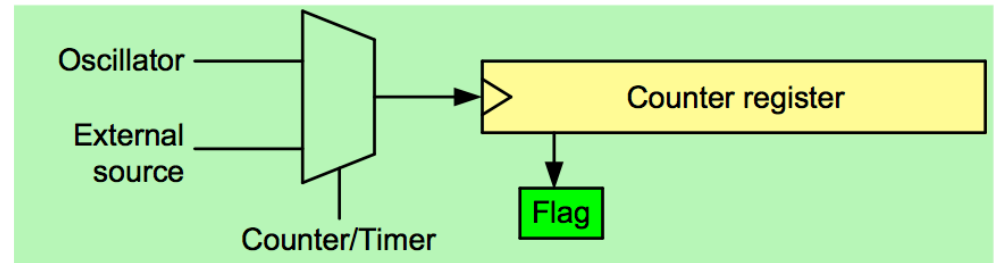


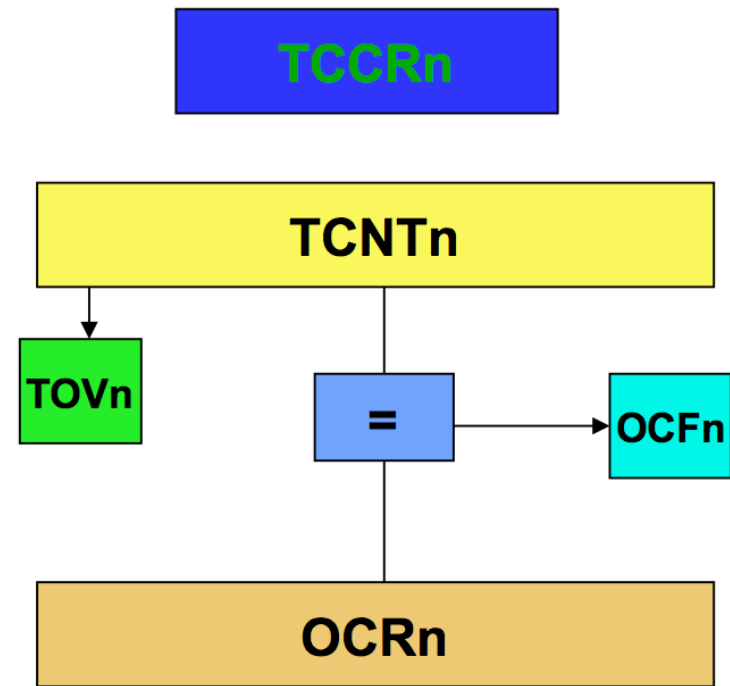
Timer in AVR

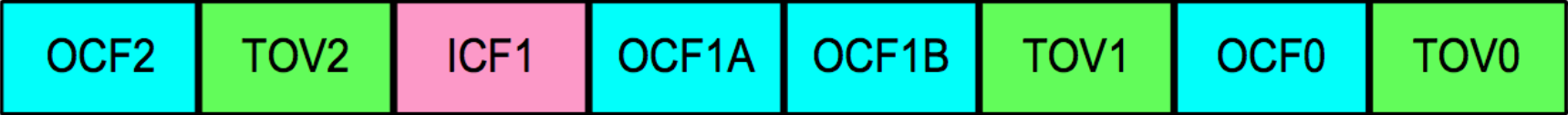
- **TCNTn** (Timer/Counter register)
- **TOVn** (Timer Overflow flag)
- **TCCRn** (Timer Counter control register)
- **OCRn** (output compare register)
- **OCFn** (output compare match flag)



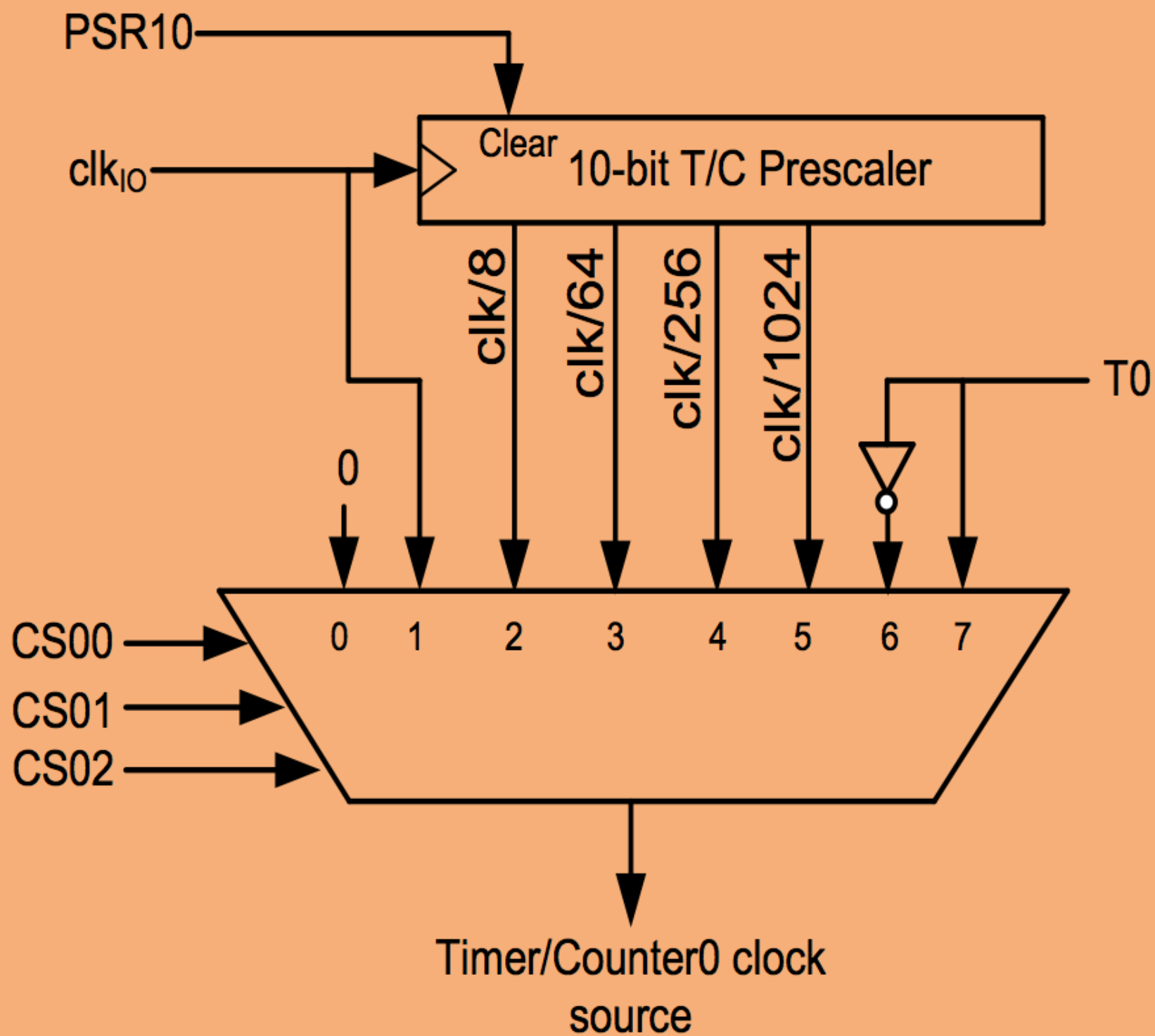
Comment:

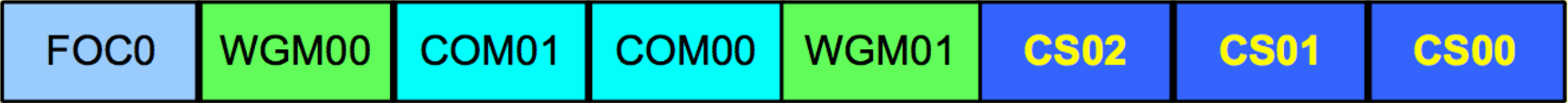
All of the timer registers are
byte-addressable I/O registers





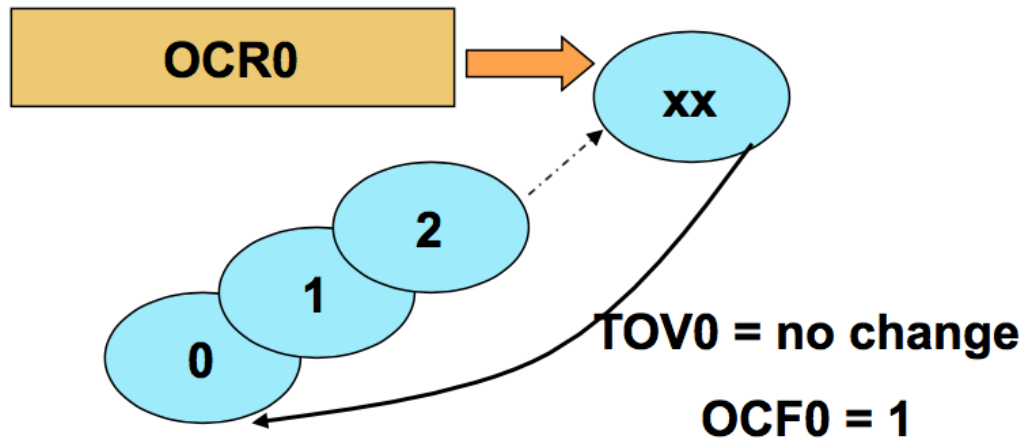
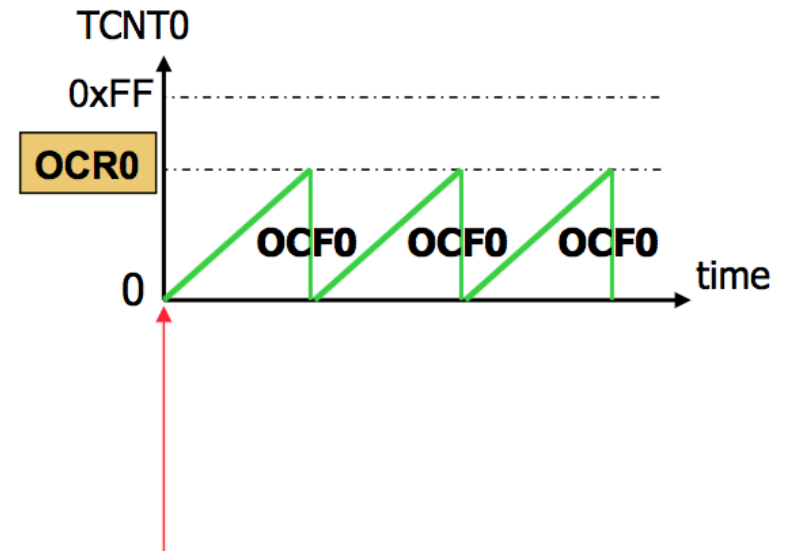
TIFR





WGM00	WGM01	Comment
0	0	Normal
0	1	CTC (Clear T
1	0	PWM, phase
1	1	Fast PWM

CTC (Clear Timer on Compare match) mode



TOV0: **0**

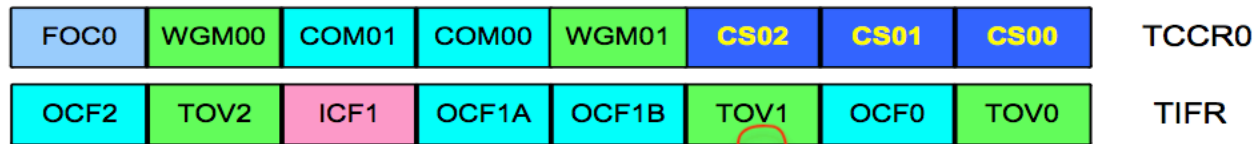
OCF0: **1**

Example 1: Write a program that waits 14 machine cycles in Normal mode.

\$100

-\$0E

\$F2



0 0 0 0 0 0 0 1

.INCLUDE "M32DEF.INC"

set byte
immediate

```
LDI R16,0x20
SBI DDRB,5 ;PB5 as an output
```

```
LDI R17,0
OUT PORTB,R17
BEGIN: LDI R20,0xF2
OUT TCNT0,R20 ;load timer0
```

```
LDI R20,0x01
OUT TCCR0,R20 ;Ti
AGAIN: IN R20,TIFR
SBRS R20,0 ;if TOV
RJMP AGAIN
```

```
LDI R20,0x0
OUT TCCR0,R20
LDI R20,(1<<TOV0)
OUT TIFR,R20
```

toggle

```
EOR R17,R16
OUT PORTB,R17
RJMP BEGIN
```

```
DDRB = 1<<5;
PORTB &= ~(1<<5); //PB5=0
while (1)
{
```

Question: How to calculate the delay generated by the timer?

Answer:

- 1) Calculate how much a machine clock lasts.
 $T = 1/f$
- 2) Calculate how many machine clocks it waits.
- 3) Delay = T * number of machine cycles

In example 1 calculate the delay. XTAL = 10 MHz.

Solution 1 (inaccurate):

1) Calculating T:

$$T = 1/f = 1/10M = 0.1\mu s$$

2) Calculating num of machine cycles:

\$100

-\$F2

$$\$0E = 14$$

3) Calculating delay

$$14 * 0.1\mu s = 1.4 \mu s$$

```
.INCLUDE "M32DEF.INC"
```

```

        LDI    R16,0x20
        SBI    DDRB,5    ;PB5 as an output
        LDI    R17,0
        OUT    PORTB,R17
BEGIN:   LDI    R20,0xF2
        OUT    TCNT0,R20    ;load timer0
        LDI    R20,0x01
        OUT    TCCR0,R20 ;Timer0,Normal mode,int clk
AGAIN:   IN     R20,TIFR    ;read TIFR
        SBRS   R20,0 ;if TOV0 is set skip next inst.
        RJMP   AGAIN
        LDI    R20,0x0
        OUT    TCCR0,R20    ;stop Timer0
        LDI    R20,0x01
        OUT    TIFR,R20    ;clear TOV0 flag

        EOR    R17,R16    ;toggle D5 of R17
        OUT    PORTB,R17  ;toggle PB5
        RJMP   BEGIN
    
```


start-timer:

LDI R20, 0x00	n
OUT TCNT0, R20	n
LDI R20, 0x02	n
OUT TCCR0, R20	; normal mode, clk/8 n
RET	

stop-timer:

LDI R20, 0x00	y
OUT TCCR0, 0x00	; clk stopped y
RET	

-4

The difference between Timer0 and Timer2

- **Timer0**

- **Timer2**

CS02	CS01	CS00	Comment
0	0	0	Timer/Counter stopped
0	0	1	clk (No Prescaling)
0	1	0	clk / 8
0	1	1	clk / 64
1	0	0	clk / 256
1	0	1	clk / 1024
1	1	0	External clock (falling edge)
1	1	1	External clock (rising edge)

CS22	CS21	CS20	Comment
0	0	0	Timer/Counter stopped
0	0	1	clk (No Prescaling)
0	1	0	clk / 8
0	1	1	clk / 32
1	0	0	clk / 64
1	0	1	clk / 128
1	1	0	clk / 256
1	1	1	clk / 1024

Example 2: Assuming that XTAL = 10 MHz, write a program to generate a square wave with a period of 10 ms on pin PORTB.3.

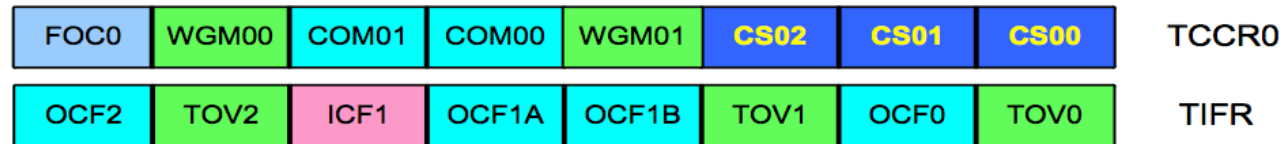
- For a square wave with $T = 10 \mu\text{s}$ we must have a time delay of $5 \mu\text{s}$. Because $\text{XTAL} = 10 \text{ MHz}$, the counter counts up every $0.1 \mu\text{s}$. This means that we need $5 \mu\text{s} / 0.1 \mu\text{s} = 50$ clocks. $256 - 50 = 206$.

```
.INCLUDE "M32DEF.INC"
```

```
        LDI        R16,0x08
        SBI        DDRB,3    ;PB3 as an output
        LDI        R17,0
        OUT        PORTB,R17
BEGIN:   LDI        R20,206
        OUT        TCNT0,R20    ;load timer0
        LDI        R20,0x01
        OUT        TCCR0,R20 ;Timer0,Normal mode,int clk
AGAIN:   IN        R20,TIFR      ;read TIFR
        SBRS       R20,TOV0 ;if TOV0 is set skip next
        RJMP       AGAIN
        LDI        R20,0x0
        OUT        TCCR0,R20    ;stop Timer0
        LDI        R20,0x01
        OUT        TIFR,R20     ;clear TOV0 flag
        EOR        R17,R16      ;toggle D3 of R17
        OUT        PORTB,R17    ;toggle PB3
        RJMP       BEGIN
```

```
DDRB = 1<<3;
PORTB &= ~ (1<<3);
while (1)
{
    TCNT0 = 206;
    TCCR0 = 0x01;
    while((TIFR&0x01) == 0);
    TCCR0 = 0;
    TIFR = 1<<TOV0;
    PORTB = PORTB ^ (1<<3);
}
```

Example 1: Rewrite example 2 using CTC



- For a square wave with $T = 10 \mu s$ we must have a time delay of $5 \mu s$. Because $XTAL = 10 \text{ MHz}$, the counter counts up every $0.1 \mu s$. This means that we need $5 \mu s / 0.1 \mu s = 50$ clocks. Therefore, we have $OCR0 = 49$.

```
.INCLUDE "M32DEF.INC"
    LDI    R16,0x08
    SBI    DDRB,3    ;PB3 as an output
    LDI    R17,0
    OUT    PORTB,R17
    LDI    R20,49
    OUT    OCR0,R20 ;load timer0
BEGIN:  LDI    R20,0x09
    OUT    TCCR0,R20 ;Timer0,CTC mode,int clk
AGAIN:  IN     R20,TIFR    ;read TIFR
    SBRS   R20,OCF0 ;if OCF0 is set skip next
    RJMP   AGAIN
    LDI    R20,0x0
    OUT    TCCR0,R20    ;stop Timer0
    LDI    R20,0x02
    OUT    TIFR,R20     ;clear TOV0 flag
    EOR    R17,R16      ;toggle D3 of R17
    OUT    PORTB,R17    ;toggle PB3
    RJMP   BEGIN
```

```
DDRB |= 1<<3;
PORTB &= ~(1<<3);
while (1)
{
    OCR0 = 49;
    TCCR0 = 0x09;

    while((TIFR & (1<<OCF0)) == 0);

    TCCR0 = 0; //stop timer0
    TIFR = 0x02;
    PORTB.3 = ~PORTB.3;
}
```