

OpenNodal User Manual

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Revision Log

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Acronyms

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1. Input Format

1.1 Main Input File

OpenNodal's input is separated into blocks describing aspects of the problem. Each block may be given a number of cards describing specific details about the problem parameters. OpenNodal currently features the following three blocks:

<u>Block Name</u>	<u>Available Cards</u>
[CASE_DETAILS]	title, nsplit, k_eps, phi_eps, max_its, nodal_method, and wielandt
[CORE]	dim, size, apitch, sym, assm_map, bc, refl_mat, and buckling
[MATERIAL]	xs_file and xs_map

1.1.1 [CASE_DETAILS] Block

The [CASE_DETAILS] block describes details for the problem case, including run specifications such as convergence criteria and solution method. The following table describes the available input cards:

<u>Card Name</u>	<u>Description</u>	<u>Options</u>	<u>Required?</u>
title	Problem Title.	String of size ≤ 100	No. Default: blank
nsplit	Spatial Refinement for nodes. Splits each assembly in the specified geometry into $\text{nsplit} \times \text{nsplit}$ nodes.	$\mathbb{Z} \geq 1$	No. Default: 1
k_eps	Eigenvalue convergence criteria.	$\mathbb{R} > 0$	No. Default: 1.0E-6
phi_eps	Flux convergence criteria.	$\mathbb{R} > 0$	No. Default: 1.0E-5
max_its	Maximum number of outer iterations.	$\mathbb{Z} \geq 1$	No. Default: 100
nodal_method	Nodal method to be employed. Either Finite Difference or polynomial NEM	fd, poly	No. Default: fd
wielandt	Wielandt shift $\delta\lambda$ value. A value of 0 will leave it turned off.	$\mathbb{R} > 0$	No. Default: off (0)

1.1.2 [CORE] Block

The [CORE] block describes the geometry of the core itself, including auxiliary geometric information such as axial buckling, symmetry, boundary conditions, etc. The following table describes the available input cards:

Card Name	Description	Options	Required?
dim	Dimensionality of problem. 1D, 2D, 3D. Currently ONLY 2D is supported.	1D, 2D, 3D	No. Default: 2D
size	Size of the core across. Cores are assumed to be square.	$\mathbb{Z} \geq 1$	No. Default: 1
apitch	Assembly pitch in cm. All assemblies are assigned assumed square and given equal widths. Non-square assemblies may be constructed using multiple assemblies.	$\mathbb{R} > 0$	No. Default: 1.0E0
sym	Problem symmetry. For half (half) symmetry it is assumed the left side is reflective, and for quarter (qtr) symmetry it is assumed that the left and top sides are reflective.	full, half, qtr	No. Default: full
assm_map	Assembly map matrix. Matrix starts on the next line. Will have number of rows and columns equal to size unless symmetry is used. For half symmetry the number of columns will be $\lceil \text{size}/2 \rceil$. For qtr symmetry the number of columns AND rows will be $\lceil \text{size}/2 \rceil$. Any gaps will be filled with refl_mat , so if gaps are left for ragged core specification, then refl_mat MUST be specified in this case.	Map of \mathbb{Z} assembly IDs	Yes.
bc	Boundary conditions to be applied. These are not applied to the reflective sides for a problem with non-full symmetry. For albedo , \mathbb{R} albedo values must also be given on the same line for each energy group. For reflector , the refl_mat will be added as a single assembly buffer as well as self-scatter diffusion length boundary, so refl_mat MUST be specified in this case.	vacuum, reflective, reflector, zero, albedo	No. Default: vacuum
refl_mat	Reflector material index to be used in either reflector boundary conditions and/or to fill in gaps for a ragged core.	$\mathbb{Z} \geq 1$	No. Default: no reflector material
buckling	Axial geometric buckling. If height is given, then it should be immediately followed by a positive real height on the same line and the axial buckling will be computed from that height.	\mathbb{R} , height \mathbb{R}	No. Default: 0.0E0

1.1.3 [MATERIAL] Block

The [MATERIAL] block describes cross sections for each assembly. The following table describes the available input cards:

- `fission_spectrum_g` = Fraction of neutrons born in fission that appear in energy group g (χ).
- `nuSigma_f_g` = Fission production cross section in group g ($\nu\Sigma_f$ NOT Σ_f).
- `nu_bar_g` = Average number of neutrons released by fission caused by a neutron in energy group g (ν).
- `Sigma_a_g` = Absorption cross section in energy group g (Σ_a).
- `sig_scat_{g'->g}` = Scattering cross section from group g' to g ($\Sigma_{s,g'\rightarrow g}$).

2. Output Format

If the input filename is of the form of one of the following `<file>.in`, `<file>.inp`, `<file>.input` then the output filenames will take on the form be `<file>_<type>.<ext>`. If the input file has any other extension, then the entire filename will simply be considered `<file>` and similarly use the convention `<file>_<type>.<ext>` for each of the output files.

2.1 Output Summary File

OpenNodal generates a summary output file for the run results. The naming convention for this summary file is `<file>_results.out`. This file contains the final eigenvalue on the first line, followed by the final flux core averaged ratio of ϕ_2/ϕ_1 iff the problem was a 2 group problem. The summary file will then have `G` blocks giving the assembly averaged flux for each energy group mapped in a manner matching `assm_map`.

2.2 Log File

OpenNodal generates a log file echoing all output which is also printed to the screen, including any warnings or errors. The naming convention for this summary file is `<file>.log`.

2.3 Flux Output Files

OpenNodal generates `G` flux output files as well as a fission power output file. The naming convention for these files is `<file>_flux_g<g>.csv` and `<file>_power.csv`. The data is listed in the following format:

```
x_centroid_node_row_1 y_centroid_node_col_1 flux_{g,1,1}
x_centroid_node_row_1 y_centroid_node_col_2 flux_{g,1,2}
x_centroid_node_row_1 y_centroid_node_col_3 flux_{g,1,3}
      :
x_centroid_node_row_1 y_centroid_node_col_Ny flux_{g,1,Ny}

x_centroid_node_row_2 y_centroid_node_col_1 flux_{g,2,1}
x_centroid_node_row_2 y_centroid_node_col_2 flux_{g,2,2}
      :
```

So that it is a map for the node averaged flux of each group onto the centroid of the node to which it belongs. Notice that each change in rows is separated by a blank line. The power output is similar, except that the

flux is replaced by node averaged power. Note that since OpenNodal solves an eigenvalue problem, values should not be considered absolute but relative to each other.

2.4 Flux Output Plots

If the user has `gnuplot` installed, then OpenNodal will generate plots of the groupwise flux, as well as the fission power. The naming convention for these files is `<file>_flux_g<g>.png` and `<file>_power.png`. The files themselves are 2D heat-maps for the magnitude of the relative flux/power in each node across the whole core. Example for the `2d_ss_iaea-BSS11.inp` case with `nsplit 64`:

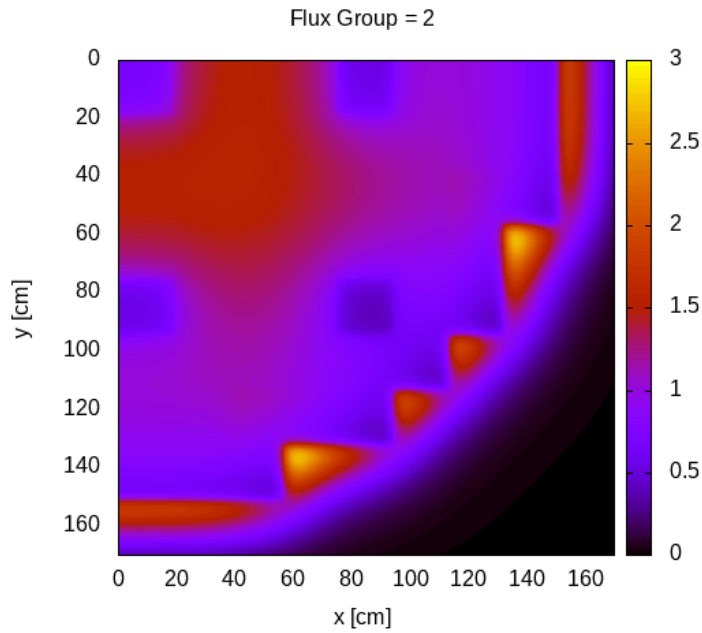


Figure 2.1: Thermal Flux for the BSS-11 Problem

Bibliography