

Jafar — Intelligent Othello Agent

Joshua Nelson, Tim Cosgrove, Andrew Haigh

COMP3130 Research Project

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**Jafar —
Intelligent
Othello Agent**

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Andrew Haigh

Outline

Problem
Overview

Solution
Structure

Static Evaluation

TD- λ

Algorithm
description
Results

The EloArena

Future
Improvements

Design
Methodology

- 1 Problem Overview
- 2 Solution Structure
- 3 Static Evaluation
- 4 TD- λ
 - Algorithm description
 - Results
- 5 The EloArena
- 6 Future Improvements
- 7 Design Methodology



Problem Overview

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Othello Agent

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Outline

Problem
Overview

Solution
Structure

Static Evaluation

TD- λ

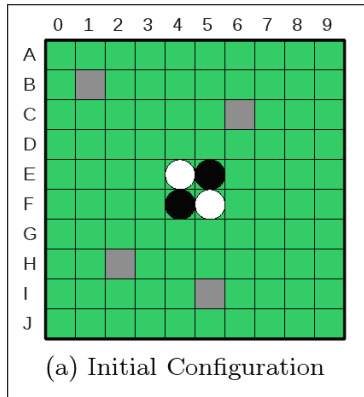
Algorithm
description
Results

The EloArena

Future
Improvements

Design
Methodology

- The Game — 10x10 Modified Othello



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Outline

Problem
Overview

Solution
Structure

Static Evaluation

TD- λ

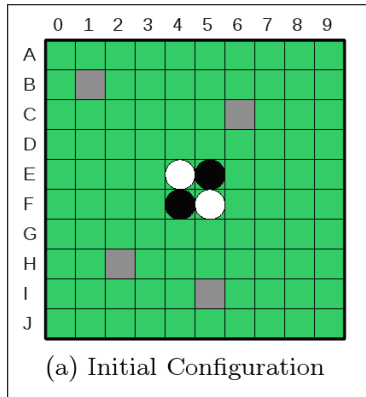
Algorithm
description
Results

The EloArena

Future
Improvements

Design
Methodology

- The Game — 10x10 Modified Othello
- The Problem — Intelligent AI player



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Outline

Problem
Overview

Solution
Structure

Static Evaluation

TD- λ

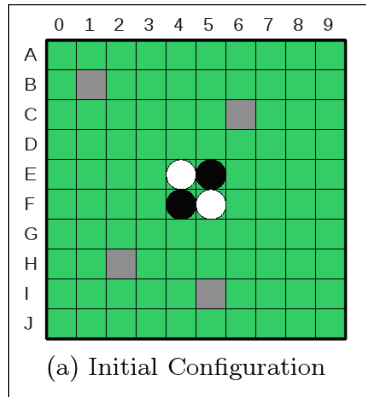
Algorithm
description
Results

The EloArena

Future
Improvements

Design
Methodology

- The Game — 10x10 Modified Othello
- The Problem — Intelligent AI player
- Solution basis



Solution Structure

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Outline

Problem
Overview

**Solution
Structure**

Static Evaluation

TD- λ

Algorithm
description
Results

The EloArena

Future
Improvements

Design
Methodology

- The MetaPlayer class — Utilises knowledge of the game state and creates instances of other players accordingly

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Othello Agent

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Outline

Problem
Overview

Solution
Structure

Static Evaluation

TD- λ

Algorithm
description
Results

The EloArena

Future
Improvements

Design
Methodology

- The MetaPlayer class — Utilises knowledge of the game state and creates instances of other players accordingly
- NegamaxPlayer (varying depth argument)
- OpeningPlayer
- GreedyPlayer

Static Evaluation

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Outline

Problem
Overview

Solution
Structure

Static Evaluation

TD- λ

Algorithm
description
Results

The EloArena

Future
Improvements

Design
Methodology

- The FeatureSet class — Maintains a list of *features*; functions which evaluate a game state based on some criteria of strength

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Outline

Problem
Overview

Solution
Structure

Static Evaluation

TD- λ

Algorithm
description
Results

The EloArena

Future
Improvements

Design
Methodology

- The FeatureSet class — Maintains a list of *features*; functions which evaluate a game state based on some criteria of strength
- LegalMoves
- Visibility
- StoneCount
- BlockedAdjacent, CornerPieces, SidePieces

TD- λ

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Outline

Problem
Overview

Solution
Structure

Static Evaluation

TD- λ

**Algorithm
description**
Results

The EloArena

Future
Improvements

Design
Methodology

- Remaining challenge: decide how important each feature is (the feature 'weights')

TD- λ

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Outline

Problem
Overview

Solution
Structure

Static Evaluation

TD- λ

Algorithm
description
Results

The EloArena

Future
Improvements

Design
Methodology

- Remaining challenge: decide how important each feature is (the feature 'weights')
- Solution - use the TD λ formula to calculate the new weights

- $$w := w + \alpha \sum_{T=1}^{N-1} \tilde{J}(x_t, w) * \left(\sum_{j=t}^{N-1} \lambda^{j-t} d_t \right)$$

The J Function

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Outline

Problem
Overview

Solution
Structure

Static Evaluation

TD- λ

Algorithm
description
Results

The Elo Arena

Future
Improvements

Design
Methodology

$$w := w + \alpha \sum_{T=1}^{N-1} \Delta \tilde{J}(x_t, w) * (\sum_{j=t}^{N-1} \lambda^{j-t} d_t)$$

- The J function returns a probability of winning, given a set of weights and a board.
- The perfect J function would always return 0 or 1 precisely.
- We are trying to learn a good approximation to the J function

TD: Temporal difference

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Outline

Problem
Overview

Solution
Structure

Static Evaluation

TD-λ

Algorithm
description
Results

The Elo Arena

Future
Improvements

Design
Methodology

$$w := w + \alpha \sum_{T=1}^{N-1} \Delta \tilde{J}(x_t, w) * (\sum_{j=t}^{N-1} \lambda^{j-t} d_t)$$

- d_t is the *Temporal Difference* between successive game states.
- The key observation is that for an ideal J function this would always be zero.
- $\Delta \tilde{J}(x_t, w)$ corrects each weight according to whether it was pointing us in the right direction.

Initial J function

Lost game

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Outline

Problem
Overview

Solution
Structure

Static Evaluation

TD- λ

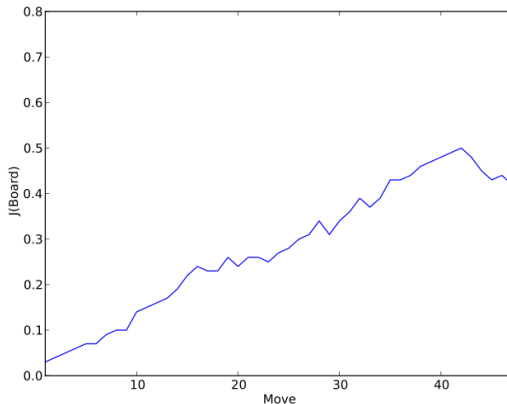
Algorithm
description

Results

The EloArena

Future
Improvements

Design
Methodology



J function after 6000 iterations

Lost game

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Outline

Problem
Overview

Solution
Structure

Static Evaluation

TD- λ

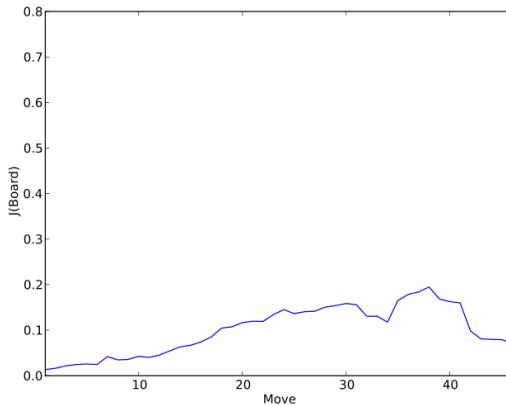
Algorithm
description

Results

The EloArena

Future
Improvements

Design
Methodology



J function after 6000 iterations

Won game

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Outline

Problem
Overview

Solution
Structure

Static Evaluation

TD- λ

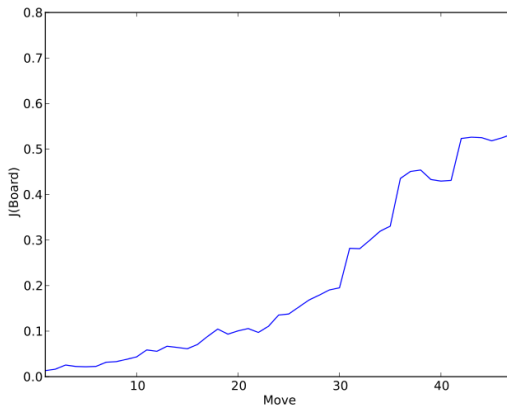
Algorithm
description

Results

The EloArena

Future
Improvements

Design
Methodology



The first 1000 learning iterations

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Outline

Problem
Overview

Solution
Structure

Static Evaluation

TD- λ

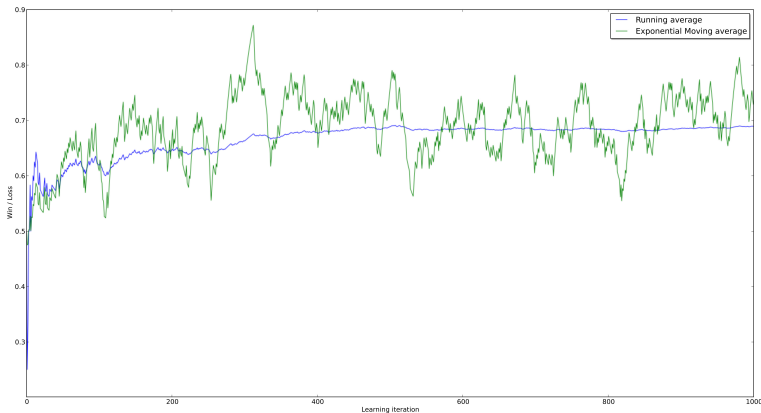
Algorithm
description

Results

The EloArena

Future
Improvements

Design
Methodology



The first 5000 learning iterations

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Outline

Problem
Overview

Solution
Structure

Static Evaluation

TD- λ

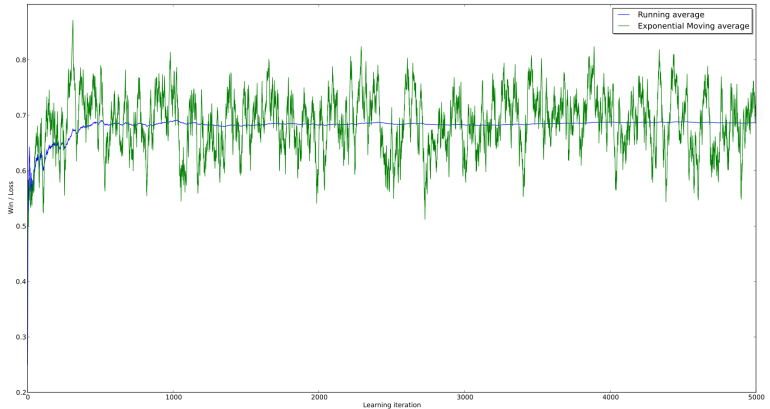
Algorithm
description

Results

The EloArena

Future
Improvements

Design
Methodology



Self play - learnt weights

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Outline

Problem
Overview

Solution
Structure

Static Evaluation

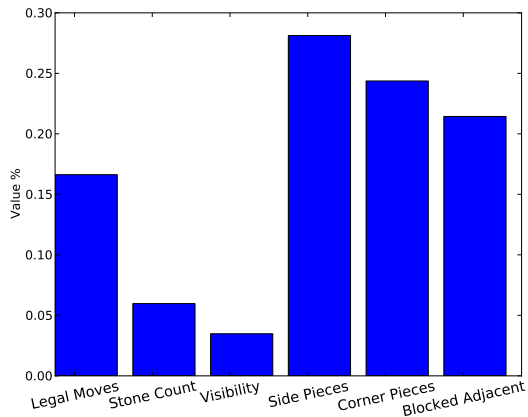
TD- λ

Algorithm
description
Results

The EloArena

Future
Improvements

Design
Methodology



Self play - learnt weights

White - Black

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Outline

Problem
Overview

Solution
Structure

Static Evaluation

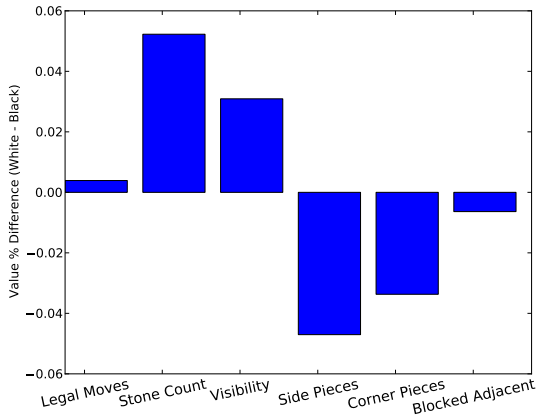
TD- λ

Algorithm
description
Results

The EloArena

Future
Improvements

Design
Methodology



Feature weight space visualisation

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Outline

Problem
Overview

Solution
Structure

Static Evaluation

TD- λ

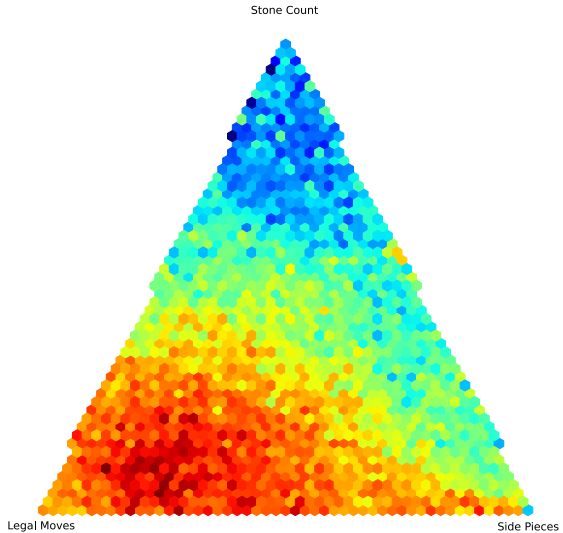
Algorithm
description

Results

The EloArena

Future
Improvements

Design
Methodology



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Outline

Problem
Overview

Solution
Structure

Static Evaluation

TD- λ

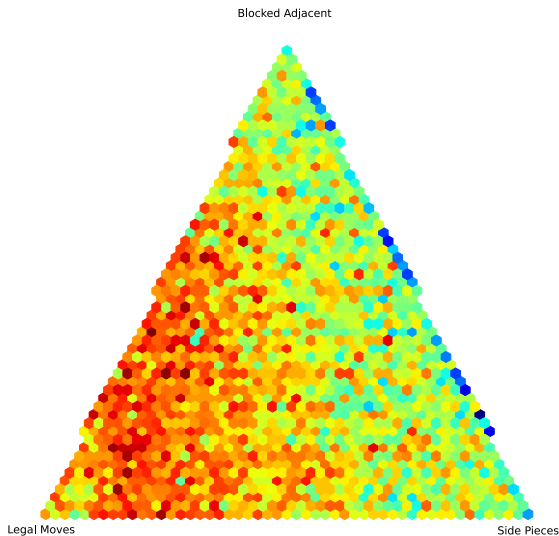
Algorithm
description

Results

The EloArena

Future
Improvements

Design
Methodology



The Elo Rankings Arena

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Outline

Problem
Overview

Solution
Structure

Static Evaluation

TD- λ

Algorithm
description
Results

The EloArena

Future
Improvements

Design
Methodology

- Custom made genetic algorithm
- Pits a group of randomly generated agents against each other for Elo style ranking points
- Creates new agents from those who perform best

The Elo Rankings Arena

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Outline

Problem
Overview

Solution
Structure

Static Evaluation

TD- λ

Algorithm
description
Results

The EloArena

Future
Improvements

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Methodology

- Custom made genetic algorithm
- Pits a group of randomly generated agents against each other for Elo style ranking points
- Creates new agents from those who perform best
- Used more as a demonstration of the learning process
- Interesting to see it come to the same conclusions as TD- λ

Future Improvements

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Outline

Problem
Overview

Solution
Structure

Static Evaluation

TD- λ

Algorithm
description
Results

The EloArena

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Improvements**

Design
Methodology

- More attention to blocked squares

Future Improvements

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Outline

Problem
Overview

Solution
Structure

Static Evaluation

TD- λ

Algorithm
description
Results

The EloArena

**Future
Improvements**

Design
Methodology

- More attention to blocked squares
- Negamax optimisations (better transposition tables, prob-cuts, etc.)

Future Improvements

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Outline

Problem
Overview

Solution
Structure

Static Evaluation

TD- λ

Algorithm
description
Results

The EloArena

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Improvements**

Design
Methodology

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- Better use of pre-computed data

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Outline

Problem
Overview

Solution
Structure

Static Evaluation

TD- λ

Algorithm
description
Results

The EloArena

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Improvements**

Design
Methodology

- More attention to blocked squares
- Negamax optimisations (better transposition tables, prob-cuts, etc.)
- Better use of pre-computed data
- More board features (locked squares, open squares, etc.)

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Outline

Problem
Overview

Solution
Structure

Static Evaluation

TD- λ

Algorithm
description
Results

The EloArena

Future
Improvements

Design
Methodology

- More attention to blocked squares
- Negamax optimisations (better transposition tables, prob-cuts, etc.)
- Better use of pre-computed data
- More board features (locked squares, open squares, etc.)
- More exploration in learning - randomise the initial board and play from that to explore more options

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Outline

Problem
Overview

Solution
Structure

Static Evaluation

TD- λ

Algorithm
description
Results

The EloArena

Future
Improvements

Design
Methodology

- C with a python interface
 - Used this for tic-tac-toe warm up problem, decided against due to development overhead

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Othello Agent

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Outline

Problem
Overview

Solution
Structure

Static Evaluation

TD- λ

Algorithm
description
Results

The EloArena

Future
Improvements

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Java

- Sacrifice low level speed improvements for high level language features and built in data structures.

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Problem
Overview

Solution
Structure

Static Evaluation

TD- λ

Algorithm
description
Results

The EloArena

Future
Improvements

Design
Methodology

