

Filtering navigation algorithm for AAUSHIP1

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Abstract—Measuring of water depths around Greenland is currently a time consuming task. This can be done by using several smaller autonomous vessels. AAUSHIP1 is a model vessel which serves as a platform for the development of such small vehicles.

Index Terms—Something, smart, goes, here

PLACE
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Michael Shell Biography text here.

I. INTRODUCTION

THIS demo file is intended to serve as a “starter file” for IEEE journal papers produced under L^AT_EX using IEEEtran.cls version 1.7 and later. I wish you the best of success.

mds

January 11, 2007

A. Subsection Heading Here

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1) Subsubsection Heading Here: Subsubsection text here.

II. CONCLUSION

The conclusion goes here.

John Doe Biography text here.

APPENDIX A

PROOF OF THE FIRST ZONKLAR EQUATION

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APPENDIX B

Appendix two text goes here.

ACKNOWLEDGMENT

The authors would like to extend a big thanks to Mr. Daniel Winther Uhrenholdt for the creation of the midsections of the ship - and also the School of Information and Communication Technology for funding the project.

REFERENCES

- [1] H. Kopka and P. W. Daly, *A Guide to L^AT_EX*, 3rd ed. Harlow, England: Addison-Wesley, 1999.

Jane Doe Biography text here.