

How to organise (motion) data

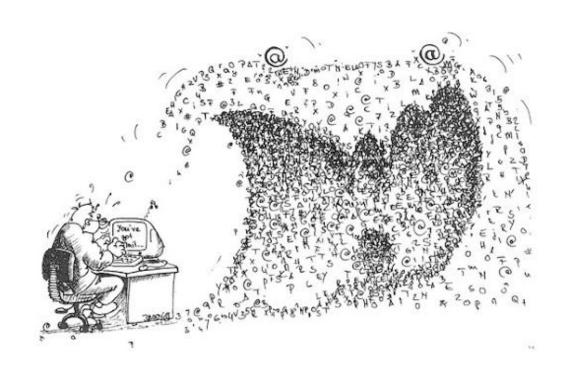
12.10.2021 – AG-Meeting





WHAT

Motivation



- Tens of thousands subjects are scanned for research purposes each year
- Lack of consensus leads to misunderstanding and time wasted on rearranging data or rewriting scripts that expect particular file formats and organization

What is BIDS?

BIDS is based on **simple file** formats and folder structures

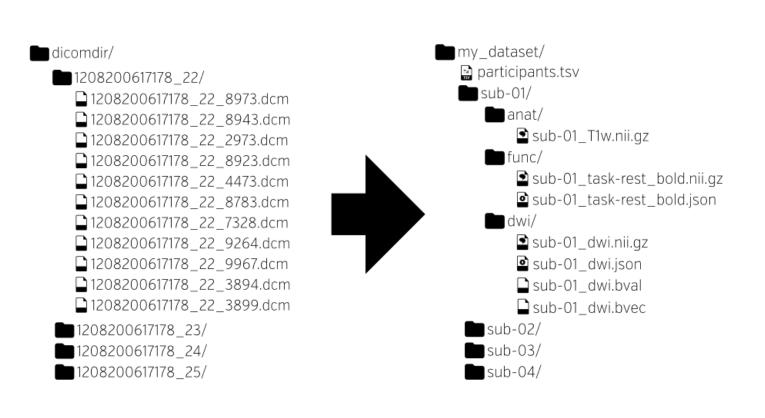
DATA STRUCTURE

- File formats to use (e.g. nifti, json, tsv) → [BIDS is NOT a file format]
- Naming convention for files and directories

METADATA

- Prevents metadata getting lost while doing your research
- Stored in json files, readable by both humans and machines
- Some metadata is better than no metadata

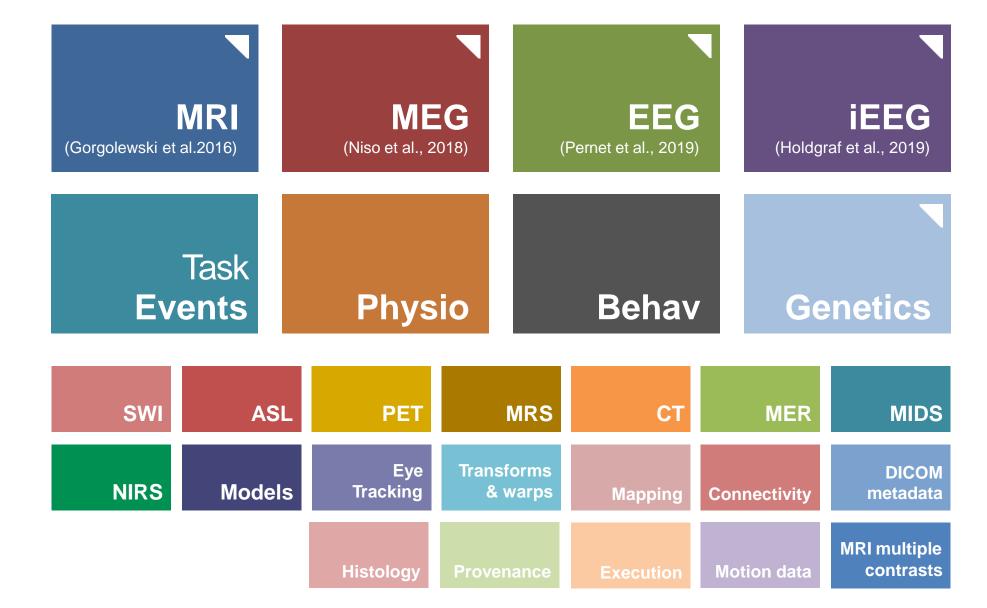
History

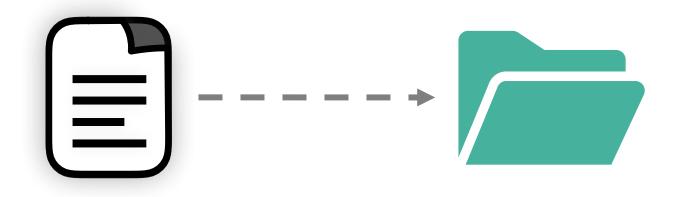


Adoption of a common standards to describe data and its organization **on disk**:

- Data remain accessible and usable by different researchers over time
- 2. Errors attributed to the misunderstanding of the meaning of a given datum
- 3. Standardized usage of data analysis software

BIDS universe





BIDS Specification

https://bids-specification.readthedocs.io

Example1/

Where do we want to go?

```
- README.tsv
- dataset_description.json
- participants.json
- - participants.tsv
L _ sub-001
  - ses-01
        L — motion/
              - sub-01_ses-01_task-BalanceTandemStand_tracksys-IMU1_motion.tsv
              - sub-01_ses-01_task-BalanceTandemStand_motion.json
              - sub-01_ses-01_task-BalanceTandemStand_channels.tsv
  L - sub-001_scans.tsv
```

Definitions

- Dataset A dataset consists of data acquired from one or more subjects, possibly from multiple sessions.
- Subject
- Session a logical grouping of neuroimaging and behavioral data consistent across subjects. Session can (but doesn't have to) be synonymous to a visit in a longitudinal study.
- Task a set of structured activities performed by the participant. Tasks are usually accompanied by stimuli and responses, and can greatly vary in complexity.
- Event something that happens or may be perceived by a test subject as happening at a particular instant during the recording. Events are most commonly associated with on- or offset of stimulus presentations, or with the distinct marker of on- or offset of a subject's response or motor action.
- Data type a functional group of different types of data. BIDS defines eight data types: func (task based and resting state functional MRI), dwi, anat (structural imaging such as T1, T2 and so on), meg (magnetoencephalography), eeg (electroencephalography), ieeg (intracranial electroencephalography), beh (behavioral), motion (time series of object positions, orientations, or their time derivatives).
- [...]

Common principles

Level of requirement:

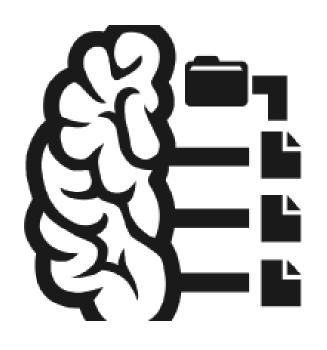
- 1. MUST
- 2. RECOMMENDED
- 3. OPTIONAL

Inheritance principile

• Any metadata file (such as .json or .tsv) may be defined at any directory level, but no more than one applicable file may be defined at a given level

Example1/

```
- - README.tsv
- dataset_description.json
- - participants.json
- participants.tsv
- task-BalanceTandemStand.json
L _ sub-001
  -- ses-01
  L — ses-02
- sub-002
   sub-003
```



Modality agnostic data

BIDS schema: example

Example1/

```
- README.tsv
- dataset_description.json
-- participants.json
- participants.tsv
  sub-001
  -- ses-01
  -- ses-02
  L- sub-001_scans.tsv
  sub-002
  sub-003
```

dataset_description.json

```
"Name": "The mother of all
experiments", "BIDSVersion":
"1.4.0",
"DatasetType":
"raw", "License":
"CC0".
"Authors": ["Paul Broca", "Carl Wernicke"],
"Acknowledgements": "Special thanks to KB for help in
formatting this dataset in BIDS",
"HowToAcknowledge": "Please cite this paper:
https://www.ncbi.nlm.nih.gov/pubmed/0928",
"Funding": [ "National Institute of Neuroscience Grant
F37823MFH1"], "EthicsApprovals": ["Human Research
Protections Office (Protocol AR0928"],
"ReferencesAndLinks": [
"https://www.ncbi.nlm.nih.gov/pubmed/ 0928", "Alzheimer et
al (2015). Nature, 21. doi.org/0928"], "DatasetDOI":
"10.0.2.3/dfjj.10"
```

BIDS schema: example

Example1/

```
- README.tsv
- dataset_description.json
- - participants.json
 - participants.tsv
L sub-001
     ses-01
  -- ses-02
  L- sub-001_scans.tsv
   sub-002
   sub-003
```

participants.json

```
"age": {
    "Description": "age of
    the participant",
    "Units": "years"     },

"sex": {
    "Description": "sex as
    reported by the participant",
    "Levels": {
        "M": "male",
        "F": "female"     }
}
```

participants.tsv

participant_id	age	sex
sub-001	34	M
sub-002	12	F
sub-003	33	F

BIDS schema: example

Example1/

```
-- README.tsv
- - dataset_description.json
-- participants.json
-- participants.tsv
L- sub-001
  -- ses-01
  -- ses-02
  L - sub-001_scans.tsv
   sub-002
   sub-003
```

sub-001_scans.tsv

filename	acq_time
ses-01/sub001-ses-01_task-TuG.csv	2019-06-15T13:45:30
ses-01/sub001-ses-01_task-DualTask.csv	2019-06-15T13:52:42
ses-02/sub001-ses-01_task-TuG.csv	2020-03-22T14:11:12



Motion specific data

Metadata | modality specific - motion

```
Example1/
L - sub-001/ses-01/
  - eeg/
  \lfloor - \text{motion} / \rfloor
       sub-001_ses-01_task-<label>[_tracksys-<label>]_motion.tsv
       sub-001_ses-01_task-<label>_motion.json
       sub-001_ses-01_task-<label>_channels.tsv
       sub-001_ses-01_task-<label>_coordsystem.json
       sub-001_ses-01_task-<label>_events.tsv
       sub-001_ses-01_task-<label>_events.json
```

Metadata | motion.json

MUST

TaskName, MotionTrackedPoints, StartTime, TrackingSystem, SamplingFrequency

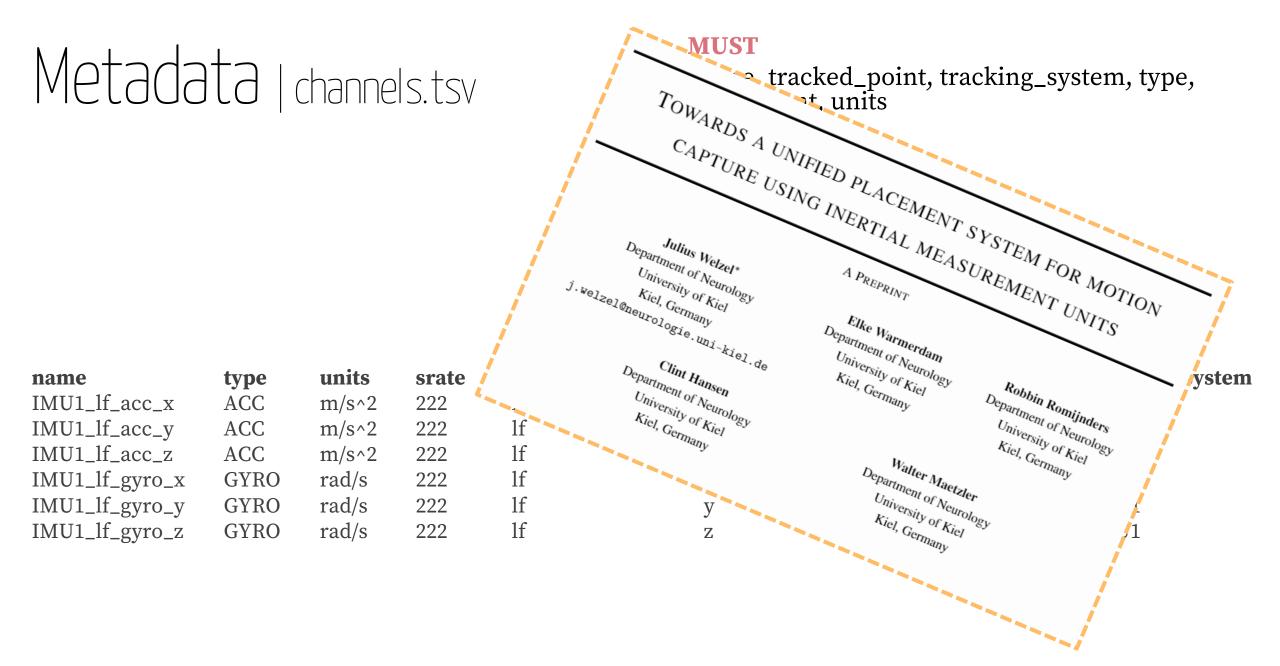
RECOMMENDED

TaskDescription, RecordingDuration, MotionChannelCount, <type>ChannelCount, SoftwareFilters, ...

OPTIONAL

Manufacuturer, RecordingSoftware, ...

```
TaskName: BIDS Motion fictive example,
TaskDescription: Running around,
StartTime: 2019-06-15T13:45:30,
Recording Duration: 4667.641106,
TrackingSystemCount: 1,
MotionTrackedPoints: 1,
MotionChannelCount: 6,
TrackingSystems:{
   IMU1: {
       Manufacturer: HasoMed,
       TrackedPointsCount: 1,
       SamplingFrequency: 120,
       SoftwareFilters:n/a,
       ACCChannelCount: 3,
       GYROChannelCount: 3,
```



Metadata | motion.tsv

- Headers correspond to channels.tsv <name>
- Raw values from recording

IMU1_lf_acc_x	IMU1_lf_acc_y	IMU1_lf_acc_z	IMU1_lf_gyro_x	IMU1_lf_gyro_y	IMU1_lf_gyro_z
0,26345511	0,092292015	0,008668652	0,930514317	0,690193606	0,809881135
0,694520294	0,191824943	0,843726573	0,397571025	0,88542996	0,895276224
0,076633595	0,258720111	0,547534792	0,282283781	0,27890791	0,232620594
0,577995093	0,045616941	0,04903375	0,940889749	0,153318421	0,668360752
0,054555716	0,791513927	0,587116733	0,466957774	0,975446368	0,048053341
0,966026984	0,196283834	0,711044406	0,338944328	0,719445195	0,438488392
0,98417512	0,507944361	0,1180168	0,796692478	0,175376468	0,488659533
0,98839607	0,155737146	0,800206213	0,633481382	0,752698206	0,852943441
0,557959342	0,095962723	0,802817734	0,749838438	0,847351997	0,2385044
0,199349532	0,183812353	0,657496925	0,891828079	0,363756585	0,059946057
0,96627098	0,727173308	0,520638452	0,759135101	0,351863205	0,813096032
•••	•••	•••	•••	•••	•••

Metadata | modality specific - motion

```
IMU1_lf_acc_x
                     IMU1_lf_acc_y
                                           IMU1_lf_acc_z
                                                                 IMU1_lf_gyro_x
                                                                                      IMU1_lf_gyro_y
                                                                                                            IMU1_lf_gyro_z
0,26345511
                     0,092292015
                                           0,008668652
                                                                                      0,690193606
                                                                                                            0,809881135
                                                                 0,930514317
0,694520294
                     0,191824943
                                           0,843726573
                                                                 0,397571025
                                                                                      0,88542996
                                                                                                            0,895276224
0.076633595
                     0.258720111
                                           0,547534792
                                                                 0.282283781
                                                                                      0,27890791
                                                                                                            0.232620594
                     0.045616941
                                                                 0,940889749
                                                                                      0.153318421
                                                                                                            0.668360752
0.577995093
                                           0.04903375
0,054555716
                     0,791513927
                                           0,587116733
                                                                 0,466957774
                                                                                      0,975446368
                                                                                                            0,048053341
0,966026984
                     0,196283834
                                           0,711044406
                                                                 0,338944328
                                                                                      0,719445195
                                                                                                            0,438488392
0,98417512
                     0,507944361
                                           0,1180168
                                                                 0,796692478
                                                                                      0,175376468
                                                                                                            0,488659533
0.98839607
                     0,155737146
                                           0,800206213
                                                                 0.633481382
                                                                                      0,752698206
                                                                                                            0.852943441
                     0,095962723
                                                                 0,749838438
                                                                                                            0,2385044
0,557959342
                                           0,802817734
                                                                                      0,847351997
0.199349532
                     0,183812353
                                           0,657496925
                                                                 0,891828079
                                                                                      0,363756585
                                                                                                            0.059946057
                     0,727173308
                                           0,520638452
                                                                                      0,351863205
                                                                                                            0,813096032
0,96627098
                                                                 0,759135101
```

```
"TaskName": "BIDS Motion fictive example",
"TaskDescription": "Running around",
"StartTime": "2019-06-15T13:45:30 ",
"RecordingDuration": 4667.641106,
"TrackingSystemCount": 1,
"MotionTrackedPoints": 1,
"MotionChannelCount": 6,
"TrackingSystems":{
       "IMU1": {
               "Manufacturer":
               "BWSensing",
               "TrackedPointsCount": 1,
               "SamplingFrequency": 120,
               "SoftwareFilters":"n/a",
               "ACCChannelCount": 3,
               "GYROChannelCount": 3,
```

```
sub-001_ses-01_task-<label>[_tracksys-<label>]_motion.tsv
sub-001_ses-01_task-<label>_motion.json
sub-001_ses-01_task-<label>_channels.tsv
sub-001_ses-01_task-<label>_coordsystem.json
sub-001_ses-01_task-<label>_events.tsv
sub-001_ses-01_task-<label>_events.json
```

```
tracked_point
                                                                                                                                               tracking_system
                                                                                                      component
                    ACC
                                                                                                                           left_foot
IMU1_lf_acc_x
                                         m/s^2
                                                             222
                                                                                                                                               IMU1
IMU1_lf_acc_y
                    ACC
                                         m/s^2
                                                             222
                                                                                                                           left_foot
                                                                                                                                               IMU1
IMU1 lf acc z
                    ACC
                                         m/s^2
                                                             222
                                                                                                                           left foot
                                                                                                                                               IMU1
IMU1_lf_gvro_x
                    GYRO
                                                             222
                                                                                                                           left_foot
                                                                                                                                               IMU1
                                         rad/s
                                                             222
IMU1_lf_gyro_y
                    GYRO
                                         rad/s
                                                                                                                           left_foot
                                                                                                                                               IMU1
                                                                                  1f
IMU1_lf_gyro_z
                    GYRO
                                         rad/s
                                                             222
                                                                                                                           left_foot
                                                                                                                                               IMU1
```

Conclusions





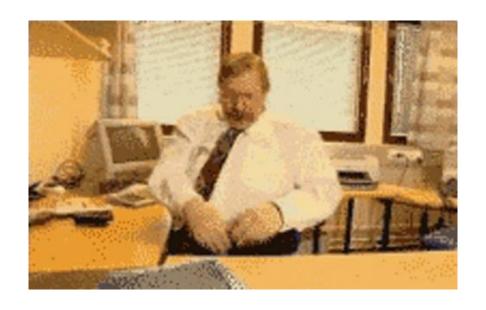


Conclusions

Example1/

sub-COKI10003

```
- - README.tsv
- dataset_description.json
- - participants.json
                             REDCap
- participants.tsv
L — sub-COKI10001
  - ses-T1
        L — motion/
              - sub-01_ses-01_task-BalanceTandemStand_tracksys-HasoMedImu_motion.tsv
              \vdash - sub-01_ses-01_task-BalanceSideBySide_tracksys-HasoMedImu_motion.tsv
              - sub-01_ses-01_motion.json
                                           - sub-01_ses-01_channels.tsv
    - ses-T2
   L - sub-COKI10001_scans.tsv
   sub-COKI10002
```



Thank you for listening carefully ©

Thanks to Clint, Elke, Robbin Special thanks to Sein Jeung (Berlin)

File naming structure

- A file name consists of a chain of *entities*, or key-value pairs, a *suffix* and an *extension*. Two prominent examples of entities are **subject** and **session**.
- For a data file that was collected in a given session from a given subject, the file name MUST begin with the string sub-<label>_ses-<label>

```
e.g.ComOn:
```

-> sub-COKI10152_ses-T1_task-BalanceTandemStand.csv