

AUTOMORPHISMS AND DEFORMATIONS OF CONFORMALLY KÄHLER, EINSTEIN–MAXWELL METRICS

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ABSTRACT. We obtain a structure theorem for the group of holomorphic automorphisms of a conformally Kähler, Einstein–Maxwell metric, extending the classical results of Matsushima [25], Licherowicz [20] and Calabi [6] in the Kähler–Einstein, cscK, and extremal Kähler cases. Combined with previous results of LeBrun [19], Apostolov–Maschler [4] and Futaki–Ono [12], this completes the classification of the conformally Kähler, Einstein–Maxwell metrics on $\mathbb{CP}^1 \times \mathbb{CP}^1$. We also use our result in order to introduce a (relative) Mabuchi energy in the more general context of (K, q, a) -extremal Kähler metrics in a given Kähler class, and show that the existence of (K, q, a) -extremal Kähler metrics is stable under small deformation of the Kähler class, the Killing vector field K and the normalization constant a .

1. INTRODUCTION

Let (M, J) be a compact Kähler manifold of complex dimension m and g a J -compatible Kähler metric. Following [4], the Hermitian metric $\tilde{g} = \frac{1}{f^2}g$ is said to be *conformally Kähler, Einstein–Maxwell* if \tilde{g} has

- (a) J -invariant Ricci tensor, i.e.
- (1) $\text{Ric}_{\tilde{g}}(\cdot, \cdot) = \text{Ric}_{\tilde{g}}(J\cdot, J\cdot),$
- (b) constant scalar curvature, i.e.
- (2) $\text{Scal}_{\tilde{g}} = \text{const.}$

These conditions extend to higher dimensions a 4-dimensional riemannian signature analogue of the Einstein–Maxwell equations in General Relativity, see [18, 1].

In [4], Apostolov–Maschler initiated a study of conformally Kähler, Einstein–Maxwell Kähler metrics in a framework similar to the famous Calabi problem [6] of finding extremal Kähler metrics in a given Kähler class, and set the existence problem of the conformally Kähler, Einstein–Maxwell Kähler metrics in a formal GIT picture, extending the work of Donaldson and Fujiki [7, 8] characterizing the Calabi extremal metrics as critical points of the norm of the corresponding moment map. In particular, fixing a Kähler class Ω on (M, J) , a quasi-periodic real holomorphic vector field K with zeroes, and a real positive constant $a > 0$, it was shown in [4] that there is a natural obstruction to the existence of conformally Kähler, Einstein–Maxwell Kähler metrics associated to the above data, similar to the Futaki invariant [10, 11] in the Kähler–Einstein and the constant scalar curvature Kähler (cscK) cases. More recently, Futaki–Ono [12] have characterized the latter obstruction in terms of a *volume-minimizing* condition on K , reminiscent to the constant scalar curvature Sasaki case [24, 14, 22].

The purpose of this paper is to extend two fundamental results in the theory of extremal Kähler metrics to a more general context relevant the conformally Kähler, Einstein–Maxwell metrics described above. The first result is a suitable extension of Calabi’s Theorem [6] on the structure of the group of holomorphic automorphisms of a compact extremal Kähler manifold. To state it, let g be a Kähler metric on (M, J) endowed with a Killing vector field K with zeroes. Hodge theory implies (see e.g. [16]) that K is hamiltonian with respect to the Kähler form $\omega = gJ$, i.e. $\iota_K \omega = -df$ for a smooth function on M , called a *Killing potential*

of K . We normalize $f = f_{(K,\omega,a)}$ by requiring $\int_M f_{(K,\omega,a)} dv_g = a > 0$, where the positive real constant a is such that $f_{(K,\omega,a)} > 0$ on M . Then, for any fixed real number q we define the (K, q, a) -scalar curvature of g to be

$$(3) \quad S_{(K,q,a)}(g) := f_{(K,\omega,a)}^2 \text{Scal}_g + 2q f_{(K,\omega,a)} \Delta_g (f_{(K,\omega,a)}) - q(q-1)|K|_g^2,$$

where Scal_g denotes the usual scalar curvature, $|\cdot|_g$ is the tensor norm induced by g , and Δ_g stands for the riemannian Laplacian on functions.

The point of this definition is that the condition (1) above yields that the conformal factor f is a positive Killing potential of a Killing vector field K for g , whereas the scalar curvature $\text{Scal}_{\tilde{g}}$ of $\tilde{g} = \frac{1}{f^2}g$ is given by the formula (3) with $q = -(2m-1)$. Other choices of the *weight* q lead to other interesting geometric problems, as it was observed in [2]. We also notice that the GIT framework of [4] makes sense for any choice of the weight q as above, see Section 2 below.

Definition 1. Let g be a Kähler metric on (M, J) endowed with a Killing vector field K as above, and $a > 0$ a real constant such the corresponding Killing potential $f_{(K,\omega,a)} > 0$ on M . We say that g is (K, q, a) -extremal if its (K, q, a) -scalar curvature given by (3) is a Killing potential, i.e. $\Xi = J \text{grad}_g(\text{Scal}_{(K,q,a)}(g))$ is a Killing vector field for g .

The definition above incorporates the case when $S_{(K,q,a)}(g)$ is constant, which in turn links to the initial motivation of studying conformally Kähler, Einstein–Maxwell metrics. We denote by \mathfrak{h}^K (resp. \mathfrak{k}^K) the centralizer of K in the Lie algebra of holomorphic vector fields (resp. Killing vector fields) of (M, J) (resp. (M, g)) and $\text{Aut}_0^K(M, J)$ (resp. $\text{Isom}_0^K(M, g)$) the corresponding closed connected Lie groups. We then have:

Theorem 1. *Suppose (M, g, J) is a compact (K, q, a) -extremal Kähler manifold. Then the group $\text{Isom}_0^K(M, g)$ is a maximal compact connected subgroup of $\text{Aut}_0^K(M, J)$. Furthermore, if $S_{(K,q,a)}(g) = \text{const}$, then $\text{Aut}_0^K(M, J)$ is a reductive complex Lie group.*

This basic result yields that each compact (K, q, a) -extremal Kähler manifold (M, J, g) is invariant under a *maximal* torus \mathbb{T} in the connected component of the identity of the reduced automorphism group $\text{Aut}_{\text{red}}(M, J)$, with $K \in \text{Lie}(\mathbb{T})$, thus linking to the point of view of [4]. In particular, we can deduce from Theorem 1 and [4, Theorem 3] that if (M, J) is toric, i.e. \mathbb{T} is m -dimensional, then the (K, q, a) -extremal Kähler metrics are unique up to isometries in their Kähler classes (see Corollary 4 below). Concerning the existence of conformally Kähler, Einstein–Maxwell metrics, Theorem 1 and [4, Theorem 5] yield together a complete classification of the latter on the toric complex surfaces $\mathbb{CP}^1 \times \mathbb{CP}^1$ and the Hirzebruch surfaces $\mathbb{F}_n = \mathbb{P}(\mathcal{O} \oplus \mathcal{O}(n)) \rightarrow \mathbb{CP}^1$ in terms of *explicit* constructions given by either the Calabi Ansatz [18, 19, 17] or by the hyperbolic ambitoric ansatz [1] (a riemannian analogue of the Plebanski–Damianski explicit solutions [26]). In practice, however, the algorithm of [4, Theorem 5] allowing one to decide whether or not for a given Kähler class, a quasi-periodic holomorphic vector field K and a constant $a > 0$ there exists a compatible conformally-Kähler, Einstein–Maxwell metric is of considerable complexity, see [12]. The case $\mathbb{CP}^1 \times \mathbb{CP}^1$ has been successfully resolved by [18, 4] (see also [12]):

Corollary 1. *Any conformally-Kähler, Einstein–Maxwell metric on $\mathbb{CP}^1 \times \mathbb{CP}^1$, must be toric, and if it is not a product of Fubini-Study metrics on each factor, it must be homothetically isometric to one of the metrics constructed in [18].*

We also notice that similarly to the Kähler–Einstein and cscK cases [25, 20], Theorem 1 places an obstruction in terms of $\text{Aut}_0^K(M, J)$ for (M, J) to admit a Kähler metric of constant (K, q, a) -scalar curvature, in particular a conformally Kähler, Einstein–Maxwell metric.

Corollary 2. *Let $(M, J) = \mathbb{P}(\mathcal{O} \oplus \mathcal{O}(1)_E) \rightarrow \mathbb{F}_n$ where $E = (\mathcal{O} \oplus \mathcal{O}(n)) \rightarrow \mathbb{CP}^1$ and $\mathbb{F}_n = \mathbb{P}(E)$ is the n -th Hirzebruch complex surface. Denote by K the generator of the S^1 -action on M , corresponding to diagonal multiplications on the $\mathcal{O}_E(1)$ -factor. Then (M, J) admits no Kähler metric of constant (bK, q, a) -scalar curvature for any values of b and q .*

We now describe our second result, which is a suitable modification of the stability of the existence of extremal Kähler metrics under deformation of the Kähler class, proved by LeBrun–Simanca in [21], see also [9]. In our extended context, and without loss of generality by using Theorem 1 above, we fix a maximal real torus $\mathbb{T} \subset \text{Aut}_{\text{red}}(M, J)$, a real weight q , and study the existence of a \mathbb{T} -invariant (K, q, a) -extremal Kähler metric as a function of the Kähler class $\Omega \in H_{\text{dR}}^2(M, \mathbb{R})$, the vector field $K \in \text{Lie}(\mathbb{T})$, and the real constant $a > 0$. We prove the following:

Theorem 2. *Suppose (without loss of generality by Theorem 1) that $\mathbb{T} \subset \text{Aut}_{\text{red}}(M, J)$ is a maximal real torus and (M, J) admits a \mathbb{T} -invariant (K, q, a) -extremal Kähler metric (g, ω) . Then, for any g -harmonic, \mathbb{T} -invariant, $(1, 1)$ -form α , and any $H \in \text{Lie}(\mathbb{T})$, there exist $\varepsilon > 0$, such that for any real numbers $|s| < \varepsilon$, $|t| < \varepsilon$ and $|u| < \varepsilon$, there exists a $(K + uH, q, a + s)$ -extremal Kähler metric in the Kähler class $[\omega + t\alpha]$.*

This result provides an efficient way to obtain many new examples from known ones.

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2. A FAMILY OF VARIATIONAL PROBLEMS IN KÄHLER GEOMETRY

In this section we recall the Apostolov–Maschler [4] moment map interpretation of the (K, q, a) -scalar curvature. In [4], the case $q = -2m + 1$ is considered, but their argument works for any weight q (see [2]).

Let (M, J, ω) be a compact Kähler manifold of real dimension $2m \geq 4$. We denote by $\mathfrak{h}_{\text{red}}$ the Lie algebra of the reduced automorphism group $\text{Aut}_{\text{red}}(M, J)$, given by the real holomorphic vector field with zeros (see [16]). Let $K \in \mathfrak{h}_{\text{red}}$ be a quasi-periodic Killing vector field generating a torus $G \subset \text{Aut}_{\text{red}}(M, J)$. It is well known that G acts in a isometric hamiltonian way on (M, ω) . Let $f_{(K, \omega, a)} \in C^\infty(M, \mathbb{R})$ be the normalized positive Killing potential of K , defined by the condition $\int_M f_{(K, \omega, a)} v_\omega = a$.

We denote by $\mathcal{K}^G(M, \omega)$ the space of all ω -compatible, G -invariant Kähler structures on (M, ω) , and consider the natural action of the infinite dimensional group $\text{Ham}^G(M, \omega)$, of G -equivariant Hamiltonian transformations of (M, ω) . We have the identification

$$\text{Lie}(\text{Ham}^G(M, \omega)) \cong C_0^\infty(M, \mathbb{R})^G$$

where $C_0^\infty(M, \mathbb{R})^G$ denote the space of smooth G -invariant functions with zero mean value with respect to $f_{(K, \omega, a)}^{q-2} v_\omega$, ($v_\omega = \frac{\omega^m}{m!}$ being the Riemannian volume form) endowed with the Poisson bracket.

For any $q \in \mathbb{R}$, the space $\mathcal{K}^G(M, \omega)$ carries a q -weighted formal Kähler structure $(\mathbf{J}, \Omega^{(K, q, a)})$ given by ([7, 8, 4])

$$\begin{aligned} \Omega_J^{(K, q, a)}(j_1, j_2) &= \frac{1}{2} \int_M \text{Tr}(J j_1 j_2) f_{(K, \omega, a)}^q v_\omega, \\ \mathbf{J}_J(j) &= J j, \end{aligned}$$

where the tangent space of $\mathcal{K}^G(M, \omega)$ at J is identified with the space of smooth G -invariant sections \dot{J} of $\text{End}(TM)$ satisfying

$$\dot{J}J + J\dot{J} = 0, \quad \omega(\dot{J}, \cdot) + \omega(\cdot, \dot{J}) = 0.$$

In what follows we denote by $g_J := \omega(\cdot, J)$ the Kähler metric corresponding to $J \in \mathcal{K}^G(M, \omega)$, and index all objects calculated with respect to J similarly. On $C_0^\infty(M, \mathbb{R})^G$, we consider the scalar product given by,

$$\langle \phi, \psi \rangle_{(K, q, a)} = \int_M \phi \psi f_{(K, \omega, a)}^{q-2} v_\omega.$$

Theorem 3. [4] *The action of $\text{Ham}^G(M, \omega)$ on $(\mathcal{K}^G(M, \omega), \mathbf{J}, \Omega^{(K, q, a)})$ is Hamiltonian with a momentum map given by the $\langle \cdot, \cdot \rangle_{(K, q, a)}$ -dual of the (K, q, a) -scalar curvature given by (3).*

Remark 1.

- (i) The weight $q = -2m + 1$ corresponds to the conformally Kähler, Einstein–Maxwell case studied in [4], and $S_{(K, q, a)}$ computes the scalar curvature of the hermitian metric $\tilde{g}_J := f_{(K, \omega, a)}^{-2} g_J$.
- (ii) If $q = 0$, $S_{(K, q, a)}(J)$ computes the so-called *conformal scalar curvature* $\tilde{\kappa}_J$ of the hermitian metric \tilde{g}_J given by (see e.g. [15]),

$$\tilde{\kappa}_J = (2m - 1) \left\langle \tilde{W} \left(\tilde{F}_J \right), \tilde{F}_J \right\rangle_{\tilde{g}_J},$$

where $\tilde{F}_J = \tilde{g}_J(J, \cdot)$ is its fundamental 2-form of (\tilde{g}_J, J) and \tilde{W} is the corresponding Weil tensor.

- (iii) The weight $q = -m - 1$ appears in the study of Levi–Kähler quotients (see e.g. [2]).
- (iv) For a real number p , one can define,

$$S_{(K, p, q, a)}(J) := f_{(K, \omega, a)}^{p-2} S_{(K, q, a)}(g_J). \quad (4)$$

Then the $\langle \cdot, \cdot \rangle_{(K, q-p+2, a)}$ -dual of (4) is a momentum map for the action of $\text{Ham}^G(M, \omega)$ on $(\mathcal{K}^G(M, \omega), \mathbf{J}, \Omega^{(K, q, a)})$. Taking $(p, q) = (2, q)$ we obtain Theorem 3, wheres the value $(p, q) = (\frac{2}{m}, -1)$ corresponds to the Lejmi–Upmeyer moment map given by the *hermitian scalar curvature* of \tilde{g}_J (see [23]).

3. THE EXTENDED CALABI PROBLEM

3.1. The (K, q, a) -constant scalar curvature Kähler metrics. Following [4] we now fix the complex manifold (M, J) and vary the Kähler form ω within a fixed Kähler class $\Omega \in H^2(M, \mathbb{R}) \cap H^{1,1}(M, \mathbb{C})$. We also fix the compact torus $G \subset \text{Aut}_{\text{red}}(M, J)$ generated by a quasi periodic vector field $K \in \text{Lie}(G)$, and denote by $\mathcal{K}_\Omega^G(M, J)$ the space of G -invariant Kähler forms $\omega \in \Omega$. Let $f_{(K, \omega, a)}$ be the normalized Killing potential of K with respect to ω , with normalization constant $a > 0$, such that $f_{(K, \omega, a)} > 0$. As shown in [4, Lemma 1] we have $f_{(K, \omega', a)} > 0$ on M for all $\omega' \in \mathcal{K}_\Omega^G(M, J)$.

The space $\mathcal{K}_\Omega^G(M, J)$ is a Frechet manifold given near $\omega \in \mathcal{K}_\Omega^G(M, J)$ by the open subset of elements $\phi \in C^\infty(M, \mathbb{R})^G / \mathbb{R}$ such that $\omega + dd^c \phi > 0$ is positive definite. The tangent space of $\mathcal{K}_\Omega^G(M, J)$ at ω is identified with $C_0^\infty(M, \mathbb{R})^G$, the space of G -invariant smooth functions with mean value 0 with respect to $f_{(K, \omega, a)}^{q-2} v_\omega$.

We then consider the following generalized Calabi problem on $\mathcal{K}_\Omega^G(M, J)$ (see [4]):

Problem. For a weight $q \in \mathbb{R}$, a quasi-periodic vector field K generating a torus G in $\text{Aut}_{\text{red}}(M, J)$, $\omega \in \mathcal{K}_\Omega^G(M, J)$ and $a > 0$ such that $f_{(K, \omega, a)} > 0$, does there exist $\phi \in C_0^\infty(M, \mathbb{R})^G$ such that $\omega + dd^c \phi$ is (K, q, a) -extremal?

In what follows we calculate the first variation of the (K, q, a) -scalar curvature along $\omega \in \mathcal{K}_\Omega^G(M, J)$. We denote by D the Levi-Civita connection and by $\delta = D^*$ the co-differential of (M, ω, g) . For a 1-form α on M , let $D^\pm \alpha$ be the J -invariant (resp. J -anti-invariant) part of $D\alpha$, i.e.

$$(D^\pm \alpha)_{X,Y} = \frac{1}{2} \left((D\alpha)_{JX,JY} \pm (D\alpha)_{X,Y} \right).$$

There is a natural action on p -forms ψ induced by J as follows,

$$(J\psi)(X_1, \dots, X_p) = (-1)^p \psi(JX_1, \dots, JX_p).$$

The twisted differential and the twisted codifferential on p -forms are defined by,

$$\begin{aligned} d^c &= JdJ^{-1}, \\ \delta^c &= J\delta J^{-1}. \end{aligned}$$

To simplify notation we omit below the index (K, ω, a) of $f_{(K, \omega, a)}$,

Lemma 1. *For any G -invariant 1-form α we have*

$$\begin{aligned} (5) \quad 2f^{2-q}\delta\delta(f^q D^- \alpha) &= 2f^2\delta\delta(D^- \alpha) - 2qf(\Delta\alpha, df) \\ &\quad + 2qf(\Delta df, \alpha) + 2qf(\delta d\alpha, df) \\ &\quad - q(q-1)(\alpha, d(df, df)) + q(q-1)(df, d(\alpha, df)), \end{aligned}$$

where (\cdot, \cdot) stand for the inner product of tensors induced by g .

Proof. Indeed,

$$\begin{aligned} 2f^{2-q}\delta\delta(f^q D^- \alpha) &= 2f^2\delta\delta(D^- \alpha) + 2qf(\delta D^- \alpha)(JK) \\ &\quad + 2qf\delta((D^- \alpha)(JK, \cdot)) - 2q(q-1)(D^- \alpha)(K, K). \end{aligned}$$

We consider the decomposition of the tensor $D^- \alpha$ in symmetric and skew-symmetric parts Ψ and Φ , respectively,

$$D^- \alpha = \Psi + \Phi.$$

For any vector field X on M we have

$$\begin{aligned} (6) \quad \delta(\Psi(X, \cdot)) &= -(\Psi, DX^b) + (\delta\Psi)(X), \\ \delta(\Phi(X, \cdot)) &= (\Phi, DX^b) - (\delta\Phi)(X). \end{aligned}$$

Using (6) for $X = JK$ we get

$$\begin{aligned} \delta(\Psi(JK, \cdot)) &= (\delta\Psi)(JK), \\ \delta(\Phi(JK, \cdot)) &= -(\delta\Phi)(JK). \end{aligned}$$

Thus,

$$(7) \quad 2f^{2-q}\delta\delta(f^q D^- \alpha) = 2f^2\delta\delta(D^- \alpha) + 4\nu f(\delta\Psi)(JK) - 2q(q-1)(D^- \alpha)(K, K).$$

Using [16, Lemma 1.23.4] and $2\Phi = d\alpha - Jd\alpha$ we have

$$\begin{aligned} (8) \quad (\delta\Psi)(JK) &= -(\delta D^- \alpha, df) + (\delta\Phi)(df^\sharp) \\ &= -\frac{1}{2}(\Delta\alpha, df) + \text{Ric}(\text{grad}_g f, \alpha^\sharp) + \frac{1}{2}(\delta d\alpha, df) - \frac{1}{2}(\delta Jd\alpha, df) \\ &= -\frac{1}{2}(\Delta\alpha, df) + (\Delta df, \alpha) - (\delta D^+ df, \alpha) + \frac{1}{2}(\delta d\alpha, df) \\ &= -\frac{1}{2}(\Delta\alpha, df) + \frac{1}{2}(\Delta df, \alpha) + \frac{1}{2}(\delta d\alpha, df) \end{aligned}$$

where we have used the identity $(\delta J d\alpha, df) = -(\delta^c d\alpha)(K) = \mathcal{L}_K \delta^c \alpha = 0$ which holds since K is Killing. Furthermore,

$$\begin{aligned}
 2(D^-\alpha)(K, K) &= (D_K \alpha)(K) - (D_{JK} \alpha)(JK) \\
 &= -(df, d(\alpha, df)) + (d^c f, d(\alpha, d^c f)) - 2\alpha(D_K K) \\
 (9) \quad &= -(df, d(\alpha, df)) + (d^c f, d(\alpha, d^c f)) + (\alpha, d(df, df)) \\
 &= -(df, d(\alpha, df)) + (\alpha, d(df, df)),
 \end{aligned}$$

since $(d^c f, d(\alpha, d^c f)) = \mathcal{L}_K(\alpha, d^c f) = 0$ by the G -invariance of α . The result follows by substituting (8) and (9) in (7). This completes the proof. \square

Definition 2. We define the (K, q, a) -Lichnerowicz operator

$$\mathbb{L}_{(K, q, a)}^g : C^\infty(M, \mathbb{R})^G \rightarrow C^\infty(M, \mathbb{R})^G,$$

with respect to a metric g in $\mathcal{K}_\Omega^G(M, J)$ by

$$\mathbb{L}_{(K, q, a)}^g(\phi) = f_{(K, \omega, a)}^{2-q} \delta \delta \left(f_{(K, \omega, a)}^q D^-(d\phi) \right),$$

for $\phi \in C^\infty(M, \mathbb{R})^G$.

Proposition 1. For any variation $\dot{\omega} = dd^c \dot{\phi}$ of ω in $\mathcal{K}_\Omega^G(M, J)$, the first variation of the (K, q, a) -scalar curvature is given by

$$(10) \quad \delta S_{(K, q, a)}(\dot{\phi}) = -2\mathbb{L}_{(K, q, a)}^g(\dot{\phi}) + \left(dS_{(K, q, a)}(\omega), d\dot{\phi} \right).$$

Proof. For a variation $\dot{\omega} = dd^c \dot{\phi}$ in $\mathcal{K}_\Omega^G(M, J)$, the corresponding variations of $f_{(K, \omega, a)}$, Δ_ω , Scal_ω are given by (see e.g. [16, 5]):

$$\begin{aligned}
 \dot{v}_\omega &= -(\Delta_\omega \dot{\phi}) v_\omega \\
 \dot{f} &= (df, d\dot{\phi}) \\
 (11) \quad \dot{\Delta}_\omega &= (dd^c \dot{\phi}, dd^c \cdot) \\
 \dot{\text{Scal}}_\omega &= -2\mathbb{L}^g(\dot{\phi}) + (d\text{Scal}(\omega), d\dot{\phi}),
 \end{aligned}$$

where $\mathbb{L}^g(\dot{\phi}) = \delta \delta (D^- d\dot{\phi})$ is the usual Lichnerowicz operator. Then the first variation of the (K, q, a) -scalar curvature is given by:

$$\begin{aligned}
 \delta S_{(K, q, a)}(\dot{\phi}) &= -2f^2 \mathbb{L}^g(\dot{\phi}) + f^2 (d\text{Scal}(\omega), d\dot{\phi}) + \text{Scal}(\omega) (df^2, d\dot{\phi}) + 2qf \Delta_\omega (df, d\dot{\phi}) \\
 &\quad + 2q(df, d\dot{\phi}) \Delta_\omega f + 2qf (dd^c f, dd^c \dot{\phi}) - q(q-1)(df, d(df, d\dot{\phi})).
 \end{aligned}$$

By (6) and the G -invariance of ϕ we have

$$(dd^c \dot{\phi}, dd^c f) = -\Delta(df, d\dot{\phi}) + (d\Delta \dot{\phi}, df).$$

Thus,

$$\begin{aligned}
 \delta S_{(K, q, a)}(\dot{\phi}) &= -2f^2 \mathbb{L}^g(\dot{\phi}) + f^2 (d\text{Scal}(\omega), d\dot{\phi}) \\
 (12) \quad &\quad + \text{Scal}_\omega(df^2, d\dot{\phi}) + 2qf(df, d\Delta \dot{\phi}) \\
 &\quad + 2q(df, d\dot{\phi}) \Delta_\omega f - q(q-1)(df, d(df, d\dot{\phi})).
 \end{aligned}$$

On the other hand we have

$$\begin{aligned}
 (dS_{(K, q, a)}(\omega), d\dot{\phi}) &= f^2 (d\text{Scal}(\omega), d\dot{\phi}) + (df^2, d\dot{\phi}) \text{Scal}(\omega) \\
 (13) \quad &\quad + 2q(\Delta f)(df, d\dot{\phi}) + 2qf(d\Delta f, d\dot{\phi}) \\
 &\quad - q(q-1)(d\dot{\phi}, d(df, df)).
 \end{aligned}$$

By taking the difference (12)-(13) we get exactly (5) for $\alpha = d\dot{\phi}$, which, in turn, is equal to $-2\mathbb{L}_{(K, q, a)}^g(\dot{\phi})$. \square

Let $\mathfrak{h}_{\text{red}}^K$ denote the centralizer of K in $\mathfrak{h}_{\text{red}}$ (i.e. the space of vector fields $H \in \mathfrak{h}_{\text{red}}$ such that $[H, K] = 0$) and $\text{Aut}_{\text{red}}^K(M, J)$ the closed connected Lie subgroup of $\text{Aut}_{\text{red}}(M, J)$ with Lie algebra $\mathfrak{h}_{\text{red}}^K$.

Let $\omega \in \mathcal{K}_{\Omega}^G(M, J)$. To each element $\phi \in C_0^\infty(M, \mathbb{R})^G$ we associate a vector field $\hat{\phi}$ on $\mathcal{K}_{\Omega}^G(M, J)$, equal to ϕ at any point of $\mathcal{K}_{\Omega}^G(M, J)$. We then have $[\hat{\phi}, \hat{\psi}] = 0$ for any $\phi, \psi \in C_0^\infty(M, \mathbb{R})^G$. We will consider the natural action of $\text{Aut}_{\text{red}}^K(M, J)$ on $\mathcal{K}_{\Omega}^G(M, J)$ defined by:

$$\gamma \cdot \omega = \gamma^* \omega.$$

Consider the 1-form σ on $\mathcal{K}_{\Omega}^G(M, J)$ given by:

$$\sigma_{\omega}(\hat{\phi}) = \int_M S_{(K, q, a)}(\omega) \phi f_{(K, \omega, a)}^{q-2} v_{\omega}$$

where $\omega \in \mathcal{K}_{\Omega}^G(M, J)$ and $\phi \in C_0^\infty(M, \mathbb{R})^G$.

Proposition 2. *The 1-form σ is $\text{Aut}_{\text{red}}^K(M, J)$ -invariant and we have the following expression for its first variation,*

$$(14) \quad \begin{aligned} \delta \left(\sigma(\hat{\phi}) \right)_{\omega} (\hat{\psi}) &= -2 \int_M (D^- d\phi, D^- d\psi) f_{(K, \omega, a)}^q v_{\omega} \\ &\quad - \int_M S_{(K, q, a)}(\omega) (d\psi, d\phi) f_{(K, \omega, a)}^{q-2} v_{\omega}. \end{aligned}$$

In particular σ is closed.

Proof. Since $\text{Aut}_{\text{red}}^K(M, J)$ preserves the complex structure J and K , the invariance of σ under the action of $\text{Aut}_{\text{red}}^K(M, J)$ follows. Now we will calculate the first variation of the functional $\omega \mapsto \sigma_{\omega}(\phi)$. By (11) we have for each $\psi \in C_0^\infty(M, \mathbb{R})^G$,

$$\begin{aligned} \delta \left(\sigma(\hat{\phi}) \right)_{\omega} (\hat{\psi}) &= \int_M \delta S_{(K, q, a)}(\dot{\omega}) \phi f^{q-2} v_{\omega} + \int_M S_{(K, q, a)}(\omega) \phi (df^{q-2}, d\psi) v_{\omega} \\ &\quad - \int_M S_{(K, q, a)}(\omega) \phi f^{q-2} (\Delta_{\omega} \psi) v_{\omega} \\ &= \int_M \delta S_{(K, q, a)}(\dot{\omega}) \phi f^{q-2} v_{\omega} - \int_M (dS_{(K, q, a)}(\omega), d\psi) \phi f^{q-2} v_{\omega} \\ &\quad - \int_M S_{(K, q, a)}(\omega) (d\psi, d\phi) f^{q-2} v_{\omega}. \end{aligned}$$

From (10) and the above formula we readily get (14). Thus,

$$(\mathbf{d}\sigma)_{\omega} \left(\hat{\phi}, \hat{\psi} \right) = \delta \left(\sigma(\hat{\psi}) \right)_{\omega} (\hat{\phi}) - \delta \left(\sigma(\hat{\phi}) \right)_{\omega} (\hat{\psi}) - \sigma_{\omega}([\hat{\phi}, \hat{\psi}]) = 0.$$

i.e. σ is a closed 1-form. □

Remark 2. One can alternatively elaborate along the lines of [4]. For $\omega \in \mathcal{K}_{\Omega}^G(M, J)$ and $J \in \mathcal{K}^G(M, \omega)$ fixed, we consider the path of Kähler metrics $\omega_t = \omega + dd^c \phi_t$ with $\phi_t \in C_0^\infty(M, \mathbb{R})^G$, $\phi_0 = 0$ and $\dot{\phi}_t = \phi$. Using the equivariant Moser Lemma (see [4, Lemma 1]) there exists a family of G -equivariant diffeomorphisms $\Phi_t \in \text{Diff}_0^G(M)$ such that $\Phi_0 = \text{id}_M$ and $\Phi_t \cdot \omega = \omega_t$. Then we have a path $J_t = \Phi_t \cdot J$ in $\mathcal{K}^G(M, \omega)$. Note that if $g_t = \omega_t(\cdot, J_t \cdot)$

then $f_{(K,\omega_t,a)} = f_{(K,\omega,a)} \circ \Phi_t$. We have,

$$\begin{aligned}
\delta \left(\sigma(\hat{\psi}) \right)_\omega (\hat{\phi}) &= \frac{d}{dt} \Big|_{t=0} \int_M S_{(K,q,a)}(\omega_t) \psi f_{(K,\omega_t,a)}^{q-2} v_{\omega_t} \\
&= \frac{d}{dt} \Big|_{t=0} \int_M \Phi_t^* \left(S_{(K,q,a)}(J_t) (\psi \circ \Phi_t^{-1}) f_{(K,\omega,a)}^{q-2} v_\omega \right) \\
&= \frac{d}{dt} \Big|_{t=0} \int_M S_{(K,q,a)}(J_t) (\psi \circ \Phi_t^{-1}) f_{(K,\omega,a)}^{q-2} v_\omega \\
&= \int_M \left(\dot{J}, D J d\psi \right) f_{(K,\omega,a)}^q v_\omega + \int_M S_{(K,q,a)}(\omega) d\psi(Z) f_{(K,\omega,a)}^{q-2} v_\omega,
\end{aligned}$$

where we used [4, Eq(9)] and that Z, \dot{J} are given by:

$$\begin{aligned}
Z &= \frac{d}{dt} \Big|_{t=0} \Phi_t^{-1} \circ \Phi = -\text{grad}_g \phi, \\
\dot{J} &= \frac{d}{dt} \Big|_{t=0} \Phi_t^* J = -\mathcal{L}_Z J.
\end{aligned}$$

It follows that,

$$\begin{aligned}
d\psi(Z) &= -(d\psi, d\phi), \\
(\dot{J}, D J d\psi) &= -2 (D^- d\phi, D^- d\psi).
\end{aligned}$$

We thus get,

$$\delta \left(\sigma(\hat{\psi}) \right)_\omega (\hat{\phi}) = -2 \int_M (D^- d\phi, D^- d\psi) f_{(K,\omega,a)}^q v_\omega - \int_M S_{(K,q,a)}(\omega) (d\psi, d\phi) f_{(K,\omega,a)}^{q-2} v_\omega.$$

As shown in [4], and as it easily follows from (14), the following expression:

$$c_{(\Omega,K,q,a)} := \frac{\int_M S_{(K,q,a)}(\omega) f_{(K,\omega,a)}^{q-2} v_\omega}{\int_M f_{(K,\omega,a)}^{q-2} v_\omega}.$$

is a topological constant (i.e. independent of the choice of ω in the Kähler class Ω). We consider the following 1-form, on $\mathcal{K}_\Omega^G(M, J)$ given by:

$$\tilde{\sigma}_\omega(\hat{\phi}) := \int_M (S_{(K,q,a)}(\omega) - c_{(\Omega,K,q,a)}) \phi f_{(K,\omega,a)}^{q-2} v_\omega.$$

Lemma 2. *The 1-form $\tilde{\sigma}$ is closed.*

Proof. We consider the 1-form θ defined on $\mathcal{K}_\Omega^G(M, J)$ by

$$\theta_\omega(\hat{\phi}) = \int_M \phi f_{(K,\omega,a)}^{q-2} v_\omega.$$

We have using (11),

$$\begin{aligned}
\delta(\theta_\omega(\hat{\phi}))(\hat{\psi}) &= \int_M \phi (df^{q-2}, d\psi) v_\omega - \int_M \phi f^{q-2} (\Delta_\omega \psi) v_\omega \\
&= - \int_M (d\psi, d\phi) f^{q-2} v_\omega.
\end{aligned}$$

Thus,

$$(\mathbf{d}\theta)_\omega (\hat{\phi}, \hat{\psi}) = \delta \left(\theta(\hat{\psi}) \right)_\omega (\hat{\phi}) - \delta \left(\theta(\hat{\phi}) \right)_\omega (\hat{\psi}) - \theta_\omega([\hat{\phi}, \hat{\psi}]) = 0,$$

i.e. θ is closed. By Proposition 2, $\tilde{\sigma} = \sigma - c_{(\Omega,K,q,a)} \cdot \theta$ is closed. \square

Since $\mathcal{K}_\Omega^G(M, J)$ is contractible, $\tilde{\sigma}$ is an exact form, so it admits a primitive functional.

Definition 3. We define the (Ω, K, q, a) -Mabuchi energy

$$\mathcal{M}_{(\Omega, K, q, a)} : \mathcal{K}_{\Omega}^G(M, J) \rightarrow \mathbb{R}$$

as minus the primitive of the one form $\tilde{\sigma}$, i.e.

$$\tilde{\sigma} = -\mathbf{d}\mathcal{M}_{(\Omega, K, q, a)},$$

normalized by $\mathcal{M}_{(\Omega, K, q, a)}(\omega_0) = 0$ for some base point $\omega_0 \in \mathcal{K}_{\Omega}^G(M, J)$.

Remark 3. By its very definition, the Kähler metrics in $\mathcal{K}_{\Omega}^G(M, J)$ of constant (Ω, K, q, a) -scalar curvature are critical points of the (Ω, K, q, a) -Mabuchi functional.

3.2. The (Ω, K, q, a) -Futaki invariant. For $\omega \in \mathcal{K}_{\Omega}^G(M, J)$ and $H \in \mathfrak{h}_{\text{red}}^K$, we denote by $h'_{(H, \omega)} + \sqrt{-1}h_{(H, \omega)} \in C_0^{\infty}(M, \mathbb{C})$ the normalized holomorphy potential of H , i.e. $h'_{(H, \omega)}$ and $h_{(H, \omega)}$ are the normalized smooth functions such that,

$$H = \text{grad}_g(h'_{(H, \omega)}) + J\text{grad}_g(h_{(H, \omega)}).$$

Using the identification $T_{\omega}\mathcal{K}_{\Omega}^G(M, J) \cong C_0^{\infty}(M, \mathbb{R})^G$, the vector field JH defines a vector field \widehat{JH} on $\mathcal{K}_{\Omega}^G(M, J)$, given by:

$$\omega \mapsto \mathcal{L}_{JH}\omega = dd^c h_{(H, \omega)},$$

so that $\widehat{JH}_{\omega} = h_{(H, \omega)}$. By the invariance of $\tilde{\sigma}$ under the $\text{Aut}_{\text{red}}^K(M, J)$ -action and Cartan's formula we get,

$$\mathcal{L}_{\widehat{JH}}\tilde{\sigma} = \mathbf{d}\left(\tilde{\sigma}_{\omega}(\widehat{JH})\right) = 0.$$

Then $\omega \mapsto \tilde{\sigma}(\widehat{JH})$ is constant on $\mathcal{K}_{\Omega}^G(M, J)$. We will use the following notation,

$$\mathcal{F}_{(\Omega, K, q, a)}(H) := \tilde{\sigma}(\widehat{JH}) = \int_M (S_{(K, q, a)}(\omega) - c_{(\Omega, K, q, a)}) h_{(H, \omega)} f_{(K, \omega, a)}^{q-2} v_{\omega}.$$

Definition 4. The linear map $\mathcal{F}_{(\Omega, K, q, a)} : \mathfrak{h}_{\text{red}}^K \rightarrow \mathbb{R}$ will be called the (Ω, K, q, a) -Futaki invariant associated to the data (Ω, K, q, a) .

Remark 4.

- (i) Definition 4 is consistent with the one given in [4] for $q = -2m + 1$, but it has the advantage to show that the (Ω, K, q, a) -Futaki invariant extends to the whole of $\mathfrak{h}_{\text{red}}^K$, not just $\text{Lie}(G)$.
- (ii) For a Kähler class Ω which admits (K, q, a) -extremal metric ω , $\mathcal{F}_{\Omega, K, q, a} = 0$ if and only if ω is a (K, q, a) -constant scalar curvature Kähler metric. In fact, for $\Xi = J\text{grad}_g(S_{(K, q, a)}(\omega)) \in \mathfrak{h}_{\text{red}}^K$ we have

$$\mathcal{F}_{(\Omega, K, q, a)}(\Xi) = \int_M (S_{(K, q, a)}(\omega) - c_{(\Omega, K, q, a)})^2 f_{(K, \omega, a)}^{q-2} v_{\omega} = 0,$$

$$\text{thus } S_{(K, q, a)}(\omega) = c_{(\Omega, K, q, a)}.$$

4. PROOF OF THEOREM 1

In this section we shall prove Theorem 1 from the introduction. We thus assume that (g, ω) is an (K, q, a) -extremal metric on a compact, connected Kähler manifold (M, J) , and $G \subset \text{Aut}_{\text{red}}(M, J)$ the torus generated by the quasi-periodic Killing vector field K .

Lemma 3. For any G -invariant function $\phi \in C^{\infty}(M, \mathbb{R})^G$ we have

$$\mathcal{L}_{\Xi}\phi = -2f_{(K, \omega, a)}^{2-q}\delta\delta\left(f_{(K, \omega, a)}^q D^-(d^c\phi)\right),$$

where \mathcal{L}_{Ξ} denotes the Lie derivative along the vector field $\Xi = J\text{grad}(S_{(K, q, a)}(\omega))$.

Proof. We have,

$$\begin{aligned}\mathcal{L}_\Xi \phi &= -(dS_{(K,q,a)}(\omega), d^c \phi) \\ &= -f^2(d\text{Scal}(\omega), d^c \phi) - 2qf(d\Delta f, d^c \phi) + q(q-1)(d^c \phi, d(df, df)).\end{aligned}$$

By taking $\alpha = d^c \phi$ in (5) we get,

$$\begin{aligned}2f^{2-q}(D^- d)^* f^q (D^- d^c) \phi &= 2f^2(D^- d)^* (D^- d^c) \phi + 2qf(d\Delta f, d^c \phi) \\ &\quad - q(q-1)(d^c \phi, d(df, df)) \\ &= f^2(dS_\omega, d^c \phi) + 2qf(d\Delta f, d^c \phi) \\ &\quad - q(q-1)(d^c \phi, d(df, df)),\end{aligned}$$

where we have used (see [16, p.63, Eq.(1.23.15)]),

$$(D^- d)^* (D^- d^c) \phi = (dS_\omega, d^c \phi),$$

and the identity,

$$(\delta d d^c \phi, df) = -(\delta^c d^c d \phi)(K) = -\mathcal{L}_K \delta^c d^c \phi = 0.$$

□

For a 1-forme α we denote by $D^{2,0}\alpha$ (resp. $D^{0,2}\alpha$) the $(2,0)$ -part (resp. $(0,2)$ -part) of the tensor $D\alpha$. We define the (K, q, a) -Calabi's operators $\mathbb{L}_{(K,q,a)}^{g,\pm}$ on $C^\infty(M, \mathbb{C})^G$ by

$$\begin{aligned}\mathbb{L}_{(K,q,a)}^{g,+}(F) &= 2f_{(K,\omega,a)}^{2-q}(D^{0,2}d)^* f_{(K,\omega,a)}^q D^{0,2}dF \\ \mathbb{L}_{(K,q,a)}^{g,-}(F) &= 2f_{(K,\omega,a)}^{2-q}(D^{2,0}d)^* f_{(K,\omega,a)}^q D^{2,0}dF.\end{aligned}$$

Recall that the space of hamiltonian Killing vector fields is given by (see [16])

$$\mathfrak{k}_{\text{ham}} = \mathfrak{h}_{\text{red}} \cap \mathfrak{k}.$$

The following Proposition is straightforward (see [16, Chapter 2]).

Proposition 3.

- (i) Let $H = \text{grad}_g P + J \text{grad}_g Q$, where P, Q are real valued functions with zero mean, such that $[H, K] = 0$. Then $H \in \mathfrak{h}_{\text{red}}$ if and only if $\mathbb{L}_{(K,q,a)}^{g,+}(P + \sqrt{-1}Q) = 0$ and $P, Q \in C^\infty(M, \mathbb{R})^G$ i.e. we have

$$\mathfrak{h}_{\text{red}}^K \cong \ker(\mathbb{L}_{(K,q,a)}^{g,+}) \cap C_0^\infty(M, \mathbb{C})^G.$$

- (ii) For any $F \in C^\infty(M, \mathbb{C})^G$ we have,

$$\mathbb{L}_{(K\nu,a)}^{g,\pm}(F) = \mathbb{L}_{(K,q,a)}^g(F) \pm \frac{\sqrt{-1}}{2} \mathcal{L}_\Xi F.$$

- (iii) Let X be real holomorphic vector field. Then $X \in \mathfrak{k}_{\text{ham}}^K$ if and only if there exists $h \in C^\infty(M, \mathbb{R})^G$ such that $X = J \text{grad}_g h$ and $\mathbb{L}_{(K,q,a)}^g(h) = 0$.

Theorem 4. Suppose (M, g, J) is a compact (K, q, a) -extremal Kähler manifold. Then \mathfrak{h}^K admits the following $\langle \cdot, \cdot \rangle_{(g,q,a)}$ -orthogonal decomposition

$$(15) \quad \mathfrak{h}^K = \mathfrak{h}_{(0)}^K \oplus \left(\bigoplus_{\lambda > 0} \mathfrak{h}_{(\lambda)}^K \right),$$

where $\mathfrak{h}_{(0)}^K$ is the centralizer of Ξ in \mathfrak{h}^K and for $\lambda > 0$, $\mathfrak{h}_{(\lambda)}^K$ denote the subspace of elements $X \in \mathfrak{h}^K$ such that $\mathcal{L}_\Xi X = \lambda JX$.

The subspace $\mathfrak{h}_{(0)}^K$ is a reductive complex Lie subalgebra of \mathfrak{h}^K ; it contains \mathfrak{a} , $\mathfrak{k}_{\text{ham}}^K$ and $J\mathfrak{k}_{\text{ham}}^K$ and is given by the $\langle \cdot, \cdot \rangle_{(g,q,a)}$ -orthogonal sum of these three spaces:

$$(16) \quad \mathfrak{h}_{(0)}^K = \mathfrak{a} \oplus \mathfrak{k}_{\text{ham}}^K \oplus J\mathfrak{k}_{\text{ham}}^K.$$

Moreover, each $\mathfrak{h}_{(\lambda)}^K$, $\lambda > 0$, is contained in the ideal $\mathfrak{h}_{\text{red}}^K$, so that we also have the following $\langle \cdot, \cdot \rangle_{(g,q,a)}$ -orthogonal decompositions:

$$(17) \quad \begin{aligned} \mathfrak{h}^K &= \mathfrak{a} \oplus \mathfrak{h}_{\text{red}}^K, \\ \mathfrak{k}^K &= \mathfrak{a} \oplus \mathfrak{k}_{\text{ham}}^K. \end{aligned}$$

Proof. Let $X = X_H + \text{grad}_g P + J \text{grad}_g Q \in \mathfrak{h}^K$, where X_H is the dual of the harmonic part of $\xi = X^\flat$ denoted ξ_H , and $P, Q \in C^\infty(M, \mathbb{R})$ with zero mean value. Since $K = J \text{grad}_g f$ is Killing we have

$$\mathcal{L}_K P = \mathcal{L}_K Q = 0.$$

By (5) in Lemma 1 we have

$$\begin{aligned} 2f^{2-q}(D^-d)^* f^q D^- \xi_H &= 2f^2(D^-d)^* D^- \xi_H \\ &= f^2(d\text{Scal}(\omega), \xi_H) + 2qf(d\Delta f, \xi_H) \\ &\quad - q(q-1)(\xi_H, d(df, df)) \\ &= J\mathcal{L}_\Xi \xi_H = 0, \end{aligned}$$

where we have used $(\xi_H, df) = 0$ and the fact that Ξ is a Killing vector field. It follows that

$$0 = f^{2-q}(D^-d)^* f^q D^- \xi = f^{2-q}(D^-d)^* f^q D^- (dP + d^c Q) = \text{Re} \left(\mathbb{L}_{(K,q,a)}(P + \sqrt{-1}Q) \right).$$

Starting from JX instead of X we similarly get

$$\text{Im} \left(\mathbb{L}_{(K,q,a)}^+(P + \sqrt{-1}Q) \right) = 0.$$

It follows that $\mathbb{L}_{(K,q,a)}^+(P + \sqrt{-1}Q) = 0$, then by Proposition 3(i) we have that X_H and $\text{grad}_g P + J \text{grad}_g Q$ are real holomorphic vector fields, which proves (17) (for the decomposition of \mathfrak{k}^K we use the fact that $\mathfrak{k}_{\text{ham}} := \mathfrak{k} \cap \mathfrak{h}_{\text{red}}$ and $\mathfrak{k} \cap \mathfrak{a} = \mathfrak{a}$).

Since Ξ is Killing and commutes with K , the operators $\mathbb{L}_{(K,q,a)}^{g,\pm}$ commute. Then $\mathbb{L}_{(K,q,a)}^{g,-}$ acts on $\mathfrak{h}_{\text{red}}^K$ and by Proposition 3(ii) this action is given by $-\sqrt{-1}\mathcal{L}_\Xi$. Since $\mathbb{L}_{(K,q,a)}^-$ is $\langle \cdot, \cdot \rangle_{(g,q,a)}$ -self-adjoint and semi-positive, $\mathfrak{h}_{\text{red}}^K$ splits as

$$\mathfrak{h}_{\text{red}}^K = \mathfrak{h}_{\text{red},(0)}^K \oplus \left(\bigoplus_{\lambda>0} \mathfrak{h}_{(\lambda)}^K \right),$$

where $\mathfrak{h}_{\text{red},(0)}^K$ is the kernel of \mathcal{L}_Ξ in $\mathfrak{h}_{\text{red}}^K$ whereas, for each $\lambda > 0$, $\mathfrak{h}_{(\lambda)}^K$ is the subspace of elements $X \in \mathfrak{h}^K$ such that $\mathcal{L}_\Xi X = \lambda JX$. Using (17) we get (15) (Notice that $\mathfrak{h}_{(\lambda)}^K = \mathfrak{h}_{\text{red},(\lambda)}^K$ since Ξ is Killing and commutes with K).

We have $\mathfrak{a} \oplus \mathfrak{k}_{\text{ham}}^K \oplus J\mathfrak{k}_{\text{ham}}^K \subset \mathfrak{h}_{(0)}^K$. By Proposition 3(ii) the restriction of \mathcal{L}_Ξ to $\ker \left(\mathbb{L}_{(K,q,a)}^{g,+} \right) \cap C_0^\infty(M, \mathbb{C})^G$ coincides with the restriction of $\mathbb{L}_{(K,q,a)}^g$ to the same space. Then, using Proposition 3 (iii), we obtain the converse inclusion, which proves (16). \square

Now we are in position to give a proof for Theorem 1.

Proof of Theorem 1. This is done as in the case where $(G = \{1\}, q = 0, a = 0)$ (see [16, 6]). Let \mathfrak{s} be the Lie algebra of a connected, compact Lie subgroup, $S \subset \text{Aut}_0^K(M, J)$ containing $\text{Isom}_0^K(M, g)$. Suppose, for a contradiction, that there exists $X \in \mathfrak{s}$ that doesn't belong to \mathfrak{k}^K . By Theorem 4, (see (15), (17) and (16)) we have the splitting

$$\mathfrak{h}^K = \mathfrak{k}^K \oplus J\mathfrak{k}_{\text{ham}}^K \oplus \left(\bigoplus_{\lambda>0} \mathfrak{h}_{(\lambda)}^K \right),$$

then we can assume that $X \in J\mathfrak{k}_{\text{ham}}^K \oplus \left(\bigoplus_{\lambda>0} \mathfrak{h}_{(\lambda)}^K \right)$. Let $X = X_0 + \sum_{\lambda>0} X_\lambda$ be the corresponding decomposition of X , then for any positive integer r we have

$$(\mathcal{L}_\Xi)^{2r} X = - \sum_{\lambda>0} \lambda^{2r} X_\lambda \in \mathfrak{s}.$$

It follows that each component X_λ of X is in \mathfrak{s} . We can therefore assume that $X \in \mathfrak{s}_\lambda := \mathfrak{s} \cap \mathfrak{h}_{(\lambda)}^K$ or $X \in J\mathfrak{k}_{\text{ham}}^K \subset \mathfrak{s}_0$. Suppose that $X \in \mathfrak{s}_\lambda$ for some $\lambda > 0$. Let B denote the Killing form of \mathfrak{s} . Since S is a compact Lie group, B is semi-negative and its kernel coincides with the center of \mathfrak{s} . On the other hand X belongs to the kernel of B , indeed for any $Y \in \mathfrak{s}_{\lambda_1}$ and $Z \in \mathfrak{s}_{\lambda_2}$, by Jacobi identity we can easily show that $[X, [Y, Z]] \in \mathfrak{s}_{\lambda+\lambda_1+\lambda_2} \neq \mathfrak{s}_{\lambda_2}$ then $\mathfrak{s}_{\lambda+\lambda_1+\lambda_2} = \{0\}$ and by consequence $[X, [Y, Z]] = 0$. It follows that for any $Y \in \mathfrak{s}$ we have $B(X, Y) = 0$. Hence X belongs to the center of \mathfrak{s} , but we have $\Xi \in \mathfrak{k}^K \subset \mathfrak{s}$ and $[X, \Xi] = -\lambda JX \neq 0$, a contradiction.

It follows that $X \in J\mathfrak{k}_{\text{ham}}^K$. Then $X = \text{grad}_g(P)$ for some real function P . By the hypothesis the flow Φ_t^X of X is contained in a compact connected subgroup of $\text{Aut}_0^K(M, J)$. It follows that X is quasi-periodic with a flow closure in $\text{Aut}_0^K(M, J)$ given by a torus T^k of dimension $k \geq 1$. Note that $k \neq 1$ since a gradient vector field does not admit any non-trivial closed integral curve, as $\frac{d}{dt}P(\Phi_t^X(x)) = |X|_{\Phi_t^X(x)}^2 \geq 0$. It follows that $k > 1$. Let $x \in M$ such that $X_x \neq 0$. We have that $P(\Phi_t^X(x))$ is an increasing function of t , so that $P(\Phi_t^X(x)) - P(x) > c$, for $t > 1$, where $c > 0$. But by density of Φ_t^X in the torus T^k , Φ_t^X meets any small neighborhood U of x , which is a contradiction. We conclude that $\mathfrak{s} = \mathfrak{k}^K$.

If the (K, q, a) -scalar curvature is constant then by Theorem 4, \mathfrak{h}^K splits as

$$\mathfrak{h}^K = \mathfrak{a} \oplus \mathfrak{k}_{\text{ham}}^K \oplus J\mathfrak{k}_{\text{ham}}^K,$$

since $\mathfrak{h}_{(\lambda)}^K = \{0\}$. In particular \mathfrak{h}^K is a reductive complex Lie algebra. □

We have the following immediate consequences of Theorem 1.

Corollary 3. *Any (K, q, a) -extremal metric on a compact Kähler manifold (M, J) belongs to $\mathcal{K}_\Omega^\mathbb{T}(M, J)$ for some maximal torus \mathbb{T} of $\text{Aut}_{\text{red}}(M, J)$ such that $K \in \text{Lie}(\mathbb{T})$.*

Corollary 4. *Let g and \tilde{g} be two (K, q, a) -extremal metrics on (M, J) . Then there is $\Phi \in \text{Aut}_0^K(M, J)$ such that $\text{Isom}_0^K(M, g) = \text{Isom}_0^K(M, \Phi^*\tilde{g})$. Furthermore if (M, J) is a toric manifold and g and \tilde{g} are two (K, q, a) -extremal metrics in the same Kähler class Ω , then they are isometric (see [4]).*

Proof of Corollary 1. This follows from Corollary 3 and [4, Proposition 6] □

Proof of Corollary 2. We have the following exact sequence (see [3, Proposition 1.3]):

$$0 \rightarrow \mathfrak{h}_B(M) \rightarrow \mathfrak{h}(M) \rightarrow \mathfrak{h}(B) \rightarrow 0$$

where $B = \mathbb{F}_n$ and $\mathfrak{h}_B(M)$ denote the Lie algebra of holomorphic vector fields on M which are tangent to the fibers of π . The proof of [3, Proposition 1.3] also shows that,

$$0 \rightarrow \mathfrak{h}_B^K(M) \rightarrow \mathfrak{h}^K(M) \rightarrow \mathfrak{h}(B) \rightarrow 0$$

where $\mathfrak{h}_B^K(M) = \text{span}_{\mathbb{C}}\{K, JK\}$ is the abelian sub-algebra generated by the vector fields K, JK . If M admits a Kähler metric of constant (bK, q, a) -scalar curvature, then $\mathfrak{h}^K(M)$ must be reductive by Theorem 1. As $\mathfrak{h}_B^K(M)$ is in the center of $\mathfrak{h}^K(M)$, it would follow that $\mathfrak{h}(B)$ is reductive, which is not the case for $B = \mathbb{F}_n$ (see e.g. [5]). It follows that M admits no Kähler metric of constant (bK, q, a) -scalar curvature. □

5. THE (K, q, a) -EXTREMAL KÄHLER METRICS RELATIVELY TO A MAXIMAL TORUS \mathbb{T} , AND (\mathbb{T}, K, q, a) -EXTREMAL VECTOR FIELD

Using Corollaries 3 and 4, we assume from now on that \mathbb{T} is a fixed maximal torus in $\text{Aut}_{\text{red}}(M, J)$ and $K \in \text{Lie}(\mathbb{T})$. We denote by $\Pi_g^{\mathbb{T}}$ the orthogonal projection with respect to the L^2 -scalar product

$$\langle \phi, \psi \rangle_{(g, q, a)} := \int_M \phi \psi f_{(K, \omega, a)}^{q-2} v_{\omega}$$

defined on the Hilbert space $L^2_{\mathbb{T}}(M, \mathbb{R})$ onto the space $P_g^{\mathbb{T}}(M, \mathbb{R})$ of Killing potentials of the elements of $\text{Lie}(\mathbb{T})$ relatively to g which is isomorphic to $\mathbb{R} \oplus \text{Lie}(\mathbb{T})$. Then we have the following decomposition of the (K, q, a) -scalar curvature,

$$S_{(K, q, a)}(\omega) = S_{(K, q, a)}^{\mathbb{T}}(\omega) + \Pi_g^{\mathbb{T}}(S_{(K, q, a)}(\omega)),$$

Definition 5. We call $S_{(K, q, a)}^{\mathbb{T}}(\omega)$ the reduced (K, q, a) -scalar curvature with respect to \mathbb{T} . We say that $\omega \in \mathcal{K}_{\Omega}^{\mathbb{T}}(M, J)$ is (K, q, a) -extremal relatively \mathbb{T} if $S_{(K, q, a)}^{\mathbb{T}}(\omega)$ is identically zero.

Remark 5. Notice that by Corollary 3, any (K, q, a) -extremal metric is extremal relatively to the maximal torus of $\text{Aut}_{\text{red}}(M, J)$ containing K .

Following [16, Proposition 4.11.1] we have,

Definition 6. For $X, Y \in \mathfrak{h}_{\text{red}}$ with normalized complex potentials $F_{\omega}^X, F_{\omega}^Y$ we define the (Ω, K, q, a) -Futaki-Mabuchi bilinear by the following expression

$$\mathcal{B}_{(\Omega, K, q, a)}(X, Y) := \int_M F_{\omega}^X F_{\omega}^Y f_{(K, \omega, a)}^{q-2} v_{\omega}$$

which is independent from the choice of $\omega \in \mathcal{K}_{\Omega}^{\mathbb{T}}(M, J)$.

We denote by $Z_{\omega}^{\mathbb{T}}(K, q, a)$ the vector field given by

$$Z_{\omega}^{\mathbb{T}}(K, q, a) := J \text{grad}_g \left(\Pi_g^{\mathbb{T}}(S_{(K, q, a)}(\omega)) \right).$$

Then for all $H \in \text{Lie}(\mathbb{T})$, we have

$$(18) \quad \mathcal{F}_{(\Omega, K, q, a)}(H) = -\mathcal{B}_{(\Omega, K, q, a)} \left(H, Z_{\omega}^{\mathbb{T}}(K, q, a) \right).$$

From its very definition, the restriction of $\mathcal{B}_{(\Omega, K, q, a)}$ to $\text{Lie}(\mathbb{T})$ is negative definite. Then $Z_{\omega}^{\mathbb{T}}(K, q, a)$ is well-defined by the above expression, so it is an element of $\text{Lie}(\mathbb{T})$, independent of the choice of $\omega \in \mathcal{K}_{\Omega}^{\mathbb{T}}(M, J)$.

Definition 7. We call $Z^{\mathbb{T}}(\Omega, K, q, a) \in \text{Lie}(\mathbb{T})$ the (Ω, K, q, a) -extremal vector field.

Now we consider the 1-form $\zeta^{\mathbb{T}}$ defined on $\mathcal{K}_{\Omega}^{\mathbb{T}}(M, J)$ by,

$$\zeta_{\omega}^{\mathbb{T}}(\hat{\phi}) = \int_M \Pi_g^{\mathbb{T}}(S_{(K, q, a)}(\omega)) \phi f_{(K, \omega, a)}^{q-2} v_{\omega}.$$

Lemma 4. The 1-form $\zeta^{\mathbb{T}}$ is closed.

Proof. To simplify notations we denote $z(\omega) := \Pi_g^{\mathbb{T}}(S_{(K, q, a)}(\omega))$. Then $Z^{\mathbb{T}}(\Omega, K, q, a) = J \text{grad}_g z(\omega)$. For a variation $\dot{\omega} = dd^c \phi$ in $\mathcal{K}_{\Omega}^{\mathbb{T}}(M, J)$, using (11) we have

$$\dot{z}(\phi) = (d\phi, dz(\omega))_{\omega}$$

and therefore,

$$\begin{aligned} \delta \left(\zeta^{\mathbb{T}}(\hat{\psi}) \right)_{\omega}(\hat{\phi}) &= \int_M (d\phi, dz(\omega))_{\omega} \psi f^{q-2} v_{\omega} + \int_M z(\omega) \psi (d\phi, df^{q-2}) v_{\omega} \\ &\quad - \int_M z(\omega) \psi \Delta_{\omega} \phi f^{q-2} v_{\omega} \\ &= - \int_M z(\omega) (d\phi, d\psi) f^{q-2} v_{\omega}. \end{aligned}$$

It follows that,

$$\left(d\zeta^{\mathbb{T}} \right)_{\omega}(\hat{\phi}, \hat{\psi}) = \delta \left(\zeta^{\mathbb{T}}(\hat{\psi}) \right)_{\omega}(\hat{\phi}) - \delta \left(\zeta^{\mathbb{T}}(\hat{\phi}) \right)_{\omega}(\hat{\psi}) = 0.$$

□

Now we consider the 1-form $\sigma^{\mathbb{T}}$ on $\mathcal{K}_{\Omega}^{\mathbb{T}}(M, J)$ given by

$$\sigma^{\mathbb{T}} := \sigma - \zeta^{\mathbb{T}}$$

which is a closed 1-form by virtue of Proposition 2 and Lemma 4.

Definition 8. The relative Mabuchi energy $\mathcal{M}_{(\Omega, K, q, a)}^{\mathbb{T}}$ is defined by

$$\sigma^{\mathbb{T}} = -d\mathcal{M}_{(\Omega, K, q, a)}^{\mathbb{T}},$$

where the primitive $\mathcal{M}_{(\Omega, K, q, a)}^{\mathbb{T}}$ is normalized by requiring $\mathcal{M}_{(\Omega, K, q, a)}^{\mathbb{T}}(\omega_0) = 0$ for some base point $\omega_0 \in \mathcal{K}_{\Omega}^{\mathbb{T}}(M, J)$.

Remark 6. By its very definition, the critical points of the relative Mabuchi energy are the \mathbb{T} -invariant (K, q, a) -extremal metrics.

6. PROOF OF THEOREM 2

Let (M, J) be a compact Kähler manifold. We fix $K \in \mathfrak{h}_{\text{red}}$, and $q \in \mathbb{R}$. Suppose that (g, ω) is a (K, q, a) -extremal Kähler metric on M with $\Omega = [\omega]$. Without loss of generality, by Corollary 3, we can assume that (g, ω) is invariant under the action of a maximal torus $\mathbb{T} \subseteq \text{Aut}_{\text{red}}(M, J)$. Let α be \mathbb{T} -invariant g -harmonic $(1, 1)$ -form. We take $(\omega, \alpha) = 0$ to avoid trivial deformations of the form $\alpha = \lambda\omega$. We denote by

$$\omega_{t, \phi} := \omega + t\alpha + dd^c \phi,$$

a \mathbb{T} -invariant deformations of ω for $t \in \mathbb{R}$ and $\phi \in C^{\infty}(M, \mathbb{R})^{\mathbb{T}}$. We consider the following map,

$$S : \mathbb{R}^3 \times C^{\infty}(M, \mathbb{R})^{\mathbb{T}} \rightarrow C^{\infty}(M, \mathbb{R})^{\mathbb{T}}$$

defined by,

$$S(s, t, u, \phi) := S_{(K+uH, q, a+s)}(\omega_{t, \phi}),$$

so that $S(0) = S_{(K, q, a)}(\omega) := S$. We denote $f_{(s, t, u, \phi)} = f_{(K+uH, \omega_{t, \phi}, a+s)} > 0$ the hamiltonian function of $K + uH$ with respect to $\omega_{t, \phi}$, with normalization constant $a + s$, so that $f_0 = f_{(K, \omega, a)} := f$. We take $k > n$ such that the Sobolev space $L_k^2(M, \mathbb{R})^{\mathbb{T}}$ form an algebra for the usual multiplication of functions, embadded in $C^4(M, \mathbb{R})^{\mathbb{T}}$. Then S defines a map

$$S : \mathbb{R}^3 \times L_{k+4}^2(M, \mathbb{R})^{\mathbb{T}} \rightarrow L_k^2(M, \mathbb{R})^{\mathbb{T}},$$

and we have:

Lemma 5. *The map S is C^1 with Fréchet derivative in 0 given by*

$$D_0 S = \begin{pmatrix} A & B & C & D \end{pmatrix}$$

with,

$$\begin{aligned} A &= 2f \text{Scal}(\omega) + 2q\Delta(f), \\ B &= -2(\rho_{(K,q,a)}(\omega), \alpha) + 2\lambda fS + 2q\Delta(f) + 2qf\Delta\lambda - 2q(q-1)(d\lambda, df), \\ C &= 2f_{(H,\omega)}f \text{Scal}(\omega) - 2q(q-1)(K, H) + 2q[f_{(H,\omega)}\Delta(f) + f\Delta(f_{(H,\omega)})], \\ D(\dot{\phi}) &= -2\mathbb{L}_{(K,q,a)}^g(\phi) + (dS, d\dot{\phi}), \end{aligned}$$

where (\cdot, \cdot) , grad , Δ , the green operator \mathbb{G} are calculated with respect to ω , and $\lambda := -\mathbb{G}(\alpha, dd^c f)$.

Proof. The expressions of A , C and D are straightforward. For the partial derivative with respect to t we have $S_{(K,q,a)}(\omega) = 2\Lambda_\omega(\rho_{(K,q,a)}(\omega))$ where (see [2])

$$\rho_{(K,q,a)}(\omega) = f^2\rho(\omega) - qfdd^c f - \frac{1}{2}q(q-1)df \wedge d^c f,$$

with $\rho(\omega)$ is the Ricci form of (g, ω) . By taking $X = -JK$ in [16, Lemma 5.2.4] we get,

$$\left. \frac{\partial}{\partial t} \right|_0 f_{(s,t,u,\phi)} = -\mathbb{G}(\delta(\alpha(K))) = -\mathbb{G}(\alpha, dd^c f_{(K,\omega,a)}) = \lambda,$$

and we have $\left. \frac{\partial}{\partial t} \right|_0 \rho(\omega_{t,\phi}) = 0$ since we assumed $(\omega, \alpha) = 0$. Thus,

$$\begin{aligned} B &= 2\left(\left. \frac{\partial}{\partial t} \right|_0 \Lambda_{\omega_{t,\phi}}\right) \rho_{(K,q,a)}(\omega) + 2\Lambda_\omega\left(\left. \frac{\partial}{\partial t} \right|_0 \rho_{(K,q,a+s)}(\omega_{t,\phi})\right) \\ &= -2(\rho_{(K,q,a)}(\omega), \alpha) + 2\lambda fS + 2q\Delta f + 2qf\Delta\lambda - 2q(q-1)(d\lambda, df). \end{aligned}$$

□

We consider the following maps,

$$\begin{aligned} \mathcal{F}(s, t, u) &:= \mathcal{F}_{([\omega+t\alpha], K+uH, q, a+s)}, \\ \mathcal{B}(s, t, u) &:= \mathcal{B}_{([\omega+t\alpha], K+uH, q, a+s)}, \\ Z(s, t, u) &:= Z^{\mathbb{T}}([\omega+t\alpha], K+uH, q, a+s). \end{aligned}$$

Lemma 6. *The t -derivative of the character $\mathcal{F}(s, t, u)$ and the bilinear for $\mathcal{B}(s, t, u)$ in the point $(s, t, u) = 0$ is given by*

$$\begin{aligned} (19) \quad \left. \frac{\partial}{\partial t} \right|_0 \mathcal{F}(s, t, u)(X) &= \langle h_{(X,\omega)}, B \rangle_{(g,q,a)} + \langle h_{(X,\omega)}, (q-2)\lambda fS \rangle_{(g,q,a)} \\ &\quad - \langle h_{(X,\omega)}, f^{2-q} \cdot (\alpha, dd^c \mathbb{G}(f^{q-2}S)) \rangle_{(g,q,a)}, \end{aligned}$$

$$\begin{aligned} (20) \quad \left. \frac{\partial}{\partial t} \right|_0 \mathcal{B}(s, t, u)(X, Y) &= \langle \alpha, f^{2-q} h_{(X,\omega)} dd^c \mathbb{G}(h_{(Y,\omega)} f^{q-2}) \rangle_{(g,q,a)} \\ &\quad + \langle \alpha, f^{2-q} \mathbb{G}(h_{(X,\omega)} f^{q-2}) dd^c h_{(Y,\omega)} \rangle_{(g,q,a)} \\ &\quad + (q-2) \langle \alpha, f^{2-q} \mathbb{G}(h_{(X,\omega)} h_{(Y,\omega)} f^{q-3}) dd^c f \rangle_{(g,q,a)}, \end{aligned}$$

for any $X = J\text{grad}_g(h_{(X,\omega)})$ and $Y = J\text{grad}_g(h_{(Y,\omega)})$ in $\text{Lie}(\mathbb{T})$ with $h_{X,\omega}$, $h_{Y,\omega}$ are the normalized real potential of $-JX$, $-JY$ respectively.

Proof. For the derivative of $\mathcal{F}(s, t, u)$ we have,

$$\mathcal{F}(s, t, u)(X) = \int_M S(s, t, u) h_{(X, \omega + t\alpha)} f_{(s, t, u)}^{q-2} v_{\omega + t\alpha},$$

then,

$$\begin{aligned} \left. \frac{\partial}{\partial t} \right|_0 \mathcal{F}(s, t, u)(X) &= \int_M B h_{(X, \omega)} f^{q-2} v_{\omega} - (q-2) \int_M S \lambda f^{q-3} h_{(X, \omega)} v_{\omega} \\ &\quad - \int_M S f^{q-2} \mathbb{G}(\delta(\alpha(X, \cdot))) v_{\omega}. \end{aligned}$$

On the other hand,

$$\begin{aligned} \int_M S f^{q-2} \mathbb{G}(\delta(\alpha(X, \cdot))) v_{\omega} &= \int_M (\alpha(X, \cdot), d\mathbb{G}(f^{q-2}S)) v_{\omega} \\ &= \int_M (\alpha, X^{\flat} \wedge d\mathbb{G}(f^{q-2}S)) v_{\omega} \\ &= \int_M (\alpha, d^c h \wedge d\mathbb{G}(f^{q-2}S)) v_{\omega} \\ &= \int_M h. (\alpha, dd^c \mathbb{G}(f^{q-2}S)) v_{\omega} \\ &= \langle h_{(X, \omega)}, f^{2-q} (\alpha, dd^c \mathbb{G}(f^{q-2}S)) \rangle_{(g, q, a)}. \end{aligned}$$

which gives the expression (19) for the t -derivative of $\mathcal{F}(s, t, u)$.

Now we calculate the t -derivative of $\mathcal{B}(s, t, u)$. We have

$$\mathcal{B}(s, t, u)(X, Y) = - \int_M h_{(X, \omega + t\alpha)} h_{(Y, \omega + t\alpha)} f_{(s, t, u)}^{q-2} v_{\omega + t\alpha}.$$

Then

$$\begin{aligned} \left. \frac{\partial}{\partial t} \right|_0 \mathcal{B}(s, t, u)(X, Y) &= \int_M \mathbb{G}(\delta(\alpha(X, \cdot))) h_Y f^{q-2} v_{\omega} \\ &\quad + \int_M \mathbb{G}(\delta(\alpha(Y, \cdot))) h_X f^{q-2} v_{\omega} \\ &\quad + (q-2) \int_M \mathbb{G}(\delta(\alpha(K, \cdot))) h_X h_Y f^{q-3} v_{\omega}. \end{aligned}$$

On the other hand,

$$\begin{aligned} \int_M \mathbb{G}(\delta(\alpha(X, \cdot))) h_Y f^{q-2} v_{\omega} &= \int_M (\alpha(X, \cdot), d\mathbb{G}(h_Y f^{q-2})) v_{\omega} \\ &= \int_M (\alpha, d^c h_X \wedge d\mathbb{G}(h_Y f^{q-2})) v_{\omega} \\ &= \langle \alpha, f^{2-q} h_X dd^c \mathbb{G}(h_Y f^{q-2}) \rangle_{(g, q, a)}, \end{aligned}$$

$$\begin{aligned} \int_M \mathbb{G}(\delta(\alpha(Y, \cdot))) h_X f^{q-2} v_{\omega} &= \int_M (\alpha(Y, \cdot), d\mathbb{G}(h_X f^{q-2})) v_{\omega} \\ &= \int_M (\alpha, d^c h_Y \wedge d\mathbb{G}(h_X f^{q-2})) v_{\omega} \\ &= \int_M (\alpha, \mathbb{G}(h_X f^{q-2}) dd^c h_Y) v_{\omega} \\ &= \langle \alpha, f^{2-q} \mathbb{G}(h_X f^{q-2}) dd^c h_Y \rangle_{(g, q, a)}, \end{aligned}$$

and,

$$\int_M \mathbb{G}(\delta(\alpha(K, \cdot))) h_X h_Y f^{q-3} v_\omega = \langle \alpha, f^{2-q} \mathbb{G}(h_X h_Y f^{q-3}) dd^c f \rangle_{(g,q,a)}.$$

Which proves (20). \square

In the following lemma we give the s and u -derivatives of $\mathcal{F}(s, t, u)$ and $\mathcal{B}(s, t, u)$ in $(s, t, u) = (0, 0, 0)$. We omit the proof since it follows from straightforward calculations.

Lemma 7.

(i) The s -derivative of $\mathcal{F}(s, t, u)$ is given by

$$(21) \quad \frac{\partial}{\partial s} \Big|_0 \mathcal{F}(s, t, u)(X) = \langle q f^{-1} S_{q-1}, h_{(X, \omega)} \rangle_{(g,q,a)}.$$

where $S_{q-1} := S_{(K, q-1, a)}(\omega)$.

(ii) The u -derivative of $\mathcal{F}(s, t, u)$

$$(22) \quad \frac{\partial}{\partial u} \Big|_0 \mathcal{F}(s, t, u)(X) = \langle C + (q-2) f^{-1} f_{(H, \omega)} S, h_{(X, \omega)} \rangle_{(g,q,a)}.$$

(iii) The s -derivative of $\mathcal{B}(s, t, u)$ is given by

$$(23) \quad \frac{\partial}{\partial s} \Big|_0 \mathcal{B}(s, t, u) = (q-2) \mathcal{B}_{(\Omega, K, q-1, a)}.$$

(iv) The u -derivative of $\mathcal{B}(s, t, u)$ is given by

$$(24) \quad \frac{\partial}{\partial u} \Big|_0 \mathcal{B}(s, t, u)(X, Y) = (q-2) \int_M h_{(X, \omega)} h_{(Y, \omega)} f_{(H, \omega)} f^{q-3} v_\omega$$

for any $X = J \text{grad}_g(h_{(X, \omega)})$ and $Y = J \text{grad}_g(h_{(Y, \omega)})$ in $\text{Lie}(\mathbb{T})$.

Lemma 8. Let ω be a (K, q, a) -extremal metric, we have

(i) The t -derivative of $Z(s, t, u)$ is given by

$$(25) \quad \frac{\partial}{\partial t} \Big|_0 Z(s, t, u) = J \text{grad}_g \left(\Pi_g^\mathbb{T} [B + \mathbb{G}(\alpha, dd^c S)] \right).$$

(ii) The s -derivative of $Z(s, t, u)$ is given by

$$(26) \quad \frac{\partial}{\partial s} \Big|_0 Z(s, t, u) = J \text{grad}_g \left(\Pi_g^\mathbb{T} [f^{-1} (q S_{q-1} + S)] \right).$$

(iii)

$$(27) \quad \frac{\partial}{\partial u} \Big|_0 Z(s, t, u) = J \text{grad}_g \left(\Pi_g^\mathbb{T} [C + 2(q-2) f^{-1} f_{(H, \omega)} S] \right).$$

Proof.

(i) We have $\frac{\partial}{\partial t} \Big|_0 Z(s, t, u) = J \text{grad}_g(P_g)$ for some function $P_g \in P_g^\mathbb{T}(M, \mathbb{R})$, since $Z(s, t, u) \in \text{Lie}(\mathbb{T})$ for all (s, t, u) . By (18), for all $X \in \text{Lie}(\mathbb{T})$ we have,

$$(28) \quad \mathcal{B}(s, t, u)(Z(s, t, u), X) = -\mathcal{F}(s, t, u)(X)$$

then

$$\begin{aligned} \mathcal{B}(0) \left(\frac{\partial}{\partial t} \Big|_0 Z(s, t, u), X \right) &= -\langle P_g, h_{(X, \omega)} \rangle_{(g,q,a)} \\ &= -\frac{\partial}{\partial t} \Big|_0 \mathcal{F}(s, t, u)(X) - \left(\frac{\partial}{\partial t} \Big|_0 \mathcal{B}(s, t, u) \right) (Z(0), X). \end{aligned}$$

Using (19), (20) and the fact that ω is (K, q, a) -extremal we get,

$$P_g = \Pi_g^{\mathbb{T}} (B + \mathbb{G}(\alpha, dd^c S)).$$

- (ii) We have $\frac{\partial}{\partial s}\big|_0 Z(s, t, u) = J\text{grad}_g(Q_g)$ for some function $Q_g \in P_g^{\mathbb{T}}(M, \mathbb{R})$, since $Z(s, t, u) \in \text{Lie}(\mathbb{T})$ for all (s, t, u) . Taking the derivative of (28) with respect to s we get,

$$\begin{aligned} -\mathcal{B}(0) \left(\frac{\partial}{\partial s}\bigg|_0 Z(s, t, u), X \right) &= \langle Q_g, h_{(X, \omega)} \rangle_{(g, q, a)} \\ &= \frac{\partial}{\partial s}\bigg|_0 \mathcal{F}(s, t, u)(X) + \left(\frac{\partial}{\partial s}\bigg|_0 \mathcal{B}(s, t, u) \right) (Z(0), X) \\ &= \langle f^{-1}(qS_{(q-1)} + S), h_{(X, \omega)} \rangle_{(g, q, a)} \end{aligned}$$

where we used the fact that ω is (K, q, a) -extremal and (21), (23). Thus

$$Q_g = f^{-1}(qS_{(K, q-1, a)}(\omega) + S_{(K, q, a)}(\omega))$$

which proves the result.

- (iii) This is done similarly to (25) and (26) by using (28), (22) and (24). □

We denote by $\Pi_{(s, t, u, \phi)}^{\mathbb{T}}$ the orthogonal projection on $\mathcal{P}_{g_t, \phi}^{\mathbb{T}}$ with respect to the inner product $\langle \cdot, \cdot \rangle_{g_t, \phi, q, a+s}$.

Lemma 9. *For a (K, q, a) -extremal metric ω we have,*

$$(29) \quad \frac{\partial}{\partial t}\bigg|_0 \Pi_{(s, t, u, \phi)}^{\mathbb{T}} S(s, t, u, \phi) = \Pi_g^{\mathbb{T}} B + (\Pi_g^{\mathbb{T}} - Id) (\mathbb{G}(\alpha, dd^c S)).$$

$$(30) \quad \frac{\partial}{\partial s}\bigg|_0 \Pi_{(s, t, u, \phi)}^{\mathbb{T}} S(s, t, u, \phi) = \Pi_g^{\mathbb{T}} [f^{-1}(qS_{q-1} + S)].$$

$$(31) \quad \frac{\partial}{\partial u}\bigg|_0 \Pi_{(s, t, u, \phi)}^{\mathbb{T}} S(s, t, u, \phi) = \Pi_g^{\mathbb{T}} [C + 2(q-2)f^{-1}f_{(H, \omega)}S].$$

Proof. We have $Z(s, t, u) = J\text{grad}_{g_t, \phi}(\Pi_{(s, t, u, \phi)}^{\mathbb{T}} S(s, t, u, \phi))$ then

$$J\text{grad}_g \left(\frac{\partial}{\partial t}\bigg|_0 (\Pi_{(s, t, u, \phi)}^{\mathbb{T}} S(s, t, u, \phi)) \right) = \frac{\partial}{\partial t}\bigg|_0 Z(s, t, u) - J \left(\frac{\partial}{\partial t}\bigg|_0 \text{grad}_{g_t, \phi} \right) (\Pi_g^{\mathbb{T}} S).$$

On the other hand we have,

$$\left(\frac{\partial}{\partial t}\bigg|_0 \text{grad}_{g_t, \phi} \right) (\Pi_g^{\mathbb{T}} S) = (\alpha(Z(0), \cdot))^{\sharp} = \text{grad}_g (\mathbb{G}(\alpha, dd^c S)).$$

By (25) it follows that

$$\frac{\partial}{\partial t}\bigg|_0 \Pi_{(s, t, u, \phi)}^{\mathbb{T}} S(s, t, u, \phi) = \Pi_g^{\mathbb{T}} B + (\Pi_g^{\mathbb{T}} - I) (\mathbb{G}(\alpha, dd^c S)) + c.$$

By differentiating in $t = 0$ the equality,

$$\int_M (\Pi_{g_t}^{\mathbb{T}} S(\omega_t)) f_{(K, \omega_t, a)}^{q-2} = \int_M S(\omega_t) f_{(K, \omega_t, a)}^{q-2}$$

we get $c = 0$, which proofs (29). Similarly we can show (30) and (31). □

Following LeBrun-Simanca's arguments [21] we give a proof of Theorem 2.

Proof. Let $L_k^2(M, \mathbb{R})^{\mathbb{T}, \perp}$ be the orthogonal complement of $P_g^{\mathbb{T}}(M, \mathbb{R})$ with respect to $\langle \cdot, \cdot \rangle_{(g, q, a)}$ in $L_k^2(M, \mathbb{R})^{\mathbb{T}}$. For $t \in (-\epsilon, \epsilon)$ and $\phi \in U$ where U is a small neighborhood of the origin in $L_{k+4}^2(M, \mathbb{R})^{\mathbb{T}}$. As in [21] by taking a smaller open set U and smaller ϵ we may assume that,

$$\ker \left(Id - \Pi_g^{\mathbb{T}} \right) \circ \left(Id - \Pi_{(s, t, u, \phi)}^{\mathbb{T}} \right) = \ker \left(Id - \Pi_{(s, t, u, \phi)}^{\mathbb{T}} \right).$$

Now we consider the LeBrun-Simanca map

$$\Psi : (-\epsilon, \epsilon)^3 \times U \rightarrow (-\epsilon, \epsilon)^3 \times L_k^2(M, \mathbb{R})^{\mathbb{T}, \perp}$$

defined by

$$\Psi(s, t, u, \phi) := \left(s, t, \left(Id - \Pi_g^{\mathbb{T}} \right) \circ \left(Id - \Pi_{(s, t, u, \phi)}^{\mathbb{T}} \right) S(s, t, u, \phi) \right).$$

Note that $\Psi(0) = 0$ and if $\Psi(s, t, u, \phi) = (s, t, u, 0)$ then $\omega_{t, \phi}$ is $(K + uH, q, a + s)$ -extremal.

The map Ψ is C^1 and its Fréchet derivative at the origin is given by:

$$D_0 \Psi = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & Id - \Pi_g^{\mathbb{T}} \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ A & B + \mathbb{G}(\alpha, dd^c S) & C & -2\mathbb{L}_{(K, q, a)}^g \end{pmatrix}$$

where A , B , and C are given in Lemma 5. Indeed, by Lemma 9 we have,

$$\begin{aligned} \frac{\partial}{\partial \phi} \Big|_0 \left(Id - \Pi_{(s, t, u, \phi)}^{\mathbb{T}} \right) S(s, t, u, \phi) \cdot \dot{\phi} &= D(\dot{\phi}) - \frac{\partial}{\partial \phi} \Big|_0 \Pi_{(s, t, u, \phi)}^{\mathbb{T}} S(s, t, u, \phi) \\ &= D(\dot{\phi}) - (dS, d\dot{\phi}) \\ &= -2f^{2-q}(D^- d)^{\star} f^q (D^- d) \dot{\phi}. \end{aligned}$$

$$\begin{aligned} \frac{\partial}{\partial t} \Big|_0 \left(Id - \Pi_{(s, t, u, \phi)}^{\mathbb{T}} \right) S(s, t, u, \phi) &= B - \frac{\partial}{\partial t} \Big|_0 \Pi_{(s, t, u, \phi)}^{\mathbb{T}} S(s, t, u, \phi) \\ &= B - \Pi_g^{\mathbb{T}} B + \left(Id - \Pi_g^{\mathbb{T}} \right) (\mathbb{G}(\alpha, dd^c S)) \\ &= \left(Id - \Pi_{(g, a)}^{\mathbb{T}} \right) (B + \mathbb{G}(\alpha, dd^c S)). \end{aligned}$$

$$\begin{aligned} \frac{\partial}{\partial s} \Big|_0 \left(Id - \Pi_{(s, t, u, \phi)}^{\mathbb{T}} \right) S(s, t, u, \phi) &= A - \frac{\partial}{\partial s} \Big|_0 \Pi_{(s, t, u, \phi)}^{\mathbb{T}} S(s, t, u, \phi) \\ &= A - \Pi_g^{\mathbb{T}} [f^{-1} (qS_{q-1} + S)]. \end{aligned}$$

$$\begin{aligned} \frac{\partial}{\partial u} \Big|_0 \left(Id - \Pi_{(s, t, u, \phi)}^{\mathbb{T}} \right) S(s, t, u, \phi) &= C - \frac{\partial}{\partial s} \Big|_0 \Pi_{(s, t, u, \phi)}^{\mathbb{T}} S(s, t, u, \phi) \\ &= \left(Id - \Pi_g^{\mathbb{T}} \right) C - \Pi_g^{\mathbb{T}} [2(q-2)f^{-1}f_{(H, \omega)}S]. \end{aligned}$$

The operator $\mathbb{L}_{(K, q, a)}^g$ is a formally $\langle \cdot, \cdot \rangle_{(g, q, a)}$ -self-adjoint, \mathbb{T} -invariant, elliptic fourth-order differential operator and extends to a continuous linear operator,

$$\mathbb{L}_{(K, q, a)}^g : L_{k+4}^2(M, \mathbb{R})^{\mathbb{T}, \perp} \rightarrow L_k^2(M, \mathbb{R})^{\mathbb{T}, \perp}$$

which is an isomorphism (since \mathbb{T} is a maximal torus of $\text{Aut}_{\text{red}}(M, J)$). Thus

$$D\Psi_0 : \mathbb{R}^3 \times L_{k+4}^2(M, \mathbb{R})^{\mathbb{T}, \perp} \rightarrow \mathbb{R}^3 \times L_k^2(M, \mathbb{R})^{\mathbb{T}, \perp}$$

is an isomorphisme. It follows from the inverse function theorem that Ψ is an isomorphisme in a neighborhood $(-\epsilon, \epsilon)^2 \times U$ of 0. Using the Sobolev embbeting theorem, we can assume that

the solution is of regularity at least C^4 . We conclude using a similar bootstrapping argument as in the case of extremal metrics [21, Proposition 4]. \square

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