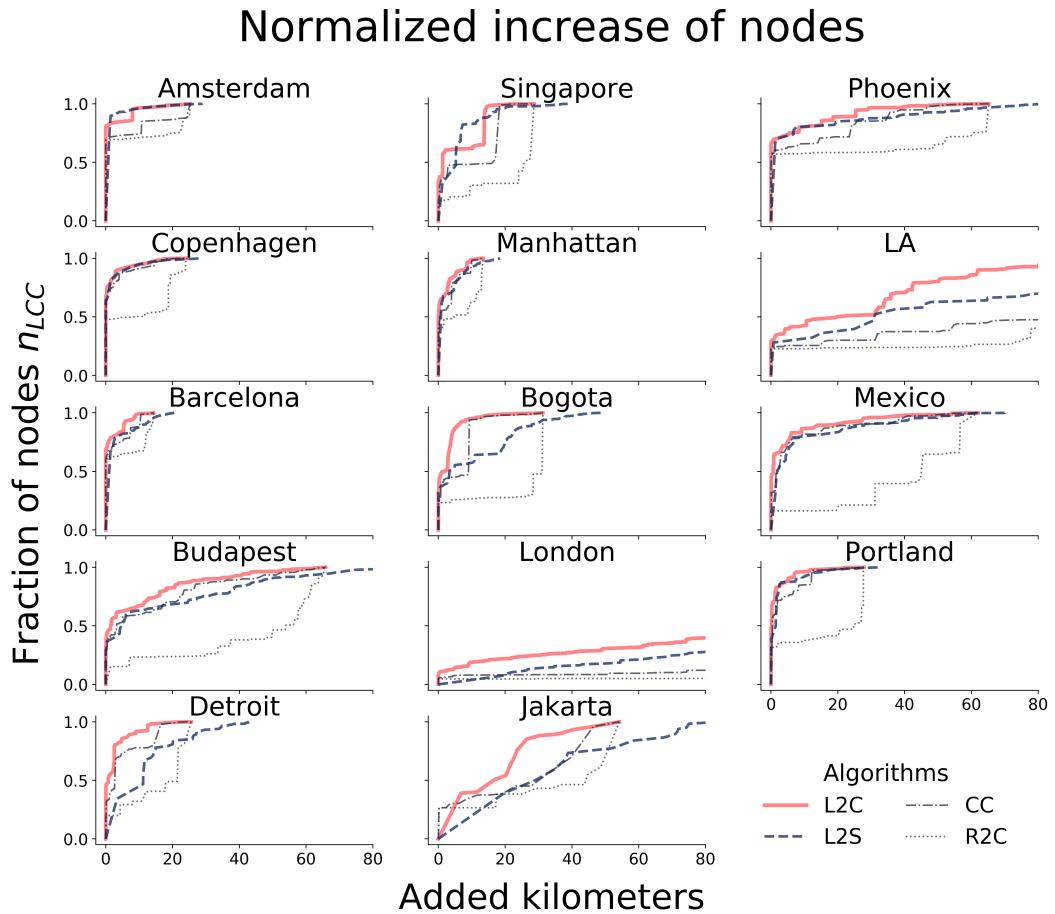


Figure 7.2. Normalized increase in nodes inside the largest connected component (n_{LCC}).

- Kindergartens, daycare, primary and secondary education [244]
- Art and music schools [245]
- Child health services [246]
- Social welfare system (eg.: elderly care) [247]
- Culture centers [248]
- Indoor playgrounds [249]
- Healthcare (hospitals, private and public clinics, specialists) [250]

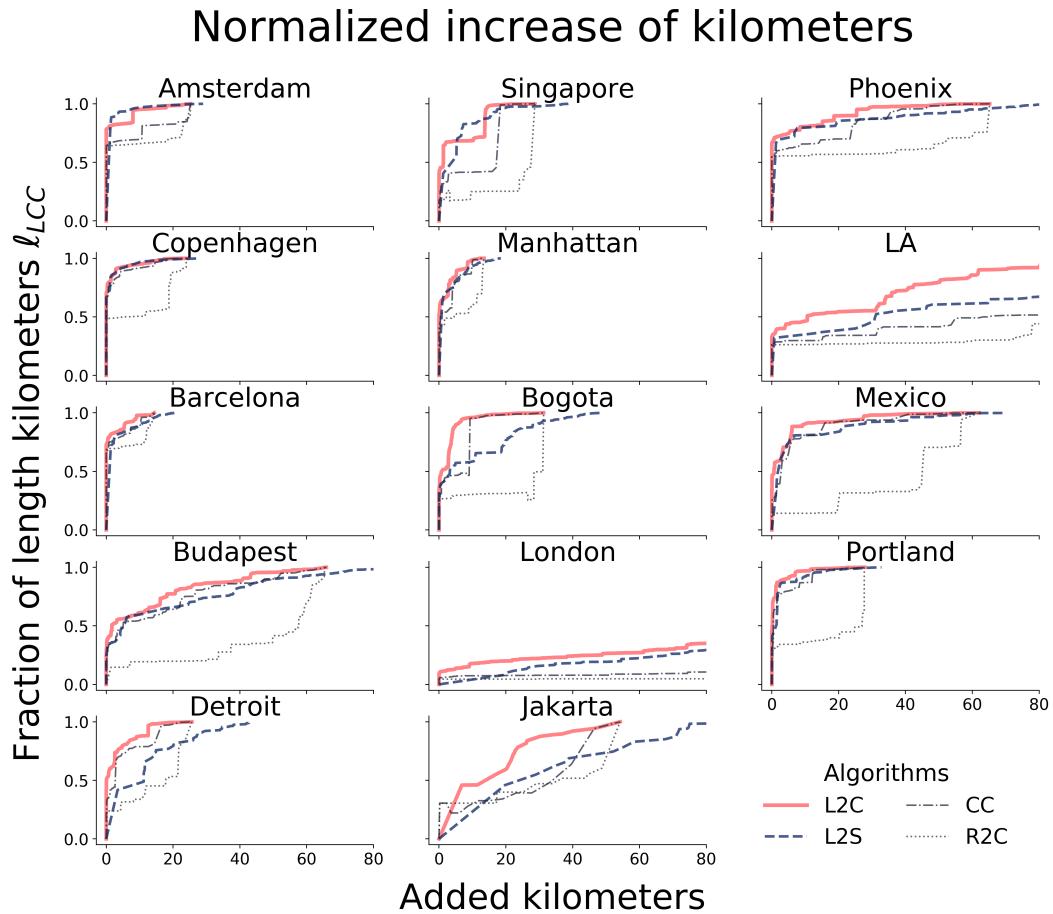


Figure 7.3. Normalized increase in kilometers inside the largest connected component (ℓ_{LCC}).

- Fitness and training facilities [251]
- Outdoor fitness facilities [252]
- Thermal baths and spa [253]
- Playgrounds and parks [254]

7.2.2 Categorization

The amenities used for each category are as follows:

- Culture

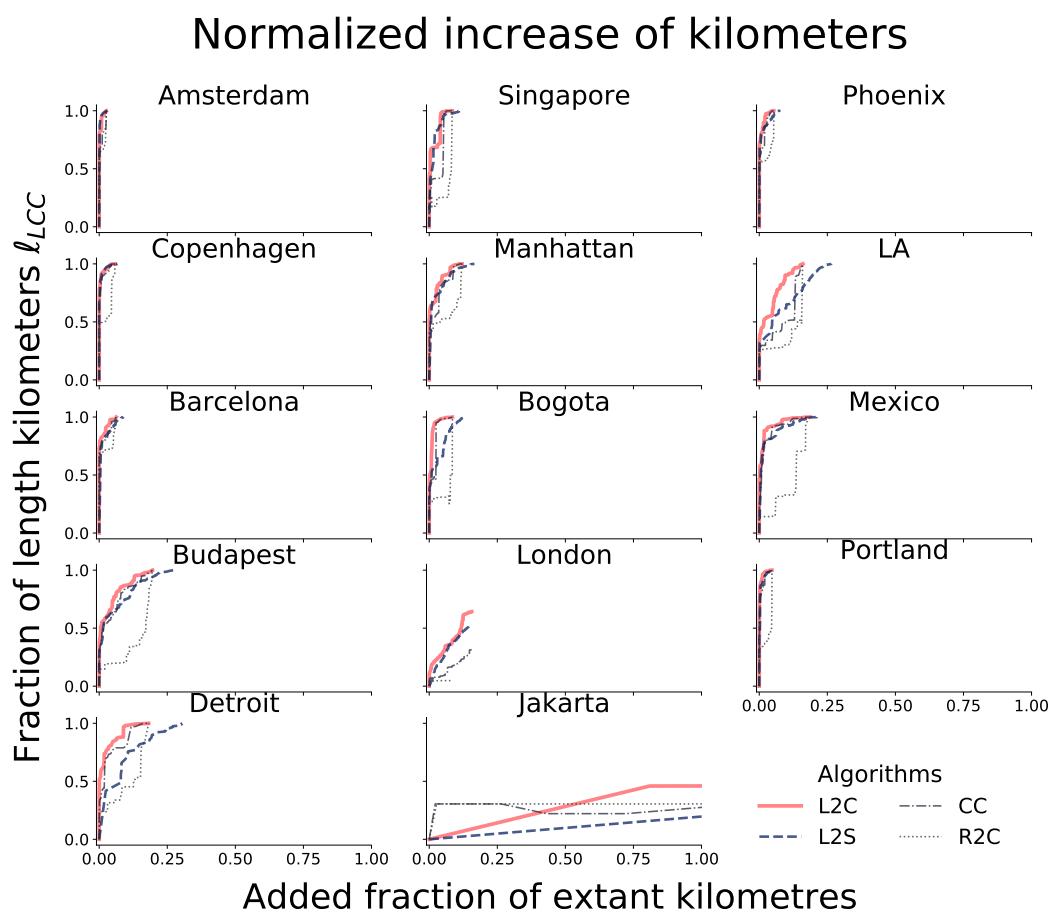


Figure 7.4. Normalized increase in kilometers inside the largest connected component (ℓ_{LCC}) versus the fraction of extant kilometers to be added.

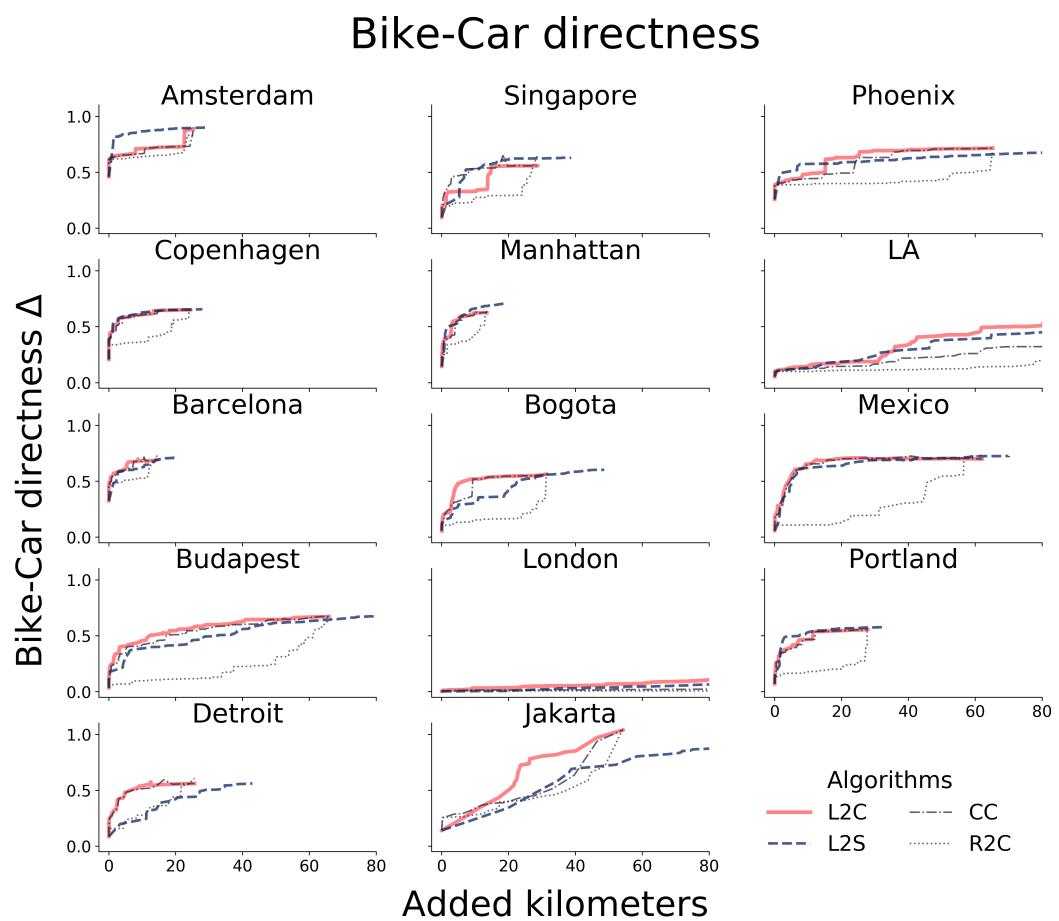


Figure 7.5. Bike-car directness Δ per invested kilometers.

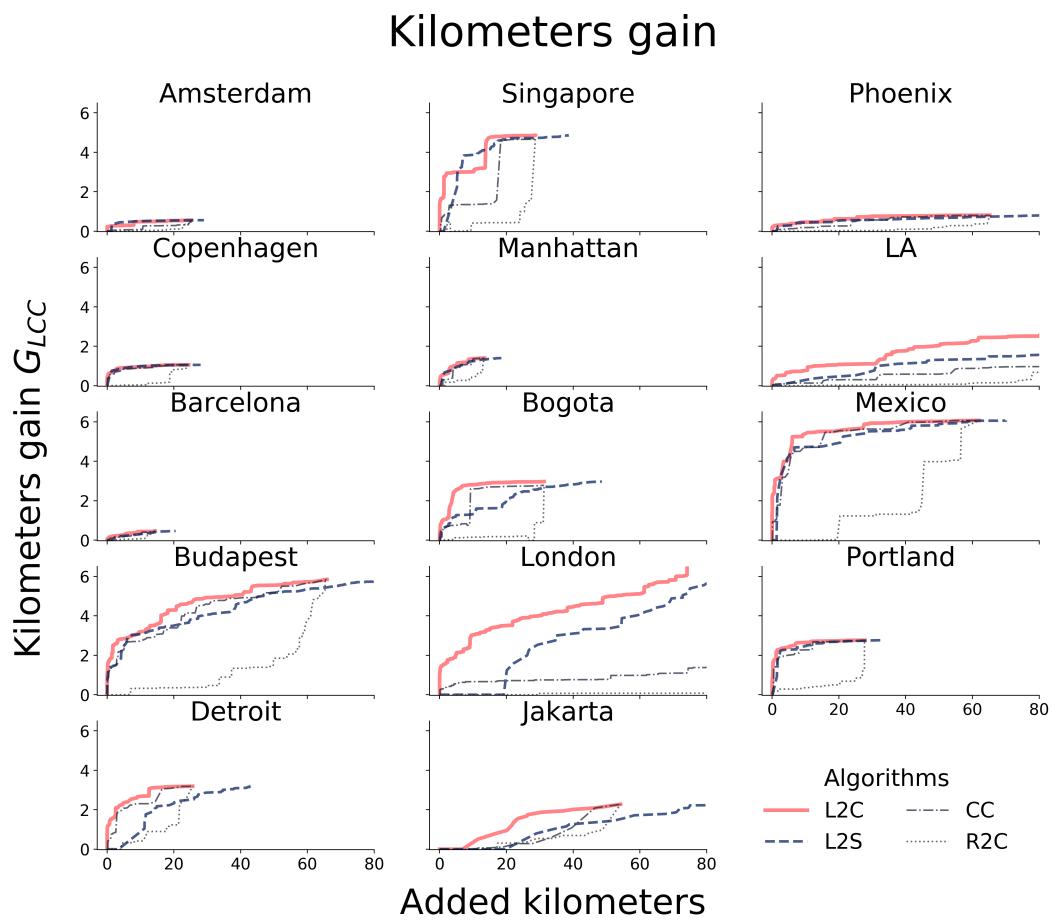


Figure 7.6. Kilometers gain in the largest connected component.

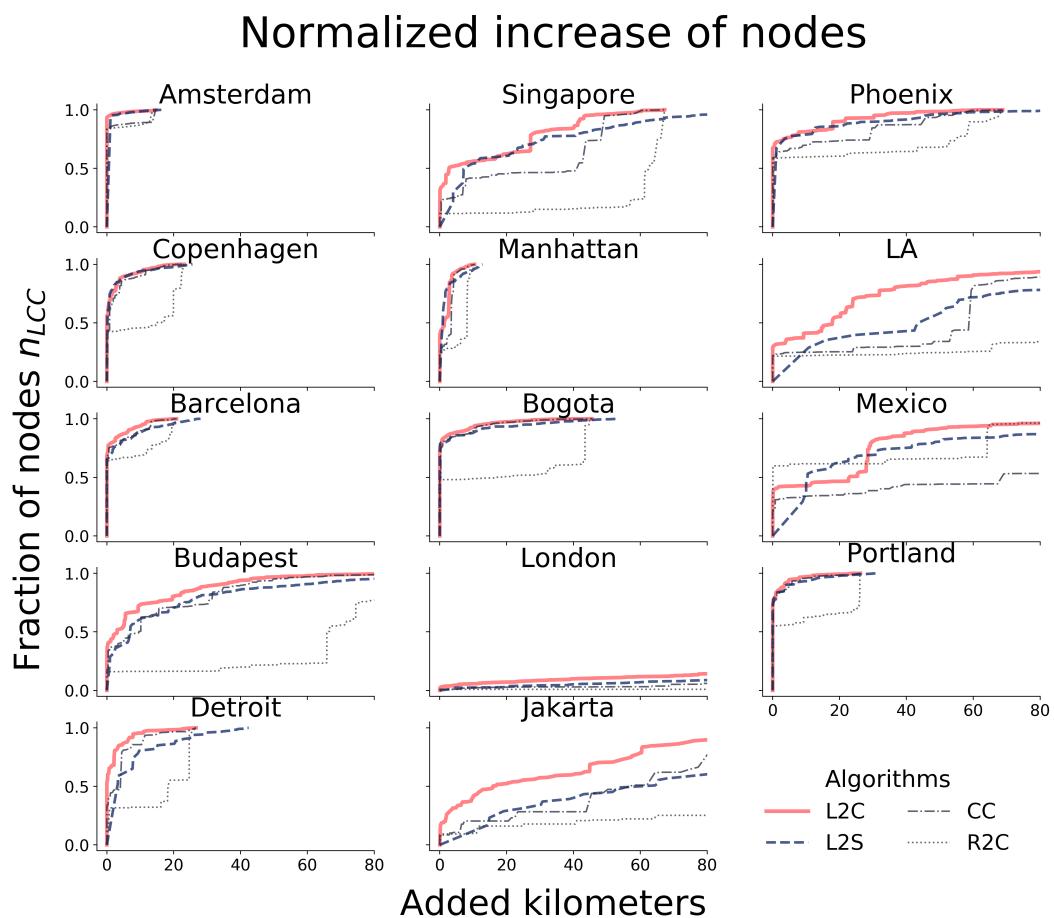


Figure 7.7. Normalized increase in nodes inside the largest connected component (n_{LCC}).

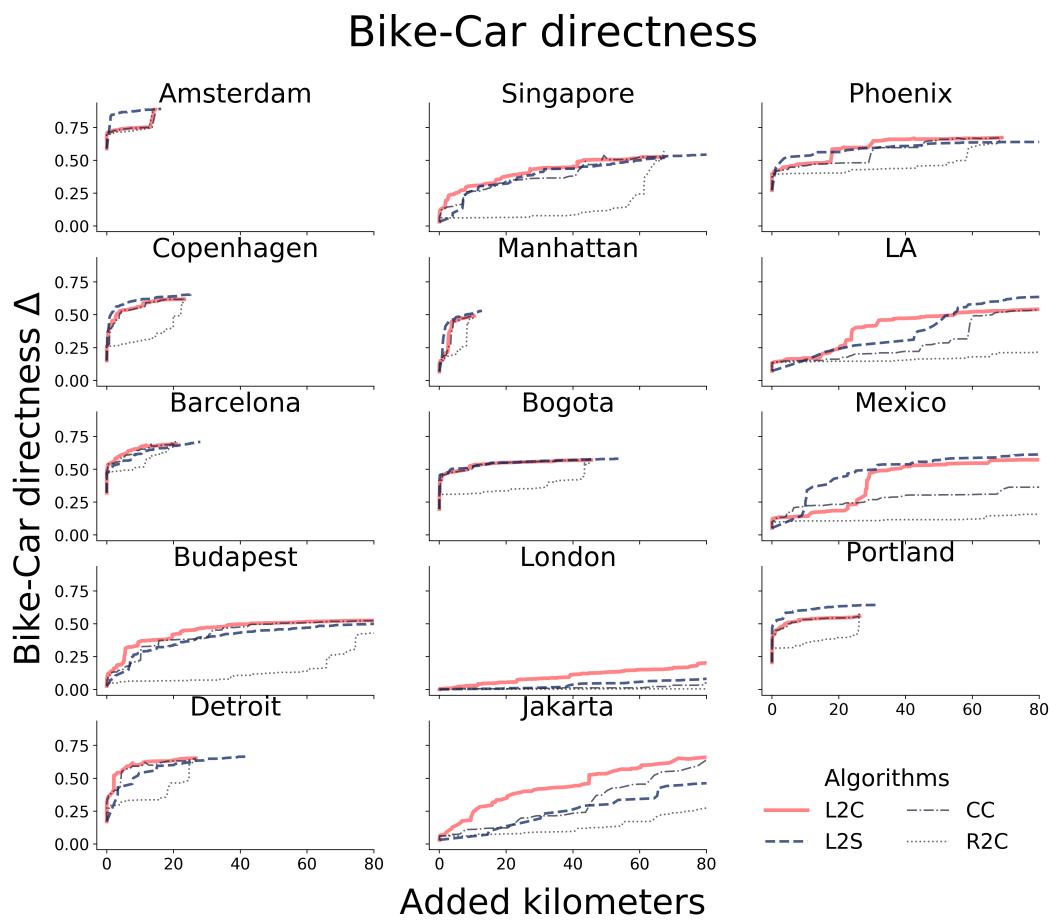


Figure 7.8. Bike-car directness Δ per invested kilometers.

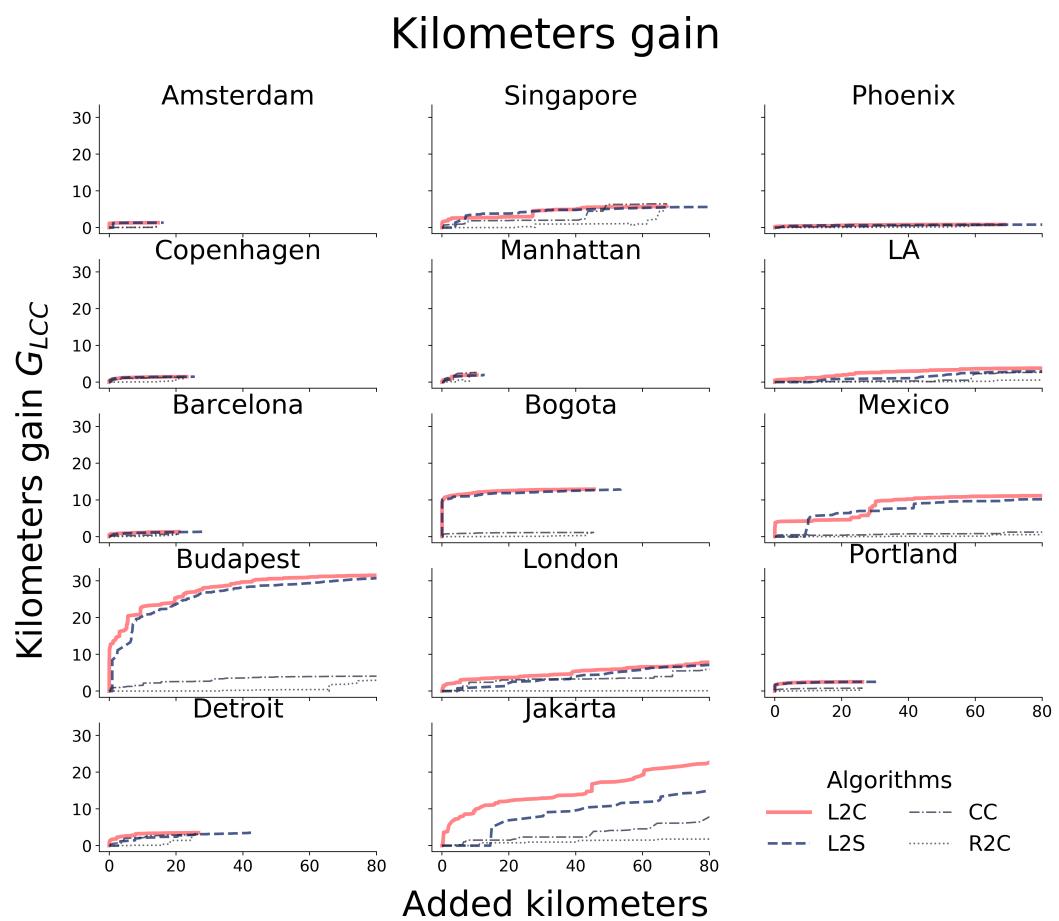


Figure 7.9. Kilometers gain in the largest connected component.

LIST OF TABLES

3.1 Layers measures for analyzed cities	35
4.1 Measures for analyzed cities	44

LIST OF FIGURES

1.1	Network representation of a city	3
3.1	Manhattan multiplex network	35
3.2	Schematic overlap census	36
3.3	Overlap Census clusters	38
4.1	Multimodal configuration	43
4.2	Algorithms schematic representation	49
4.3	Algorithmic improvement in Budapest	51
4.4	Normalized increase in kilometers inside the largest connected component (ℓ_{LCC})	52
4.5	Cities bicycle connectivity improvement 5 new kilometers	53
4.6	Cities bicycle connectivity improvement 35 new kilometers	55
4.7	Bicycle infrastructure service area	56
5.1	Budapest pedestrian network	63
5.2	Budapest neighborhoods life quality index	68
5.3	Budapest life quality index correlation with real estate prices	70
7.1	Connected component size distribution for analyzed cities	98
7.2	Normalized increase in nodes inside the largest connected component (n_{LCC})	99
7.3	Normalized increase in kilometers inside the largest connected component (ℓ_{LCC})	100
7.4	Normalized increase in kilometers inside the largest connected component (ℓ_{LCC}) versus the fraction of extant kilometers to be added.	101
7.5	Bike-car directness Δ per invested kilometers.	102
7.6	Kilometers gain in the largest connected component.	103

7.7	Normalized increase in nodes inside the largest connected component (n_{LCC}).	104
7.8	Bike-car directness Δ per invested kilometers.	105
7.9	Kilometers gain in the largest connected component.	106

