

Laboratory Test

DSP 2020-2021

Information

- The test is taken in the lab, and lasts for 1 hour
- General Matlab stuff you need to know is listed in the **Syllabus** section. This is not an exhaustive list. There may be things I forgot to put in the list, but the basics are there.
- Template subjects (i.e. exercises extracted from the labs) are in **Template Subjects** section
- The test will be roughly based on these templates, with modifications

Syllabus (not exhaustive)

- Define scalars, vectors, matrices
 - Generate constant vectors (zeros, ones, some value)
 - Generate sin and cos signals of a certain length, with various amplitude, frequencies and initial phase
 - Generate random numbers, vectors and matrices, using `rand` and `randn`
 - Generate linearly spaced values between a start value and a stop value (e.g. `linspace()` or `start:step:stop`)
- Concatenate vectors and matrices. Build longer signals from more parts.
- Access elements from vectors/matrices. Select rows or columns from matrices.
- Do basic mathematical operations with scalars, vectors, matrices
- Display a text message (`disp()` or `fprintf()`)
- Use simple instructions (`if`, `for`, `while`)

- Make plots
 - Plot a vector
 - Plot a vector against another vector (e.g. put the vector \mathbf{n} on the horizontal axis)
 - Plot multiple signals on the same figure
 - Use subplots
- Operate with audio files (`.wav`, `.mp3`)
 - load a file
 - load only a certain part of a file (e.g. the first 5 seconds)
 - extract a single channel
 - play with the data, e.g. swap channels
- Operate with images
 - Create a simple grayscale or color image and display it
 - Load and display an image file. Also do simple adjustments (convert to grayscale, divide to 255).
 - Apply a simple filter to an image (e.g. a 3×3 matrix with coefficients)
- Create and display a video based on a simple animation of an image (e.g. scrolling the image, change luminosity)
- Create and use Matlab functions
- Implement a system in a Matlab function, based on the system equation
 - the function takes \mathbf{x} as input and outputs the result vector \mathbf{y}
- Pass a function as argument to another function and use it inside
- Do convolutions of vectors with `conv()`
- Compute the Discrete Fourier transform (DFT) of a vector, compute and display the modulus and the phase of the Fourier transform
- Implement a system in Simulink based on the equation
 - Also apply some input, visualize the output
 - Apply an impulse and visualize the impulse response
- Test linearity ~~and time-invariance~~ of systems in Simulink
- Design a low-pass/high-pass etc. filter with `fdatool` GUI, and implement it in Simulink (Lab 11)
- Design an oscillator with a prescribed frequency, and implement it in Simulink (Lab 11)

Template Subjects

Lab 2

1. Plot on the same figure the signals $\sin(2\pi ft + \frac{\pi}{4})$ and $\cos(2\pi ft + \frac{\pi}{8})$, with $f = 0.3$ and $t \in [0, 10]$.
2. Load the audio file ‘Kalimba.mp3’ in the Matlab workspace. Only load samples between 1 and 200000 (to avoid out of memory error)
 - a. Play it through the computer’s audio device
 - b. Change the sampling frequency to half the correct value, and play again. How will the sound be changed?
 - c. Amplify the sound by multiplying the data by 4. Play the sound and observe the difference.
 - d. Swap the left and right channels (it’s a stereo file) and play the sound again.

Lab 3 version 1

3. Create a color image representing the Romanian flag (3 stripes of blue, yellow, red). Create the image using the following steps: Create three matrices for the R, G, B components of the image Concatenate the three matrices across third dimension, into a 3D tensor

Variant: Make another simple flag or figure, color or grayscale, and show it

Lab 3 version 2

1. Load the **Lena** image (use `imread()`), convert it to double, convert it to grayscale, scale the values to the $[0, 1]$ range, and display the image (use `imshow()`).
2. Construct a new image based on the **Lena**, but in which each pixel value is set as a linear combination of the original pixels around it, as in the following equation:

$$\begin{aligned} y[i, j] = & \frac{1}{9}x[i-1, j-1] + \frac{1}{9}x[i-1, j] + \frac{1}{9}x[i-1, j+1] \\ & + \frac{1}{9}x[i, j-1] + \frac{1}{9}x[i, j] + \frac{1}{9}x[i, j+1] \\ & + \frac{1}{9}x[i+1, j-1] + \frac{1}{9}x[i+1, j] + \frac{1}{9}x[i+1, j+1] \end{aligned}$$

Ignore the first and last row/column, if needed.

Display the resulting image in a new window. How did it change?

Lab 4

1. Load the **Lena** image (use `imread()`), convert it to a grayscale image, convert it to `double` type, adapt the values to the $[0, 1]$ range, and display it (use `imshow()`).
2. Create a video sequence by scrolling the Lena image circularly to the right, by 3 pixels at every frame. Display the video at 25fps.

Code template for creating a video sequence in Matlab:

```
height = ...; % desired height
width  = ...; % desired width
NoF    = ...; % desired number of frames
% an array of size height x width x 1 x NoF:
video  = zeros(height, width, 1, NoF);
for i = 1:NoF
    video(:,:,i) = ... the frame number i ... ;
end

% Play the sequence
implay(video);
```

Variant: do another thing instead of scrolling, like change luminosity etc.

Lab 5

1. Create a function `mysys1()` that implements the following system H_1 :

$$y[n] = H_1\{x[n]\} = \frac{1}{4}x[n] - \frac{1}{2}x[n-1] + \frac{1}{4}x[n-2]$$

- the function takes 1 input argument **x** and outputs 1 result vector **y**
2. In a separate script, test the linearity of this system in the following way:
 - generate two random vectors **x** and **y** and two random numbers **a** and **b**
 - apply the function `mysys1()` to **a*x**, **b*y**, and **a*x + b*y**, and check if the results verify the linearity equation
 - display a message indicating if the system is linear or not linear

Lab 6

1. Create a Simulink model to implement the following system H_1 :

$$y[n] = H_1\{x[n]\} = \frac{1}{4}(x[n] + x[n-1] + x[n-2] + x[n-3])$$

- the system should be implemented as a Subsystem block with one input and one output signal
2. Visualize the impulse response of the system
 - add a unit impulse as the input (hint: can be created from two unit ramp blocks, delayed)
 - add a Scope at the output to visualize the data

Lab 7 Variant 1

1. Create a Simulink model to implement the following system H_1 :

$$y[n] = H_1\{x[n]\} = 0.8y[n-1] + 0.25x[n] + 0.1x[n-1]$$

- the system should be implemented as a Subsystem block with one input and one output signal
2. Test linearity of this system as follows:
 - create three copies of the system inside the model (copy/paste)
 - use two random input vectors \mathbf{x} and \mathbf{y} (use two *Random* blocks)
 - apply input signals \mathbf{x} , \mathbf{y} and $\mathbf{x}+\mathbf{y}$ to the three copies of the system
 - add the outputs of the systems which have \mathbf{x} and \mathbf{y} as inputs, then subtract the output of the system which has $\mathbf{x} + \mathbf{y}$ as input
 - show the resulting signal. Is the system linear?

Lab 7 Variant 2

~~Same thing, but test time invariance instead of linearity (Ex. 5):~~

- ~~• the system will be applied to an input vector \mathbf{x} , and to \mathbf{x} prepended with a variable number of zeros (i.e. time delayed)~~
- ~~• the outputs shall be checked if they verify the time invariance equation~~

Lab 8

1. Load an audio signal and extract a 10 seconds long sequence of it.
 - a. Convolve the sequence with the impulse response $\{1/6, 1/6, 1/6, 1/6, 1/6, 1/6\}$. Play the resulting sequence.
 - b. Load another impulse response from the file “Scala Milan Opera Hall.wav” (use `audioread()`). Call the resulting vector **h**. Convolve the original audio signal with **h** and play the result.
 - c. Convolve the result from b) with another impulse response from the pack. Play the resulting signal.
 - d. Compute and display the equivalent impulse response of the complete system in points b) and c).

Lab 9

1. Generate a 100 samples long signal **x** defined as $x[n] = 0.7 \cos(2\pi f_1 n) + 1.2 \sin(2\pi f_2 n)$, with $f_1 = 0.05$ and $f_2 = 0.1$.
 - a. Plot the signal in the top third of a figure (use `subplot()`).
 - b. Compute the Fourier series coefficients with `fft()` and plot their magnitude in the middle third, and their phase in the lower third.
 - c. Repeat the plot but do the FFT in N=1000 points (use `fft(x, N)`). What changes?

Lab 11 Variant 1

1. Use the Filter Design tool in Matlab (`fdatool`) to design a IIR high-pass filter with order 3, with cutoff frequency 0.07. Implement the filter in Simulink and then apply at the input the signal $x[n] = \cos(2\pi 0.03n) + \cos(2\pi 0.18n)$ and visualize the output $y[n]$. Compare with the input signal.

Lab 11 Variant 2

2. Use the Filter Design tool in Matlab (`fdatool`) to design an oscillator with frequency 0.05. Implement it in Simulink, visualize & play the output signal.

Use the following steps to design the oscillator:

1. design a system of order 2 with 2 conjugate poles placed **on the unit circle** at the correct frequency, and 2 zeros at low & high frequencies
2. implement the system in Simulink, **omitting the input signal** (not necessary)
3. set a non-zero initial condition in the system, to start-up the oscillator