

LOOPING DIRECTIONS AND INTEGRALS OF EIGENFUNCTIONS OVER SUBMANIFOLDS

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ABSTRACT. Let (M, g) be a compact n -dimensional Riemannian manifold without boundary and e_λ be an L^2 -normalized eigenfunction of the Laplace-Beltrami operator with respect to the metric g , i.e

$$-\Delta_g e_\lambda = \lambda^2 e_\lambda \quad \text{and} \quad \|e_\lambda\|_{L^2(M)} = 1.$$

Let Σ be a d -dimensional submanifold and $d\mu$ a smooth, compactly supported measure on Σ . It is well-known (e.g. proved by Zelditch in [15] in far greater generality) that

$$\int_{\Sigma} e_\lambda d\mu = O(\lambda^{\frac{n-d-1}{2}}).$$

We show this bound improves to $o(\lambda^{\frac{n-d-1}{2}})$ provided the set of looping directions,

$$\mathcal{L}_\Sigma = \{(x, \xi) \in SN^*\Sigma : \Phi_t(x, \xi) \in SN^*\Sigma \text{ for some } t > 0\}$$

has measure zero as a subset of $SN^*\Sigma$, where here Φ_t is the geodesic flow on the cosphere bundle S^*M and $SN^*\Sigma$ is the unit conormal bundle over Σ .

1. Introduction.

In what follows, (M, g) will denote a compact, boundaryless, n -dimensional Riemannian manifold. Let Δ_g denote the Laplace-Beltrami operator and e_λ an L^2 -normalized eigenfunction of Δ_g on M , i.e.

$$-\Delta_g e_\lambda = \lambda^2 e_\lambda \quad \text{and} \quad \|e_\lambda\|_{L^2(M)} = 1.$$

In [13], Sogge and Zelditch investigate which manifolds have a sequence of eigenfunctions e_λ with $\lambda \rightarrow \infty$ which saturate the bound

$$\|e_\lambda\|_{L^\infty(M)} = O(\lambda^{\frac{n-1}{2}}).$$

They show that the bound above is necessarily $o(\lambda^{\frac{n-1}{2}})$ if at each x , the set of looping directions through x ,

$$\mathcal{L}_x = \{\xi \in S_x^*M : \Phi_t(x, \xi) \in S_x^*M \text{ for some } t > 0\}$$

has measure zero¹ as a subset of S_x^*M for each $x \in M$. Here, Φ_t denotes the geodesic flow on the unit cosphere bundle S^*M after time t . The hypotheses were later weakened by Sogge, Toth, and Zelditch in [10], where they showed

$$\|e_\lambda\|_{L^\infty(M)} = o(\lambda^{\frac{n-1}{2}})$$

provided the set of *recurrent* directions at x has measure zero for each $x \in M$.

¹Let $\psi_j : U_j \subset \mathbb{R}^n \rightarrow M$ be coordinate charts of a general manifold M . We say a set $E \subset M$ has measure zero if the preimage $\psi_j^{-1}(E)$ has Lebesgue measure 0 in \mathbb{R}^n for each chart ψ_j . Sets of Lebesgue measure zero are preserved under transition maps, ensuring this definition is intrinsic to the C^∞ structure of M .

We are interested in extending the result in [13] to integrals of eigenfunctions over submanifolds. Let Σ be a submanifold of dimension d with $d < n$ and a measure $d\mu(x) = h(x)d\sigma(x)$ where $d\sigma$ is the surface measure on Σ and h is a smooth function supported on a compact subset of Σ . In his 1992 paper [15], Zelditch proves, among other things, a Weyl law- type bound

$$(1.1) \quad \sum_{\lambda_j \leq \lambda} \left| \int_{\Sigma} e_j d\mu \right|^2 \sim \lambda^{n-d} + O(\lambda^{n-d-1})$$

from which follows

$$(1.2) \quad \int_{\Sigma} e_{\lambda} d\mu = O(\lambda^{\frac{n-d-1}{2}}).$$

Though (1.2) is already well known, we will give a direct proof which will be illustrative for our main argument.

Theorem 1.1. *Let Σ be a d -dimensional submanifold with $0 \leq d < n$, and $d\mu(x) = h(x)d\sigma(x)$ where h is a smooth, real valued function supported on a compact neighborhood in Σ . Then, (1.2) holds.*

We let $SN^*\Sigma$ denote the unit conormal bundle over Σ . We define the set of looping directions through Σ by

$$\mathcal{L}_{\Sigma} = \{(x, \xi) \in SN^*\Sigma : \Phi_t(x, \xi) \in SN^*\Sigma \text{ for some } t > 0\}.$$

Our main result shows the bound (1.2) cannot be saturated whenever the set of looping directions through Σ has measure zero.

Theorem 1.2. *Assume the hypotheses of Theorem 1.1 and additionally that \mathcal{L}_{Σ} has measure zero as a subset of $SN^*\Sigma$. Then,*

$$\int_{\Sigma} e_{\lambda} d\mu = o(\lambda^{\frac{n-d-1}{2}}).$$

The argument for Theorem 1.2 is modeled after Sogge and Zelditch's arguments in [13]. In fact if $d = 0$ we obtain the first part of [13, Theorem 1.2].

We expect the bound (1.2) to be saturated in the case $M = S^n$, since $\mathcal{L}_{\Sigma} = SN^*\Sigma$ always. The spectrum of $-\Delta_g$ on S^n consists of λ_j^2 where

$$\lambda_j = \sqrt{j(j+n-1)} \quad \text{for } j = 0, 1, 2, \dots$$

(see [9]). For each λ_j we select an eigenfunction e_j maximizing $|\int_{\Sigma} e_j d\mu|$. By Zelditch's Weyl law type bound (1.1), there exists an increasing sequence of λ with $\lambda \rightarrow \infty$ for which

$$\sum_{\lambda_j \in [\lambda, \lambda+1]} \left| \int_{\Sigma} e_j d\mu \right|^2 \gtrsim \lambda^{n-d-1}.$$

Since the gaps $\lambda_j - \lambda_{j-1}$ approach a constant width of 1 as $j \rightarrow \infty$, we may pick a subsequence of λ 's so that only one λ_j falls in each band $[\lambda, \lambda+1]$. Hence,

$$\left| \int_{\Sigma} e_j d\mu \right| \gtrsim \lambda_j^{\frac{n-d-1}{2}}$$

for some subsequence of λ_j .

It is worth remarking that there are some cases where the hypotheses of Theorem 1.2 are naturally fulfilled and we obtain an improvement over (1.2). Chen and

Sogge [2] proved that if M is 2-dimensional and has negative sectional curvature, and Σ is a geodesic in M ,

$$\int_{\Sigma} e_{\lambda} d\mu = o(1).$$

They consider a lift $\tilde{\Sigma}$ of Σ to the universal cover of M . Using the Gauss-Bonnet theorem, they show for each non-identity deck transformation α , there is at most one geodesic which intersects both $\tilde{\Sigma}$ and $\alpha(\tilde{\Sigma})$ perpendicularly. Since there are only countably many deck transformations, \mathcal{L}_{Σ} is at most a countable subset of $SN^*\Sigma$ and so satisfies the hypotheses of Theorem 1.2. This result was extended to a larger class of curves in [14] which similarly have countable \mathcal{L}_{Σ} .

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2. Proof of Theorem 1.1.

Theorem 1.1 is a consequence of this stronger result.

Proposition 2.1. *Given the hypotheses of Theorem 1.1, we have*

$$\sum_{\lambda_j \in [\lambda, \lambda+1]} \left| \int_{\Sigma} e_{\lambda} d\mu \right|^2 \leq C\lambda^{n-d-1}.$$

We lay out some local coordinates which we will use repeatedly. Fix $p \in \Sigma$, and consider local coordinates $x = (x_1, \dots, x_n) = (x', \bar{x})$ centered about p , where x' denotes the first d coordinates and \bar{x} the remaining $n-d$ coordinates. We let $(x', 0)$ parametrize Σ on a neighborhood of p in such a way that dx' agrees with the surface measure on Σ . Let g denote the metric tensor with respect to our local coordinates. We require

$$g = \begin{bmatrix} * & 0 \\ 0 & I \end{bmatrix} \quad \text{wherever } \bar{x} = 0,$$

where I here is the $(n-d) \times (n-d)$ identity matrix. This is ensured after inductively picking smooth sections $v_j(x')$ of $SN\Sigma$ for $j = d+1, \dots, n$ with $\langle v_i, v_j \rangle = \delta_{ij}$, and then using

$$(2.1) \quad (x_1, \dots, x_n) \mapsto \exp(x_{d+1}v_{d+1}(x') + \dots + x_nv_n(x'))$$

as our coordinate map.

Now we prove Proposition 2.1. For simplicity, we assume without loss of generality that $d\mu$ is a real measure. We set² $\chi \in C^\infty(\mathbb{R})$ with $\chi \geq 0$ and $\hat{\chi}$ supported on a small neighborhood of 0. It suffices to show

$$\sum_j \chi(\lambda_j - \lambda) \left| \int_{\Sigma} e_j d\mu \right|^2 \leq C\lambda^{n-d-1}.$$

²This reduction is standard and appears in [13], [2], proofs of the sharp Weyl law as presented in [9] and [8], and in many other similar problems.

By Fourier inversion, we write the left hand side as

$$\begin{aligned}
 & \sum_j \int_{\Sigma} \int_{\Sigma} \chi(\lambda_j - \lambda) e_j(x) \overline{e_j(y)} d\mu(x) d\mu(y) \\
 &= \frac{1}{2\pi} \sum_j \int_{-\infty}^{\infty} \int_{\Sigma} \int_{\Sigma} \hat{\chi}(t) e^{-it\lambda} e^{it\lambda_j} e_j(x) \overline{e_j(y)} d\mu(x) d\mu(y) dt \\
 (2.2) \quad &= \frac{1}{2\pi} \int_{-\infty}^{\infty} \int_{\Sigma} \int_{\Sigma} \hat{\chi}(t) e^{-it\lambda} e^{it\sqrt{-\Delta_g}}(x, y) d\mu(x) d\mu(y) dt
 \end{aligned}$$

where $e^{it\sqrt{-\Delta_g}}$ is the half wave operator with kernel

$$e^{it\sqrt{-\Delta_g}}(x, y) = \sum_j e^{it\lambda_j} e_j(x) \overline{e_j(y)}.$$

Using the coordinates $x = (x', \bar{x})$ as in (2.1), the last line of (2.2) is written

$$(2.3) \quad = \frac{1}{2\pi} \int_{-\infty}^{\infty} \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} \hat{\chi}(t) e^{-it\lambda} e^{it\sqrt{-\Delta_g}}(x', y') h(x') h(y') dx' dy' dt$$

where h is a smooth function on \mathbb{R}^d such that $d\mu(x) = h(x') dx'$, and where by abuse of notation x' is taken to mean $(x', 0)$ where appropriate. We now use Hörmander's parametrix as presented in [8], i.e

$$e^{it\sqrt{-\Delta_g}}(x, y) = \frac{1}{(2\pi)^n} \int_{\mathbb{R}^n} e^{i(\varphi(x, y, \xi) + tp(y, \xi))} q(t, x, y, \xi) d\xi$$

modulo a smooth kernel, where

$$p(y, \xi) = \sqrt{\sum_{j,k} g^{jk}(y) \xi_j \xi_k}$$

is the principal symbol of $\sqrt{-\Delta_g}$ and φ is smooth for $|\xi| > 0$, homogeneous of degree 1 in ξ , and satisfies

$$(2.4) \quad |\partial_{\xi}^{\alpha}(\varphi(x, y, \xi) - \langle x - y, \xi \rangle)| \leq C_{\alpha} |x - y|^2 |\xi|^{1-|\alpha|}$$

for multiindices $\alpha \geq 0$ and for x and y sufficiently close. Moreover, q satisfies bounds

$$(2.5) \quad |\partial_{\xi}^{\alpha} \partial_{t,x,y}^{\beta} q(t, x, y, \xi)| \leq C_{\alpha,\beta} (1 + |\xi|)^{-|\alpha|},$$

and where for $t \in \text{supp } \hat{\chi}$, q is supported on a small neighborhood of $x = y$. Hence, we write (2.3) as

$$\begin{aligned}
 &= \frac{1}{(2\pi)^{n+1}} \int_{-\infty}^{\infty} \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} \int_{\mathbb{R}^n} e^{i(\varphi(x', y', \xi) + tp(y', \xi) - t\lambda)} \hat{\chi}(t) q(t, x', y', \xi) h(x') h(y') \\
 &\quad d\xi dx' dy' dt,
 \end{aligned}$$

and after making a change of coordinates $\xi \mapsto \lambda \xi$ is

$$\begin{aligned}
 &= \frac{\lambda^n}{(2\pi)^{n+1}} \int_{-\infty}^{\infty} \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} \int_{\mathbb{R}^n} e^{i\lambda(\varphi(x', y', \xi) + t(p(y', \xi) - 1))} \hat{\chi}(t) q(t, x', y', \lambda \xi) h(x') h(y') \\
 &\quad d\xi dx' dy' dt.
 \end{aligned}$$

We introduce a function $\beta \in C_0^{\infty}(\mathbb{R})$ with $\beta \equiv 1$ near 0 and support contained in a small neighborhood of 0, and cut the integral into $\beta(\log p(y', \xi))$ and $1 -$

$\beta(\log p(y', \xi))$ parts. $|p(y', \xi) - 1|$ is bounded away from 0 on the support of $1 - \beta(\log p(y', \xi))$, so integrating by parts in t yields

$$\begin{aligned} & \frac{\lambda^n}{(2\pi)^{n+1}} \int_{-\infty}^{\infty} \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} \int_{\mathbb{R}^n} e^{i\lambda(\varphi(x', y', \xi) + t(p(y', \xi) - 1))} \\ & \quad (1 - \beta(\log p(y', \xi))) \hat{\chi}(t) q(t, x', y', \lambda\xi) h(x') h(y') d\xi dx' dy' dt. \\ & \quad = O(\lambda^{-N}) \end{aligned}$$

for each $N = 1, 2, \dots$. What is left to bound is the $\beta(\log p(y', \xi))$ part, i.e.

$$(2.6) \quad \lambda^n \int_{-\infty}^{\infty} \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} \int_{\mathbb{R}^n} e^{i\lambda\Phi(t, x', y', \xi)} a(\lambda; t, x', y', \xi) d\xi dx' dy' dt = O(\lambda^{n-d-1})$$

where we have set the amplitude

$$a(\lambda; t, x', y', \xi) = \frac{1}{(2\pi)^{n+1}} \beta(\log |\xi|) \hat{\chi}(t) q(t, x', y', \lambda\xi) h(x') h(y')$$

and the phase

$$\Phi(t, x', y', \xi) = \varphi(x', y', \xi) + t(p(y', \xi) - 1).$$

By (2.5) and since a has compact support in t, x', y' , and ξ , a and all of its derivatives are uniformly bounded in λ .

We are now in a position to apply stationary phase. Write $\xi = (\xi', \bar{\xi})$ and write $\bar{\xi} = r\omega$ in polar coordinates with $r \geq 0$ and $\omega \in S^{n-d-1}$. The integral in (2.6) is then written

$$\begin{aligned} & \lambda^n \int_{-\infty}^{\infty} \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} \int_{S^{n-d-1}} \int_0^{\infty} e^{i\lambda\Phi(t, x', y', \xi)} a(\lambda; t, x', y', \xi) \\ & \quad r^{n-d-1} dr d\omega d\xi' dx' dy' dt \end{aligned}$$

We will fix y' and ω and use the method of stationary phase in the remaining variables t, x', ξ' , and r (a total of $2d + 2$ dimensions). We assert that, for fixed y' and ω , there is a nondegenerate stationary point at $(t, x', \xi', r) = (0, y', 0, 1)$. $\Phi = 0$ at such a stationary point, and after perhaps shrinking the support of a we apply [8, Corollary 1.1.8] to write the left hand side of (2.6) as

$$\lambda^{n-d-1} \int_{\mathbb{R}^d} \int_{S^{n-d-1}} a(\lambda; y', \omega) dy' d\omega$$

for some amplitude $a(\lambda; y', \omega)$ uniformly bounded with respect to λ . (2.6) follows.

We have

$$\begin{aligned} \partial_t \Phi &= p(y', \xi) - 1 \\ \nabla_{x'} \Phi &= \nabla_{x'} \varphi(x', y', \xi) \\ \nabla_{\xi'} \Phi &= \nabla_{\xi'} \varphi(x', y', \xi) + t \nabla_{\xi'} p(y', \xi) \\ \partial_r \Phi &= \partial_r \varphi(x', y', \xi) + t \partial_r p(y', \xi). \end{aligned}$$

Note for fixed y' and ω , $(t, x', \xi', r) = (0, y', 0, 1)$ is a critical point of Φ . Now we compute the second derivatives at this point. We immediately see that $\partial_t^2 \Phi$, $\partial_t \nabla_{x'} \Phi$, $\nabla_{\xi'}^2 \Phi$, $\partial_r \nabla_{\xi'} \Phi$, and $\partial_r^2 \Phi$ all vanish. Moreover, $\partial_r \partial_r \Phi = 1$ since $p(y', \xi) = r$

where $\xi' = 0$. By our coordinates (2.1) and the fact that $[g^{ij}]_{i,j \leq d}$ is necessarily positive definite,

$$p(y', \xi) = \sqrt{\sum_{j,k} g^{jk} \xi_j \xi_k} = \sqrt{r^2 + \sum_{j,k \leq d} g^{jk} \xi'_j \xi'_k} \geq r = p(y', r\omega).$$

Hence, $\partial_t \nabla_{\xi'} \Phi = \nabla_{\xi'} p(y', \xi) = 0$. Since φ is homogeneous of degree 1 in ξ , at $\xi' = 0$ and $t = 0$,

$$\nabla_{x'} \partial_r \Phi = \nabla_{x'} \partial_r \varphi(x', y', \xi) = \nabla_{x'} \varphi(x', y', \omega) = 0$$

since $\varphi(x', y', \omega) = O(|x' - y'|^2)$ by (2.4) and the fact that $\langle x' - y', \omega \rangle = 0$. Finally by (2.4),

$$\nabla_{\xi'} \varphi(x', y', \xi' + \omega) = x' + O(|x' - y'|^2)$$

whence at the critical point

$$\nabla_{x'} \nabla_{\xi'} \Phi = I,$$

the $d \times d$ identity matrix. In summary, the Hessian matrix of Φ at the critical point $(t, x', \xi', r) = (0, y', 0, 1)$ is

$$\nabla_{t, x', \xi', r}^2 \Phi = \begin{bmatrix} 0 & 0 & 0 & 1 \\ 0 & * & I & 0 \\ 0 & I & 0 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix}$$

which has full rank.

3. Microlocal tools.

The hypotheses on the looping directions in Theorem 1.2 ensure that the wavefront sets of μ and $e^{it\sqrt{-\Delta_g}}\mu$ have minimal intersection for any given t . We can then use pseudodifferential operators to break μ into two parts, the first whose wavefront set is disjoint from that of $e^{it\sqrt{-\Delta_g}}\mu$ and the second which contributes a small, controllable term to the bound. The following propositions will allow us to handle these cases, respectively.

Proposition 3.1. *Let u and v be distributions on M for which*

$$\text{WF}(u) \cap \text{WF}(v) = \emptyset.$$

Then

$$t \mapsto \int_M e^{it\sqrt{-\Delta_g}} u(x) \overline{v(x)} dx$$

is a smooth function of t on some neighborhood of 0.

Proof. Using a partition of unity, we write

$$I = \sum_j A_j$$

modulo a smoothing operator where $A_j \in \Psi_{\text{cl}}^0(M)$ with essential supports in small conic neighborhoods. We then write, formally,

$$\int e^{it\sqrt{-\Delta_g}} u(x) \overline{v(x)} dx = \sum_{j,k} \int A_j e^{it\sqrt{-\Delta_g}} u(x) \overline{A_k v(x)} dx.$$

We are done if for each i and j ,

$$(3.1) \quad \int_M A_j e^{it\sqrt{-\Delta_g}} u(x) \overline{A_k v(x)} dx \quad \text{is smooth for } |t| \ll 1.$$

If the essential supports of A_j and A_k are disjoint, then $A_j^* A_k$ is a smoothing operator, and so $A_j^* A_k v$ is a smooth function and the contributing term

$$\int u(x) e^{it\sqrt{-\Delta_g}} \overline{A_j^* A_k v(x)} dx$$

is smooth in t . Assume the essential support of A_j are small enough so that for each j there exists a small conic neighborhood Γ_j which fully contains the essential support of A_k if it intersects the essential support of A_j . We in turn take Γ_j small enough so that for each j , $\overline{\Gamma_j}$ either does not intersect $\text{WF}(u)$ or does not intersect $\text{WF}(v)$. In the latter case, $A_k v$ is smooth and we have (3.1) as before. In the former case,

$$\overline{\Gamma_j} \cap \text{WF}(e^{it\sqrt{-\Delta_g}} u) = \emptyset \quad \text{for } |t| \ll 1$$

since both sets above are closed and the geodesic flow is continuous. Then $A_j e^{it\sqrt{-\Delta_g}} u(x)$ is smooth as a function of t and x , and we have (3.1). \square

The second piece of our argument requires the following generalization of Proposition 2.1, modeled after [9, Lemma 5.2.2]. In the proof we will come to a point where it seems like we may have to perform a stationary phase argument involving an eight-by-eight Hessian matrix. Instead, we appeal to Proposition 5.1 in the appendix to break the argument into two steps involving two four-by-four Hessian matrices.

Proposition 3.2. *Let $b(x, \xi)$ be smooth for $\xi \neq 0$ and homogeneous of degree 0 in the ξ variable. We define $b \in \Psi_{cl}^0(M)$ by*

$$b(x, D)f(x) = \frac{1}{(2\pi)^n} \int_{\mathbb{R}^n} \int_{\mathbb{R}^n} e^{i\langle x-y, \xi \rangle} b(x, \xi) dy d\xi$$

for x, y , and ξ expressed locally according to our coordinates (2.1). Then,

$$\begin{aligned} & \sum_{\lambda_j \in [\lambda, \lambda+1]} \left| \int_{\Sigma} b e_j(x) d\mu(x) \right|^2 \\ & \leq C \left(\int_{\mathbb{R}^d} \int_{S^{n-d-1}} |b(x', \omega)|^2 h(x')^2 d\omega dx' \right) \lambda^{n-d-1} + C_b \lambda^{n-d-2} \end{aligned}$$

where C is a constant independent of b and λ and C_b is a constant independent of λ but which depends on b .

Proof. We may by a partition of unity assume that $b(x, D)$ has small x -support. Let χ be as in the proof of Proposition 2.1. It suffices to show

$$\begin{aligned} & \sum_j \int_{\Sigma} \int_{\Sigma} \chi(\lambda_j - \lambda) b(x, D) e_j(x) \overline{b(y, D) e_j(y)} d\mu(x) d\mu(y) \\ & \sim \left(\int_{\mathbb{R}^d} \int_{S^{n-d-1}} |b(y', \omega)|^2 h(y')^2 d\omega dy' \right) \lambda^{n-d-1} + O_b(\lambda^{n-d-2}). \end{aligned}$$

Using the same reduction as in Proposition 2.1, the left hand side is

$$(3.2) \quad \frac{1}{2\pi} \int_{-\infty}^{\infty} \int_{\Sigma} \int_{\Sigma} \hat{\chi}(t) e^{-it\lambda} b e^{it\sqrt{-\Delta_g}} b^*(x, y) d\mu(x) d\mu(y) dt.$$

Set $\beta \in C_0^\infty(\mathbb{R})$ with small support and where $\beta \equiv 1$ near 0. Then,

$$(3.3) \quad \begin{aligned} & \int_{\mathbb{R}^d} b(x', D) f(x') h(x') dx' \\ &= \frac{\lambda^n}{(2\pi)^n} \int_{\mathbb{R}^n} \int_{\mathbb{R}^n} \int_{\mathbb{R}^d} e^{i\lambda\langle x' - w, \eta \rangle} b(x', \eta) f(w) h(x') dx' dw d\eta \\ &= \frac{\lambda^n}{(2\pi)^n} \int_{\mathbb{R}^n} \int_{\mathbb{R}^n} \int_{\mathbb{R}^d} e^{i\lambda\langle x' - w, \eta \rangle} \beta(\log |\eta|) b(x', \eta) f(w) h(x') dx' dw d\eta \\ & \quad + O(\lambda^{-N}), \end{aligned}$$

where the second line is obtained by a change of variables $\eta \mapsto \lambda\eta$, and the third line is obtained after multiplying in the cutoff $\beta(\log |\eta|)$ and bounding the discrepancy by $O(\lambda^{-N})$ by integrating by parts in x' . Additionally,

$$(3.4) \quad \begin{aligned} b^*(z, D) d\mu(z) &= \frac{1}{(2\pi)^n} \int_{\mathbb{R}^n} \int_{\mathbb{R}^d} e^{i\langle z - y', \zeta \rangle} b(y', \zeta) h(y') dy' d\zeta \\ &= \frac{\lambda^n}{(2\pi)^n} \int_{\mathbb{R}^n} \int_{\mathbb{R}^d} e^{i\lambda\langle z - y', \zeta \rangle} b(y', \zeta) h(y') dy' d\zeta \\ &= \frac{\lambda^n}{(2\pi)^n} \int_{\mathbb{R}^n} \int_{\mathbb{R}^d} e^{i\lambda\langle z - y', \zeta \rangle} \beta(\log |\zeta|) b(y', \zeta) h(y') dy' d\zeta + O(\lambda^{-N}) \\ &= \frac{\lambda^n}{(2\pi)^n} \int_{\mathbb{R}^n} \int_{\mathbb{R}^d} e^{i\lambda\langle z - y', \zeta \rangle} \beta(\log |\zeta|) \beta(|z - y'|) b(y', \zeta) h(y') dy' d\zeta \\ & \quad + O(\lambda^{-N}), \end{aligned}$$

where the second and third lines are obtained similarly as before and the fourth line is obtained after multiplying by $\beta(\log |z - y'|)$ and integrating the remainder by parts in ζ . Using Hörmander's parametrix,

$$(3.5) \quad \begin{aligned} & \frac{1}{2\pi} \int_{-\infty}^{\infty} \hat{\chi}(t) e^{-it\lambda} e^{it\sqrt{-\Delta_g}}(w, z) dt \\ &= \frac{1}{(2\pi)^{n+1}} \int_{-\infty}^{\infty} \int_{\mathbb{R}^n} e^{i(\varphi(w, z, \xi) + t p(z, \xi) - t\lambda)} \hat{\chi}(t) q(t, w, z, \xi) d\xi dt \\ &= \frac{\lambda^n}{(2\pi)^{n+1}} \int_{-\infty}^{\infty} \int_{\mathbb{R}^n} e^{i\lambda(\varphi(w, z, \xi) + t(p(z, \xi) - 1))} \hat{\chi}(t) q(t, w, z, \lambda\xi) d\xi dt \\ &= \frac{\lambda^n}{(2\pi)^{n+1}} \int_{-\infty}^{\infty} \int_{\mathbb{R}^n} e^{i\lambda(\varphi(w, z, \xi) + t(p(z, \xi) - 1))} \beta(\log p(z, \xi)) \hat{\chi}(t) q(t, w, z, \lambda\xi) d\xi dt \\ & \quad + O(\lambda^{-N}). \end{aligned}$$

Here the third line comes from a change of coordinates $\xi \mapsto \lambda\xi$. The fourth line follows after applying the cutoff $\beta(\log p(z, \xi))$ and integrating the discrepancy by parts in t . Combining (3.3), (3.4), and (3.5), we write (3.2) as

$$(3.6) \quad \begin{aligned} & \lambda^{3n} \int \dots \int e^{i\Phi(t, x', y', w, z, \eta, \zeta, \xi)} a(\lambda; t, x', y', w, z, \eta, \zeta, \xi) \\ & \quad dx' dy' dw dz d\eta d\zeta d\xi + O(\lambda^{-N}) \end{aligned}$$

with amplitude

$$a(\lambda; t, x', y', w, z, \eta, \zeta, \xi) = \frac{1}{(2\pi)^{3n+1}} \hat{\chi}(t) q(t, w, z, \lambda \xi) \beta(\log p(z, \xi)) \beta(\log |\eta|) \beta(\log |\zeta|) \beta(|z - y'|) b(x', \eta) b(y', \zeta) h(x') h(y')$$

and phase

$$\Phi(t, x', y', w, z, \eta, \zeta, \xi) = \langle x' - w, \eta \rangle + \varphi(w, z, \xi) + t(p(z, \xi) - 1) + \langle z - y', \zeta \rangle.$$

We pause here to make a couple observations. First, a has compact support in all variables, support which we may adjust to be smaller by controlling the supports of $\hat{\chi}$, β , b , and the support of q near the diagonal. Second, the derivatives of a are bounded independently of $\lambda \geq 1$. We are now in a position to use the method of stationary phase – not in all variables at once, though. First, we fix t , x' , y' and ξ , and use stationary phase in w , z , η , and ζ . We have

$$\begin{aligned} \nabla_w \Phi &= -\eta + \nabla_w \varphi(w, z, \xi) \\ \nabla_z \Phi &= \nabla_z \varphi(w, z, \xi) + t \nabla_z p(z, \xi) + \zeta \\ \nabla_\eta \Phi &= x' - w \\ \nabla_\zeta \Phi &= z - y' \end{aligned}$$

which all simultaneously vanishes if and only if

$$(3.7) \quad (w, z, \eta, \zeta) = (x', y', \nabla_x \varphi(x', y', \xi), -\nabla_y \varphi(x', y', \xi) - t \nabla_y p(y', \xi)).$$

At such a critical point we have the Hessian matrix

$$\nabla_{w,z,\eta,\zeta}^2 \Phi = \begin{bmatrix} * & * & -I & 0 \\ * & * & 0 & I \\ -I & 0 & 0 & 0 \\ 0 & I & 0 & 0 \end{bmatrix},$$

which has determinant -1 . By Proposition 5.1 in the appendix, (3.6) is equal to complex constant times

$$\begin{aligned} & \lambda^n \int_{-\infty}^{\infty} \int_{\mathbb{R}^n} \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} e^{i\lambda \Phi(t, x', y', \xi)} a(\lambda; t, x', y', \xi) dx' dy' d\xi dt \\ & + \lambda^{n-1} \int_{-\infty}^{\infty} \int_{\mathbb{R}^n} \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} e^{i\lambda \Phi(t, x', y', \xi)} R(\lambda; t, x', y', \xi) dx' dy' d\xi dt + O(\lambda^{-N}) \end{aligned}$$

where we have phase

$$\Phi(t, x', y', \xi) = \varphi(x', y', \xi) + t(p(y', \xi) - 1),$$

amplitude

$$a(\lambda; t, x', y', \xi) = a(\lambda; t, x', y', w, z, \eta, \zeta, \xi)$$

with w , z , η , and ζ subject to the constraints (3.7), and where R is a compactly supported smooth function in t , x' , y' , and ξ whose derivatives are bounded uniformly with respect to λ . Our phase function matches that in the proof of Proposition 2.1, and so we repeat that argument – we write $\bar{\xi} = r\omega$ and fix y' and ω . We obtain unique nondegenerate stationary points

$$(t, x', \xi', r) = (0, y', 0, 1).$$

Now,

$$a(\lambda; 0, y', y', \omega) \sim |b(y', \omega)|^2 h(y')^2.$$

Hence, we have

$$\begin{aligned} & \lambda^n \int_{-\infty}^{\infty} \int_{\mathbb{R}^n} \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} e^{i\lambda\Phi(t,x',y',\xi)} a(\lambda; t, x', y', \xi) dx' dy' d\xi' dt \\ & \sim \lambda^{n-d-1} \left(\int_{\mathbb{R}^d} \int_{S^{n-d-1}} b(y', \omega)^2 h(y')^2 d\omega dy' \right) + O(\lambda^{n-d-2}) \end{aligned}$$

by Proposition 5.1 as desired. The same argument applied to the remainder term gives

$$\lambda^{n-1} \int_{-\infty}^{\infty} \int_{\mathbb{R}^n} \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} e^{i\lambda\Phi(t,x',y',\xi)} R(\lambda; t, x', y', \xi) dx' dy' d\xi' dt = O(\lambda^{n-d-2})$$

as desired. \square

4. Proof of Theorem 1.2.

Theorem 1.2 follows from the following stronger statement.

Proposition 4.1. *Given the hypotheses of Theorem 1.2, we have*

$$\sum_{\lambda_j \in [\lambda, \lambda+\varepsilon]} \left| \int_{\Sigma} e_{\lambda} d\mu \right|^2 \leq C\varepsilon\lambda^{n-d-1} + C_{\varepsilon}\lambda^{n-d-2},$$

where C is a constant independent of ε and λ , and C_{ε} is a constant depending on ε but not λ .

We make a few convenient assumptions. First, we take the injectivity radius of M to be at least 1 by scaling the metric g . Second, we assume the support of $d\mu$ has diameter less than $1/2$ by a partition of unity. We reserve the right to further scale the metric g and restrict the support of $d\mu$ as needed, finitely many times.

As before, we set $\chi \in C^{\infty}(\mathbb{R})$ with $\chi(0) = 1$, $\chi \geq 0$, and $\text{supp } \hat{\chi} \subset [-1, 1]$. It suffices to show

$$\sum_j \chi(T(\lambda_j - \lambda)) \left| \int_{\Sigma} e_{\lambda} d\mu \right|^2 \leq CT^{-1}\lambda^{n-d-1} + C_T\lambda^{n-d-2}$$

for $T > 1$. Similar to the reduction in the proof of Proposition 2.1, we have

$$\begin{aligned} & \sum_j \int_{\Sigma} \int_{\Sigma} \chi(T(\lambda_j - \lambda)) e_j(x) \overline{e_j(y)} d\mu(x) d\mu(y) \\ &= \frac{1}{2\pi} \sum_j \int_{-\infty}^{\infty} \int_{\Sigma} \int_{\Sigma} \hat{\chi}(t) e^{itT(\lambda_j - \lambda)} e_j(x) \overline{e_j(y)} d\mu(x) d\mu(y) dt \\ &= \frac{1}{2\pi T} \sum_j \int_{-\infty}^{\infty} \int_{\Sigma} \int_{\Sigma} \hat{\chi}(t/T) e^{-it\lambda} e^{it\lambda_j} e_j(x) \overline{e_j(y)} d\mu(x) d\mu(y) dt \\ &= \frac{1}{2\pi T} \int_{-\infty}^{\infty} \int_{\Sigma} \int_{\Sigma} \hat{\chi}(t/T) e^{-it\lambda} e^{it\sqrt{-\Delta_g}}(x, y) d\mu(x) d\mu(y) dt. \end{aligned}$$

Hence, it suffices to show

$$\begin{aligned} (4.1) \quad & \left| \int_{-\infty}^{\infty} \int_{\Sigma} \int_{\Sigma} \hat{\chi}(t/T) e^{-it\lambda} e^{it\sqrt{-\Delta_g}}(x, y) d\mu(x) d\mu(y) dt \right| \\ & \leq C\lambda^{n-d-1} + C_T\lambda^{n-d-2}. \end{aligned}$$

Set $\beta \in C_0^\infty(\mathbb{R})$ with $\beta(t) \equiv 1$ near 0 and β . We cut the integral in (4.1) into $\beta(t)$ and $1 - \beta(t)$ parts. Since $\beta(t)\hat{\chi}(t/T)$ and its derivatives are all bounded independently of $T \geq 1$,

$$\left| \int_{-\infty}^{\infty} \int_{\Sigma} \int_{\Sigma} \beta(t) \hat{\chi}(t/T) e^{-it\lambda} e^{it\sqrt{-\Delta_g}}(x, y) d\mu(x) d\mu(y) dt \right| \leq C\lambda^{n-d-1}$$

by the proof of Proposition 2.1. Hence, it suffices to show

$$(4.2) \quad \left| \int_{-\infty}^{\infty} \int_{\Sigma} \int_{\Sigma} (1 - \beta(t)) \hat{\chi}(t/T) e^{-it\lambda} e^{it\sqrt{-\Delta_g}}(x, y) d\mu(x) d\mu(y) dt \right| \leq C\lambda^{n-d-1} + C_T \lambda^{n-d-2}.$$

Here we shrink the support of μ so that $\beta(d_g(x, y)) = 1$ for $x, y \in \text{supp } \mu$. We now state and prove a useful decomposition based off of those in [13], [10], and Chapter 5 of [9]. We let $\mathcal{L}_{\Sigma}(\text{supp } \mu, T)$ denote the subset of \mathcal{L}_{Σ} relevant to the support of μ and the timespan $[1, T]$, specifically

$$\mathcal{L}_{\Sigma}(\text{supp } \mu, T) = \{(x, \xi) \in SN^*\Sigma : \Phi_t(x, \xi) = (y, \eta) \in SN^*\Sigma \text{ for some } t \in [1, T] \text{ and where } x, y \in \text{supp } \mu\}.$$

Lemma 4.2. *Fix $T > 1$ and $\varepsilon > 0$. There exist $b, B \in \Psi_{cl}^0(M)$ supported on a neighborhood of $\text{supp } \mu$ with the following properties.*

- (1) $b(x, D) + B(x, D) = I$ modulo a smoothing operator on $\text{supp } \mu$.
- (2) Using coordinates (2.1),

$$\int_{\mathbb{R}^d} \int_{S^{n-d-1}} |b(x', \omega)|^2 d\omega dx' < \varepsilon,$$

where $b(x, \xi)$ is the principal symbol of $b(x, D)$.

- (3) The essential support of $B(x, D)$ contains no elements of $\mathcal{L}_{\Sigma}(\text{supp } \mu, T)$.

Proof. As shorthand, we write

$$SN_{\text{supp } \mu}^*\Sigma = \{(x, \xi) \in SN^*\Sigma : x \in \text{supp } \mu\}.$$

We first argue that $\mathcal{L}_{\Sigma}(\text{supp } \mu, T)$ is closed for each $T > 1$. However, $\mathcal{L}_{\Sigma}(\text{supp } \mu, T)$ is the projection of the set

$$(4.3) \quad \{(t, x, \xi) \in [1, T] \times SN_{\text{supp } \mu}^*\Sigma : \Phi_t(x, \xi) \in SN_{\text{supp } \mu}^*\Sigma\}$$

onto $SN_{\text{supp } \mu}^*\Sigma$, and since $[1, T]$ is compact it suffices to show that (4.3) is closed. However, (4.3) is the intersection of $[1, T] \times SN_{\text{supp } \mu}^*\Sigma$ with the preimage of $SN_{\text{supp } \mu}^*\Sigma$ under the continuous map

$$(t, x, \xi) \mapsto \Phi_t(x, \xi).$$

Since $SN_{\text{supp } \mu}^*\Sigma$ is closed, (4.3) is closed.

Since $\mathcal{L}_{\Sigma}(\text{supp } \mu, T)$ is closed and has measure zero, there is $\tilde{b} \in C^\infty(SN^*\Sigma)$ supported on a neighborhood of $SN_{\text{supp } \mu}^*\Sigma$ with $0 \leq \tilde{b}(x, \xi) \leq 1$, $\tilde{b}(x, \xi) \equiv 1$ on an open neighborhood of $\mathcal{L}_{\Sigma}(\text{supp } \mu, T)$, and

$$\int_{\mathbb{R}^d} \int_{S^{n-d-1}} |b(x', \omega)|^2 d\omega dx' < \varepsilon.$$

We use the coordinates in (2.1) and define

$$b(x, D)f(x) = \frac{1}{(2\pi)^n} \int_{\mathbb{R}^n} \int_{\mathbb{R}^n} e^{i\langle x-y, \xi \rangle} \tilde{b}(x, \xi/|\xi|) f(y) dy d\xi,$$

hence (2). We set $\psi \in C_0^\infty(\Sigma)$ to be a cutoff function supported on a neighborhood of $\text{supp } \mu$ with $\psi \equiv 1$ on $\text{supp } \mu$. Defining

$$B(x, D)f(x) = \frac{1}{(2\pi)^n} \int_{\mathbb{R}^n} \int_{\mathbb{R}^n} e^{i\langle x-y, \xi \rangle} \psi(x) (1 - \tilde{b}(x, \xi/|\xi|)) f(y) dy d\xi$$

yields (1). We have (3) since the support of $1 - \tilde{b}(x, \xi)$ contains no elements of $\mathcal{L}_\Sigma(\text{supp } \mu, T)$. \square

Returning to the proof of Proposition 4.1, let X_T denote the function with

$$\hat{X}_T(t) = (1 - \beta(t))\hat{\chi}(t/T),$$

and let $X_{T,\lambda}$ denote the operator with kernel

$$X_{T,\lambda}(x, y) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \hat{X}_T(t) e^{-it\lambda} e^{it\sqrt{-\Delta_g}}(x, y) dt.$$

We use part (1) of Lemma 4.2 to write the integral in (4.2) as

$$\begin{aligned} \int_{\Sigma} \int_{\Sigma} X_{T,\lambda}(x, y) d\mu(y) d\mu(x) &= \int_{\Sigma} \int_{\Sigma} B X_{T,\lambda} B^*(x, y) d\mu(y) d\mu(x) \\ &\quad + \int_{\Sigma} \int_{\Sigma} B X_{T,\lambda} b^*(x, y) d\mu(y) d\mu(x) \\ &\quad + \int_{\Sigma} \int_{\Sigma} b X_{T,\lambda} B^*(x, y) d\mu(y) d\mu(x) \\ &\quad + \int_{\Sigma} \int_{\Sigma} b X_{T,\lambda} b^*(x, y) d\mu(y) d\mu(x). \end{aligned}$$

We claim the first three terms on the right are $O_T(\lambda^{-N})$ for $N = 1, 2, \dots$. We will only prove this for the first term – the argument is the same for the second term and the bound for the third term follows since $X_{T,\lambda}$ is self-adjoint. Interpreting μ as a distribution on M , we write formally

$$\begin{aligned} \int_{\Sigma} \int_{\Sigma} B X_{T,\lambda} B^*(x, y) d\mu(y) d\mu(x) &= \int_M \int_M X_{T,\lambda}(x, y) B^* \mu(y) \overline{B^* \mu(x)} dx dy \\ (4.4) \quad &= \frac{1}{2\pi} \int_{-\infty}^{\infty} \hat{X}_T(t) e^{-it\lambda} \int_M e^{it\sqrt{-\Delta_g}}(B^* \mu)(x) \overline{B^* \mu(x)} dx dt \end{aligned}$$

Once we show

$$(4.5) \quad \text{WF}(e^{it\sqrt{-\Delta_g}} B^* \mu) \cap B^* \mu = \emptyset \quad \text{for all } t \in \text{supp } \hat{X}_T,$$

the integral over M will be smooth in t by Proposition 3.1. Integration by parts in t then gives the desired bound of $O_T(\lambda^{-N})$. To prove (4.5), suppose $(x, \xi) \in \text{WF}(B^* \mu)$. By part (3) of Lemma 4.2, $\Phi_t(x, \xi)$ is not in $SN_{\text{supp } \mu}^* \Sigma$ for any $1 \leq |t| \leq T$. By propagation or singularities,

$$\text{WF}(e^{it\sqrt{-\Delta_g}} B^* \mu) = \Phi_t \text{WF}(B^* \mu),$$

hence

$$(4.6) \quad \text{WF}(e^{it\sqrt{-\Delta_g}} B^* \mu) \cap \text{WF}(B^* \mu) = \emptyset \quad \text{for } 1 \leq |t| \leq T.$$

Since the support of μ has been made small, if there is $(x, \xi) \in SN_{\text{supp } \mu}^* \Sigma$ and some $t > 0$ in the support of $(1 - \beta(t))\hat{\chi}(t/T)$ for which $\Phi_t(x, \xi) \in SN_{\text{supp } \mu}^* \Sigma$, then $t \geq 1$

since the diameter of $\text{supp } \mu$ is small and the injectivity radius of M is at least 1. We now have (4.5), from which follows (4.4) as promised.

What remains is to bound

$$(4.7) \quad \left| \int_{\Sigma} \int_{\Sigma} b X_{T,\lambda} b^*(x, y) d\mu(x) d\mu(y) \right| \leq \lambda^{n-d-1} + C_{T,b} \lambda^{n-d-2}.$$

We have

$$b X_{T,\lambda} b^*(x, y) = \sum_j X_T(\lambda_j - \lambda) b e_j(x) \overline{b e_j(y)},$$

and so we write the integral in (4.7) as

$$(4.8) \quad \sum_j X_T(\lambda_j - \lambda) \left| \int_{\Sigma} b(x, D) e_j(x) d\mu(x) \right|^2.$$

By the bounds

$$|X_T(\tau)| \leq C_{T,N} (1 + |\tau|)^{-N} \quad \text{for } N = 1, 2, \dots$$

and Proposition 3.2,

$$\begin{aligned} & \left| \sum_j X_T(\lambda_j - \lambda) \left| \int_{\Sigma} b(x, D) e_j(x) d\mu(x) \right|^2 \right| \\ & \leq C_T \lambda^{n-d-1} \int_{\mathbb{R}^d} \int_{S^{n-d-1}} |b(x', \omega)|^2 h(x')^2 d\omega dx' + C_{T,b} \lambda^{n-d-2}. \end{aligned}$$

Taking ε in part (2) of Lemma 4.2 small enough so that $\varepsilon C_T \leq 1$ yields (4.7). This concludes the proof of Proposition 4.1.

5. Appendix: Stationary phase tool.

The following tool is a combination of Corollary 1.1.8 with the discussion at the end of Section 1.1 in [8]. Let $\phi(x, y)$ be a smooth phase function on $\mathbb{R}^m \times \mathbb{R}^n$ with

$$\nabla_y \phi(0, 0) = 0 \quad \text{and} \quad \det \nabla_y^2 \phi(0, 0) \neq 0,$$

and let $a(\lambda; x, y)$ be a smooth amplitude with small, adjustable support satisfying

$$|\partial_{\lambda}^j \partial_x^{\alpha} \partial_y^{\beta} a(\lambda; x, y)| \leq C_{j,\alpha,\beta} \lambda^{-j} \quad \text{for } \lambda \geq 1$$

for $j = 0, 1, 2, \dots$ and multiindices α and β . $\nabla_y^2 \phi \neq 0$ on a neighborhood of 0 by continuity. There exists locally a smooth map $x \mapsto y(x)$ whose graph in $\mathbb{R}^m \times \mathbb{R}^n$ contains all points in a neighborhood of 0 such that $\nabla_y \phi = 0$, by the implicit function theorem. Let p and q be integers denoting the number of positive and negative eigenvalues of $\nabla_y^2 \phi$, respectively, counting multiplicity. By continuity, p and q are constant on a neighborhood of 0. We adjust the support of a to lie in the intersection of these neighborhoods.

Proposition 5.1. *Let*

$$I(\lambda; x) = \int_{\mathbb{R}^n} e^{i\lambda\phi(x,y)} a(\lambda; x, y) dy$$

with ϕ and a as above. Then,

$$\begin{aligned} I(\lambda; x) &= (\lambda/2\pi)^{-n/2} |\det \nabla_y^2 \phi(x, y(x))|^{-1/2} e^{\pi i(p-q)/4} e^{i\lambda\phi(x, y(x))} a(\lambda; x, y(x)) \\ &\quad + \lambda^{-n/2-1} e^{i\lambda\phi(x, y(x))} R(\lambda; x) + O(\lambda^{-N}) \end{aligned}$$

for $N = 1, 2, \dots$, where R has compact support,

$$|\partial_\lambda^j \partial_x^\alpha R(\lambda; x)| \leq C_{j,\alpha} \lambda^{-j} \quad \text{for } \lambda \geq 1,$$

and the $O(\lambda^{-N})$ term is constant in x .

Proof. We have

$$(5.1) \quad e^{-i\lambda\phi(x,y(x))} I(\lambda; x) = \int_{\mathbb{R}^n} e^{i\lambda\Phi(x,y)} a(\lambda; x, y) dy$$

where we have set

$$\Phi(x, y) = \phi(x, y) - \phi(x, y(x)).$$

The proof of the Morse-Bott lemma in [1] lets us construct a smooth map $F : \mathbb{R}^m \times \mathbb{R}^n \rightarrow \mathbb{R}^n$ such that $y \mapsto F(x, y)$ is a diffeomorphism between neighborhoods of 0 in \mathbb{R}^n for each x , and for which

$$F(x, 0) = y(x)$$

and

$$\Phi(x, F(x, y)) = \frac{1}{2}(y_1^2 + \dots + y_p^2 - y_{p+1}^2 - \dots - y_n^2) = Q(y).$$

Applying a change of variables in y to (5.1) yields

$$\begin{aligned} &= \int_{\mathbb{R}^n} e^{i\lambda Q(y)} a(\lambda; x, F(x, y)) |\det D_y F(x, y)| dy \\ &= \int_{\mathbb{R}^n} e^{i\lambda Q(y)} a(\lambda; x, F(x, 0)) |\det D_y F(x, 0)| dy + \int_{\mathbb{R}^n} e^{i\lambda Q(y)} r(\lambda; x, y) dy \end{aligned}$$

where

$$r(\lambda; x, y) = a(\lambda; x, F(x, y)) |\det D_y F(x, y)| - a(\lambda; x, F(x, 0)) |\det D_y F(x, 0)|.$$

The first term evaluates to

$$(\lambda/2\pi)^{-n/2} |\det \nabla_y^2 \phi(x, y(x))|^{-1/2} e^{\pi i(p-q)/4} a(\lambda; x, y(x))$$

since

$$\int_{-\infty}^{\infty} e^{i\lambda t^2/2} dt = (\lambda/2\pi)^{-1/2} e^{\pi i/4}$$

and

$$|\det \nabla_y^2 \phi(x, y(x))| = |\det D_y F(x, 0)|^{-2}.$$

To estimate the second term, we let χ be a smooth compactly supported cutoff function with $\chi(|y|) = 1$ for all $y \in \text{supp}_y a$. Then,

$$\begin{aligned} &\int_{\mathbb{R}^n} e^{i\lambda Q(y)} r(\lambda; x, y) dy \\ &= \int_{\mathbb{R}^n} e^{i\lambda Q(y)} \chi(|y|) r(\lambda; x, y) dy + \int_{\mathbb{R}^n} e^{i\lambda Q(y)} (1 - \chi(|y|)) r(\lambda; x, y) dy \\ &= R_1(\lambda; x) + R_2(\lambda; x), \end{aligned}$$

respectively. Since $r(\lambda; x, y)$ vanishes for $y = 0$,

$$|\partial_\lambda^j \partial_x^\alpha R_1(\lambda; x)| \leq C_{j,\alpha} \lambda^{-n/2-1-j}$$

by [8, Lemma 1.1.6] applied to the x -derivatives of R_1 . Finally,

$$R_2(\lambda; x) = c \int_{\mathbb{R}^n} e^{i\lambda Q(y)} (1 - \chi(|y|)) dy = O(\lambda^{-N})$$

by integration by parts. □

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